# REGION 4A Agos (Infanta) River: DREAM Ground Surveys Report



TRAINING CENTER FOR APPLIED GEODESY AND PHOTOGRAMMETRY

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## List of Abbreviations

ADCP	Acoustic Doppler Current Profiler
AWLS	Automated Water Level Sensor
BM	Benchmark
DAC	Data Acquisition Component
DEM	Digital Elevation Model
DG	Depth Gauge
DOST	Department of Science and Technology
DPC	Data Processing Component
DREAM	Disaster Risk Exposure and Assessment for Mitigation
DVC	Data Validation Component
EGM 2008	Earth Gravitation Model 2008
FMC	Flood Modeling Component
GCP	Ground Control Point
GE	Geodetic Engineer
GIS	Geographic Information System
GNSS	Global Navigation Satellite System
GPS	Global Positioning System
LGUs	Local Government Units
NAMRIA	National Mapping and Resource Information Authority
PCG	Philippine Coast Guard
PDRRMC	Provincial Disaster Risk Reduction Management Council
PPA	Philippine Ports Authority
РРК	Post Processed Kinematic
RG	Rain Gauge
TCAGP	Training Center for Applied Geodesy and Photogrammetry
UTM	Universal Transverse Mercator
WGS84	World Geodetic System 1984





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#### 1.1 DREAM Program Overview

The UP training Center for Applied Geodesy and Photogrammetry (UP TCAGP) conducts a research program entitled "Nationwide Disaster Risk and Exposure Assessment for Mitigation" supported by the Department of Science and Technology (DOST) Grant-in-Aide Program. The DREAM Program aims to produce detailed, up-to-date, national elevation dataset for 3D flood and hazard mapping to address disaster risk reduction and mitigation in the country.

The DREAM Program consists of four components that operationalize the various stages of implementation. The Data Acquisition Component (DAC) conducts aerial surveys to collect LiDAR data and aerial images in major river basins and priority areas. The Data Validation Component (DVC) implements ground surveys to validate acquired LiDAR data, along with bathymetric measurements to gather river discharge data. The Data Processing Component (DPC) processes and compiles all data generated by the DAC and DVC. Finally, the Flood Modeling Component (FMC) utilizes compiled data for flood modeling and simulation.

Overall, the target output is a national elevation dataset suitable for 1:5000 scale mapping, with 50 centimeter horizontal and vertical accuracies, respectively. These accuracies are achieved through the use of state-of-the-art airborne Light Detection and Ranging (LiDAR) Systems collects point cloud data at a rate of 100,000 to 500,000 points per second, and is capable of collecting elevation data at a rate of 300 to 400 square kilometer per day, per sensor.

#### **1.2 Objectives and target outputs**

The program aims to achieve the following objectives:

a. To acquire a national elevation and resource dataset at sufficient resolution to produce information necessary to support the different phases of disaster management,
b. To operationalize the development of flood hazard models that would produce updated and detailed flood hazard maps for the major river systems in the country,
c. To develop the capacity to process, produce and analyze various proven and potential thematic map layers from the 3D data useful for government agencies,
d. To transfer product development technologies to government agencies with geospatial information requirements, and,

- e. To generate the following outputs
  - 1. flood hazard map
  - 2. digital surface model
  - 3. digital terrain model and
  - 4. orthophotograph



## **1.3 General methodological framework**

The methodology employed to accomplish the project's expected outputs are subdivided into four (4) major components, as shown in Figure 1. Each component is described in detail in the following sections.



Figure 1. The General Methodological Framework of the Program





# The Infanta River Basin



## **The Infanta River Basin**

The methodology employed to accomplish the project's expected outputs are subdivided into four (4) major components, as shown in Figure 1. Each component is described in detail in the following sections.



Figure 2. Infanta River Basin Location Map

The land and soil characteristics are important parameters used in assigning the roughness coefficient for different areas within the river basin. The roughness coefficient, also called Manning's coefficient, represents the variable flow of water in different land covers (i.e. rougher, restricted flow within vegetated areas, smoother flow within channels and fluvial environments).

The shape files of the soil and land cover were taken from the Bureau of Soils, which is under the Department of Environment and Natural Resources Management, and National Mapping and Resource Information Authority (NAMRIA). The soil and land cover of the Agos River Basin are shown in Figure 3 and Figure 4, respectively.



## **The Infanta River Basin**



Figure 3. Infanta River Basin Soil Map



Figure 4. Infanta River Basin Land Cover Map







A set of activities were designed and implemented by DVC with four (4) main activities as shown in Figure 5.





Figure 5. DVC Main Activities



### 3.1 Pre-field Preparation

#### 3.1.1 Preparation of Field Plan

The planning for research fieldwork considers all the necessary technical and logistical concerns conceptualized in a field plan.

This serves as a basis and guide of the survey team in the implementation of the fieldwork activities and included the following activities:

• Delineation of bathymetry lines and determination of the river basin extent using Google Earth<sup>®</sup> images and available topographic maps;

- Listing and preparation of the survey equipment and other materials needed;
- Designation of tasks to DVC members for the field survey;
- Approximation of field duration and cost based on the delineated survey extent; and

• Assessment of the initial field plan by the program management for approval and implementation.

#### 3.1.2 Collection of Reference Points

Technical data and other relevant information are collected from the National Mapping and Resource Information Authority (NAMRIA) such as locations and descriptions of established horizontal and vertical control points with a minimum of 2nd order accuracy. These ground control points and benchmarks are selected and occupied as primary reference points for the establishment of a GNSS network for the survey.



#### 3.2 Field Surveys



Figure 6. DVC Field Activities

#### 3.2.1 Control Survey

A GNSS network is established through occupation of reference points with dual frequency GNSS receivers for four (4) hours. Reference points from NAMRIA only bear vertical coordinates (z or elevation value) and horizontal coordinates (x and y values) for benchmarks and ground control points, respectively.

Control survey aims to provide both the horizontal and vertical position for every control point established through network adjustment. Horizontal position is acquired through static survey while establishment of vertical position can be done either using a Total Station (TS) or digital level or through static survey.

For the vertical position control survey using a TS or Level, a double run is carried out connecting the nearest existing NAMRIA benchmarks (BMs) to the control point. A double run consists of a forward run (from BM to GCP) and backward run (from GCP to BM). The accuracy shall be assessed and accepted if it is within the third order differential leveling standard.

A benchmark may be used to refer elevation data to Mean Sea Level (MSL) within 20km radius. Additional benchmarks are located for survey areas exceeding this 20-km radius.

Establishment of a GNSS network through control survey is pre-requisite for the conduct of other ground survey activities. Reference and control points occupied for the control survey may serve as base stations throughout the survey area.



#### 3.2.2 Cross-section Survey

The objective of this activity is to derive a sectional view of the main river and the flood plain (right and left banks). Cross-sections are surveyed perpendicular to the riverbanks with an average length of 100 meters for each bank. The cross-section line shall follow the path of the nearby road or goat trails with a 10-meter interval for each point measurement. Additional points are obtained to describe apparent change in elevation along the cross-section line. Each cross-section is identified sequentially from upstream to downstream direction.

Cross-section surveys are done using dual frequency GNSS receivers and differential kinematic GNSS survey technique. The accuracy of the horizontal position and elevation of each individual cross-section surveys is within  $\pm 20$  cm for horizontal and  $\pm 10$  cm for vertical position residuals.

Areas where kinematic GNSS survey is not applicable due to the presence of obstructions such as tall structures and canopy of trees, conventional surveying techniques such as total stations and level are used to collect cross-sectional data.



#### 3.2.3 Profile Surveys

Profile surveys are conducted to obtain the upper and lower banks of the river. This data is overlaid with LIDAR data to delineate the longitudinal extent of the river.

A profile survey consists of the Left Upper Bank (LUB) and Left Lower Bank (LLB), Right Upper Bank (RUB) and Right Lower Bank (RLB). An interval between successive profile points is approximately 10 meters. Additional points are gathered to describe apparent change in elevation along the profile line

Profile surveys are conducted using dual frequency GNSS receivers and kinematic survey technique with a prescribed vertical accuracies of  $\pm 20$  cm for horizontal and  $\pm 10$  cm for vertical position, respectively. Conventional surveying techniques such as total stations and level are used to collect profile data for areas where kinematic GNSS survey is not applicable due to obstructions such as tall structures and canopy of trees.

#### 3.2.4 Bathymetric Survey

Bathymetric survey is performed using a survey-grade single beam echo sounder capable of logging time-stamped depth value in centimeter and dual frequency GNSS using kinematic survey technique, with prescribed vertical accuracies of  $\pm 20$  cm for horizontal and  $\pm 10$  cm for vertical position for rivers navigable by boat. Data acquisition is logged at one second intervals both for GPS positions and elevation and echo sounder depth reading

For portions of the river that is not navigable by boat due to shallow waterless than a meter, riverbed may be acquired using manual bathymetric survey. Manual bathymetric survey means manually acquiring riverbed points without the use of an echo sounder. It can be done using a GPS receiver, Total Station or Level.



#### 3.2.5 Hydrometric Survey

Hydrometric survey consists of deployment of flow gathering sensors in order to produce a Stage-Discharge (HQ) computation for specific locations in the river such as in its upstream, tributaries, and downstream. This is done to determine the behavior of the river given specific precipitation levels.

The elements of discharge computation are the ff.:

• **River flow data** – river flow data can be acquired using an Acoustic Doppler Current Profiler (ADCP) or by mechanical or digital flow meters. River flow data sensors measure velocity of the river for a specific time period and interval.

• **Cross-section data** – cross section data is acquired using dual frequency GPS receivers to obtain the cross-section area of the river. Cross-section area of a river changes in time as influenced by water level change.

• **Water level change –** water level change is measured using either a depth gauge or an Automated Water Level Sensor (AWLS) installed by DOST. Depth gauges relates pressure to water level change while AWLS uses laser pulsed at specific time intervals for measurement.

• Water surface elevation – water surface elevation in MSL is measured near the banks of the river with dual frequency GPS receivers. This will refer the measured water level change to a corresponding elevation value in MSL in order to derive Stage or water level height a particular time.

Precipitation is the biggest factor influencing stage and river velocity. These two (2) sets of data must be synchronized by time in order to compute for its cross-section area, and subsequently, for discharge.

The element of time is crucial in determining the delay between the onset of precipitation and the time of significant water level change along key points of the river for early flood warning system of communities. The correlation of stage-discharge computation is used for calibrating flood-simulation programs utilized by the Flood Modeling Component (FMC).

The summary of elements for discharge computation is illustrated in Figure 7.





Figure 7. Flow Chart for Stage-Discharge Correlation Computation

#### 3.2.5 Validation Points Acquisition Survey

Ground validation survey is conducted for quality checking purpose of the Aerial LiDAR data acquired by the Data Acquisition Component (DAC). A roving GNSS receiver is mounted on a range pole attached to a vehicle to gather points thru continuous topo method in a PPK Survey Technique. Points are measured along major roads and highway across the flight strips provided by DAC.

GNSS surveys setup used to accomplish DVC's field survey activities are illustrated in Figure 8.





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Data processing procedures used by DVC are summarized in Figure 9.

3.3 Data Processing

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#### 3.3.1 Collection of Raw Data

GPS Raw data in (\*.to2) format are downloaded from Trimble<sup>™</sup> GPS receivers used in static, cross-section, LiDAR ground validation, and bathymetric surveys. Depth values in (\*.som) files from bathymetric surveys are also downloaded from OHMEX® echo sounder.

#### 3.3.2 Data Processing

#### **Processing for GNSS Data**

The horizontal and vertical coordinates of the reference point used as base station are held fixed, based on its NAMRIA certification, for the establishment of a GNSS network for the survey area. Coordinates of this fixed point is used to give horizontal and vertical coordinates for the other reference points occupied and control points established.

Data from GNSS control surveys are processed in Trimble<sup>™</sup> Business Center (TBC) software and settings were set to the required accuracy of +/-10cm for vertical and +/-20cm for horizontal controls. The TBC coordinate system parameters were set to Universal Transverse Mercator (UTM) Zone 51 North, World Geodetic System of 1984 (WGS1984), and the geoid model EGM2008 for horizontal and vertical datum, respectively.

An offset is derived by comparing the MSL elevation of the benchmark stated in the NAMRIA certification and its elevation value that resulted from the processed and adjusted control survey. This offset is used to refer all elevation from other surveys into MSL (BM Ortho).

The formulas used for offset and BM Ortho computation are shown in Equations 1-2:

#### **Computation for offset:**

Equation 1:

OFFSET = BM - EGM

#### Computation for BM ortho:

Equation 2:

$$BM_{ortho} = EGM_{ortho} \pm OFFSET$$



where:

OFFSET	= difference/offset between Geoid model, EGM 2008 and MSL datum. Can be a positive or negative value
ВМ	= MSL elevation of vertical control point certified by NAMRIA
EGM	= EGM2008 elevation of the same NAMRIA vertical control point derived from TBC software processing
EGM Ortho	= elevation of points referred to geoid model, EGM 2008
BM_ <sub>Ortho</sub>	= elevation of points referred to MSL

GNSS processing is also done for the other surveys with the coordinates from the occupied points for the control survey held fixed, depending on which base station is used for the survey.

Processed and adjusted data are exported to comma delimited (\*.csv) file format with the ff. columns: Point Name, Latitude, Longitude, Ellipsoidal Height, Northing, Easting, and Elevation (EGM\_Ortho). This file format can be accessed through Microsoft Excel/Spreadsheet program.



#### Depth Data Processing

Figure 10. Illustration of Echo Sounder and GPS rover set-up for Bathymetric survey

There are two types of echo sounders used for bathymetric surveys – Hi-Target<sup>™</sup> single beam echo sounder which is capable of recording depth data of one decimal place and the OHMEX<sup>™</sup> single beam echo sounder capable of recording two-decimal places of depth data.

Raw depth data from Hi-Target<sup>™</sup> single beam echo sounder is exported in (\*.txt) file format with the ff. columns: Point No., Time, Depths H, Depths L, Draft, and Sound Velocity. This (\*.txt) file is copied to a spreadsheet, retaining only the columns for Time and Depths H.



Raw depth data from OHMEX<sup>™</sup> single beam echo sounder are exported in (\*.som) file format. It is imported into SonarVista then exported into \*.csv format with the ff. columns: Type, Date/Time, Sec, X/E, Y/N, Z/H, Tide, Depth and QA. SonarVista is used as file conversion tool only. The (\*.csv) file opened using spreadsheet, making use of only the columns for Date/ Time and Depth.

#### Data Matching for Bathymetric Data

Data matching is done by pairing an individual attribute of a bathymetric point to a depth data acquired using either OHMEX or HI-Target echo sounder. Matching is possible by ensuring that both bathymetric points and depth values acquisition has time stamp capability. These two sets of data are matched using VLOOKUP tool of a spreadsheet program, such that each point will have an accompanying (x,y,z) and depth data.

Below is the formula used for computing the elevation of the riverbed:

Equation 3:	DDE(t) TDE(t) Denth(t)
where:	RBE(t) = TRE(t) - Depth(t)
RBE(t)	= elevation of the riverbed during time t,
TRE(t)	= transducer elevation (reckoned from EGM 2008)
Depth(t)	= depth recorded by the echo sounder at time t, with the
	assumption that depth is measured from the bottom of the
	transducer down to the riverbed

The resulting RBE(t) data are referred to MSL (BM\_ortho) by applying the offset for the established network.

Final processed data are imported to Google Earth<sup>™</sup> and Geographic Information Systems (GIS) software for viewing and checking horizontal position.



#### Hydrometry Data Processing

The processes done for Hydrometry data for HQ computation are described in the ff. steps:

#### 1. River Flow Data

a.) ADCP

Data from the ADCP is logged internally and can be downloaded using either SonUtils<sup>M</sup> or View Argonaut<sup>M</sup> software. River velocity is recorded for a specified time duration and interval can be exported in a (\*.csv) format.

b.) Flow Meter

Acquisition of river velocity using flow meters is done manually. Measurements for a specified time duration and interval is recorded in a field notebook and saved in a spreadsheet program.

#### 2. Cross Section and Water Surface Elevation Data

Cross Section data and water surface elevation data is acquired using GNSS receivers described in section 3.3.4 for GNSS data processing with a resulting file in (\*.xls) format.

#### 3. Water Level Change-Stage

a.) Depth Gauge

Data from depth gauge can be downloaded using HobowarePro<sup>TM</sup>. Water level in meters are logged for a specific time interval and it can be exported in a (\*.csv) format.

b.) AWLS

Data from installed AWLS can be accessed via the internet (http://repo. pscigrid.gov.ph/predict/). Water levels are logged in ten-minute time intervals and can be copied into a spreadsheet program.

#### 4. Discharge Computation

River flow data and water level change is synchronized by time. Parameters were preset in its respective programs so the deployment of each instrument will begin and end in the same time. All data in (\*.csv) and (\*.csv) format are combined in a single worksheet wherein the computation for the coefficient of determination or R2 are done.

The illustration in Figure 7 shows how each set of data from each instrument can be synchronized.



#### 3.3.3 Filtering of Data

A processed point which resulted to float or did not meet the desired accuracy is filtered out. Resurveys are conducted immediately if data gaps are present for the ground surveys.

#### 3.3.4 Final Editing

Final editing is performed to be able to come up with the desired data format: Point Value, Latitude, Longitude, Ellipsoidal Height, Northing, Easting, EGM\_Ortho and BM\_Ortho.

Processes discussed are valid for static, cross section, ground validation, and manual bathymetric surveys not employing echo sounders. For bathymetric surveys using a single beam echo sounder, the GPS rover is mounted on top of a 2m pole and a transducer at the bottom (see Figure 10). Figure is valid in both using OHMEX and HI-Target echo sounders. The GPS rover provides horizontal and vertical coordinates whereas the echo sounder transducer measures depth of the river from its bottom down to the riverbed.

#### 3.3.5 Output

Filtered data are furthered processed into desired template using a spreadsheet program. Final data are generated into maps and CAD plots for cross-section, profile, and riverbed profiles. Cross-section, Profile, Validation Points, and Bathymetric data shall be turned-over to DPC while hydrometric data shall be turned-over to FMC.







The survey for Agos River Basin was conducted on June 14-19, 2013 and September 10-13, 2013 with the following activities: control, bathymetric and hydrometric surveys.

Hydrometric Survey of Agos River was conducted on June 14-19, 2013. An ADCP, depth gauge and rain gauge were deployed in Brgy. Batangan, General Nakar, Quezon.

Bathymetric Survey of Agos River was conducted on September 10-13, 2013 which started from the upstream in Brgy. Ilog, Infanta down to Brgy. Pinaglapatan, Infanta, draining into Polillo Strait with a total length of about 8 km.

Another set of fieldwork was conducted on January 28, 2014 to acquire ground validation points. Validation points acquisition survey from Brgy. Dinahican, Infanta to Brgy. Poblacion 61, Real with a total length of about 10.42 km and from Brgy. Comon, Infanta to Brgy. Pamplona, General Nakar with a total length of 7.59 km. A total length of 18.01 km validations points were acquired for this survey.

#### **4.1 Control Survey**

Two (2) NAMRIA reference points were considered for the static GNSS observations of Agos River, Infanta. These include a first order benchmark QZ-555 at Lion Club Monument Rotonda, Brgy. Gumian, Infanta and a second order reference point QZN-5 at the playground of Real Elementary School, Municipality of Real. The GNSS set-up for the two (2) base stations is shown in Figure 12 and Figure 13 while the locations of these controls are shown in Figure 11. The reference points QZ-555 and QZN-5 served as GNSS base station for Agos River bathymetry and validation points acquisition survey for aerial LiDAR.





Figure 11. Location of control points

Continuous differential static observations were done simultaneously at these three stations for two hours to provide reference control points for the ground and bathymetric surveys. The horizontal coordinates and elevations of the two (2) control points were computed using Trimble<sup>™</sup> Business Center GNSS processing software. The result of control survey for the control points are indicated in Table 1.

	1		00	,	`	,	/
			WGS84	UTM Zone	51N		Flowation
Point Name	Order	Latitude	Longitude	Ellipsoid Height (m)	Northing (m)	Easting (m)	in MSL (m)
QZN-5	1st	14°39'53.91240''	121°36'19.15477''	49.676	1621734.174	349817.649	1.9357
QZ-555 (BLLM 26)	1st	14°42'59.68961''	121°37'15.29012''	52.379	1627432.895	351531.898	4.7067

Table 1. Control points occupied during Agos River Survey (Source: NAMRIA, UP-TCAGP)



The GNSS setup for the two (2) control points are illustrated in Figure 12 and Figure 13:



Figure 12. Static GNSS observation at QZN-5 at Real Central Elementary School



Figure 13. Static GNSS observation at QZ-555 (BLLM-26) at Brgy. Gumian, Infanta



#### **4.1 Control Survey**

The bathymetry of the river channel was surveyed using echosounding surveying technique. Differential GNSS surveying technique and an Ohmex<sup>™</sup> single beam echo sounder were utilized in measuring the depth, eventually obtaining elevation with corresponding horizontal position.

The entire bathymetry survey took three (3) days to accomplish from September 11-13, 2013. The Bathymetry Team executed the survey using a fishing boat rented from the locals in the area. Centerline and zigzag sweep of the survey were performed in order to fully capture the topography of the river. A total length of 7.35 km out of 8.37 km bathymetric points were surveyed using an echo sounder. The remaining length was surveyed by traversing the river by foot due to shallow river depth as shown in Figure 15. Portions of the river channel were covered in gravel and mud due to previous typhoons as shown in Figure 16.



Figure 14. Bathymetric survey setup





Figure 15. Shallow part of Agos River



Figure 16. Gravels and solid ground covered the channel from the previous typhoon







## 4.3 Validation Points Acquisition Survey

Validation points survey data is essential to check and validate the accuracy of aerial LiDAR data acquired by DAC. The installation of the GPS receivers prior the validation points acquisition survey are shown in Figure 18 and Figure 19. Validation data gathered from Brgy. Dinahican, Infanta to Brgy. Poblacion 61, Real with a total length of about 10.42 km and from Brgy. Comon, Infanta to Brgy. Pamplona, General Nakar with a total length of 7.59 km is shown in Figure 20. A total of 18.01 km validated length in Infanta, Quezon.



Figure 18: Installation of GPS Receivers on top of the vehicle



Figure 19. Validation points acquisition survey setup





NL0.57-71

N.0.07-21

Figure 20. Validation data in Infanta, Quezon

## 4.4 Hydrometric Survey



Figure 21. Infanta Watershed with control points and sensor deployment site

Different sensors were deployed Agos River to obtain its physical characteristics such as cross-section elevation in MSL, velocity, and elevation of water level in MSL at a particular time.

The following data logging sensors were deployed to determine the flow of Agos River:

- Acoustic Doppler Current Profiler (ADCP);
- Rain gauge or udometer; and
- Depth gauge or Pressure gauge

The ADCP and depth gauge was deployed on June 14, 2013 on the banks of Agos River in Brgy. Batangan, General Nakar, Quezon. It was relocated on June 15, 2013 near the meander part of the river about 100m from the first deployment site to capture the change of terrain in the river channel due to the recent typhoons.



The ADCP with depth gauge was deployed and left on the site to constantly collect data while being watched over by a local hire. It was also monitored every other day by the team, checking the progress of the data collected particularly during heavy rainfalls brought by monsoon winds. The rain gauge was also installed approximately 330 meters away from where the ADCP was deployed. The sensors were then retrieved on June 19, 2013 after days of continuously collecting data.

Sensor	Location	Municipality	Deployment – Start	Deployment – End	Latitude	Longitude
Rain Gauge	Brgy. Batangan	Gen. Nakar	14-June	19-June	14º41 <b>'</b> 25 <b>.</b> 58''	121º31'48.13''
ADCP & Depth Gauge (1st setup)	Brgy. Batangan	Gen. Nakar	14-June	15-June	14º41'21.62''	121º31'46.07"
ADCP & Depth Gauge (2nd setup)	Brgy. Batangan	Gen. Nakar	15-June	19-June	114º41'21.47''	121º31'48.77"

 Table 2. Location and deployment date of the sensors

The date and time of deployment for each data logging sensor were shown in Table 2. The total number of deployment hours were filtered for each sensor in such a way that it synchronize with each other for the purpose of calculating the discharge and its relationships to other parameter. The deployment setups of sensors are shown in Figure 22 and Figure 23. The locations of deployed sensors are shown in Figure 21.





Figure 22. Deployment of rain gauge in Brgy. Batangan, General Nakar



**Figure 23.** (A) Setting up of ADCP and depth gauge, (B) deployment of ADCP and depth gauge in Brgy. Batangan, General Nakar



The terrain around the ADCP deployment site is shown in Figure 25 while the actual cross-section survey in the deployment site is shown in Figure 26.



Figure 25. River terrain along the ADCP deployment site in Brgy. Batangan, General Nakar



Figure 26. Cross section survey along the ADCP deployment site



The plotted cross-section diagram in CAD format for the 1st and 2nd set-up of ADCP in the Agos River where shown in Figure 27 and Figure 28.



Figure 27. Cross section plot of the first deployment site along Agos River



Figure 28. Cross Section plot of the second deployment site along Agos River



The rain gauge was deployed on June 14, 2013 at 5:45 pm while the ADCP and depth gauge were deployed on June 15, 2013 at 6:50 pm. The rain gauge logged data in a 5-min interval until June 19, 2013 at 10:40. The total/accumulated rainfall during this 103 hour period is 29.6 mm. Rainfall peaked up to 4.4 mm on June 15, 2013 at around 7:25 pm. The relationship between stage and river discharge on a specific area of the river is illustrated in Figures 29-32. A value approaching R<sub>2</sub> = 1 indicates a good correlation.



Figure 29. Stage vs Velocity graph









Figure 31. Stage vs Rainfall graph



Figure 32. Agos River HQ Curve







#### ANNEX A. PROBLEMS ENCOUNTERED AND RESOLUTIONS APPLIED

LIMITATION/PROBLEMS	SOLUTIONS
June 14, 2013: Courtesy call with the military exceeded its allotted time in the planned itinerary.	Courtesy calls should be initated prior field works via letters and phone calls to free the schedule for field works
June 14, 2013: The upstream hike to Brgy. Batangan, General Nakar was exhausting.	Three (3) local people from the area were hired to help carry the heavy equipment needed for the survey proper.
June 14, 2013: The 4x4 vehicle used to transport the team upstream along a difficult terrain was unavailable.	Tricycles which were familiar with the trail were hired to transport the team.
September 11, 2013: Strong river currents made it difficult to maneuvere the canoe.	The team started the survey upstream in- stead.



#### ANNEX B. LIST OF EQUIPMENT AND INSTRUMENTS

ТҮРЕ	BRAND	QUANTITY	OWNER
ADCP	SONTEK (SIDELOOK- ING)	1 unit	UP - TCAGP
Depth Gauge	Hobo	1 unit	UP - TCAGP
Rain Gauge	Hobo	1 unit	UP - TCAGP
GPS Receivers	Trimble SPS882	2 rovers	UP - TCAGP
	Trimble SPS852	1 base	UP - TCAGP
Singlebeam Echo- sounder	Ohmex	1 unit	UP - TCAGP
Handheld	Garmin Oregon 550	2 units	UP - TCAGP
Laptop	Dell ATG	1 unit	UP - TCAGP
Tripod	Trimble	1 unit	UP - TCAGP
Rangle pole with Bipod	Trimble	2 units	UP - TCAGP



#### ANNEX C. THE SURVEY TEAM

Designation	Name	Agency/Affiliation
Survey Team Coordinator	Glenn C. Sabio	Flood Modelling Component
Team Member	Kenneth Niño G. Punay	Flood Modelling Component
Survey Team Coordinator	Engr. Melchor Rey M. Nery	Data Validation Component
Team Member	Mark Lester Rojas	Data Validation Component
Bathymetric Survey Team	Mr. Jojo E. Morillo	Data Validation Component
Ground Validation Team	Ms. Jeline Amante	Data Validation Component



## Annexes

#### **ANNEX D. NAMRIA CERTIFICATION**

September 30, 2 TRON office, the requested survey information is as fold ON N-5
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Location Description

GZN-6 is located on the playground of Real Dem. School, approx. 100 m. SE of the DENR Bidg, about 60 m. SE of the school bidg; 20 m. SE of the basketball court and approx. 200 m. N of the public market. It is accessible by 2-wheel drive vehicle. Station mark is a 0.15 m. x 0.01 m. dia. brass rod set in standard concrete monument 0.7 m. deep and 0.15 m. sbove the ground, flush with the ground surface and insorted with the station name. Sub-surface mark is a bottle set in concrete block. The top of the bottle is 0.617 m. below station mark. Reference mark is a mark is a bottle set in concrete block. The top of the bottle is 0.617 m. below station mark. Reference mark is a mark is a bottle set in concrete blocks 0.45 m. deep and 0.15 m. above the ground, flushed with the 0.15 m. x 0.01 m. brass rod set in concrete blocks 0.45 m. deep and 0.15 m. above the ground, flushed with the ground surface and inscribed with the station name and RM number.

Requesting Party Nationwide Dream Pupper: OR Number: T.N.:

Reference 3946960 B 2013-0999

RUEL BM. BEVEN, MNBA Director, Jadging And Geodesy Branch





## Annexes











## DREAM Disaster Risk and Exposure Assessment for Mitigation

