REGION 3

Pampanga Floodplain:

DREAM LiDAR Data Acquistion and Processing Report







© University of the Philippines and the Department of Science and Technology 2015

Published by the UP Training Center for Applied Geodesy and Photogrammetry (TCAGP)
College of Engineering
University of the Philippines Diliman
Quezon City
1101 PHILIPPINES

This research work is supported by the Department of Science and Technology (DOST) Grants-in-Aid Program and is to be cited as:

UP-TCAGP (2015), DREAM LiDAR Data Acquisition and Processing for Pampanga River Floodplain, Disaster Risk and Exposure Assessment for Mitigation (DREAM) Program, DOST Grants-In-Aid Program, 162pp.

The text of this information may be copied and distributed for research and educational purposes with proper acknowledgment. While every care is taken to ensure the accuracy of this publication, the UP TCAGP disclaims all responsibility and all liability (including without limitation, liability in negligence) and costs which might incur as a result of the materials in this publication being inaccurate or incomplete in any way and for any reason.

For questions/queries regarding this report, contact:

Engr. Czar Jakiri Sarmiento, MSRS

Project Leader, Data Acquisition Component, DREAM Program University of the Philippines Diliman Quezon City, Philippines 1101 Email: czarjakiri@gmail.com

Engr. Ma. Rosario Concepcion O. Ang, MSRS

Project Leader, Data Processing Component, DREAM Program University of the Philippines Diliman Quezon City, Philippines 1101 Email: concon.ang@gmail.com

Enrico C. Paringit, Dr. Eng.

Program Leader, DREAM Program University of the Philippines Diliman Quezon City, Philippines 1101 E-mail: paringit@gmail.com

National Library of the Philippines

ISBN: 978-621-9695-05-9



Table of Contents

1.	INTRO	DDUCTION	1				
	1.1	About the DREAM Program	2				
	1.2	Objectives and Target Outputs	2				
	1.3	General Methodological Framework					
2.	STUD	Y AREA					
3.	METH	IODOLOGY	-				
	3.1	Acquisition Methodology	-				
		3.1.1 Pre-Site Preparations					
		3.1.1.1 Creation of Flight Plans					
		3.1.1.2 Collection of Exisitng Reference Points					
		and Benchmarks	12				
		3.1.1.3 Preparation of Field Plan					
		3.1.2 Ground Base Set-up					
		3.1.3 Acquisition of Digital Elevation Data (LiDAR Survey)	-				
		3.1.4 Transmittal of Acquired LiDAR Data					
		3.1.5 Equipment					
	3.2	Processing Methodology	-				
	J•-2	3.2.1 Data Transfer					
		3.2.2 Trajectory Computation	-				
		3.2.3 LiDAR Point Cloud Rectification					
		3.2.4 LiDAR Data Quality Checking					
		3.2.5 LiDAR Point Cloud Classification and Rasterization					
		3.2.6 DEM Editing and Hydro-correction					
4.	RESUI	LTS AND DISCUSSION					
٦٠	4.1	LiDAR Data Acquisition in Pampanga Floodplains					
	7.1	4.1.1 Flight Plans					
		4.1.2 Ground Base Station					
	4.2	LiDAR Data Processing	-				
	4.2	4.2.1 Trajectory Computation					
		4.2.2 LiDAR Point Cloud Computation					
		4.2.3 LiDAR Data Quality Checking	-				
		4.2.4 LiDAR Point Cloud Classification and Rasterization					
		4.2.5 DEM Editing and Hydro-correction					
_	ANNE						
5.			_				
		x A. Optech Technical Specification Of The Pegasus Sensorsus Sensor					
	_						
	Gemini Sensor Annex B. Optech Technical Specification Of The D-8900 Aerial Digital Camera						
	Annex C. The Survey Team Annex D. NAMRIA Certification						
		Annex E. Data Transfer Sheets					
	Annex F. Flight Logs						
	1.		88				
	2.		89				
	3.		90				
	4.		91				
	5.		92				
	6.	Flight Log for Pam 8D Mission	93				



Table of Contents

7.	Flight Log for Pam 8CS Mission	94
8.	Flight Log for 1P8Co56B Mission	95
9.	Flight Log for PAM8D Mission	96
10.	Flight Log for PAM8D Mission	97
11.	Flight Log for PAM 8E Mission	98
12.	Flight Log for PAM 8G1 Mission	99
13.	Flight Log for PAM 8G2 Mission	100
14.	Flight Log for PAM 8DS (G2) Mission	101
15.	Flight Log for PAM 8H1 Mission	102
16.	Flight Log for PAM 8H2 Mission	103
17.	Flight Log for PAM 8I Mission	104
18.	Flight Log for PAM 8I Mission	105
19.	Flight Log for PAM 8FS Mission	106
20.	Flight Log for PAM 8J Mission	107
21.	Flight Log for PAM 3A Mission	108
22.	Flight Log for PAM 3A Mission	109
23.	Flight Log for PAM 3DS Mission	110
24.	Flight Log for PAM 3B Mission	111
25.	Flight Log for PAM 3C1 Mission	112
26.	Flight Log for PAM 3C2 Mission	113
27.	Flight Log for PAM 3D Mission	114
28.	Flight Log for PAM 3CS (3D) Mission	115
29.	Flight Log for PAM 3E Mission	116
30.	Flight Log for PAM 3E Mission	117
31.	Flight Log for PAM 3BS (3F) Mission	118
32.	Flight Log for PAM 3G1 Mission	119
33.	Flight Log for 2PAM3G2 Mission	120
34.	Flight Log for 1P3G2005B Mission	121
35.	Flight Log for 2P3G2008B Mission	122
36.	Flight Log for 1P3H364A Mission	123
37.	Flight Log for 1P3H364B Mission	124
38.	Flight Log for 1P3AS058B Mission	125
39.	Flight Log for 2PAM3I1007A Mission	126
40.	Flight Log for 2P3I2008A Mission	127
41.	Flight Log for 1P3J007A Mission	128
42.	Flight Log for 1P3K008A Mission	129
43.	Flight Log for 2P7A1043A Mission	130
44.	Flight Log for 2P7A2045A Mission	131
45.	Flight Log for 2P7B1045B2 Mission	132
46.	Flight Log for 2PAM7B2046A Mission	133
47.	Flight Log for 1P7CO44A Mission	134
48.	Flight Log for 1P7C047B Mission	135
49.	Flight Log for 1P7Co49B Mission	136
50.	Flight Log for PAM7D Mission	137
51.	Flight Log for 1P7E047A Mission	138
52.	Flight Log for 2P7F1009A Mission	139
53.	Flight Log for 2P7F2009B Mission	140
54.	Flight Log for 1P7G049A Mission	141



Table of Contents

55.	Flight Log for 1P7Hoo9A and 1P7Doo8B (3LINES) Mission	142
56.	Flight Log for AGN10338A Mission	143
57•	Flight Log for AGN10338B Mission	144
58.	Flight Log for 1A10A046A Mission	145
59.	Flight Log for 1A10A046B Mission	146
60.	Flight Log for 1A10C045B Mission	147
61.	Flight Log for 2AGN10D1046B Mission	148
62.	Flight Log for IA10E10A Mission	149
63.	Flight Log for 1A10F10B Mission	150
64.	Flight Log for 2AGN10G1010A Mission	151
65.	Flight Log for 2AGN10G010B Mission	152
66.	Flight Log for 1A10H11A Mission	153
67.	Flight Log for 2AGNI1049B Mission	154
68.	Flight Log for 2A6N10I2011A Mission	155
69.	Flight Log for 1PAM8HR240A Mission	156
70.	Flight Log for 1PAM3A242A Mission	157
71.	Flight Log for 1PAM3B242B Mission	158
72.	Flight Log for 1AGNO338243A Mission	159
73.	Flight Log for 1AGNOE243B Mission	160
74.	Flight Log for 1AGNOE244A Mission	161
75.	Flight Log for 1PAM7C244A Mission	162



List of Figures

Figure 1.	The General Methodological Framework Of The Program 3		
Figure 2.	Pampanga River Basin Location Map6		
Figure 3.	Pampanga River Basin Soil Map		
Figure 4.	Pampanga River Basin Land Cover Map 7		
Figure 5.	Flowchart Of Project Methodology 1		
Figure 6.	Concept Of LiDAR Data Acquisition Parameters		
Figure 7.	LiDAR Data Management For Transmittal 1		
Figure 8.	The ALTM Pegasus System: A) Parts Of The Pegasus System, B) The		
	System As Installed In Cessna T206h	16	
Figure 9.	ALTM Gemini System	16	
Figure 10.	Schematic Diagram Of The Data Processing	17	
Figure 11.	Misalignment Of A Single Roof Plane From Two Adjacent Flight		
	Lines, Before Rectification (Left). Least Squares Adjusted Roof		
	Plane, After Rectification (Right)	19	
Figure 12.	Elevation Difference Between Flight Lines Generated From		
	LAStools	20	
Figure 13.	Profile Over Roof Planes (A) And A Zoomed-In Profile On The		
	Area Encircled In Yellow (B)	21	
Figure 14.	Ground Classification Technique Employed In Terrascan	22	
Figure 15.	Resulting DTM Of Ground Classification Using The Default		
	Parameters (A) And Adjusted Parameters (B)	23	
Figure 16.	Default Terrascan Building Classification Parameters	24	
Figure 17.	Different Examples Of Air Points Manually Deleted In The		
	Terrascan Window	24	
Figure 18.	Pampanga Floodplain Flight Plans		
Figure 19.			
	Of F.M. Cruz Orthopedic Hospital In Pulilan, Bulacan	33	
Figure 20.	Ground Base Station Observation At Aac-1 Established Inside		
	Asian Aerospace Corporation Hangar At Clark International		
	Airport In Pampanga		
Figure 21.	Pampanga Floodplain Flight Plans And Base Station		
Figure 22.	Pampanga Floodplain Data Acquisition Coverage	35	
Figure 23.	Flight Plans For Pampanga Floodplain Reflights	46	
Figure 24.	Base Stations For Pampanga Floodplain Reflights		
Figure 25.	Pampanga Reflights Flight Plans And Actual LiDAR Data	48	
Figure 26.	Smoothed Performance Metric Parameters Of Pampanga Flight	49	
Figure 27.	Solution Status Parameters Of Pampanga Flight	50	
Figure 28.	Coverage Of LiDAR Data For The Pampanga Mission	51	
Figure 29.	Image Of Data Overlap For The Pampanga Mission	52	
Figure 30.	Density Map Of Merged LiDAR Data For The Pampanga Mission 53		
Figure 31.	Elevation Difference Map Between Flight Lines5		
Figure 32.	Quality Checking With The Profile Tool Of QT Modeler5		
Figure 33.	(A) Pampanga Floodplains And (B) Pampanga Classification		
	Results In Terrascan	56	
Figure 34.	Point Cloud (A) Before And (B) After Classification		
Figure 35.	Images Of DTMs Before And After Manual Editing	57	



List of Figures

Figure 36.	Map Of Pampanga River System With Validation Survey Shown	
	In Blue	58
Figure 37.	One-One Correlation Plot Between Topographic And LiDAR Data	58
Figure 38.	Final DTM Of Pampanga With Validation Survey Shown In Blue	59
Figure 39.	Final DSM In Pampanga	60
Figure 40.	Sample 1X1 Square Kilometer DSM	60
Figure 41.	Sample 1X1 Square Kilometer DSM	61



List of Tables

Table 1.	Relevant LiDAR Parameters	11		
Table 2.	List Of Target River Systems In The Philippines	13		
Table 3.	Smoothed Solution Status Parameters In POSPac MMS V6.2	18		
Table 4.	Parameters Investigated During Quality Checks			
Table 5.	Ground Classification Parameters Used In Terrascan For Flood			
	Plain And Watershed Areas	23		
Table 6.	Classification Of Vegetation According To The Elevation Of			
	Points	23		
Table 7.	Parameters Used In LiDAR System During Flight Acquisition	28		
Table 8.	Details Of Dvs-1 Gcp Used As Base Station For The LiDAR			
	Acquisition	30		
Table 9.	Details Of PMG-3148 Used As Base Station For The LiDAR			
	Acquisition	31		
Table 10.	Details Of NEJ-3332 Used As Base Station For The LiDAR			
	Acquisition	31		
Table 11.	Details Of NEJ-3060 Used As Base Station For The LiDAR			
	Acquisition	32		
Table 12.	Details Of Established Ground Control Points By Data Acquisition			
	Component For LiDAR Survey In Pampanga Floodplain	32		
Table 13.	Flight Missions For LiDAR Data Acquisition In Pampanga Floodplain	36		
Table 14.	Area Of Coverage Of The LiDAR Data Acquisition In Pampanga			
	Floodplain	40		
Table 15.	Flight Missions For Supplementary LiDAR Data Acquisition In			
	Pampanga Floodplain	45		
Table 16.	Area Of Coverage Of The LiDAR Data Acquisition In Pampanga			
	Floodplain	49		
Table 17.	Pampanga Classification Results In Terrascan	56		
Table 18.	Statistical Values For The Calibration Of Flights	59		



Abbreviations

ALTM Airborne Laser Terrain Mapper DAC Data Acquisition Component

DEM Digital Elevation Model
DSM Digital Surface Model
DTM Digital Terrain Model

DVC Data Validation Component

FOV Field of View

FTP File Transfer Protocol
GPS Global Positioning System

GNSS Global Navigation Satellite System

POS Position Orientation System
PRF Pulse Repetition Frequency

NAMRIA National Mapping and Resource Information Authority





Introduction

1.1 About the DREAM Program

The UP Training Center for Applied Geodesy and Photogrammetry (UP TCAGP) conducts a research program entitled "Nationwide Disaster Risk and Exposure Assessment for Mitigation (DREAM) Program" funded by the Department of Science and Technology (DOST) Grants-in-Aid Program. The DREAM Program aims to produce detailed, up-to-date, national elevation dataset for 3D flood and hazard mapping to address disaster risk reduction and mitigation in the country.

The DREAM Program consists of four components that operationalize the various stages of implementation. The Data Acquisition Component (DAC) conducts aerial surveys to collect Light Detecting and Ranging (LiDAR) data and aerial images in major river basins and priority areas. The Data Validation Component (DVC) implements ground surveys to validate acquired LiDAR data, along with bathymetric measurements to gather river discharge data. The Data Processing Component (DPC) processes and compiles all data generated by the DAC and DVC. Finally, the Flood Modeling Component (FMC) utilizes compiled data for flood modeling and simulation.

Overall, the target output is a national elevation dataset suitable for 1:5000 scale mapping, with 50 centimeter horizontal and vertical accuracies. These accuracies are achieved through the use of state-of-the-art airborne Light Detection and Ranging (LiDAR) technology and appended with Synthetic-aperture radar (SAR) in some areas. It collects point cloud data at a rate of 100,000 to 500,000 points per second, and is capable of collecting elevation data at a rate of 300 to 400 square kilometers per day, per sensor.

1.2 Objectives and Target Output

The program aims to achieve the following objectives:

- a) To acquire a national elevation and resource dataset at sufficient resolution to produce information necessary to support the different phases of disaster management,
- b) To operationalize the development of flood hazard models that would produce updated and detailed flood hazard maps for the major river systems in the country,
- c) To develop the capacity to process, produce and analyze various proven and potential thematic map layers from the 3D data useful for government agencies,
- d) To transfer product development technologies to government agencies with geospatial information requirements, and,
- e) To generate the following outputs
 - 1) flood hazard map
 - 2) digital surface model
 - 3) digital terrain model and
 - 4) orthophotograph



Introduction

1.3 General Methodological Framework

The methodology employed to accomplish the project's expected outputs are subdivided into four (4) major components, as shown in Figure 1. Each component is described in detail in the following sections.

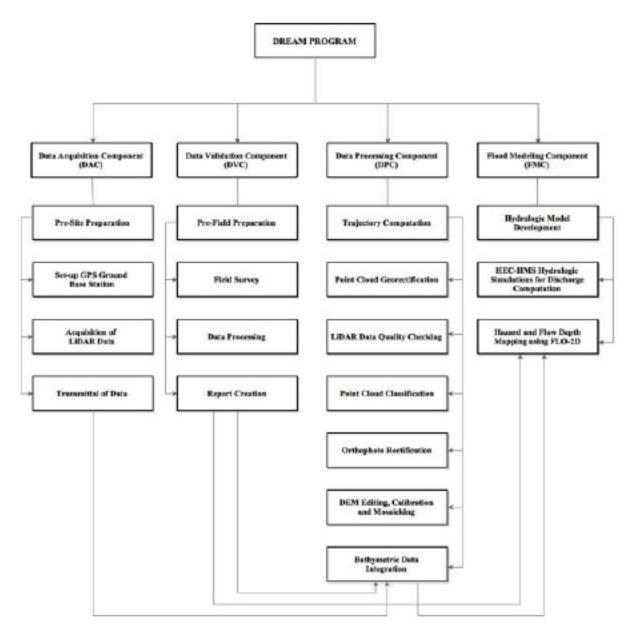


Figure 1. The General Methodological Framework of the Program





Study Area

The Pampanga River Basin is located in the Central Luzon Region. The Pampanga River Basin is considered as the fourth largest river basin in the Philippines. It is also considered as the second largest of Luzon's catchments, next to Cagayan River. It has an estimated basin area of 9,759 square kilometers. The location of Pampanga River Basin is as shown in Figure 2.

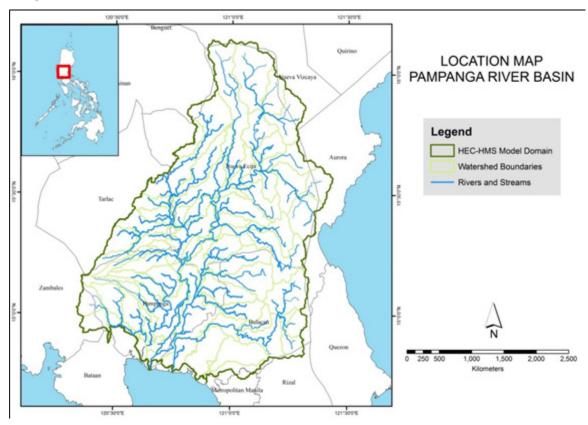


Figure 2. Pampanga River Basin Location Map

It traverses from the southern slopes of Caraballo Mountains, range of Sierra Madre, Central Plain of the Luzon Island to its mouth in Manila Bay via the Lanbangan Channel. It is supported by four tributaries namely: Penaranda River, Coronel-Santor River, Rio Chico River and Bagbag River. The river basin encompasses parts of the following provinces: Aurora, Bataan, Bulacan, Nueva Ecija, Nueva Vizcaya, Pampanga, Pangasinan, Rizal and some parts of the national capital region including Valenzuela, Caloocan, and Quezon City. The Pampanga River Basin serves as a source of water supply for the irrigation of Nueva Ecijia.

The land and soil characteristics are important parameters used in assigning the roughness coefficient for different areas within the river basin. The roughness coefficient, also called Manning's coefficient, represents the variable flow of water in different land covers (i.e. rougher, restricted flow within vegetated areas, smoother flow within channels and fluvial environments).

The shape files of the soil and land cover were taken from the Bureau of Soils, which is under the Department of Environment and Natural Resources Management, and National Mapping and Resource Information Authority (NAMRIA). The soil and land cover of the Pampanga River Basin are shown in Figures 3 and 4, respectively.

Study Area

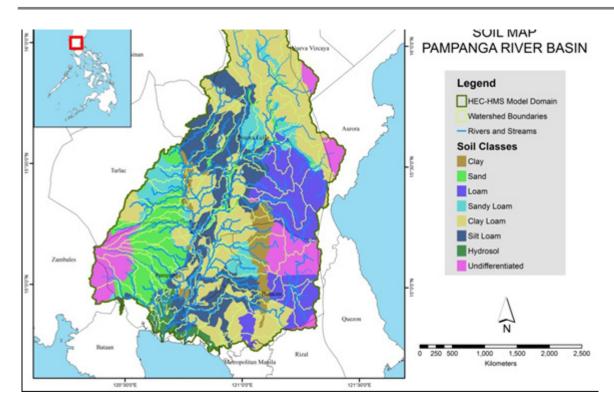


Figure 3. Pampanga River Basin Soil Map

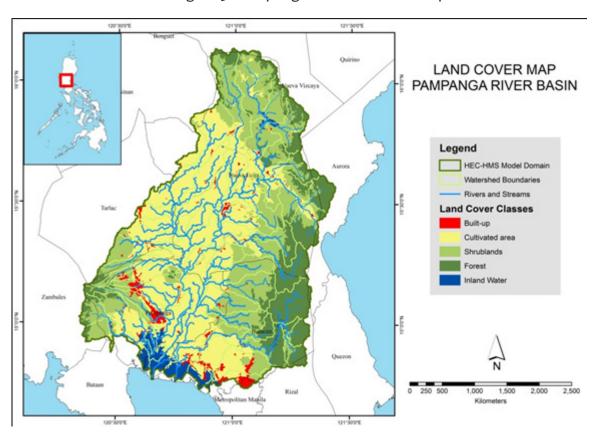


Figure 4. Pampanga River Basin Land Cover Map





3.1 Aquisition Methodology

The methodology employed to accomplish the project's expected outputs are subdivided into four (4) major components, as shown in Figure 5. Each component is described in detail in the following sections.

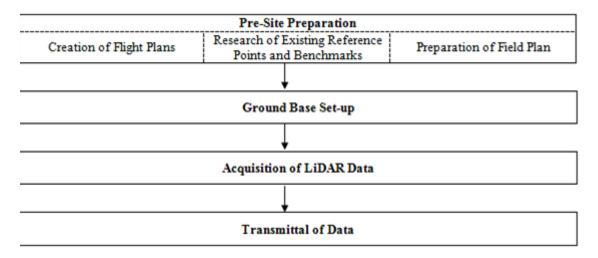


Figure 5. Flowchart of Project Methodology

3.1.1 Pre-Site Preparations

3.1.1.1 Creation of Flight Plans

Flight planning is the process of configuring the parameters of the aircraft and LiDAR technology (i.e., altitude, angular field of view (FOV)), speed of the aircraft, scans frequency and pulse repetition frequency) to achieve a target of two points per square meter point density for the floodplain. This ensures that areas of the floodplain that are most susceptible to floods will be covered. LiDAR parameters and their computations are shown in Table 1.

The parameters set in the LiDAR sensor to optimize the area coverage following the objectives of the project and to ensure the aircraft's safe return to the airport (base of operations) are shown in Table 1. Each flight acquisition is designed for four operational hours. The maximum flying hours for Cessna 206H is five hours.

Table 1. Computation of LiDAR parameter

SW (Swath Width)		SW = 2 * H * tan (θ/2)	H – altitude Θ – angular FOV
Pointing Space	ΔXacross	ΔXacross = (Θ * Η) / (Ncos2(Θ/2))	ΔXacross – point spacing across the flight line H – altitude Θ – angular FOV N – number of points in one scanning line
·	ΔXalong	ΔXalong = v / fsc	ΔXalong- point spacing along the flight line v – forward speed (m/s) fsc – scanning rate or scan frequency
Point density, dmin		dmin = 1 / (Δ Xacross * Δ X-along)	ΔXacross, ΔXalong point spacings
Flight line separation, e		e = SW * (1 – overlapping factor)	SW – swath width

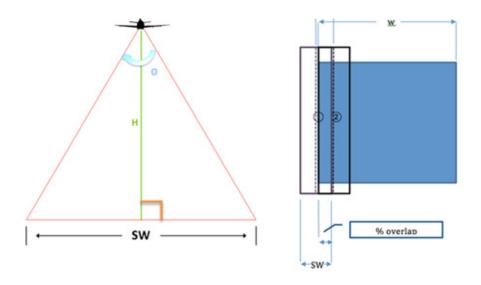


Figure 6. Concept of LiDAR data acquisition Parameters

The relationship among altitude, swath, and FOV is show in Figure 6. Given the altitude of the survey (H) and the angular FOV, the survey coverage for each pass (swath) can be calculated by doubling the product of altitude and tangent of half the field of view.

3.1.1.2 Collection of Existing Reference Points and Benchmarks

Collection of pertinent technical data, available information, and coordination with the National Mapping and Resource Information Authority (NAMRIA) is conducted prior to the surveys. Reference data collected includes locations and descriptions of horizontal and vertical control (elevation benchmarks) points within or near the project area. These control points are used as base stations for the aerial survey operations. Base stations are observed simultaneously with the acquisition flights.

3.1.1.3 Preparation of Field Plan

In preparation for the field reconnaissance and actual LiDAR data acquisition, a field plan is prepared by the implementation team. The field plan serves as a guide for the actual fieldwork and included personnel, logistical, financial, and technical details. Three major factors are included in field plan preparation: priority areas for the major river basin system; budget; and accommodation and vehicle rental.

LiDAR data are acquired for the floodplain area of the river system as per order of priority based on history of flooding, loss of lives, and damages of property. The order of priority in which LiDAR data surveys are conducted by the team for the floodplain areas of the 18 major river systems and 3 additional systems is shown in Table 2.

Table 2. List of Target River Systems

	Target River System	Location	Area of the River Sys- tem (km²)	Area of the Flood Plain (km²)	Area of the Watershed (km²)
1	Cagayan de Oro	Mindanao	1,364	25	1,338.51
1.1	Iponan	Mindanao	438	33	404.65
2	Mandulog	Mindanao	714	7	707.41
2.1	Iligan	Mindanao	153	7	146.38
2.2	Agus	Mindanao	1,918	16	1,901.60
3	Pampanga	Luzon	11,160	4458	6702
4	Agno	Luzon	6,220	1725	4495
5	Bicol	Luzon	3,173	585	2,587.79
6	Panay	Visayas	2,442	619	1823
7	Jalaur	Visayas	2,105	713	1,392
8	Ilog Hilbangan	Visayas	2,146	179	1967
9	Magasawang Tubig	Luzon	1,960	483	1,477.08
10	Agusan	Mindanao	11,814	262	11,551.62
11	Tagoloan	Mindanao	1,753	30	1,722.90
12	Davao	Mindanao	1,609	54	1555
13	Tagum	Mindanao	2,504	595	1,909.23
14	Buayan	Mindanao	1,589	201	1,388.21
15	Mindanao	Mindanao	20,963	405	20,557.53
16	Lucena	Luzon	238	49	189.31
17	Infanta	Luzon	1,029	90	938.61
18	Boracay	Visayas	43.34	43.34	N/A
19	Cagayan	Luzon	28,221	10386	17,835.14

3.1.2 Ground Base Set-up

A reconnaissance is conducted one day before the actual LiDAR survey for purposes of recovering control point monuments on the ground and site visits of the survey area set in the flight plan for the floodplain. Coordination meetings with the Airport Manager, regional DOST office, local government units and other concerned line government agencies are also held.

Ground base stations are established within 30-kilometer radius of the corresponding survey area in the flight plan. This enables the system to establish its position in three-dimensional (3D) space so that the acquired topographic data will have an accurate 3D position since the survey required simultaneous observation with a base station on the ground using terrestrial Global Navigation Satellite System (GNSS) receivers.

3.1.3 Acquisition of Digitial Elevation Data (LiDAR Survey)

Acquisition of LiDAR data is done by following the flight plans. The survey uses a LiDAR instrument mounted on the aircraft with its sensor positioned through a specially modified peep hole on the belly of the aircraft. The pilots are guided by the flight guidance software which uses the data out of the flight planning program with a mini-display at the pilot's cockpit showing the aircraft's real-time position relative to the current survey flight line. The reference points established by NAMRIA are also monitored and used to calibrate the data.

As the system collected LiDAR data, ranges and intensities are recorded on hard drives dedicated to the system while the images are stored on the camera hard drive. Position Orientation System (POS) data is recorded on the POS computer inside the control rack. It can only be accessed and downloaded via file transfer protocol (ftp) to the laptop computer. GPS observations were downloaded each day for efficient data management.

3.1.4 Transmittal of Acquired LiDAR Data

All data surrendered are monitored, inspected and re-checked by securing a data transfer checklist signed by the downloader (Data Acquisition Component) and the receiver (Data Processing Component). The data transfer checklist shall include the following: date of survey, mission name, flight number, disk size of the necessary data (LAS, LOGS, POS, Images, Mission Log File, Range, Digitizer and the Base Station), and the data directory within the server. Figure 7 shows the arrangement of folders inside the data server.

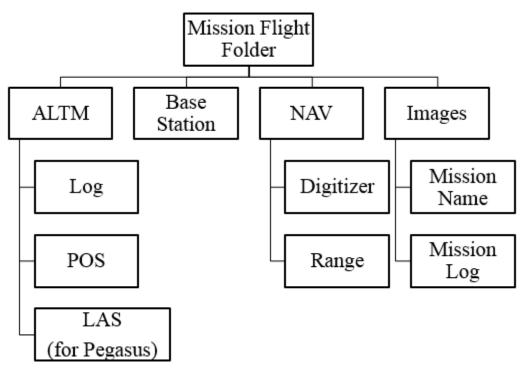


Figure 7. LiDAR Data Management for Transmittal

3.1.5 Equipment

3.1.5.1 ALTM Pegasus

The ALTM Pegasus (Optech, Inc) is a laser based system suitable for topographic survey (Figure 8). It has a dual output laser system for maximum density capability. The LiDAR system is equipped with an Inertial Measurement Unit (IMU) and GPS for geo-referencing of the acquired data (Annex A contains the technical specification of the system).

The camera of the Pegasus sensor is tightly integrated with the system. It has a footprint of 8,900 pixels across by 6,700 pixels along the flight line (Annex B contains the technical specification of the D-8900 aerial digital camera).

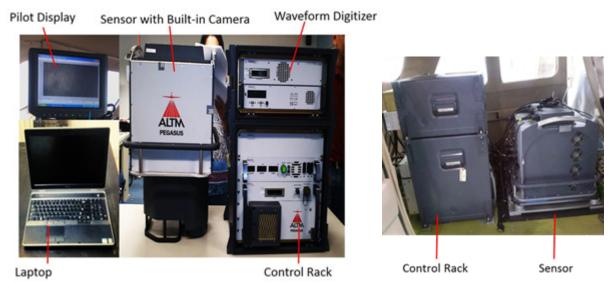


Figure 8. The ALTM Pegasus System: a) parts of the Pegasus system, b) the system as installed in Cessna T206H

3.1.5.1 ALTM Gemini

The ALTM Gemini is a laser based system suitable for topographic survey especially in high altitude areas with 16 kHz of effective laser rate. It has integrated camera and waveform digitizer. Image footprint has 8,900 pixels by 6,700 pixels along the flight line.



Figure 9. ALTM Gemini System

3.2 Processing Methodology

The schematic diagram of the workflow implemented by the Data Processing Component (DPC) is shown in Figure 10. The raw data collected by the Data Acquisition Component (DAC) is transferred to DPC. Pre-processing of this data starts with the computation of trajectory and georectification of point cloud, in which the coordinates of the LiDAR point cloud data are adjusted and checked for gaps and shifts, using POSPac, LMS, LAStools and Quick Terrain (QT) Modeler software.

The unclassified LiDAR data then undergoes point cloud classification, which allows cleaning of noise data that are not necessary for further processing, using TerraScan software. The classified point cloud data in American Standard Code for Information Interchange (ASCII) format is used to generate a data elevation model (DEM), which is edited and calibrated with the use of validation and bathymetric survey data collected from the field by the Data Validation and Bathymetry Component (DVBC). The final DEM is then used by the Flood Modeling Component (FMC) to generate the flood models for different flooding scenarios.

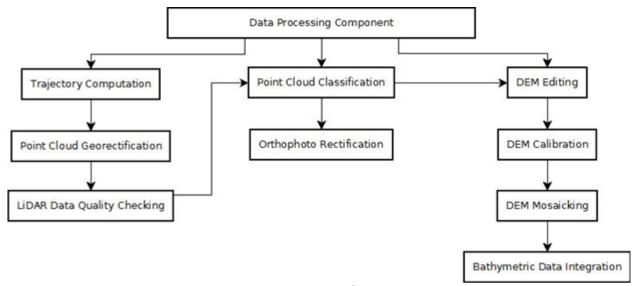


Figure 10. Schematic diagram of the data processing

3.2.1 Data Transfer

The Pampanga mission, named 2P3C2005A, was flown with the Airborne LiDAR Terrain Mapper (ALTM™ Optech Inc.) by Gemini system on January 18, 2013. The Data Acquisition Component (DAC) transferred 14.0 Gigabytes of Range data, 265 Megabytes of POS data, 7.38 Megabytes of GPS base station data, and 36.8 Gigabytes of raw image data to the data server on May 29, 2014.

3.2.2 Trajectory Computation

The trajectory of the aircraft is computed using the software POSPac MMS v6.2. It combines the POS data from the integrated GPS/INS system installed on the aircraft, and the Rinex data from the GPS base station located within 25 kilometers of the area. It then computes the Smoothed Best Estimated Trajectory (SBET) file, which contains the best estimated trajectory

of the aircraft, and the Smoothed Root Mean Square Estimation error file (SMRMSG), which contains the corresponding standard deviations of the position parameters of the aircraft at every point on the computed trajectory.

The key parameters checked to evaluate the performance of the trajectory are the Solution Status parameters and the Smoothed Performance Metrics parameters. The Solution Status parameters characterize the GPS satellite geometry and baseline length at the time of acquisition, and the processing mode used by POSPac. The acceptable values for each Solution Status parameter are shown in Table 3.

The Smoothed Performance Metrics parameters describe the root mean square error (RMSE) for the north, east and down (vertical) position of the aircraft for each point in the computed trajectory. A RMSE value of less than 4 centimeters for the north and east position is acceptable, while a value of less than 8 centimeters is acceptable for the down position.

Table 3. Solution Status Parameters in POSPac MMS v6.2.

Parameter	Optimal Values	
Number of satellites	More than 6 satellites	
Position Dilution of Precision	Less than 3	
Baseline Length	Less than 30 km	
Processing mode	Less than or equal to 1, however short burt- sts of values greater than 1 are acceptable	

3.2.3 LiDAR Point Cloud Rectification

The trajectory file (SBET) and its corresponding accuracy file (SMRMSG) generated in POSPac are merged with the Range file to compute the coordinates of each individual point. The coordinates of points within the overlap region of contiguous strips vary due to small deviations in the trajectory computation for each strip. These strip misalignments are corrected by matching points from overlapping laser strips. This is done by the Lidar Mapping Suite (LMS) software developed by Optech.

LMS is a LiDAR software package used for automated LiDAR rectification. It has the capability to extract planar features per flight line and to form correspondence among the identical planes available in the overlapping areas (illustrated in Figure 11). In order to produce geometrically correct point cloud, the redundancy in the overlapping areas of flight lines is used to determine the necessary corrections for the observations.

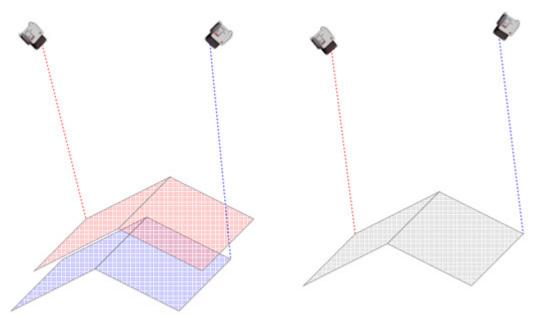


Figure 11. Misalignment of a single roof plane from two adjacent flight lines, before rectification (left). Least squares adjusted roof plane, after rectification (right).

The orientation parameters are corrected in LMS by using least squares adjustment to obtain the best-fit parameters and improve the accuracy of the LiDAR data. The primary indicators of the LiDAR rectification accuracy are the standard deviations of the corrections of the orientation parameters. These values are seen on the Boresight corrections, GPS position corrections, and IMU attitude corrections, all of which are located on the LMS processing summary report. Optimum accuracy is obtained if the Boresight and IMU attitude correction standard deviations are less than 0.001°, and if the GPS position standard deviations are below 0.01 m.

3.2.4 LiDAR Data Quality Checking

After the orientation parameters are corrected and the point cloud coordinates are computed, the entire point cloud data undergoes quality checking, to see if: (a) there are remaining horizontal and vertical misalignments between contiguous strips, and; (b) to check if the density of the point cloud data reach the target density for the site. The LAStools software is used to compute for the elevation difference in the overlaps between strips and the point cloud density. It is a software package developed by Rapidlasso GmbH for filtering, tiling, classifying, rasterizing, triangulating and quality checking Terabytes of LiDAR data, using robust algorithms, efficient I/O tools and memory management. LAStools can quickly create raster representing the computed quantities, which provide guiding images in determining areas where further quality checks are necessary. The target requirements for floodplain acquisition, computed by LAStools, are shown in Table 4.

Table 4. Parameters investigated during quality checks

Criteria	Requirement
Minimum per cent overlap	25%
Average point cloud density per square meter	2.0
Elevation difference between strips (on flat areas)	0.20 meters

LAStools can provide guides where elevation differences probably exceed the 20 centimeters limit. An example of LAStools output raster visualizing points in the flight line overlaps with a vertical difference of +/- 20 centimeters (displayed as dense red/blue areas) is shown in Figure 12.

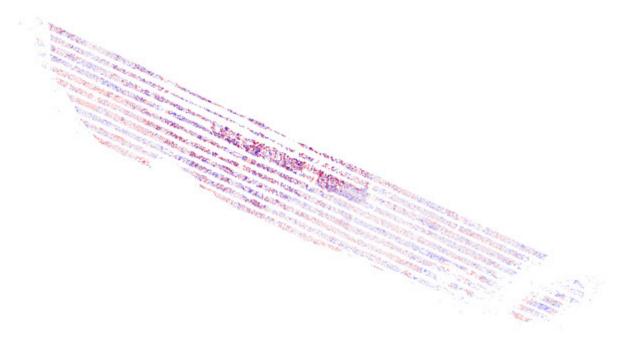


Figure 12. Elevation difference between flight lines generated from LAStools

To investigate the occurrences of elevation differences in finer detail, the profiling tool of Quick Terrain Modeler software is used. Quick Terrain Modeler (QT Modeler) is a 3D point cloud and terrain visualization software package developed by Applied Imagery, Inc. The profiling capability of QT Modeler is illustrated in Figure 13.

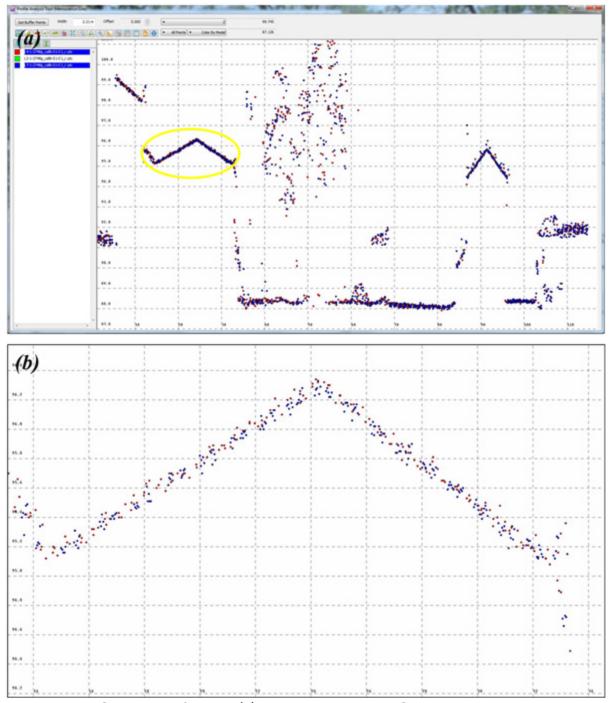


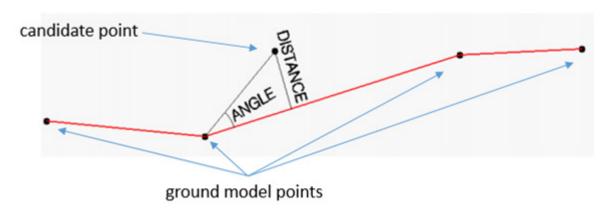
Figure 13. Profile over roof planes (a) and a zoomed-in profile on the area encircled in yellow

The profile (e.g., over a roof plane) shows the overlapping points from different flight lines which serve as a good indicator that the correction applied by LMS for individual flight lines is good enough to attain the desired horizontal and vertical accuracy requirements. Flight lines that do not pass quality checking are subject for reprocessing in LMS until desired accuracies are obtained.

3.2.5 LiDAR Point Cloud Classification and Rasterization

Point cloud classification commences after the point cloud data has been rectified. TerraScan is a TerraSolid LiDAR software suite used for the classification of point clouds. It can read airborne and vehicle-based laser data in raw laser format, LAS, TerraScan binary or other ASCII-survey formats. Its classification and filtering routines are optimized by dividing the whole data into smaller geographical datasets called blocks, to automate the workflow and increase efficiency. In this study, the blocks were set to 1 kilometer by 1 kilometer with a 50 m buffer zone to prevent edge effects.

The process includes the classification of all points into Ground, Low Vegetation, Medium Vegetation, High Vegetation and Buildings. The classifier tool in TerraScan first filters air points and low points by finding points that are 5 standard deviations away from the median elevation of a search radius, which is 5 meters by default. It then divides the region into 60m by 60m search areas (the maximum area where at least one laser point hits the ground) and assigns the lowest points in these areas as the initial ground points from which a triangulated ground model is derived. The classifier then iterates through all the points and adds the points to the ground model by testing if it is (a) within the maximum iteration angle of 4° by default from a triangle plane, and (b) if it is within the maximum iteration distance (1.2 m by default) from a triangle plane. The ground plane is continuously updated from these iterations. The ground classification technique is illustrated in Figure 14. It is apparent that the smaller the iteration angle, the less eager the classifier is to follow changes in the point cloud (small undulations in terrain or hits on low vegetation). An angle close to 4° is used in flat terrain areas while an angle of 10° is used in mountainous or hilly terrains.

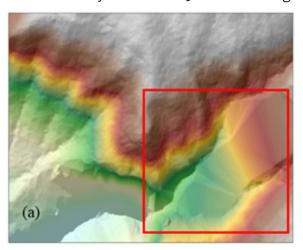


The parameters for ground classification routines used in floodplain and watershed areas are listed in Table 5.

Table 5. Ground classification parameters used in Terrascan for floodplain and watershed areas

Classification maximums	Floodplain (default)	Watershed (adjusted)
Iteration angle (degrees)	4	8
Iteration distance (meters)	1.20	1.50

The comparison between the produced DTM using the default parameters versus the adjusted is shown in Figure 15. The default parameters may fail to capture the sudden change in the terrain, resulting to less points being classified as ground that makes the DTM interpolated (Figure 15a). The adjusted parameters works better in these spatial conditions as shown in Figure 15b. Statistically, the number of ground points and model key points correctly classified can increase by as much as 50% when using the adjusted parameters.



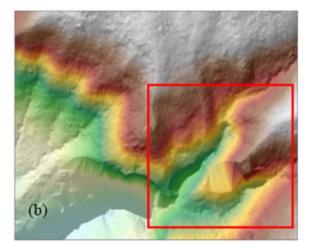


Figure 15. Resulting DTM of ground classification using the default parameters (a) and adjusted parameters (b)

The classification to Low, Medium and High vegetation is a straightforward testing of how high a point is from the ground model. The range of elevation values and its corresponding classification is shown in Table 6.

Table 6. Classification of vegetation according to the elevation of points

Elevation of points	Classification	
(meters)		
0.05 to 0.15	Low Vegetation	
0.15 to 2.50	Medium Vegetation	
2.50 to 50.0	High Vegetation	

The classification to Buildings routine tests points above 2 meters if they only have one echo, and if they form a planar surface of at least 40 square meters with points adjacent to them. Minimum size and Z tolerance are the parameters used in the classify buildings routine as shown in Figure 16.

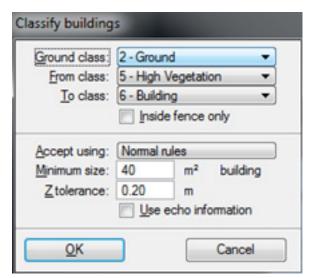


Figure 16. Default TerraScan building classification parameters

Minimum size is set to the smallest building footprint size of 40 square meters while the Z tolerance of 20 centimeters is the approximate elevation accuracy of the laser points.

The point cloud data are examined for possible occurrences of air points which are to be deleted manually in the TerraScan window. Air points are defined as groups of points which are significantly higher or lower from the ground points. The different examples of air points are shown in Figure 17.

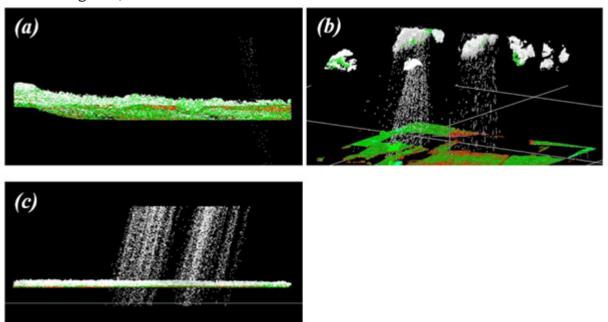


Figure 17. Different examples of air points manually deleted in the TerraScan window

The noise data can be as negligible as shown in Figure 17a or can be as severe as the one shown in Figure 17c. A combination of cloud points and shower of short ranges is displayed in Figure Figure 17b. Shower of short ranges are caused by signal interference from the radio transmission of the tower and the aircraft. During every transmission on a specific frequency (around 120 MegaHertz), the signal is getting distorted due to the interference causing showers of short ranges in the output LAS.

Classified LiDAR point clouds that are free of air points, noise and unwanted data are processed in TerraScan to produce Digital Terrain Model (DTM) and the corresponding first and last return Digital Surface Models (DSM). These ground models are produced in ASCII format.

DTMs are produced by rasterizing all points classified to ground and model key points in a 1 m by 1 m grid. The last return DSMs are produced by rasterizing all last returns from all classifications (Ground, Model Key Points, Low, Medium, High Vegetation, Buildings and Default) in a 1 m by 1 m grid. The first return DSMs on the other hand are produced by rasterizing all first returns from all classifications. Power lines are usually included in this model. All of these ground models are used in the mosaicking, manual editing and hydro correction of the topographic dataset, in preparation for the floodplain hydraulic modelling.

3.2.6 DEM Editing and Hydro-correction

Even though the parameters of the classification routines are optimized, various digital elevation models (DTM, first and last return DSM) that are automatically produced may still display minor errors that still need manual correction to make the DEMs suitable for fine-scale flood modelling. This is true especially for features that are under heavy canopy. Natural embankments on the side of the river might be flattened or misrepresented because no point pierced the canopy on that area. The same difficulty might also occur on smaller streams that are under canopy. The DTM produced might have discontinuities on these channels that might affect the flood modelling negatively. Manual inspection and correction is still a very important part of quality checking the LiDAR DEMs produced.

To correctly portray the dynamics of the flow of water on the floodplain, the river geometry must also be taken into consideration. The LiDAR data must be made consistent to the topographic surveys done for the area, and the bathymetric data must be "burned" into the DEM to make the dataset suitable for hydraulic analyses. For more information on how the topographic and bathymetric data was obtained and processed, the reader is referred to DREAM technical report entitled "Report on the Profile, Cross Section, Bathymetric Surveys and Flow Measurements in Pampanga River", which was prepared by the DREAM Data Validation Component.





4.1 LiDAR Acquisition in Pampanga Floodplains

4.1.1 Flight Plans

Plans were made to acquire LiDAR data within the floodplains. Each flight mission had an average of ten to twelve (10-12) flight lines and ran for at most 4 hours including take-off, landing and turning time. The parameter used in the LiDAR system for acquisition is found in Table 7.

Table 7. Parameters used in LiDAR System during Flight Acquisition

Fixed Variables		Values	
Flying Height (AGL - Above Ground Level) (m)	750	1000	1200
Overlap	30 %	30 %	30 %
Max. field of View (θ)	50	50	50
Speed of Plane (kts)	130	130	130
Turn around minutes	5	5	5
Swath (m)	661.58m	882m	1058.53m

The parameters that set in the LiDAR sensor to optimize the area coverage following the objectives of the project and to ensure the aircraft's safe return to the airport (base of operations) are shown in Table 7. Each flight acquisition is designed for four operational hours. The maximum flying hours for Cessna 206H is five hours.

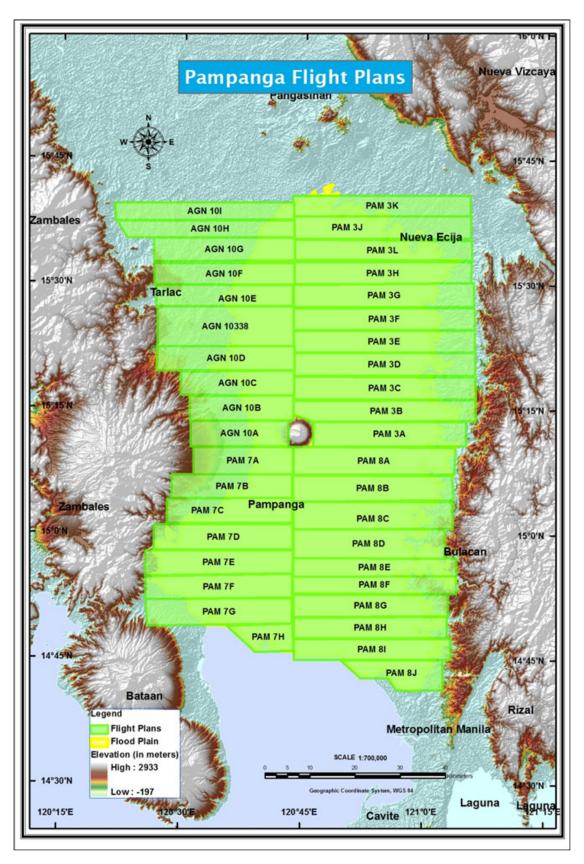


Figure 18. Pampanga floodplain flight plans

4.1.2 Ground Base Station

The project team was able to recover four (4) NAMRIA control stations; TRC-1 with first (1st) order and NEJ-3060, NEJ-3332 and PMG-3148 with fourth (4th) order accuracies. The team also established four ground control points, namely, FMC-1, AAC-1, BM-5A and PAM 7-1. The ground control point (GCPs) was used as reference point during flight operations using TRIM-BLE SPS R8, a dual frequency GPS receiver.

Table 8. Details of TRC-1 used as base station for the LiDAR acquisition

Station Name	TRC- 1				
Order of Accuracy	ıst				
Relative Error (horizontal positioning)	1 in 100,000				
Geographic Coordinates,	Latitude	15° 28' 44.13765"			
Philippine Reference of 1992	Longitude	120° 35' 52.67202"			
Datum (PRS 92)	Ellipsoidal height	46.89100 meters			
Grid Coordinates, Philippine Transverse Mercator Zone 5 (PTM	Easting	456,859.89 meters			
Zone 5 PRS 92)	Northing	1,711,833.357 meters			
Geographic Coordinates, World	Latitude	15° 28' 38.48550" North			
Geodetic System 1984 Datum	Longitude	120° 35' 57.49329'' East			
(WGS 84)	Ellipsoidal height	88.90220 meters			
Grid Coordinates, Universal Transverse Mercator Zone 51 North	Easting	242 , 278 . 30 meters			
(UTM 51N WGS 1984)	Northing	1,712,636.20 meters			

Table 9. Details of PMG-3148 used as base station for the LiDAR acquisition

Station Name	P	MG-3148			
Order of Accuracy	4th				
Relative Error (horizontal positioning)	1 in 100,000				
Geographic Coordinates,	Latitude	15° 1' 19.45298''			
Philippine Reference of 1992	Longitude	120° 51' 27.34493''			
Datum (PRS 92)	Ellipsoidal height	11.08000 meters			
Grid Coordinates, Philippine Transverse Mercator Zone 5 (PTM Zone	Easting	484,686.479 meters			
5 PRS 92)	Northing	1,661,251.527 meters			
Geographic Coordinates, World	Latitude	15° 1' 13.92611'' North			
Geodetic System 1984 Datum (WGS	Longitude	120° 51' 31.20370'' East			
84)	Ellipsoidal height	53.05900 meters			
Grid Coordinates, Universal Transverse Mercator Zone 51 North	Easting	269,649.32 meters			
(UTM 51N WGS 1984)	Northing	1,661,781.75 meters			

Table 10. Details of NEJ-3332 used as base station for the LiDAR acquisition.

Table 101 Details of 1125 35552 asea as base station for the Library acquisition.									
Station Name	NEJ-3332								
Order of Accuracy	4th								
Relative Error (horizontal positioning)	1 in 100,000								
Geographic Coordinates,	Latitude	15° 32' 42.98257"							
Philippine Reference of 1992	Longitude	120° 49' 9.35425''							
Datum (PRS 92)	Ellipsoidal height	27.14780 meters							
Grid Coordinates, Philippine Transverse Mercator Zone 5 (PTM Zone 5	Easting	480,612.682 meters							
PRS 92)	Northing	1,719,141.792 meters							
	Latitude	15° 32' 77.33289" North							
Geographic Coordinates, World Geodetic System 1984 Datum (WGS 84)	Longitude	120° 49' 14.16885'' East							
detic system 1904 Datum (WGS 04)	Ellipsoidal height	67.50000 meters							
Grid Coordinates, Universal Transverse Mercator Zone 51 North (UTM	Easting	266,107.50 meters							
51N WGS 1984)	Northing	1,719,725.18 meters							

Table 11. Details of NEJ-3060 used as base station for the LiDAR acquisition

Table 111 because of 1125 Jose abea as base station for the 2157 in acquisition									
Station Name	NEJ-3060								
Order of Accuracy	4th								
Relative Error (horizontal positioning)	1 in 100,000								
Geographic Coordinates,	Latitude	15° 19' 32.78238''							
Philippine Reference of 1992	Longitude	120° 53' 29.45676''							
Datum (PRS 92)	Ellipsoidal height	21.54500 meters							
Grid Coordinates, Philippine Transverse Mercator Zone 5 (PTM Zone 5	Easting	488,350.739 meters							
PRS 92)	Northing	1,694,850.752 meters							
	Latitude	15° 19' 27.18854" North							
Geographic Coordinates, World Geodetic System 1984 Datum (WGS 84)	Longitude	120° 53' 34.28956'' East							
detic system 1984 Datum (WGS 84)	Ellipsoidal height	62.72000 meters							
Grid Coordinates, Universal Transverse Mercator Zone 51 North (UTM	Easting	273,621.71 meters							
51N WGS 1984)	Northing	1,695,355.91 meters							

Table 12. Details of established Ground Control Points by Data Acquisition Component for Li-DAR survey in Pampanga Floodplain

Point Name	Location	WGS '84 C	Coordinates	Ellipsoidal height
Ivanic		Latitude	Longitude	(in meters)
AAC-1	AAC Hangar, Clark, Pampanga	15° 11' 21.26316	120° 32' 50.12046	187.627
BM 5A	Guagua, Pampanga	14° 52' 47.37638	120° 35' 44.23254	47.642
FMC-1	FMC Hospital, Pulilan, Bulacan	14° 54' 23.45769	120° 52' 09.88011	54.87
PAM 7-1	Porac, Pampanga	15° 03' 43.45809	120° 37' 58.66334	86.681



Figure 19. Ground Base Station Observation at FMC-1 established in front of F.M. Cruz Orthopedic Hospital in Pulilan, Bulacan



Figure 20. Ground Base Station Observation at AAC-1 established inside Asian Aerospace Corporation Hangar at Clark International Airport in Pampanga

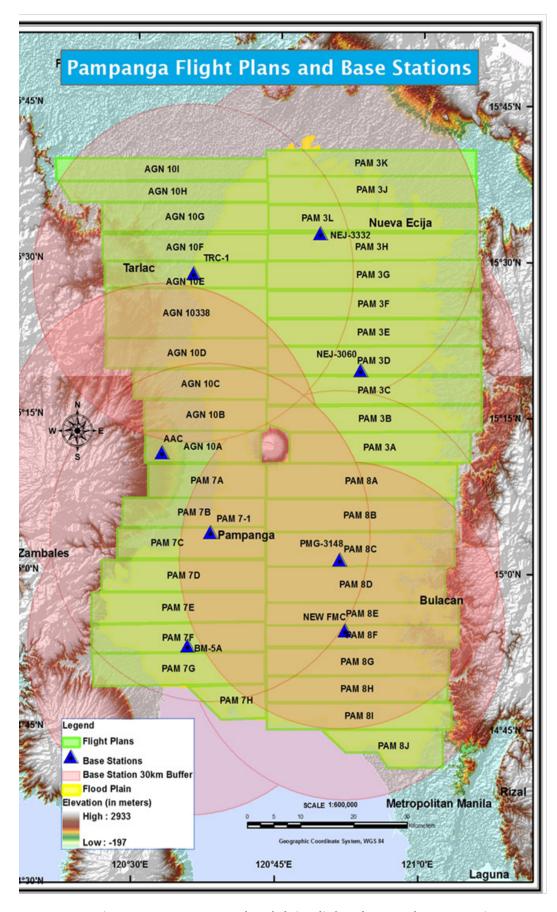


Figure 21. Pampanga Floodplain Flight Plans and Base Stations

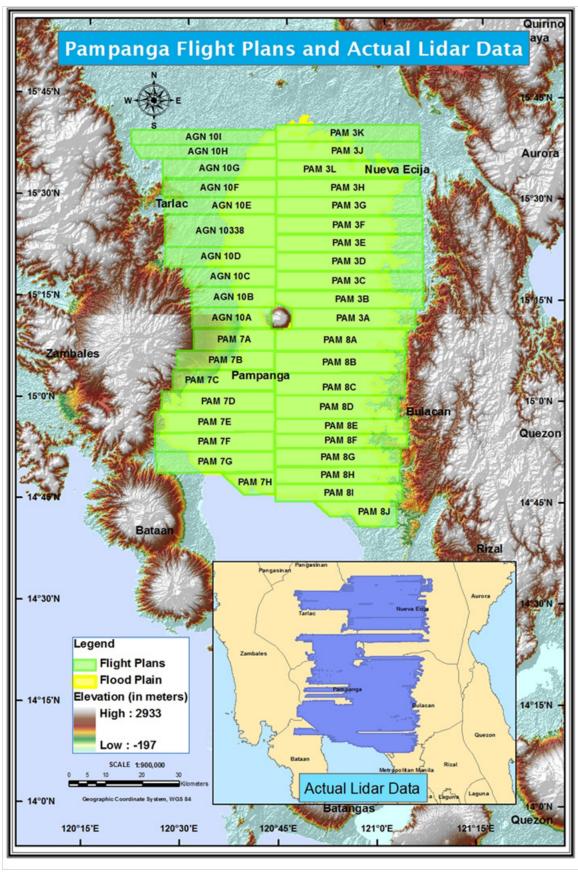


Figure 22. Pampanga Floodplain Data Acquisition Coverage



Table 13. Flight Missions for LiDAR Data Acquisition in Pampanga Floodplain

Date Surveyed	Name	Flight Plan Area (km2)	Surveyed Area (km2)	Area Surveyed within the River Systems (km2)	Area Surveyed Outside the River Systems (km2)	No. of Images (Frames)	Flying	
							Hours	Mins
Nov 29,2012	Pam 8A					746	3	12
Nov 30,2012		226.61	237.52	237.52	0	256	2	4
Feb 20,2013	Pam 8AS					no data	3	34
Dec 1, 2012	Pam 8B	217.16	223.16	223.16	0	no camera data	3	40
Feb 20,2013	Pam 8BS					no data	3	5
Dec 6,2012						no data	1	44
Dec 10,2012	Pam 8C	227	205.56	205.56	0	973	3	19
Dec 10,2012	Faiii oC	227	205.50	205.50	O	no data	1	44
Dec 13,2012						409	3	13
Dec 11,2012						no data	2	48
Dec 11,2012	Pam 8D	. 228.51	235.86	235.86	0	no camera data	3	41
Feb 25,2013	Pam 8CS (Pam8D)	220.51	255.00	255.00		527	3	0
Feb 25,2013	Pam 8CS (Pam8D)					510	2	43
Dec 15,2012	Pam 8E	139.9	141.68	141.68	0	561	2	45
Dec 17,2012	Pam 8F	153.03	158.11	158.11	0	201	2	10
Dec 20,2012	1 0111 01	رن،رور ا	150.11	150.11		770	3	20
Dec 13,2012	Pam 8G1					642	3	9
Dec 14,2012	Pam 8G2	184.1	182.67	182.67	0	783	3	45
Feb 25,2013	Pam 8DS (Pam 8G)	104.1	2, 2,	2.27		559	2	55
Dec 14,2012	Pam 8H1	175.14	126.92	126.92	0	no camera data	3	25
Dec 15,2012	Pam 8H2					696	3	12

Table 13, cont'd

Date Surveyed	Name	Flight Plan Area (km2)	Surveyed Area (km2)	Area Surveyed within the River Systems (km2)	Area Surveyed Outside the River Systems (km2)	No. of Images (Frames)		Hours
Dec 20,2012	Pam 3A					792	Hours 3	Mins 0
Jan 5,2013	Pam 3A		_	_		824	3	37
Feb 27,2013	Pam 3DS (Pam 3A)		163.41	163.41	0	no data	4	0
Dec 21,2012	Pam 3B					no data	2	0
Jan 2,2013	Pam 3B		95.138	95.138	О	948	1	0
Jan 3,2013	Pam 3B]				758	3	20
Dec 21,2012	Pam 3C1	245.00	22440	22440	0	1,182	3	16
Jan 5,2013	Pam 3C2	215.98	234.19	234.19	0	611	3	16
Jan 2,2013	Pam 3D		219.22	219.22		88	4	6
Feb 27,2013	Pam 3CS (Pam 3D)				0	28	1	30
Jan 4,2013	Pam 3E	200.47	124.06	124.06	0	782	4	0
Jan 5,2013	Pam 3E	209.17	17 131.06	131.06		376	2	37
Dec 21,2012	Pam 3F					no data	4	20
Feb 27,2013	Pam 3BS (Pam 3F)	209.13	228.19	228.19	0	449	3	5
Dec 28,2012	Pam 3G1]				889	3	1
Dec 29,2012	Pam 3G2	227.33	245.76	245.76	0	no camera data	1	28
Jan 5,2013	Pam 3G2	/-	15.75	- 15.7 -		no data	1	40
Jan 7,2013	Pam 3G2]				no data	0	20
Jan 8,2013	Pam 3G2					889	2	55
Dec 29,2012	Pam 3H					no data	2	15
Dec 29,2012	Pam 3H	207.41	221.31	221.31	0	no camera data	3	0
Feb 27,2013	Pam 3AS (Pam 3H)					685	3	18



Table 13, cont'd

Date Surveyed	Name	Flight Plan Area (km2)	Surveyed Area (km2)	Area Surveyed within the River Systems (km2)	Area Surveyed Outside the River Systems (km2)	No. of Images (Frames)	Flying		
_							Hours	Mins	
Jan 7,2013	Pam 3l1	184.34	190.48	190.48	0	904	3	3	
Jan 8,2013	Pam 3l2					1,476	3	11	
Jan 7,2013	Pam 3J	211.92	233.48	233.48	0	781	3	45	
Jan 8,2013	Pam 3K	198.94	196.36	196.36	0	865	3	55	
Feb 12,2013	Pam 7A1	140.69	156.98	156.98	0	452	3	5	
Feb 14,2013	Pam 7A2	140103	.,,,,,,	.,,,,,,	0	356	2	55	
Feb 14,2013	Pam 7B1	148.6	106.54	106.54	0	444	3	20	
Feb 15,2013	Pam 7B2	140.0	100.54	100.54	0	402	3	24	
Feb 13,2013	Pam 7C					354	2	20	
Feb 13,2013	Pam 7C	163.22	110.99	110.99	0	no camera data	1	18	
Feb 16,2013	Pam 7C					113	1	34	
Feb 18,2013	Pam 7C					414	2	45	
Jan 8,2013	Pam 7D	183.78	117.88	117.88	0	447	2	48	
Feb 16,2013	Pam 7E	195.48	194.35	194.35	0	687	3	7	
Jan 9,2013	Pam 7F1					314	2	33	
Jan 9,2013	Pam 7F2	194.3	159.54	159.54	6.97	418	2	51	
Feb 18,2013	Pam 7G	208.47	194.57	194.57	71.7	702	3	5	
Jan 9,2013	Pam 7H	94.991	76.081	76.081	20.08	621	3	40	
Dec 3,2012	Agno 10 338	242.88	25 526	25 526	0	187	2	6	
Dec 3,2012	Agno 10 338	242.00))·) ²⁰	35.526	35.526	U	592	2	36
Feb 15,2013	Agno 10A	127.16	137.82	137.82	0	522	2	55	
Feb 15,2013	Agno 10B	136.13	146.63	146.63	0	477	2	53	
Feb 14,2013	Agno 10C	141.64	142.22	142.22		496	2	55	
Feb 15,2013	Agno 10 D1	172.82	123.32	123.32	0	379	2	53	
Jan 10,2013	Agno 10E	139.07	18.618	18.618	0	1,062	4	6	
Jan 10,2013	Agno 10F	155.56	160.71	63.744	96.966	no camera data	2	38	

Table 13, cont'd

Date Surveyed	Name	Flight Plan Area (km2)	Surveyed Area (km2)	Area Surveyed within the River Systems (km2)	Area Surveyed Outside the River Systems (km2)	No. of Images (Frames)	Flying	
					, ,		Hours	Mins
Jan 10,2013	Agno 10 G1					713	2	35
Jan 10,2013	Agno 10 G2	171.27	171.27 197.4	47.059	150.341	no camera data	2	40
Jan 11,2013	Agno 10H	159.99	150.1	28.18	121.92	no camera data	2	40
Feb 18,2013	Agno 10l1					728	3	0
Jan 11,2013	Agno 10l2	177.4	171.32	11.258	160.062	no camera data	3	19
Mar 4,2013	Mt. Arayat	87.817	0	0	0	no data	2	0
Feb 20,2013	No Area	0	0	0	0	no data	0	20
						Total fly- ing hours	227.7	7 hrs

Eighty (80) missions were conducted to complete the LiDAR Data Acquisition in Pampanga floodplain, for a total of two hundred twenty eight hours (228) of flying time for RP-C9022 and RP-C9122. All missions were acquired using both the Pegasus and Gemini LiDAR System. The total area to be surveyed according to the flight plan and the total area of actual coverage per mission is shown in Table 13.

Pampanga floodplain with a total of four thousand four hundred fifty eight (4,458) square kilometers was surveyed from December 3, 2013-February 28, 2013 by James Novilla, Iro Roxas, Christopher Cruz, Lovely Gracia Acuna, Mark Gregory Ano and Jasmine Alviar as shown in Table 14.

Table 14. Area of Coverage of the LiDAR Data Acquisition in Pampanga floodplain

Location	Date Surveyed	Operator	Mission Name	Floodplain Surveyed Area (km²)	Total Floodplain Area (km²)	Water- shed Suveyed Area (km²)	Total Water- shed Area (km²)
	Nov 30,2012	JAMES NOVILLA	PAM8A				
Ą.	Nov 30,2012	JAMES NOVILLA	PAM8A	203.696		33.824	
ANG	Feb 20,2013	IRO ROXAS	2P8AS051A		4,458		(702
PAMPANGA	Dec 1,2012	IRO ROXAS	РАМ8В	188.462		34.698	6,702
₹	Dec 6, 2012	CHRISTOPHER CRUZ	1P8C3342A	169.097			
	Dec 10, 2012	LOVELY ACUÑA	2P8C345A	168.987		36.573	

Table 14, cont'd

14510 14,	1	100000	1	1		1				
	Dec 10, 2012	JAMES NOVILLA	2P8C345B							
	Dec 13, 2012	JAMES NOVILLA	2P8C348A	168.987		36.573				
	Feb 25, 2013	MARK GREGORY AÑO	1P8C056A	100.907		30.5/3				
	Feb 25, 2013	JASMINE ALVIAR	1P8Co56B							
	Dec 11, 2012	CHRISTOPHER CRUZ	1P8D346A							
	Dec 11, 2012	JAMES NOVILLA	2P8D346A							
	Feb 25, 2013	MARK GREGORY AÑO	1P8CS056A	176.487		59.373				
	Feb 25, 2013	JASMINE ALVIAR	1P8CS056B			27.111				
<	Dec 15, 2012	CHRISTOPHER CRUZ	1P8E350B	114.569						
PAMPANGA	Dec 17, 2012	CHRISTOPHER CRUZ	1P8F352A	A 4,458			6,702			
PAN	Dec 20, 2012	MARK GREGORY AÑO	1P8F355A	105.599			52.511			
	Dec 13, 2012	LOVELY ACUÑA	2P8GI348B							
	Dec 14, 2012	JAMES NOVILLA	2P8G349A	146.16		36.51				
	Feb 25, 2013	LOVELY ACUÑA	2P8DS056A							
	Dec 14, 2012	IRO ROXAS	2P8H349B	101.323		25.597				
	Dec 15, 2012	IRO ROXAS	2P8h2350A]						
	Dec 17, 2012	IRO ROXAS	2P81352B							
	Dec 19, 2013	IRO ROXAS	2P8l1354B	151.208		26.242				
	Feb 25, 2013	IRO ROXAS	2P8FS056B							
	Dec 20, 2013	JAMES NOVILLA	2P8J355A	71.237		0				
	Jan 5, 2013	MARK GREGORY AÑO	1P3ANoo5A	126.874		36.536				

Table 14, cont'd

Location	Date Surveyed	Operator	Mission Name	Floodplain Surveyed Area (km²)	Total Floodplain Area (km²)	Water- shed Suveyed Area (km²)	Total Water- shed Area (km²)
	Dec 21, 2012	CHRISTOPHER CRUZ	1P3B356B				
	Jan 2, 2013	CHRISTOPHER CRUZ	1P3B002B	85.092		10.046 76.588	
	Jan 3, 2013	JASMINE ALVIAR	1P3B003A				
	Dec 21, 2012	JAMES NOVILLA	2P3C356B	157.602			
	Jan 5, 2013	IRO ROXAS	2P3C2005A				
	Jan 2, 2013	MARK GREGORY AÑO	1P3D002A	158.003		61.217	
	Feb 27, 2013	IRO ROXAS	2P3D058A				6,702
	Feb 27, 2013	JASMINE ALVIAR	1P3CS058A		4,458	32.559 56.299	
	Jan 4, 2013	IRO ROXAS	1P3E004A	98.501			
	Jan 5, 2013	JASMINE ALVIAR	1P3E005B				
PAMPANGA	Dec 21, 2012	MARK GREGORY AÑO	1P3F363A	171.891			
PAM	Feb 27, 2013	LOVELYN ASUNCION	2P3BS058B				
	Dec 28, 2012	IRO ROXAS	2P3G1B			64.815	
	Dec 29, 2012	LOVELY ACUÑA	2Pam3G2				
	Jan 5, 2013	CHRISTOPHER CRUZ	1P3G2005B	180.945			
	Jan 7, 2013	CHRISTOPHER CRUZ					
	Jan 8, 2013	LOVELY ACUÑA	2P3G2008B				
	Dec 29, 2012	CHRISTOPHER CRUZ	1P3H364A	179.324		41.986	
	Dec 29, 2012	IRO ROXAS	1P3H364B				
	Feb 27, 2013	MARK GREGORY AÑO	1P3AS058B	427.00		52.52	
	Jan 7, 2013	LOVELY ACUÑA		137.96			
	Jan 8, 2013	IRO ROXAS	2P3I2008A				

Table 14, cont'd

Location	Date Surveyed	Operator	Mission Name	Floodplain Surveyed Area (km²)	Total Flood- plain Area (km²)	Water- shed Suveyed Area (km²)	Total Water- shed Area (km²)	
	Jan 7, 2013	JASMINE ALVIAR	1P3J007A	105.74		127.74		
	Jan 8, 2013	MARK GREGORY AÑO	1P3K008A	48.478		147.882		
	Feb 12, 2013	IRO ROXAS	2P7A1043A			105.256		
	Feb 14, 2013	IRO ROXAS	2P7A2045A	51.624		105.356		
	Feb 14, 2013	LOVELY ACUÑA	2P7B1045B	39.735		66.805		
	Feb 15, 2013	IRO ROXAS	2P7B2046A					
	Feb 13, 2013	JASMINE ALVIAR	1P7C044A					
	Feb 13, 2013	MARK GREGORY AÑO	1P7C044A					
	Feb 16, 2013	MARK GREGORY AÑO	1P7C047B	78.314	32.676			
PAMPANGA	Feb 18, 2013	MARK GREGORY AÑO	1P7C049B		4,458		- 6,702	
PAMP	Jan 8, 2013	CHRISTOPHER CRUZ	PAM7D	99.792		18.088		
	Feb 16, 2013	JASMINE ALVIAR	1P7E047A	169.479		24.871		
	Jan 9, 2013	LOVELY ACUÑA	2P7F1009A	152.57		0		
	Jan 9, 2013	IRO ROXAS	2P7F2009A					
	Feb 18, 2013	JASMINE ALVIAR	1P7G049A	122.87		0		
	Jan 9, 2013	MARK GREGORY AÑO	1P7H009A	56.001		0		
	Dec 3, 2012	LOVELY ACUÑA	AGN10338A	25.526				
	Dec 3, 2012	CHRISTOPHER CRUZ	AGN10338B	35.526		0	_	
	Feb 15, 2013	MARK GREGORY AÑO	1A10A046B	137.82		8.81		
	Feb 15, 2013	JASMINE ALVIAR	1A10B046A	57.458		84.762		

Table 14, cont'd

Location	Date Surveyed	Operator	Mission Name	Floodplain Surveyed Area (km²)	Total Floodplain Area (km²)	Water- shed Suveyed Area (km²)	Total Water- shed Area (km²)	
	Feb 14, 2013	MARK GREGORY AÑO	1A10C045B	66.157		76.063		
	Feb 15, 2013	LOVELY ACUÑA	2AG- N10D1046B	58.418		31.877		
	Jan 10, 2013	JASMINE ALVIAR	IA10E10A	18.618		0	6,702	
AGA	Jan 10, 2013	MARK GREGORY AÑO	1A10F10B	63.744		0		
PAMPANGA	Jan 10, 2013	IRO ROXAS	2AG- N10G1010A	47.050	4,458	0		
4	Jan 10, 2013	JAMES NOVILLA	2AG- N10G010B	47.059				
	Jan 11, 2013	MARK GREGORY AÑO	1A10H11A	28.18		0		
	Feb 18, 2013	IRO ROXAS	2AGNI1049B					
	Jan 11, 2013	LOVELY ACUÑA	2AG- N10l2011A	11.258		0		
	Mar 4, 2013	IRO ROXAS	Mt Arayat					

Supplementary flights were conducted to cover the data voids due to clouds and weather condition during the initial survey last November 2012 to February 2013. DPC had to cut flight lines with void data for processing good survey lines. Upon the commencement of the LiDAR acquisition (after the LiDAR training in December), the team always encountered loss communication problem with FMS NAV - the operator interface with the Pegasus LiDAR System. Because reflights are based on the processed data from DPC, DAC had to coordinate with DPC regarding the delineation of area for reflights. Hence, DAC generated flight plans to cover these data voids. Aside from data voids, there are also special cases wherein DPC cannot process the data because of its corrupted range while ANGNO10ER has 13 sets of range data which made it impossible to be processed. Seven (7) flight plans are created to cover the data voids in Pampanga floodplain.

Table 15. Flight Missions for Supplementary LiDAR Data Acquisition in Pampanga Floodplain

				Area	Area		Flying	Hours
Date Surveyed	Name	Flight Plan Area (km²)	Surveyed Area (km²)	Surveyed within the River Systems (km²)	Surveyed Outside the River Systems (km²)	No. of Images (Frames)	Hrs	Mins
Aug 29,2013	Pam 8H	117.40	170.64	170.64	0	no camera images	3	15
Aug 30,2013	Pam 3BR (Pam 3B)	98.0	231.14	231.14	0	no camera images	3	5
Aug 30,2013	Pam 3ER (Pam 3E)	181.25	149.92	124.674	0	no camera images	2	50
Aug 31,2013	Agno 10338 Agno 10D	103.26 84.54	244.2	71.264	52.42	no camera images	2	50
Aug 31,2013	Agno 10E	127.05	149.01	135.762	53.444	no camera images	4	0
Sep 1,2013	Pam 7B Pam 7C Pam 7D	48.87 58.27 84.54	265.071	265.071	0	no camera images	4	0

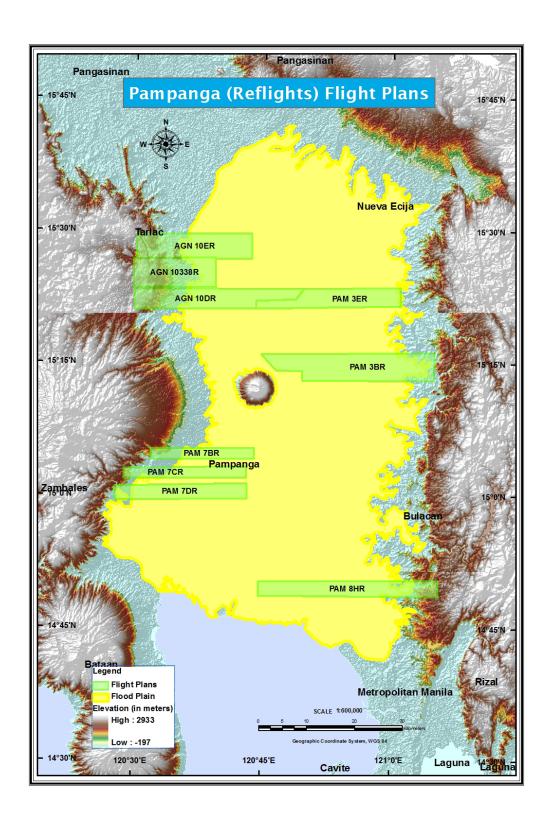


Figure 15. Flight plans for Pampanga Floodplain reflights

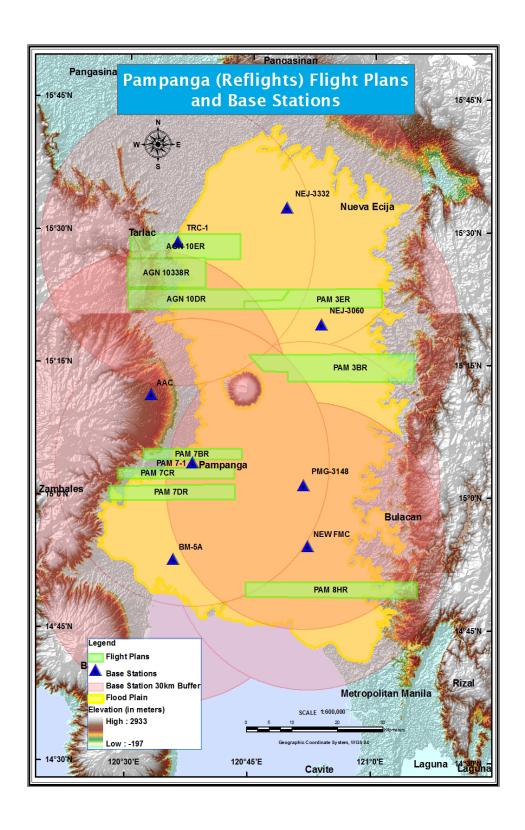


Figure 24. Base stations for Pampanga Floodplain reflights



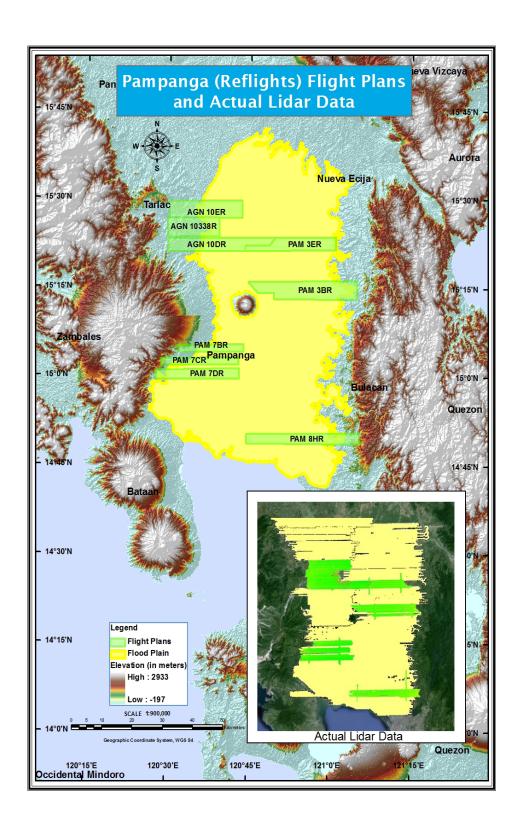


Figure 25. Pampanga reflights flight plans and actual LiDAR data

Table 16. Area of Coverage (km²) of the Supplementary LiDAR Data Acquisition Reflights in Pampanga floodplain

Date Surveyed	Operator	Mission Name	Flood- plain Surveyed Area (km²)	Total Flood- plain Area (km²)	Watershed Surveyed Area (km²)	Total Watershed Area (km²)	
Aug 29,2013	M. Ano	1P8HR240A	126.814		43.826		
Aug 30,2013	C. Joaquin	1PAM3AR242A	192.007		39.133		
Aug 30,2013	M. Funtilon	1PAM3BR242B	137.297		12.623		
Aug 31,2013	M. Ano	1AG- NO338243A	105.312	4,458	86.468	6,702	
Aug 31,2013	C. Joaquin	1AGN10E243B	88.942		6.624		
Sep 1,2013	M. Ano	1PAM7C244A	191.408		73.663		

4.2 LiDAR Data Processing

4.2.1 Trajectory Computation

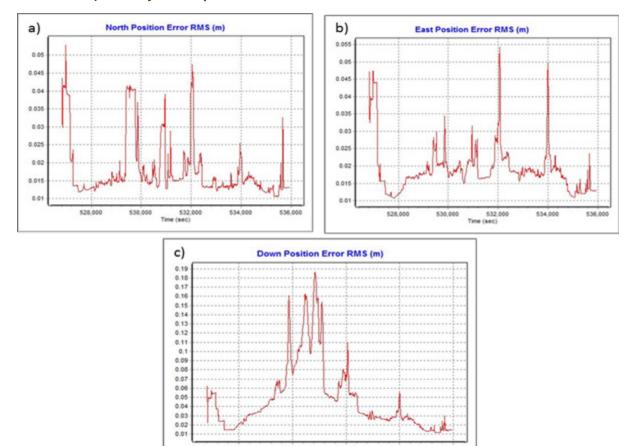
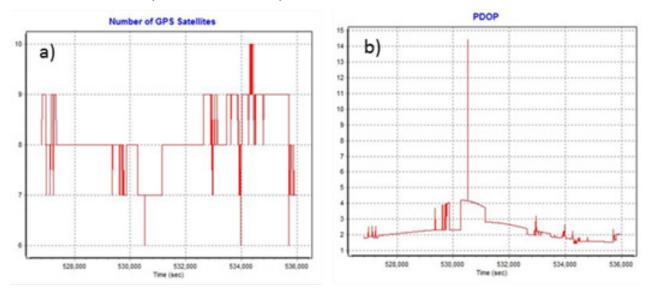


Figure 26. Smoothed Performance Metric Parameters of Pampanga flight

The Smoothed Performance Metric parameters of the Pampanga flight are shown in Figure 26. The x-axis is the time of flight, which is measured by the number of seconds from the midnight of the start of the GPS week. The y-axis is the RMSE value for a particular aircraft position with respect to GPS survey time. The North (Figure 26a) and east (Figure 26b) position RMSE values fall within the prescribed accuracy of 4 centimeters, and all Down (Figure 26c) position RMSE values fall within the prescribed accuracy of 8 centimeters.



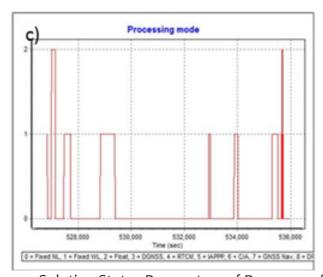


Figure 27. Solution Status Parameters of Pampanga flight

The Solution Status parameters of the computed trajectory for Pampanga flight, which are the number of GPS satellites, Positional Dilution of Precision (PDOP), and the GPS processing mode used are shown in Figure 27. The processing mode (Figure 27a) stays at a value of 0, which corresponds to a Fixed, Narrow-Lane mode, which indicates an optimum solution for trajectory computation by POSPac MMS v6.2. The PDOP (Figure 27b) value does not exceed the value of 3, indicating optimal GPS geometry. The number of GPS satellites (Figure 27c) graph indicates that the number of satellites during the acquisition was between 6 and 10. All of the parameters satisfied the accuracy requirements for optimal trajectory solutions as indicated in the methodology.

4.2.2 LiDAR Point Cloud Computation

The LAS data output contains 8 flight lines, with each flight line containing one channel, a feature of the Gemini system. The result of the boresight correction standard deviation values for the channel is better than the prescribed 0.001°. The position of the LiDAR system is also accurately computed since all GPS position standard deviations are less than 0.0017m. The attitude of the LiDAR system passed accuracy testing since the standard deviation of the corrected roll and pitch values of the IMU attitudes are less than 0.001°.

4.2.3 LiDAR Data Quality Checking

The LAS boundary of the LiDAR data on top of the SRTM elevation data is shown in Figure 28. The map shows gaps in the LiDAR coverage that are attributed to cloud cover present during the survey.

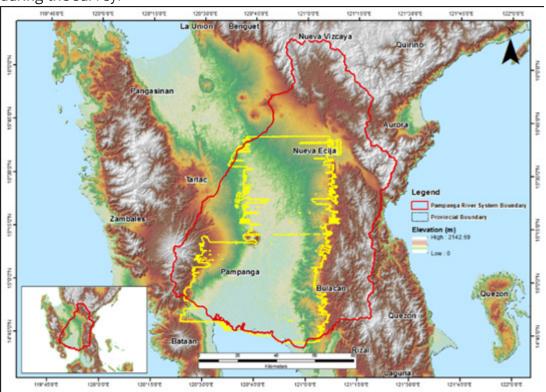


Figure 28. Coverage of LiDAR data for the Pampanga mission

The overlap data for the merged LiDAR data showing the number of channels that pass through a particular location is shown in Figure 29. Since the Gemini system employs one channel, an average value of 2 (blue) for areas where there are only two overlapping flight lines, and a value of 3 (yellow) or more (red) for areas with three or more overlapping flight lines, are expected. The average data overlap for Pampanga is 30.75%.

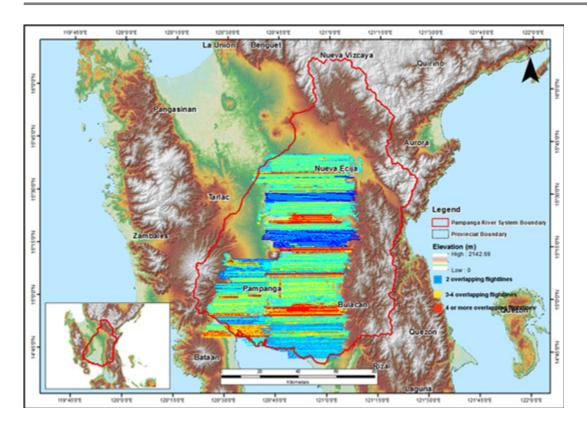


Figure 29. Ilmage of data overlap for the Pampanga mission

The density map for the merged LiDAR data, with the red areas showing the portions of the data that satisfy the 2 points per square meter requirement, is shown in Figure 30. It was determined that 81.22% of the total area satisfied the point density requirement, and the average density for the entire survey area is 2.6 points per square meter.

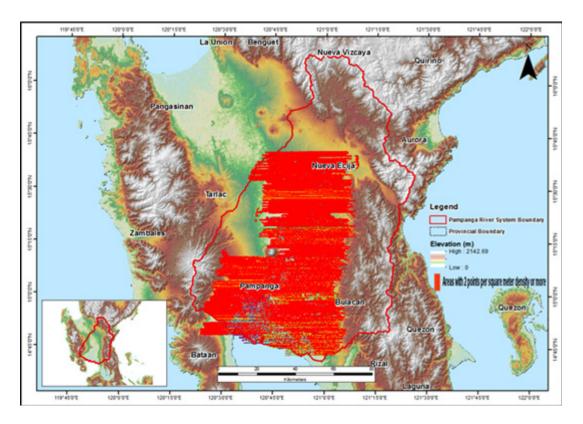


Figure 30. Density map of merged LiDAR data for the Pampanga mission

The elevation difference between overlaps of adjacent flight lines is shown in Figure 31. The default color range is from blue to red, where bright blue areas correspond to a -0.20 m difference, and bright red areas correspond to a +0.20 m difference. Areas with bright red or bright blue need to be investigated further using QT Modeler.

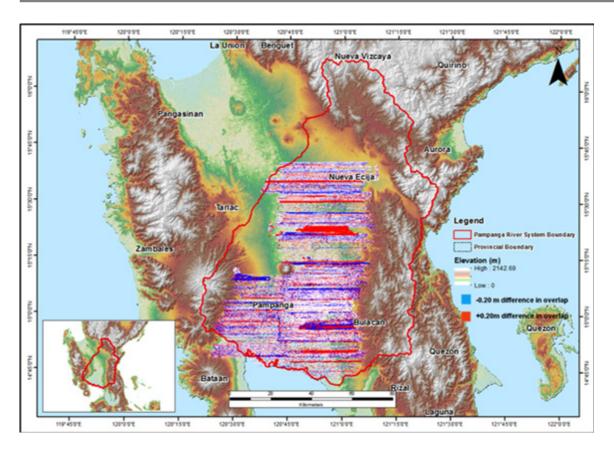
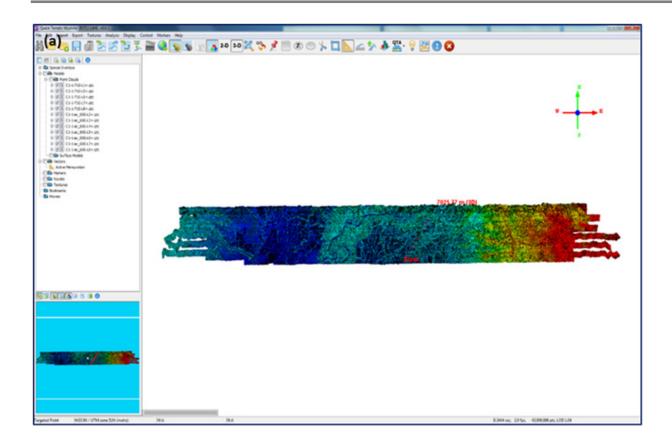


Figure 31. Elevation difference map between flight lines

A screen capture of the LAS data loaded in QT Modeler is shown in Figure 32a. A line graph showing the elevations of the points from all of the flight strips traversed by the profile in red line is shown in Figure 32b. It is evident that there are differences in elevation, but the differences do not exceed the 20-centimeter mark. No reprocessing was necessary for this LiDAR dataset.



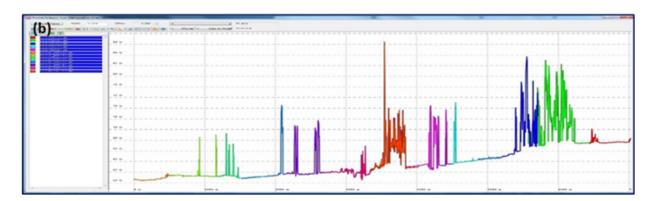


Figure 32. Quality checking with the profile tool of QT Modeler

4.2.4 LiDAR Point Cloud Classification and Rasterization

The block system that TerraScan employed for the LiDAR data is shown in Figure 33a generated a total of 3458 1 kilometer by 1 kilometer blocks. The final classification of the point cloud for a mission in the Pampanga floodplain is shown in Figure 33b. The number of points classified to the pertinent categories along with other information for the mission is shown in Table 17.

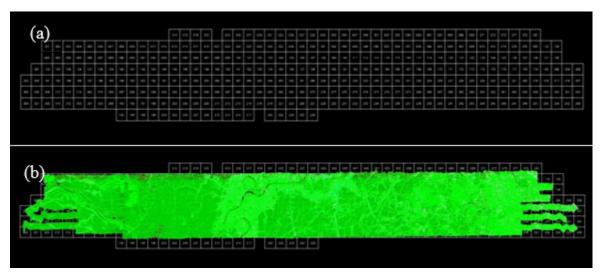


Figure 33. (a) Pampanga floodplains and (b) Pampanga classification results in TerraScan

Table 17.	Pampanga ¹	floodplain	point cloud	classification results

Pertinent Class	Count
Ground	1,416,332,051
Low Vegetation	1,985,408,028
Medium Vegetation	2,070,817,103
High Vegetation	1,744,801,076
Building	99,194,577
Number of 1km x 1km blocks	3,458
Maximum Height	705.94 m
Minimum Height	48.65 m

An isometric view of an area before (a) and after (b) running the classification routines for the mission is shown in Figure 34. The ground points are in brown, the vegetation is in different shades of green, and the buildings are in cyan. It can be seen that residential structures adjacent or even below canopy are classified correctly, due to the density of the LiDAR data.

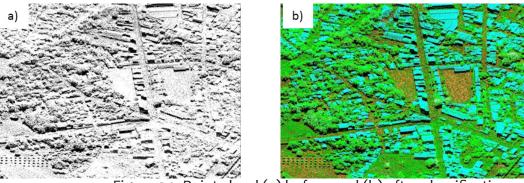


Figure 34. Point cloud (a) before and (b) after classification

4.2.5 DEM Editing and Hydro-correction

Portions of DTMs before and after manual editing are shown in Figure 35. It shows that the embankment might have been drastically cut by the classification routine in Figure 35a and clearly needed to be retrieved to complete the surface as in Figure 35b to allow to hydrologically correct flow of water. A small stream suffers from discontinuity of flow due to an existing bridge in Figure 35c. The bridge is removed also in order to hydrologically correct the flow of water through the river in Figure 35d.

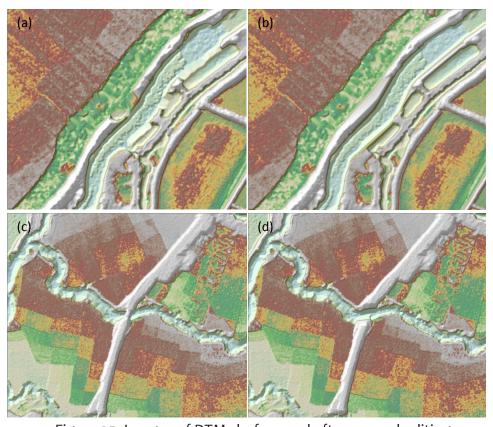


Figure 35. Images of DTMs before and after manual editing

The extent of the validation survey done by the Data Validation Component (DVC) in Pampanga to collect points with which the LiDAR dataset is validated is shown in Figure 36. A total of 148 control points were collected. The good correlation between the airborne LiDAR elevation values and the ground survey elevation values, which reflects the quality of the LiDAR DTM is shown in Figure 37. The computed RMSE between the LiDAR DTM and the surveyed elevation values is 5.480 centimeters with a standard deviation of 5.498 centimeters. The LE 90 value represents the linear vertical distance that 90% of the sampled DEM points and their respective DVC validation point counterparts should be found from each other. Other statistical information can be found in Table 18. The final DTM and extent of the bathymetric survey done along the river is shown in Figure 38.

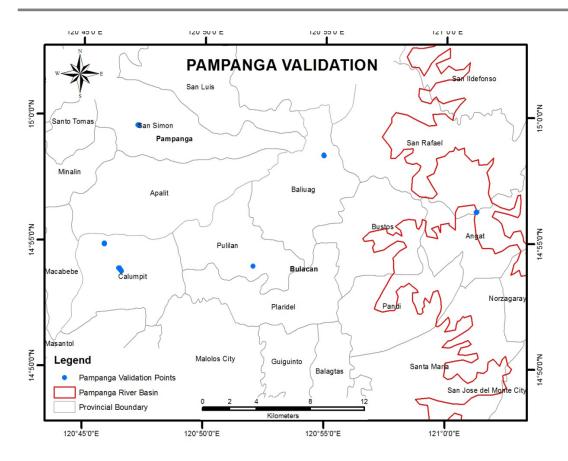


Figure 36. Map of Pampanga River System with validation survey shown in blue

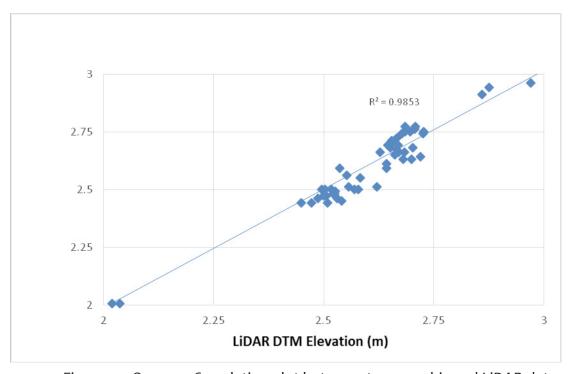


Figure 37. One-one Correlation plot between topographic and LiDAR data

Table 18. Statistical values for the calibration of Pampanga flights

Statistical Information	Values (cm)
Min	-10.784
Max	11.116
RMSE	5.480
Standard Deviation	5.498
LE90	8.516

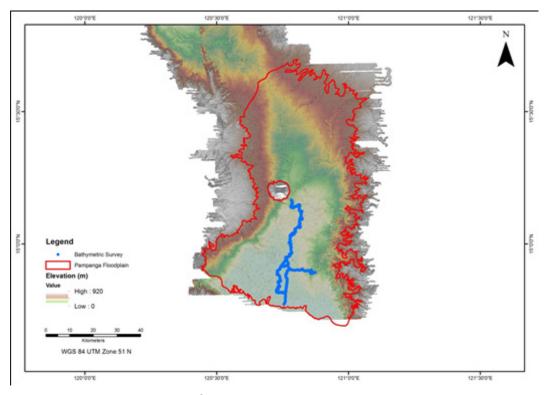


Figure 38. Final DTM of Pampanga with validation survey shown in blue

The floodplain extent for Pampanga is also presented, showing the completeness of the Li-DAR dataset and DSM produced, is shown in Figure 39. Samples of 1 kilometer by 1 kilometer of DSM and DTM are shown in Figure 40 and Figure 41, respectively.

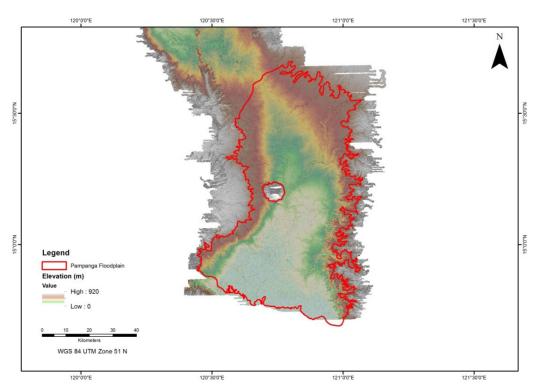


Figure 39. Final DSM in Pampanga

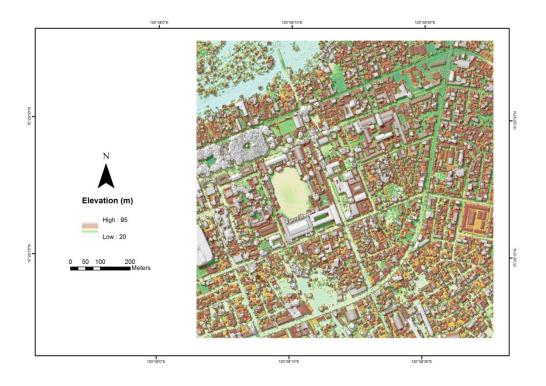


Figure 40. Sample 1x1 square kilometer DSM

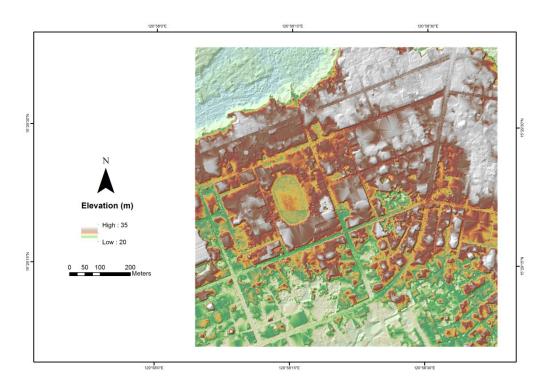


Figure 41. Sample 1x1 square kilometer DTM





Annex A

Annex A. OPTECH TECHNICAL SPECIFICATION OF THE PEGASUS SENSOR

PEGASUS SENSOR

Parameter	Specification
Operational envelope (1,2,3,4)	150-5000 m AGL, nominal
Laser wavelength	1064 nm
Horizontal accuracy (2)	1/5,500 x altitude, 1σ
Elevation accuracy (2)	< 5-20 cm, 1σ
Effective laser repetition rate	Programmable, 100-500 kHz
Position and orientation system	POS AV ™AP50 (OEM)
Scan width (FOV)	Programmable, 0-75 °
Scan frequency (5)	Programmable, 0-140 Hz (effective)
Sensor scan product	800 maximum
Beam divergence	0.25 mrad (1/e)
Roll compensation	Programmable, ±37° (FOV dependent)
Vertical target separation distance	<0.7 m
Range capture	Up to 4 range measurements, including 1st, 2nd, 3rd, and last returns
Intensity capture	Up to 4 intensity returns for each pulse, including last (12 bit)
Image capture	5 MP interline camera (standard); 60 MP full frame (optional)
Full waveform capture	12-bit Optech IWD-2 Intelligent Waveform Digitizer
Data storage	Removable solid state disk SSD (SATA II)
Power requirements	28 V, 800 W, 30 A
Dimensions and weight	Sensor: 630 x 540 x 450 mm; 65 kg
Dimensions and weight	Control rack: 650 x 590 x 490 mm; 46 kg
Operating Temperature	-10°C to +35°C
Relative humidity	o-95% non-condensing

Annex A

GEMINI SENSOR

Parameter	Specification
Operational envelope (1,2,3,4)	150-5000 m AGL, nominal
Laser wavelength	1064 nm
Horizontal accuracy (2)	1/5,500 x altitude, 1σ
Elevation accuracy (2)	< 5-35 cm, 1σ
Effective laser repetition rate	Programmable, 33-167 kHz
Position and orientation system	POS AV ™AP50 (OEM); 220-channel dual frequency GPS/GNSS/Galileo/ L-Band receiver
Scan width (FOV)	Programmable, 0-50 °
Scan frequency (5)	Programmable, 0-70 Hz (effective)
Sensor scan product	1000 maximum
Beam divergence	Dual divergence: 0.25 mrad (1/e) and 0.8 mrad (1/e), nominal
Roll compensation	Programmable, ±5° (FOV dependent)
Range capture	Up to 4 range measurements, including 1st, 2nd, 3rd, and last returns
Intensity capture	Up to 4 intensity returns for each pulse, including last (12 bit)
Video camera	Internal video camera (NTSC or PAL)
Image capture	Compatible with full Optech camera line (optional)
Full waveform capture	12-bit Optech IWD-2 Intelligent Waveform Digitizer (optional)
Data storage	Removable solid state disk SSD (SATA II)
Power requirements	28 V, 900 W, 35 A (peak)
	Sensor: 260 mm (w) x 190 mm (l) x 570 mm (h); 23 kg
Dimensions and weight	Control rack: 650 mm (w) x 590 mm (l) x 530 mm (h); 53 kg
Operating Temperature	-10°C to +35°C (with insulating jacket)
Relative humidity	o-95% no-condensing

Annex B. OPTECH TECHNICAL SPECIFICATION OF THE D-8900 AERIAL DIGITAL CAMERA

Parameter	Specification
	Camera Head
Sensor type	60 Mpix full frame CCD, RGB
Sensor format (H x V)	8,984 x 6,732 pixels
Pixel size	6µm x 6 µm
Frame rate	1 frame/2 sec.
FMC	Electro-mechanical, driven by piezo technology (patented)
Shutter	Electro-mechanical iris mechanism 1/125 to 1/500++ sec. f-stops: 5.6, 8, 11, 16
Lenses	50 mm/70 mm/120 mm/210 mm
Filter	Color and near-infrared removable filters
Dimensions (H x W x D)	200 x 150 x 120 mm (70 mm lens)
Weight	~4.5 kg (70 mm lens)
	Controller Unit
Computer	Mini-ITX RoHS-compliant small-form-factor embedded computers with AMD TurionTM 64 X2 CPU 4 GB RAM, 4 GB flash disk local storage IEEE 1394 Firewire interface
Removable storage unit	~500 GB solid state drives, 8,000 images
Power consumption	~8 A, 168 W
Dimensions	2U full rack; 88 x 448 x 493 mm
Weight	~15 kg
Image P	re-Processing Software
Capture One	Radiometric control and format conversion, TIFF or JPEG
Image output	8,984 x 6,732 pixels 8 or 16 bits per channel (180 MB or 360 MB per image)

Annex C

Annex C. THE SURVEY TEAM

Data Acquisition Component Sub-team	Designation	Name	Agency/Affiliation
Data Acquisition Component Leader	Data Component Project Leader –I	ENGR. CZAR JAKIRI S. SARMIENTO	UP-TCAGP
Survey Supervisor	Chief Science Research Specialist (CSRS)	ENGR. CHRISTOPHER CRUZ	UP TCAGP
LiDAR Operation	Supervising Science Research Specialist (Supervising SRS)	LOVELYN ASUNCION	UP TCAGP
LiDAR Operation	Supervising Science Research Specialist (Supervising SRS)	LOVELY GRACIA ACUNA	UP TCAGP
LiDAR Operation	Senior Science Research Specialist (SSRS)	MARK GREGORY ANO	UP TCAGP
LiDAR Operation	Senior Science Research Specialist (SSRS)	JASMINE ALVIAR	UP TCAGP
LiDAR Operation	Senior Science Research Specialist (SSRS)	JAMES NOVILLA	UP TCAGP
LiDAR Operation	Research Associate	IRO ROXAS	UP TCAGP
LiDAR Operation	Research Associate	MARVY FUNTILON	UP TCAGP
Ground Survey	Senior Science Research Specialist (SSRS)	ENGR. GEROME HIPOLITO	UP TCAGP
Ground Survey	Research Associate	ENGR. JAMES WILBERT BELTRAN	UP TCAGP
Data Download and Transfer	Research Associate	CHRISTOPHER JOAQUIN	UP TCAGP
LiDAR Operation	Airborne Security	SSG. PRADYUMNA DAS RAMIREZ	Philippine Air Force (PAF)
LiDAR Operation	Pilot	FRANCISCO CADENAS	ASIAN AEROSPACE CORP (AAC)
LiDAR Operation	Pilot	HARRY ROQUE	AAC
LiDAR Operation	Pilot	JAMAAL CLEMENTE	AAC
LiDAR Operation	Co-pilot	LAWRENCE MADAYAG	AAC
LiDAR Operation	Co-pilot	GRAIUS DELA CRUZ	AAC
LiDAR Operation	Co-pilot	FRANCO JESUS PEPITO	AAC

Annex D. NAMRIA CERTIFICATION NEJ-3332



Republic of the Philippines Department of Environment and Natural Resource NATIONAL MAPPING AND RESOURCE INFORMATION AUTHORITY

May 10, 2013

CERTIFICATION

To whom it may concern:

This is to certify that according to the records on file in this office, the requested survey information is as follows -

Province: NUEVA ECIJA

Station Name: NEJ-3332

Order: 4th

Island: LUZON Municipality: QUEZON

PRS92 Coordinates

Latitude: 15° 32' 42.98257"

Longitude: 120° 49' 9.35425"

Ellipsoidal Hgt: 27.14780 m.

WGS84 Coordinates

Latitude: 15° 32' 37.33289"

Longitude: 120° 49' 14,16885"

Ellipsoidal Hgt: 67.50000 m.

Barangay: PULONG BAHAY

PTM Coordinates

Northing: 1719141.792 m.

Easting: 480612.682 m. Zone: 3

UTM Coordinates

Northing: 1,719,725.18

Easting: 266,107.50

Zone:

51

Location Description

NEJ-3332

Station is located along the Provincial Road of Quezon-Aliaga Highway in Brgy. Pulong Bahay. It is situated SW end of the irrigation canal and 3 m SE of the welcome arch of Pulong Bahay. Station mark is the head of a 4 in. bolt screw centered on a 0.20 m x 0.20 m concrete block with inscriptions, "NEJ-3332, 2008, NAMRIA".

Requesting Party: Christopher Cruz

Pupose: OR Number: Reference 3943636B

T.N.:

2013-0417

RUEL OM. BELEN, MNSA Director, Mapping and Geodesy Department





NAMELA DEFICES:

Main : Lawton Avenue, Fort Bonifacio, 1634 Taguig City, Philippines Tel. No.: (632) \$10-4831 to 41 Branch : 421 Berroca St. Sen Nicoles, 1010 Manilo, Philippines, Tel. No. (622) 241-3494 to 98 www.namria.gov.ph



NEJ-3148



Republic of the Philippines
Department of Environment and Natural Resources NATIONAL MAPPING AND RESOURCE INFORMATION AUTHORITY

May 10, 2013

CERTIFICATION

To whom it may concern:

This is to certify that according to the records on file in this office, the requested survey information is as follows -

Province: PAMPANGA

Station Name: PMG-3148

Order: 4th

Island: LUZON

Municipality: SAN LUIS

PRS92 Coordinates

Latitude: 15° 1' 19,45298"

Longitude: 120° 51' 27.34493" WGS84 Coordinates

Ellipsoidal Hgt:

Barangay: TENEJERO

11.08000 m.

Latitude: 15° 1' 13.92611"

Longitude: 120° 51' 32.20370"

Ellipsoidal Hgt:

53.05900 m.

PTM Coordinates Easting:

3

Northing: 1661251.527 m.

484686.479 m.

Zone:

Northing: 1,661,781.75

UTM Coordinates Easting: 269,649.32

Zone:

51

Location Description

PMG-3148

From San Luis Town Proper in the Province of Pampanga travel towards SW direction for about 3 Km. passing through Pampanga River until reaching the intersection road. Turn left and continue to travel for about 8 Km. until reaching Brgy. Tenejero, Mun. of San Luis. Station is located at the side of culvert at the side of the road and 250 m NE of the Shell Gasoline Station. Mark is the center of a brass rod with cross-cut on top set flushed at the center of a 20 cm x 20 cm x 100 cm concrete monument with inscriptions, "PPMG-3148, 2008, NAMRIA".

Requesting Party: Christopher Cruz

Pupose: OR Number: Reference

T.N.:

3943636B 2013-0421

> RUEL ØM. BELEN, MNSA Director, Mapping and Geodesy Department





Main: Lawton Avenue, Fort Bonifacio, 1634 Taguig City, Philippines Tel. No.: (632) 810-4831 to 41 Branch : 421 Barraca St. San Nicolas, 1010 Manila, Philippines, Tel. No. (632) 241-3494 to 98 www.namria.gov.ph



NEJ-3060



Republic of the Philippines Department of Environment and Natural Resources NATIONAL MAPPING AND RESOURCE INFORMATION AUTHORITY

May 10, 2013

CERTIFICATION

To whom it may concern:

This is to certify that according to the records on file in this office, the requested survey information is as follows -

Province: NUEVA ECIJA

Station Name: NEJ-3060

Order: 4th

Island: LUZON Municipality: JAEN

PRS92 Coordinates

Latitude: 15° 19' 32.78238"

Longitude: 120° 53' 29.45676"

Barangay: NIYUGAN

Ellipsoidal Hgt: 21.54500 m.

WGS84 Coordinates

Latitude: 15° 19' 27.18854"

Longitude: 120° 53' 34,28956"

Ellipsoidal Hgt:

62.72000 m.

PTM Coordinates

Northing: 1694850.752 m.

Easting: 488350.739 m. Zone:

Northing: 1,695,355.91

UTM Coordinates Easting: 273,621.71

Zone:

51

Location Description

NEJ-3060

Station is located at Brgy. Niyugan, Jaen, Nueva Ecija. Situated infront of the brgy. hall and brgy. chapel. about 4 m W of waiting shed. To reach the station, from the town of Jaen travel NW for about 4.2 Km. until reaching Brgy. Niyugan. Station mark is the head of a 4 in. concrete nail centered on a 0.20 m x 0.20 m concrete block and mark with, "NEJ-3060, 2008, NAMRIA".

Requesting Party: Christopher Cruz

Pupose: OR Number:

T.N.:

Reference 3943636B 2013-0418

RUEL OM BELEN, MINSA

Director, Manufing and Geodesy Department



Main: Lawton Avenue, Fort Bonifocio, 1634 Taguig City, Philippines Tel. No.: (632) 810-4831 to 41 Branch : 421 Barroca St. San Nicolas, 1010 Manila, Philippines, Tel. No. (632) 241-3494 to 98 www.namria.gov.ph



TRC-1



Republic of the Philippines Department of Environment and Natural Resources NATIONAL MAPPING AND RESOURCE INFORMATION AUTHORITY

May 10, 2013

CERTIFICATION

To whom it may concern:

This is to certify that according to the records on file in this office, the requested survey information is as follows -

Province: TARLAC

Station Name: TRC-1

Order: 1st

Island: LUZON

Barangay: SAN ROQUE

Municipality: TARLAC

PRS92 Coordinates

Longitude: 120° 35' 52.67202"

Ellipsoidal Hgt: 46.89100 m.

WGS84 Coordinates

Latitude: 15° 28' 38.48550"

Latitude: 15° 28' 44.13765"

Longitude: 120° 35' 57,49329"

Ellipsoidal Hgt:

86.90220 m.

PTM Coordinates

Northing: 1711833.357 m.

Easting: 456859.89 m. Zone:

3

UTM Coordinates

Northing: 1,712,636.20

Easting: 242,278.30

Zone:

51

Location Description

TRC-1
Is located in a NIA irrigation canal concrete floodgate 300 m. E of the natl, highway, 1.5 km. SE of Tarlac town proper. From Manila, travel along MacArthur Highway to Tarlac. A small bridge, 10 m. NW of Sombrero Food Center along the irrigation canal bank to the railroad. It is 2 m. W of the railroad on the eastern floodgate wall, which is 5 min. walk from highway. Mark is a 0.15 m. x 0.01 m. dia. brass rod set on a drilled hole in a standard concrete block with cement putty, 0.03 m. above the top of the concrete railing, inscribed with station name. Reference marks (RM): RM's 1, 2 & 3 are 0.15 m. x 0.01 m. dia. brass rods set in a drilled hole with cement putties. RM-2 is a 0.15 m. x 0.01 m. dia. brass rod set on concrete block, 0.6 m. below ground level; Sub-RM is a 0.15 m. x 0.01 m. dia. brass rod set on a drilled hole on top of the concrete railing. dia. brass rod set on a drilled hole on top of the concrete railing.

Requesting Party: Christopher Cruz

Pupose: OR Number: Reference

T.N.:

3943636B 2013-0420

RUEL/DM. BELEN, MNSA Director, Mapping and Geodesy Department

JAB CIP/4701/12/09/614

Main : Lawton Avenue, Fort Banifacio, 1634 Taguig City, Philippines Tel. No.: (632) 810-4831 to 41 Branch : 421 Barraca St. San Nicolas, 1010 Manila, Philippines, Tel. No. (632) 241-3494 to 98

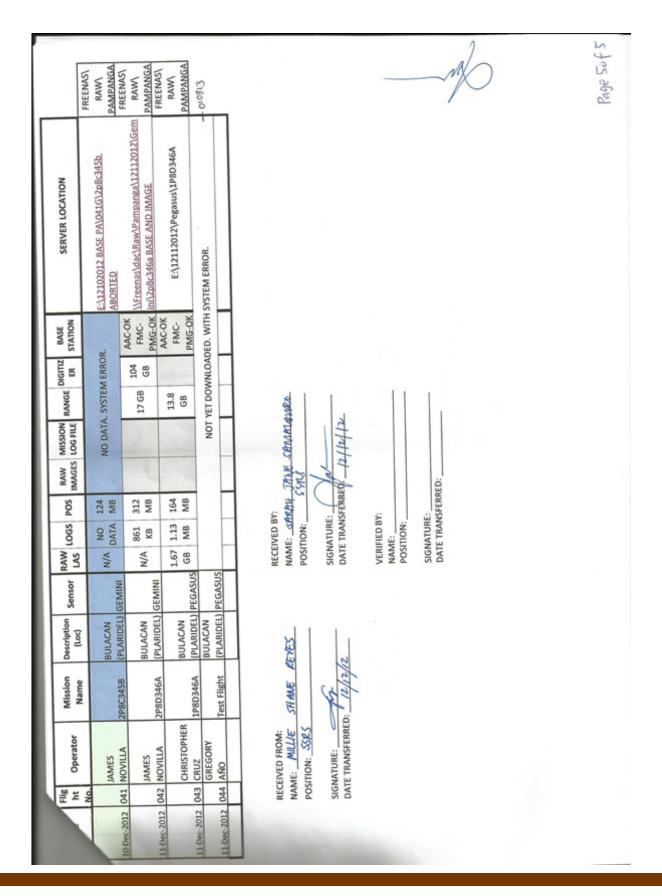
www.namria.gov.ph

ANNEX G. DATA TRANSFER SHEETS FOR THE PAMPANGA FLOODPLAIN

Data transfer sheet for PAM8A, PAM8B, 1P8C3342A, and 2P8C345A missions

					FREENAS\ RAW\ PAMPANGA	FREENAS\ RAW\	3			D		FREENAS\ RAW\ PAMPANGA
					FRE PAM	FRE						FRE
SERVER LOCATION	\\\ \lambda \text{\from DPC Hard.} \\\\ \text{Drive\DAC\Date\11292012\Fight\Number\029} \\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	\\ \freenas\DAC\from DPC.Hard.\\ \text{Drive\DAC\Date\11302012\Flight Number\030}\)		\\Interenas\DAC\from DPC Hard.\\Dive\DAC\Date\12012012\Fight Number\032.\\\Dive\DAC\Date\12012012\Fight Number\032.\\\Dive\Date\12012012\Fight Number\032.\\\\\Dive\Date\10012\Fight Number\032.\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	E:\12032012\33\1AGN10338A	E:\12032012\34\AGN10 PEGASUS	couns		DATA ARE STORED IN MS. DIMOG'S PCAND USB.		TO RAIN.	E:\12102012 BASE PA\\040G
BASE	MULTIPL E BASE	MULTIPL E BASE	27.2 MB		2.059 MB	4.78 MB	NO DATA, OVERCAST CLOUDS	,	MS. DIMO		FLIGHT ABORTED DUE TO RAIN	AAC-OK FMC- PMG-
DIGITIZ ER	98.1 GB	32.4 GB	26 GB		23.7		DATALO		RED IN		IT ABOF	88 68
RANGE	14 GB	7.59 GB	6.78 GB	25.1 GB	8.73 GB	8.36 GB	NO		ARE STC		FLIGH	17.7 GB
RAW MISSION IMAGES LOG FILE					95 KB				DATA			
RAW	43.3 GB	15.6 GB	16.2 GB		11.3							57.6 GB
POS	185 MB	104 MB	99.2 MB	211 MB	126 MB	154 MB						265 MB
rogs	1.14 MB	599 KB	638 KB	1.48 MB	471 KB	954 KB						941 KB
RAW LAS	2.54 GB	0.98 GB	921 MB	2.95 GB	168	1.03 GB						N/A
Sensor	PEGASUS	PEGASUS	PEGASUS	PEGASUS	PEGASUS 1 GB	PEGASUS	PEGASUS	AQUARI US	GEMINI	GEMINI	GEMINI	GEMINI
Description (Loc)	ARAYAT	ARAYAT	ARAYAT	PAMPANG	TARLAC		BULACAN	NALONA	BINALONA	TARLAC	TARLAC	BULACAN
Mission Name	PAM 8A PART 1	PAM 8A PART 2	LMS CALIBRATION 3	PAM 88	AGN10 1AKATO338A	AGN10	1P8C3342A	AQUARIUS ZTH BI CALIBRATION N	ZTH BI	LMS CAUBRATION / CAMERA CAUBRATION TARLAC	CALIBRATION TARLAC	2P8C345A
Operator	JAMES NOVILLA	JAMES NOVILLA	IRO ROXAS	IRO ROXAS	LOVELY ACUÑA	CHRISTOPHER CRUZ	CHRISTOPHER	LOVELY ACUÑA	JAMES NOVILLA	LOVELY 038 ACUÑA	039 IRO ROXAS	LOVELY ACUÑA
N H R	029	030	031	032	033	034	035	036	037	038	039	040
	29-Nov-2012	30-Nov-2012	30-Nov-2012	1-Dec-2012	3-Dec-2012	3-Dec-2012	6-Dec-2012	7-Dec-2012	7-Dec-2012	8-Dec-2012	8-Dec-2012	LOVELY 10-Dec-2012 040 ACUÑA

Data transfer sheet for 2P8C345B, 2P8D346A, and 1P8D346A missions



Data transfer sheet for PAM8C and PAM8G missions

checklist 12132012
DATA TRANSFER FILE CHECKLIST
DECEMBER 13, 2012

SERVER LOCATION	KEENNS/dac/from Engg.covm HD	do	80	80
BASE	N.d.	AAC-OK FMC-OK	AAC-OK FMC-OK	AMC OF PANC OF
DIGITIZER		32.6 GB	72.8 GB	GEMINI N/A 74/KB 286/18 4846 38/16 14:0 51.5 68 AMCOL
RANGE	ERROR	9.13 GB	13.3 7.	H.0 6B
MISSION LOG FILE	AIRCRAFT	206 KB	321 KB	38/18
RAW	NO DATA, AIRCRAFT ERROR	24.9 GB	259 42.0 GB 321 KB	484CB
POS	Z	259 MB	259 MB	286kg
RAW LOGS POS		480 KB	750 KB	19th
RAW		N/A	N/A	N/A
Sensor	PEGASUS	GEMINI N/A 480 KB 259 24.9 GB 206 KB 9.13	GEMINI N/A 750 KB	
Description (Loc)	10g5 pos (213g4	MISSOUT FOR TRANSFER	PRANCIPER TRANSPER	TEMSTER.
Mission	PAMSE ABORTED	PAM8C	PAM8G PART 1	PAM8G PART 2
Operator	IRO ROXAS	JAMES	LOVELY	JAMES
Flight No.	047P	0486	0496	9090
Date	DECEMBER 13,2012	DECEMBER 13,2012	DECEMBER 13,2012	DECEMBER 14,2012

RECEIVED BY:
NAME: CARACH TRUE SANGELES UK
POSITION:
SIGNATURE:
DATE TRANSFERED: 121/4 10

RECEIVED FROM:

NAME: AUGSTON: REALTH ASPECTME
POSITION: REALTH ASPECTME

SIGNATURE: DATE TRANSFERRED:

VERIFIED BY:

VERIFIED BY:
NAME: JOHN IOJE TRBAM
POSITION: C.5.E.S
SIGNATURE: (M.L.
DATE TRANSFERRED! D./IV/A

age 1

Data transfer sheet for 21P8E350B, 2P8H350A, 2P8H352A and 1P8F352A missions

				,*			
		SERVER LOCATION	To se pouncounds	PREERINS/dec	TO BE DOWNKONDED	FPEEBNAS/dac	
		FUGHT			ĕ	XO.	
		BASE	AAC-OK FMC-OK	AAC-OK FMC-OK	AAC-OK FMC-OK	AAC-OK FMC-OK	
		DIGITIZER	62.6 GB	TO BE DOWNLOADED [OS (C;) PC-13]		7.07 GB	
		RANGE	15.5 GB	13.8 GB	14.3 GB	4.48 GB	
	,	MISSION LOG	281 KB	424 KB			
182012	DATA TRANSFER FILE CHECKLIST DECEMBER 18, 2012	RAW IMAGES	32.0 GB	41.8 GB	TO BE DOWNLOADED (GEM B)	TO BE DOWNLOADED (PEG B)	
checklist 12182012	SFER FILE	POS	166 MB	273 MB	302 MB	126 MB	Page 1
5	NTA TRANS	5901	824 KB	786 KB	822 KB	222 KB	RRED: 124
	à	RAW LAS	2.01 GB	N/A	N/A	264 MB	RECENTED BY: NAME: Strata, Str
		Sensor	PEGASUS	GEMINI	GEMINI	PEGASUS	
		Description (Loc)	DAC hand offive	525 526	THE hard	Engs Chuz/	니
		Mission Name	1P8E3508	2P8H350A	2P811352A	1P8F352A	T. Alvier
			CRUZ	IRO ROXAS	IRO	CHRIS	RECEIVED FROM: NAME: Jacobi & L. POSITION: Regeneral SIGNATURE: DATE TRANSFERRÉD: Z
		Flight No.	S3P	526	546	SSP	RECEIVED FROM: NAME: Jacobia POSITION: Residential SIGNATURE: DATE TRANSFERRE DATE TRANSFERRE
		Date	DECEMBER 15,2012	DECEMBER 15,2012	DECEMBER 17,2012	DECEMBER 17,2012	

Data transfer sheet for 2P8I132A, 1P8F352A, P8I2, P8J1, P8F, 1P3A355B, and 2P3C356B missions

		Server Location	Winemasidaci64@2P81 1362A	UFreenasidaci55P	NFreenasidaci56G/2P8I 23548	Wheenasidaci67G/2P8 J1355A1	WFreenas/dac/58P\1P8 F365A	WFreemas/dac/69P\1P3 A365B	VFreenas/dac/60G						
	-				-	0Freenas J1355A1	WFree F365	Ange	WFree						
		Flight Plan	OK- 121812	OK- 121813	š	š	š	š	š						
		Base Station(s)	OK- 121812	OK- 121812	×	×	¥	¥	ž						
		Digitizer	<	OK- 121812	NO DIGITIZE	-	TO BE DOWNLO ADED	TO BE DOWNLO ADED	137 GB	Sampleres					
	\perp					8 585	490 MB TO (TO BE DO VERIFIED AD	3.95 GB TO AND 20.1 DC GB AD	51		5				
	-	on Range	KB OK- 121812	2ED OK-						Someth (James)	13				
	-	Mission Log File	3 450 KB	WNLOA	128 KB	360 KB AND 38 26.5 KB	384 KB	TO BE DOWNLOADED	589 KB		sferred:				
		Raw Images	51.160	TO BE DOWNLOADED	14.8G	44.3 GB AND 3.0 GB	44.5 GB	DOWN	75.3 GB	Received By: Name: Position:	Signature Date Transferred: 3 3				
			_		275 MB	274 MB	193 MB	175 MB							
	.	908	OK-121812 OK-121812	OK-121812 OK-121812				8 175	TO BE DOWNLOA 276 MB DED		П				
#CKLIS	_	LOGS	OK-12	OK-12	775 KB	751 KB	139 KB AND 1.14 MB		TO BE DOWN	Scen	Po de la constantina della con				
SFER	3-Jan-12	Raw Las	NA	OK- 121812	NA	N/A	44.5 GB	1.67 GB	NIA	madica	113/30				
DATA TRANSFER CHECKLIST		Sensor	GEMINI	PEGASUS	GEMINI	GEMINI	PEGASUS	PEGASUS	GEMINI	Assleray 55.Kg	de				
8	+		8	2	35	8	82	26	8		paud				
		Route (location)				Novaliches; Valenzuela				Received From: Name: Position:	Signature Date Transferred:				
	\perp				TE				-	828	Sign				
		Mission Name	32A	1P8F352A	PBI2-COMPLETE	PEJ1-COMPLETE		1P3A355B	29303568						
	-	Miss	2P8H32A	1985	P812-		78	NE 41	N. 2930						
		perator	Ino Roxass	Chris Cruz	tro Roxas	James Novilla	Greg Año	Jasmine Alviar	Chris Cruz						
	-	Flight No. Operator													
	-	Filg	17-Dec-12 54G	17-Dec-12 55P	19-Dec-12 56G	20-Dec-12 57G	20-Dec-12 58P	20-Dec-12 59P	21-Dec-12 60G						
		Date	17-De	17-De	19-De	30-De	80.08	30-De	21-De						

Data transfer sheet for P8F, 1P8D356B, 1P3F363, 2P3G, 2P3G2, 1P3H, 1P3A355B, 2P3C356B and 1P3B missions

							4-Jan-12								
-	Flight No. Operator	Operator	Mission Name	Route (location)	Sensor	Raw	roes	POS	Raw Images Log File		Range	Digitizer	(ŝ)	Flight	Server Location
20-Dec-12 58P	dg	Greg Año	PBF		PEGASUS	OK- 01/03/ 2013	OK- 01/03/2013	OK- 01/03/201	OK- 01/03/2013	OK- 01/03/20 F	OK- 490 MB IS 01/03/20 REPLACED BY 13 20.3 GB	TO BE DOWNLOA DED	2013	OK- 01/03/201 3	VFreenas\dac\58P\1P8 F355A
21-Dec-12 61P		Ohris Cruz	1P8D356B				TO BE DOWNLOA 118 MB DED		NO DATA						WFreenas\dac\61P
28-Dec-12 62P	95	Greg Año	1P3F363		PEGASUS	1.30	1.81 MB	252 MB	Thirtipad		25.7 GB	Engg_Cnz HD	×	×	WFreenas/dac/62P
28-Dec-12 63G	96	Ino Roxas	2930		GEMINI	NA	53.8 KB		Engg_Cruz HD		14.4 GB	NO	ĕ	×	VEnenas/dac/63/9
29-Dec-12 64G	990	Lovely Acufts	29/302		GEMINI	NA	751 KB	274 MB	NO DATA						Wreenas/dac/64G
29-Dec-12 65P	99	Chris Cruz	1P3H		PEGASUS N/A	NIA	TO BE DOWNLOADED	TO BE CWNLOADED	NO DATA						'iFreenas\dac\65P
126			1P3A3558		PEGASUS					DAC Hard drive					WFreemas/dac/66P
02-Jan-13 67P		Chris Cruz	2P3C3568		GEMINI	DACH	DAC Hard drive			Î	26.1 GB	PC-12	to be downloaded	paged	VFreenas/dac/67P
02-Jan-13 68P	98	Chris Cruz	1938		PEGASUS NIA		TO BE DOWNLOADED		NO DATA						\Freenasidaci68P
				Received From: Name: Position: Signature Date Transferred:	3 1	they shabi	ر ا ځ		Received By: J Name: Position: Signature Date Transferred:		Joida F. Prieto				
						-				0					

Data transfer sheet for 2P8H350A, 2P8J1355A1, 1P8F355A, 1P3A355B, 1P3F363, 2P3G, 2P3G1B, 1P3H364A, 1P3H364B, 1P3D002A, 1P3B002B, and 1P3B003A missions

	Raw Images Mission Range Digilizer (Starton(s) Plan Server Location	OK- OK- 1218/20 OK-12/18/2012 92.39 GB OK- 12/18/2012 12/18/2014 1	OK- OK- OK-01032013 72.0 GB OK-01032013 72.0 GB 01032013 0M3201 0M32013 0M32013 0M32013 0M32013 0M32013	ON- 010020 (DIRREGARD 96.9 GB ON- 01002013 (13 (0)042012) (0)04000 (0)040000 (0)0400000000000000	394 KB OK-01/03/2013 99.9 GB OK- 01/03/2013 (Virgensatidac/S)P	TO BE OK.	445 KB OK-01/04/2012 NO DIGITIZER			505 KB 26.2 CB 124 GB OK OK Winemas/dac/8682	THINKPAD 26.1 GB PC-13 VErensatidac@ZP	NO DATA - ENGNE ON AND ENGNE OFF ONLY	378 KB 10.7 GB 80.2 GB OK OK WFreenastdact69P	Name: JODA E. PRIETO	Signature Date Transferred
DATA TRANSFER CHECKLIST 8-Jan-13	sod spon	OK- 12/18/2012 12/18/20	OK- 01/03/2013 01/03/20	OK- 01/03/2013 01/03/20	OK: OK: OK: 01/03/20 43.3 GB		OK: 01/04/20 AND 46.4 01/04/20 12 GB	MB	485 KB 119 MB NO DATA	TO BE DOWNLOADED 59.8 GB	313 KB AND 1.38 199 MB MB	O ON	1.8 MB 192 MB 40.4 GB		
	Sensor Raw Las	GEMINI 12/18/201	GEMINI 01/03/201	A GEMINI 01/03/201	PEGASUS 01/03/201	PEGASUS 01/04/201	GEMINI N/A	GEMINI N/A	PEGASUS 152 MB	PEGASUS TO	PEGASUS AND 333	PEGASUS	PEGASUS 2.69 GB 1.8 MB	ankray Water	1
	Route (location)	BULACAN	NOVALICHES; VALENZUELA	ARAYAT; NUEVA GCUA	NUEVA ECUA	NUEVA ECUA	NUEVA ECLIA	NUEVA ECLIA	NUEVA ECUA	NUEVA ECUA	NUEVA ECLIA	NUEVA ECUA	NUEVA ECUA	Received From: Name: President	Signature Date Transferred:
	rator Mission Name	to Roxas 2P8H350A	James Novilla 2P8J1355A1	Greg Año 1P8F355A	Jasmine Aiviar 1P3A355B	Greg Año 1P3F363	ino Roxas 2P3G	Lovely Acufla 2 P3G18	Chris Cruz 1P3H364A	INO ROXAS 1p3h364b	MARK GREGORY AÑO 11°3D002A	CHRISTOPHER CRUZ 1P3B0028	Jasmine Aviar 1P38003A		
	Date Flight No. Operator	15-Dec-12 52G Iro F	20-Dec-12 57G Jam	20-Dec-12 58P Grey	20-Dec-12 59P Jase	28-Dec-12 62P Gre	28-Dec-12 63G Ins F	29-Dec-12 64G Low	29-Dec-12 65P Chri	29-Dec-12 66P INO	02-Jan-13 67P MARK GRIGG	02-Jan-13 68P CHRIS	03-Jan-13 09P Jasr		

Data transfer sheet for 1P3H364B, 1P3E005B, 1P3K008A, 2P3I2008A, 2P3G208B, 1P7D008B, 2P7F1009A, 1P7H009A missions

		Alexand Rain	*								
İ											
	SERVER LOCATION	(PC 21) G:\66P	(PC22) G:\74P	(PC21) G:\78P	(PC21) G:\79G	(PC22) G3/80G	(PC22) G:\81P	(PC22) G:\82G	(PC22) G:\83G		
-		H		48	NB /	/ AB		798	798		
-	BASE STATION		1	AAC - 6.99 MB / NE53332 -5.58 MB	AAC - 6.99 MB / NE53332 -5.58 MB	AAC - 6.99 MB / NES333Z - 5.58 MB	AAC - 6.99 MB	AAC - 6.48 MB / BM5A01.09-13 -798 MB	AAC - 6.48 MB / BM5A01-09-13 -798 MB		
t	GM2 ER		74.6 GB	110 GB	69.8 GB	109 GB	64.8 GB	59.3	80 O9		
. 1	AMGE, DI		19.8 GB	15.6 GB / 6.08 GB	5.36 GB / 9.43	14.5 GB	14 GB / 1.25 GB	8.92	15.8 GB		
JANUARY 15, 2012	SSION R			1KB/38 6KB/49 KB	246KB/ 150KB	445 KB	24 Kb	157 KB	311 KB		
JANUARY 15, 2012	RAW MISSION RANGE ER	-	23.1 GB	53.6 GB 68	46.7 24 GB 1	48.6 GB	23 GB 224 Kb	18.2 GB 1	37.2 GB 3		
WARY	POS	228 M8	158 2 MB 0	209 MB	256 MB	248 MB	162 MB 2	206 MB	200 MB		
JAN	P 6003	471 2 KB h	702 1 KB P	1.05 MB / 2 497 KB	808 KB	833 KB	951 KB	383 KB			
DAIA	RAW IG	632 4 MB	_	S21 MB NB / / 727 MB	N/A	N/A	1.9 GB / 67.6 MB	N/A	1.35 MB / GB 61 KB		
	Sensor	PEGASUS	PEGASUS	PEGASUS	GEMINI	GEMINI	PEGASUS	GEMINI	PEGASUS		
	(Loc.)		Nueva Ecija	Nueva Edja	Nueva Ecija	Nueva Ecija	Nueva Ecija	Bataan	Bataan		
	Mission	1P3H364B	1P3E005B	1P3K008A	2P3I2008A	2P3G208B	1P7D008B	2P7F1009A	1P7H009A		
	Operator		Jasmine	- Pig	Iro Neil Roxas	080 Lovely Acuña	Christopher	082 Lovely Acuña 2P7F1009A	083 Lovely Acuña 1P7H009A		
	Flig ht No.	990	074	870	079	080	081	_			
1	Darte	29/Dec/2012	$\overline{}$	8/Jan/2013	8/Jan/2013	8/Jan/2013	8/Jan/2013	9/Jan/2013	9/Jan/2013		

Data transfer sheet for 2P7F2009B mission

SERVER LOCATION	(PC21) C:\Dream\846	(PC21) C:\Dream\85G	(PC22) G:\86P	(PC21) G:\87G	(PC21) G:88P and (PC22) G:\88P	(PC21) E:\New Transfer\01112013\89G abd (PC22) G\89G	(PC22)G390P	
BASE STATION	7.26 MB	AAC - 4.09 MB / TRC - 6.69 MB	AAC - 4.09 MB / TRC - 6.69 MB	AAC - 4.09 MB / TRC - 6.69 MB	AAC - 4.09 MB / TRC - 6.69 MB	AAC - 4,99 MB/ TRC - 5,36 MB	AAC - 4.99 MB/TRC - 5.36 MB	
piorni ER	51.8 GB	59.3	58.8	81.4 GB	93.7 GB	124 GB	79.8 GB	a
BAMAGE ,	11.9 GB	12 GB	31.9	11.4 GB	17.6 GB	15.8 GB	15.2 GB	da
	6 KB / 169 KB /38 KB	359 KB	531 KB		332 KB	437 KB	238 KB / 78 KB	RECEIVED BY: NAME: SCACILL TRING SCATE alband POSTITION: 5185 SIGMATURE: DATE TRANSFERITED 1 19 13
RAW MESSION IMAGES LOG PLE	24.1 GB	47.1 GB	72.7		37.5 GB	51.4 GB	37 GB	A STATE OF THE STA
808	217 MB	231 MB	245 MB	212 MB	152 MB	282 MB	156 MB	RECEIVED BY: NAME:
1068	924 KB	706 KB	1.60 MB	8 8 8	1.09 MB	824 KB	930 6 KB / 8 125 KB	RECENTO BY: NAME: _SGC POSITION: SIGNATURE: DATE TRANSF
RAW	N/A	N/A	3.26 GB	N/A	2.31 GB	A/A	846 MB	8 5 8 8 9
Sensor	GEMINI	GEMINI	PEGASUS	GEMINI	PEGASUS	GEMINI	PEGASUS	
(loc)	Bataan	Tarlac	Tarlac	Tarlac	Pampanga	Tariac	Pangasinan	र ।
Mission	2P7F20098	2AGN10G1 010A	1A10E10A	2AGN10G2 10B	1A10F108	2AGN10120	1A10H11A	Arthur D. D. Mark. Tr.
Operator	Iro Neil Roxas		Jasmine	James Albert 2AGN10G2 Novilla 10B	Mark Gregory Año	089 Lovely Acuña 2AGN10120	Mark Gregory Año	RECEIVED FROM: NAME: LONGESP ACCIDIOLA FOOSTION: MR-4 SAGMATUME: CAM-17-412. DATE TRANSFERRED: LIBA4-17-1412.
File No.	180	085	980		088	089		MAN NA NA
Date	9/Jan/2013	-	10/Jan/2013	10/Jan/2013	10/Jan/2013	11/Jan/2013	11/Jan/2013	

Data transfer sheet for 2P7A043A mission

Date	-					DA1	ATR	obrust	y 13, 21	February 13, 2013	9			
	Flight No.	Operator	Mission Name	Description (Loc)	Sensor	RAW	5901	POS	RAW	RAW MISSION MAGES LOGFILE	- RANGE	DIGITIZER	BASE STATION	SERVER LOCATION Patadrive 2 El Pata Acquisition
09/feb/2013	137		1AGN51040B	-	PEGASUS	144 MB	941 KB/	137 MB/	18.4 GB/	180 KB	14.1 GB/	NO DIGITIZEK	6.17 MB	(DVC WS2) C\DAC\02092013\137P
11/feb/2013	138		2AGNSA042A		GEMINÍ	N/A	426 KB	183 MB,	19.6 GB/	167 KB	9.75 GB/	NO DIGITIZER	4.42 MB	(DVC WS2) C\DAC\02112013\138G
11/feb/2013	139		1AGNSH042A		PEGASUS	, / 71.8 M8			9.20 GB	68 KB	5.32 GB	20.8 GB	4.42 MB	(DVC WS2) C-\DAC\Q2113013\J38F
11/feb/2013	140		1AGN5G042B		PEGASUS	174 MB	815 KB/	125 MB	17.8	1 KB / 163 KB	15 GB	NO DIGITIZER	4.42 MB	(DVC WS2) CADACA02112013\140P
12/feb/2013	141		1A5H043A		PEGASUS	303.AUB 181 MB	833 KB	119 MB/	25.2 GB/	63 KB/ 117 KB	18.4 GB/	NO DIGITIZER	33 BYTES No. pa\$6 /	(DVC W52) C:\DAC\02122013\02122015\
12/feb/2013	142		2P7A043A		GEMINI	N/A	674 KB	262 MB	28.8 GB	206 KB/ 1 KB/ 21 KB	13.2 GB /	NO DIGITIZER	, 33 BYTES AQ 12 A3.C	(DVC-WS2) CADAC\02122013\\02122013\\
	RECEIVED FROM: NAME: C+F, POSTION: SIGNATURE: DAIE TRANSFERE	RECEIVED FROM: NAME: ::-FLS POSTION: SIGNATURE: DATE TRANSFERRED.	A Partie	- 1 S		RECEIVED BY: NAME: JOID, FOSITION: SIGNATURE: DATE TRANSFERE		SSRS F	JOUGH F. PRIETO SERS	F. PRIETO S (L. P.	11	1 h		

Data transfer sheet for 1P7Co44A and 2P7B2o46A missions

	ATION											
	SERVER LOCATION	Physics are an extensive and	DESC WAST CAPACITABLE	IDVC WSQ C.(DAC)147P	(DVC WS2) C\DAC\1486	(DVC WS2) C\DAC\149P	(DVC WS2) C\DAC\1506	(DVC WS2) C\DAC\151P				
	DASE STATION	4.79 MB	6.87 MB									
	DOGITIZER	NO	NO	NO	NO	NO	NO	DIGITIZER				
February 20, 2013	RANGE	17.2 GB	19.7 GB	13.4 GB	24.8	12.3	19.2	SB				
913	MISSION LOG FILE	177 KB		1 KB/	262 KB	191 KB	240 KB	П	0	12013		
February 20, 2013	RAW MISSION RANGE	22.9 GB	33.4		-			9	Jourh F. PRIETO	02/21		
enroe.		139 MB	163 MB	304 MB	175 MB	-	+-	g l	SSRS	0		
	tods Pos	88 88	1.27 MB		-		_		8	SFERRE		
	RAW LAS	167 MB		N/A	8		1	_	RECEIVED BY: NAME: POSITION:	SKRAATURE: DATE TRANSFERRED;		
	Sensor	PEGASUS	PEGASUS	GEMINI	PEGASUS	GEMINI	PEGASUS			v 0		
	Description (Loc.)								1	-		
	Mission Name	1P7C044A	1A10C045B	2P7B2046A	1A108046A	2A10010468	1A10A0468		epi kalikuri	LIATION ASS		
	Operator								RECEIVED FROME HAME: GHELSCHTLEFF POSITION: Clean	DATE TRANSFERRED:		
L	Flight No.	143	147	148	149	150	151		RECEIVED FR NAME: (3)E POSITION:	DATE TR		
1		013	.013	15/FEB. 113	-013	2013	15/FEF 1113					
1	à	13/FEP	14/FEP	/FER	15/FEP	15/FEB/2013	FEF	1				

Data transfer sheet for 1P3E004A, 2P3C2005A, 1P3AN005A, and 1P3E005B missions

	71	1	The Gross	Ront	Seal				
	Server Location	WFreenasidact70P	WFreenasidac/71G	VFreenas/dac/72P **	\Freenasidac\74P		i		
	ght		ins	-			1//	1	
	Flight s) Plan				ĕ				
	Base Station(s)		7.38 MB	7.38 MB	7.38 MB				
	Digitizer	21.2GB 78.3GB	14.0GB DIGITIZER 7	19.4GB 95.5GB	74.6GB 19.8GB	Jin			
	Range	21.2GB	14.0GB	19.4GB	74.6GB	F. Paets RS			
19-Feb-13	Mission Log File		117KB, 306KB,45 48YTES	411KB		Syry Syry Syry Syry Syry Syry Syry Syry			
13	Raw	44,0GB	36.8GB	50.4GB	23.1GB	RECEIVED BY: NAME: (Sida) POSTION: SS SIGNATURE: DATE TRANSFERRED			
TRANSFE 19-Feb-13	o s		265 MB		158 MB				
4	LOGS		897KB		702KB	J. Meting			
	Raw		N/A						
	Sensor	PEGASUS	GEMINI	PEGASUS	PEGASUS 1.33	5			
	Route Sensor (location)	NUEVA	NUEVA	NUEVA	NUEVA	Received From: A Name: Position: 84 Signature Date Transferre C			
	Mission	MA	2P3C2005A	1P3AN005A	1P3E005B				
	Operator	Iro Roxas	Iro Roxas	Greg Arlo	JASMINE				
	Flight No.	70P	716	72P	74P				
	671	· 1-Jan-13 70P	-: Jan-13 71G	S-Jan-13 72P	-0-Jan-13 74P				

Data transfer sheets for 2P3P058A, 1P3CS058A, 2P3B058B, 1P3A558B, 2P7A2054A, 2P7B204513, 1P7E047A, 1P7G049A, 1P7C049B, 1P7C048B, 2P8A5051A, and 1P9B5051A missions

CHONE)	EELAS (-22615) PERAS (-22615) PERAS (-2415) PERAS (-2415) ITHERAS (-2415)	Freeze, S (Orang) Receves (Orang) Receves (Orang) Receves (Orang)
FREEHALT COORTY FREEHALT COORTY FREEHALT COORTY FREEHALT COORTY FREEHALT COORTY	五年 44 日	4 1 4
g wb	5.6 with 5.7 cm. 5.6 with 5.8 cm. 5.7 cm. 5.8	2 + 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4
(20.5 GR)	4-4 as 5. 5-4 as 5 5-4 as 5	3 2
CHECKUST LOS PILE B SOL.2 KB (1948 PU-6 KB	175-1 KE 17-5 KE /2.8 KB 462.8 KB 14-9 EG 22-9 GP	5 4 4 5 4 4 5 6 4 4 5 6 6 6 6 6 6 6 6 6
88 88 88 88 88 88 88 88 88 88 88 88 88	24.7 c/8 7 1.8 c/8 7 2.5 c/8 7 [4.0 c/4	25.25 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4
THE CHI PROPORTY OF SOLIS FROM INVAGANTY CASES WIRE 45.9 GB	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	269.5 mg. 249.5 mg. 300.3 mg. 2.45.3 mg. 2.00.3 mg. 1.45.3 mg. 1.4
PORPRY DATA TRANSPORT OF 2013 POR PORT PORT 1440 EN 227.3 WR 45.9 G FYS 199.5 WITS 254 G1	13.4	550-9-46 26 550-9-46 26 550-9-46 26 1-4-46 16
AS LOGIC POLICE ON THE HE THE T	T 2 3	The state of the s
1/4 1/4 1/4 014ep	R 2 2 7	, , , , ,
MICCORN HAWE ZAGAI SE OSA A ZAGAI SE OSOB [Higher 5]	1 AGH GR SO57A 2018 QLO57B 1 AGHL, CSO57B 2P SP PO57B 1 P 3 C 957B 2P 58058 B 1 P 3 P 55058	2P7-122045A 2P7-122045B 1P7-6047B 1P7-6049B 1P7-6049B 1P7-6049B 1P7-6049B
152.4 154.6 154.6 154.7 154.7 154.7 154.7 154.7	14 HD 168 P 169 G 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	44 NS G 1447 157 P 155 G 157 P 157 P 157 P 157 P 157 P
04 290 HD	DAC / CRC 4 + 49 022615 68 P 022615 69 G 022415 70 P 022713 77 G 022713 77 G 022713 77 G	02/8/12 02/8/12 02/8/12 02/8/12 02/8/12 02/8/12 02/8/12 02/8/12

Lo CATIVAS (MILLI)	Pretions (or 113)		
H/H H7-9 (-5 mg 1604 22)-5 GB 22-524 9.4 GB - PP	4.8 mgs 1920.8 mg 65-4 Cm5 135-7157900 19-4Gm 4.8 mgs 137-12500 mgs 137-12500 191-3 mgs 137-12500 191-3 mgs 15-6 Gm 19-9 cmgs 15-6 Gm 19-9 cmgs 15-6 Gm 19-9 cmgs 19-9 cmg 19-9 cmgs 19-9	JOIN F. PRIETO	
DAC 2 " MISSION WAYS LAS LAS COLORS 195 4 " LAS COLORS 195 4 " LAS COLORS 196 4 " LAS COL	022013 60 G - 2P8BSOSIG 4/A P	CHRIS JOHALIM	

Data transfer sheet for 2P8DS56A, 1P8CS56A, 1PSCS56B, and 2P8FS56B missions

	SERVER	NEC HP:2013 flights/0225201 Z:Vairborne_Ra 3:164G:2P8DS M:164G:2P8DS 56A	NEC HP:2013 31165P11P8CS W1165P11PBCS 56A 56A	NEC HP12013 flights/0225301 27/Arborne Ra 3168P1PSCS w1166P1PSCS 568	NEC HP1/2013 flights/02/25201 Z.Varborne_Ra 3167/3/2PBFS M167/3/2PBFS 568				
	HARDRIVE	NEC HP:2013 flights/0225201 3/164G/2P6DS 56A	NEC HP:\2013 flights\0225201 3\165P\1P8CS 56A	NEC HP:/2013 flights/0225207 3/166P/1PSCS 508	NEC HP/2013 flights/022520 3/167/G/2P8FS 568				
	FLIGHT	150KB	65.1KB	40.3KB	86.7KB				
	COMMENTS (DPC LOGS)	583 BYTES	NA	7608YTES	433BYTES				
	BASE STATION(S)		6.96MB	6.96MB	6.96MB		+		
EET	MISSION LOG FILE RANGE DIGITIZER	B N/A	15.0GB MA	8 N/A	8.04GB N/A		NameSignature JGDA PRIETO JA Position SSRS Date 03-23-13		
ER SI	RANG	13.6GB N/A	15.0G	24.0GB N/A	8.04G		10A P		Page 1
DATA TRANSFER SHEET			263KB	254KB	1638/8	d by	55.R5 03-23-13		
DATA	RAW	34.5GB	35.068	29,1GB	15.8GB	Received by	Name/Si Position Date		
	POS	606KB 248 MB 34.5GB	90.4MB1.21MB172MB	23GMB 1.01MB 163MB	1,01MB 206MB		- Cart		
	1003	606KB	B121M	M10.1	1.01M		Motin Greature		
	RAW	N/A					Method		
	SENSOR	GEMINI	PEGASUS	PEGASUS	GEMINI		KA KA (3-27-20)3		
	MISSION NAME SENSOR	2P8DS56A	1P8CS56A	1PSCS568	2P8F5568	Received from	Name/Signature () Position KA Date (3-2-		
	FLIGHT	, 2013	Feb 25, 2013 165	Feb 25, 2013 166	Feb 25, 2013 167				
	DATE	Feb	Feb	Feb	Pe				

Data transfer sheet for 1PAM8HR240A, 1PAM3A242A, 1PAM3B242B, 1PAM338243A, and 1PAM7C244A missions

Sep 3, 2013 Sep 3, 2013 Sep 3, 2013 Sep 4, 2013 Server LOCATION Straton	13
195 MB N/A N/A 10.8 GB N/A 1.60 MB 1.60 MB 1.70 MB N/A 10.7 GB N/A 1.60 MB 1.70 MB N/A 10.7 GB N/A 1.07 MB 1.0	195 MB N/A N/A 10.8 GB N/A 1.60 MB 1.60 MB 1.70 MB N/A 10.7 GB N/A 1.60 MB 1.70 MB N/A 10.7 GB N/A 1.07 MB 1.0
N/A N/A 20 GB N/A 1.60 MB N/A 17.1 GB N/A 1.60 MB N/A N/A 17.1 GB N/A 1.60 MB N/A N/A 28.8 GB N/A 6.01 MB N/A N/A 10.7 GB N/A 6.01 MB N/A N/A 25.8 GB N/A 1.07 MB Position Signature Benjamin Donal Megaliun Full 1.07 MB 1.07 MB	N/A N/A 20 GB N/A 1.60 MB N/A 17.1 GB N/A 1.60 MB N/A N/A 17.1 GB N/A 1.60 MB N/A N/A 28.8 GB N/A 6.01 MB N/A N/A 10.7 GB N/A 6.01 MB N/A N/A 25.8 GB N/A 1.07 MB Received by NA 25.8 GB N/A 1.07 MB Position 5 1k 5 Position 5 1k 5 Position 5 1k 5 Position 5 1k 5
N/A N/A 17.1 GB N/A 1.60 MB N/A N/A 28.8 GB N/A 6.01 MB N/A N/A 10.7 GB N/A 6.01 MB N/A N/A 25.8 GB N/A 1.07 MB Received by Name/Signature Benjamin Jonah Magalian for Janagalan 5.8 k s	N/A N/A 17.1 GB N/A 1.60 MB N/A N/A 28.8 GB N/A 6.01 MB N/A N/A 10.7 GB N/A 6.01 MB N/A N/A 25.8 GB N/A 1.07 MB Received by Name/Signature Benjamin Jonak Megallan f. Magallan Date of 18
N/A N/A 28.8 GB N/A 6.01 MB N/A N/A 10.7 GB N/A 6.01 MB N/A N/A 25.8 GB N/A 1.07 MB Racelved by Name/Signature Benjamin Jonah Megalian f. Jungulungsition 5.5 k.5	N/A N/A 28.8 GB N/A 6.01 MB N/A N/A 10.7 GB N/A 6.01 MB N/A N/A 25.8 GB N/A 1.07 MB Received by Name/Signature Benjamin Jonal Megallin, f./hingalling Position 5.4 k.5
N/A N/A 10.7 GB N/A 6.01 MB N/A N/A 1.07 MB N/A 1.07 MB N/A 25.8 GB N/A 1.07 MB Name/Signature Benjamin Jonah Megalian f. / Megalian s. s.k.s.	N/A N/A 10.7 GB N/A 6.01 MB N/A N/A 25.8 GB N/A . 1.07 MB Received by Name/Signature Ecolomin Jonak Michaelian & Miney Date of 18
N/A N/A 25.8 GB N/A 1.07 MB Received by Name/Signature Benjamin Jonal Megallan for fungation sikes	N/A N/A 25.8 GB N/A 1.07 MB Received by Name/Signature Benjamin Jonak Megallun, ferfungation 5 fk 5 Date of 18
Name/Signature Benjamin Jonah Magallan for Mugal	Racelved by Name/Signature Benjamin Jonah Mangallan F./Lungulu Position 5 Str & Date of 18
Name/Signature Benjamin Jonah Magallan for Sungal	Name/Signature Benjamin Jonah Magathan for fungaling Position & Str & Date of 18
Date of 15	

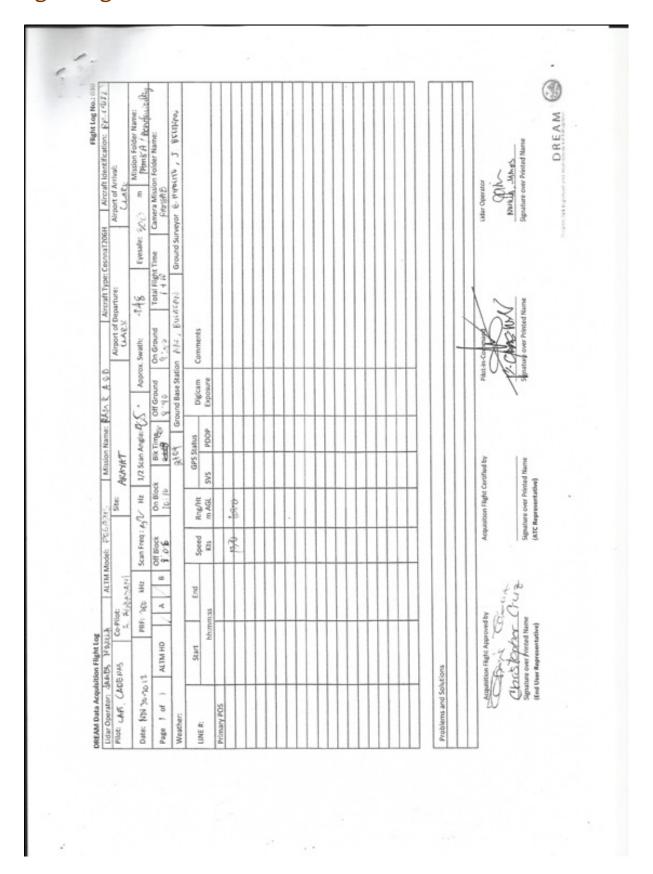
Annex H. FLIGHT LOGS

Flight Log for PAM8A Mission

Flight Log No.: 629 Holentification:新任務息 Invited: A & Li A Station Folder Name: Fritag A	Ser Name: 5 g EFFKm			D R E A M
Aircraft Sort of A	Time Camera Mission Folder Name: Fig. 6 Fig. 6 Ground Surveyor 6-18 pt (175) 5 8 EFF			Signature over Printed Name
Aircraft Type: Cesma 7206il At & Common Cesma 7206il At & Common Cesma 747	Total Flight Tigne Car			and the same of th
20	1 3	Herks		over Pricaced Name
Approx. S	Giff Ground On Ground (150) 17/79 Ground Base Station (144, 194			Piece in Company
Mission Name: PRIN ER APPRINT, Bitt Activ 1/2 Scan Angle: 7.5*	Sk Time Off	Status P0009		Arme and by
ag 포	On Block	Reg/let/	ARTASC 1820	Acquisition Flight Centified by Signature over Printed Name (ATC Representative)
LA ALTM Model: PEDAIS A. AG IRYAN Son Freq : 3	10	End Speed Kiss	Jana Char	
NAM O-Pilo	TM HD	hhammas hhammas	oblems and Solutions Service 1980 M. Control C	Acquaisting Flight Approved by Christoff Children Signature overforested Name (End User Representative)
DREAM Data Acquisition Flight Log Lidar Operator: Jangs 4/2850 Pilot: CAT CASSAS Date: Now 43 Account	Page of At	Primary POS	Problems and Solutions SCACOR BEAD 8 MoNAS PROPASE CAREAD TO	Acquisition (TAY St. Standard on (End User R.

Annex H

Flight Log for PAM8A Mission



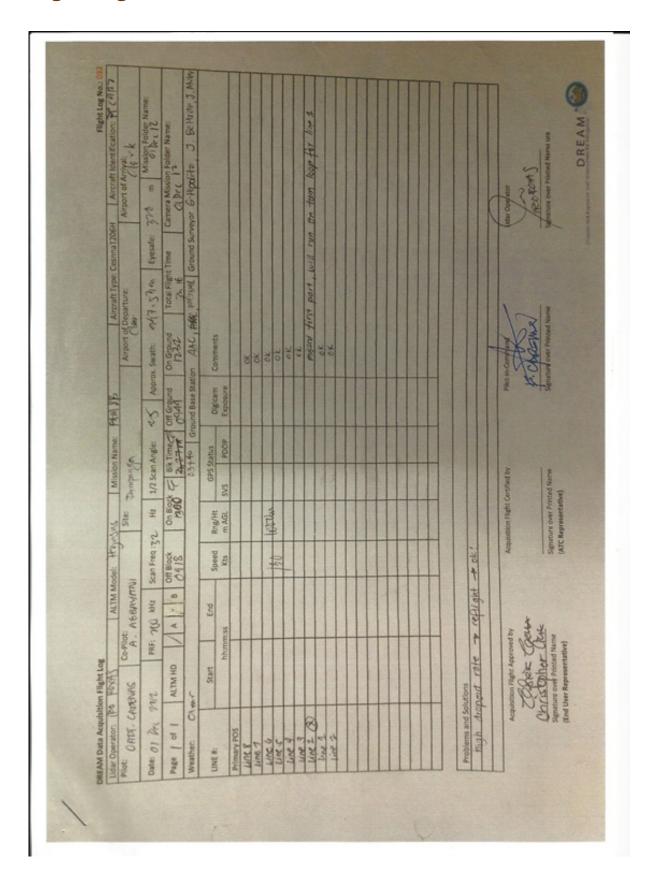
Annex H. FLIGHT LOGS

Flight Log for 2P8AS051A Mission

7 Pilot: L. Medayda 8 Co-Pil	ag 2 ALTM Model: Demini	3 Mission Name: 2PBASSIA 4	4 Type: VFR	5 Aircraft Type: Cesnna T206H	S Aircraft Type: Cesnna 7206H 6 Aircraft Identification: PPB127-
000	12 Airport of Departure (Airport, City/Province):		12 Airport of Arrival (12 Airport of Arrival (Airport, Gty/Province): Clask	
.o. H 14 Eng	ne Off: 3354	74	16 Take off: 場: 1055 H	17 Landing: 315H	18 Total Flight Time: 2+40
19 Weather					
Acquistion Flight Approved by	Acquisit		Pilot-in-Command	2	Lidar Operator
Signature over Printed Name (End User Representative)	Signature (PAF Repri	Mozzo 20 Pereno Per Sgnature over Printed Name (PAF Representative)	Signature over Printed Name		Signature over Printed Name

Annex H

Flight Log for PAM8B Mission



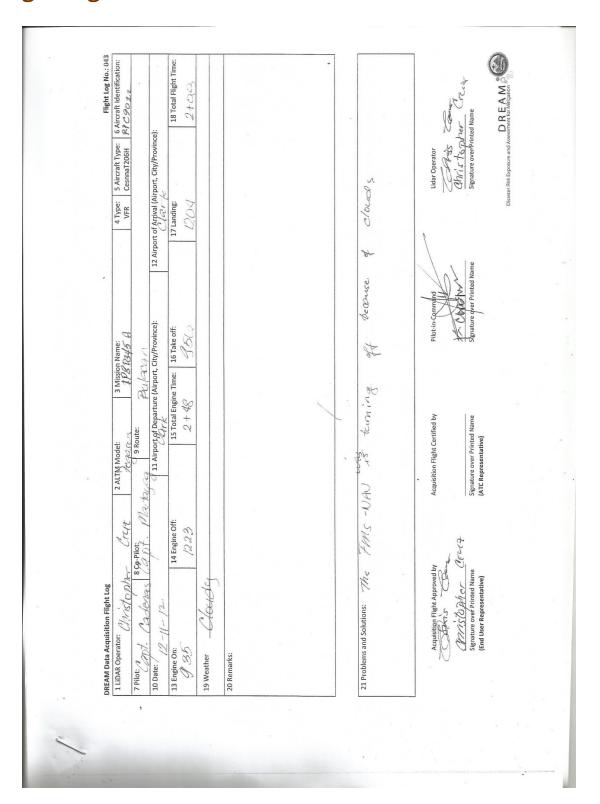
Annex H. FLIGHT LOGS

Flight Log for 1P8C3342A Mission

Flight Log No.: Prince	6 Aircraft Identification: ドア・C引い	2.	18 Total Flight Time:	2+05					d Name D R E A M Peritor Mitgalion
	4 Type: 5 Aircraft Type: VFR CesnnaT206H	12 Airport of Arrival (Airport, City/Province):	AKK ling:	\$9			,		Lidar Operator Control Signature over Printed Name Disaster Bisk Exposure and Assessment for Mitgation DAR A MO
		- CLARK 12 Airport of Arriv	17 Landing:	17:02					nted Name
			:: 16 Take off:	90-01					Pilot-in-Command Signature over Printed Name
	nte:	Departu	15 Total Engine Time:	2+12					Acquisition Flight Certified by Signature over Printed Name (ATC Representative)
	S ALTM Model:	JAMAL A'GBAYAN) TOIN		Charles Miles	583				Acquisition Flight Certi Signature over Printed (ATC Representative)
n Flight Log	mile	[13	14 Eng	UNINE , the	3	Line 2-A PobP		ons:	Acquisition Flight Approved by Control of the Cont
DREAM Data Acquisition Flight Log	7 Pilot: 1 2000	10 Date:	13 Engine On:	19 Weather		20 Remarks: Line 1		21 Problems and Solutions:	Acquistion Flight. CATT CAT SIGNATURE OVER PIT (End User Represent

Annex H

Flight Log for PAM8D Mission



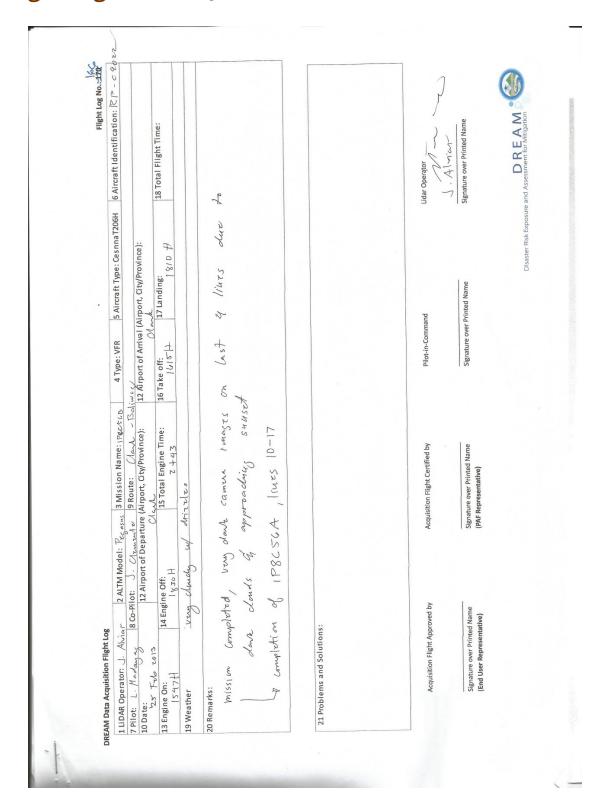
Annex H. FLIGHT LOGS

Flight Log for PAM8CS Mission

Flight Log No.: 165	S Aircraft Type: CesnnaT206H 6 Aircraft Identification: aiport, City/Province):	18 Total Flight Time: ンイ化	average with speod		Lidar Operator MATTO Ansatz Signature over Printed Name Signature over Printed Name DREAM Disaster Risk Exposure and Assessment for Mittgattom
	snnaT206H 6 Al				Lider Signa Signa Signa Fer Risk Exposure and J
	4 Type: VFR 5 Aircraft Type: Cesnn 12 Airport of Arrival (Airport, City/Province):	17 Landing:	of the state.		
	1 8	16 Take off:	as face classed	2)	Pilot-in-Command L - MADA Signature over Printed Name
	Clerk. (Probad 12 A		Jan 1	byer feel	d by
	AND 2 ALTM Model: Constant 3 Mission Name: 108 COSTAP RO-Pilot: 104 Medical 9 Route: 04 And 17 Air	15 Total Engine Time: 3 + 10	c to sen	odre b	Acquisition Flight Certified by Signature over Printed Name (PAF Representative)
	8 Co-Pilot: Chemerate	Off: 12:30	flying Reaght to fine of the prince of the p	s: bone cloube = 1	4 1005
	Ark AND 2/	14 Eng	4 2 3	Solutions:	Acquisition Flight Approved by May WAT AND Signifure over Printed Name (End User Representative)
	DREAM Data Acquisition Flight Log 1 LiDAR Operator: Mark 7 Pilot: Papar	10 Date: ACTO 1013. 13 Engine On: 9:30. 19 Weather	20 Remarks: adrict	21 Problems and Solutions	Acquisition F

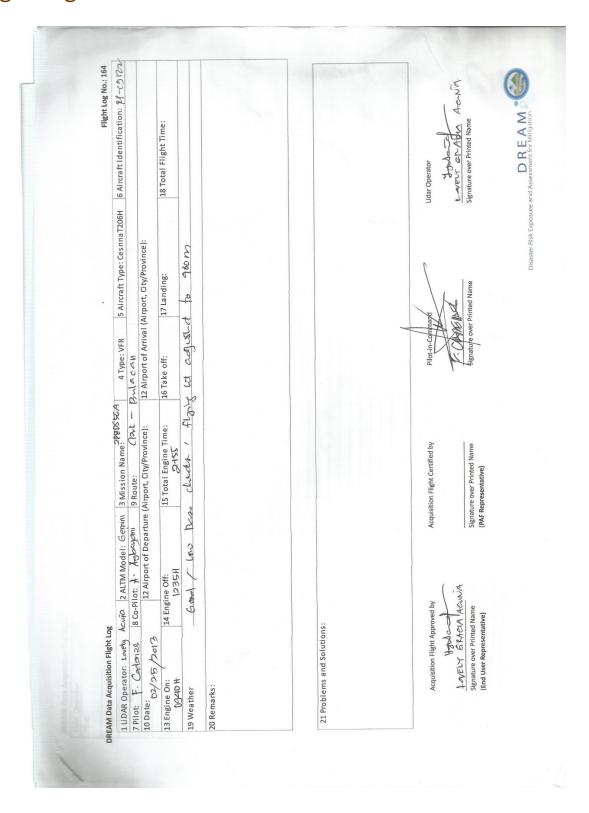
Annex H

Flight Log for 1P8Co56B Mission



Annex H. FLIGHT LOGS

Flight Log for PAM8D Mission



Annex H

Flight Log for PAM8D Mission

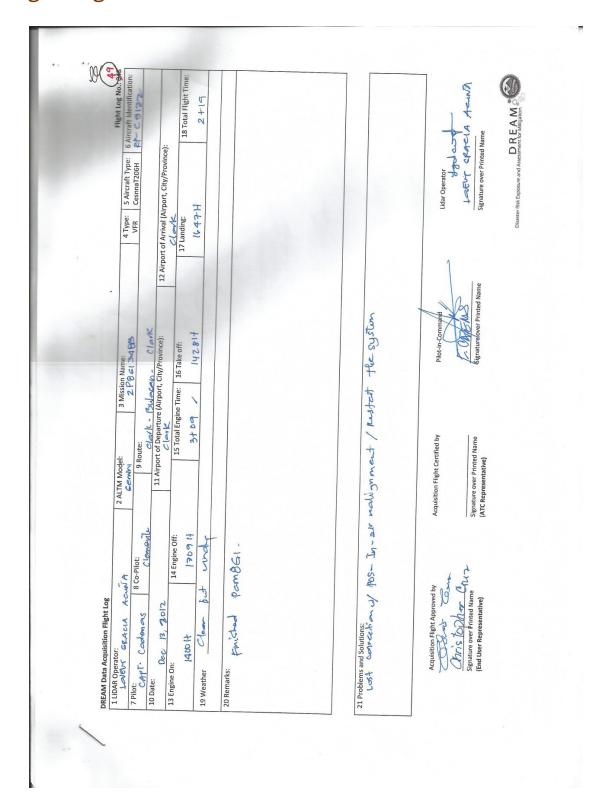
Total Capears Stop Pilots Asgray Asker Ask	8 Co-Pi	3 Mission Name: 2PW46.13	4 Type: VFR	5 Aircraft Type: CesnnaT206H	6 Aircraft Identification: Pp crim
12 Airport of Departure (Airport, City/Province): 12 Airport of Parival (Airport, City/Province): 16 Take Off: 17 Landing: 16 Take Off: 18 Take Off	12 Airport of Departure (A	1	4		
4 Engine Off: 15 Total Engine Time: 16 Take Off: 17 Landing: 193 H Clear THE R ATTER EVENT WHERE Ved by Acquisition Flight Certified by Right and Signature over Printed Name (PAF Representative) Signature over Printed Name (PAF Representative)	CA CA		12 Airport of Arrival	(Airport, City/Province):	*
Clear LATER EXEM WIEPE Ved by Acquisition Flight Certified by Pilot-in-Command Signature over Printed Name Signature over Printed Name (PAF Representative)	14 Engine Off:	4	16 Take off:		18 Total Flight Time:
red by Acquisition Flight Certified by Pilot-in-Command Signature over Printed Name Signature over Printed Name Signature over Printed Name Signature over Printed Name					
ved by Acquisition Flight Certified by Pilot-in-Command Signature over Printed Name Signatu	olsinule.				
Acquisition Flight Certified by Pilot-in-Command Signature over Printed Name (PAF Representative)	×	m			
ved by Acquisition Flight Certified by Pilot-in-Command Signature over Printed Name Signature over Printed Name					
ved by Acquisition Flight Certified by Pilot-in-Command Signature over Printed Name Signature over Printed Name (PAF Representative)					
	Acquisition Flight Approved by Acquisition Signature over Printed Name Signature (PAF Representative)	on Flight Certified by	Pilot-in-Comr	nand r Printed Name	Lidar Operator Tho ported Signature/over Printed Name

Annex H. FLIGHT LOGS

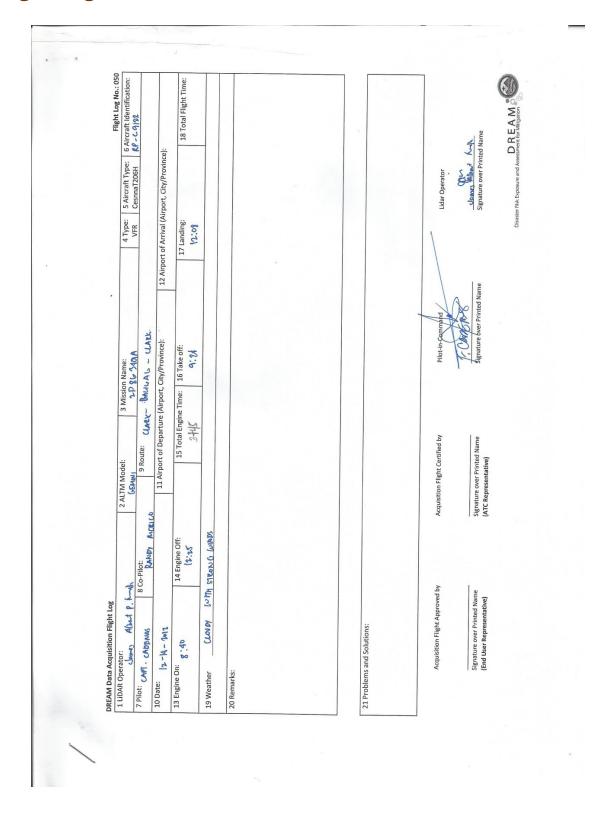
Flight Log for PAM8E Mission

11 DORG DESCRIPTION THAT IS NOT THE STANDARD STA	Flight Log No.: 053	A Pic	Province): 18 Total Flight Time:		(tie ling).	maybe the	y on the		tor	Signature over Printed Name	DESTRET RIsk Exposure and Assessment for Metgation	
The state of the secondation of		4 Type: 5 Aircraft VFR CesnnaT2C	Airport of Arrival (Airport, City)	_	Bleeby line	6 th gins	mmunicaths	205 NA	Lidar Opera	Signature ov	Disaster Riek Exposure	
Might Log MISTORIAN 8 CO-Pilot: 14 Engine Off: 15 2012 14 Engine Off: 15 2012 16 Att B. COMM 16 Acquisition F 16 Acquisition F 17 COMM 18 COMM 18 COMM 19 Acquisition F 10 Fight Approved by 10 Fight Approved by 11 Engine Off: 12 COMM 13 Engine Log 14 Comm 15 COMM 16 Comm 17 Comm 18 Comm 18 Comm 18 Comm 19 Comm 19 Comm 19 Comm 10 Comm 11 Comm 12 Comm 13 Comm 14 Comm 15 Comm 16 Comm 17 Comm 18 Comm 18 Comm 18 Comm 18 Comm 18 Comm 18 Comm 19 Comm 19 Comm 19 Comm 10 Comm	,	2		0		5th Bire t		restart the se	Pilot-in-Dommand	Signature over Printed Name		
MISTERIAL PARTY OF THE BOOK OFFICE OF THE BOOK OFFICE OF THE OFFICE OFFI		2 ALTM Model: 3 Miss			garallel Rines	the middle of	the System	O: Just	equisition Flight Certified by	gnature over Printed Name TC Representative)		
		Mistoric Rus	14 25 14 Engine Off	'	lished 1/6 states	shating	10	fions:		T		

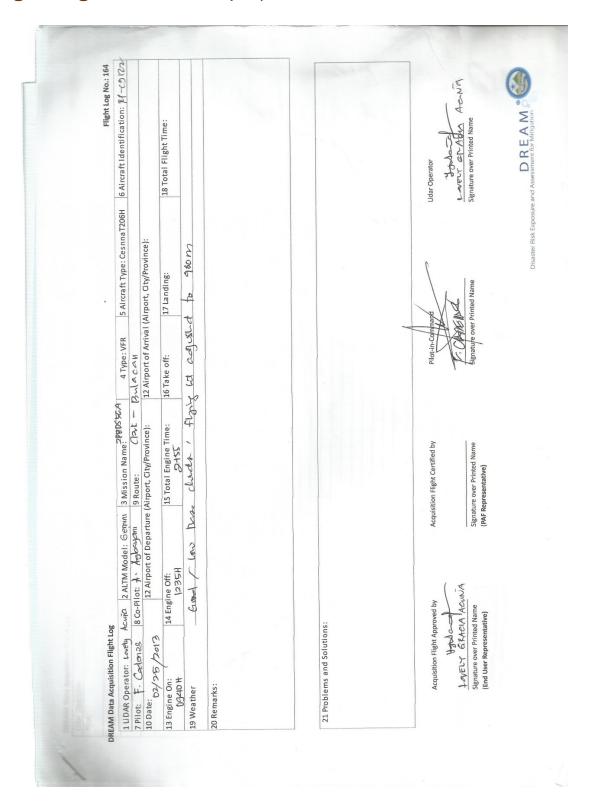
Flight Log for PAM8G1 Mission



Flight Log for PAM8G2 Mission



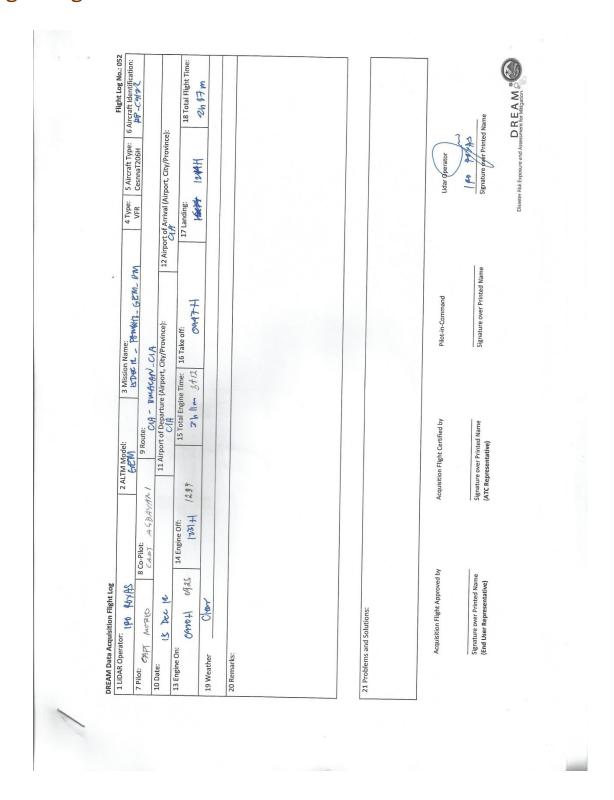
Flight Log for PAM8DS (G2) Mission



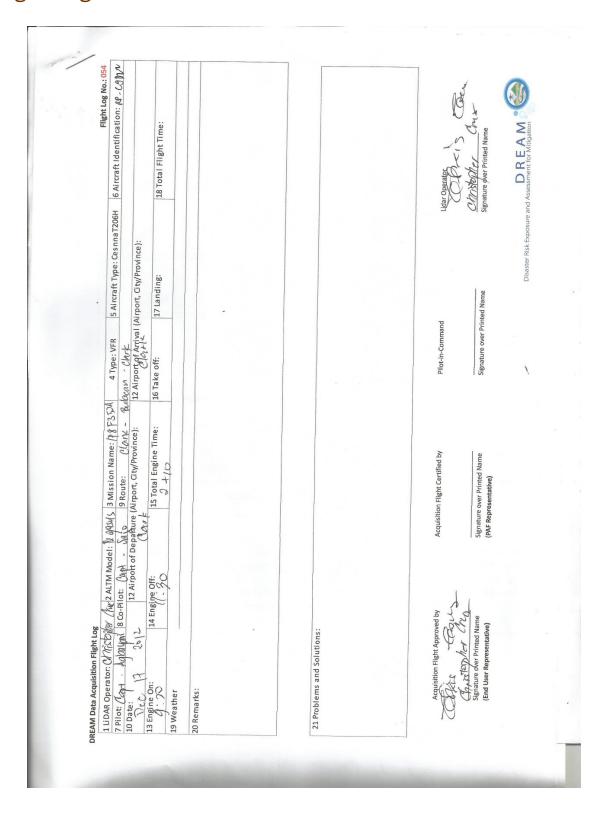
Flight Log for PAM8H1 Mission

* *	Flight Log No.: 051 6 Aircraft Identification:	72/60/12	ce):	18 Total Flight Time:			ted Name DREAM Cosment for Milgation
	e: 5 Aircraft Type:		12 Airport of Arrival (Airport, City/Province): $C(\mathcal{A})$	IB:	7	Udar Operator	Signature piver Printed Name Signature piver Printed Name DREAM Disaster Risk Exposure and Assessment for Alliquion
	4 Type:	VFR	12 Airport of Arriva	17 Landing:	7,50		
	ame:	- C14	/Province):	16 Take off:		Pilot-in-Coumpand	Signature over Printed Name
	3 Mission Name:	C(A - Bulgan			2 8 2 /		La
	2 ALTM Model:	9 Route:				Acquisition Filght Certified by	(ATC Representative)
	2	SHARW		14 Engine Off: 763		Acqu	Signa (ATC
Hight log	a poxys	NAK 8 CO-PILOT:		13 38 14 6	Fint	s and Solutions: Acquisition Flight Approved by	Signature over Printed Name (End User Representative)
DREAM Data Acquisition Flight Log	1 LiDAR Operator: 1828	7 Pilot: CAPT CADENUM	10 Date: 14 Dec	13 Engine On: (336 M	19 Weather F 20 Remarks:	2.1 Problems and Solutions: Acquisition Flight	Signature ow (End User Re)

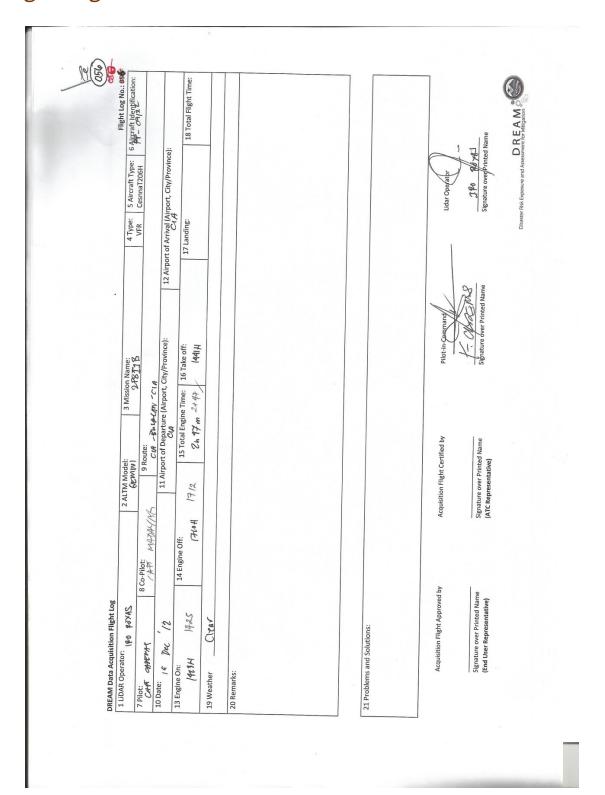
Flight Log for PAM8H2 Mission



Flight Log for PAM8I Mission



Flight Log for PAM8I Mission



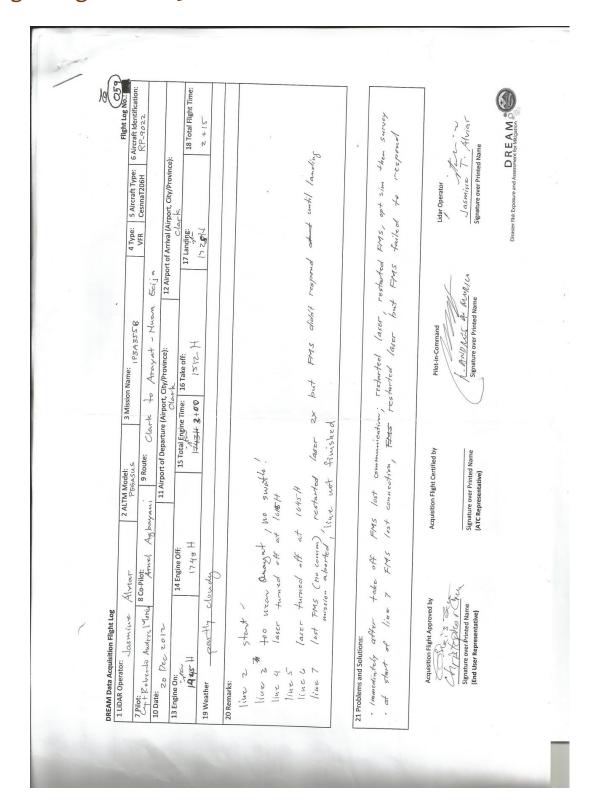
Flight Log for PAM8FS Mission

Till Disk Operator Port	DREAM Data Acquisition Flight Log	The second secon			•	Flight Log No.: 167
Acquisition Flight Approved by Acquisition Flight Representative) Acquisition Flight Approved by Acquisition Flight Representative) Signature over Printed Name Signature over Pr	Operator: KorAS	M Model: 6 EM	3 Mission Name: 24/400 13		5 Aircraft Type: CesnnaT206H	6 Aircraft Identification: Pront
15 Total Engine Time: 16 Take off: 17 Landings Clear Clear Prof. Mag 24.19 Clear Coloring Place off: 17 Landings Acquistion Flight Certified by Pilot-in-Command Signature over Printed Name Representative) Signature over Printed Name Signature over Printed Name (PAF Representative)	CADUMAS	12 Airport of Departure	(Airport, City/Province):	12 Airport of Arrival	(Airport, City/Province):	
THERE IS THE PROPERTY OF THE PARTY OF THE PROPERTY OF THE PROP	FOR 13	2		16 Tabo off.	17 anding.	18 Total Elight Time
For Profit Mark Every Warder For and Solutions: S and Solutions: Acquisition Flight Approved by Acquisition Flight Certified by Acquisition Flight Certified by Acquisition Flight Certified by Acquisition Flight Approved by Acquisition Flight Certified by Acquisition Flight Approved by Acquisition Flight Certified by Pilot-in-Command Signature over Printed Name Signature over Printed Name Signature over Printed Name Signature over Printed Name	1/58H	ingine Off:	8	To lake off:	1	10 10tal Filght 11116.
S and Solutions: Acquisition Flight Approved by Acquisition Flight Certified by Acquisition Flight Mame Signature over Printed Name (PAF Representative) Signature over Printed Name (PAF Representative)						
to profit the proved by Acquisition Flight Certified by Pilot-in-Command autistion Flight Approved by Acquisition Flight Mare over Printed Name Signature over Printed Name (PAF Representative)		Ren				
oved by Acquisition Flight Certified by Pilot-in-Command Name Signature over Printed Name Signature over Printed Name (PAF Representative)	4	MER				
oved by Acquisition Flight Certified by Pilot-in-Command Signature over Printed Name Signature over Printed Name (PAF Representative)	water,	ATOR ENER WHEN	20			
oved by Acquisition Flight Certified by Pilot-in-Command Name Signature over Printed Name Signature over Printed Name (PAF Representative) Signature over Printed Name						
oved by Acquisition Flight Certified by Pilot-in-Command Name Signature over Printed Name Signature over Printed Name (PAF Representative)						
oved by Acquisition Flight Certified by Pilot-in-Command Name Signature over Printed Name Signature over Printed Name (PAF Representative)						
Acquisition Flight Certified by Pilot-in-Command Signature over Printed Name (PAF Representative)	21 Problems and Solutions:					
Acquisition Flight Certified by Pilot-in-Command Signature over Printed Name Signature over Printed Name (PAF Representative)						
Signature over Printed Name (PAF Representative)	Acquisition Flight Approver		ition Flight Certifled by	Pilot-in-Comm	pue	Lidar Operator
Disaster Risk Exposure and Assessment for Mitigation	Signature over Printed Nan (End User Representative)		ure over Printed Name epresentative)	Signature ove.	r Printed Name	Signature/over Printed Name
					Disaster Risk Exposure	D R E A M

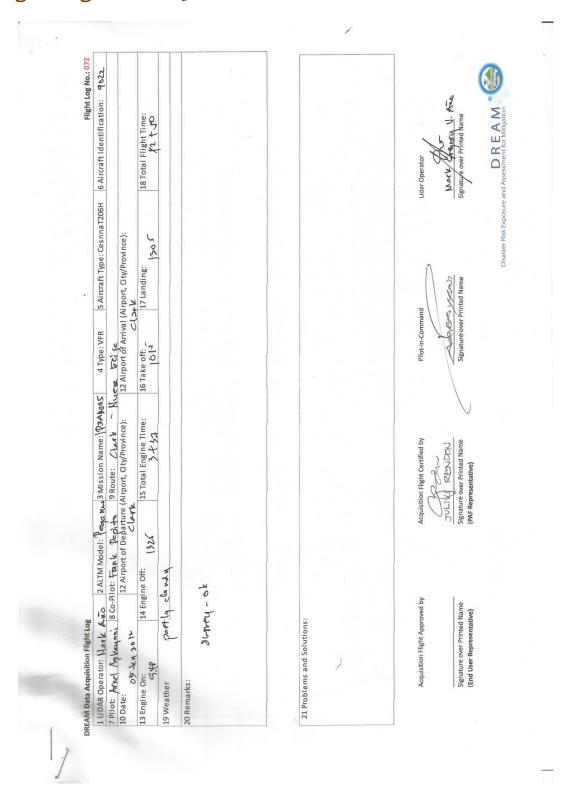
Flight Log for PAM8J Mission

Hight tog No.: 05-	6 Airci	:[65]	18 Total Elight Time	2+30			Mark Character V. And Signature over Printed Name Filst Exposure and Assessment for Magazian
	4 Type: 5 Aircraft Type: VFR CesnnaT206H	12 Airport of Arrival (Airport, City/Province):	Clark 17 Landing:	12:10		Tides Organization	Обызи
	ame: P&F 3SSA	ue:		04:40		PilotinicCommand	2. HADNAT BY WOLL CO. Signature over Frinted Name
	Model: 3 Mission Name:	Airport of Departure (Airpor	15 Total Engine Time: 16 Take off:	3+20		th claudes restart the institute of the consistion Flight Certified by	Signature over Printed Name (ATC Representative)
	y V. Ano 2 ALTM Model:	Armel Ambayani	14 Engine Off:	12:30	hp	their henge	بخ
DREAM Data Acquisition Flight Log	1 LiDAR Operator: Nark Gregory 7 Pilot	Wi Co	20 Dec 2017.	9:10	19 Weather Partly Cloudy	21 Problems and Solutions: PMC- NAV PAT	Chirich There Signature over Printed Name (End User Representative)

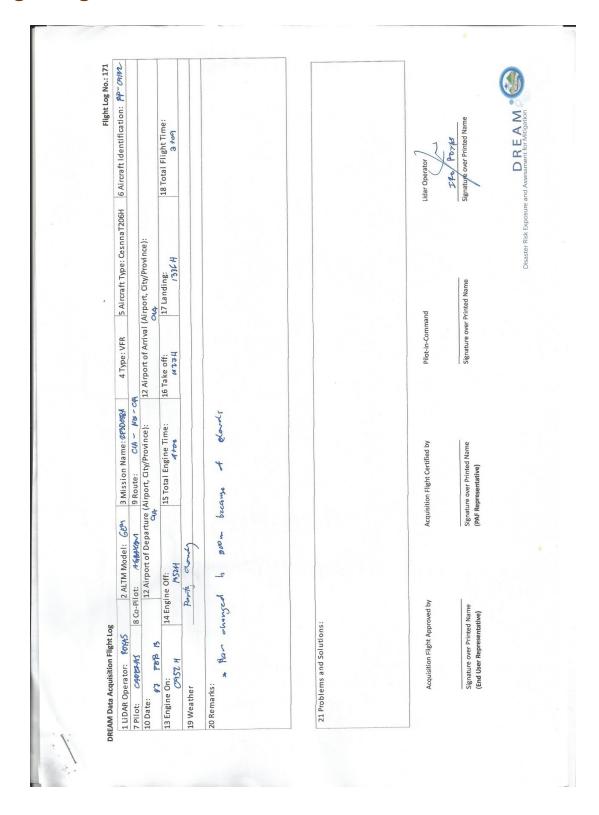
Flight Log for PAM3A Mission



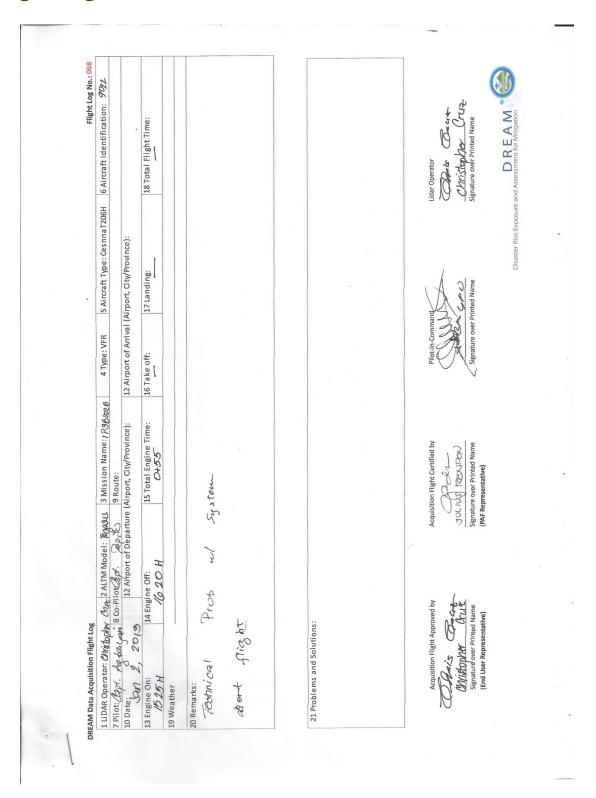
Flight Log for PAM3A Mission



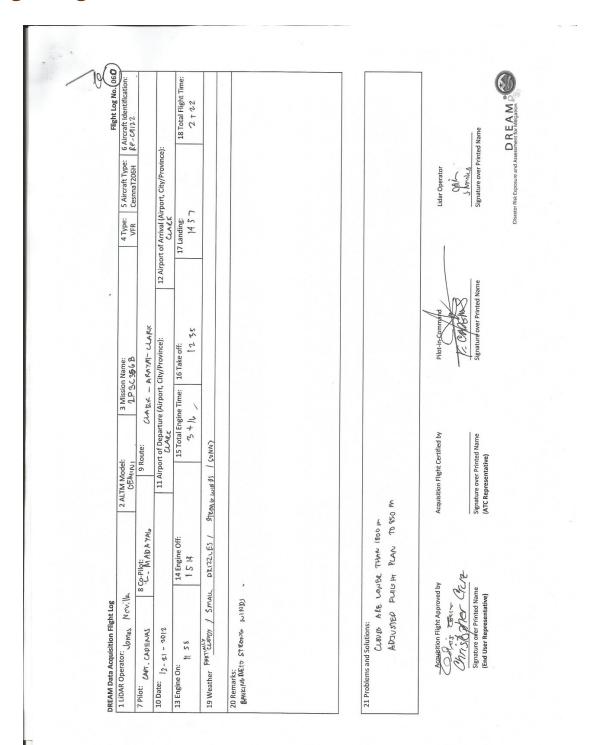
Flight Log for PAM3DS Mission



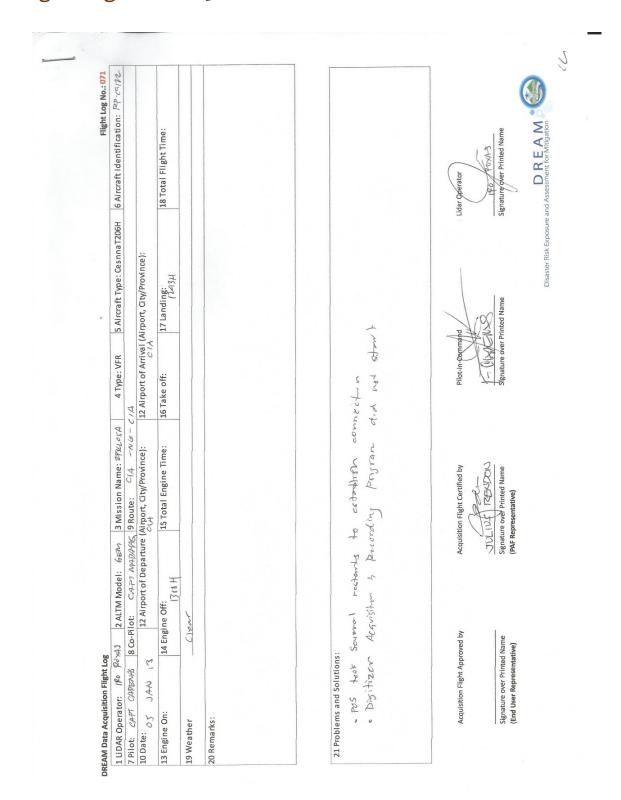
Flight Log for PAM3B Mission



Flight Log for PAM₃C₁ Mission



Flight Log for PAM₃C₂ Mission



Flight Log for PAM3D Mission

4 Type: VFR 5 Aircraft Type: Cesnna 1206H 6 Aircraft Identification: K1-C902. Nuew Ective 12 Airport of Airwal (Airport, Gity/Province):	17 Landing: 18 Total Flight Time: 12.5% 34 03	tion error)		ind Udar Operator
Nuew Ecta 12 Airport of Arrival (16 Take off: 09:47	bess communica		Pilot-in-Command
AS 2 ALTM Model: Peggaus 3 Mission Name: 1930002A 8 Co-Pilot: Frank Pegga 9 Broute: Clark to 12 Aiport of Departure (Aiport, Gly/Province): Clark	15-56 1:13 Atold Engine Time:	that te refact pyrtan once due to loss communication error)		Acquisition Flight Certified by
1 LiDAR Operator: Mark Ans 2 ALTM 7 Pilot: Arnel Aybuyani 8 Co-Pilot: Fr 10 Date: 03-Jan 3012	14 Engine C	20 Remarks: - sarvey ok (hul to	21 Problems and Solutions:	Acquisition Flight Approved by

Flight Log for PAM₃CS (3D) Mission

2 ALTM Model: Regions 3 Mission Name: 172C.505/84 4 Type: VFR 5 Aircraft Type: CesnnaT206H Olt: 4. Cleaved Pawyp angles 17 Almort All Minort Claubenings).		\$0	: Pos name 1735/58A Imposión aborted due to thick, douds & air traffic	ons: , think of low, changed plans to ssountate, still within clauds traffic of clouds at ssounton, mission aborted as per pilots, discretion	Acquisition Flight Certified by Pilot-in-Command	Signature over Printed Name (PAF Representative) Signature over Printed Name (PAF Representative) DREAM DREAM
DREAM Data Acquisition Flight Log 1 LiDAR Operator: J. Alviar 2 ALTM Model: Regions 17 Philot: L. Madaway 8 Co-Pilot: 1, Clause, Perilot: 1, C	13 Engine On: 27 Feb 2013 13 Engine On: 0455 ∰ 14 Engine Off: (19	19 Weather Vous cloudy	20 Remarks: Pos name 1P35158A Inglssion aborted dux	21 Problems and Solutions: clouds too thick diffe the thoo hunch that the fi	Acquisition Flight Approved by	Signature over Printed Name (End User Representative)

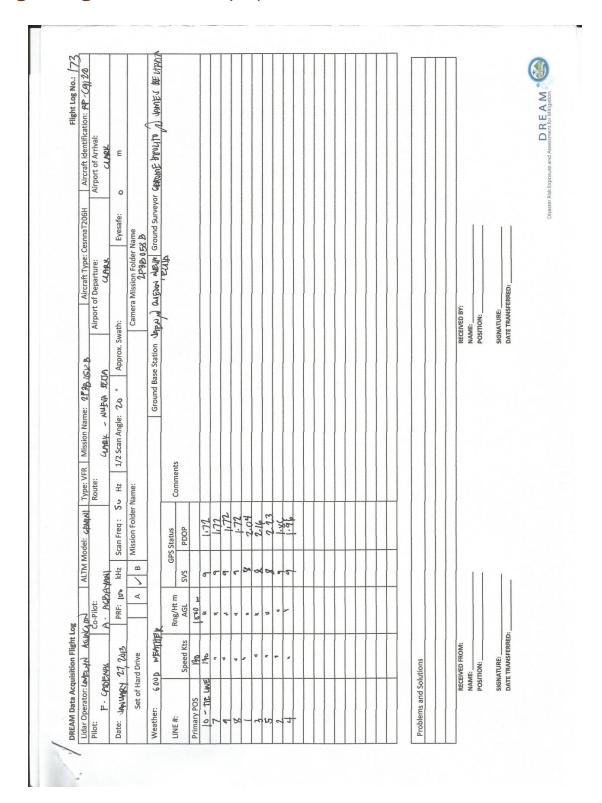
Flight Log for PAM3E Mission

2 ALTM Model: PEGHAN 3 Mission Name: 1990 A A Type: VFR 5 Arrash Type: Cosnna1206H 6 Aircraft Identific (SO-Pilot: Capturate (Airport of Arriva) (Airport of Airport of Arriva) (Airport of Airport of Airpor	2 ALTM Model: Reserved 3 Mission Name: 1936-014 4 Type: VFR 5 Aircraft Type: Cosnna1206H 6 Aircraft Identific ICO-NICC 12 Aircraft Type: Cosnna1206H 6 Aircraft Identific ICO-NICC 12 Aircraft Type: Cosnna1206H 6 Aircraft Identific ICO-NICC 12 Aircraft Identific ICO-NICC 12 Aircraft Identific ICO-NICC 13 Total Engine Time: 15 Total Engine T	Scoring Zalim Model: PEd-Mod Sinission Name: PEd-Mod Sinission Name: PEd-Mod Sinission Name: PEd-Mod Sinission Name: PED-Model: PED					Flight Log No.: 070
Co-Pilot: Care House: CAA - Na - CAA 12 Airport of Arrival (Airport, City/Province): 12 Airport of Arrival (Airport, City/Province): 13 Airport of Arrival (Airport, City/Province): 14 Engine Off: 15 Total Engine Time: 15 Total Engine Time: 16 Take off: 17 Landing 18 Signature over Printed by 18 Acquisition Flight Certified by Acquisition Flight Certified by 18 Acquisition Flight Certified by 19 Route over Printed Name Signature over Printed Name	Co-Pilot: Cat June 19 Route: CA - ND - CAH 12 Airport of Amival (Airport, Clay) Province): 12 Airport of Amival (Airport, Clay) Province): 15 Total Engine Time: 16 Take off: 17 Landing 18 Strun 19 Str	12 Airport of Arrival (Airport, City/Province): 12 Airport of Arrival (Airport, City/Province): 12 Airport of Arrival (Airport, City/Province): 15 Total Engine Off: 15 Total Engine Time: 16 Take off: 17 Landing 15 Total Engine Time: 16 Take off: 17 Landing 15 Total Engine Time: 16 Take off: 17 Landing 17 Landing 18 Landing		del: PECHIM 3 Mission Name: 193604A	4 Type: VFR	5 Aircraft Type: CesnnaT206H	6 Aircraft Identification: や・このい
12 Airport of Departure (Airport, Gty/ Province): 12 Airport of Arrival (Airport, Gty/ Province): 12 Airport of Arrival (Airport, Gty/ Province): 15 Total Engine Time: 16 Take off: 17 Landing 17 Landing 18 Signature over Printed Name (PAF Representative)	12 Airport of Departure (Airport, City/Province): 12 Airport of Arrival (Airport, City/Province): 15 Total Engine Time: 16 Take off: 17 Landing 18 Sizart 18 Take off: 17 Landing 19 Sizart 18 Sizart 19	12 Airport of Departure (Airport, City/Province): 12 Airport of Arrival (Airport, City) Shyriff Clevely Shyriff Clevely Construct fires Co	8 Co-Pi				
Signature over Printed Name	Signature over Printed by Acquisition Flight Certified by Acquisition Flight Certified by Acquisition Flight Certified by Pilot-in-Command Signature over Printed Name	Signature over Printed Name	13	of Departure (Airport, City/Province): $C(\mathcal{H})$	12 Airport of Arrival	(Airport, City/Province): ○ℓ∯	
Slysufty Cloudy correction to continue times correctly of orbite error red by Acquisition Flight Certified by Pilot-in-Command Signature over Printed Name	Signiffy Cloudy continued to continue times extent restort extent restort extent of orbitic error red by Acquisition Flight Certified by Pilot-in-Command Signature over Printed Name	Slysufty Cloudy corrections for contract times correct of contract times coult of cotton error solution flight certified by Acquisition flight certified by Not to presentative) Signature over printed Name	14 Engine C		16 Take off:	17 Landing:	18 Total Flight Time:
create to continue times crows of orbite error red by Acquisition Flight Certified by Pilot-in-Command Signature over Printed Name	criter : restort country of country of country of security fight Certified by Acquisition Flight	course of contract three courses the contract three courses of contract course of contract course of contract course course of contract course course of contract course c		nga			
country of contract fires country of contract fires country cou	error coult of orbite error red by Acquisition Flight Certified by Pilot-in-Command Signature over Printed Name Signature over Printed Name Signature over Printed Name Signature over Printed Name	error coulc of cobbe error red by Acquisition Flight Certified by Pilot-in-Command Signature over Printed Name					
ector respect times countrate of orbite error red by Acquisition Flight Certified by Pliot-in-Command Signature over Printed Name	error restort coulc of coborc error ed by Acquisition Flight Certified by Pilot-in-Command Signature over Printed Name Signature over Printed Name Signature over Printed Name Signature over Printed Name	ector respect times could by Acquisition Flight Certified by Plipt-in-Command No. 104 REPRESENTED Signature over Printed Name	13				
ector is restort red by Acquisition Flight Certified by Pilot-in-Command Signature over Printed Name	ector (colored ecron) red by Acquisition Flight Certified by Pllot-in-Command Signature over Printed Name Signature over Printed Name (PAR Representative)	ector of corbor error red by Acquisition Flight Certified by Pilot-in-Command Signature over Printed Name	. unable				
certer restort ved by Acquisition Flight Certified by Pilot-in-Command Signature over Printed Name Signature over Printed Name Signature over Printed Name Signature over Printed Name	red by Acquisition Flight Certified by Pliot-in-Command Command Comman	red by Acquisition Flight Certified by Pilot-in-Command Signature over Printed Name Signature over Printed Name Signature over Printed Name (PAF Representative)					
ector restort red by Acquisition Flight Certified by Plipt-in-Command Signature over Printed Name Signature over Printed Name Signature over Printed Name Signature over Printed Name Signature over Printed Name Signature over Printed Name	ector : restort red by Acquisition Flight Certified by Pilot-in-Command Signature over Printed Name Signature over Printed Name (PAF Representative)	ector restort red by Acquisition Flight Certified by Pilot-in-Command Signature over Printed Name Signature over Printed Name Signature over Printed Name Signature over Printed Name	(
Acquisition Flight Certified by Flight Certi	Acquisition Flight Certified by Acquisition Flight Certified by Acquisition Flight Certified by Acquisition Flight Certified by Signature over Printed Name (PAF Representative)	Acquisition Flight Certified by Flight Certi	solutions:				
Acquisition Flight Certified by Acquisition Flight Certified by TOLIUM RESULTAN Signature over Printed Name (PAF Representative)	Acquisition Flight Certified by	Acquisition Flight Certified by Acquisition Flight Certified by Thoughton Command Signature over Printed Name (PAF Representative)	Crist	restort			
Acquisition Flight Certified by The Many C. ISA Signature over Printed Name (PAF Representative)	Acquisition Flight Certified by TOLLION RESULTAN Signature over Printed Name [PAF Representative]	Acquisition Flight Certified by The control of the certified by Signature over Printed Name (PAF Representative)	scoule of	whole comm			
Acquisition Flight Certified by SULLY REALTH Signature over Printed Name (PAF Representative)	Acquisition Flight Certified by The Command Acquisition Flight Certified by Sultant Certified by Signature over Printed Name (PAF Representative)						
Acquisition Flight Certified by STULLIVE REALDSA Signature over Printed Name (PAF Representative)	Acquisition Flight Certified by Moud C. IN Signature over Printed Name (PAF Representative)	Acquisition Flight Certified by Signature over Printed Name (PAF Representative)					
Signature over Printed Name (PAF Representative)	Signature over Printed Name (PAF Representative)	Signature over Printed Name (PAF Representative)	on Flight Approved by	Acquisition Flight Certified by	Pilot-in-Comr		Lidar Operator
Signature over Printed Name (PAF Representative)	Signature over Printed Name (PAF Representative)	Signature over Printed Name (PAF Representative)		JULIA REVEN	Harry	C. (ERS)	I per ports
	במפסיבו וויפו היו מיים במיים ב	TO NORTH THE TOTAL OF THE PROPERTY AND THE PROPERTY.	over Printed Name Representative)	Signature over Printed Name (PAF Representative)	Signature ovè		Signature over Printed Name DREAM DREAM

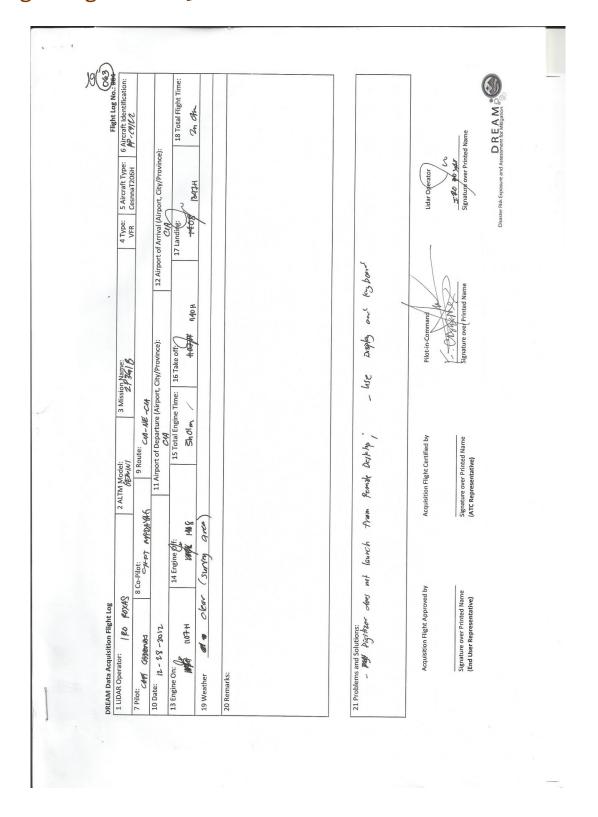
Flight Log for PAM3E Mission

					Flight Log No.: 074
R Operator: Jasmine Alv	riar 2 ALTM Model: Pegasus	1 LIDAR Operator: Jasmine Alvian 2 ALTM Model: Pegasus 3 Mission Name: 1836005B	4 Type: VFR	5 Aircraft Type: CesnnaT206H 6 Aircraft Identification:	6 Aircraft Identification: ADJ
	8 Co-Pilot: Pepito	Nrc	ia Ocija		-
10 Date: Jan 5, 2013	12 Airport of Departure (Airport, City/Province):		12 Airport of Arrival Clark	12 Airport of Arrival (Airport, City/Province): $C(lpha_{\mathcal{L}}\mathcal{K})$	
	14 Engine Off: H	15 Total Engine Time:	16 Take off: S 2 8 り	17 Landing:	18 Total Flight Time:
19 Weather	partly doubly				
to complet	to complete Pam3E (lines S-7 & cast corridor)		about 8 Huzz	about 8 times due to clouds	
	lone before end of line	4			
11	ofted survey line	John Song Survey (in 5 was along the way of roturn flight	way of retur	flight	
1	returned to complete	rehund to complete unfluished scotion; done	done		
21 Problems and Solutions: Let No Comm Ther Same creat	before take off;	restorted to continue flight. Huizs during flight.	me flight. ght.		
Acquisition Flight Approved by Construction of the plant Construction Signature over Printed Name [End User Representative]	on the	Acquisition Flight Certified by JULINS TESTON Signature Over Printed Name (PAF Representative)	Pilot-in-Comman	inted Name	Lidar Operator The included land Signature over Printed Name
				Disaster Risk Exposure a	D R E A M Disaster Risk Exposure and Assessment for Mitigation

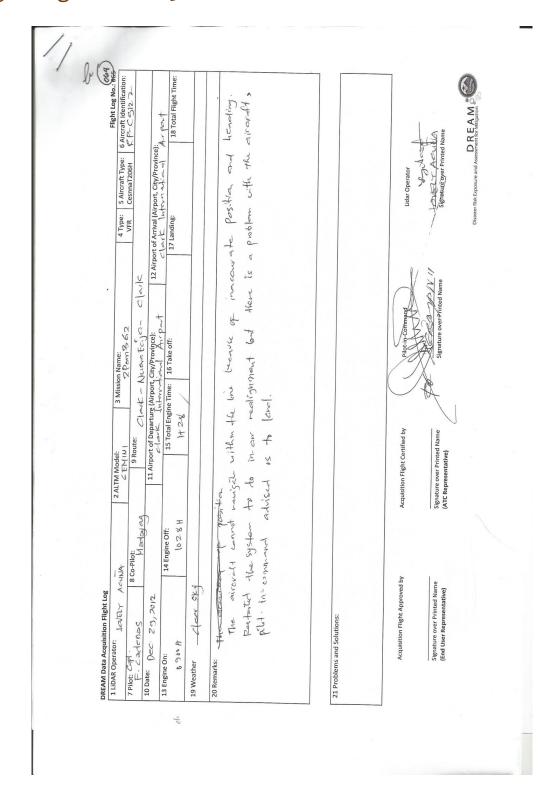
Flight Log for PAM3BS (3F) Mission



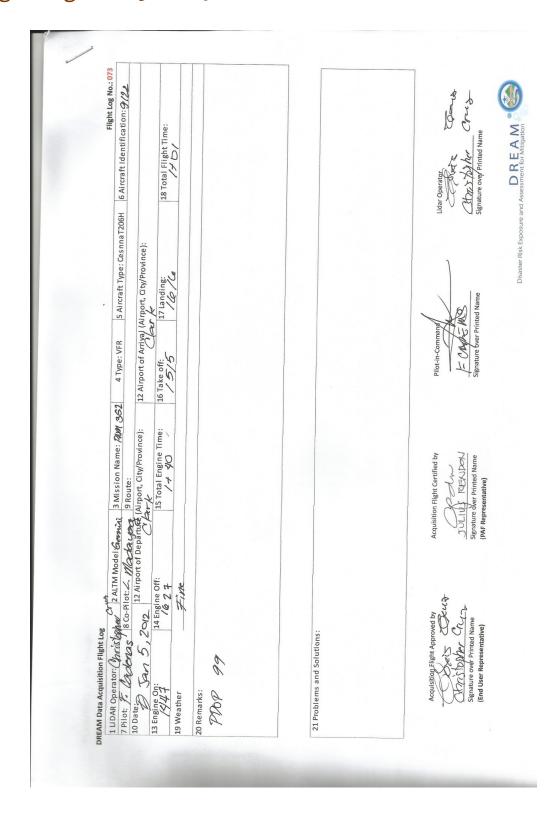
Flight Log for PAM3G1 Mission



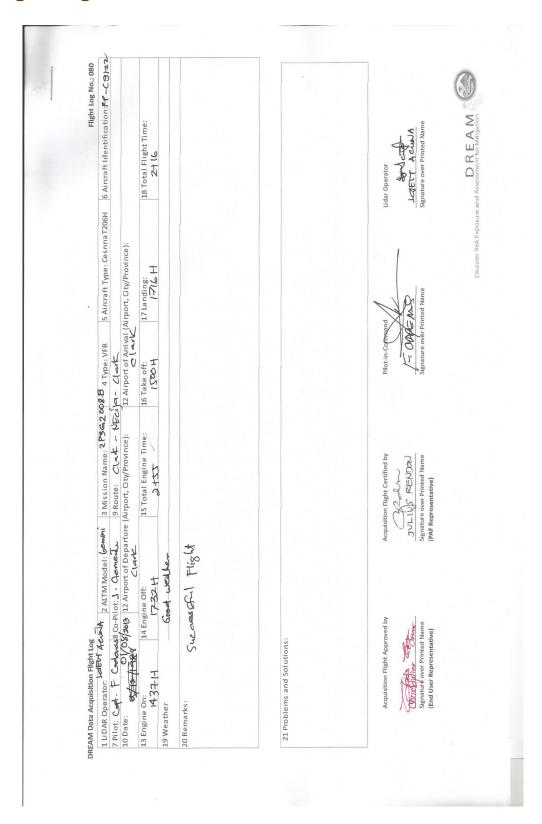
Flight Log for 2PAM3G2 Mission



Flight Log for 1P3G2005B Mission



Flight Log for 2P3G2008B Mission



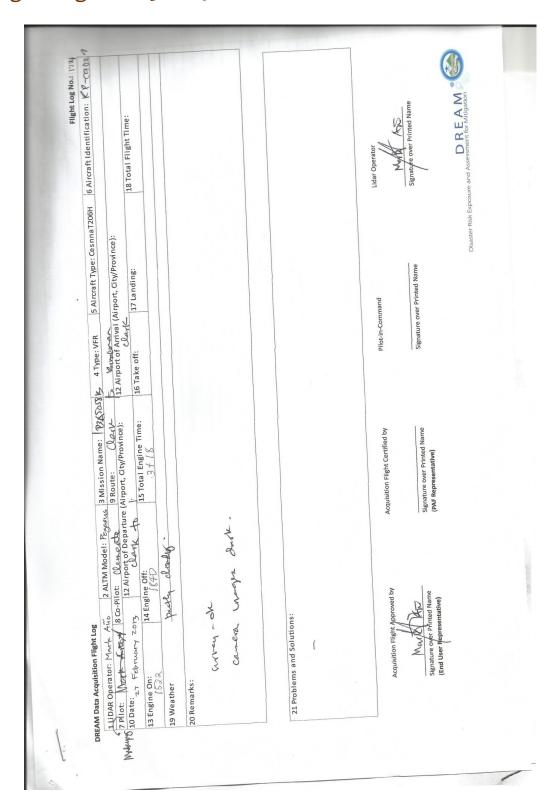
Flight Log for 1P3H364A Mission

Flight Log No.: West 6 Aircraft Identification:	18 Total Flight Time: (7, 20) 1.0	Udar Operator Signature over Pfinted Name DREAM Disaster Flik Exposure and Assessment for Mitgation
ft Type: 6 Airc		Udar Operator A 171 S 100 Serv Signature over Printed Name D R E
4 Type: S Aircraft Type: VFR Cesnna7206H	17 Landing: 655 C Perienains	Udar Operator Lidar Operator Signature over 15
4 Type: S Aircraft Type: 6 VFR Cesnna1206H 2	17 Landing:	
Anton	7	Piloyfin dominand Signature over Printed Name
3 Mission Name: P 3 H 30 K	S of stem	d by Signature over P. Signature over P.
M Model: 3 Mission Name:	15 Total Engine Time: 16 Take off: 2 4/5 5:0.1 Soy	to h
Model: 9 Soute:	West side.) E
2 Ar	3,	Acquisition Flight Certi
(4)	14 Engine Off. 14 20 14 1 W (fie Ring, TMS NAV	
ht Log	for the	
DREAM Data Acquisition Flight Log 1 LiDAR Operator: Mrstor 7 Pilot: Mexico 10 Date: Date	1 1 1 8 3	Solutions: Solutions:
DREAM Data Acquis 1 LIDAR Operator: 7 Pilot: 10 Date:	13 Engine On: 9 05 19 Weather 20 Remarks: 20 Remarks:	21 Problems and Perent Acqui

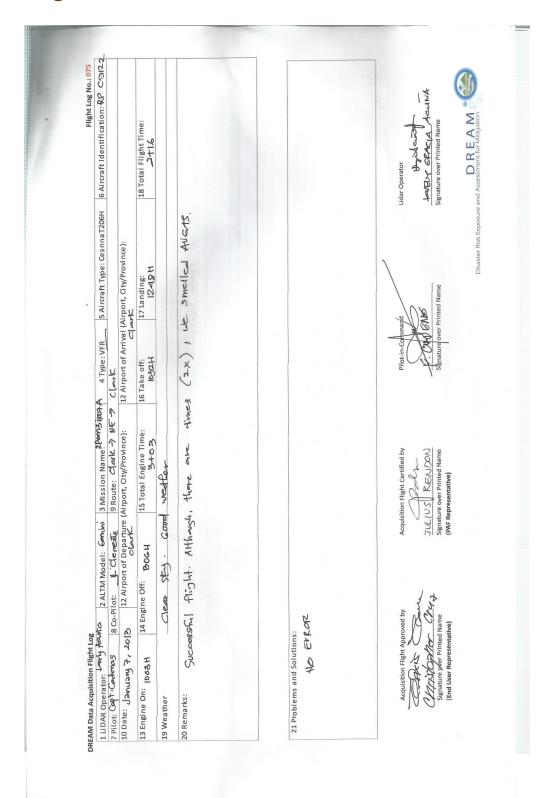
Flight Log for 1P3H364B Mission

DREAM Data Acquisition Flight Log	Bo				Flight Log No.: 066
1 LiDAR Operator:	2 ALTM Model:	3 Mission Name:	4 Type: VFR	5 Aircraft Type: CesnnaT206H	6 Aircraft Identification: RP - G023
7 Pilot:	8 Co-Pilot:	9 Route: CIA - NE-	CA		
10 Date: 12-29-2012	12 Airport of Departure (Airport, City/Province):	(Airport, City/Province):	12 Airport of Arrival	12 Airport of Arrival (Airport, City/Province):	
13 Engine On:	14 Engine Off:	15 Total Engine Time:	16 Take off: #60	17 Landing:	18 Total Flight Time:
19 Weather	chauding				
pata gaps — sch	schedult retilims at in	refugins at in the plant are stone			
Acquisition Flight Approved by		Acquisition Flight Certified by	Pilot-in-Command		2
Signature over Printed Name (End User Representative)		JULIUC RENIDED Signature over Printed Name (PAF Representative)	Signature over	Signature over Printed Name	Signature over Printed Name
				Discussion Old Eventure	DREAM CO.

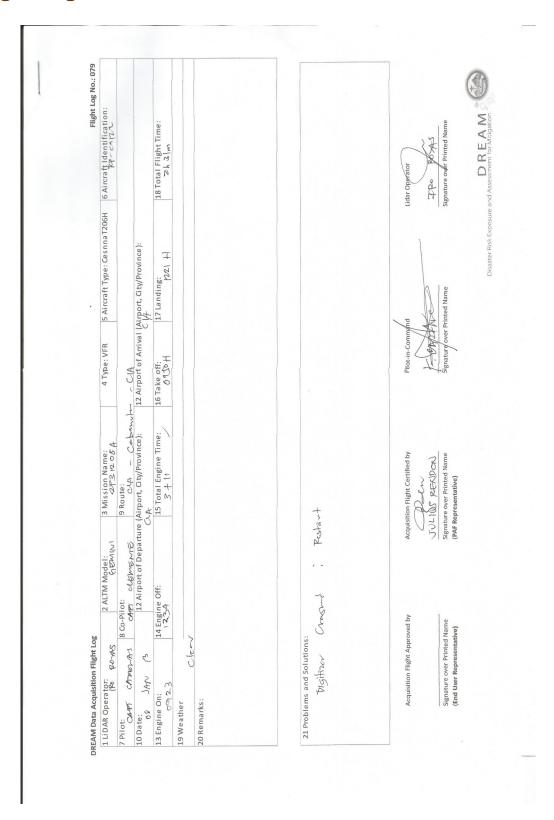
Flight Log for 1P3AS058B Mission



Flight Log for 2PAM3I1007A Mission



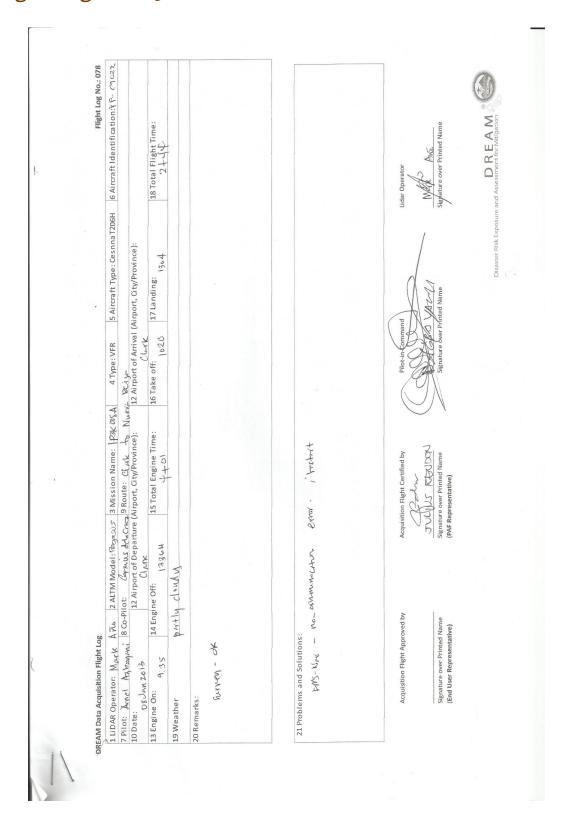
Flight Log for 2P3I2008A Mission



Flight Log for 1P3J007A Mission

STO - OM and I shall I	n: RP-9022									
2	6 Aircraft Identification: RIP-9022			18 Total Flight Time:					Lidar Operator	T 2
	5 Aircraft Type: Cesnna T206H		12 Airport of Arrival (Airport, City/Province): $c(a, r, k)$	17 Landing: 1 < (00 H						1 0
	4 Type: VFR	a Eccia	12 Airport of Arrival	16 Take off: 				٨-	Pilot-in-Command	Signature over
	3 Mission Name: 1P330074	9 Route: Clark - Nuce		15 Total Engine Time: 3 ナル国		due to clouds		and condituted unission.	Acquisition Flight Certified by	(PAF Representative)
	1 LIDAR Operator: Jasumine Almand ALTM Model: Praise cue	8 Co-Pilot: Dela Ghaz	12 Airport of Departure (Airport, City/Province):	14 Engine Off:	cloudy	with saps	۵	Mo coum before take off, restarted o		1
	1 Li DAR Operator: Asswitz	7 Pilot: Aqbayami 8			19 Weather	Veget corridor - done but line 7 - done (no swe line 5 - done (line 5 - done line 5 - done (line 5 - done line 5 - done line 5 - done line 5 - done line 5 - done	East corridor - dou C	No country before	Acquisition Flight Approved by	Signature over Printed Name (End User Representative)

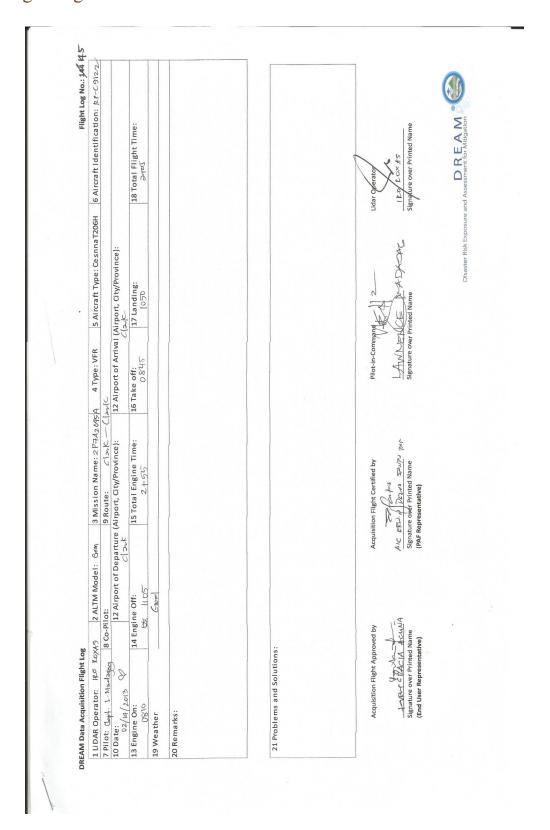
Flight Log for 1P3K008A Mission



Flight Log for 2P7A1043A Mission

Sperator: Kt RoxAs 2 ALTM Model: Genneral Front Front Parks 8 CO-Pilot: Cat 1 Maderial	3 Mission Name: 名和子	4 Type: VFR	5 Aircraft Type: CesnnaT206H	6 Aircraft Identification: ドゲーCのプレ
02/12/2013 12 Airport	(Airport, City/Province):	12 Airport of Arriva	12 Airport of Arrival (Airport, City/Province):	
3 On: 14 Engine Off: 000 H	15 Total Engine Time:	16 Take off:	17 Landing:	18 Total Flight Time: 종사 3 만
ier (laddy	Law Base (lovels (< 1000m)			
rks: possible date gayis	zaps beause of low base	cluds (eyesafely shall and	(the voc
lems and Solutions:				
Acquisition Flight Approved by	Acquisition Flight Certified by For Carter ALC ERSUM PROPOS SOLVERS	Pilot-in-Command	Start	Lidar Operator
Signature over Printed Name (End User Representative)	Signature ove <u>t</u> /Printed Name (PAF Representative)	Signature ove	Signature over Printed Name	Sj <u>é</u> nature over Printed Name
			Disaster Risk Exposure	DREAM Disaster Risk Exposure and Assessment for Mitigation

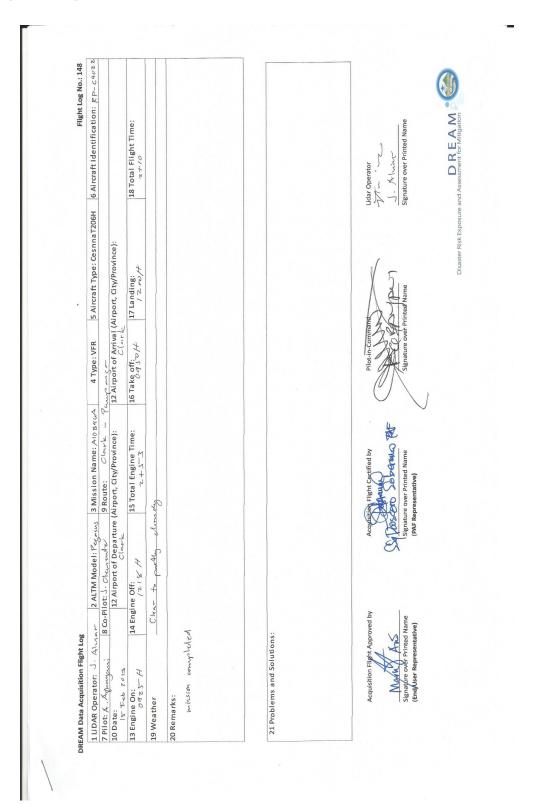
Flight Log for 2P7A2045A Mission



Flight Log for 2P7B1045B2 Mission

A la	DREAM Data Acquisition Flight Log				,	Flight Log No.: 146
Go-Piloti Cenerity 12 Airport of Arrival (Airport, Gty/Province): 12 Airport of Arrival (Airport, Gty/Province): 15 Take off: 16 Take off: 17 Landing: 19 Route: 18 Take off: 18 Take off: 19 Tanding: 19 Route: 19 Route: 10 Take off: 10 Take off: 11 Tanding: 12 Tanding: 13 Tanding: 14 Tanding: 15 Take off: 16 Take off: 17 Landing: 18 Tanding: 18 Take off: 18 Take off: 19 Take off: 10 Take off: 11 Tanding: 12 Tanding: 13 Tanding: 14 Tanding: 15 Take off: 16 Take off: 17 Tanding: 18 Tanding: 18 Tanding: 19 Take off: 19 Take off: 10 Take off: 11 Tanding: 12 Tanding: 13 Tanding: 14 Tanding: 15 Take off: 16 Take off: 17 Tanding: 18 Take off: 18 Take off: 18 Take off: 19 Take off: 19 Take off: 10 Take Representative)	1 LIDAR Operator: Hank Aus	2 ALTM Model:	3 Mission Name:	4 Type: VFR	5 Aircraft Type: CesnnaT206H	6 Aircraft Identification: RF-c9012
S and Solutions: 12 Airport of Departure (Airport, City/Province):	7 Pilot: Ashanai. 8 Co.	-Pilot: Jenente	9 Route: Clark to	KIndonen		
S and Solutions: Signature over Printed Name (PAF Representative)	10 Date: 1 Folgrand 2013	12 Airport of Departure	(Airport, City/Province):	12 Airport of Arrival	(Airport, City/Province):	
s and Solutions: s and Solutions: Acquestion High Approved by Acquestio	3	ngine Off:	15 Total Engine Time:	16 Take off:	17 Landing:	18 Total Flight Time:
s and Solutions: Acquerion light Approved by Acquerion light Certified by Acquerion light Approved by Acquerion light Certified by Signature over Printed Name (PAF Representative)						
ved by Acquisition Night Certified by Pilot-in-Command Signature over Printed Name (PAF Representative)		, y				
ved by Acquisition Pught Certified by Pilot-in-Command Signature over Printed Name Signature over Printed Name (PAF Representative)						
ved by Acquestion Night Certified by Pilot-in-Commann Signature over Printed Name Signature over Printed Name (PAF Representative)	21 Droblems and Colutions					
Acquisition light Certified by December Pilot-in-Command Pilot-)					
Acquisition light Certified by Signature over Printed Name (PAF Representative)						
	Acquisition Flight Approved May May Signature dover Printed Name (End User Representative)	S	right Cert	Pilot-in-Comm	1/ 5	My A KW

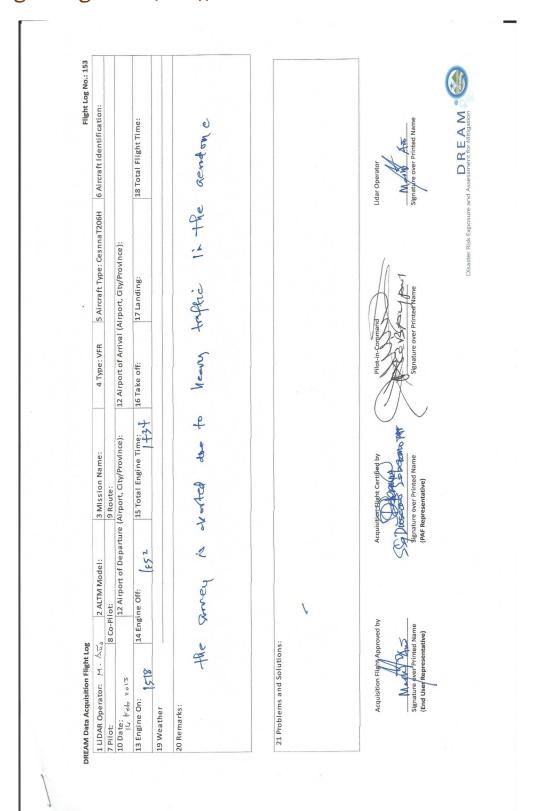
Flight Log for 2PAM7B2046A Mission



Flight Log for 1P7CO44A Mission

1 LIDAR Operator: J. Alvrey 2 ALTM Model: Pigerins 3 Mission Name: 1972 6444 7 Pilot: A. Agbessymm 8 Co-Pilot: J. Chrun wafe 9 Route: Charle 10 Date: D. T-chrun can 12 Aliport of Departure (Aliport, City/Province): D. T-chrum can 13 Engine On: 14 Engine Off: 15 Total Engine Time: 003.9 ch. charles 19 Weather can 12 Charles 19 Weather can 12 Charles 19 Meanths:	The second secon		Flight Log No.: 143
14 Eng	ie: 1アフム ピイム 4 Type: VFR	5 Aircraft Type: CesnnaT206H	6 Aircraft Identification: RP- 6402 2
14 Eng	and - Pour pour ye - as	7	
14 Engine Off: Sept quilly denuty	vince): 12 Airport of Arriv	12 Airport of Arrival (Airport, City/Province):	
	Time: 16 Take off:	17 Landing:	18 Total Flight Time:
done 5/10 lives aborted due to too much	ed.		
, '			
(are C. I a. 2. 8 commented			
Acquisition Flight Approved by North And Signature over Printed Name (End User Representative)		Red Name	Ligar Operator Active Signature over Printed Name
		Disaster Risk Exposure a	Disaster Risk Exposure and Assessment for Mitgation

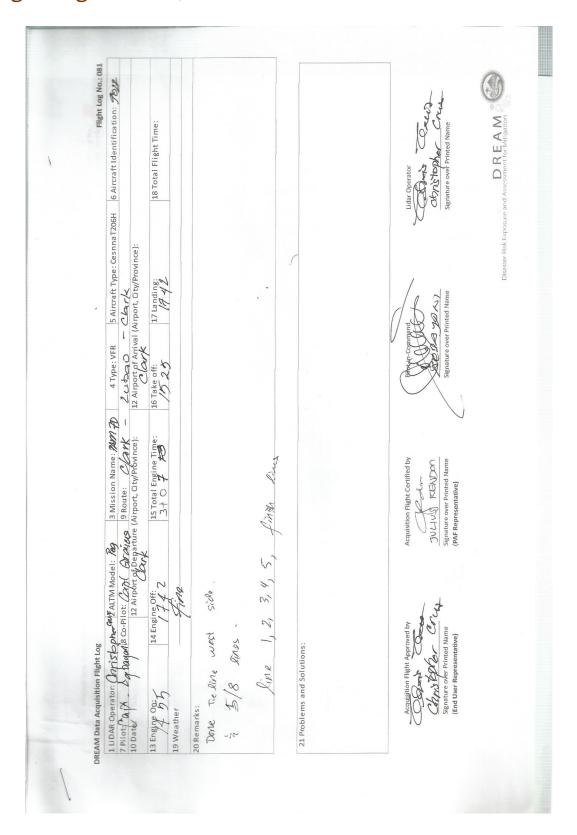
Flight Log for 1P7C047B Mission



Flight Log for 1P7C049B Mission

Flight Log No.: 156	4 Type: VFR 5 Aircraft Type: CesnnaT206H 6 Aircraft Identification:		12 Airport of Arrival (Airport, City/Province):	off: 17 Landing: 18 Total Flight Time: 2485			Lidar Operator Lidar Operator Manne Signature over Printed Name	DREAM Disaster Risk Exposure and Assessment for Mitigation
	3 Mission Name: 4 Type		ty/Province):	15 Total Engine Time: 16 Take off: 2.4%			Acquistion, Flight Coastled by Charles over Printed Name (PAF Representative)	
DREAM Data Acquisition Flight Log	1 LiDAR Operator: rt. A∞ 2 ALTM Model:	3 Co-P	10 Date: 12 Airport of Depart of Dep	13 Engine On: (533) 14 Engine Off: (6)	20 Remarks:	21 Problems and Solutions:	Acquisition glight Approved by North Fro Signature over Printed Name (End Uker Representative)	

Flight Log for PAM7D Mission



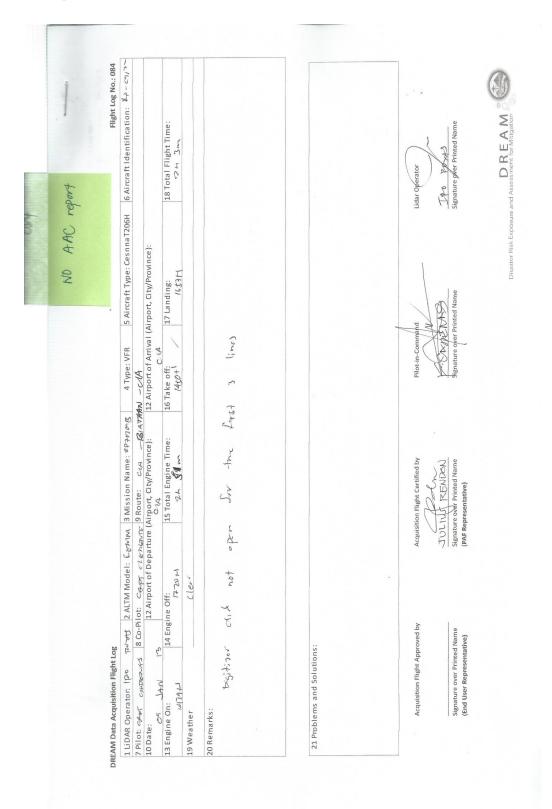
Flight Log for 1P7E047A Mission

Fight Log No.: 152	6 Aircraft Identification: PP-C9072									
Fiign	Identification		18 Total Flight Time:						Lidar Operator	REAM
			18 Total						Lidar Operator	
	5 Aircraft Type: CesnnaT206H	CA Land (Airport, City/Province):	17 Landing:				25	0	Pilot-in-Command Signature over Printed Name	DREAM
	4 Type: VFR		16 Take off:				164 m15510m		Pilot-in-Command	
	2 ALTM Model: P. was 3 Mission Name: 1 P7E47A	9 Route: Ole L. Airport, City/Province):	15 Total Engine Time:				on Jailed Testasted craves, was mission los		Acquisition fight Certified by the second sec	
	2 ALTM Model: Per orgus	8 Co-Pilot: J. Clement 9 Route: Ole.	14 Engine Off:	gently clarety to choose		ded	hon Sailed 1785		8	
DREAM Data Acquisition Flight Log	1 Li DAR Operator: J. 人いい	7 Pilot: A. Agbaroni 8 Cc 10 Date:	13 Engine On: 14E		20 Remarks:	mission complet	21 Problems and Solutions:		Acquisition Flight Approved by Nart. Signature over Printed Name (End User Representative)	

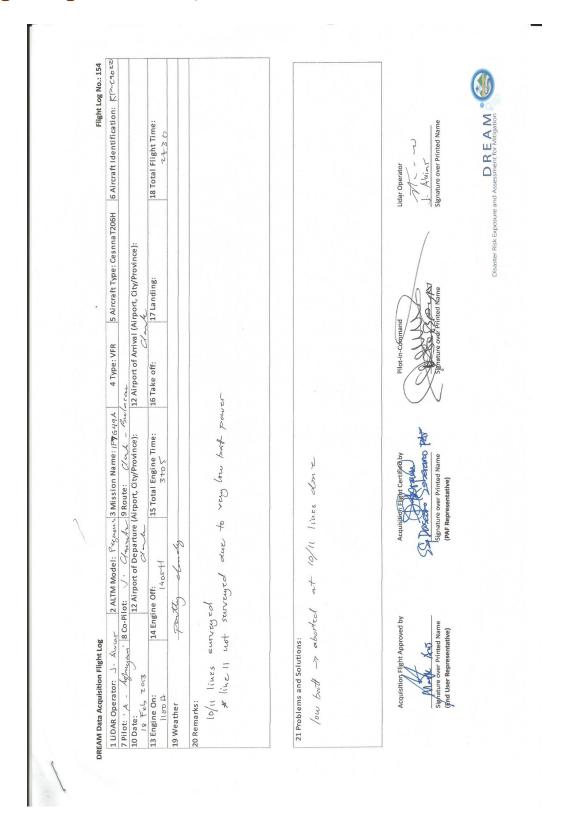
Flight Log for 2P7F1009A Mission

6 Aircraft Identification: RP-CG122	18 Total Flight Time: 수피	in radius of	Sinc Ame	Uldar Operator # 12 - 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1
4 Type: VFR 5 Aircraft Type: CesnnaT206H Betwan 7 Clevk 12 Airport of Arrive (Airport, City/Province):	17 Landing: 1274 (†	Successful flight. Kithnush, we are advised by the former not of go inside the Isnni methos of clark ampat, so Indicated Europe (Line Land 2) Photo avoilap is any 30 h - Shald So to 8	postely Rightzen hitalization at that It was of othe sine time-	nted Name
4 Type: VFR Behach > Clerk 12 Airport of Arrival	16 Take off: 043日	the fower not not cond 2)	+4	Pilot-in-Command
1009,		essful flight Although, we are advised 39 the timer nor and a compact, so It didn't survive (Line I and 2) photo overlap is only 30 h - should be to 8	r Ritalization	Acquistion Flight Certified by SOLLIUS READON Signature over Printed Name (PAF Representative)
2 ALTM Model: Genini 3 Mission Name:2P7F. ilot: J. Cleme T. 9 Route: Clark > Hon 12 Airport of Departure (Airport, Gty/Province):	14 Engine Off: 12 45 H Can weeker	oralla stifficult	uelly Risitiza	4 10 S
1 LIDAR Operator Larely Acount 2 ALTM Model: Gen 7 Pilot: Carl + Codenas 8 Co-Pilot: J. Clement 10 Date: A Lala	14 Eng		21 Problems and Solutions:	Acquisition Flight Approved by Signature over Printed Name (End User Representative)

Flight Log for 2P7F2009B Mission



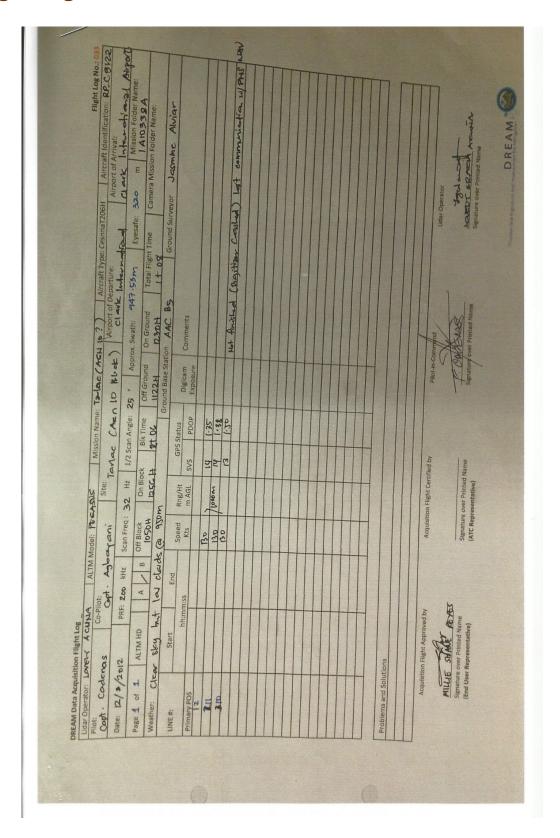
Flight Log for 1P7G049A Mission



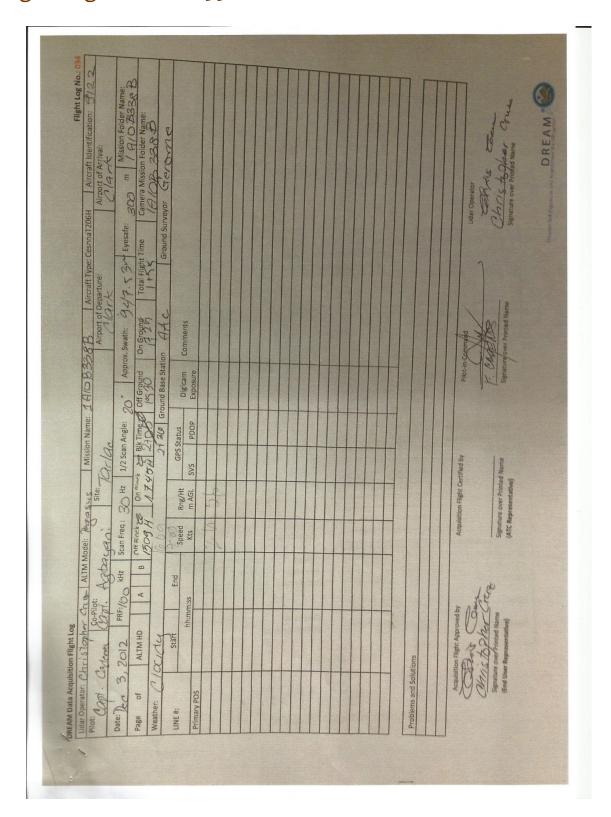
Flight Log for 1P7H009A and 1P7D008B (3LINES) Mission

			,
DREAM Data Acquisition Flight Log			Flight Log No.: 083
12 O-0	KRUS 3 Mission Name: 1974+00 Crox 9 Route: (Joseph true (Airport, City/Province):	Notice (17) S Aircraft Type: Cesnna T206H (Notice): 12 Airport of Arrival (Airport, City/Province):	6 Aircraft Identification: pp-c902.
1 5011	15 Total Engine Time: 16 Take 1445 3 7 40	16 Take off: 17 Landing: 14.30	18 Total Flight Time: アイ ダン
19 Weather prothy cloud B			
20 Remarks:	(F) (P95008B 6/7/8.		
21 Problems and Solutions:	+40		
- PAVE - NAV Marys (- Di-Ops eyrar, restact - degitizer tweez,	- Chilops error, restact morble to save about lags Chilops error, restact morble to save about lags degitizer invage; restact.		
Acquisition Flight Approved by	Acquisition Flight Certified by	Province infinites	Lidar Operator With Man
Signature over Printed Name (End User Representative)		Signature over Printed Name	Signature over Printed Name
		Disaster Risk Exposur	DREAM Consure and Assessment for Miligation

Flight Log for AGN10338A Mission



Flight Log for AGN10338B Mission



Flight Log for 1A10A046A Mission

1 I I DAR Operator IP POPTS 2 ATTM Model: Level 3 Mission Name 2P19244 4 Type: VFR 5 Aircraft Type: Cosmo 2D6H 6 Aircraft Identification: Profit Cosmo 2D Name 2P19244 1 The Indines: Shringly I	8 Co-Pilot: 12 Airport of Departure (12 Airport of Departure (14 Engine Off: 16 Coo. 14 Common (16 Coo. 14 Common (17 Coo. 14 Common (18 Coo. 15 Common (18 Coo. 18			,	Flight Log No.: 149
12 Airport of Departure (Airport, City/Province): 12 Airport of Arrival (Airport, City/Province): 12 Airport of Arrival (Airport, City/Province): 12 Airport of Arrival (Airport, City/Province): 14 Engine Off: 15 Table Off: 1	12 Airport of Departure (14 Engine Off:			5 Aircraft Type: CesnnaT206H	6 Aircraft Identification: Pr. Ca. 7
12 Airport of Departure (Airport, City/Province): 12 Airport of Arrival (Airport, City/Province): 12 Airport of Arrival (Airport, City/Province): 15 Take off: 17 Landing Ref. 18 Take off: 17 Landing Ref. 18 Take off: 18 Take off	12 Airport of Departure (v				
14 Engine Off: 15 Total Engine Time: 16 Total 17 Landing 18 18 18 18 18 18 18 18 18 18 18 18 18 1	14 Engine Off: Note H		port of Arrival (A	۱۰ irport, City/Province):	
Mayortsingus Arch to the west Might certified by Replicin-Command Signature over Printed Name Signature over Name	Chan a. 12 Some low has			17 Landing: 1239H	18 Total Flight Time:
Acquisition Flight Approved by Acquisition Flight Approved by Acquisition Flight Approved by Signature over Printed Name Signature over Name Signature ove	and a sound in the second				
Ved by Acquisition Filipt Certified by Pilot-in-Copynaed Signature over Printed Name Signature over Printed Name Signature over Printed Name (PAF Representative)					
Acquisition Flight Certified by Pilot-in-Coppnsord Signature over Printed Name Signature over Printed Name Signature over Printed Name	21 Problems and Solutions:				
M A H A C	Acquisition Filiph Ce	ed by	Pilot-in-Comman		idar Operator

Flight Log for 1A10A046B Mission

Activity modes: 12 Air part of Arminal Chipper, Clay Province): 12 Air part of Arminal Chipper, Clay Province): 13 Air part of Arminal Chipper, Clay Province): 14 Air part of Arminal Chipper, Clay Province): 15 Air part of Arminal Chipper, Clay Province): 16 Air part of Arminal Chipper, Clay Province): 17 Air part of Arminal Chipper, Clay Province): 18 Air part of Arminal Chipper, Clay Province): 19 Air part of Arminal Chipper, Chip	O VITRA NACIOI.
12 Airport of Arrival (Airport, City) 16 Take off: 15 Take off: 15 Take off: 16 Take off: 16 Take off: 16 Take off: 16 Take off: 18 Take off: 18 Take off: 18 Take off: 19 Take off: 10 Take off: 11 Take off: 12 Airport of Airbor, Charles 13 Take off: 14 Take off: 15 Take off: 16 Take off: 17 Take off: 18 Take off: 18 Take off: 19	i Gom
16 Take off: 17 Landing 157 1-1 173 1-	eparture
Ton Flight Certified by Pilot-in-Command in the control of the co	
quisition Right Certified by The certified by Pilot-in-Command	Choud
Analytion Flight Certified by Pilot-in-Command Incommand	
And the second of the second o	
Signature over Printed Name AF Representative)	Acqu
Disaster Risk Exposure and Assessment for Mitigation	Signa (PAF

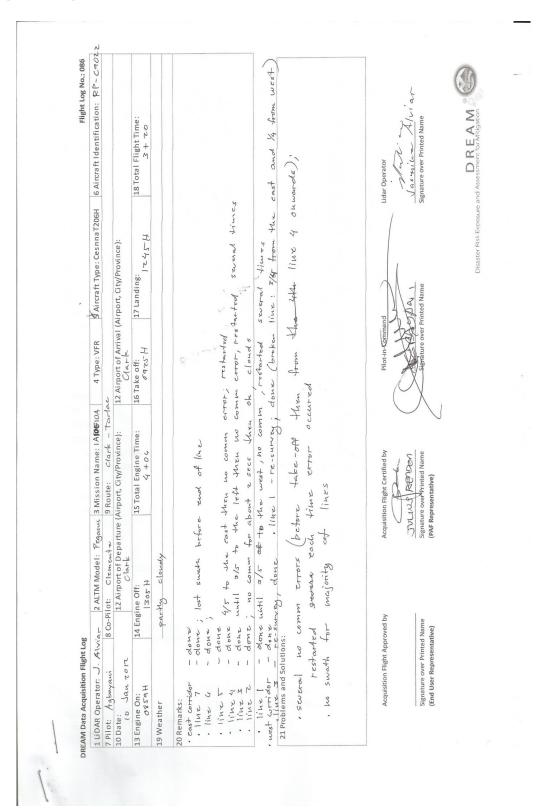
Flight Log for 1A10C045B Mission

Pilot-in-Command Pilot-in-Com	Is Alive to the command of the comma	Flight Log No.: 146 47 6 Aircraft Identification: 29-03/22	18 Total Flight Time: 2+3.	Udar Operator Jack T. Acad Mane Signature over Printed Name D. R. E. A. M. Sand Assessment for Miligation
Pilot-in-Compage Signature over P Signat	Sco-Pilot: 12 Airport of Departure (Airport, City/Province): 12 Airport of Arrival (Airport, City/Province): 13 Airport of Arrival (Airport, City/Province): 14 Engine Off: 15 Total Engine Time: 16 Take off: 17 Airport of Arrival (Airport, City/Province): 18 Airport of Arrival (Airport, City/Province): 19 Airport of Arrival (Airport, City/Province): 10 Airport of Arrival (Airport, City/Province): 12 Airport of Arrival (Airport, City/Province): 12 Airport of Arrival (Airport, City/Province): 12 Airport of Arrival (Airport, City/Province): 13 Airport of Arrival (Airport, City/Province): 14 Airport of Arrival (Airport, City/Province): 15 Airport of Arrival (Airport, City/Province): 16 Take off: 17 Airport of Arrival (Airport): 18 Airport of Arrival (Airport): 19 Airport of Arrival (Airport): 10 Airport of Arrival (Airport): 10 Airport of Arrival (Airport): 11 Airport of Arrival (Airport): 12 Airport of Arrival (Airport): 13 Airport of Arrival (Airport): 14 Airport of Arrival (Airport): 15 Airport of Arrival (Airport): 16 Airport of Arrival (Airport): 17 Airport of Arrival (Airport): 18 Airport of Arrival (Airport): 19 Airport of Arrival (Airport): 10 Airport of Arrival (Airport): 11 Airport of Arrival (Airport): 12 Airport of Arrival (Airport): 14 Engine Off: 15 Airport of Arrival (Airport): 16 Airport of Arrival (Airport): 17 Airport of Arrival (Airport): 18 Airport of Airport of Arrival (Airport): 18 Airport of Airport of Arrival (Airport): 18 Airport of Airp	аТ206Н		1 1 7
A Mission Name: 27951 04 9 Route: (276 - (27	So-Pilot: 12 Airport of Departure (Airport, Glassion Off: 14 Engine Off: 15 Total II 15 Total II 15 Total II 16 Feb. 12 Province overlying to the Representative overlying to the Signature overlying to the	4 Type: VFR	16 Take off: 11-4/1-4/1-4/1-4/1-4/1-4/1-4/1-4/1-4/1-4	Pilot-in-Command
	14 Eng B Co-P	3 Mission Name: 299B(0) 9 Route: clark -	(John Time: 15 Total Engine Time: 3ナネン	cquisition Flight Certified by

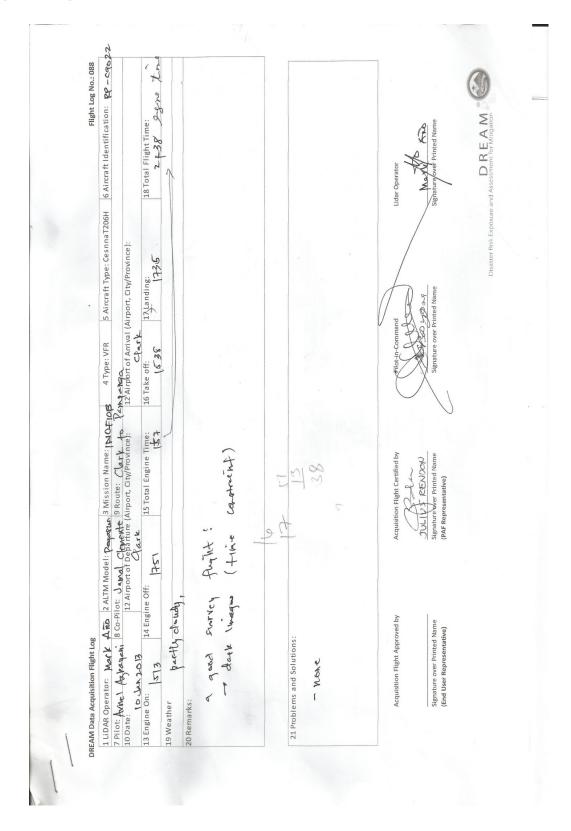
Flight Log for 2AGN10D1046B Mission

12 Airport of	Time: 16 Take off: 17 Landing: 18 Total Flight Time: 1420			Pilot-in-Command Signature over Printed Name	Disaster Risk Exposure and Assessment for Mitgation
8 CO-Pilot: Conente 9 Route: Clark 12 Airport of Departure (Airport, City/Province):	14 Engine Off: 15 Total Engine Time: Pofty wordy windy	×		Acquisition Flight Certified by Acquisition Flight Certified by Acquisition September 1997 (PAF Representative)	
1 LiDAR Operator: Hart 7 Pilot: Appendant 10 Date: Tak 7013	1430	20 Remarks:	21 Problems and Solutions:	Acquisition Flight Approved by Mostly Accordance Signature over Printed Name (End User Representative)	

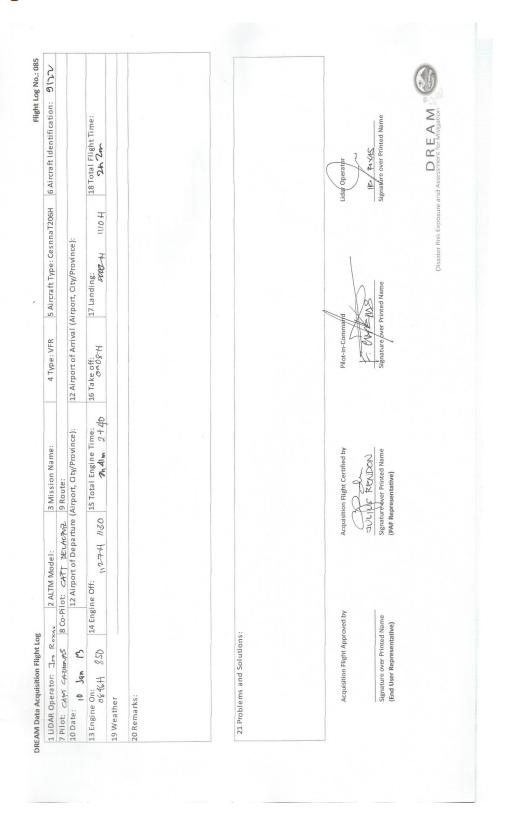
Flight Log for IA10E10A Mission



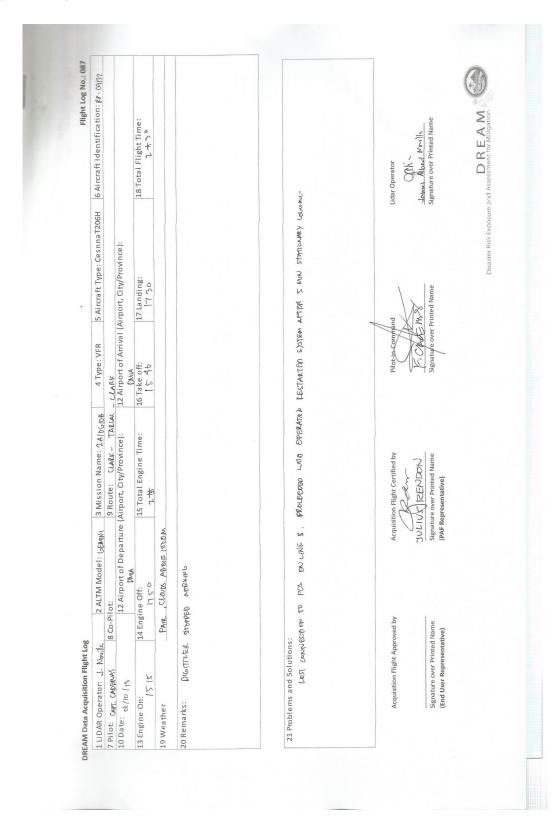
Flight Log for 1A10F10B Mission



Flight Log for 2AGN10G1010A Mission



Flight Log for 2AGN10G010B Mission



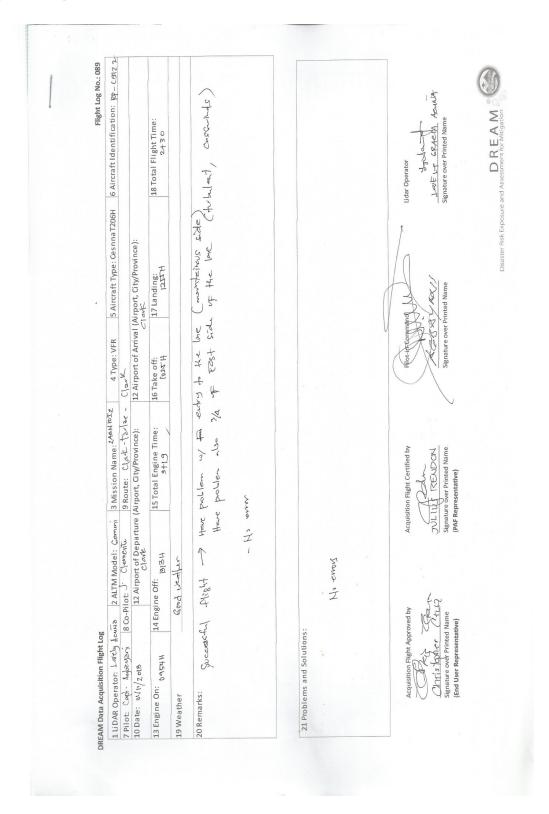
Flight Log for 1A10H11A Mission

13 Figure On: 14 Figure Off Sequence Off Sequence of Personal Chippot, City/Province): 15 Figure Off: 16 Figure Off: 17 Figure Off: 17 Figure Off: 18 Fi		ilot: 6King 10/ Ca 9 Route: Clark to a		5 Aircraft Type: CesnnaT206H	6 Aircraft Identification: 89-0027
1130 1140 15 Total Engine Off: 15 Total Engine Time: 16 Take off: 17 Landing: 18 Total File off: 15.05 15 Lotal File off:	20 20 X	rture (Airport, City/Province):	12 Airport of Arrival	(Airport, City/Province):	
SIL live surpey 3 to communication. Sand Solutions: Love course. & rephysical bright Certified by Acquisition Flight Certified by Acquisition Flight Certified by Signature over Printed Name Signature over Printed Name (1945 Representative) Signature for Printed Name (1945 Representative)	14 Engine Off.	15 Total Engine Time: 3 \(\frac{2}{2} \)	16 Take off:	-	18 Total Flight Time:
anthurser burgs on the last pure, bestard agates, signature over Printed Name (PAR Representative)	3/6 live sworey a				
ed by Acquisition Flight Certified by Signature over Printed Name Signature over Printed Name (PAF Representative)	6/6 - togs communication				
ed by Acquisition Flight Certified by Acquisition Flight Certified by TULLY FEEL DEN Signature over Printed Name (PAF Representative)		8		8	
Acquisition Flight Certified by Plot-in-Coormand TO LLA S PENDON Signature over Printed Name (PAF Representative)	Ta ~		jude, testan	4 Retent	
Signature over Printed Name (PAF Representative)	Acquisition Flight Approved by	cquisition Flight Certified by	Pilot-in-Gorama		dar Operator
		10 LMS FED LEN ignature over Printed Name PAF Representative)	Senature over P		gnature over Printed Name

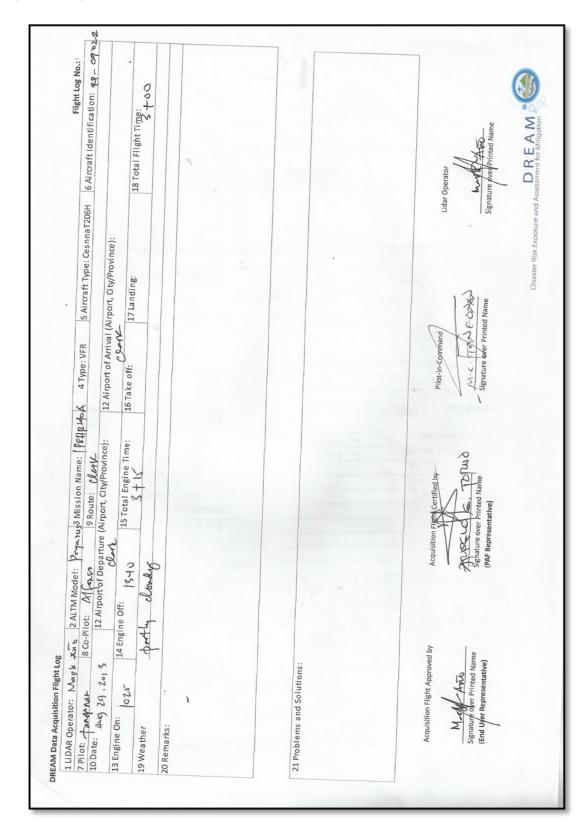
Flight Log for 2AGNI1049B Mission

Flight Log No.: 155		18 Total Flight Time: タャ40			Lidar Operator	Signature over Printed Name DREAM
S Aircraft Tyne: Cesnna T206H	rport, City/Province):					Signature dwer printed Name
A TYDO. VEB	12 Airport of Arrival	16 Take off:				
\$ tag lot 22 male activities	ALIN MOUGH: Creeking James 10 Market	15 Total Engine Time:			Acquisition Flight Certified by	
	9-0	Engine Off:				
DREAM Data Acquisition Flight Log	Con Mary	13 Engine On: 14 (2013) 13 Engine On: 15 (2013) 15 (5) St. H 19 Weather	20 Remarks:	21 Problems and Solutions:	Acquisition Flight Approved by	Signature over Printed Name (End User Representative)

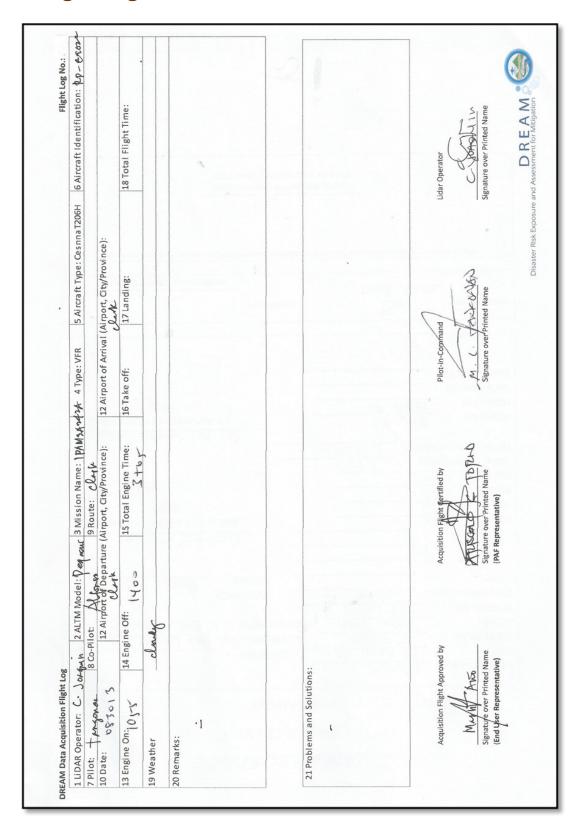
Flight Log for 2A6N10I2011A Mission



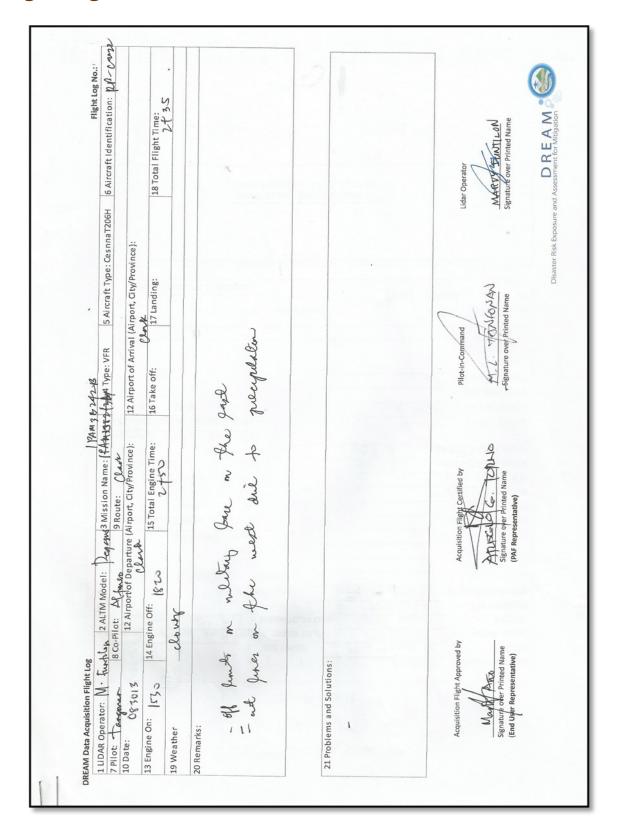
Flight Log for 1PAM8HR240A Mission



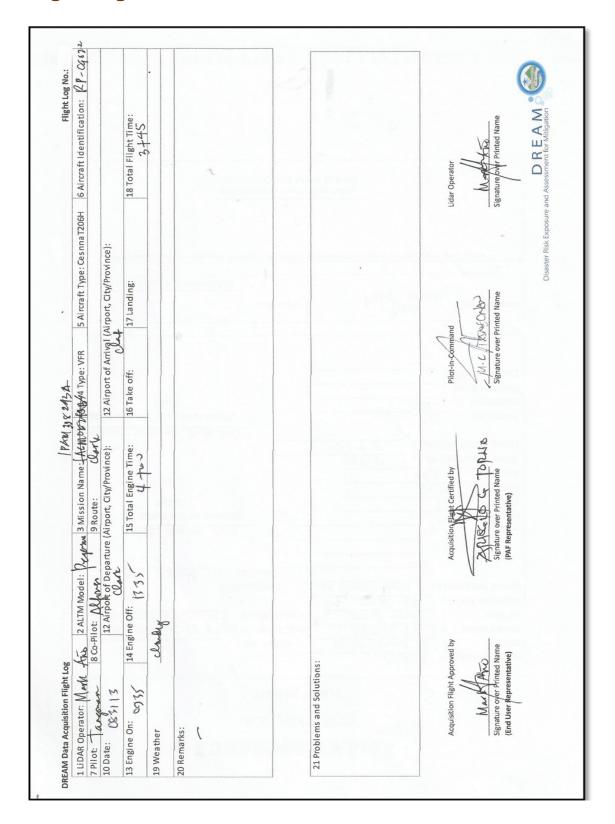
Flight Log for 1PAM3A242A Mission



Flight Log for 1PAM3B242B Mission



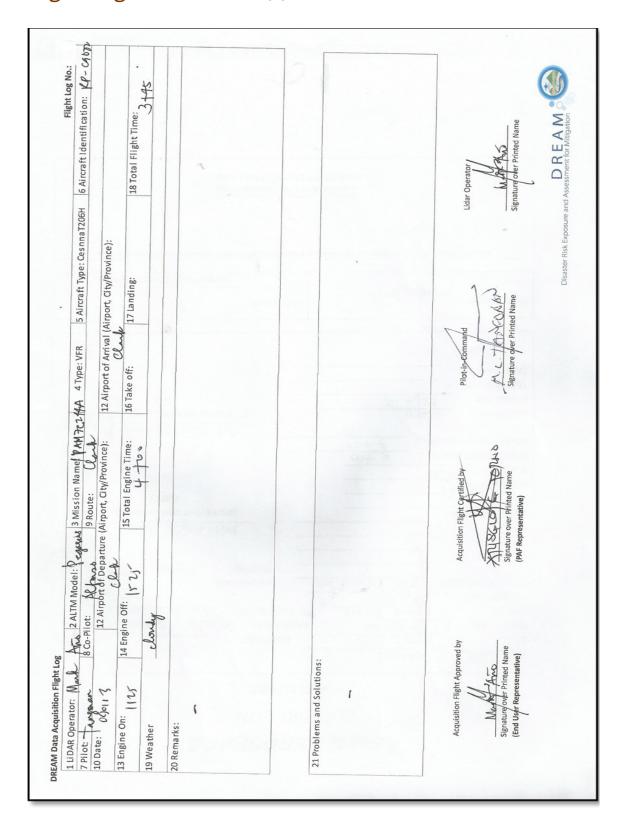
Flight Log for 1AGNO338243A Mission



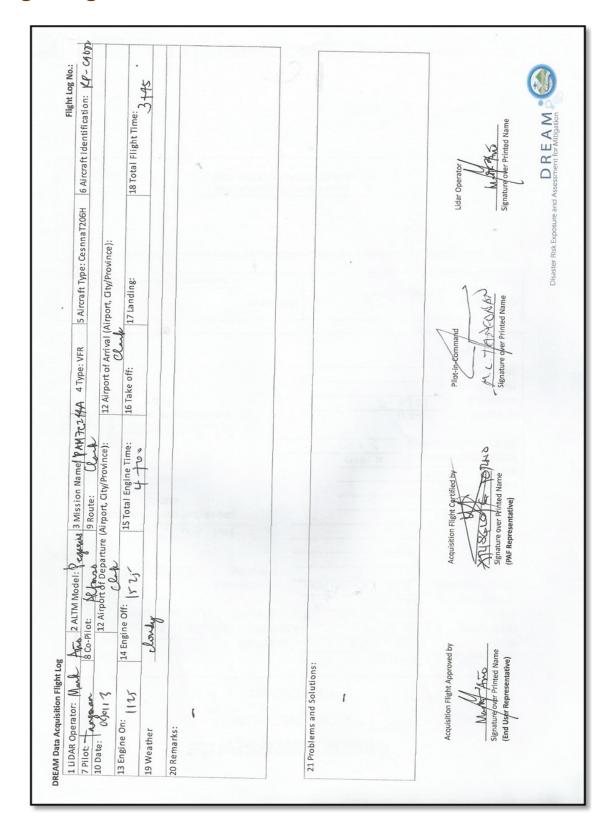
Flight Log for 1AGNOE243B Mission

Flight Log No.:	6 Aircraft Identification: Rp. CA62		18 Total Flight Time: 2+35.		*			Lidar Operator Signature over Printed Name	DRFAM
			18					Lidar o	
	5 Aircraft Type: Cesnna T206H	12 Airport of Arrival (Airport, City/Province):	17 Landing:		P			Pilot-in-command Pilot-in-command Command Signature ovjet Printed Name	
1 ACN 10 E 2436	82 934 4 Type: VFR	12 Airport of Arriva	16 Take off:	,	In warming			Pilot-in-Command	
IACK	2 ALTM Model: Prans 3 Mission Name: Physystel 4 Type: VFR	12 Airport of Departure (Airport, City/Province):	15 Total Engine Time:		abouted due to pari cloude, you working why			Acquisition Flight Certified by ALL SET CE TO TAIL Signature over Printed Name (PAF Representative)	
	Jodel: Paper	t of Departure	725		d d			Acquisition F	
	8 Co-Pilot: A	12 Airpor	14 Engine Off:		aborted d			oved by	
DREAM Data Acquisition Flight Log	7 Pilot: According 8 Co-Pilot: Alloward	ate: 683/13	n: Fres	19 Weather 20 Remarks:	- Welther		ZI Problems and Solutions:	Acquisition Flight Approved by Merry Signature over Printed Name (End User Representative)	

Flight Log for 1AGNOE244A Mission



Flight Log for 1PAM7C244A Mission



Bibliography

- Hilario, F. (2007, January 9). Pampanga River Basin. Lecture presented at 2nd Asia Water Cycle Symposium (AWCI) International Task Team (ITT) in University of Tokyo, Tokyo.
- The Pampanga River Basin. (2009, October 23). Retrieved October 29, 2015, from http://www.abs-cbnnews.com/research/10/23/09/pampanga-river-basin







