

HAZARD MAPPING OF THE PHILIPPINES USING LIDAR ( PHIL-LIDAR I )

# **LiDAR Surveys and Flood Mapping of Pagsangahan River**



University of the Philippines Training Center  
for Applied Geodesy and Photogrammetry  
Visayas State University

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For questions/queries regarding this report, contact:

**Engr. Florentino Morales, Jr.**

Project Leader, PHIL-LiDAR 1 Program  
Visayas State University  
Baybay, Leyte, Philippines 6521  
E-mail: ffmorales\_jr@yahoo.com

**Enrico C. Paringit, Dr. Eng.**

Program Leader, DREAM Program  
University of the Philippines Diliman  
Quezon City, Philippines 1101  
E-mail: ecparingit@up.edu.ph

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## LIST OF ACRONYMS AND ABBREVIATIONS

<b>AAC</b>	Asian Aerospace Corporation	<b>LAS</b>	LiDAR Data Exchange File format
<b>Ab</b>	abutment	<b>LC</b>	Low Chord
<b>ALTM</b>	Airborne LiDAR Terrain Mapper	<b>LGU</b>	local government unit
<b>ARG</b>	automatic rain gauge	<b>LiDAR</b>	Light Detection and Ranging
<b>AWLS</b>	Automated Water Level Sensor	<b>LMS</b>	LiDAR Mapping Suite
<b>BA</b>	Bridge Approach	<b>m AGL</b>	meters Above Ground Level
<b>BM</b>	benchmark	<b>MMS</b>	Mobile Mapping Suite
<b>BSWM</b>	Bureau of Soils and Water Management	<b>MSL</b>	mean sea level
<b>CAD</b>	Computer-Aided Design	<b>NAMRIA</b>	National Mapping and Resource Information Authority
<b>CN</b>	Curve Number	<b>NDRRMC</b>	National Disaster Risk Reduction and Management Council
<b>CSRS</b>	Chief Science Research Specialist	<b>NSO</b>	National Statistics Office
<b>DA</b>	Department of Agriculture	<b>NSTC</b>	Northern Subtropical Convergence
<b>DAC</b>	Data Acquisition Component	<b>PAF</b>	Philippine Air Force
<b>DEM</b>	Digital Elevation Model	<b>PAGASA</b>	Philippine Atmospheric Geophysical and Astronomical Services Administration
<b>DENR</b>	Department of Environment and Natural Resources	<b>PDOP</b>	Positional Dilution of Precision
<b>DOST</b>	Department of Science and Technology	<b>PPK</b>	Post-Processed Kinematic [technique]
<b>DPPC</b>	Data Pre-Processing Component	<b>PRF</b>	Pulse Repetition Frequency
<b>DREAM</b>	Disaster Risk and Exposure Assessment for Mitigation [Program]	<b>PTM</b>	Philippine Transverse Mercator
<b>DRRM</b>	Disaster Risk Reduction and Management	<b>QC</b>	Quality Check
<b>DSM</b>	Digital Surface Model	<b>QT</b>	Quick Terrain [Modeler]
<b>DTM</b>	Digital Terrain Model	<b>RA</b>	Research Associate
<b>DVBC</b>	Data Validation and Bathymetry Component	<b>RBCO</b>	River Basin Control Office
<b>FMC</b>	Flood Modeling Component	<b>RIDF</b>	Rainfall-Intensity-Duration-Frequency
<b>FOV</b>	Field of View	<b>RMSE</b>	Root Mean Square Error
<b>GiA</b>	Grants-in-Aid	<b>SAR</b>	Synthetic Aperture Radar
<b>GCP</b>	Ground Control Point	<b>SCS</b>	Soil Conservation Service
<b>GNSS</b>	Global Navigation Satellite System	<b>SRTM</b>	Shuttle Radar Topography Mission
<b>GPS</b>	Global Positioning System	<b>SRS</b>	Science Research Specialist
<b>HEC-HMS</b>	Hydrologic Engineering Center - Hydrologic Modeling System	<b>SSG</b>	Special Service Group
<b>HEC-RAS</b>	Hydrologic Engineering Center - River Analysis System	<b>TBC</b>	Thermal Barrier Coatings
<b>HC</b>	High Chord	<b>UP-TCAGP</b>	University of the Philippines – Training Center for Applied Geodesy and Photogrammetry
<b>IDW</b>	Inverse Distance Weighted [interpolation method]	<b>UTM</b>	Universal Transverse Mercator
<b>IMU</b>	Inertial Measurement Unit	<b>VSU</b>	Visayas State University
<b>kts</b>	knots	<b>WGS</b>	World Geodetic System

# CHAPTER 1: OVERVIEW OF THE PROGRAM AND PANGSANGAHAN RIVER

*Enrico C. Paringit, Dr. Eng., Dr. George Puno, and Eric Bruno*

## 1.1 Background of the Phil-LiDAR 1 Program

The University of the Philippines Training Center for Applied Geodesy and Photogrammetry (UP-TCAGP) launched a research program in 2014 entitled “Nationwide Hazard Mapping using LiDAR” or Phil-LiDAR 1, supported by the Department of Science and Technology (DOST) Grants-in-Aid (GiA) Program. The program was primarily aimed at acquiring a national elevation and resource dataset at sufficient a resolution to produce information necessary to support the different phases of disaster management. Particularly, it targeted to operationalize the development of flood hazard models that would produce updated and detailed flood hazard maps for the major river systems in the country.

The program was also aimed at producing an up-to-date and detailed national elevation dataset suitable for a 1:5,000 scale mapping, with 50 cm and 20 cm horizontal and vertical accuracies, respectively. These accuracies were achieved through the use of the state-of-the-art Light Detection and Ranging (LiDAR) airborne technology procured by the project through the DOST. The methods applied in this report are thoroughly described in a separate publication entitled “Flood Mapping of Rivers in the Philippines Using Airborne LiDAR: Methods” (Paringit, et. al., 2017), available separately.

The implementing partner university for the Phil-LiDAR 1 Program is the Visayas State University (VSU). VSU is in charge of processing LiDAR data and conducting data validation reconnaissance, cross section, bathymetric survey, validation, river flow measurements, flood height and extent data gathering, flood modeling, and flood map generation for the twenty-seven (27) river basins in the Eastern Visayas region. The university is located in Baybay City in the province of Leyte.

## 1.2 Overview of the Pagsangahan River Basin

The Pagsangahan River Basin is located in Eastern Visayas, at the northwestern portion of the province of Leyte. It traverses through the Municipalities of Capoocan, Villaba, Kananga, Matag-ob, and the City of Ormoc. It covers an area of 406 square kilometers, and travels for approximately 31.5 kilometers from its source to its mouth in the Ormoc Bay.

The Department of Environment and Natural Resources – River Basin Control Office (DENR-RBCO) identified the Pagsangahan River Basin as one of the one hundred and forty (140) critical watersheds in the Philippines, having a drainage area of 453 km<sup>2</sup>, and an estimated 871 million cubic meter annual run-off.

The river basin’s main stem, the Pagsangahan River, is part of the twelve (12) river systems in the Visayas Region.

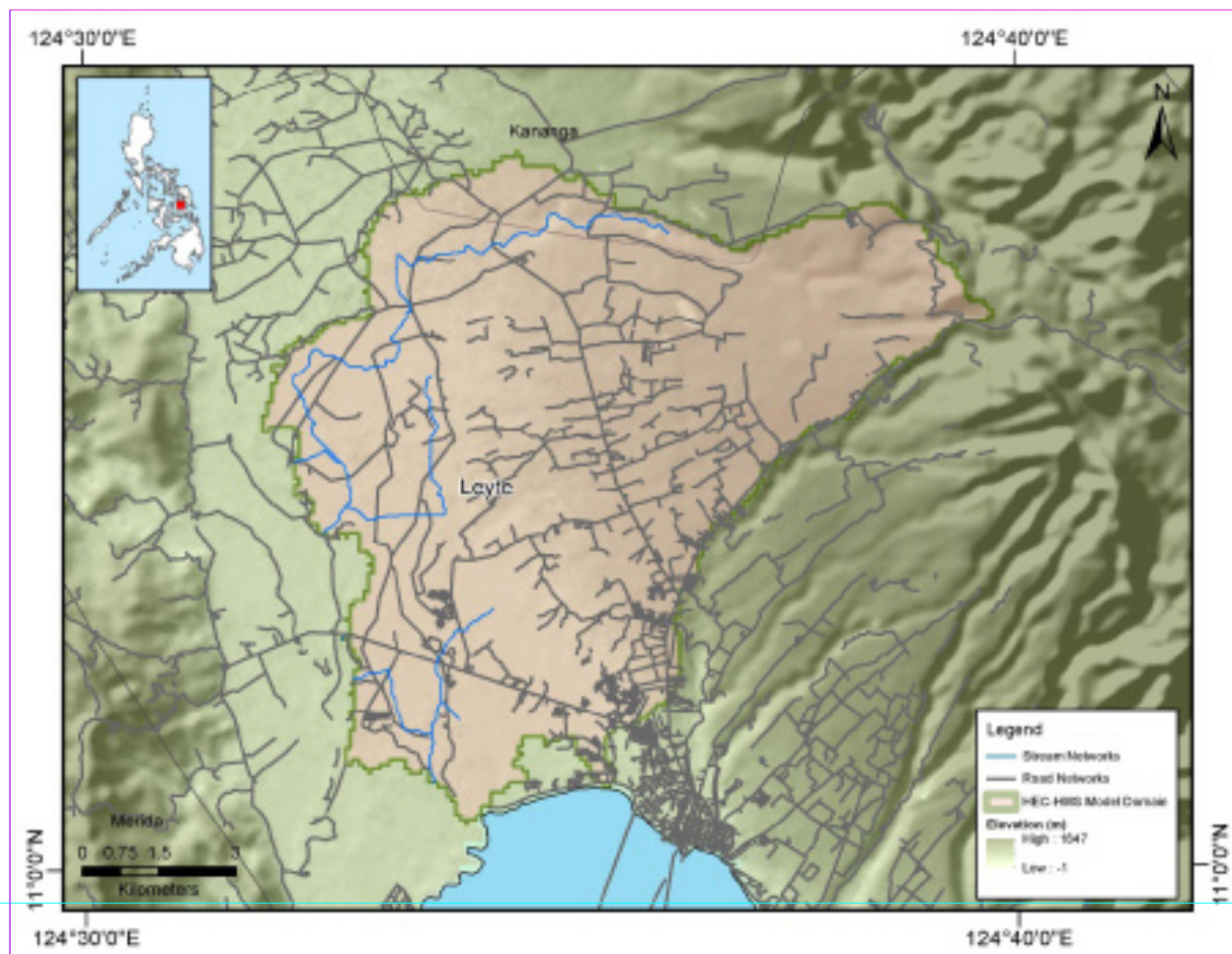


Figure 1. Location map of the Pagsangahan River Basin (in brown)

According to the 2010 national census of the National Statistics Office (NSO), the population of residents within the immediate vicinity of the river is 8,309 people, which are under the jurisdiction of two (2) barangays in Ormoc City, namely Liloan and Lao.

Settlements in the area face the constant threat of flooding due to frequent heavy rainfall, especially in the months of June to February. On November 8, 2013, Super Typhoon Haiyan (local name, Yolanda) induced a storm surge that brought about flooding and devastation in the province. The official list of the National Disaster Risk Reduction and Management Council (NDRRMC) reports that Typhoon Haiyan caused the deaths of 6,193 people, most of whom are from the provinces of Samar and Leyte.

## CHAPTER 2: LIDAR DATA ACQUISITION OF THE PANGSANGAHAN FLOODPLAIN

*Engr. Louie P. Balicanta, Engr. Christopher Cruz, Lovely Gracia Acuña, Engr. Gerome Hipolito, Engr. Iro Niel D. Roxas, and Rowena M. Gabua*

The methods applied in this Chapter were based on the DREAM methods manual (Sarmiento, et al., 2014) and further enhanced and updated in Paringit, et al. (2017).

### 2.1 Flight Plans

To initiate the LiDAR acquisition survey of the Pagsangahan floodplain, the Data Acquisition Component (DAC) created flight plans within the delineated priority area for the floodplain in Leyte. These missions were planned for nineteen (19) lines that ran for at most four and a half (4.5) hours, including take-off, landing, and turning time. The Aquarius and Gemini LiDAR systems were used for the flight missions (See ANNEX 1 for the sensor specifications). The flight planning parameters for the LiDAR system are found in Table 1 and Table 2. Figure 2 illustrates the flight plans for the Pagsangahan floodplain survey.

Table 1. Flight planning parameters for the Aquarius LiDAR System

Block Name	Flying Height (m AGL)	Overlap (%)	Field of View ( $\theta$ )	Pulse Repetition Frequency (PRF) (KHz)	Scan Frequency (Hz)	Average Speed (kts)	Average Turn Time (Minutes)
BLK 35A	600, 700, 550, 500	30, 35	50, 36	70, 50	40, 50, 35, 30	130	5
BLK 35B	700, 600, 550	30, 35	36	50	50, 35, 30	130	5
BLK 35C	700, 550, 600	30	36	50, 33	50, 30	130	5
BLK 35D	700, 550, 600	30	36	50, 33	50, 30	130	5
BLK 35E	700, 550, 600	30	36	50, 33	50, 30	130	5
BLK 35F	600	30	36	50	50	130	5
BLK 35G	700	30	36	50	50	130	5
BLK 35H	700, 800	30	36	50	50	130	5
BLK 35I	800, 700, 600	30, 55, 40, 50	36	50	50	130	5

Table 2. Flight planning parameters for the Gemini LiDAR System

Block Name	Flying Height (m AGL)	Overlap (%)	Field of View ( $\theta$ )	Pulse Repetition Frequency (PRF) (KHz)	Scan Frequency (Hz)	Average Speed (kts)	Average Turn Time (Minutes)
BLK 35A	800, 1000	30	40	100	30	130	5
BLK 35B	800, 1000	30	40	100	30	130	5
BLK 35C	1100	30	40	100	30	130	5

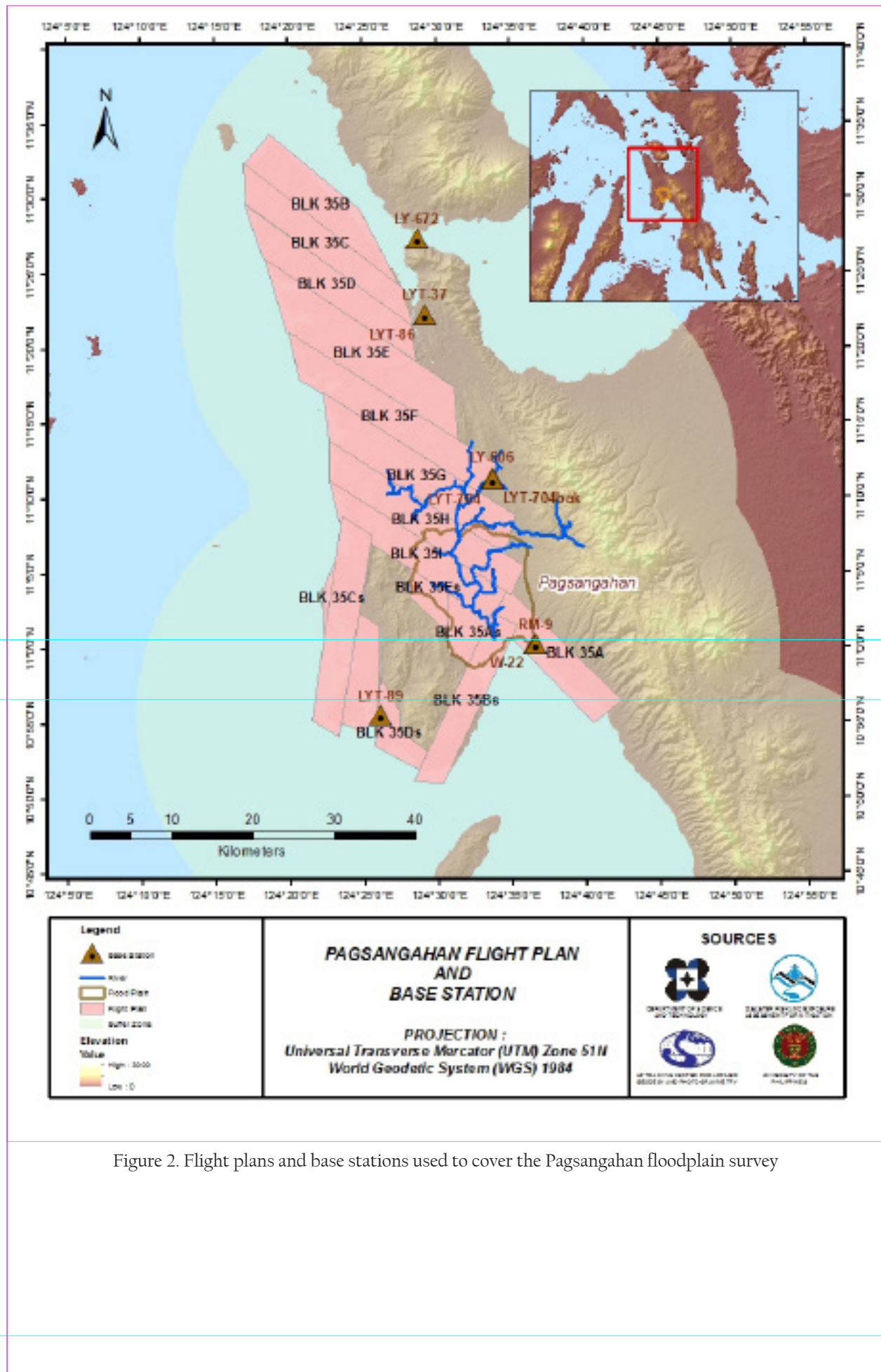


Figure 2. Flight plans and base stations used to cover the Pagsangahan floodplain survey

## 2.2 Ground Base Stations

The field team for this undertaking was able to recover eight (8) NAMRIA control stations: (i.) LYT-89, which is of first (1<sup>st</sup>) order accuracy; (ii.) CBU-340, (iii.) LYT-86, (iv.) LYT-90, (v.) LYT-690, (vi.) LYT-704, and (vii.) LYT-731, which are of second (2<sup>nd</sup>) order accuracy; and (viii.) LYT-37, which is of fourth (4<sup>th</sup>) order accuracy. The field team also established three (3) control points: RM-9, W-22 and LYT-704bak. Two (2) benchmarks were processed: LY-606 and LY-672. These were used as base stations during the flight operations for the entire duration of the survey, held on January 28, 2014; May 15-26, 2014; January 21-February 17, 2015; March 9-19, 2016; and April 16, 2016. The base stations were observed using dual frequency GPS receivers, TRIMBLE SPS 852, SPS 882 SPS 985, and TOPCON GR-5. The flight plans and the locations of the base stations used during the aerial LiDAR acquisition in the Pagsangahan floodplain are shown in Figure 2. The certifications for the NAMRIA reference points are found in ANNEX 2, while the baseline processing reports for the established control points are provided in ANNEX 3. The composition of the project team is presented in ANNEX 4.

Figure 3 to Figure 5 exhibit the recovered NAMRIA reference points within the area. Table 3 to Table 15 provide the details about the NAMRIA control stations and established points. Table 16 lists all of the ground control points occupied during the acquisition, together with the dates of utilization during the survey.

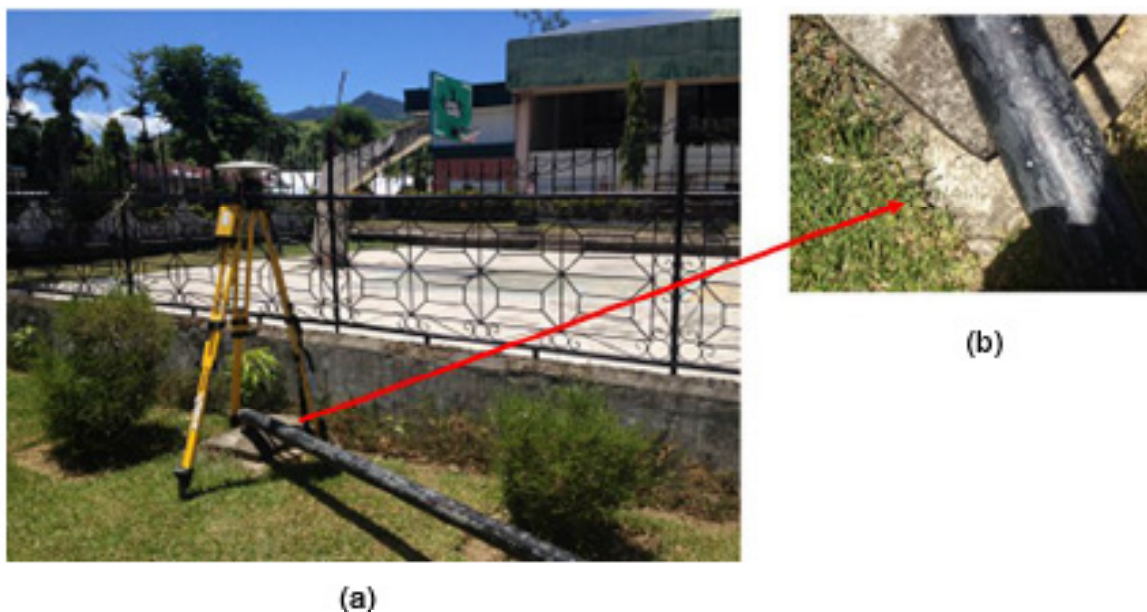


Figure 3. (a) GPS set-up over LYT-37, as recovered inside the town plaza of the Municipality of Leyte, Leyte; and (b) NAMRIA horizontal control point LYT-37, as recovered by the field team

Table 3. Details of the recovered NAMRIA horizontal control point LYT-37, used as a base station for the LiDAR acquisition

Station Name	LYT-37	
Order of Accuracy	2 <sup>nd</sup> Order	
Relative Error (horizontal positioning)	1:50000	
Geographic Coordinates, Philippine Reference of 1992 Datum (PRS 92)	Latitude Longitude Ellipsoidal Height	11° 22' 17.79271" North 124° 29' 07.61910" East 5.33900 meters
Grid Coordinates, Philippine Transverse Mercator Zone 5 (PTM Zone 5 PRS 92)	Easting Northing	443839 meters 1257489.277 meters
Geographic Coordinates, World Geodetic System 1984 Datum (WGS 84)	Latitude Longitude Ellipsoidal Height	11°22'13.44918" North 124°29'12.76807" East 65.99800 meters
Grid Coordinates, Universal Transverse Mercator Zone 51 North (UTM 51N WGS 1984)	Easting Northing	662088.45 meters 1257404.79 meters



(a)



(b)

Figure 4. (a) GPS set-up over LY-606, as recovered in a bridge in Kananga, Leyte; and (b) NAMRIA benchmark LY-606, as recovered by the field team

Table 4. Details of the recovered NAMRIA benchmark LY-606, used as a base station for the LiDAR acquisition

Station Name	LY-606	
Order of Accuracy	1 <sup>st</sup> order	
Relative Error (horizontal positioning)	1:100000	
Geographic Coordinates, Philippine Reference of 1992 Datum (PRS 92)	Latitude Longitude Ellipsoidal Height	17° 23' 30.09" North 120° 27' 09.94 East 19.22 meters
Grid Coordinates, Universal Transverse System 1984 Datum (WGS84)	Easting Northing	229263.009 meters 1906054.331 meters
Geographic Coordinates, World Geodetic System 1984 Datum (WGS 84)	Latitude Longitude Ellipsoidal Height	717° 13' 24.35635" North 120° 27' 15.02916" East 53.562 meters





(a)



(b)

Figure 5. Figure 5. (a) GPS set-up over LY-672, as recovered at the concrete sidewalk of the Biliran Bridge between the Municipality of Leyte, Leyte and the Municipality of Biliran, Biliran; and (b) NAMRIA reference point LY-672, as recovered by the field team

Table 5. Details of the recovered NAMRIA benchmark LY-672, used as a base station for the LiDAR acquisition

Station Name	LY-672	
Order of Accuracy	1 <sup>st</sup> Order	
Relative Error (horizontal positioning)	1:100000	
Geographic Coordinates, Philippine Reference of 1992 Datum (PRS 92)	Latitude Longitude Ellipsoidal Height	11° 27' 23.02" North 124° 28' 39.82" East 20.86 meters
Grid Coordinates, Philippine Transverse Mercator Zone 5 (PTM Zone 5 PRS 92)	Easting Northing	443013.31 meters 1266859.739 meters
Geographic Coordinates, World Geodetic System 1984 Datum (WGS 84)	Latitude Longitude Ellipsoidal Height	11° 27' 18.15339" North 124° 28' 44.13652" East 81.2745 meters
Grid Coordinates, Universal Transverse Mercator Zone 51 North (UTM 51N WGS 1984)	Easting Northing	661327.389 meters 1266708.04 meters

Table 6. Details of the recovered NAMRIA horizontal control point CBU-340, used as a base station for the LiDAR acquisition

Station Name	CBU-340	
Order of Accuracy	2 <sup>nd</sup> order	
Relative Error (horizontal positioning)	1:50000	
Geographic Coordinates, Philippine Reference of 1992 Datum (PRS 92)	Latitude Longitude Ellipsoidal Height	10°38'14.87646" North 124°28'04.68006" East 15.533 meters
Geographic Coordinates, World Geodetic System 1984 Datum (WGS 84)	Latitude Longitude Ellipsoidal Height	10°38'10.71737" North 124°28'09.89389" East 77.920 meters
Grid Coordinates, Universal Transverse Mercator Zone 51 North (UTM 51N WGS 1984)	Easting Northing	660577.527 meters 1176200.458 meters

Table 7. Details of the recovered NAMRIA benchmark LY-672, used as a base station for the LiDAR acquisition

Station Name	LYT-86	
Order of Accuracy	2 <sup>nd</sup> Order	
Relative Error (horizontal positioning)	1:50000	
Geographic Coordinates, Philippine Reference of 1992 Datum (PRS 92)	Latitude Longitude Ellipsoidal Height	11°22'16.75118" North 124°29'08.10940" East 15.43100 meters
Grid Coordinates, Philippine Transverse Mercator Zone 5 (PTM Zone 5 PRS 92)	Easting Northing	443853.897 meters 1257448.25 meters
Geographic Coordinates, World Geodetic System 1984 Datum (WGS 84)	Latitude Longitude Ellipsoidal Height	11°22'12.40727" North 124°29'13.25847" East 66.09100 meters
Grid Coordinates, Universal Transverse Mercator Zone 51 North (UTM 51N PRS 92)	Easting Northing	662103.47 meters 1257372.86 meters

Table 8. Details of the recovered NAMRIA horizontal control point LYT-89, used as a base station for the LiDAR acquisition

Station Name	LYT-89	
Order of Accuracy	1 <sup>st</sup> Order	
Relative Error (horizontal positioning)	1:100000	
Geographic Coordinates, Philippine Reference of 1992 Datum (PRS 92)	Latitude Longitude Ellipsoidal Height	10°55'37.75929" North 124°25'59.22187" East 2.53400 meters
Grid Coordinates, Philippine Transverse Mercator Zone 5 (PTM Zone 5 PRS 92)	Easting Northing	438033.007 meters 1208330.431 meters
Geographic Coordinates, World Geodetic System 1984 Datum (WGS 84)	Latitude Longitude Ellipsoidal Height	10°55'33.52339" North 124°26'4.41045" East 64.14500 meters
Grid Coordinates, Universal Transverse Mercator Zone 51 North (UTM 51N PRS 92)	Easting Northing	656614.72 meters 1208220.77 meters

Table 9. Details of the recovered NAMRIA horizontal control point LYT-90, used as a base station for the LiDAR acquisition

Station Name	LYT-90	
Order of Accuracy	2 <sup>nd</sup> order	
Relative Error (horizontal positioning)	1:50000	
Geographic Coordinates, Philippine Reference of 1992 Datum (PRS 92)	Latitude Longitude Ellipsoidal Height	11°00'17.75728" North 124°36'28.24066" East 15.532 meters
Geographic Coordinates, World Geodetic System 1984 Datum (WGS 84)	Latitude Longitude Ellipsoidal Height	11°00'13.51665" North 124°36'33.42083" East 77.386 meters
Grid Coordinates, Universal Transverse Mercator Zone 51 North (UTM 51N PRS 92)	Easting Northing	675667.875 meters 1216919.360 meters

Table 10. Details of the recovered NAMRIA horizontal control point LYT-690, used as a base station for the LiDAR acquisition

Station Name	LYT-690	
Order of Accuracy	2 <sup>nd</sup> order	
Relative Error (horizontal positioning)	1:50000	
Geographic Coordinates, Philippine Reference of 1992 Datum (PRS 92)	Latitude Longitude Ellipsoidal Height	11°00'17.68909" North 124°36'28.25530" East 4.361 meters
Geographic Coordinates, World Geodetic System 1984 Datum (WGS 84)	Latitude Longitude Ellipsoidal Height	11°00'13.44846" North 124°36'33.43548" East 66.214 meters
Grid Coordinates, Universal Transverse Mercator Zone 51 North (UTM 51N PRS 92)	Easting Northing	67568.331 meters 1216917.267 meters

Table 11. Details of the recovered NAMRIA horizontal control point LYT-704, used as a base station for the LiDAR acquisition

Station Name	LYT-704	
Order of Accuracy	2 <sup>nd</sup> order	
Relative Error (horizontal positioning)	1:50000	
Geographic Coordinates, Philippine Reference of 1992 Datum (PRS 92)	Latitude Longitude Ellipsoidal Height	11°11'16.35419" North 124°33'36.47427" East 38.29100 meters
Grid Coordinates, Philippine Transverse Mercator Zone 5 (PTM Zone 5 PRS 92)	Easting Northing	451959.944 meters 1237144.619 meters
Geographic Coordinates, World Geodetic System 1984 Datum (WGS 84)	Latitude Longitude Ellipsoidal Height	11°11'12.06307" North 124°33'41.63876" East 99.58400 meters
Grid Coordinates, Universal Transverse Mercator Zone 51 North (UTM 51N PRS 92)	Easting Northing	670347.64 meters 1237125.91 meters

Table 12. Details of the recovered NAMRIA horizontal control point LYT-731, used as a base station for the LiDAR acquisition

Station Name		LYT-731	
Order of Accuracy		2 <sup>nd</sup> order	
Relative Error (horizontal positioning)		1:50000	
Geographic Coordinates, Philippine Reference of 1992 Datum (PRS 92)	Latitude	10°42'47.59464" North	
	Longitude	124°48'34.34385" East	
	Ellipsoidal Height	15.61000 meters	
Grid Coordinates, Philippine Transverse Mercator Zone 5 (PTM Zone 5 PRS 92)	Easting	479165.977 meters	
	Northing	1184617.338 meters	
Geographic Coordinates, World Geodetic System 1984 Datum (WGS 84)	Latitude	10°42'43.44572" North	
	Longitude	124°48'39.54791" East	
	Ellipsoidal Height	78.65700 meters	
Grid Coordinates, Universal Transverse Mercator Zone 51 North (UTM 51N PRS 92)	Easting	697902.97 meters	
	Northing	1184777.35 meters	

Table 13. Details of the established NAMRIA horizontal control point LYT-704bak, used as a base station for the LiDAR acquisition

Station Name		LYT-704bak	
Order of Accuracy		2 <sup>nd</sup> order	
Relative Error (horizontal positioning)		1:50000	
Geographic Coordinates, Philippine Reference of 1992 Datum (PRS 92)	Latitude	11°11'16.44188" North	
	Longitude	124°33'37.00349" East	
	Ellipsoidal Height	38.093 meters	
Geographic Coordinates, World Geodetic System 1984 Datum (WGS 84)	Latitude	11°11'12.15076" North	
	Longitude	124°33'42.16798" East	
	Ellipsoidal Height	99.386 meters	
Grid Coordinates, Universal Transverse Mercator Zone 51 North (UTM 51N PRS 92)	Easting	670363.675 meters	
	Northing	1237128.684 meters	

Table 14. Details of the established NAMRIA horizontal control point RM-9, used as a base station for the LiDAR acquisition

Station Name	RM-9	
Order of Accuracy	2 <sup>nd</sup> order	
Relative Error (horizontal positioning)	1:50000	
Geographic Coordinates, Philippine Reference of 1992 Datum (PRS 92)	Latitude Longitude Ellipsoidal Height	11°00'18.53023" North 124°36'28.25559" East 4.384 meters
Geographic Coordinates, World Geodetic System 1984 Datum (WGS 84)	Latitude Longitude Ellipsoidal Height	11°00'14.28954" North 124°36'33.79880" East 65.114 m
Grid Coordinates, Universal Transverse Mercator Zone 51 North (UTM 51N PRS 92)	Easting Northing	675679.222 meters 1216943.169 meters

Table 15. Details of the established NAMRIA horizontal control point W-22, used as a base station for the LiDAR acquisition

Station Name	W-22	
Order of Accuracy	1 <sup>st</sup> order	
Relative Error (horizontal positioning)	1:100000	
Geographic Coordinates, Philippine Reference of 1992 Datum (PRS 92)	Latitude Longitude Ellipsoidal Height	11°00'18.93705" North 124°36'24.81698" East 7.666 meters
Geographic Coordinates, World Geodetic System 1984 Datum (WGS 84)	Latitude Longitude Ellipsoidal Height	11°00'14.69624" North 124°36'29.99714" East 69.516 meters
Grid Coordinates, Universal Transverse Mercator Zone 51 North (UTM 51N PRS 92)	Easting Northing	675563.750 meters 1216955.050 meters

Table 16. Ground control points used during the LiDAR data acquisition

Date Surveyed	Flight Number	Mission Name	Ground Control Points
January 28, 2014	1032A	2BLK35A028A	LY-606, LYT-704
May 15, 2014	1458A	3BLK35B135A	LYT-37, LYT-86
May 15, 2014	1460A	3BLK35CD135B	LYT-37, LYT-86
May 16, 2014	1462A	3BLK35DSE136A	LYT-37, LY-672
May 16, 2014	1464A	3BLK35ES136B	LYT-37, LY-672
May 17, 2014	1466A	3BLK35F137A	LYT-37, LY-672
May 19, 2014	1474A	3BLK35G139A	LYT-37, LY-672
May 24, 2014	1494A	3BLK35GSH144A	LY-606, LYT-704
May 25, 2014	1498A	3BLK35HSI145A	LY-606, LYT-704
May 26, 2014	1502A	3BLK35IS146A	LYT-690, LYT-704
May 26, 2014	1504A	3BLK35AIS146B	LYT-690, LYT-704
January 21, 2015	7753AC	3BLK35B021A	LYT-690
January 25, 2015	7760AC	3BLK35A025A	LYT-690, RM-9
February 04, 2015	7780AC	3BLK35AX035A	LYT-690, RM-9
February 05, 2015	7782AC	3BLK35AX036A	LYT-690, RM-9
February 15, 2015	7802AC	3BLK35SV046A	LYT-690, RM-9
February 17, 2015	7806AC	3BLK35X1048A	LYT-690, LYT-731
March 09, 2016	8389AC	3BLK35A069A	LYT-89, W-22
March 10, 2016	8391AC	3BLK35EC070A	LYT-89, W-22
March 10, 2016	8392AC	3BLK35BD070B	LYT-89, W-22
March 11, 2016	8394AC	3BLK35BD071B	LYT-90, W-22
March 19, 2016	8408AC	3BLK48BD079A	LYT-89, CBU-340
March 19, 2016	8409AC	3BLK34079B	LYT-89, CBU-340
April 16, 2016	3945G	2BLK35AB107A	LYT-704, LYT-704bak
April 16, 2016	3947G	2BLK35CS107B	LYT-704, LYT-704bak

## 2.3 Flight Missions

A total of twenty-five (25) flight missions were conducted to complete the LiDAR data acquisition in the Pagsangahan floodplain, for a total of one hundred hours and fifty-six minutes (100+56) of flying time for RP-C9022, RP-C9122 and RP-C9322. All missions were acquired using the Aquarius and Gemini LiDAR systems. The flight logs of the missions are found in ANNEX 6. Table 17 indicates the total area of actual coverage and the corresponding flying hours per mission, and Table 18 presents the actual parameters used during the LiDAR data acquisition.

Table 17. Flight missions for the LiDAR data acquisition in the Pagsangahan floodplain

Date Surveyed	Flight Number	Flight Plan Area (km <sup>2</sup> )	Surveyed Area (km <sup>2</sup> )	Area Surveyed within the Floodplain (km <sup>2</sup> )	Area Surveyed outside the Floodplain (km <sup>2</sup> )	No. of Images (Frames)	Flying Hours	
							Hr	Min
28-Jan-14	1032A	84.59	86.05	27.39	58.66	867	4	41
15-May-14	1458A	97.25	108.72	NA	108.72	1174	4	35
15-May-14	1460A	176.02	119.23	NA	119.23	1128	4	35
16-May-14	1462A	240.97	115.47	NA	115.47	1347	4	41
16-May-14	1464A	151.06	119.82	NA	119.82	1258	4	11
17-May-14	1466A	116.84	124.66	NA	124.66	1383	4	47
19-May-14	1474A	124.69	124.90	NA	124.90	1189	4	53
24-May-14	1494A	110.19	113.80	16.76	97.04	1294	4	53
25-May-14	1498A	201.35	108.30	48.87	59.43	1293	4	41
26-May-14	1502A	175.76	73.08	38.54	34.54	1236	4	41
26-May-14	1504A	91.17	84.46	30.09	54.37	943	4	23
21-Jan-15	7753AC	75.59	79.73	20.38	59.35	NA	3	5
25-Jan-15	7760AC	94.30	78.99	NA	78.99	NA	4	11
04-Feb-15	7780AC	84.59	19.98	5.00	14.98	NA	1	17
05-Feb-15	7782AC	84.59	83.53	27.31	56.22	NA	4	23
15-Feb-15	7802AC	169.90	71.43	3.91	67.52	NA	4	11
17-Feb-15	7806AC	84.59	55.81	28.67	27.14	NA	3	23
09-Mar-16	8389AC	33.78	35.25	24.22	11.03	NA	4	17
10-Mar-16	8391AC	51.67	68.05	16.72	51.33	NA	4	23
10-Mar-16	8392AC	81.66	67.21	NA	67.21	NA	3	29
11-Mar-16	8394AC	81.66	33.55	NA	33.55	NA	2	47
19-Mar-16	8408AC	51.67	43.43	2.16	41.27	NA	3	35
19-Mar-16	8409AC	75.59	33.57	2.82	30.75	NA	2	5
16-Apr-16	3945G	109.37	108.02	70.92	37.1	NA	4	22
16-Apr-16	3947G	18.51	153.94	25.60	128.34	NA	4	27
<b>TOTAL</b>		<b>2667.38</b>	<b>2110.98</b>	<b>389.36</b>	<b>1721.62</b>	<b>13112</b>	<b>100</b>	<b>56</b>



Table 18. Actual parameters used during the LiDAR data acquisition

Date Surveyed	Flight Number	Flying Height (AGL) (m)	Overlap (%)	Field of View	PRF (kHz)	Scan Frequency (Hz)	Speed of Plane (Kts)
1032A	600	30	50	70	40	130	5
1458A	700	30	36	50	50	130	5
1460A	700	30	36	50	50	130	5
1462A	700	30	36	50	50	130	5
1464A	700	30	36	50	50	130	5
1466A	600	30	36	50	50	130	5
1474A	700	30	36	50	50	130	5
1494A	700	30	36	50	50	130	5
1498A	800	30	36	50	50	130	5
1502A	700	55, 40, 50	36	50	50	130	5
1504A	600	30	36	50	50	130	5
7753AC	600	35	36	50	35	130	5
7760AC	550	35	36	50	35	130	5
7780AC	500	35	36	50	35	130	5
7782AC	600	35	36	50	35	130	5
7802AC	600	35	36	50	35	130	5
7806AC	600	35	36	50	35	130	5
8389AC	600	30	36	50	30	130	5
8391AC	550	30	36	50	30	130	5
8392AC	550	30	36	50	30	130	5
8394AC	550	30	36	50	30	130	5
8408AC	600	30	36	33	30	130	5
8409AC	600	30	36	50	30	130	5
3945G	800, 1000	30	40	100	30	130	5
3947G	1100	30	40	100	30	130	5

## 2.4 Survey Coverage

This certain LiDAR acquisition survey covered the Pagsangahan floodplain located in the province of Leyte, with majority of the floodplain situated within the municipality of Ormoc City. The Municipalities of Calubian, Merida, San Isidro, Tabango, and Villaba were mostly covered by the survey. The list of municipalities and cities surveyed, with at least one (1) square kilometer coverage, is presented in Table 19. The actual coverage of the LiDAR acquisition for the Pagsangahan floodplain is illustrated in Figure 6. ANNEX 7 provides the flight status reports of the survey.

Table 19. List of municipalities and cities surveyed during the Pagsangahan floodplain LiDAR survey

Province	Municipality/City	Area of Municipality/ City (km <sup>2</sup> )	Total Area Surveyed (km <sup>2</sup> )	Percentage of Area Surveyed
Leyte	Albuera	167.61	13.43	8%
	Calubian	102.58	102.58	100%
	Isabel	102.07	93.35	91%
	Kananga	145.85	85.7	59%
	Leyte	240.2	105.78	44%
	Matag-ob	63.46	60.32	95%
	Merida	101.48	101.36	100%
	Ormoc City	451.96	198.13	44%
	Palompon	125.87	79.25	63%
	San Isidro	112.26	112.26	100%
	Tabango	115.97	115.97	100%
	Villaba	133.68	133.38	100%
<b>Total</b>		<b>1862.99</b>	<b>1201.51</b>	<b>64.49%</b>

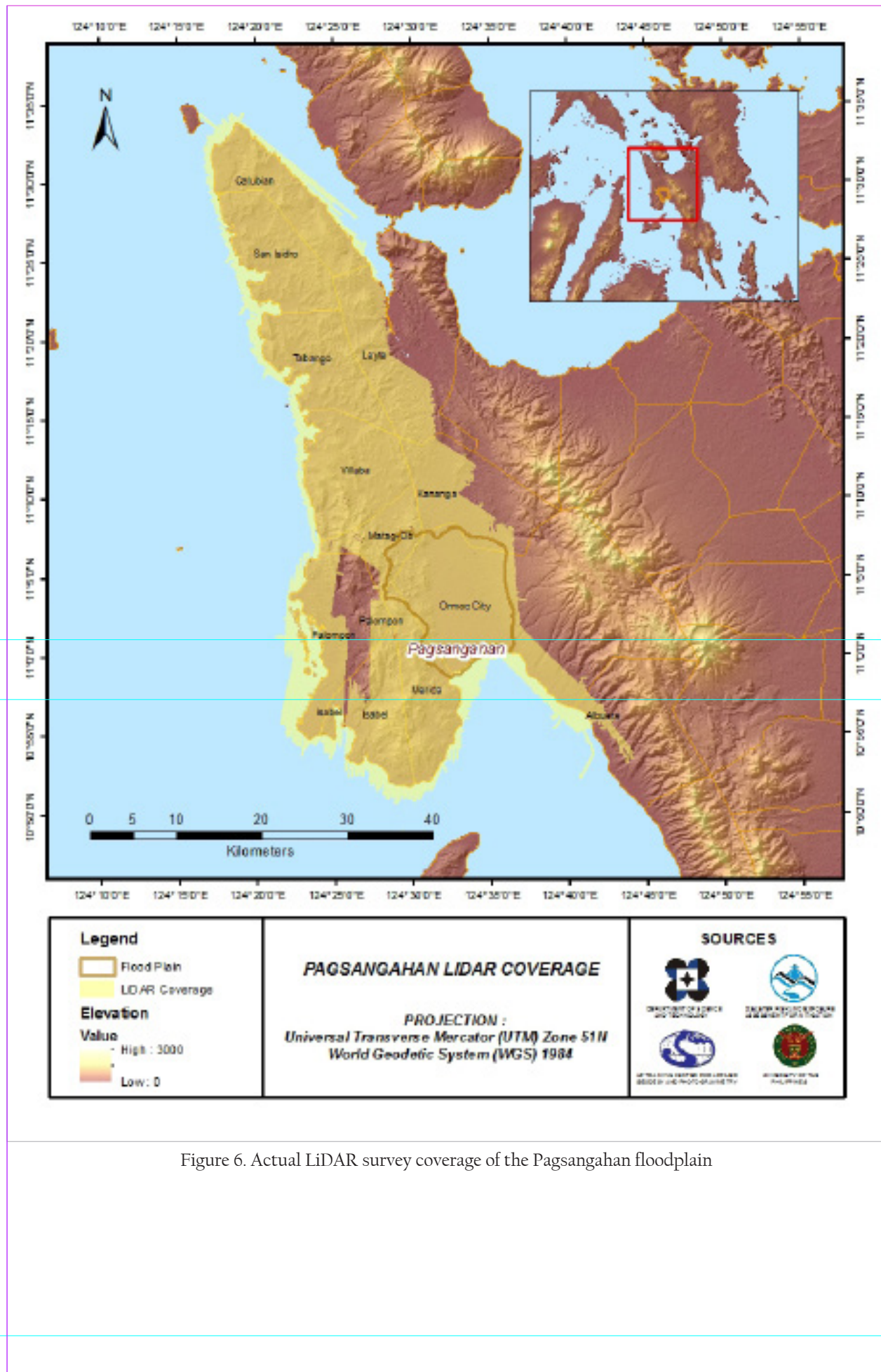


Figure 6. Actual LiDAR survey coverage of the Pagsangahan floodplain

## CHAPTER 3: LIDAR DATA PROCESSING OF THE PANGSAHAN FLOODPLAIN

*Engr. Ma. Ailyn L. Olanda, Engr. Velina Angela S. Bemida, and Jovy Anne S. Narisma*

The methods applied in this Chapter were based on the DREAM methods manual (Ang, et al., 2014) and further enhanced and updated in Paringit, et al. (2017).

### 3.1 Overview of the LIDAR Data Pre-Processing

The data transmitted by the DAC were checked for completeness based on the list of raw files required to proceed with the pre-processing of the LiDAR data. Upon acceptance of the LiDAR field data, georeferencing of the flight trajectory was done in order to obtain the exact location of the LiDAR sensor when the laser was shot. Point cloud georectification was performed to incorporate the correct position and orientation for each point acquired. The georectified LiDAR point clouds were subjected to quality checking to ensure that the required accuracies of the program, which are the minimum point density, and vertical and horizontal accuracies, were met. The point clouds were then categorized into various classes before generating Digital Elevation Models (DEMs), such as the Digital Terrain Model (DTM) and the Digital Surface Model (DSM).

Using the elevation of points gathered from the field, the LiDAR-derived digital models were calibrated. Portions of the river that were barely penetrated by the LiDAR system were replaced by the actual river geometry, measured from the field by the Data Validation and Bathymetry Component (DVBC). LiDAR acquired temporally were then mosaicked to completely cover the target river systems in the Philippines. Orthorectification of images acquired simultaneously with the LiDAR data was accomplished through the help of the georectified point clouds, and the metadata containing the time the image was captured.

These processes are summarized in the diagram in Figure 7.

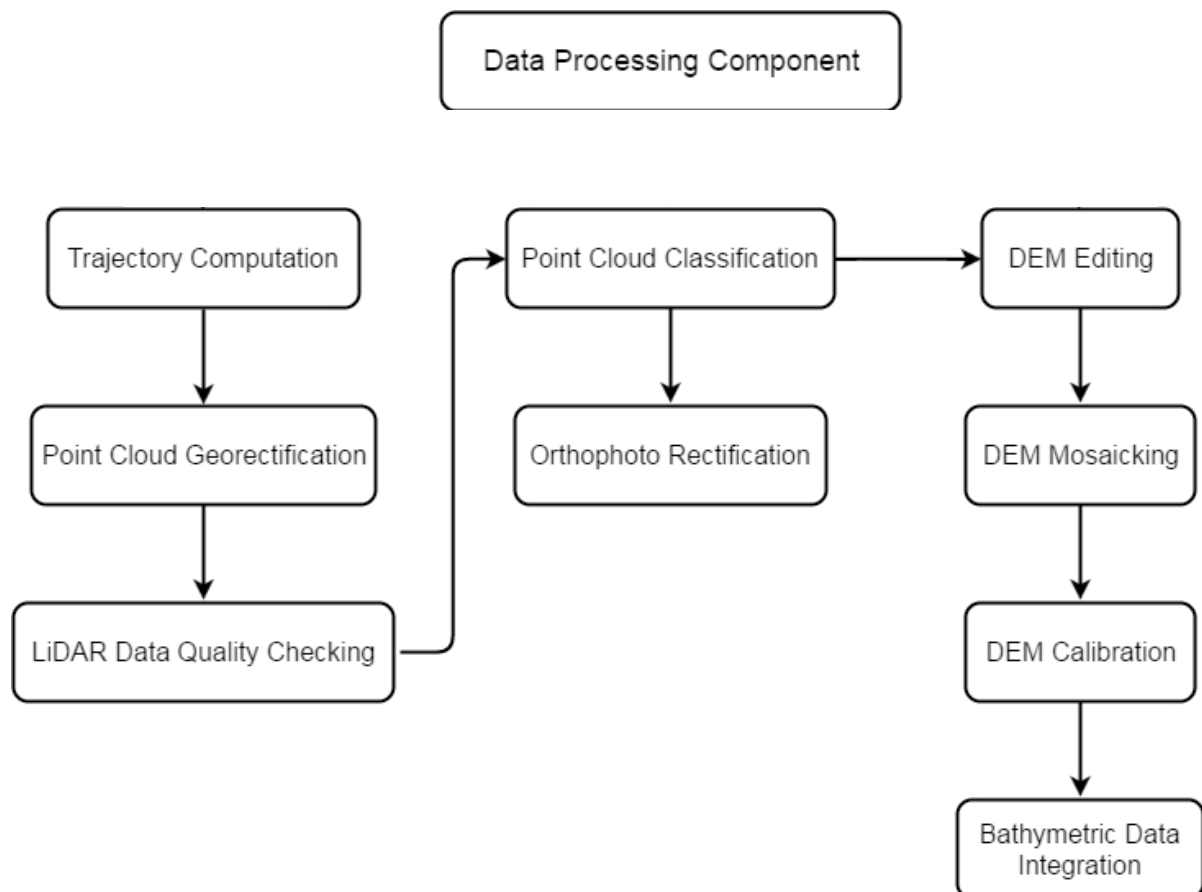


Figure 7. Schematic diagram for the Data Pre-Processing Component

### 3.2 Transmittal of Acquired LiDAR Data

The data transfer sheets for all the LiDAR missions for the Pagsangahan floodplain can be found in ANNEX 5. Missions flown during the first survey conducted in April 2014 used the Airborne LiDAR Terrain Mapper (ALTM™ Optech Inc.) Aquarius system; while missions acquired during the second survey in January 2016 were flown using the Gemini system over Ormoc, Leyte. The DAC transferred a total of 287.50 Gigabytes of Range data, 5.83 Gigabytes of POS data, 1600.83 Megabytes of GPS base station data, and 1175.8 Gigabytes of raw image data to the data server on January 28, 2014 for the first survey, and on April 16, 2016 for the second survey. The Data Pre-processing Component (DPPC) verified the completeness of the transferred data. The whole dataset for the Pagsangahan River survey was fully transferred on May 6, 2016, as indicated on the data transfer sheets for the Pagsangahan floodplain.

### 3.3 Trajectory Computation

The Smoothed Performance Metrics of the computed trajectory for flight 1462A, one of the Pagsangahan flights, which are the North, East, and Down position RMSE values, are demonstrated in Figure 8. The x-axis corresponds to the time of flight, which is measured by the number of seconds from the midnight of the start of the GPS week, which fell on May 16, 2014 at 00:00 hrs. on that week. The y-axis represents the RMSE value for that particular position.

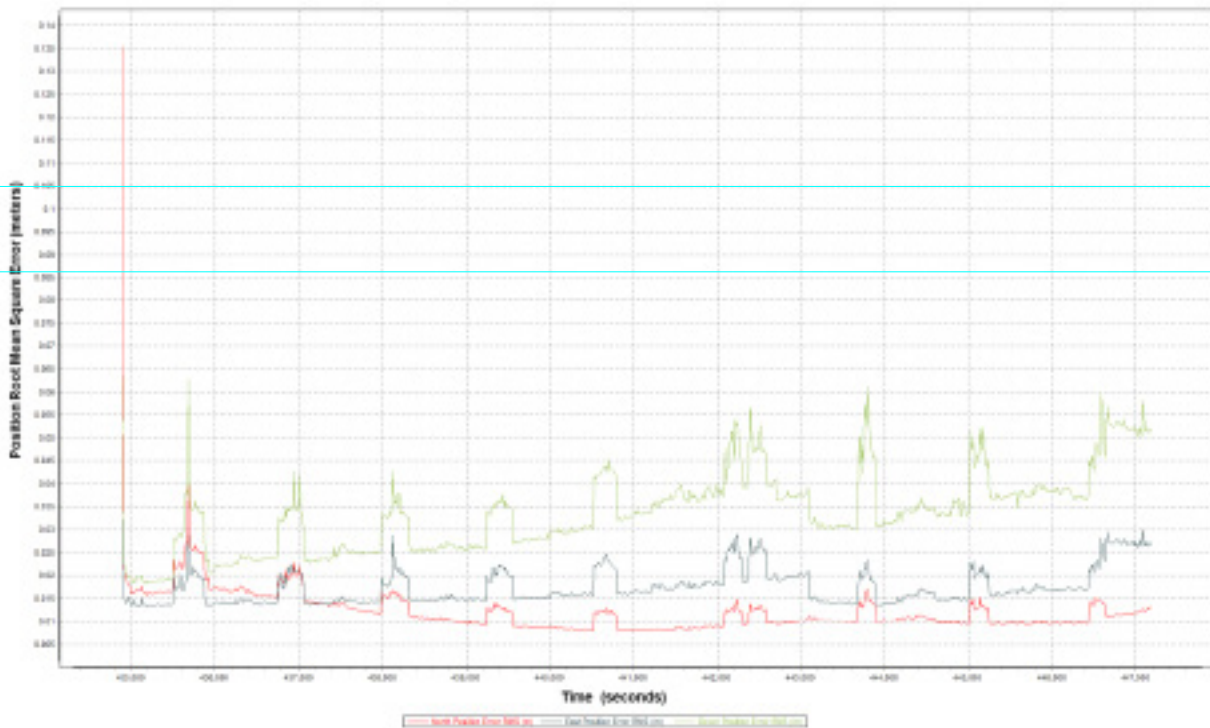


Figure 8. Smoothed Performance Metrics of a Pagsangahan Flight 1462A

The time of flight was from 435000 seconds to 447000 seconds, which corresponds to the morning of May 16, 2014. The initial spike reflected on the data corresponds to the time that the aircraft was getting into position to start the acquisition, and the POS system was starting to compute for the position and orientation of the aircraft. Redundant measurements from the POS system quickly minimized the RMSE values of the positions. The periodic increase in RMSE values from an otherwise smoothly curving RMSE values corresponds to the turn-around period of the aircraft, when the aircraft makes a turn to start a new flight line. Figure 8 depicts that the North position RMSE peaked at 4.00 centimeters, the East position RMSE peaked at 3.00 centimeters, and the Down position RMSE peaked at 6.50 centimeters, which are all within the prescribed accuracies described in the methodology.

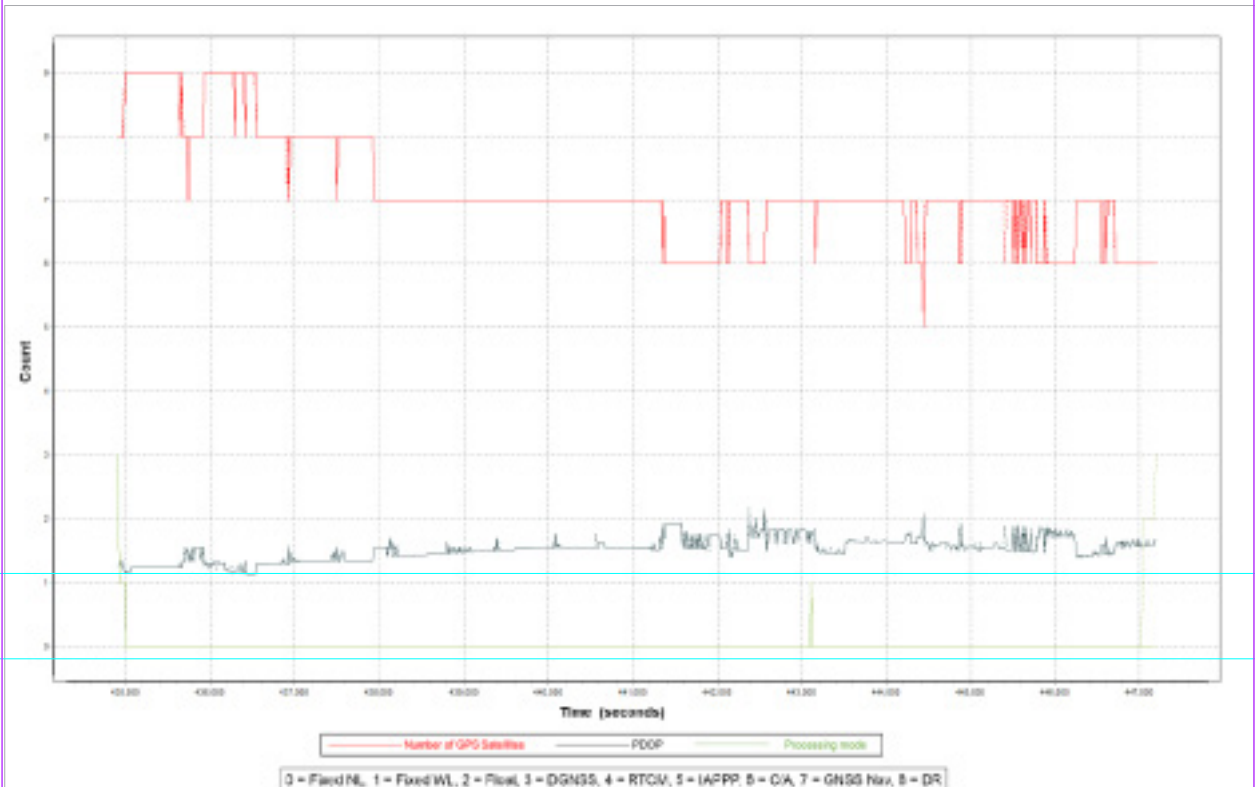


Figure 9. Smoothed Performance Metric Parameters of a Pagsangahan Flight 1462A

The Solution Status parameters of flight 1462A, one of the Pagsangahan flights, which indicate the number of GPS satellites, Positional Dilution of Precision (PDOP), and the GPS processing mode used, are presented in Figure 9. The graphs indicate that the number of satellites during the acquisition did go down to six (6). Most of the time, the number of satellites tracked was between five (5) and nine (9). The PDOP value did not go above the value of three (3), which indicates optimal GPS geometry. The processing mode remained at zero (0) for majority of the survey with some peaks to up to two (2), attributed to the turns performed by the aircraft. The value of zero (0) corresponds to a Fixed, Narrow-Lane mode, which is the optimum carrier-cycle integer ambiguity resolution technique available for POSPAC MMS. All of the parameters satisfied the accuracy requirements for optimal trajectory solutions, as indicated in the methodology. The computed best estimated trajectory for all Pagsangahan flights is exhibited in Figure 10.

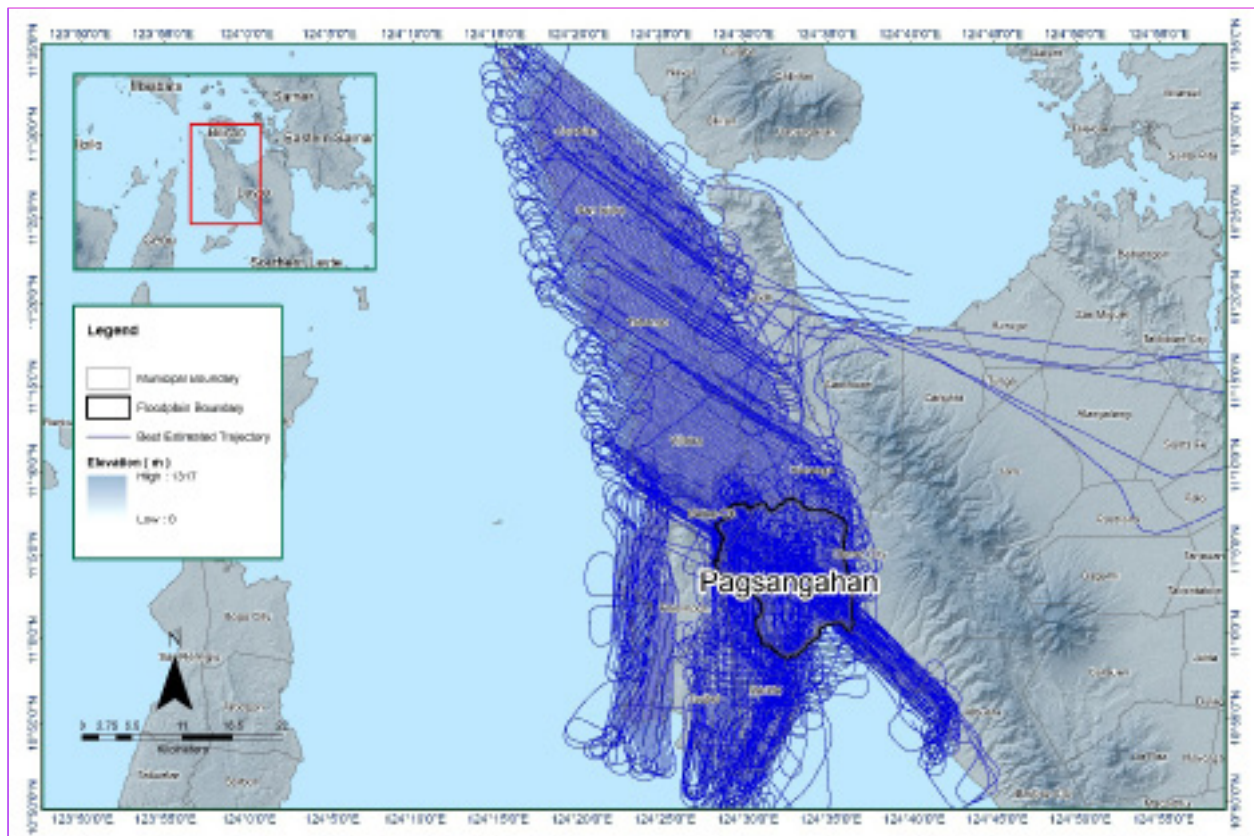


Figure 10. The best estimated trajectory conducted over the Pagsangahan floodplain

### 3.4 LiDAR Point Cloud Computation

The produced LAS data contains 506 flight lines, with each flight line containing one (1) channel, since the Gemini and Aquarius systems both contain only one (1) channel. The summary of the self-calibration results for all flights over the Pagsangahan floodplain, obtained from LiDAR processing in the LiDAR Mapping Suite (LMS) software, is given in Table 20.

Table 20. Self-calibration results for the Pagsangahan flights

Parameter	Computed Value
Boresight Correction stdev (<0.001degrees)	0.000208
IMU Attitude Correction Roll and Pitch Corrections stdev (<0.001degrees)	0.000943
GPS Position Z-correction stdev (<0.01meters)	0.0082

Optimum accuracy was obtained for all Pagsangahan flights, based on the computed standard deviations of the corrections of the orientation parameters. The standard deviation values for the individual blocks are available in ANNEX 8. Mission Summary Reports.

### 3.5 LiDAR Data Quality Checking

The boundaries of the processed LiDAR data are represented in Figure 11. The map shows gaps in the LiDAR coverage that are attributed to cloud coverage.

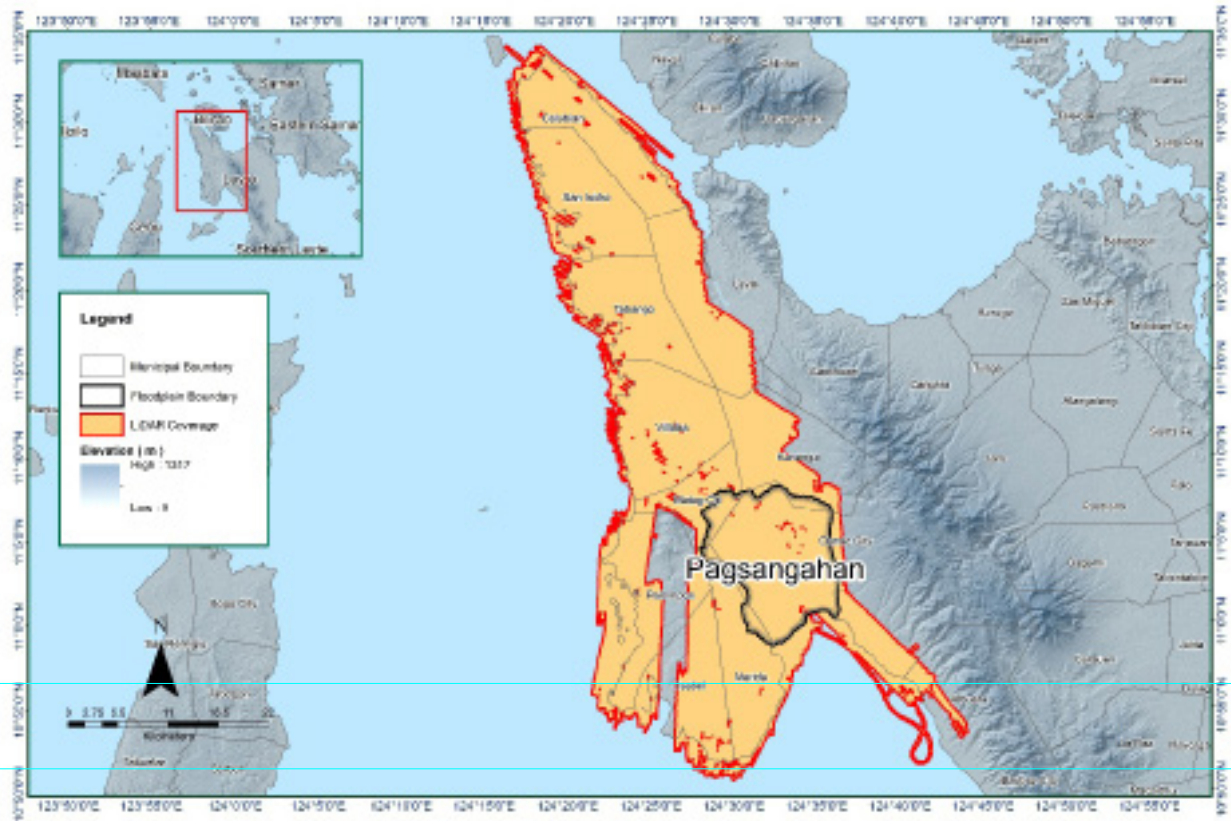


Figure 11. Boundaries of the processed LiDAR data on top of a SAR Elevation Data over the Pagsangahan floodplain.

The total area covered by the Pagsangahan missions is 1799.76 sq. km., comprised of twenty-five (25) flight acquisitions grouped and merged into thirty (30) blocks, as reflected in Table 21.



Table 21. List of LiDAR blocks for the Pagsangahan floodplain

<b>LiDAR Blocks</b>	<b>Flight Numbers</b>	<b>Area (sq. km)</b>
Samar_Leyte_Bl35A	1504A	68.59
Samar_Leyte_Bl35I	1502A	64.25
	1504A	
Samar_Leyte_Bl35I_additional	1502A	13.55
	1504A	
Samar_Leyte_Bl35H_supplement	1498A	104.32
Samar_Leyte_Bl35F	1466A	158.46
	1474A	
Samar_Leyte_Bl35E	1464A	116.20
	1474A	
Samar_Leyte_Bl35D	1462A	110.56
Samar_Leyte_Bl35C	1460A	118.95
	1474A	
Samar_Leyte_Bl35B	1458A	79.46
Samar_Leyte_Bl35H	1494A	108.32
Samar_Leyte_Bl35H_supplement2	1498A	0.18
Ormoc_Bl35A_supplement	7806AC	74.91
Ormoc_Bl35A	7780AC	86.29
	7782AC	
Ormoc_Bl35B	7753AC	68.76
Ormoc_Bl35A_additional	7760AC	74.78
Ormoc_Bl35B_additional	7802AC	25.57
Ormoc_Bl35CD_additional	7806AC	6.43
Ormoc_Camotes_Bl35E	8391AC	36.84
Ormoc_Camotes_Bl35E_additional	8408AC	8.87
Ormoc_Camotes_Bl35E_supplement	8389AC	61.52
Ormoc_Camotes_Bk35F	8391AC	25.65
Ormoc_Camotes_Bl35F_additional	8408AC	8.34
Ormoc_Camotes_Bl35G	8392AC	52.24
Ormoc_Camotes_Bl35H	8392AC	11.11
Ormoc_Camotes_Bl35H_supplement	8408AC	20.80
Ormoc_Camotes_Bl35J	8409AC	19.16
Ormoc_South_Bl35A	3945G	106.48
Ormoc_South_Bl35B	3945G	59.81
	3947G	
Ormoc_South_Bl35C	3947G	96.01
Tacloban_Bl35A	1032A	13.35
<b>TOTAL</b>		<b>1799.76 sq.km</b>

The overlap data for the merged LiDAR blocks, showing the number of channels that pass through a particular location, is illustrated in Figure 12. Since the Gemini and Aquarius systems both employ one (1) channel, it is expected to have an average value of 1 (blue) for areas where there is limited overlap, and a value of 2 (yellow) or more (red) for areas with three or more overlapping flight lines.

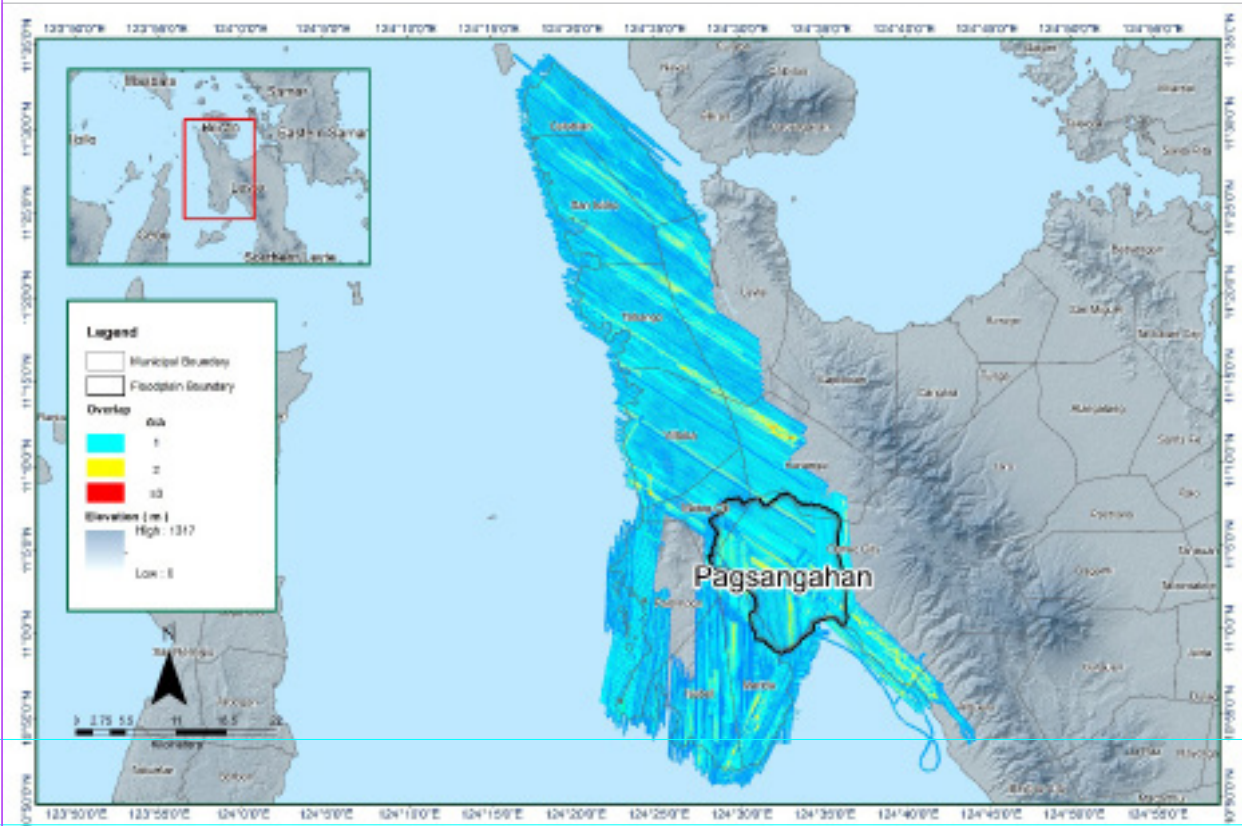


Figure 12. Image of data overlap for the Pagsangahan floodplain

The overlap statistics per block for the Pagsangahan floodplain can be found in ANNEX 8. One (1) pixel corresponds to 25.0 square meters on the ground. For this area, the minimum and maximum percent overlaps are 26.50% and 68.60%, respectively, which satisfied the 25% requirement.

The pulse density map for the merged LiDAR data, with the red parts showing the portions of the data that satisfy the two (2) points per square meter criterion, is illustrated in Figure 13. It was determined that all LiDAR data for the Pagsangahan floodplain satisfy the point density requirement, and that the average density for the entire survey area is 3.45 points per square meter.

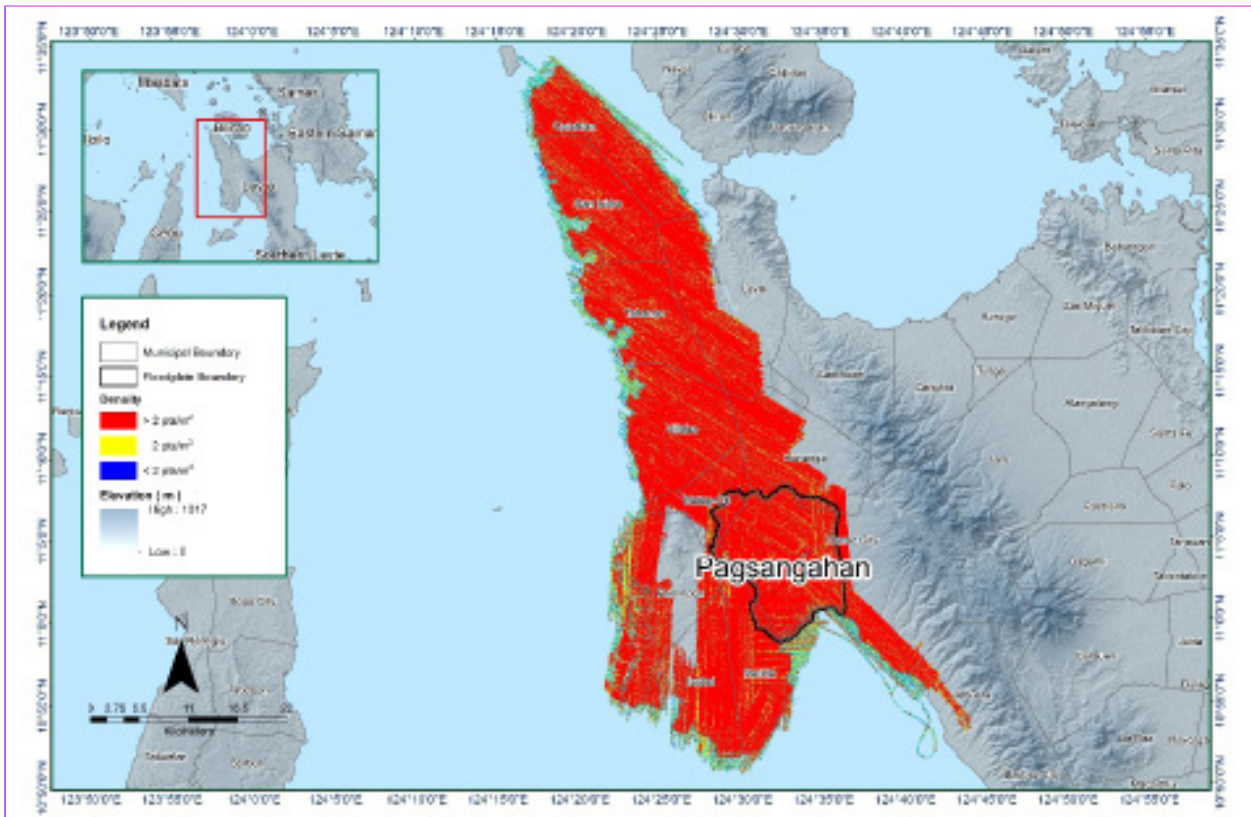


Figure 13. Pulse density map of merged LiDAR data for the Pagsangahan floodplain

The elevation difference between overlaps of adjacent flight lines is depicted in Figure 14. The default color range is from blue to red, Bright blue areas represent portions where elevations of a previous flight line, identified by its acquisition time, are higher by more than 0.20 meters relative to elevations of its adjacent flight line. Bright red areas indicate portions where elevations of a previous flight line are lower by more than 0.20 meters relative to elevations of its adjacent flight line. Areas with bright red or bright blue were investigated further using the Quick Terrain (QT) Modeler software.

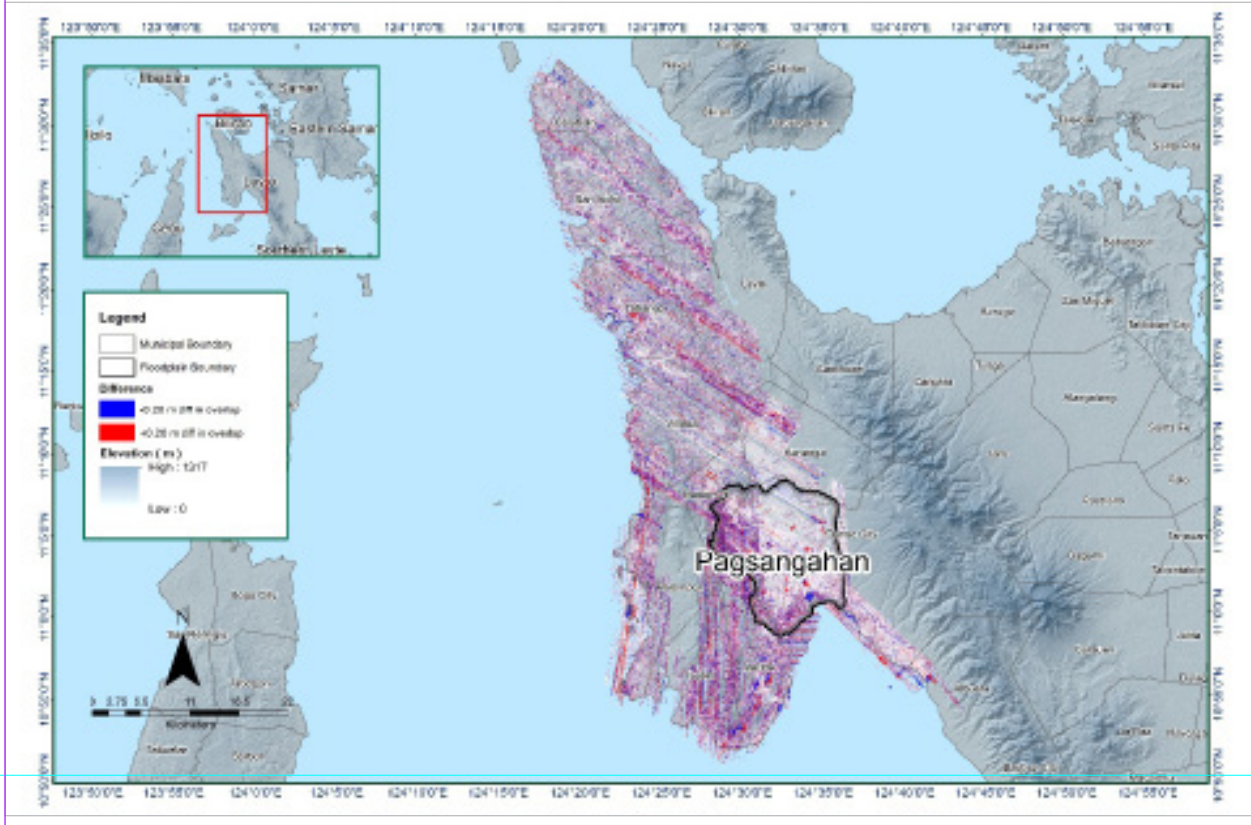


Figure 14. Pulse density map of merged LiDAR data for the Pagsangahan floodplain

A screen capture of the processed LAS data from a Pagsangahan flight 1462A loaded in the QT Modeler is provided in Figure 15. The upper left image shows the elevations of the points from two (2) overlapping flight strips traversed by the profile, illustrated by a dashed yellow line. The x-axis corresponds to the length of the profile. It is evident that there were differences in elevation, but the differences did not exceed the 20-centimeter mark. This profiling was repeated until the researcher was satisfied with the quality of the LiDAR data. No reprocessing was done for this LiDAR dataset.

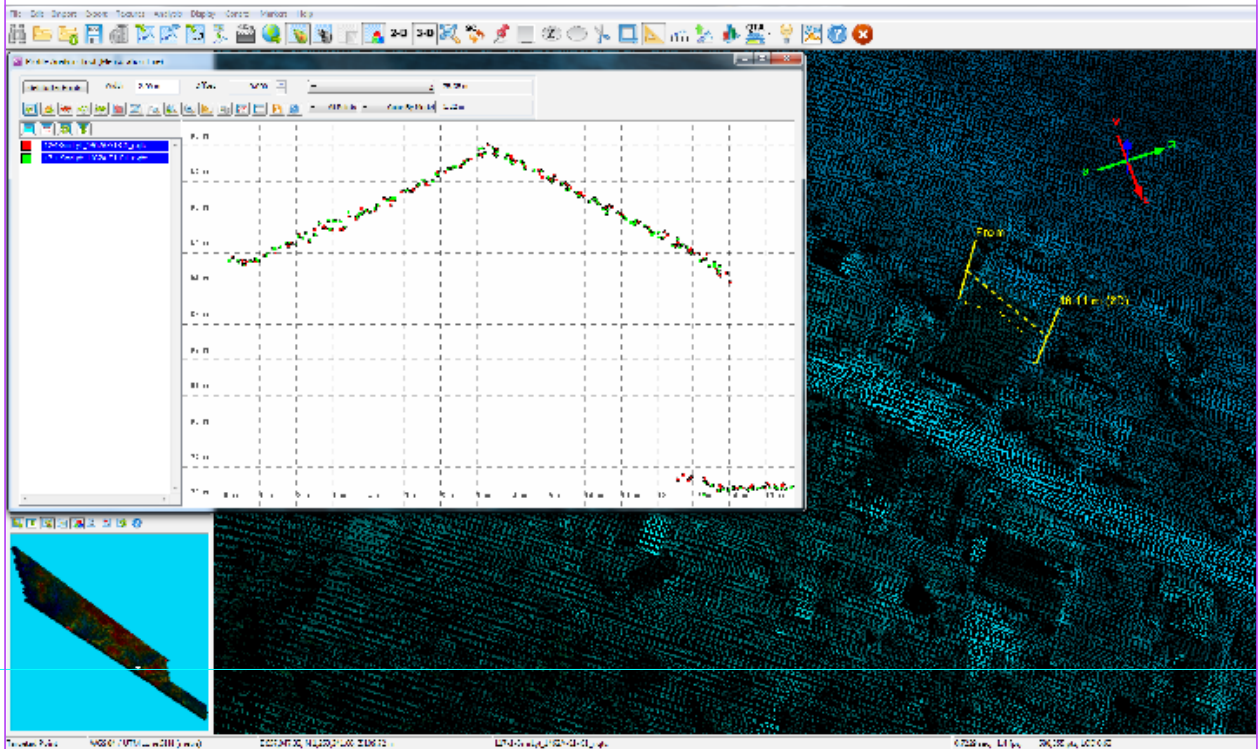


Figure 15. Quality checking for Pagsangahan flight 1462A using the Profile Tool of the QT Modeler

### 3.6 LiDAR Point Cloud Classification and Rasterization

Table 22. Pagsangahan classification results in TerraScan

Pertinent Class	Total Number of Points
Ground	1,193,199,945
Low Vegetation	1,297,574,181
Medium Vegetation	2,126,173,720
High Vegetation	1,242,378,242
Building	56,017,725

The tile system that the TerraScan employed for the LiDAR data, as well as the final classification image for a block in Pagsangahan floodplain, are presented in Figure 16. A total of 2,737 1km by 1km tiles were produced. The number of points classified according to the pertinent categories is illustrated in Table 22. The point cloud had a maximum and minimum height of 664.42 meters and 36.39 meters, respectively.

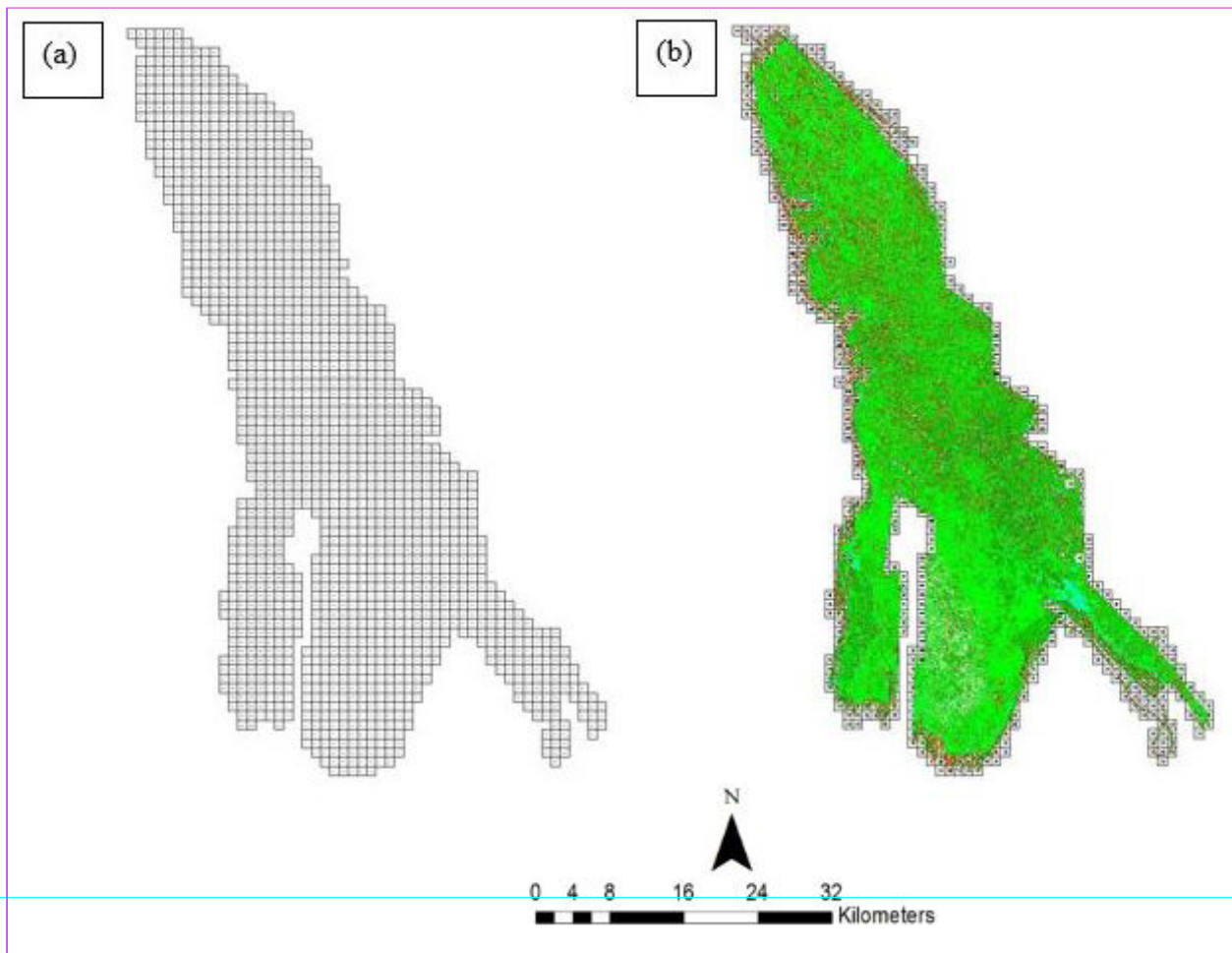


Figure 16. (a) Tiles for the Pagsangahan floodplain; and (b) classification results in TerraScan

An isometric view of an area before and after running the classification routines is shown in Figure 17. The ground points are in orange, the vegetation is in different shades of green, and the buildings are in cyan. It is evident that residential structures adjacent or even below canopy were classified correctly, due to the density of the LiDAR data.

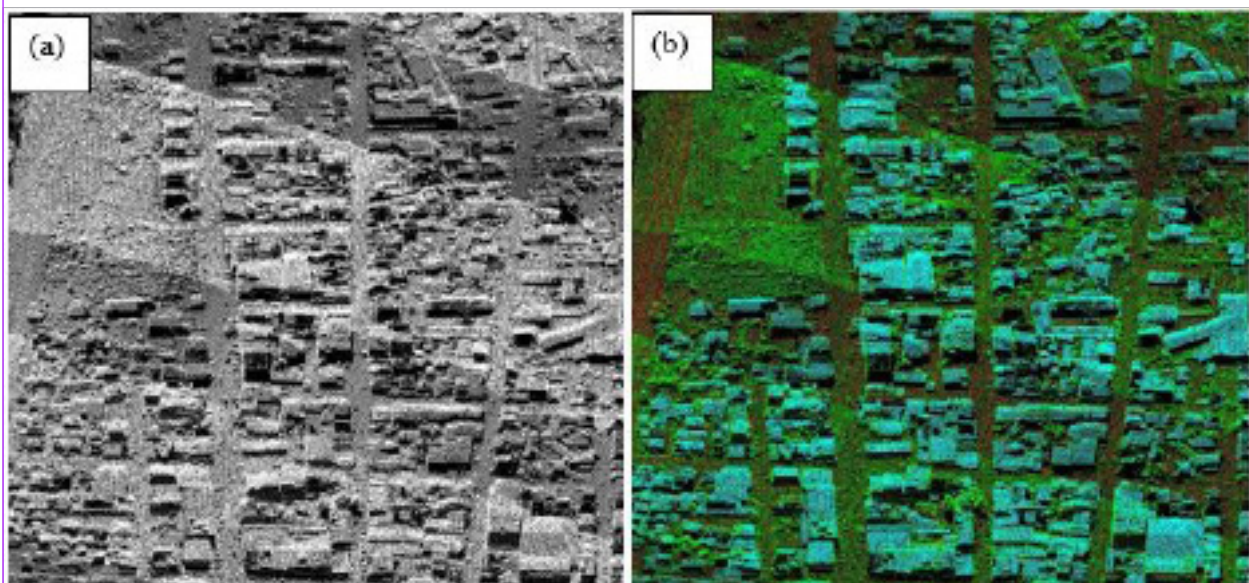


Figure 17. Point cloud (a) before and (b) after classification

The production of last return (V\_ASCII) and the secondary (T\_ASCII) DTM, and the first (S\_ASCII) and last (D\_ASCII) return DSM of the area are presented in Figure 18, in top view display. It shows that DTMs are a representation of the bare earth, while the DSMs reflect all features that are present, such as buildings and vegetation.

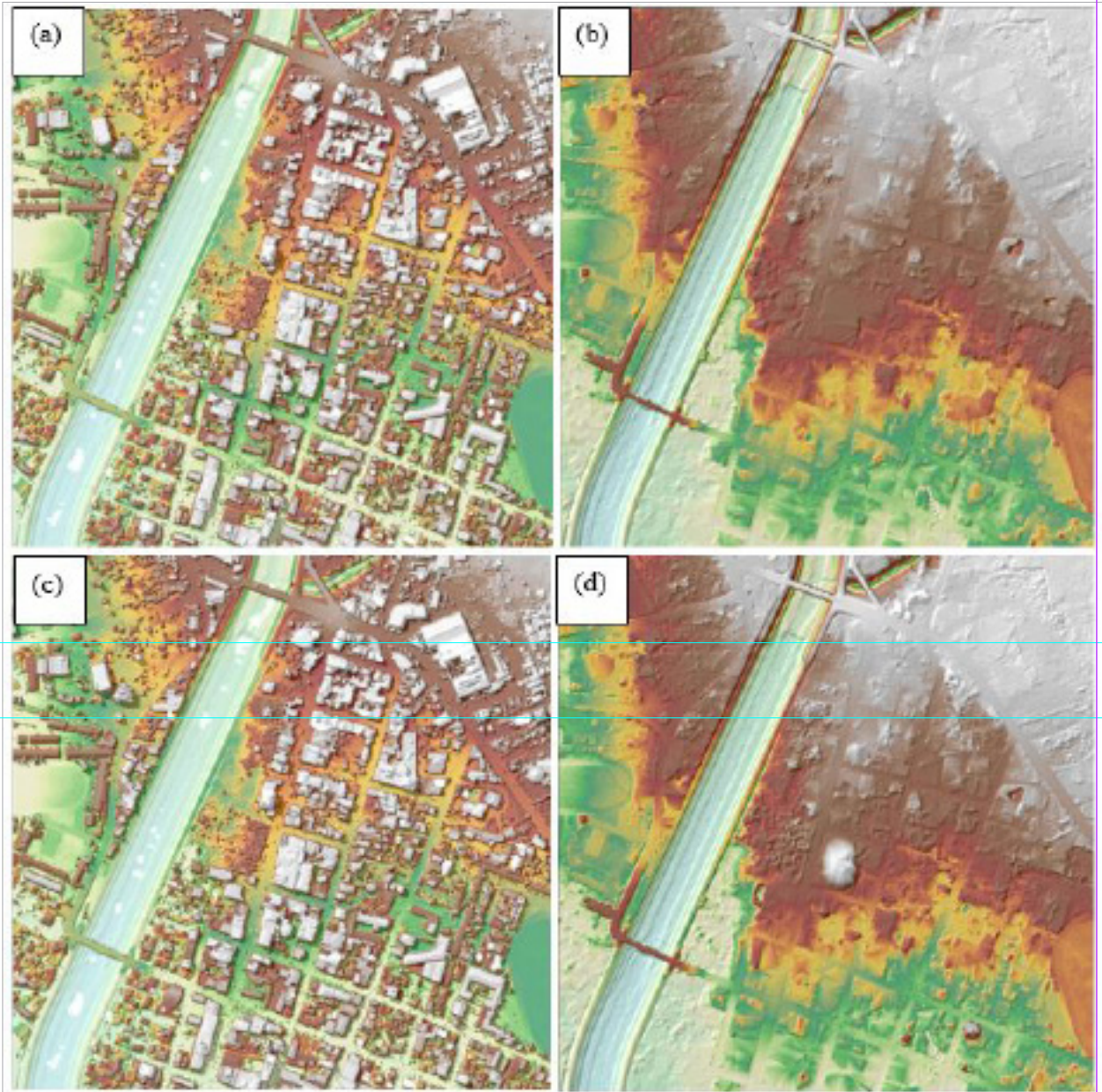


Figure 18. The production of (a) last return DSM and (b) DTM; (c) first return DSM and (d) secondary DTM in some portion of Pagsangahan floodplain

### 3.7 LiDAR Image Processing and Orthophotograph Rectification

The 1,134 1km by 1km tiles area covered by the Pagsangahan floodplain is illustrated in Figure 19. After employing tie point selection to fix photo misalignments, color points were added to smoothen out visual inconsistencies along the seamlines where photos overlap. The Pagsangahan floodplain survey attained a total of 774.39 sq. km. in orthophotographic coverage, comprised of 9,430 images. Zoomed-in versions of sample orthophotographs, identified by their tile numbers, are provided in Figure 20.

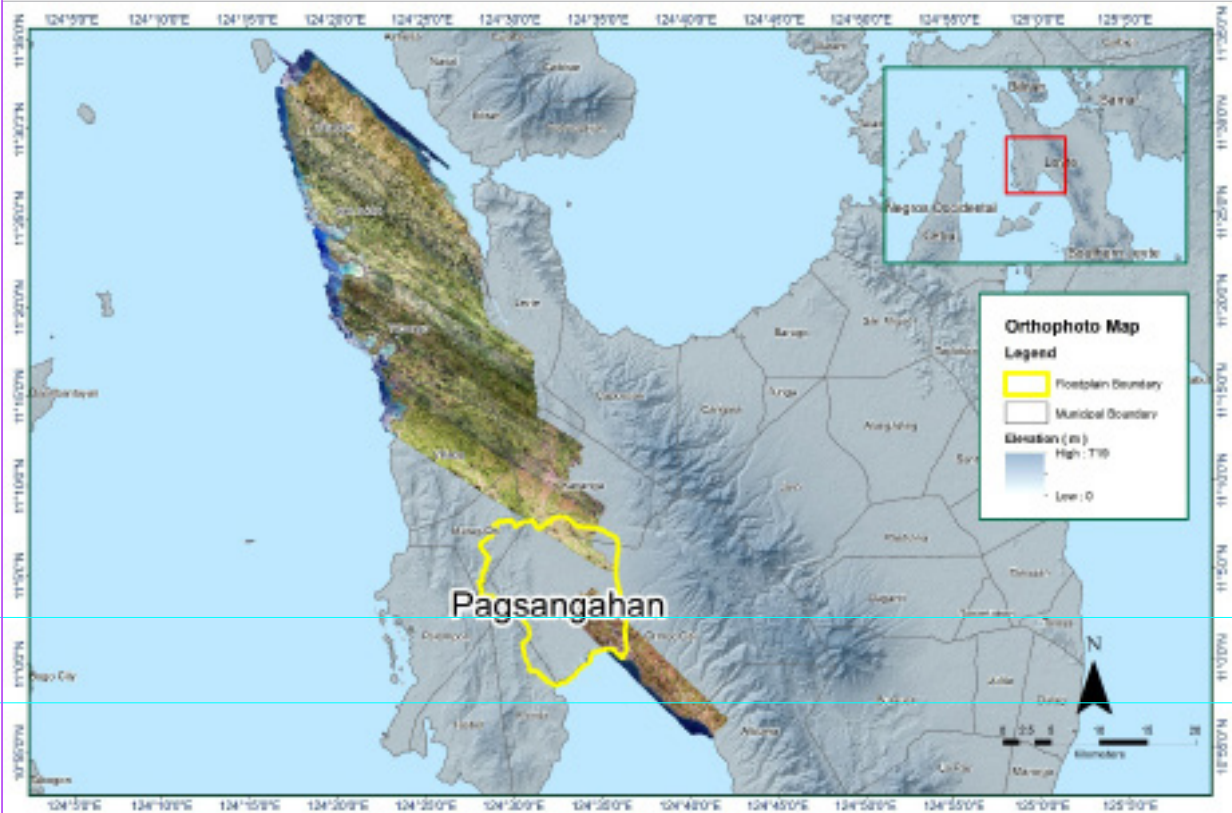


Figure 19. The Pagsangahan floodplain with available orthophotographs



Figure 20. Sample orthophotograph tiles for the Pagsangahan floodplain

### 3.8 DEM Editing and Hydro-Correction

Thirty (30) mission blocks were processed for the Pagsangahan floodplain survey. These blocks are composed of Samar\_Leyte, Ormoc, Ormoc\_South, and Ormoc\_Camotes blocks, with a total area of 1,799.76 square kilometers. Table 23 indicates the name and corresponding area of each block, in square kilometers.

Table 23. LiDAR blocks with their corresponding areas

LiDAR Blocks	Area (sq.km)
Samar_Leyte_Bl35A	68.59
Samar_Leyte_Bl35I	64.25
Samar_Leyte_Bl35I_additional	13.55
Samar_Leyte_Bl35H_supplement	104.32
Samar_Leyte_Bl35F	158.46
Samar_Leyte_Bl35E	116.20
Samar_Leyte_Bl35D	110.56
Samar_Leyte_Bl35C	118.95
Samar_Leyte_Bl35B	79.46
Samar_Leyte_Bl35H	108.32
Samar_Leyte_Bl35H_supplement2	0.18
Ormoc_Bl35A_supplement	74.91
Ormoc_Bl35A	86.29
Ormoc_Bl35B	68.76
Ormoc_Bl35A_additional	74.78
Ormoc_Bl35B_additional	25.57
Ormoc_Bl35CD_additional	6.43
Ormoc_Camotes_Bl35E	36.84
Ormoc_Camotes_Bl35E_additional	8.87
Ormoc_Camotes_Bl35E_supplement	61.52
Ormoc_Camotes_Bl35F	25.65
Ormoc_Camotes_Bl35F_additional	8.34
Ormoc_Camotes_Bl35G	52.24
Ormoc_Camotes_Bl35H	11.11
Ormoc_Camotes_Bl35H_supplement	20.80
Ormoc_Camotes_Bl35J	19.16
Ormoc_South_Bl35A	106.48
Ormoc_South_Bl35B	59.81
Ormoc_South_Bl35C	96.01
Tacloban_Bl35A	13.35
<b>TOTAL</b>	<b>1799.76 sq.km</b>

Portions of the DTM before and after manual editing are represented in Figure 21. The bridge and other misclassified objects on the river (Figure 21a) were considered to be impedances to the flow of water and had to be removed (Figure 21b) in order to hydrologically correct the river. The paddy field embankment (Figure 21c) was misclassified and removed during the classification process, and had to be retrieved to complete the surface (Figure 21d) to allow for the correct flow of water.



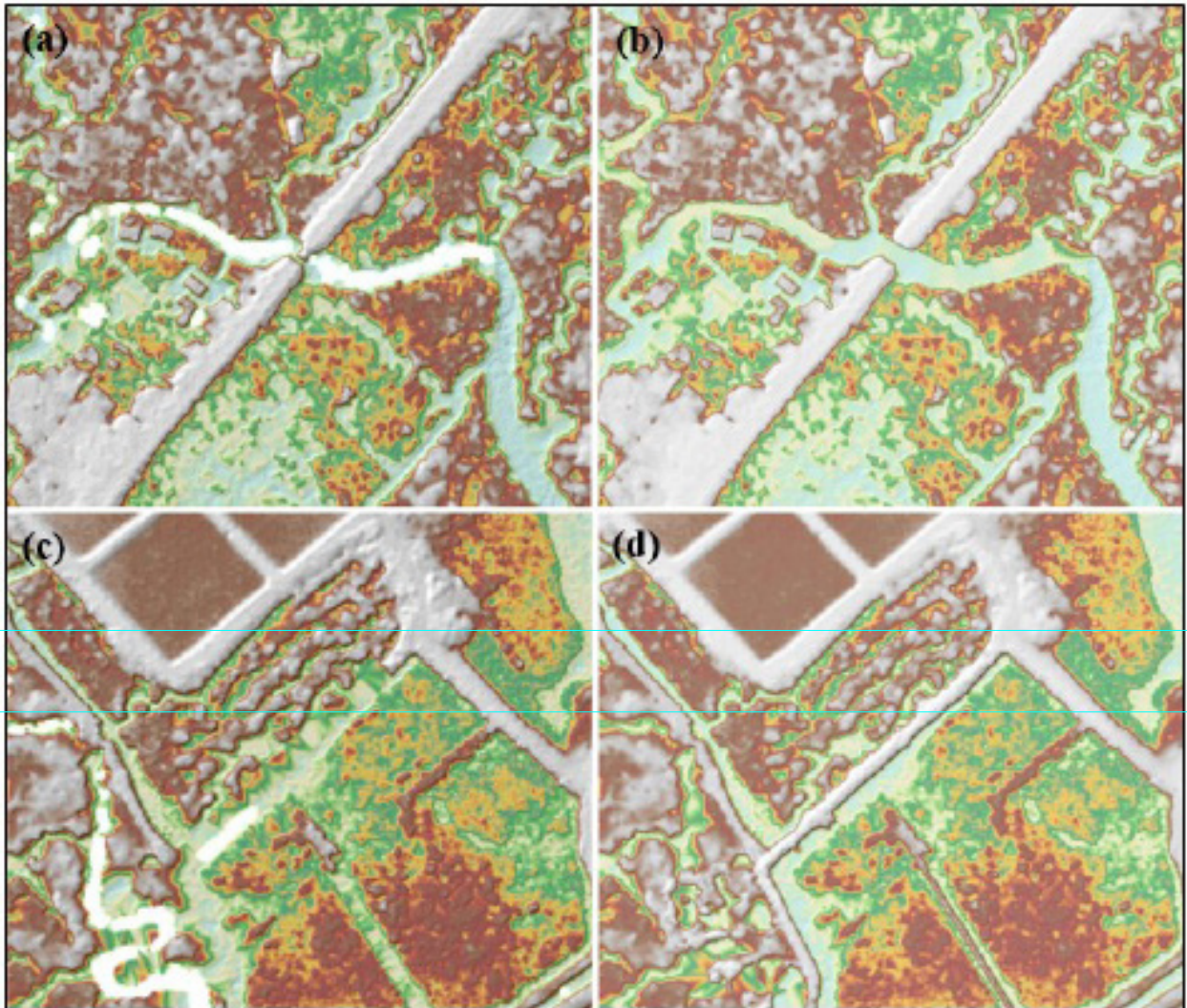


Figure 21. Figure 21. Portions in the DTM of the Pagsangahan floodplain – a bridge and other obstructions on the river (a) before and (b) after manual editing; a paddy field embankment (c) before and (d) after manual editing

### 3.9 Mosaicking of Blocks

The Samar\_Leyte\_Bl35I block was used as the reference block at the start of mosaicking, because this was the first available block for processing in the floodplain. Table 24 summarizes the shift values applied to each LiDAR block during the mosaicking process.

The mosaicked LiDAR DTM for the Pagsangahan floodplain is exhibited in Figure 22. It demonstrates that the entire Pagsangahan floodplain is 99.92% covered by LiDAR data.

Table 24. Shift values of each LiDAR block of the Pagsangahan floodplain

Mission Blocks	Shift Values (meters)		
	x	y	z
Samar_Leyte_Bl35I	0.00	0.00	0.00
Ormoc_Bl35A	0.00	0.00	-0.30
Ormoc_Bl35B	0.00	0.00	-0.32
Ormoc_Bl35A_supplement	0.00	0.00	-0.18
Ormoc_Bl35A_additional	0.00	1.00	0.00
Samar_Leyte_Bl35H_supplement	0.00	0.00	0.00
Samar_Leyte_Bl35H	0.00	0.00	0.00
Samar_Leyte_Bl35F	1.00	0.00	-0.32
Samar_Leyte_Bl35E	2.00	0.00	-0.32
Samar_Leyte_Bl35D	2.00	1.00	-0.32
Samar_Leyte_Bl35C	2.00	2.00	-0.27
Samar_Leyte_Bl35B	3.00	2.00	-0.27
Ormoc_Bl35F	0.00	0.00	-0.14
Ormoc_Bl35CD_additional	0.00	0.00	-0.69
Samar_Leyte_Bl35I_additional	0.00	0.00	0.00
Samar_Leyte_Bl35A	0.00	0.00	0.00
Ormoc_Camotes_Bl35E	0.00	0.00	0.00
Ormoc_Camotes_Bl35E_supplement	0.00	0.00	0.03
Ormoc_Camotes_Bl35G	0.50	-0.50	0.64
Ormoc_Camotes_Bl35F_additional	0.00	0.00	0.15
Ormoc_Camotes_Bl35H_supplement	-1.00	0.50	0.30
Ormoc_Camotes_Bl35H	-2.00	0.50	0.24
Ormoc_Camotes_Bl35E_additional	0.00	0.50	0.00
Ormoc_South_Bl35B	0.00	0.50	-0.55
Ormoc_South_Bl35A	0.00	0.00	-0.79
Ormoc_South_Bl35C	0.00	0.00	-0.60
SamarLeyte_Bl35H_supplement2	0.00	0.00	0.00
Ormoc_Bl35B_additional	0.00	0.00	-0.31
Ormoc_Camotes_Bl35J	0.00	-2.00	-11.23
Tacloban_Bl35A	0.00	0.00	0.00

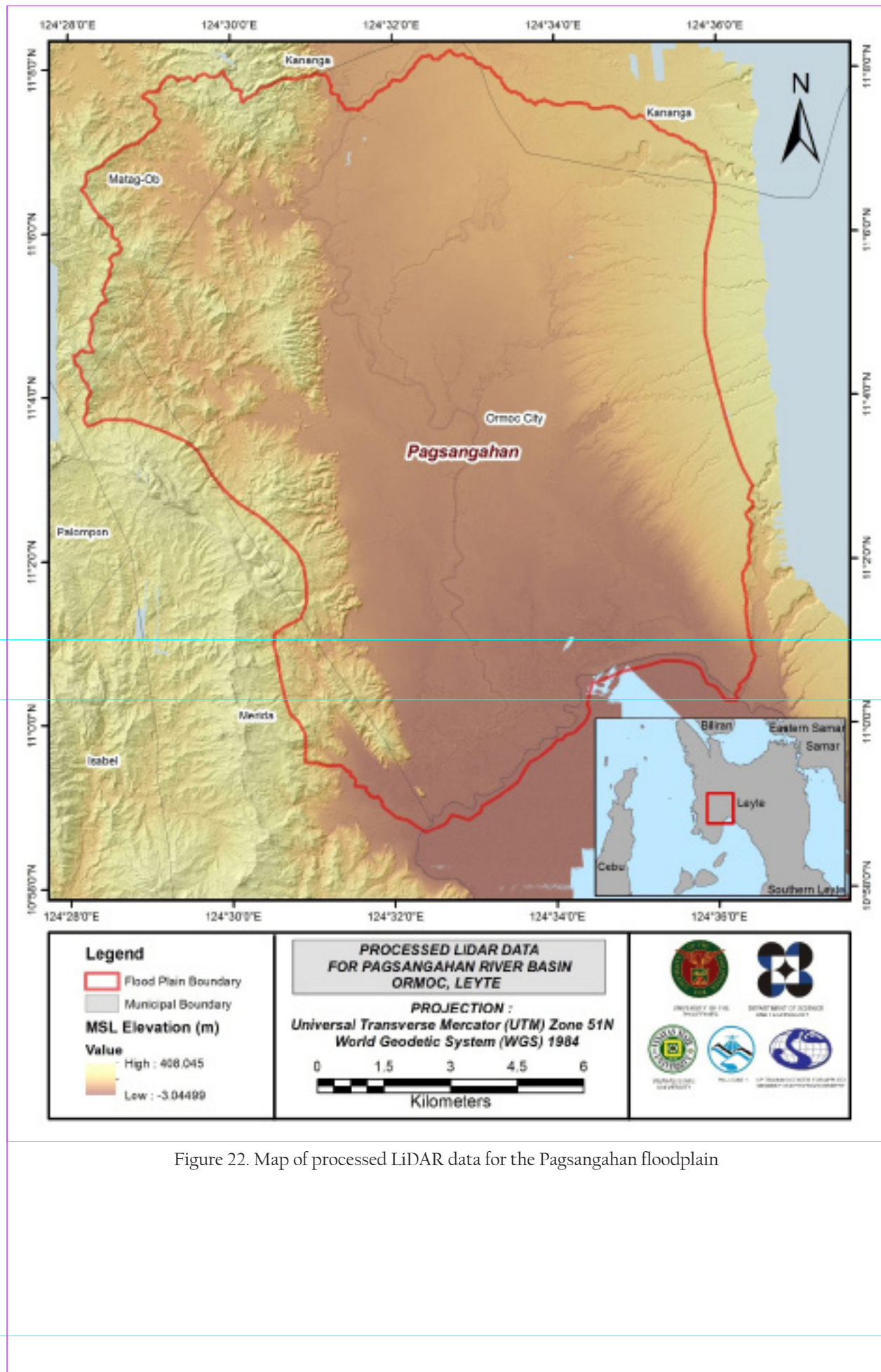


Figure 22. Map of processed LiDAR data for the Pagsangahan floodplain

### 3.10 Calibration and Validation of Mosaicked LiDAR DEM

The extent of the validation survey done by the Data Validation and Bathymetry Component (DVBC) in Ormoc City and Bato Municipality to collect points with which the LiDAR dataset is validated is shown in Figure 23. A total of 25,710 survey points were gathered for all the flood plains within Ormoc City and Bato Municipality wherein the Pagsangahan is located. Random selection of 80% of the survey points, resulting to 20,568 points, were used for calibration.

A good correlation between the uncalibrated mosaicked LiDAR DTM and ground survey elevation values is shown in Figure 24. Statistical values were computed from extracted LiDAR values using the selected points to assess the quality of data and obtain the value for vertical adjustment. The computed height difference between the LiDAR DTM and calibration points is 0.26 meters with a standard deviation of 0.19 meters. Calibration of the LiDAR data was done by adding the height difference value, 0.26 meters, to the mosaicked LiDAR data. Table 25 shows the statistical values of the compared elevation values between the LiDAR data and calibration data.

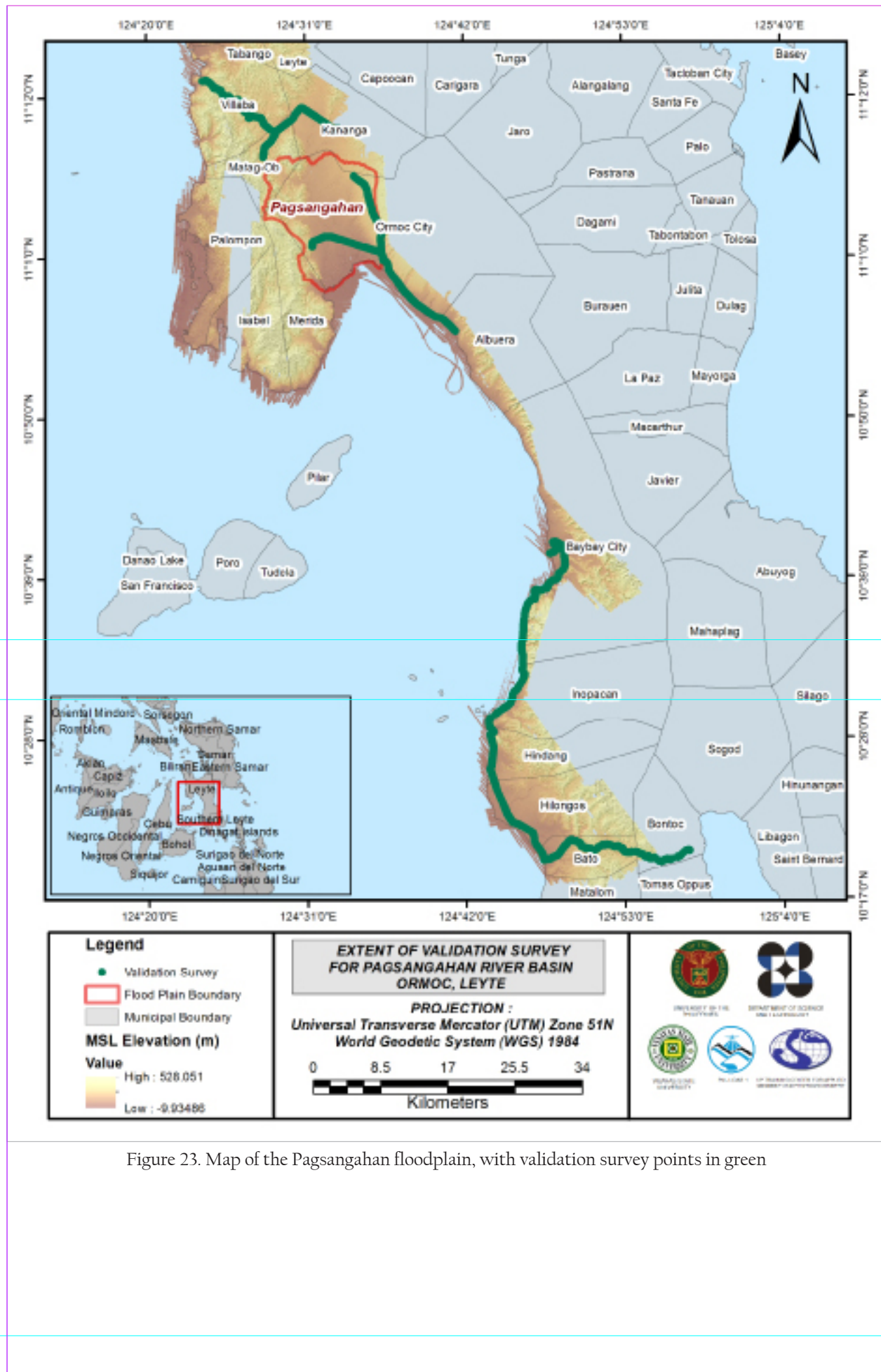


Figure 23. Map of the Pagsangahan floodplain, with validation survey points in green

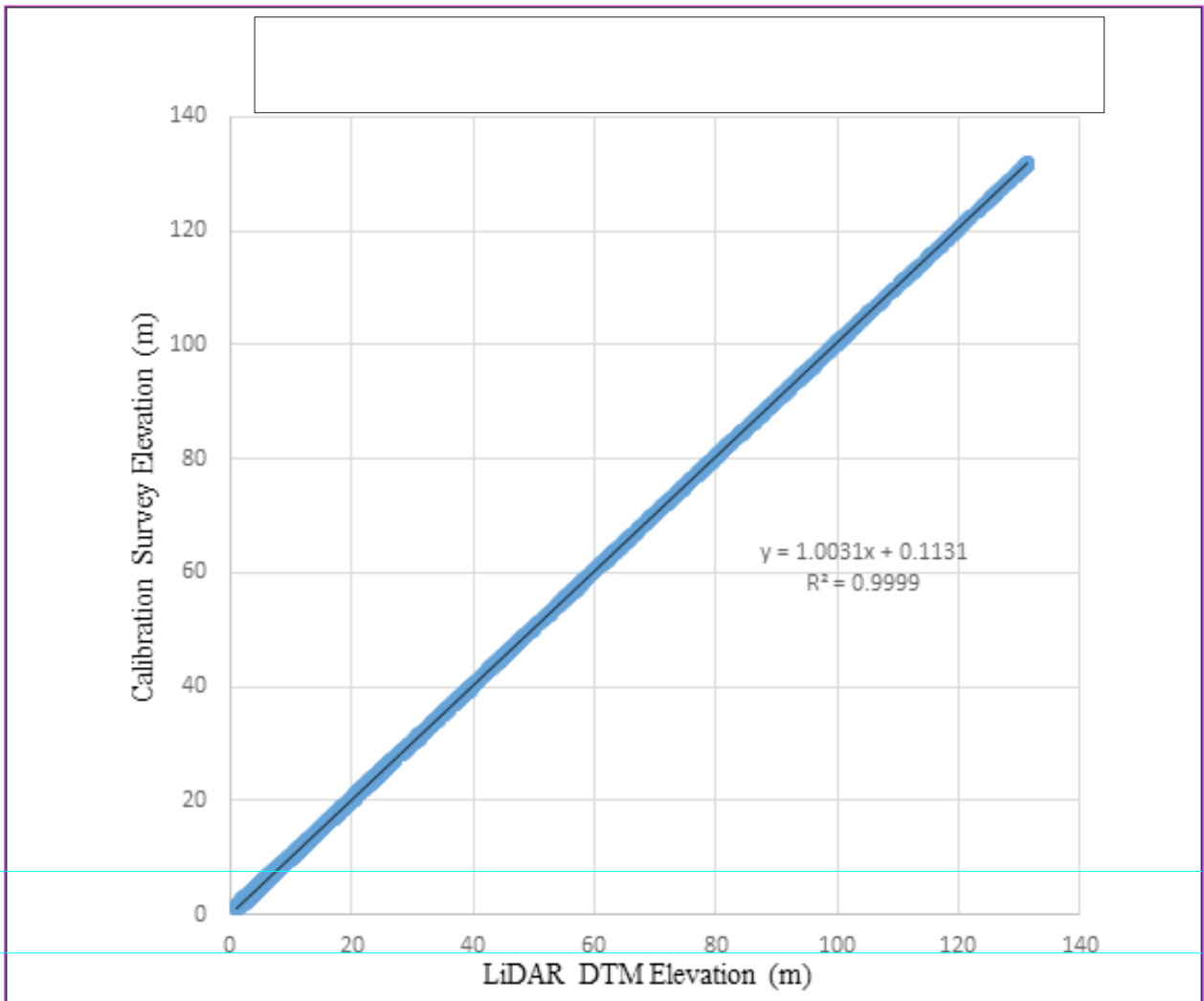


Figure 24. Correlation plot between the calibration survey points and the LiDAR data

Table 25. Calibration statistical measures

Calibration Statistical Measures	Value (meters)
Height Difference	0.26
Standard Deviation	0.19
Average	0.16
Minimum	-0.30
Maximum	0.60

The remaining 20% of the total survey points, resulting in 5,142 points, were used for the validation of calibrated Pagsangahan DTM. A good correlation between the calibrated mosaicked LiDAR elevation values and the ground survey elevation, which reflects the quality of the LiDAR DTM, is demonstrated in Figure 25. The computed RMSE between the calibrated LiDAR DTM and the validation elevation values is 0.20 meters, with a standard deviation of 0.18 meters, as shown in Table 26.

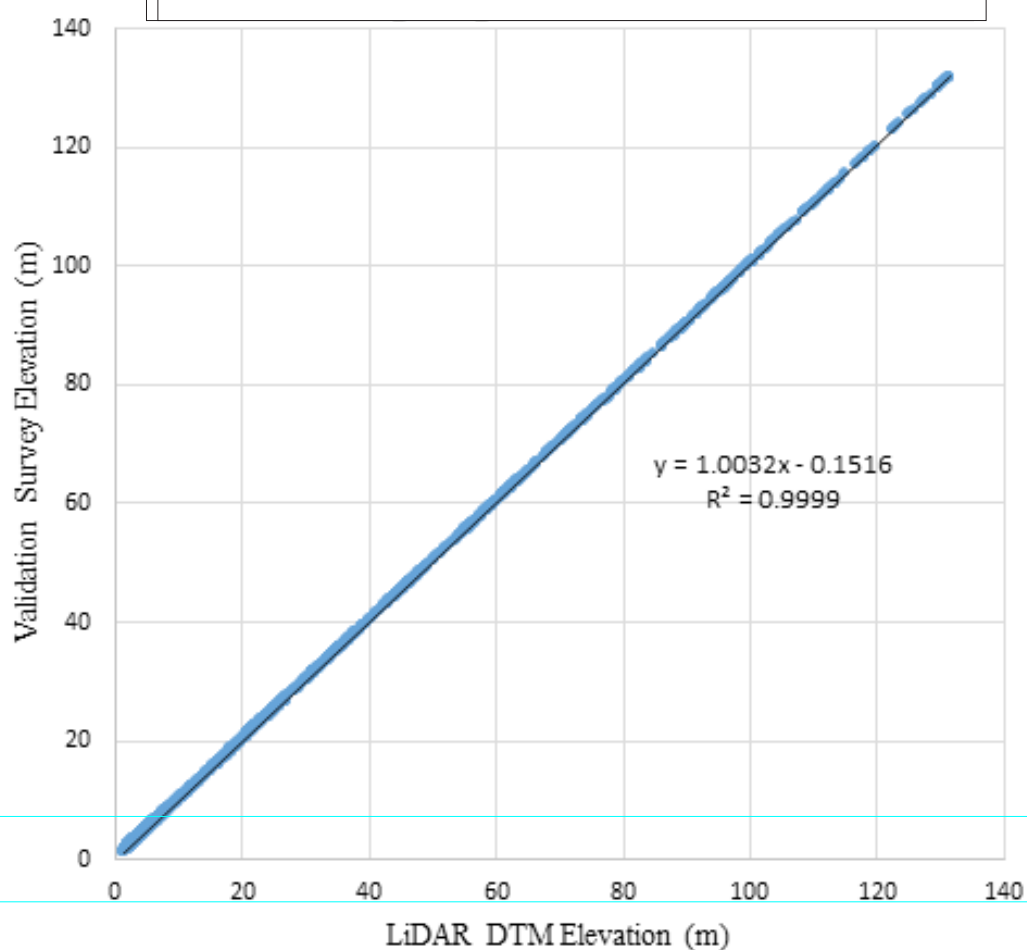


Figure 25. Correlation plot between the validation survey points and the LiDAR data.

Table 26. Validation statistical measures

Calibration Statistical Measures	Value (meters)
RMSE	0.20
Standard Deviation	0.18
Average	-0.10
Minimum	-0.47
Maximum	0.29

### 3.11 Integration of Bathymetric Data into the LiDAR Digital Terrain Model

For bathy integration, only centerline data were available for Pagsangahan, with 4,352 bathymetric survey points. The resulting raster surface produced was obtained through the Kernel Interpolation with Barriers method. After burning the bathymetric data to the calibrated DTM, assessment of the interpolated surface is represented by the computed RMSE value of 0.68 meters. The extent of the bathymetric survey done by the DVBC in the Pagsangahan River, integrated with the processed LiDAR DEM, is illustrated in Figure 26.

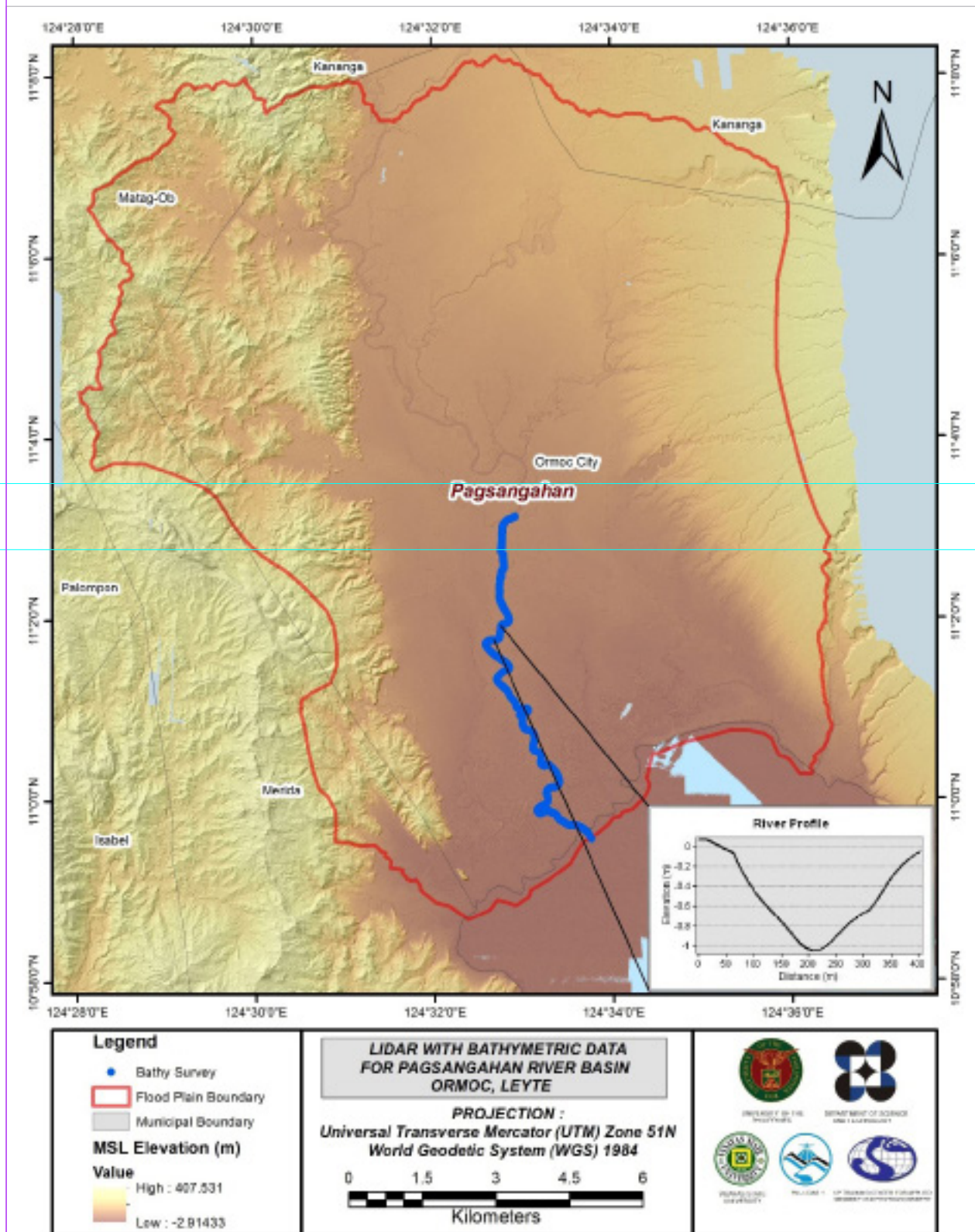


Figure 26. Map of the Pagsangahan floodplain, with bathymetric survey points in blue



### 3.12 Feature Extraction

The features salient in flood hazard exposure analysis include buildings, road networks, bridges, and water bodies within the floodplain area, with a 200-meter buffer zone. Mosaicked LiDAR DEM with a 1-meter resolution was used to delineate footprints of building features, which consist of residential buildings, government offices, medical facilities, religious institutions, and commercial establishments, among others. Road networks – comprised of main thoroughfares, such as highways, and municipal and barangay roads – are essential for routing disaster response efforts. These features are represented by a network of road centerlines.

#### 3.12.1 Quality Checking of Digitized Features' Boundary

The Pagsangahan floodplain, including its 200-meter buffer zone, has a total area of 192.38 sq. km. Of this area, a total of 6.0 sq. km., corresponding to a total of 2,285 building features, was considered for quality checking (QC). Figure 27 exhibits the QC blocks for the Pagsangahan floodplain.

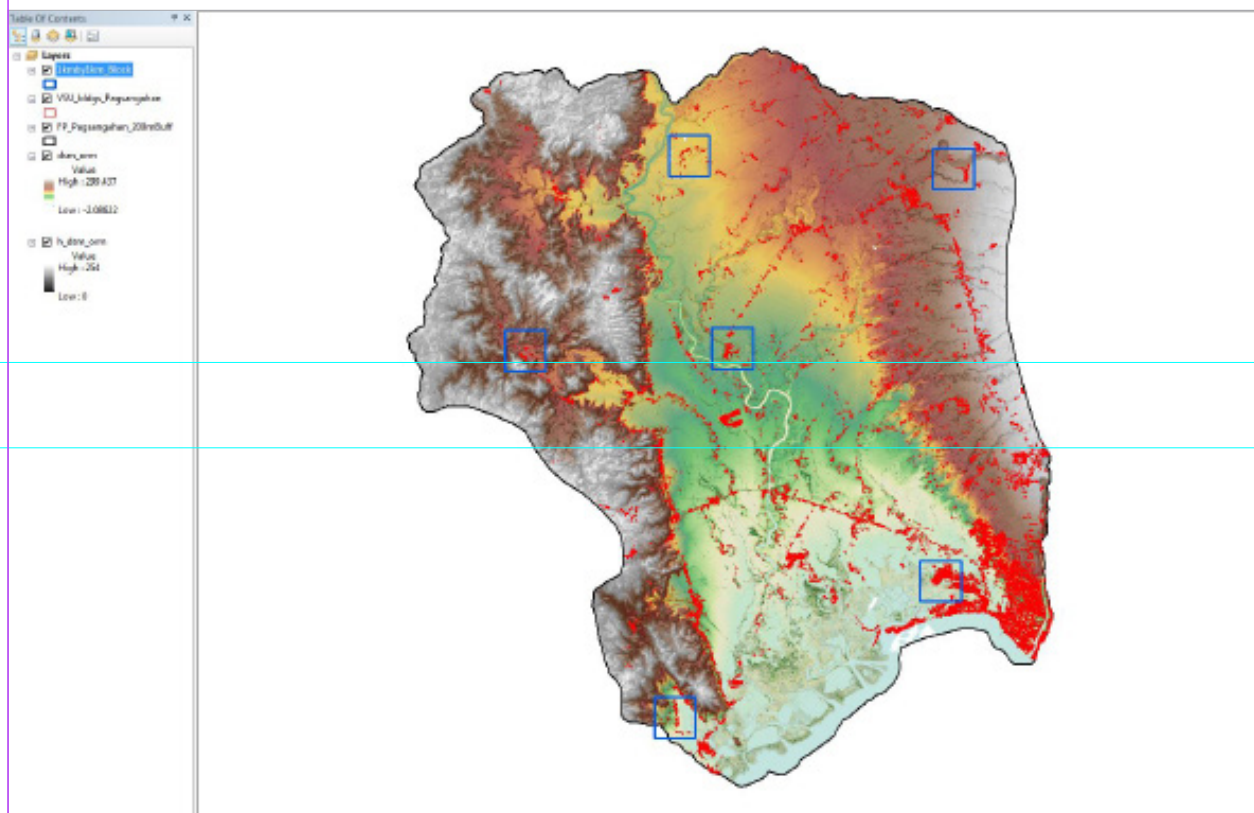


Figure 27. Blocks (in blue) of the Pagsangahan building features that were subjected to QC

Quality checking of the Pagsangahan building features resulted in the ratings presented in Table 27.

Table 27. Quality checking ratings for the Pagsangahan building features

Floodplain	Completeness	Correctness	Quality	Remarks
Pagsangahan	99.82	100.00	99.59	PASSED

### 3.12.2 Height Extraction

Height extraction was performed for 31,264 building features in the Pagsangahan floodplain. Of these building features, 147 were filtered out after height extraction, resulting in 31,117 buildings with height attributes. The lowest building height is at 2.00 meters, while the highest building is at 6.73 meters.

### 3.12.3 Feature Attribution

The digitized features were marked and coded in the field using handheld GPS receivers. The attributes of non-residential buildings were first identified; and then all other buildings were coded as residential. A normalized DSM was generated using the LiDAR DEMs to extract the heights of the buildings. A minimum height of 2 meters was used to filter out the terrain features that were digitized as buildings. Buildings that were not yet constructed during the time of LiDAR acquisition were noted as new buildings in the attribute table.

Table 28 summarizes the number of building features per type. Table 29 presents the total length of each road type, and Table 30 lists the number of water features extracted per type.

Table 28. Building features extracted for the Pagsangahan floodplain

Facility Type	No. of Features
Residential	29,464
School	656
Market	80
Agricultural/Agro-Industrial Facilities	51
Medical Institutions	40
Barangay Hall	52
Military Institution	0
Sports Center/Gymnasium/Covered Court	35
Telecommunication Facilities	1
Transport Terminal	7
Warehouse	154
Power Plant/Substation	6
NGO/CSO Offices	13
Police Station	4
Water Supply/Sewerage	17
Religious Institutions	144
Bank	5
Factory	23
Gas Station	24
Fire Station	1
Other Government Offices	99
Other Commercial Establishments	217
New Buildings	14
Abandoned Buildings	10
<b>Total</b>	<b>31,117</b>

Table 29. Total length of extracted roads for the Pagsangahan floodplain

Floodplain	Road Network Length (km)					Total
	Barangay Road	City/Municipal Road	Provincial Road	National Road	Others	
Pagsangahan	245.53	12.93	0.00	37.71	0.00	<b>296.17</b>

Table 30. Number of extracted water bodies for the Pagsangahan floodplain

Floodplain	Water Body Type					Total
	Rivers/Streams	Lakes/Ponds	Sea	Dam	Fish Pen	
Pagsangahan	55	91	0	1	0	<b>147</b>

A total of sixty-one (61) bridges and culverts over small channels that are part of the river network were also extracted for the floodplain.

### 3.12.4 Final Quality Checking of Extracted Features

All extracted ground features were completely given the required attributes. All these output features comprise the flood hazard exposure database for the Pagsangahan floodplain. This completes the feature extraction phase of the project.

Figure 28 represents the Digital Surface Model (DSM) of the Pagsangahan floodplain, overlaid with its ground features.

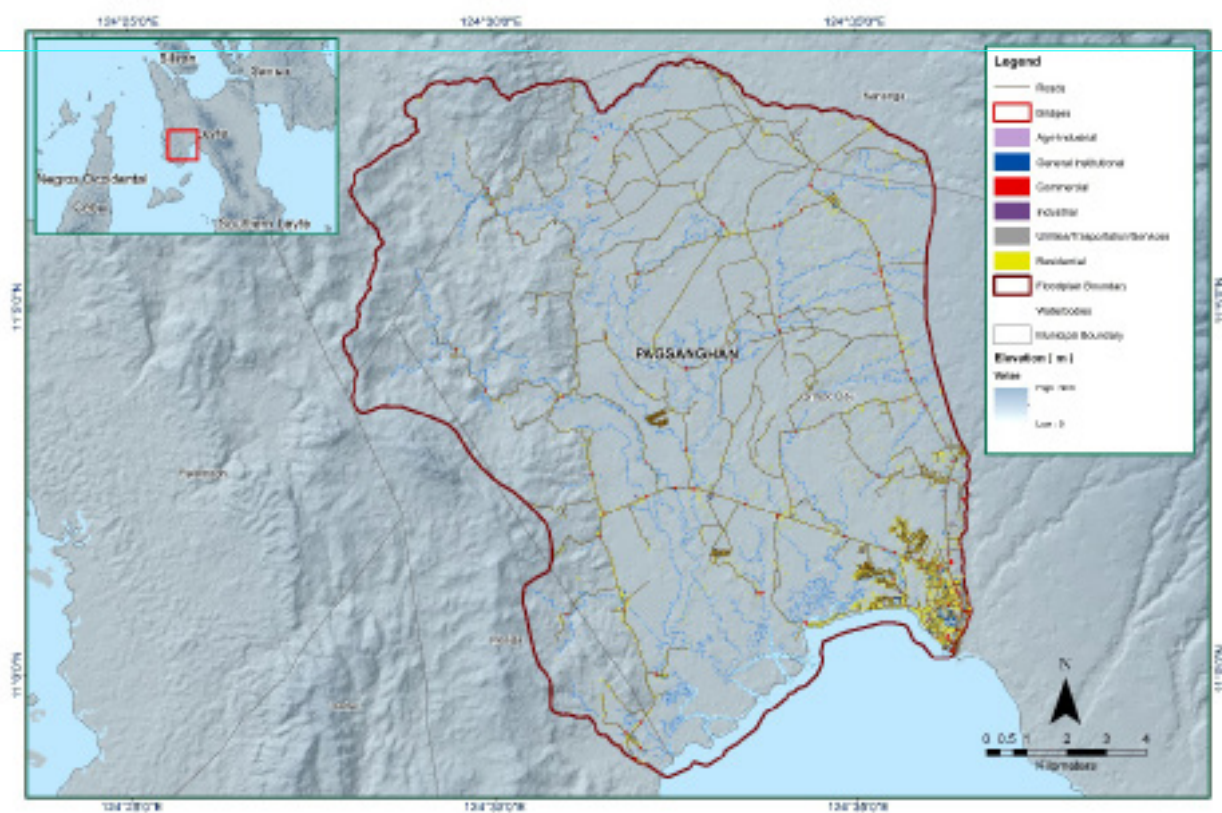


Figure 28. Extracted features for the Pagsangahan floodplain

## **CHAPTER 4: LIDAR VALIDATION SURVEY AND MEASUREMENTS OF THE PANGSANGAHAN RIVER BASIN**

*Engr. Louie P. Balicanta, Engr. Joemarie S. Caballero, Patrizia Mae. P. dela Cruz,  
and Engr. Dexter T. Lozano*

The methods applied in this Chapter were based on the DREAM methods manual (Balicanta, et al., 2014) and further enhanced and updated in Paringit, et al. (2017).

### **4.1 Summary of Activities**

The DVBC conducted field surveys in the Pagsangahan River on January 6-20, 2015, and on September 10-24, 2014, with the following scope of work: (i.) initial reconnaissance; (ii.) control survey for the establishment of a control point; (iii.) bridge as-built cross-section; (iv.) water level marking in MSL of the Pagsangahan Bridge in Ormoc City, Leyte; (v.) Aquarius LiDAR Validation of about 15.4 km; and (vi.) bathymetric survey from Barangay Liloan down to the mouth of the river in Barangay Lao, with an estimated length of 9.45 km., using an OHMEX™ Single Beam Echo Sounder and GNSS PPK survey technique. The extent of the survey is shown by the map in Figure 29.

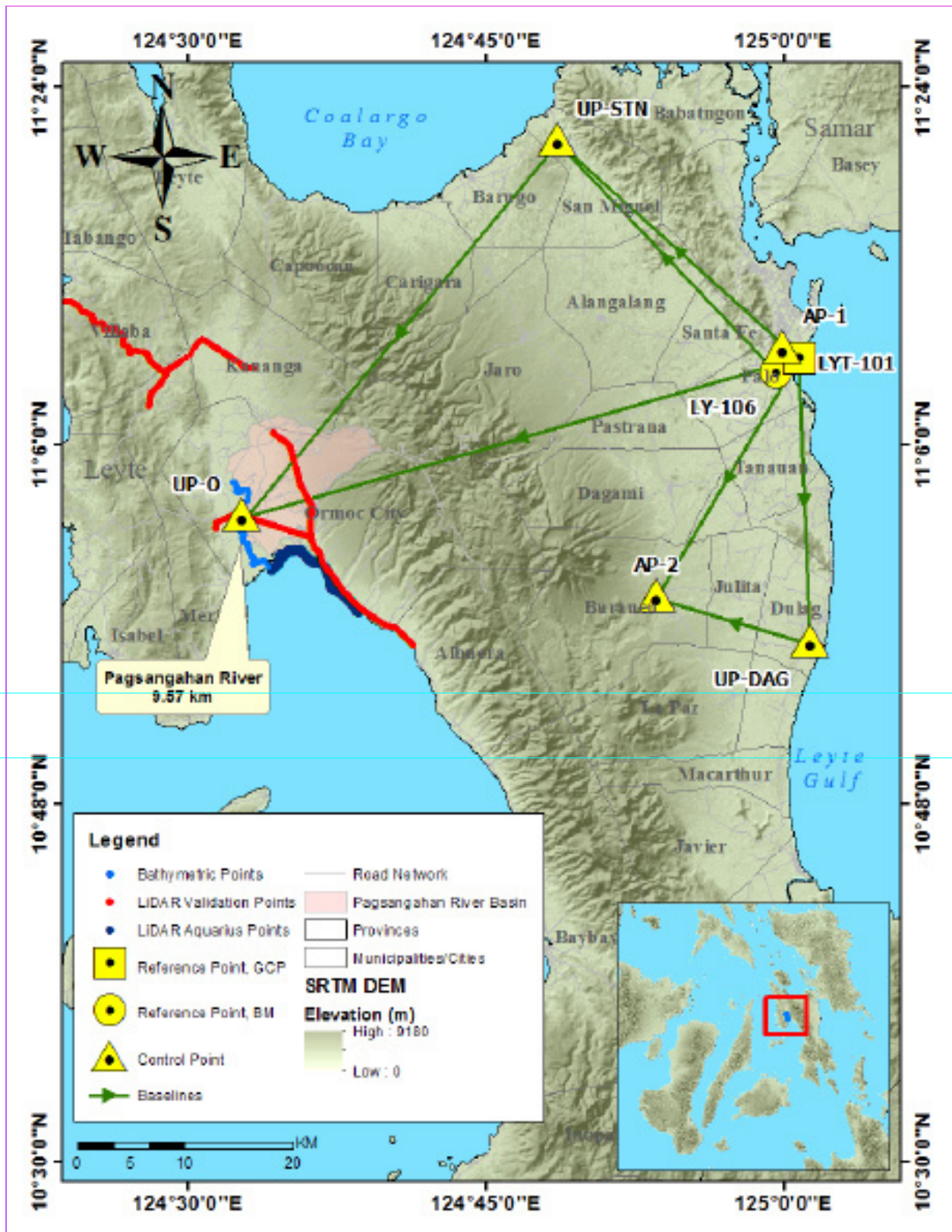


Figure 29. Extent of the bathymetric survey (in blue line) in the Pagsangahan River and the LiDAR data validation survey (in red)

## 4.2 Control Survey

The GNSS network used for the Pagsangahan River Basin is composed of three (3) loops established on September 18-20, 2014, occupying the following reference points: (i.) LYT-101, a second-order GCP, located in Barangay Candahog, Municipality of Palo; and (ii.) LY-106, a second-order GCP, located in Barangay Luntad, Municipality of Palo.

Three (3) control points were established at the approach of bridges, namely: (i.) UP-DAG at the Daguitan Bridge in Barangay Fatima, Municipality of Dulag; (ii.) UP-O at the Ormoc Merida Bridge in Barangay Liloan, Ormoc City; and (iii.) UP-STN at the Calay-calay Bridge in Barangay Caraycaray, Municipality of San Miguel. Two (2) arbitrary points were also observed to complete the network, AP1 and AP2. The former is located at the corner of the Maharlika Highway and an unnamed street going to Campetic Road in Barangay Campetik, Municipality of Palo, and the latter is located inside the Burauen Church Plaza on the Julita Burauen Road corner Burauen – Dagami Road, in Barangay Poblacion VII, Municipality of Burauen, Province of Leyte.

The summary of reference and control points and their respective locations is provided in , while the GNSS network established is illustrated in .

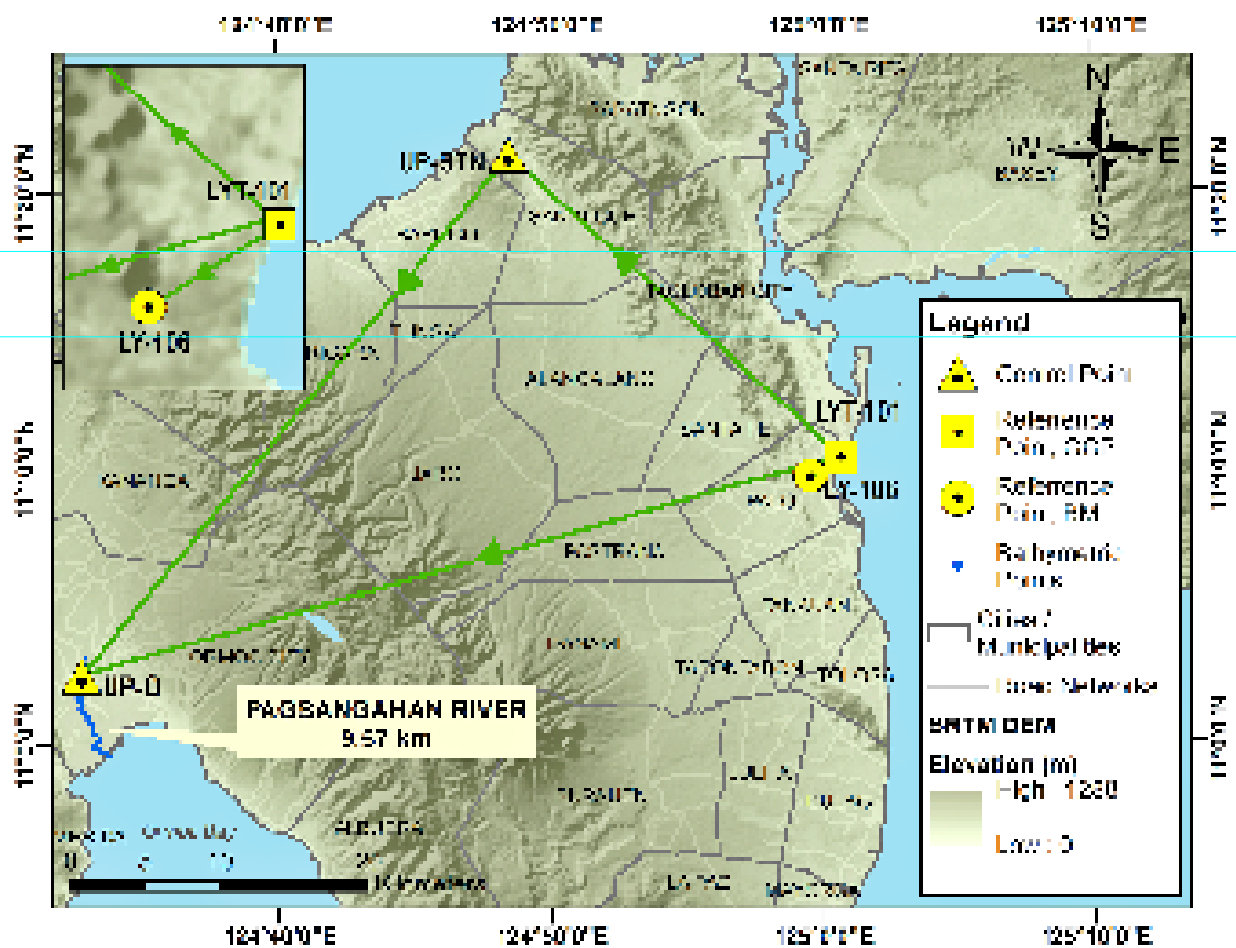


Figure 30. GNSS network for the Pagsangahan River field survey

Table 31. Table 31. List of reference and control points used in the Pagsangahan Survey on January 8, 2015  
(Source: NAMRIA and UP-TCAGP)

Control Point	Order of Accuracy	Geographic Coordinates (WGS UTM Zone 52N)				
		Latitude	Longitude	Ellipsoid Height (m)	Elevation (MSL) (m)	Date of Establishment
LYT-101	2 <sup>nd</sup> order, GCP	11°10'19.64869" N	125°00'43.78230" E	69.228	-	09-20-2014
LY-106	1 <sup>st</sup> order, BM	-	-	68.051	4.028	2007
UP-DAG	UP Established	-	-	-	-	09-20-2014
UP-O	UP Established	-	-	-	-	09-19-2014
UP-STN	UP Established	-	-	-	-	09-11-2014
AP1	Arbitrary	-	-	-	-	09-18-2014
AP2	Arbitrary	-	-	-	-	09-20-2014

The GNSS set-ups established in the locations of the reference and control points are exhibited in Figure 31 to 35.



Figure 31. GNSS base set-up, Trimble® SPS 852, at LYT-101, located at the General McArthur Shrine in Barangay. Candahog, Municipality of Palo, Leyte



Figure 32. GNSS base set-up, Trimble® SPS 985, at LY-106, located at the approach of the Bernard Reed Bridge along Maharlika Highway, Barangay Luntad, Municipality of Palo, Leyte



Figure 33. GNSS receiver set-up, Trimble® SPS 985, at UP DAG, an established control point, located at the bridge approach of the Daguitan Bridge along Maharlika Highway in Barangay Fatima, Municipality of Dulag, Leyte





Figure 34. GNSS receiver set-up, Trimble® SPS 985, at UP-O, an established control point, located at the bridge approach of the Ormoc Merida Bridge along Ormoc-Merida-Isabel-Palompon Road in Barangay Liloan, City of Ormoc, Leyte



Figure 35. GNSS base set-up, Trimble® SPS 852, at UP-STN, an established control point, located at the Pagbanganan Bridge approach in Barangay Poblacion Zone 12, City of Baybay, Leyte

### 4.3 Baseline Processing

The GNSS baselines were processed simultaneously in TBC by observing that all baselines have fixed solutions, with horizontal and vertical precisions within +/- 20 cm and +/- 10 cm requirement, respectively. In cases where one or more baselines did not meet all of these criteria, masking was performed. Masking is the removal of these baseline data using the same processing software. It is repeatedly processed until all baseline requirements are met. If the reiteration yields out of the required accuracy, a re-survey is initiated. The baseline processing results of the control points in the Pagsangahan River Basin, generated by the TBC software, are summarized in

Table 32. Baseline Processing Report for the Pagsangahan River Basin static survey

Observation	Date of Observation	Solution Type	H. Prec. (Meter)	V. Prec. (Meter)	Geodetic Az.	Ellipsoid Dist. (Meter)
UP-STN --- UP-O (B2)	09-19-2014	Fixed	0.003	0.013	219°39'13"	45132.753
LY-106 --- AP1 (B4)	09-18-2014	Fixed	0.003	0.012	12°44'49"	2489.516
LY-106 --- UP-STN (B11)	09-18-2014	Fixed	0.005	0.042	317°02'38"	29477.609
LYT-101 --- UP-O (B1)	09-19-2014	Fixed	0.005	0.013	254°12'03"	52970.388
LYT-101 --- AP1 (B6)	09-18-2014	Fixed	0.002	0.003	307°32'43"	1903.266
LYT-101 --- UP-STN (B10)	09-18-2014	Fixed	0.005	0.039	312°31'18"	30045.665
LYT-101 --- UP-STN (B3)	09-18-2014	Fixed	0.003	0.011	312°31'18"	30045.649
LYT-101 --- LY-106 (B7)	09-20-2014	Fixed	0.003	0.016	238°21'43"	2417.850
LYT-101 --- LY-106 (B5)	09-20-2014	Fixed	0.002	0.004	238°21'42"	2417.858
LYT-101 --- UPDAG (B13)	09-20-2014	Fixed	0.004	0.011	177°43'46"	26154.013
LYT-101 --- AP2 (B12)	09-20-2014	Fixed	0.003	0.012	210°46'11"	25458.032
UP-DAG --- AP2 (B14)	09-20-2014	Fixed	0.004	0.014	286°51'16"	14691.113

As reflected in a total of twelve (12) baselines were processed, with reference points LYT-101 and LY-106 held fixed for grid values and elevation values, respectively. All of the baselines satisfied the required accuracy.

### 4.4 Network Adjustment

After the baseline processing procedure, network adjustment was performed using TBC. Looking at the adjusted grid coordinates table of the TBC-generated Network Adjustment Report, it is observed that the square root of the sum of the squares of  $x$  and  $y$  must be less than 20 cm, and  $z$  less than 10 cm, or in equation form:

$$\sqrt{(x_e)^2 + (y_e)^2} < 20 \text{ cm and } z_e < 10 \text{ cm}$$

Where:

- $x_e$  is the Easting Error,
- $y_e$  is the Northing Error, and
- $z_e$  is the Elevation Error

for each control point. See the Network Adjustment Report shown in [ ] to [ ] for the complete details.

The seven (7) control points – LYT-101, LY-106, UP-DAG, UP-O, UP-STN, and two (2) arbitrary points – were occupied and observed simultaneously to form a GNSS loop. The coordinates of point LYT-101 and the elevation value of LY-106 were held fixed during the processing of the control points, as presented in [ ] .

Through these reference points, the coordinates and elevation values of the unknown control points were computed.

Table 33. Constraints applied to the adjustments of the control points

Point ID	Type	North (Meter)	East (Meter)	Height (Meter)	Elevation (Meter)
LYT-101	Local	Fixed	Fixed		
LY-106	Grid				Fixed
Fixed = 0.000001(Meter)					

The list of adjusted grid coordinates; i.e., Northing, Easting, Elevation, and computed standard errors of the control points in the network, is indicated in . The fixed control points, LYT-101 and LY-106, have no values for grid errors and for elevation errors, respectively.

Table 34. Adjusted grid coordinates for the control points used in the Pagsangahan floodplain survey

Point ID	Easting (Meter)	Easting Error (Meter)	Northing (Meter)	Northing Error (Meter)	Elevation (Meter)	Elevation Error (Meter)	Constraint
LYT-101	1235759.250	?	719729.823	?	5.141	0.040	LL
LY-106	1234476.732	0.007	717679.601	0.006	4.028	?	e
UP-DAG	1209628.100	0.013	720942.270	0.009	5.993	0.077	e
UP-O	1220991.402	0.014	668855.819	0.010	8.719	0.076	
UP-STN	1255916.567	0.009	697443.625	0.007	8.835	0.070	
AP1	1236908.994	0.007	718212.616	0.007	4.834	0.051	
AP2	1213793.946	0.012	706851.618	0.010	56.317	0.079	

The network is was fixed at reference points LYT-101 with known coordinates, and LY-106 with known elevation. With the mentioned equation,  $\sqrt{(x_e)^2 + (y_e)^2} < 20 \text{ cm}$  for horizontal accuracy and  $z_e < 10 \text{ cm}$  for the vertical accuracy,, the computations for the accuracy are as follows:

**a. LYT-101**

Horizontal Accuracy = Fixed  
 Vertical Accuracy = 4.0 cm < 10 cm

**b. LY-106**

Horizontal Accuracy =  $\sqrt{(1.30)^2 + (0.6^2)}$   
 =  $\sqrt{0.49 + 0.36}$   
 = 0.92 cm < 20 cm  
 Vertical Accuracy = Fixed

**c. UP-DAG**

Horizontal Accuracy =  $\sqrt{(1.3)^2 + (0.90)^2}$   
 =  $\sqrt{1.69 + 0.81}$   
 = 1.58 cm < 20 cm  
 Vertical Accuracy = 7.70 cm < 10 cm

**d. UP-O**

Horizontal Accuracy =  $\sqrt{(1.40)^2 + (1.10)^2}$   
 =  $\sqrt{1.96 + 1.21}$   
 = 1.78 cm < 20 cm  
 Vertical Accuracy = 7.60 cm < 10 cm

**e. UP-STN**

Horizontal Accuracy =  $\sqrt{(0.90)^2 + (0.70)^2}$   
 =  $\sqrt{0.81 + 0.49}$   
 = 1.14 cm < 20 cm  
 Vertical Accuracy = 7.0 cm < 10 cm

**f. AP1**

Horizontal Accuracy =  $\sqrt{(0.70)^2 + (0.70)^2}$   
 =  $\sqrt{0.49 + 0.49}$   
 = 0.98 cm < 20 cm  
 Vertical Accuracy = 5.10 cm < 10 cm

**g. AP2**

Horizontal Accuracy =  $\sqrt{(1.20)^2 + (1.0)^2}$   
 =  $\sqrt{1.44 + 1.0}$   
 = 1.56 cm < 20 cm  
 Vertical Accuracy = 7.9 cm < 10 cm

Following the given formula, the horizontal and vertical accuracy results of the two (2) occupied control points are within the required precision.

Table 35. Table 35. Adjusted geodetic coordinates for control points used in the Pagsangahan River floodplain validation

Point ID	Latitude	Longitude	Height (Meter)	Height Error (Meter)	Constraint
LY-106	N11°09'38.36982"	E124°59'35.93684"	68.051	?	e
UP-DAG	N10°56'09.12671"	E125°01'17.90763"	70.609	0.077	
UP-O	N11°02'28.97646"	E124°32'44.58922"	71.626	0.076	
UP-STN	N11°21'20.28504"	E124°48'33.44650"	71.793	0.070	
AP1	N11°10'57.39411"	E124°59'54.04241"	68.821	0.051	
AP2	N10°58'27.65859"	E124°53'34.80074"	120.385	0.079	

The corresponding geodetic coordinates of the observed points are within the required accuracy, as shown in . Based on the results of the computation, the accuracy conditions are satisfied; hence, the required accuracy for the program was met.

The computed coordinates of the reference and control points utilized in the Pagsangahan River GNSS Static Survey are indicated in .

Table 36. Reference and control points used in the Pagsangahan River Static Survey, with their corresponding locations (Source: NAMRIA, UP-TCAGP)

Control Point	Order of Accuracy	Geographic Coordinates (WGS 84)			UTM ZONE 51 N		
		Latitude	Longitude	Ellipsoid Height (m)	Northing (m)	Easting (m)	BM Ortho (m)
LYT-101	2 <sup>nd</sup> Order, GCP	11°10'19.64869"	125°00'43.78230"	69.228	1235759.250	719729.823	5.141
LY-106	1 <sup>st</sup> order, BM	11°09'38.36982"	124°59'35.93684"	68.051	1234476.732	717679.601	4.028
UP-DAG	UP Established	10°56'09.12671"	125°01'17.90763"	70.609	1209628.100	720942.270	5.993
UP-O	UP Established	11°02'28.97646"	124°32'44.58922"	71.626	1220991.402	668855.819	8.719
UP-STN	UP Established	11°21'20.28504"	124°48'33.44650"	71.793	1255916.567	697443.625	8.835
AP1	Arbitrary Point	11°10'57.39411"	124°59'54.04241"	68.821	1236908.994	718212.616	4.834
AP2	Arbitrary Point	10°58'27.65859"	124°53'34.80074"	120.385	1213793.946	706851.618	56.317

#### 4.5 Cross-section and Bridge As-Built Survey and Water Level Marking

The cross-section and bridge as-built surveys were performed on September 17, 2014 along the upstream side of the Ormoc-Merida (Pagsangahan) Bridge in Ormoc City, Leyte. The survey was conducted with the application of PPK technique using a survey-grade GPS, Trimble® SPS 882, as exhibited in .



Figure 36. (a) Acquisition of water surface elevation (b) cross Section survey using Trimble® SPS 882 at Pagsangahan Bridge in City of Ormoc and (c) water level marking of bridge pier for Pagsangahan River

The length of the cross-sectional line surveyed in the Pagsangahan Bridge is about 150 meters with a total of twenty-six (26) points acquired, using UP-O as the GNSS base station. The location map, cross-section diagram, and bridge as-built form are presented in to .

The water surface elevation in MSL of the Pagsangahan River was determined using Trimble® SPS 882 in PPK mode technique on September 17, 2014 at 17:15 hrs., with a value of 1.21 m in MSL (see ). This was translated into markings on one of the bridge’s piers using digital levels, which were used by the VSU PHIL-LiDAR 1 Team as their reference for flow data gathering and depth gauge deployment for the Pagsangahan River (Figure 36).

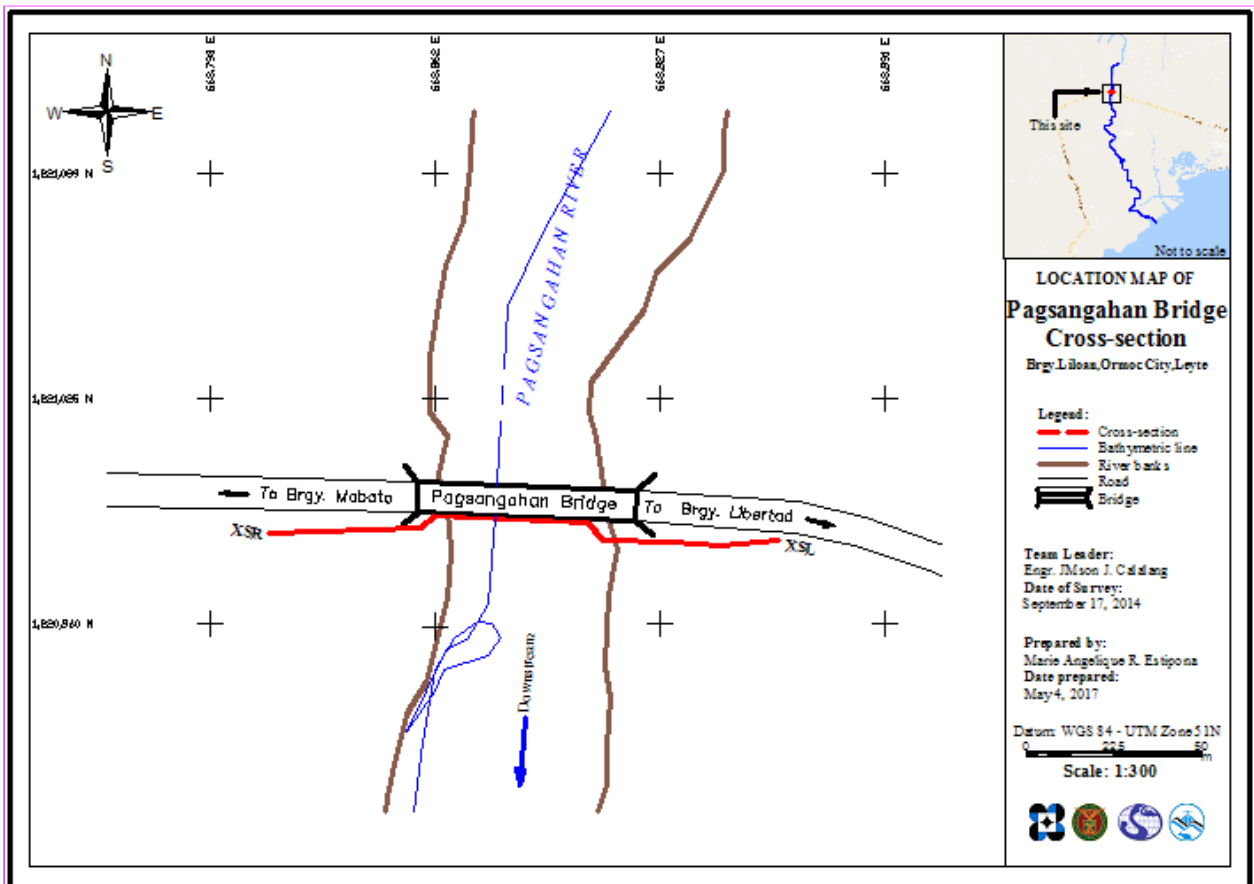


Figure 37. Pagsangahan Bridge cross-section location map

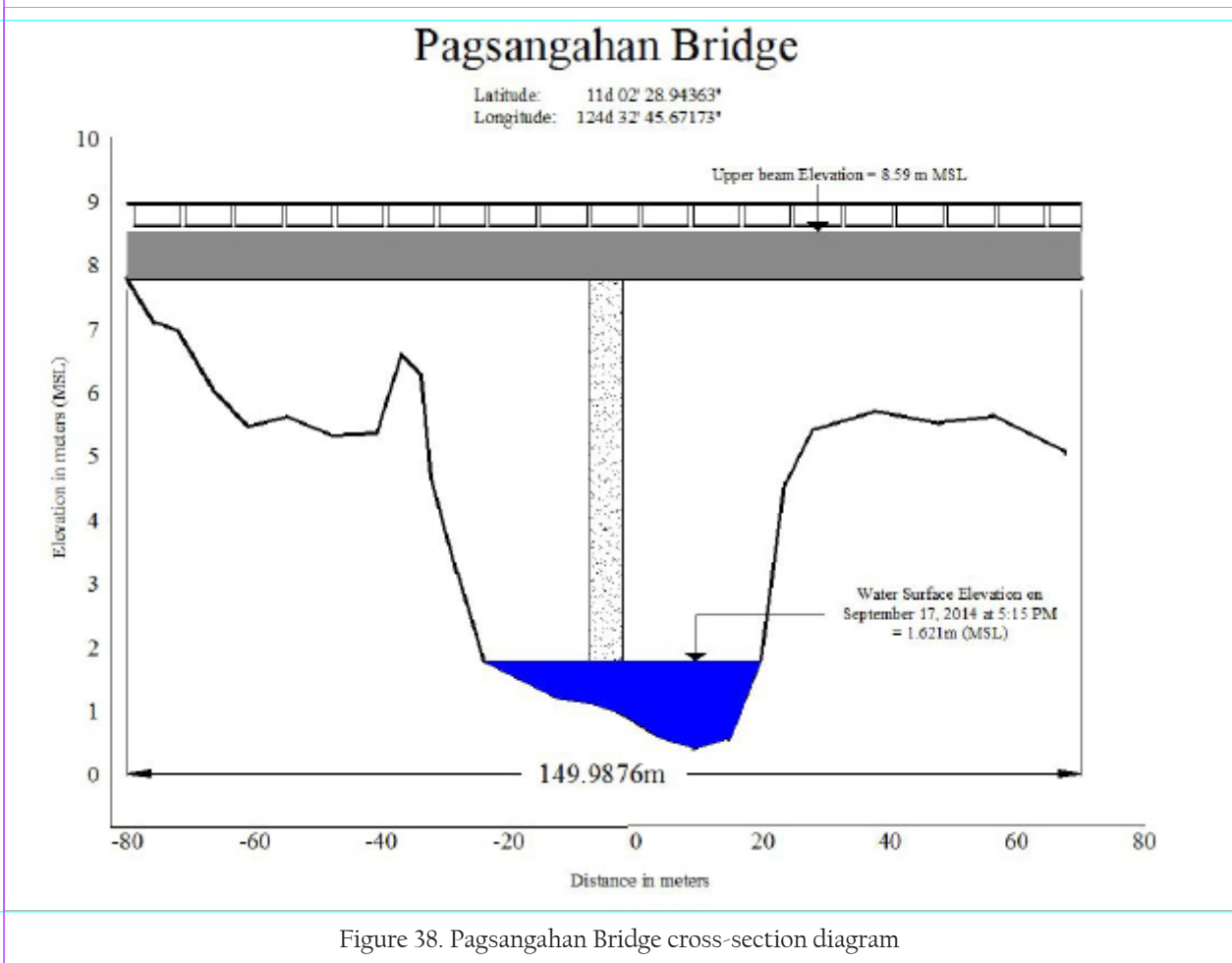
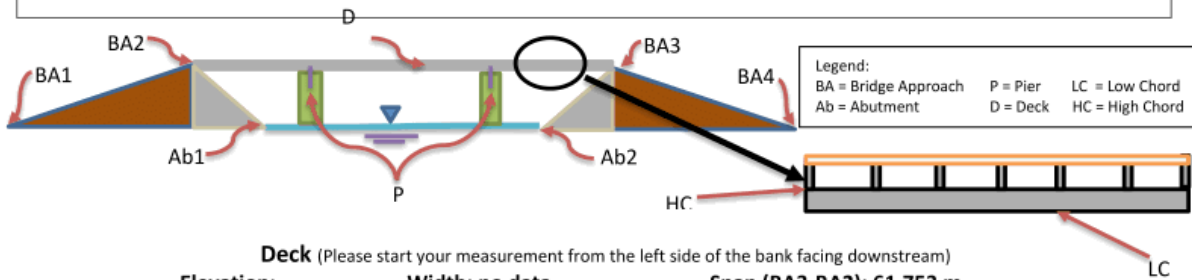


Figure 38. Pagsangahan Bridge cross-section diagram

**Bridge Data Form**

<b>Bridge Name:</b> <u>Pagsangahan Bridge</u>	<b>Date:</b> <u>September 17, 2014</u>
<b>River Name:</b> <u>PAGSANGAHAN RIVER</u>	<b>Time:</b> <u>5:15 pm</u>
<b>Location (Brgy, City, Region):</b> <u>Ormoc, Leyte</u>	
<b>Survey Team:</b> <u>Team JMson Calalang</u>	
<b>Flow condition:</b> low <u>normal</u> high	<b>Weather Condition:</b> <u>fair</u> rainy
<b>Latitude:</b> <u>11°02'28.94363"N</u>	<b>Longitude:</b> <u>124°32'45.67173" E</u>



**Deck** (Please start your measurement from the left side of the bank facing downstream)  
**Elevation:**                      **Width:** no data                      **Span (BA3-BA2):** 61.753 m

	Station	High Chord Elevation	Low Chord Elevation
1	9.568	8.350	7.15
2	26.054	8.333	7.133
3	40.982	8.388	7.188
4	53.801	8.338	7.138
5	72.378	8.288	7.088

**Bridge Approach** (Please start your measurement from the left side of the bank facing downstream)

	Station(Distance from BA1)	Elevation		Station(Distance from BA1)	Elevation
<b>BA1</b>	0	8.12	<b>BA3</b>	72.37	8.49
<b>BA2</b>	9.568	8.35	<b>BA4</b>	81.297	8.29

**Abutment:** Is the abutment sloping?      Yes      No;      If yes, fill in the following information:

	Station (Distance from BA1)	Elevation
<b>Ab1</b>	15.430	5.08
<b>Ab2</b>	72.378	4.87

**Pier** (Please start your measurement from the left side of the bank facing downstream)

**Shape:**Rectangular                      **Number of Piers:** one (1)                      **Height of column footing:** n/a

	Station (Distance from BA1)	Elevation	Pier Width
<b>Pier 1</b>	40.982	1.891	1.270

NOTE: Use the center of the pier as reference to its station

Figure 39. Pagsangahan Bridge as-built survey data form

#### 4.6 Validation Points Acquisition Survey

The validation points acquisition survey was conducted on September 23, 2014. As depicted in , a Trimble® SPS 882 was attached to the side of a vehicle to measure points, utilizing Continuous Topography Method in PPK Survey Technique. The height of the instrument was measured and noted at 2.404 meters, measured from the ground up to the bottom of the notch. Points were gathered along major concrete roads with the aid of a vehicle that moved at a speed of 20-40 kilometers per hour, cutting across the flight strips of the DAC, with the aid of available topographic maps and Google Earth™ images.

The ground validation started in the Municipality of Villaba, traversing the major roads of Matag-ob and Kananga, and ended in the City of Ormoc. The established control point UP-O was used as the base station all throughout the conduct of the survey.



Figure 40. Ground validation set-up: a Trimble® SPS 882, mounted on a 2-meter pole and attached on the side of the vehicle

The map in illustrates the extent of the ground validation survey, which acquired 6,872 ground validation points, with an approximate length of 34.9 km. using the base station UP-O.



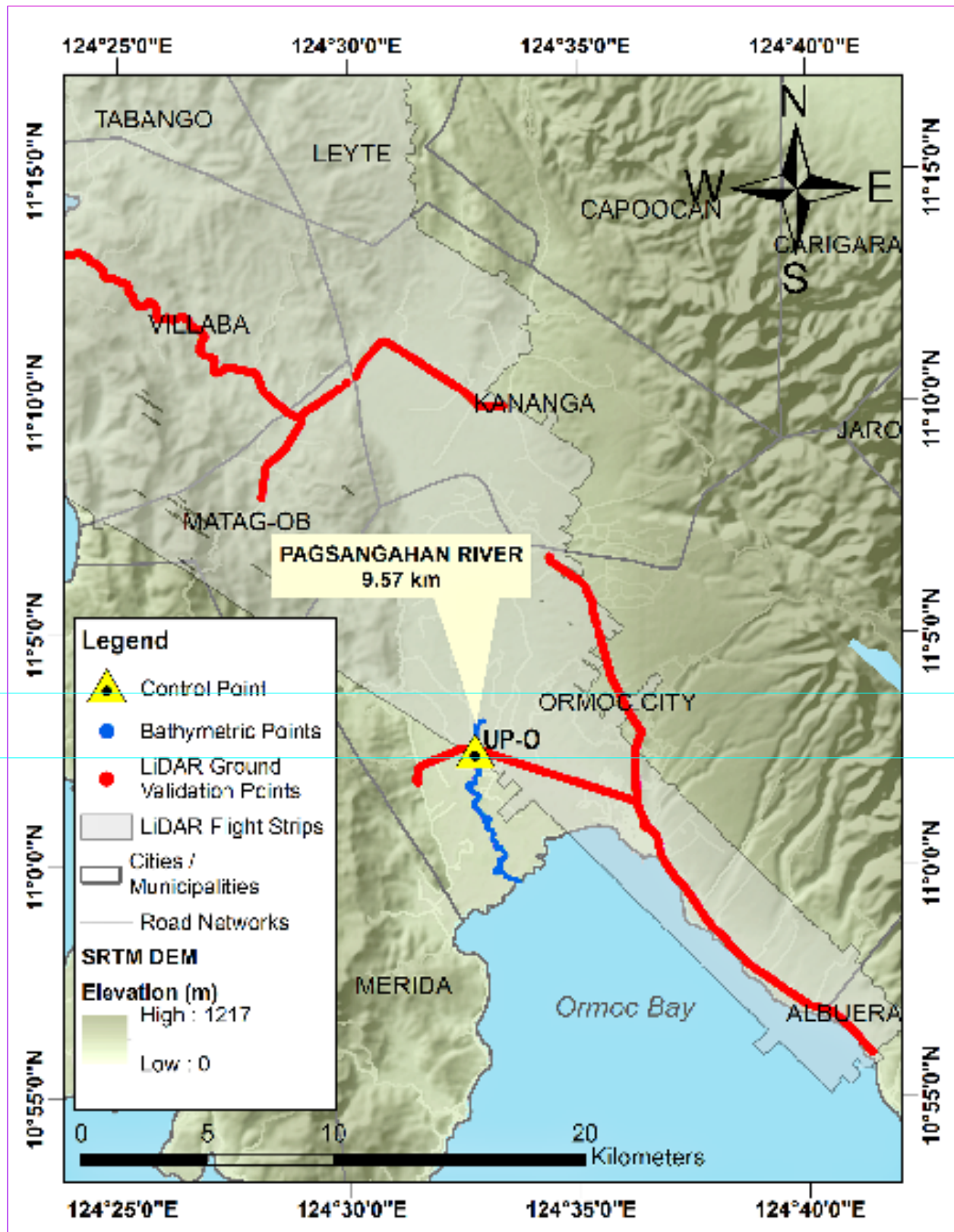


Figure 41. Extent of the LiDAR ground validation survey of the Pagsangahan River



Figure 42. Acquisition of validation points for the Aquarius LiDAR system in the Ormoc Bay

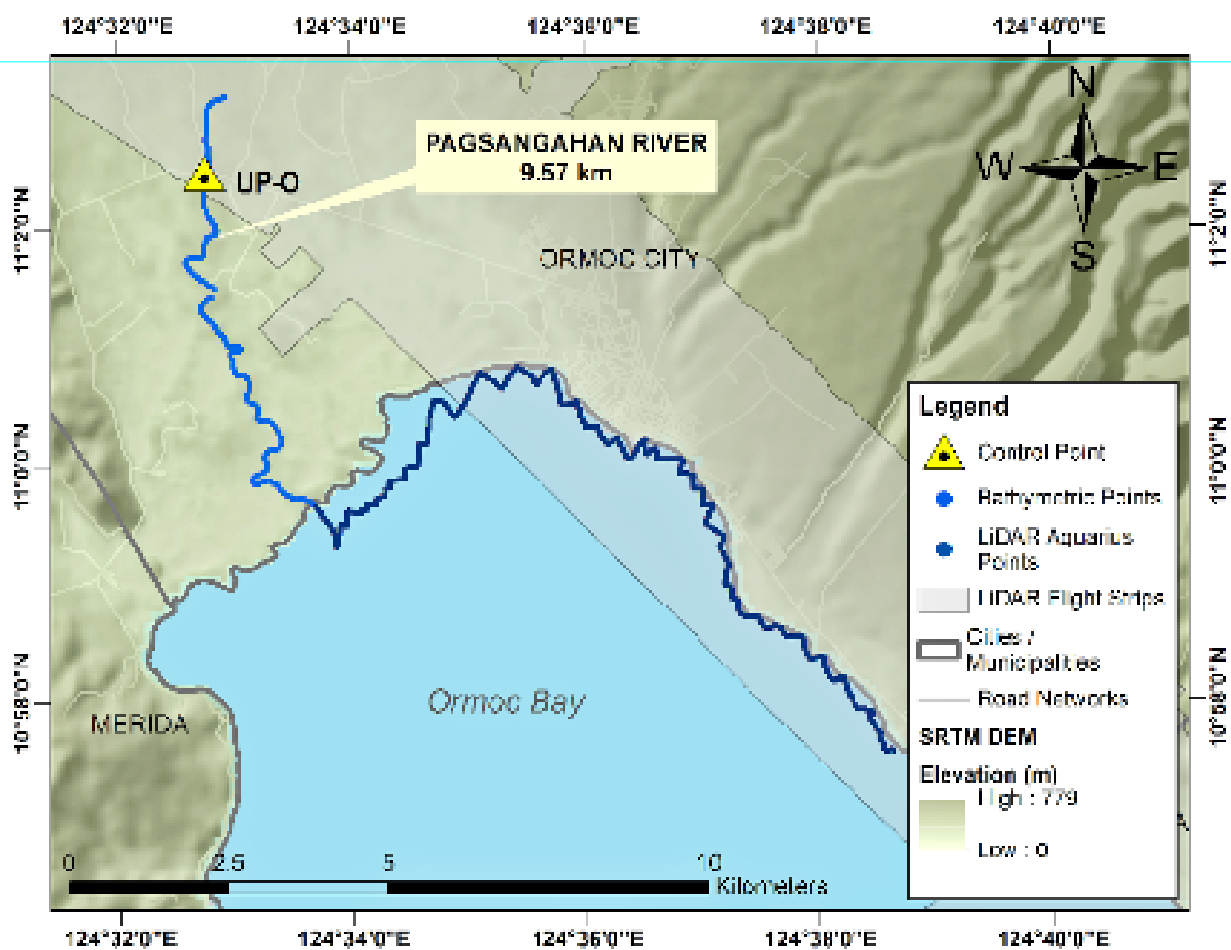


Figure 43. Extent of the Aquarius validation points acquisition survey in the Pagsangahan River Basin

In addition to the ground validation survey, an Aquarius LiDAR validation was also conducted along the coast of Ormoc City (Figure 42). The total length for the Aquarius LiDAR validation survey is 18.50 km., with a total of 8,652 points. The map in illustrates the results of the Aquarius LiDAR validation.

#### 4.7 Bathymetric Survey

A manual bathymetric survey was conducted on January 15, 2014 in the Pagsangahan River using a boat with an installed Hi-Target™ Single Beam Echo Sounder and a mounted Trimble® SPS 882 GNSS receiver in GNSS PPK survey technique, as demonstrated in . The survey began in the upstream side of the river in Barangay Liloan, Ormoc City, Leyte, with coordinates 11°03'07.50056" 124°32'55.32941"; and ended at the mouth of the river in Barangay Lao, Ormoc City, with coordinates 10°59'34.20739" 124°33'45.04847". The map in exhibits the extent of the conducted bathymetric survey.



Figure 44. Bathymetry set-up using Ohmex™ Single Beam Echo Sounder with Trimble® SPS 882

The bathymetric line of the Pagsangahan River had an estimated length of 9.57 km., gathering a total of 4,386 points acquired using UP-O as the GNSS base station. A CAD drawing was also produced to illustrate the Pagsangahan riverbed profile, presented in . The profile shows that there is no abrupt change in elevation on the riverbed, mainly because the area is on lowland. The highest elevation observed was 1.28 meters in MSL in the upstream part of the river; while the lowest elevation observed was -7.72 meters below MSL in Barangay Lao, near the mouth of the river.

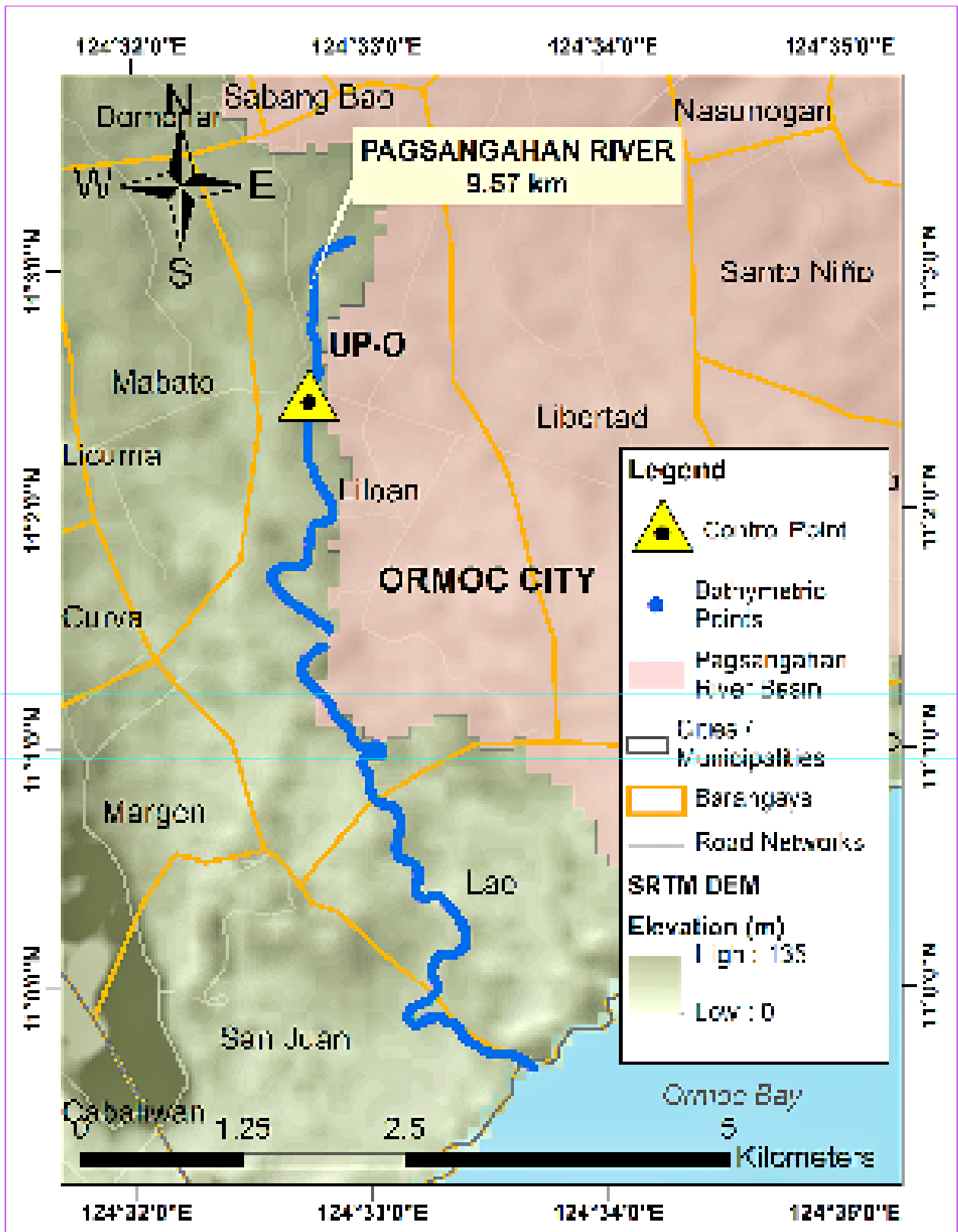


Figure 45. Extent of the bathymetric survey of the Pagsangahan River

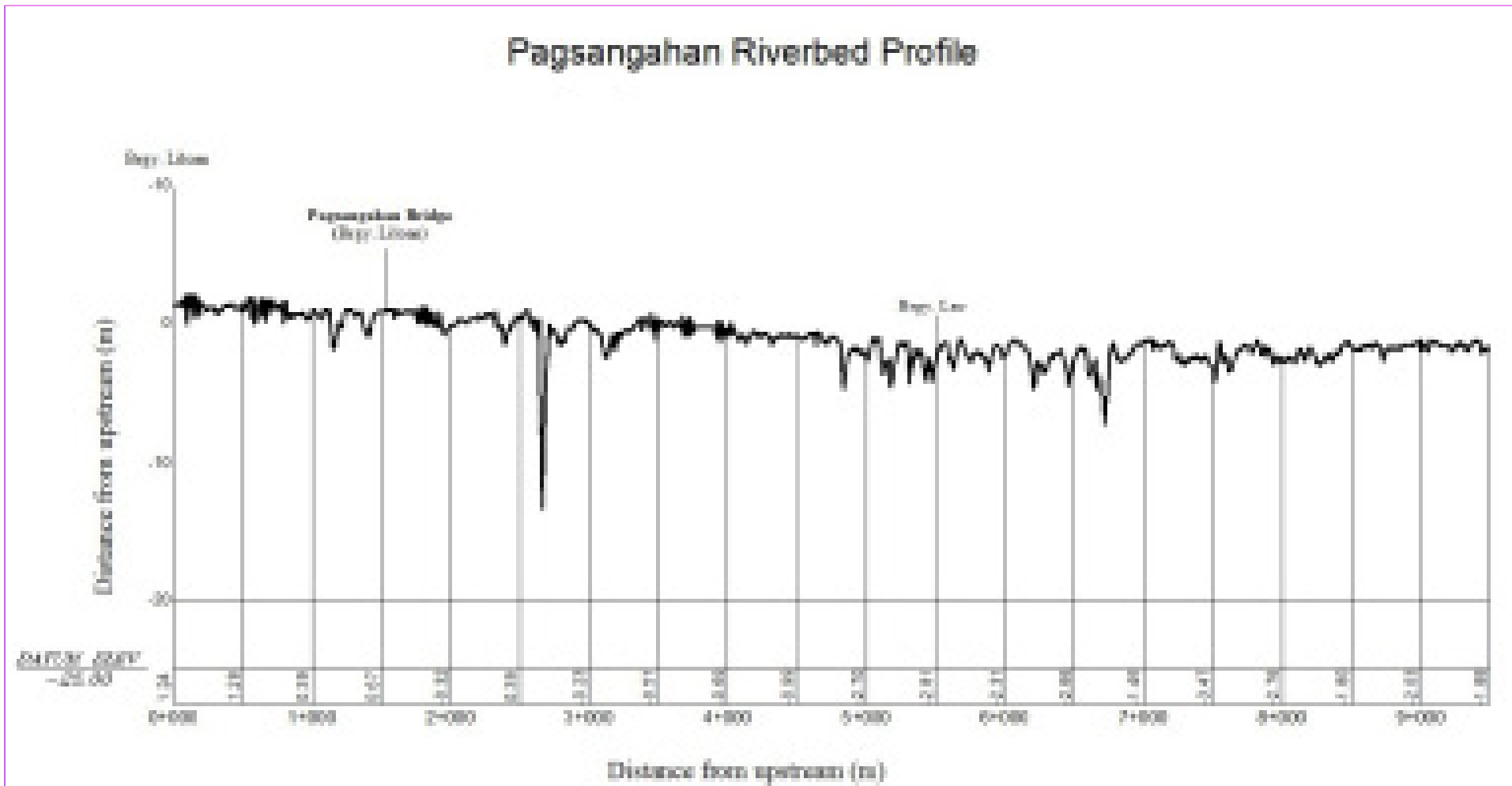


Figure 46. Riverbed profile of the Pagsangahan River

## CHAPTER 5: FLOOD MODELING AND MAPPING

*Dr. Alfredo Mahar Lagmay, Christopher Uichanco, Sylvia Sueno, Marc Moises, Hale Ines, Miguel del Rosario, Kenneth Punay, and Neil Tingin*

The methods applied in this Chapter were based on the DREAM methods manual (Lagmay, et al., 2014) and further enhanced and updated in Paringit, et al. (2017).

### 5.1 Data Used for Hydrologic Modeling

#### 5.1.1 Hydrometry and Rating Curves

Rainfall, water level, and flow in a certain period of time, which are all components and data that affect the hydrologic cycle of the Pagsangahan River Basin, were monitored, collected, and analyzed.

#### 5.1.2 Precipitation

Precipitation data was taken from the automatic rain gauge (ARG) installed by the Flood Modeling Component (FMC) at Barangay Libungao, Kananga, Leyte. The location of the rain gauge is seen in Figure 47.

Total rain from the Libungao rain gauge was 52.4 mm. It peaked at 10.8 mm on 29 July 2016 at 4:20 hours. The lag time between the peak rainfall and discharge was five (5) hours and fifty (50) minutes.

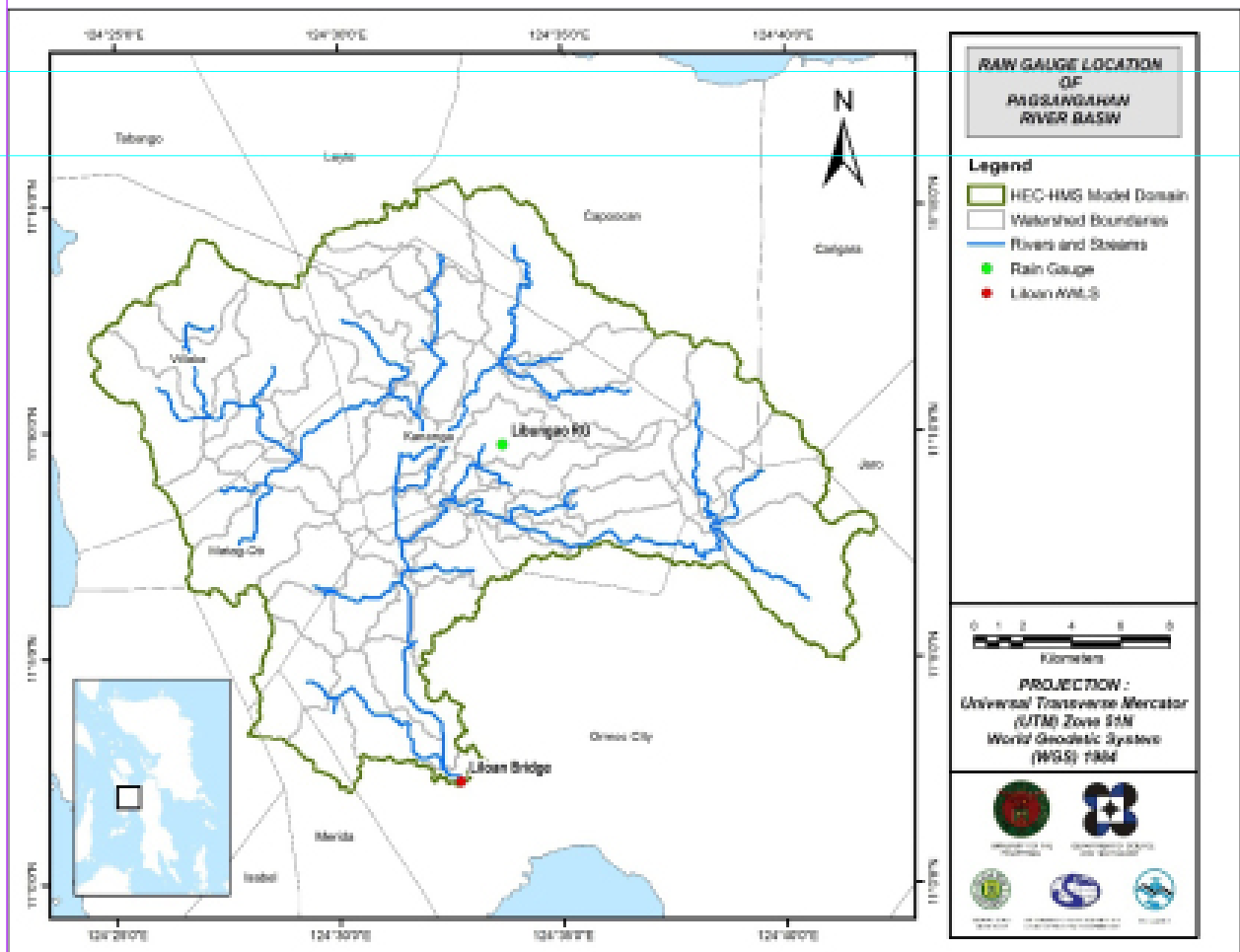


Figure 47. Location map of the Pagsangahan HEC-HMS model used for calibration

### 5.1.3 Rating Curves and River Outflow

A rating curve was computed using the prevailing cross-section (Figure 48) at the Liloan Bridge, Barangay Liloan, Ormoc City, Leyte, to establish the relationship between the observed water levels (H) at the Liloan Bridge and the outflow (Q) of the watershed at this location.

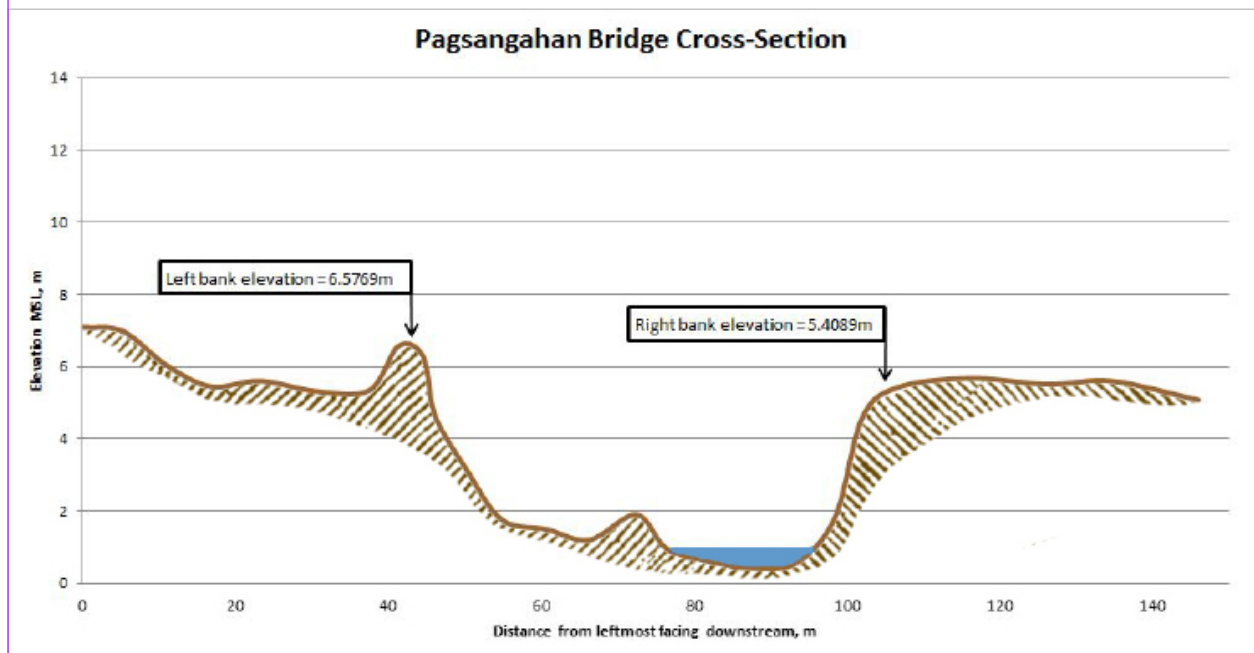


Figure 48. Cross-Section Plot of Liloan Bridge

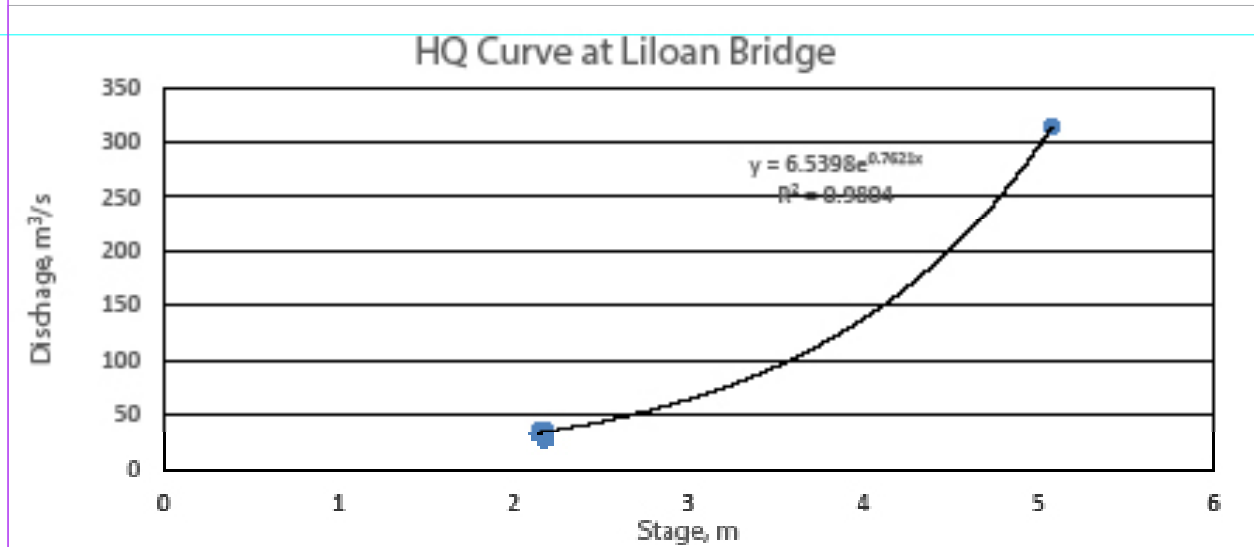


Figure 49. Rating curve at the Liloan Bridge, Barangay Bago, Bato, Leyte

This rating curve equation was used to compute for the river outflow at the Liloan Bridge, for the calibration of the HEC-HMS model. Peak discharge was at 58.7 cu.m/s on July 30, 2016 11:30 hrs.

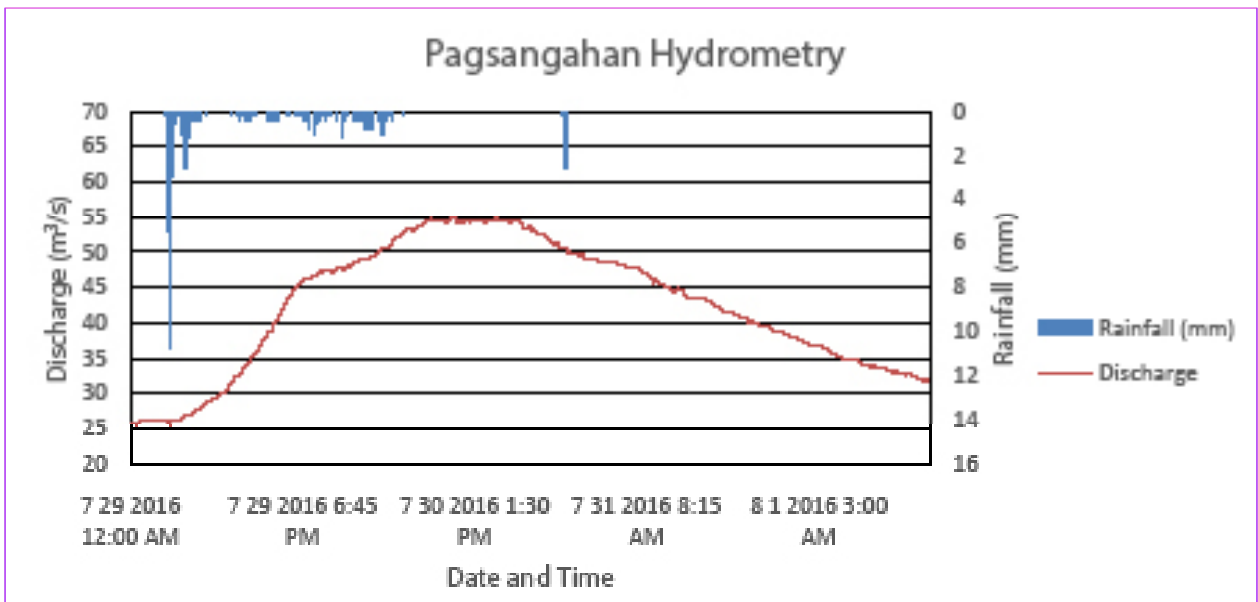


Figure 50. Rainfall and outflow data at Pagsangahan used for modeling

### 5.2 RIDF Station

The Philippine Atmospheric Geophysical and Astronomical Services Administration (PAGASA) computed Rainfall Intensity Duration Frequency (RIDF) values for the Tacloban Rain Gauge (Table 37). This station chosen based on its proximity to the Pagsangahan watershed (Figure 51). The RIDF rainfall amount for twenty-four (24) hours was converted into a synthetic storm by interpolating and re-arranging the values such that certain peak values were attained at a certain time. The extreme values for this watershed were computed based on a 59-year record.

Table 37. RIDF values for the Tacloban Rain Gauge computed by PAGASA

COMPUTED EXTREME VALUES (in mm) OF PRECIPITATION									
T (yrs)	10 mins	20 mins	30 mins	1 hr	2 hrs	3 hrs	6 hrs	12 hrs	24 hrs
2	17.8	26.9	33.6	42.8	59.7	70.5	87.2	104	120.6
5	24.3	36.7	45.7	57.4	80.7	95.2	117.9	140.6	161.4
10	28.5	43.2	53.7	67.1	94.6	111.5	138.2	164.9	188.4
15	30.9	46.8	58.3	72.5	102.5	120.7	149.6	178.6	203.7
20	32.6	49.4	61.4	76.3	108	127.1	157.7	188.1	214.3
25	33.9	51.4	63.9	79.3	112.2	132.1	163.8	195.5	222.6
50	37.9	57.5	71.4	88.3	125.2	147.4	182.9	218.2	247.9
100	41.8	63.5	78.9	97.3	138.2	162.5	201.8	240.8	273



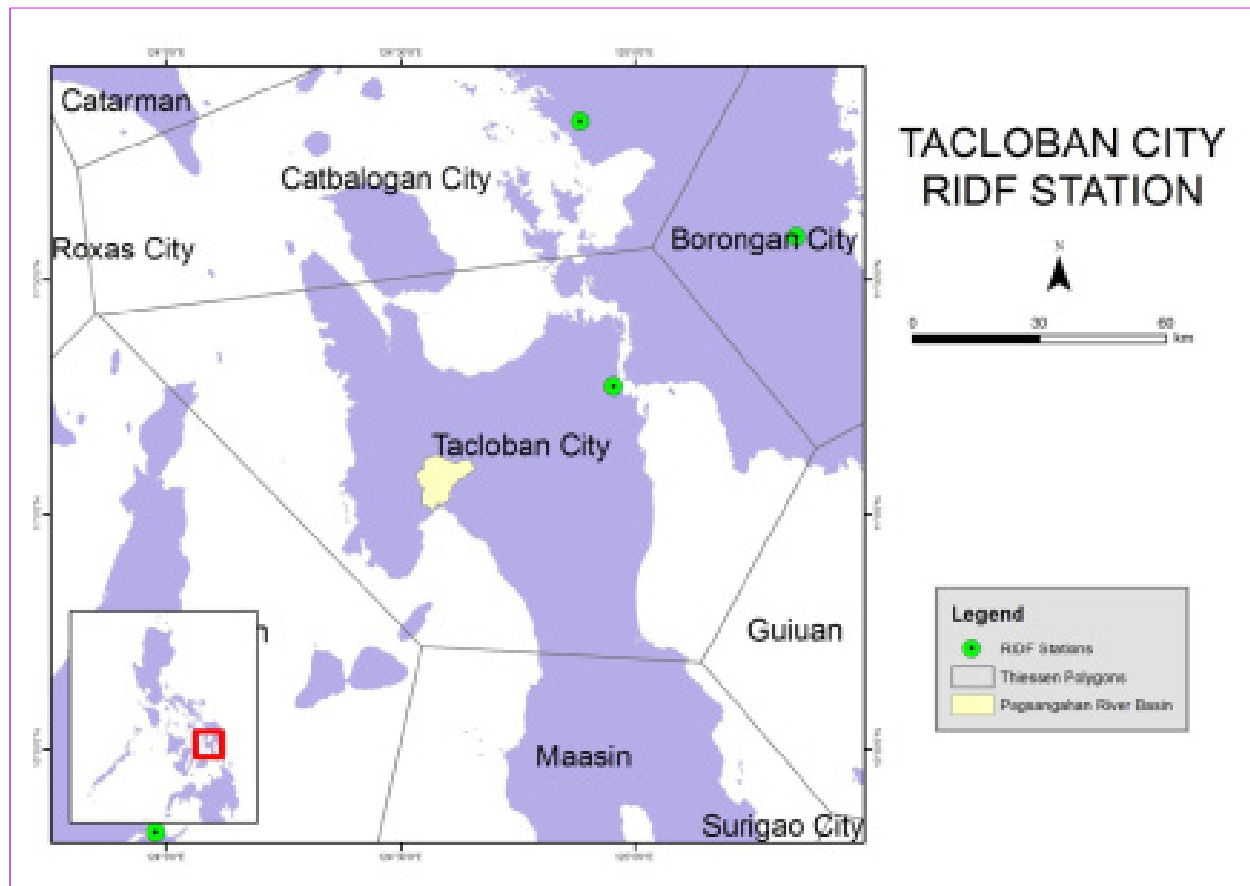


Figure 51. Location of the Tacloban RIDF Station relative to the Pagsangahan River Basin

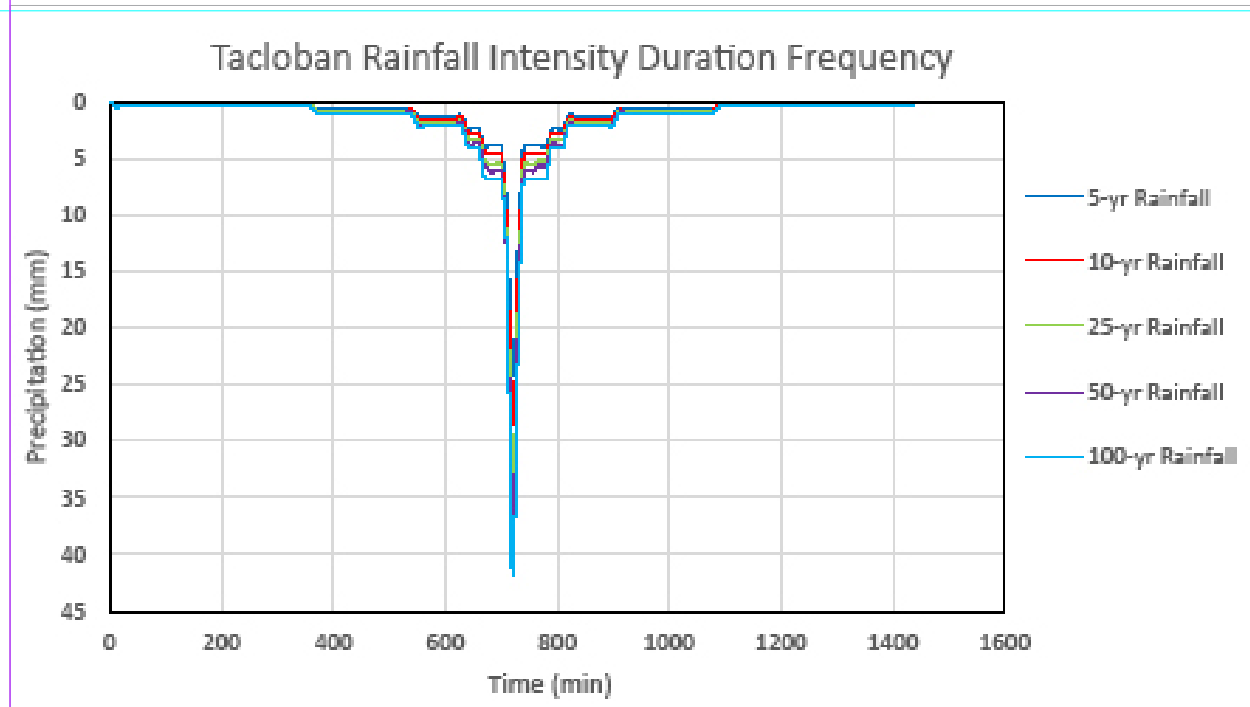


Figure 52. Synthetic storm generated from a 24-hour period rainfall, for various return periods

### 5.3 HMS Model

The soil shapefile was taken from the Bureau of Soils and Water Management (BSWM) under the Department of Agriculture (DA). The land cover dataset is from the National Mapping and Resource information Authority (NAMRIA). These soil datasets were obtained before 2004. The soil and land cover maps of the Pagsangahan River Basin are presented in Figures 53 and 54, respectively.

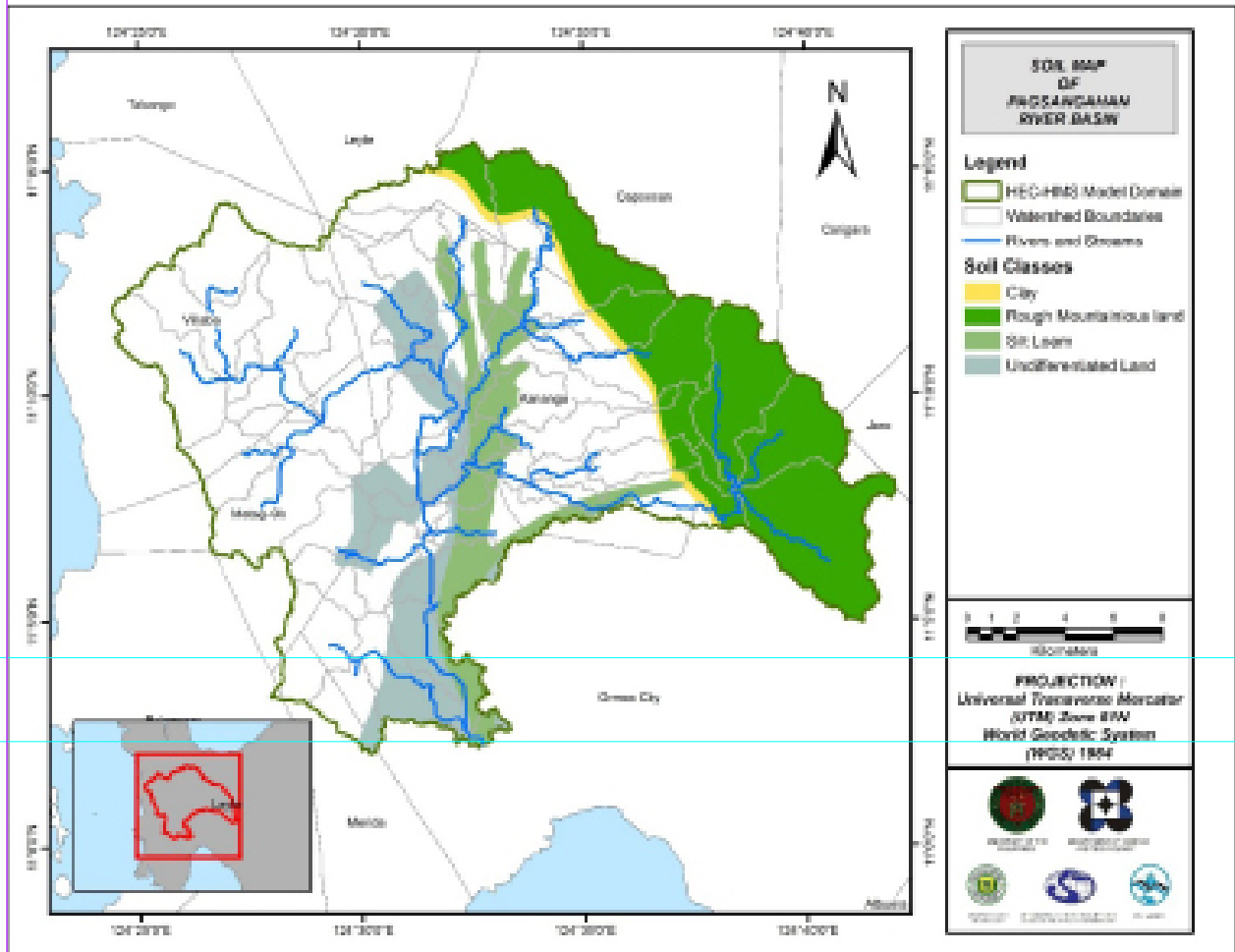


Figure 53. Soil map of the Pagsangahan River Basin (Source: DA)

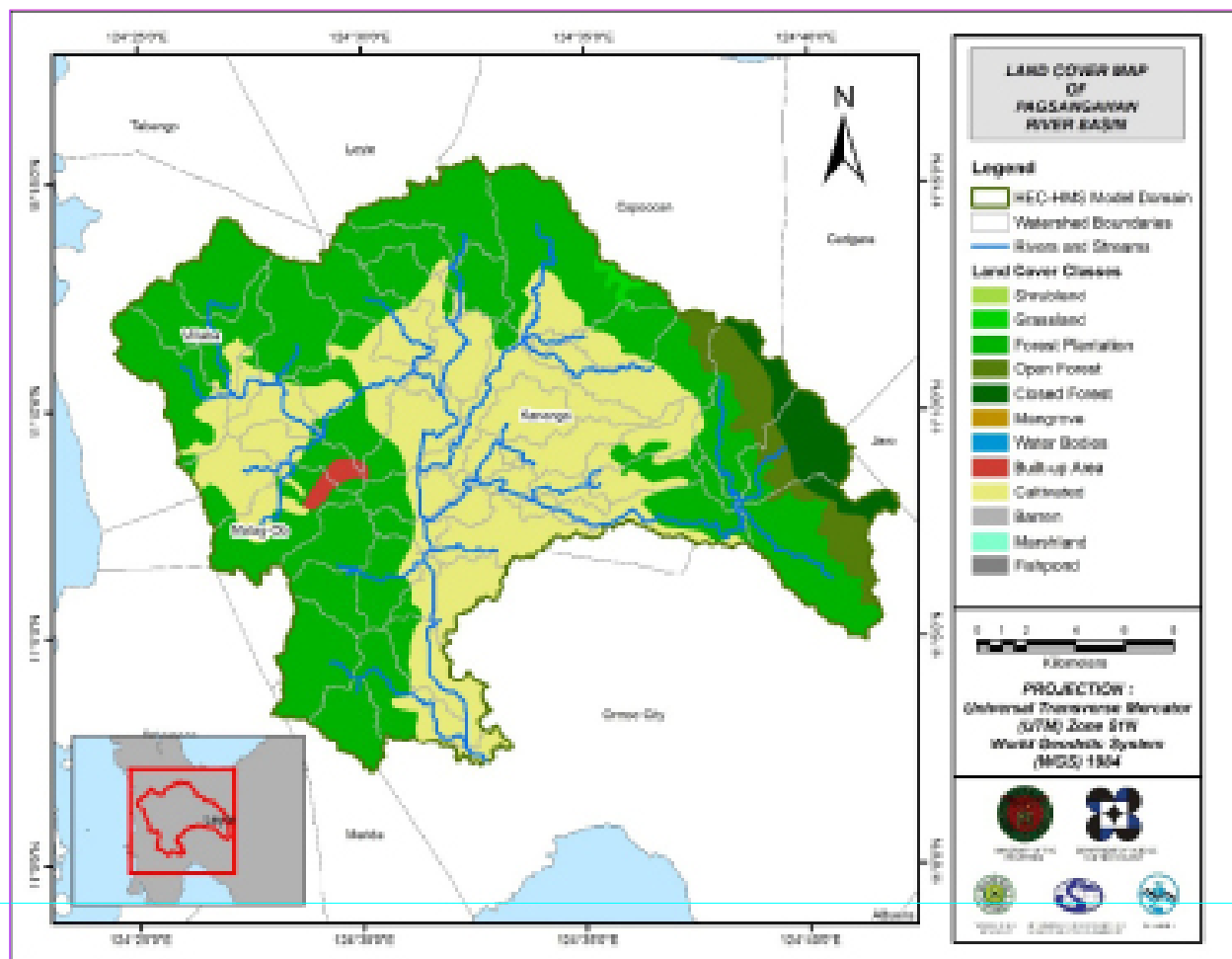


Figure 54. Land cover map of the Pagsangahan River Basin (Source: NAMRIA)

For the Pagsangahan River Basin, the soil classes identified were clay, rough mountainous land, silt loam, and undifferentiated land. The land cover types identified were grasslands, forest plantations, open forests, closed forests, built-up areas, and cultivated land.

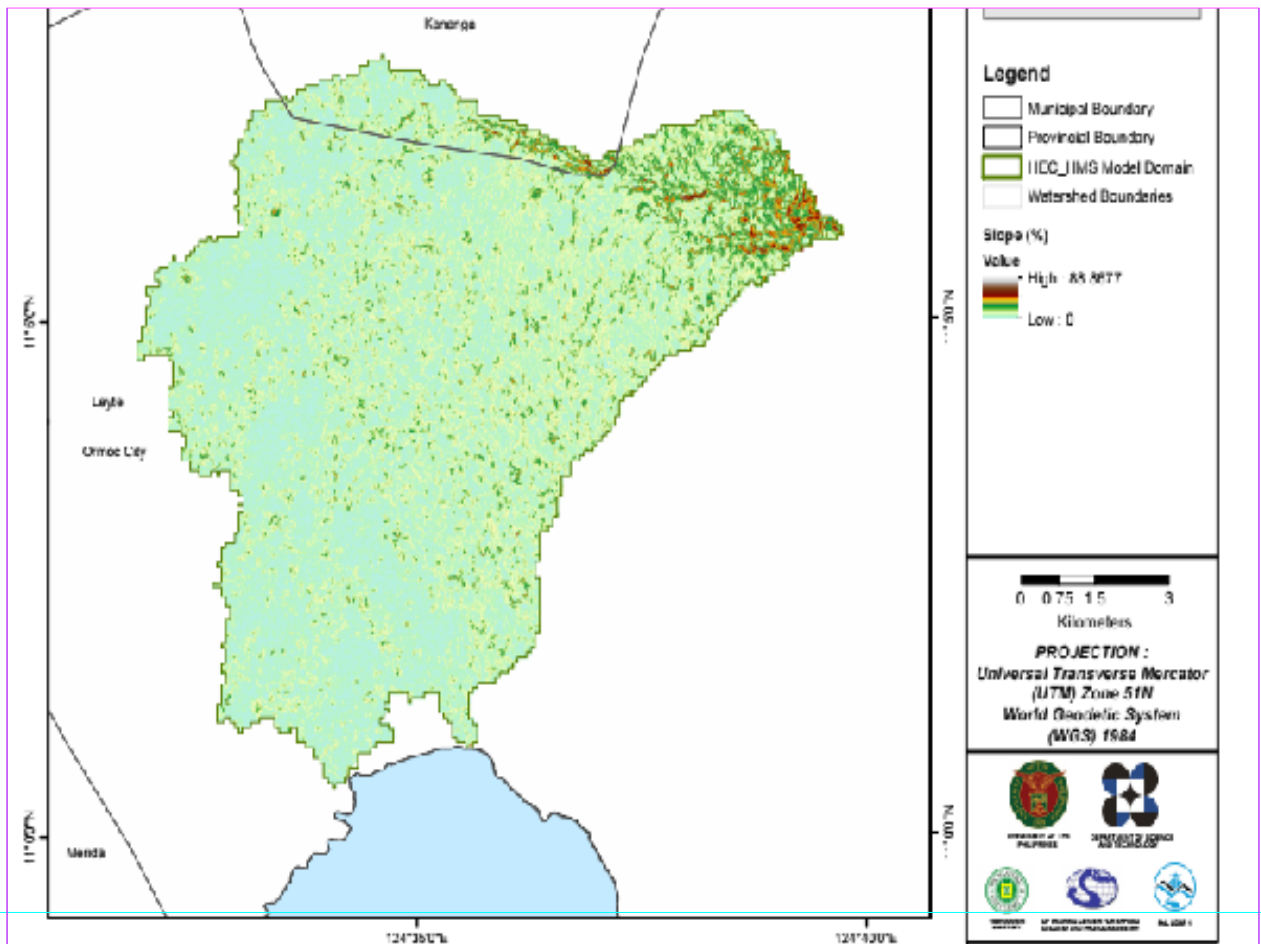


Figure 55. Slope map of the Pagsangahan River Basin

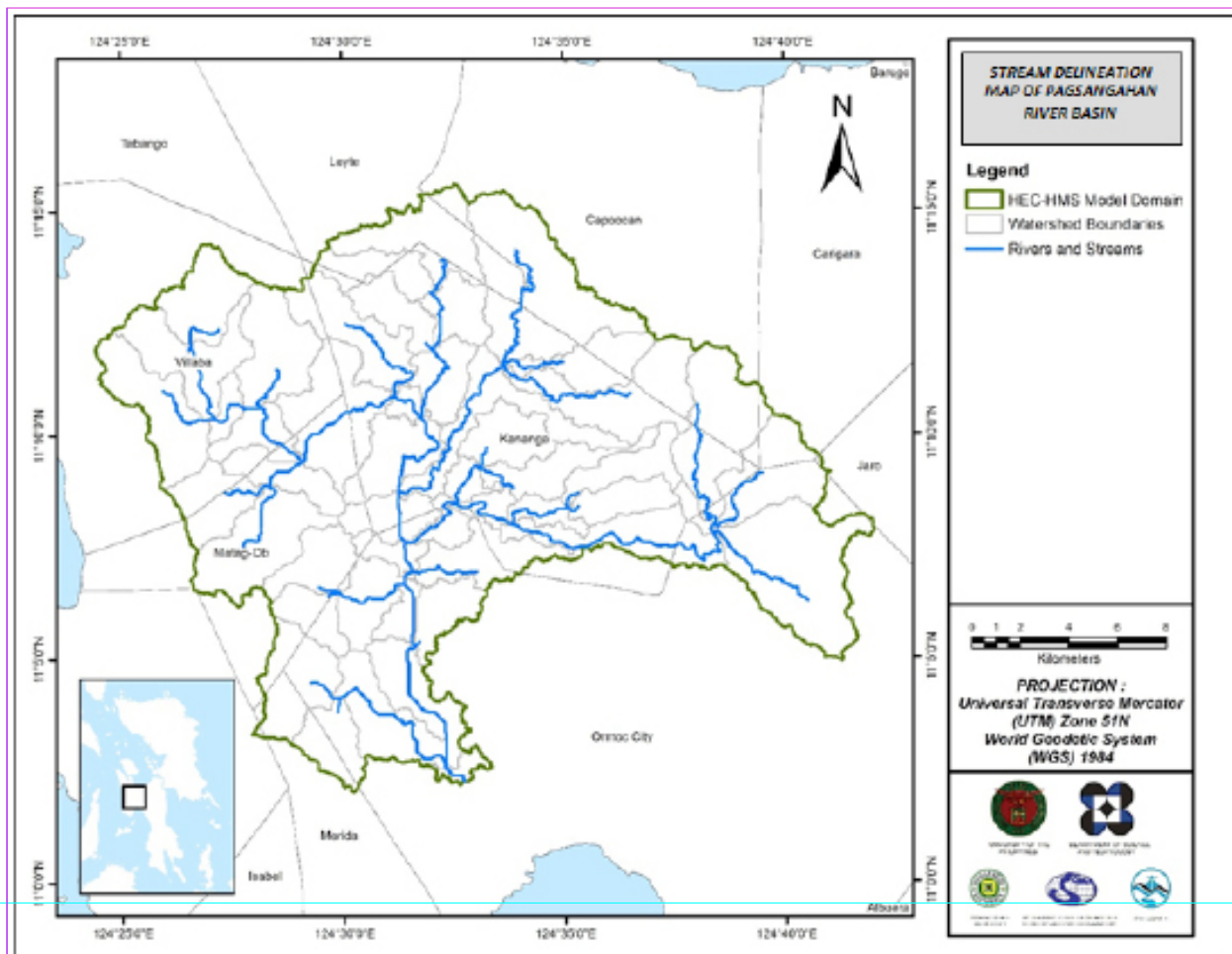


Figure 56. Stream delineation map of the Pagsangahan River Basin

Using the SAR-based DEM, the Pagsangahan basin was delineated and further subdivided into sub-basins. The model consists of fifty-one (51) sub-basins, twenty-five (25) reaches, and fifty-five (55) junctions. The main outlet is at the Liloan Bridge. See ANNEX 10 for the Pagsangahan Model Reach Parameters

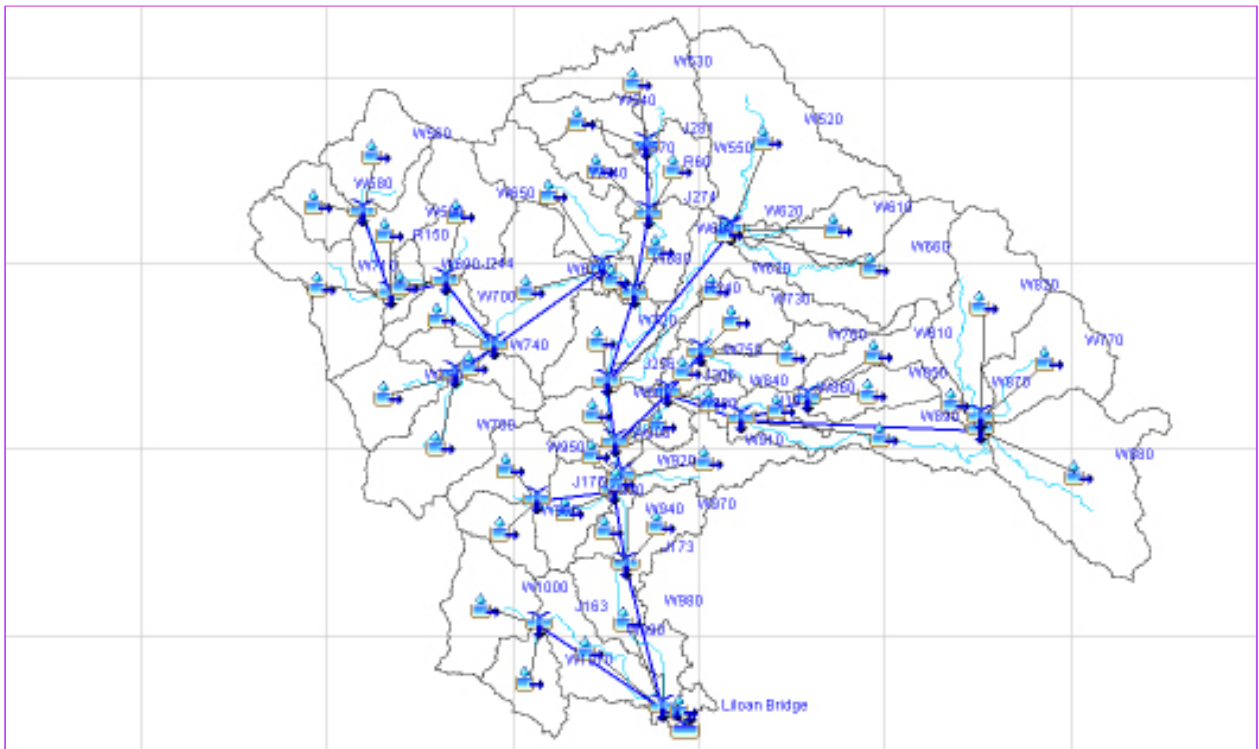


Figure 57. The Pagsangahan River Basin model, generated using HEC-HMS

#### 5.4 Cross-section Data

Riverbed cross-sections of the watershed were necessary in the HEC-RAS model set-up. The cross-section data for the HEC-RAS model were derived from the LiDAR DEM data. It was defined using the Arc GeoRAS tool and was post-processed in ArcGIS (Figure 58).

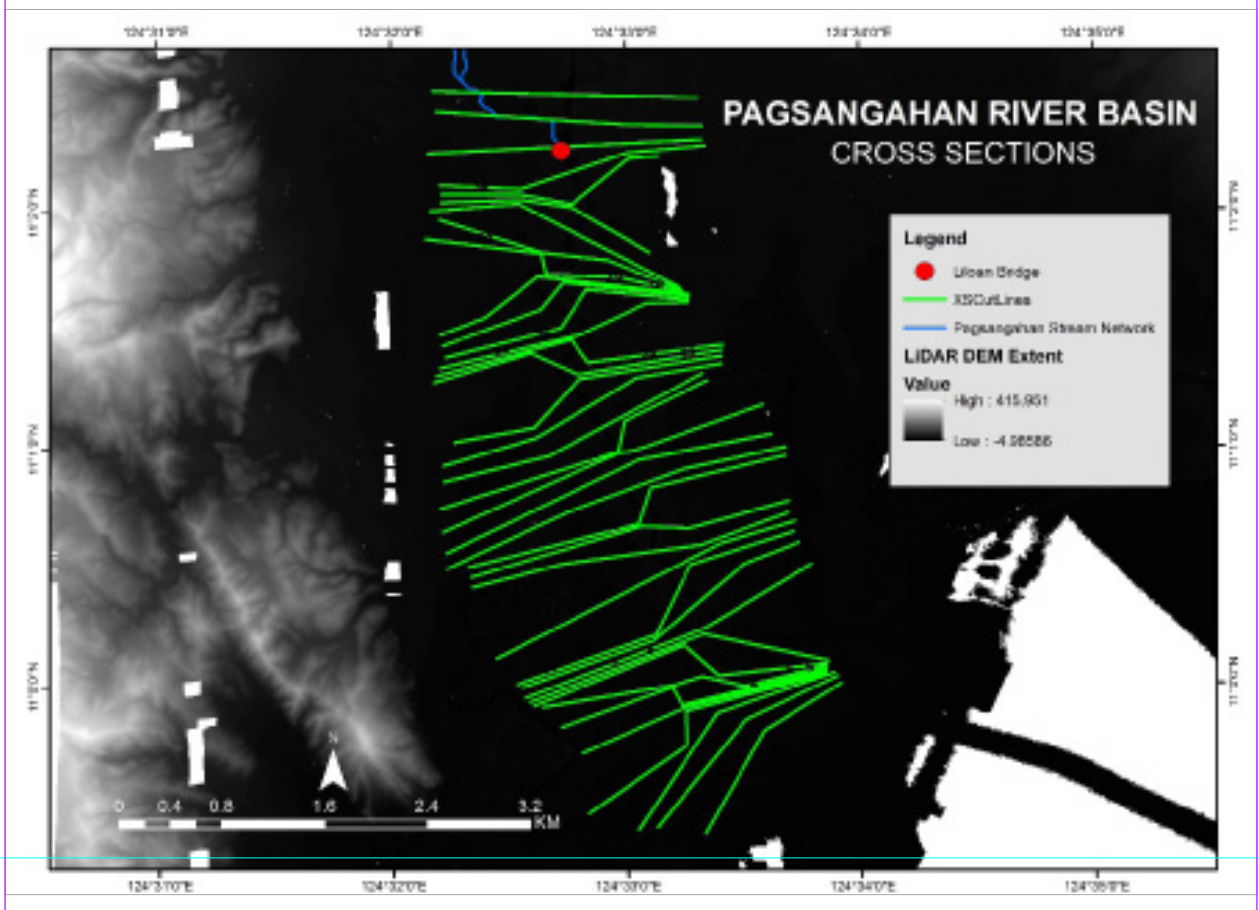


Figure 58. River cross-section of the Pagsangahan River, generated through Arcmap HEC GeoRAS tool

## 5.5 Flo 2D Model

The automated modelling process allows for the creation of a model with boundaries that are almost exactly coincidental with that of the catchment area. As such, they have approximately the same land area and location. The entire area is divided into square grid elements, 10 meter by 10 meter in size. Each element is assigned a unique grid element number which serves as its identifier, then attributed with the parameters required for modelling such as x-and y-coordinate of centroid, names of adjacent grid elements, Manning coefficient of roughness, infiltration, and elevation value. The elements are arranged spatially to form the model, allowing the software to simulate the flow of water across the grid elements and in eight directions (north, south, east, west, northeast, northwest, southeast, southwest).

Based on the elevation and flow direction, it is seen that the water will generally flow from the north of the model to the south, following the main channel. As such, boundary elements in those particular regions of the model are assigned as inflow and outflow elements respectively.

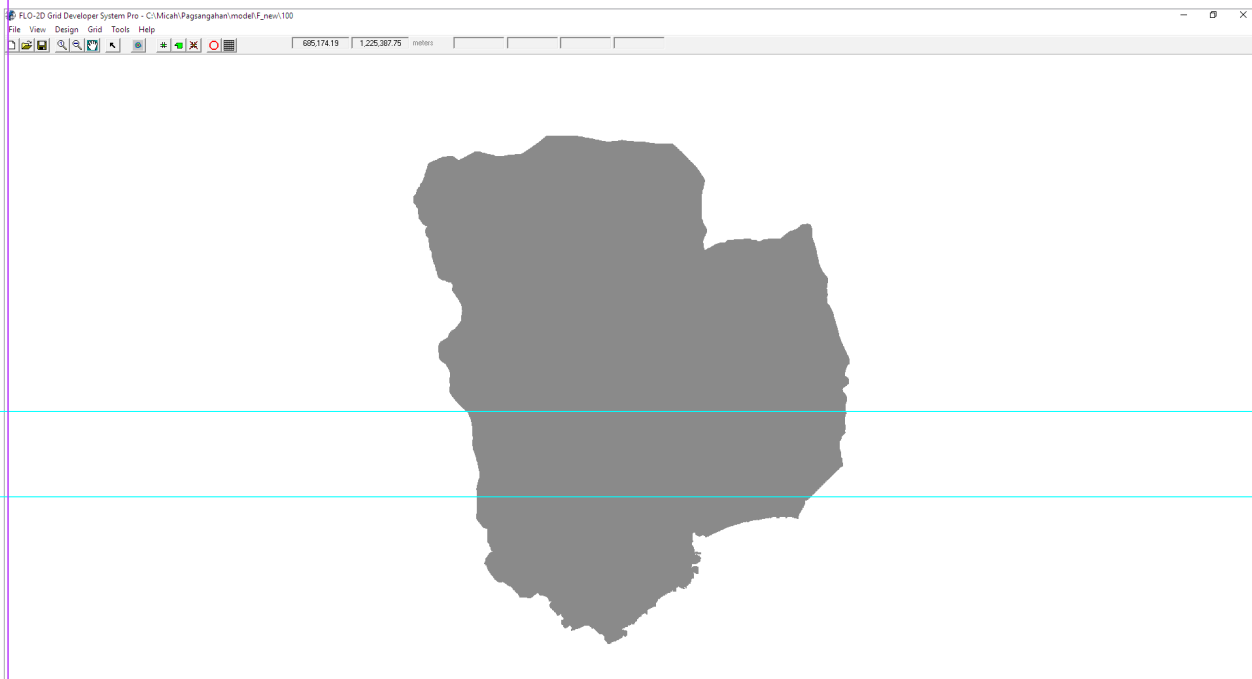


Figure 59. Screenshot of a sub-catchment with the computational area to be modeled in the FLO-2D GDS Pro

The simulation is then run through FLO-2D GDS Pro. This particular model had a computer run time of 81.55957 hours. After the simulation, FLO-2D Mapper Pro is used to transform the simulation results into spatial data that shows flood hazard levels, as well as the extent and inundation of the flood. Assigning the appropriate flood depth and velocity values for Low, Medium, and High creates the following food hazard map. Most of the default values given by FLO-2D Mapper Pro are used, except for those in the Low hazard level. For this particular level, the minimum  $h$  (Maximum depth) is set at 0.2 m while the minimum  $vh$  (Product of maximum velocity ( $v$ ) times maximum depth ( $h$ )) is set at 0 m<sup>2</sup>/s.

The creation of a flood hazard map from the model also automatically creates a flow depth map depicting the maximum amount of inundation for every grid element. The legend used by default in Flo-2D Mapper is not a good representation of the range of flood inundation values, so a different legend is used for the layout. In this particular model, the inundated parts cover a maximum land area of 94 945 000.00 m<sup>2</sup>.

There is a total of 51 334 327.54 m<sup>3</sup> of water entering the model. Of this amount, 24 436 414.50 m<sup>3</sup> is due to rainfall while 26 897 913.04 m<sup>3</sup> is inflow from other areas outside the model. 13 151 253.00 m<sup>3</sup> of this water is lost to infiltration and interception, while 29 852 675.29 m<sup>3</sup> is stored by the flood plain. The rest, amounting up to 8 330 411.25 m<sup>3</sup>, is out-flow.

### 5.6 Results of HMS Calibration

After calibrating the Pagsangahan HEC-HMS river basin model, its accuracy was measured against the observed values. Figure 60 demonstrates the comparison between the two (2) discharge data. ANNEX 9 presents the Pagsangahan Model Basin Parameters.

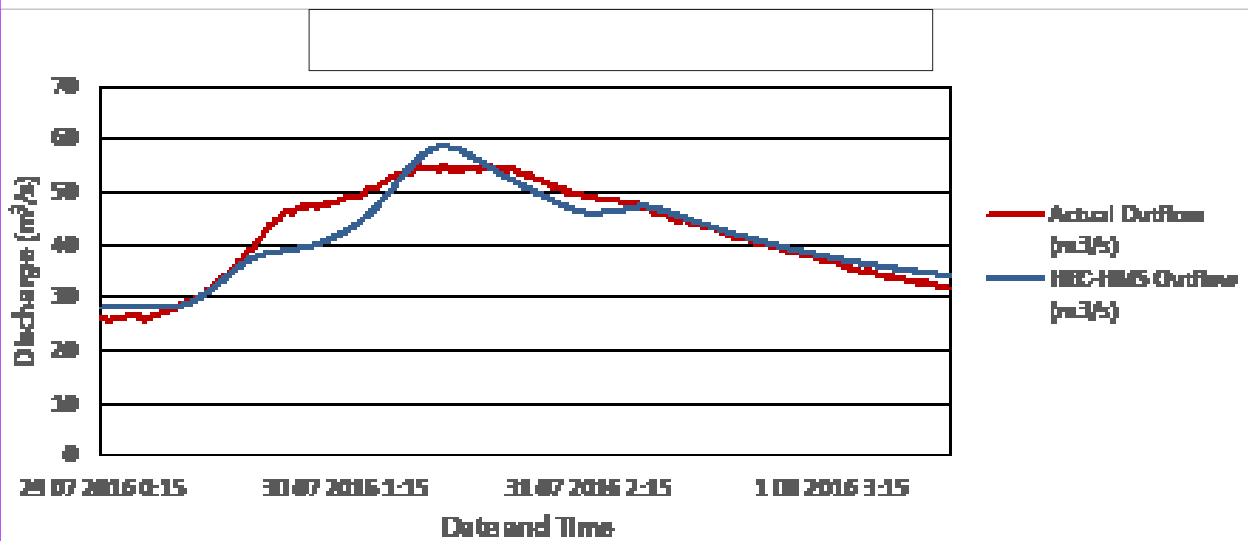


Figure 60. Outflow hydrograph of Pagsangahan produced by the HEC-HMS model, compared with observed outflow

Enumerated in Table 38 are the adjusted ranges of values of the parameters used in calibrating the model.

Table 38. Range of calibrated values for the Pagsangahan River Basin Model

Hydrologic Element	Calculation Type	Method	Parameter	Range of Calibrated Values
Basin	Loss	SCS Curve number	Initial Abstraction (mm)	
			Curve Number	
	Transform	Clark Unit Hydrograph	Time of Concentration (hr.)	
			Storage Coefficient (hr.)	
	Baseflow	Recession	Recession Constant	
Ratio to Peak				
Reach	Routing	Muskingum-Cunge	Manning's Coefficient	

Initial abstraction defines the amount of precipitation that must fall before surface runoff. The magnitude of the outflow hydrograph increases as the initial abstraction decreases. The range of values from 9 to 30 mm for initial abstraction means that there is a minimal to average amount of infiltration or rainfall interception by vegetation, per sub-basin.

The curve number is the estimate of the precipitation excess of soil cover, land use, and antecedent moisture. The magnitude of the outflow hydrograph increases as the curve number increases. The range of 40 to 60 for the curve number is relatively low compared to the advisable values for Philippine watersheds, depending on the soil and land cover of the area.

The time of concentration and the storage coefficient are the travel time and index of temporary storage of runoff in a watershed. The range of calibrated values from 0.2 to 9 hours determines the reaction time of the model, with respect to the rainfall. The peak magnitude of the hydrograph decreases when these parameters are increased.



The recession constant is the rate at which the baseflow recedes between storm events; and ratio to peak is the ratio of the baseflow discharge to the peak discharge. A recession constant of 0.98 indicates that the basin is unlikely to quickly return to its original discharge, and will be higher instead. A ratio to peak of 0.1 to 0.3 indicates a steeper receding limb of the outflow hydrograph.

A Manning’s roughness coefficient of 0.04 corresponds to the common roughness of the Pagsangahan watershed, which is determined to be cultivated with mature field crops (Brunner, 2010).

Table 39. Summary of the Efficiency Test of the Pagsangahan HMS Model

Accuracy measure	Value
RMSE	2.9
$r^2$	0.89
NSE	0.88
PBIAS	0.84
RSR	0.34

The Root Mean Square Error (RMSE) method aggregates the individual differences of these two measurements. It was computed as 2.9 (m<sup>3</sup>/s).

The Pearson correlation coefficient ( $r^2$ ) assesses the strength of the linear relationship between the observations and the model. A coefficient value close to 1 corresponds to an almost perfect match of the observed discharge and the resulting discharge from the HEC HMS model. Here, it was measured at 0.89.

The Nash-Sutcliffe (E) method was also used to assess the predictive power of the model. Here, the optimal value is 1. The model attained an efficiency coefficient of 0.88.

A positive Percent Bias (PBIAS) indicates a model’s propensity towards under-prediction. Negative values indicate a bias towards over-prediction. The optimal value is 0. In the model, the PBIAS is 0.84.

The Observation Standard Deviation Ratio, RSR, is an error index. A perfect model attains a value of 0 when the error units of the values are quantified. The model has an RSR value of 0.34.

## 5.7 Calculated outflow hydrographs and Discharge values for different rainfall return periods

### 5.7.1 Hydrograph using the Rainfall Runoff Model

The summary graph (Figure 61) reflects the Pagsangahan outflow using the Tacloban RIDF curves in five (5) different return periods (i.e., 5-year, 10-year, 25-year, 50-year, and 100-year rainfall time series), based on the data from PAGASA. The simulation results reveal a significant increase in outflow magnitude as the rainfall intensity increases, for a range of durations and return periods.

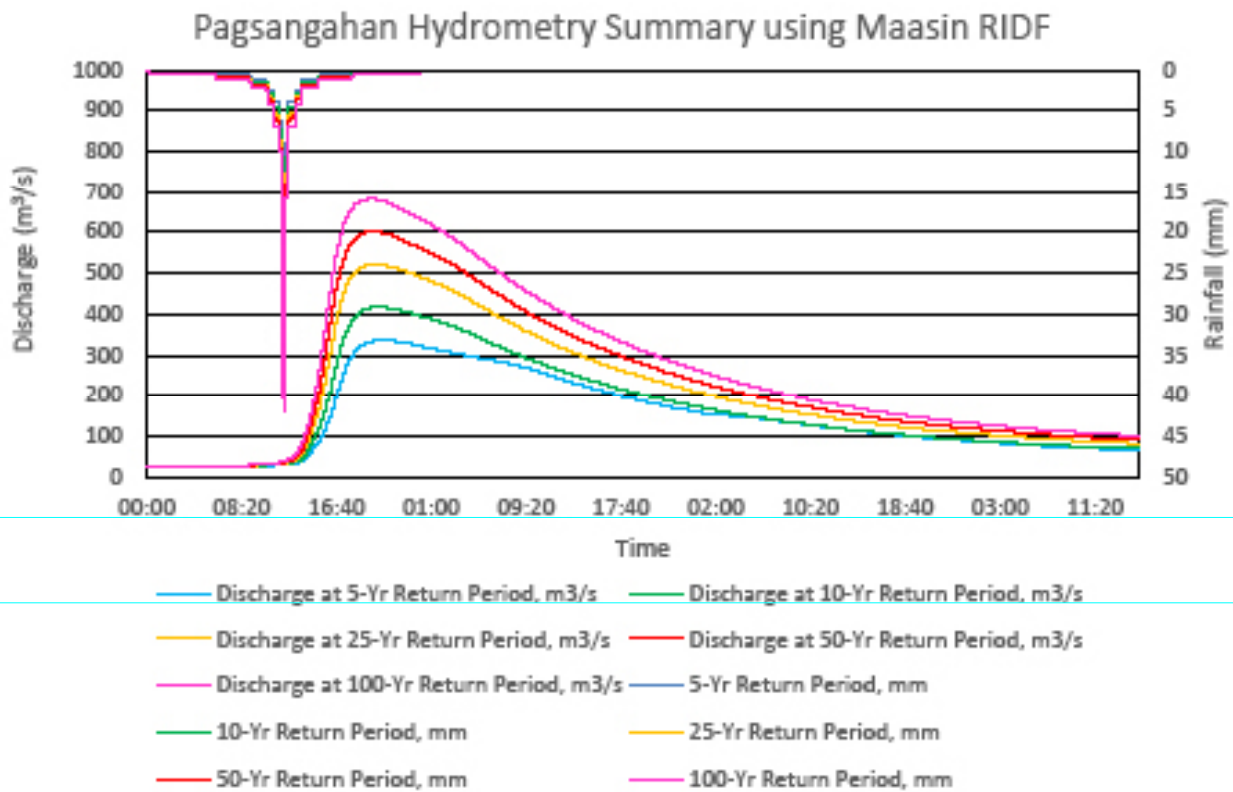


Figure 61. Outflow hydrograph at Pagsangahan Station generated using Tacloban RIDF simulated in HEC-HMS

A summary of the total precipitation, peak rainfall, peak outflow, and time to peak of the Pagsangahan discharge using the Tacloban RIDF curves in five (5) different return periods is outlined in Table 40.

Table 40. Peak values of the Pagsangahan HEC-HMS Model outflow using the Tacloban RIDF

RIDF Period	Total Precipitation (mm)	Peak rainfall (mm)	Peak outflow (m <sup>3</sup> /s)	Time to Peak
5-Year	161.4	24.3	336.7	8 hours, 45 minutes
10-Year	188.4	28.5	417.4	8 hours, 15 minutes
25-Year	222.6	33.9	522.6	8 hours, 00 minutes
50-Year	247.9	37.9	601.3	7 hours, 45 minutes
100-Year	273.0	41.8	681.9	7 hours, 45 minutes

### 5.7.2 Discharge data using Dr. Horritts' recommended hydrologic method

The river discharge values for the nine (9) rivers entering the floodplain are shown in [ ] to [ ], and the peak values are summarized in [ ] to [ ].

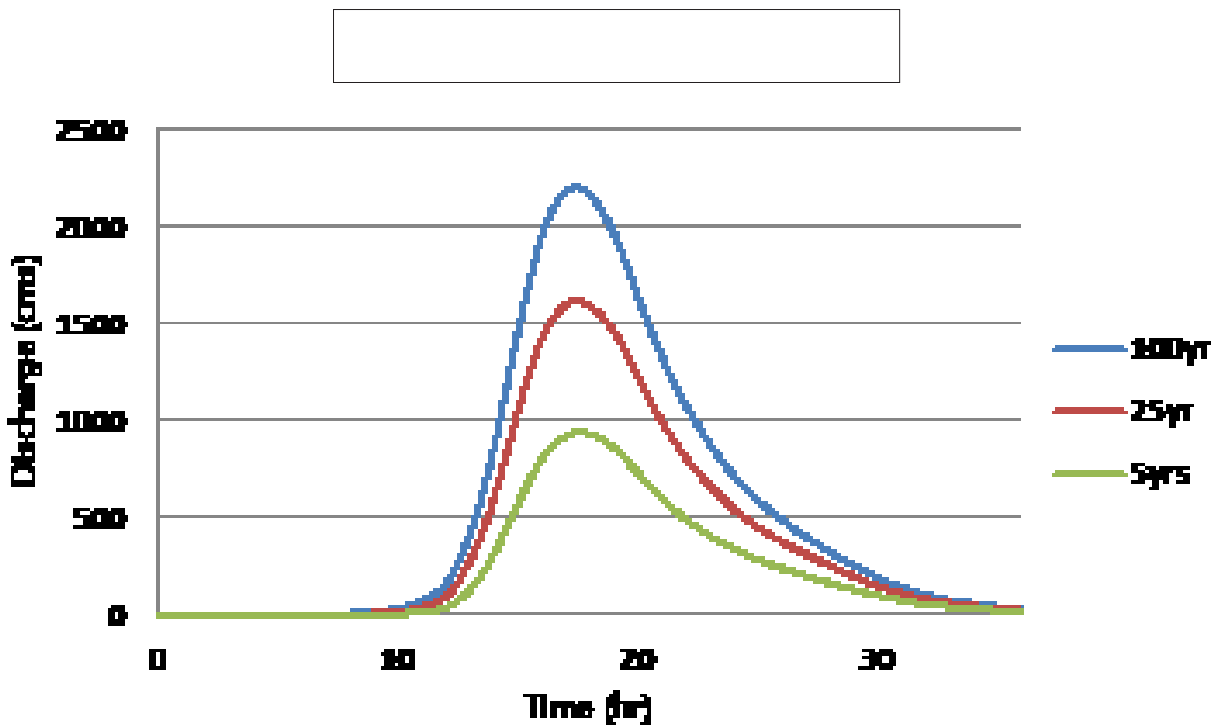


Figure 62. Pagsangahan river (1) generated discharge using 5-, 25-, and 100-year Tacloban RIDF in HEC-HMS

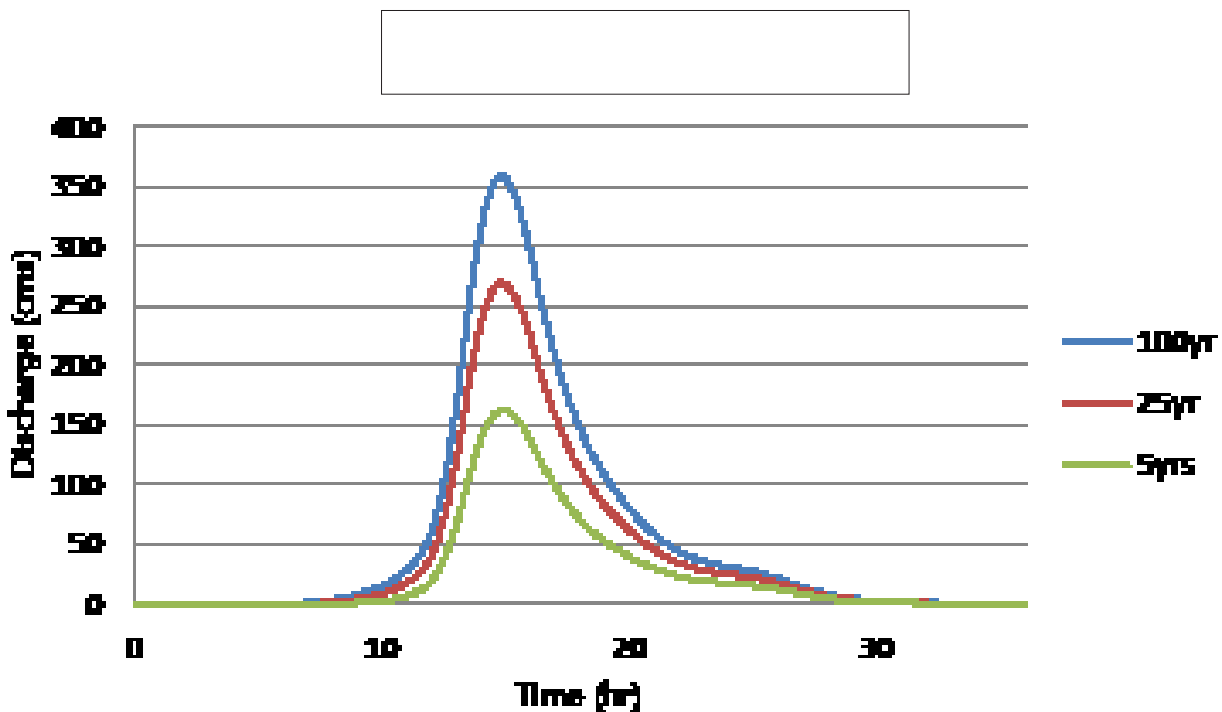


Figure 63. Pagsangahan River (2) generated discharge using 5-, 25-, and 100-year Tacloban RIDF in HEC-HMS

Table 41. Summary of the Pagsangahan River (1) discharge generated in HEC-HMS

RIDF Period	Peak discharge (cms)	Time-to-peak
100-Year	2206.7	17 hours, 30 minutes
25-Year	1621.3	17 hours, 30 minutes
5-Year	936.7	17 hours, 30 minutes

Table 42. Summary of the Pagsangahan River (2) discharge generated in HEC-HMS

RIDF Period	Peak discharge (cms)	Time-to-peak
100-Year	359.1	14 hours, 50 minutes
25-Year	269.8	14 hours, 50 minutes
5-Year	162.1	14 hours, 50 minutes

Table 43. Validation of river discharge estimates

Discharge Point	QMED(SCS), cms	QBANKFUL, cms	QMED(SPEC), cms	VALIDATION	
				Bankful Discharge	Specific Discharge
Pagsangahan (1)	824.296	846.408	525.539	Pass	Fail
Pagsangahan (2)	142.648	99.949	127.626	Pass	Pass

Two (2) values from the HEC-HMS river discharge estimates were able to satisfy the conditions for validation using the Bankful method; and one did not satisfy the specific discharge methods and will need recalculation. The passing values are based on theory but are supported by other discharge computation methods; thus, they are applicable for flood modeling. These values will need further investigation for the purpose of validation. It is therefore recommended to obtain the actual values of the river discharges for higher-accuracy modeling.

## 5.8 River Analysis (RAS) Model Simulation

The HEC-RAS Flood Model produced a simulated water level at every cross-section, for every time step, for every flood simulation created. The resulting model will be used in determining the flooded areas within the model. The simulated model will be an integral part in determining the extent of real-time flood inundation of the river, after it has been automated and uploaded on the DREAM website. For this publication, a sample output for the river flow during Typhoon Carina is provided, since the model was calibrated from this event. The sample generated map of the Pagsangahan River using the calibrated HEC-HMS model for Typhoon Carina is presented in Figure 64.

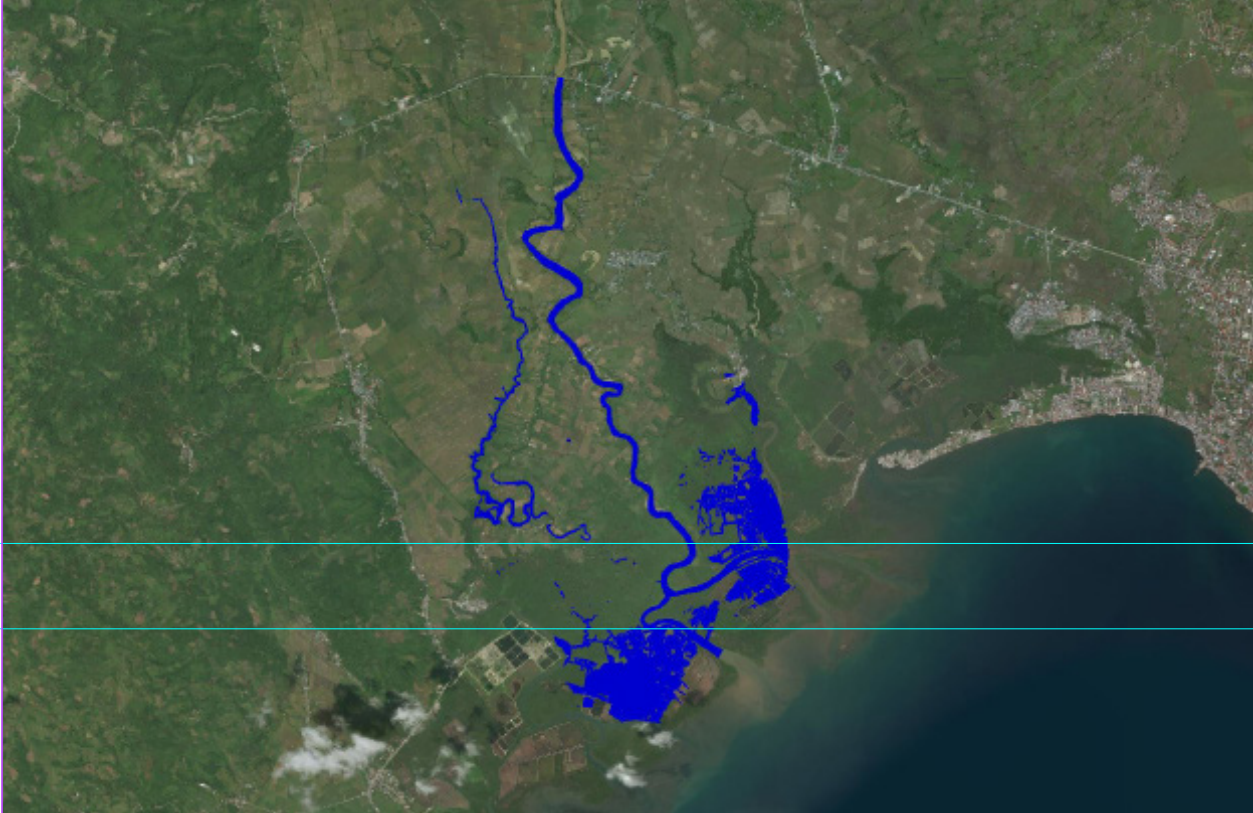


Figure 64. Sample output map of the Pagsangahan RAS Model

## 5.9 Flow Depth and Flood Hazard

The resulting flood hazard and flow depth maps for the 5-year, 25-year, and 100-year rain return scenarios of the Pagsangahan floodplain are exhibited in Figure 65 to 70. The floodplain, with an area of 96.71 sq. km., covers four (4) municipalities, namely Matag-Ob, Merida, Ormoc City, and Palompon. Table 44 enumerates the percentage of area affected by flooding per municipality.

Table 44. Municipalities affected in the Pagsangahan floodplain

City / Municipality	Total Area	Area Flooded	% Flooded
Matag-Ob	63.4592	2.334299	367.84%
Merida	101.477	13.51544	1331.87%
Ormoc City	451.96	80.6196	1783.78%
Palompon	125.866	0.113434	9.01%

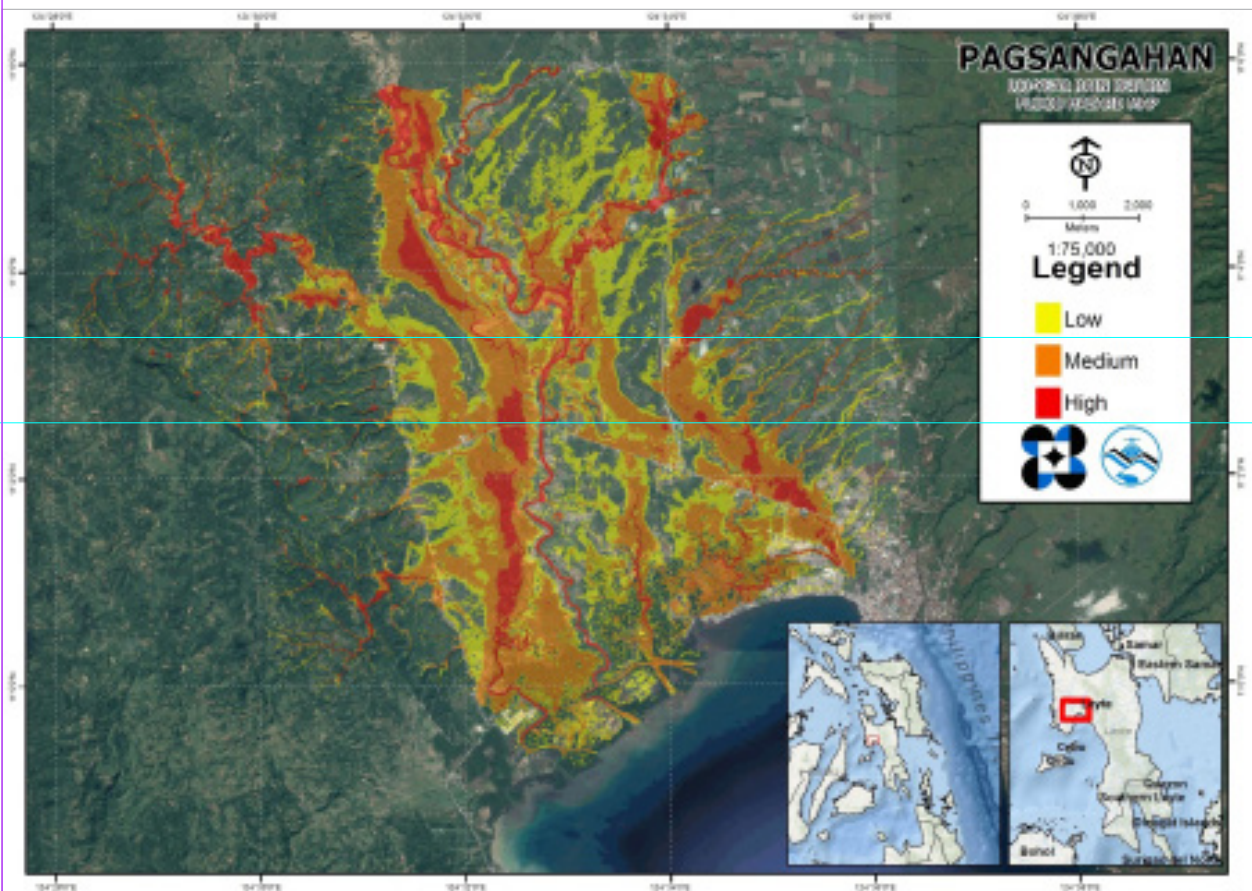


Figure 65. 100-year flood hazard map for the Pagsangahan floodplain

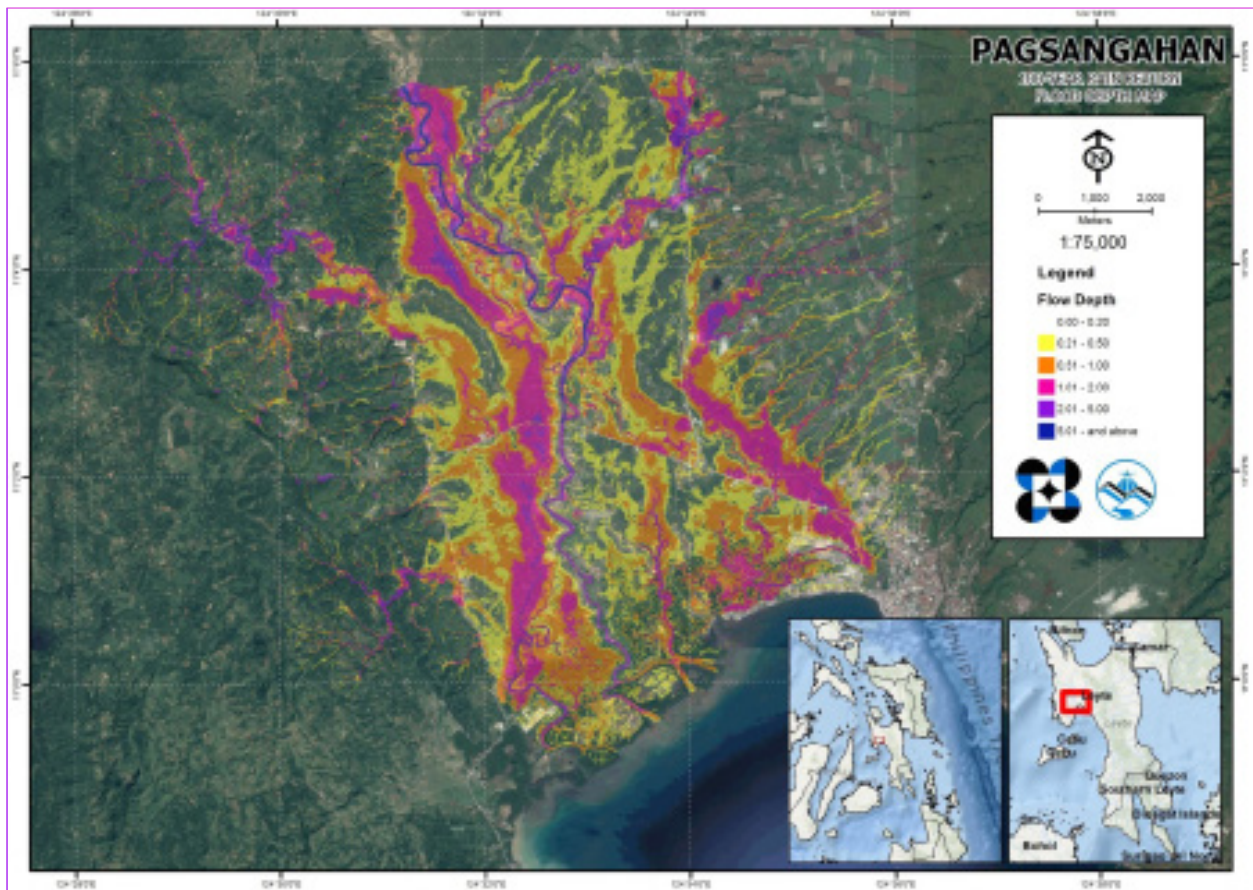


Figure 66. 100-year flow depth map for the Pagsangahan floodplain

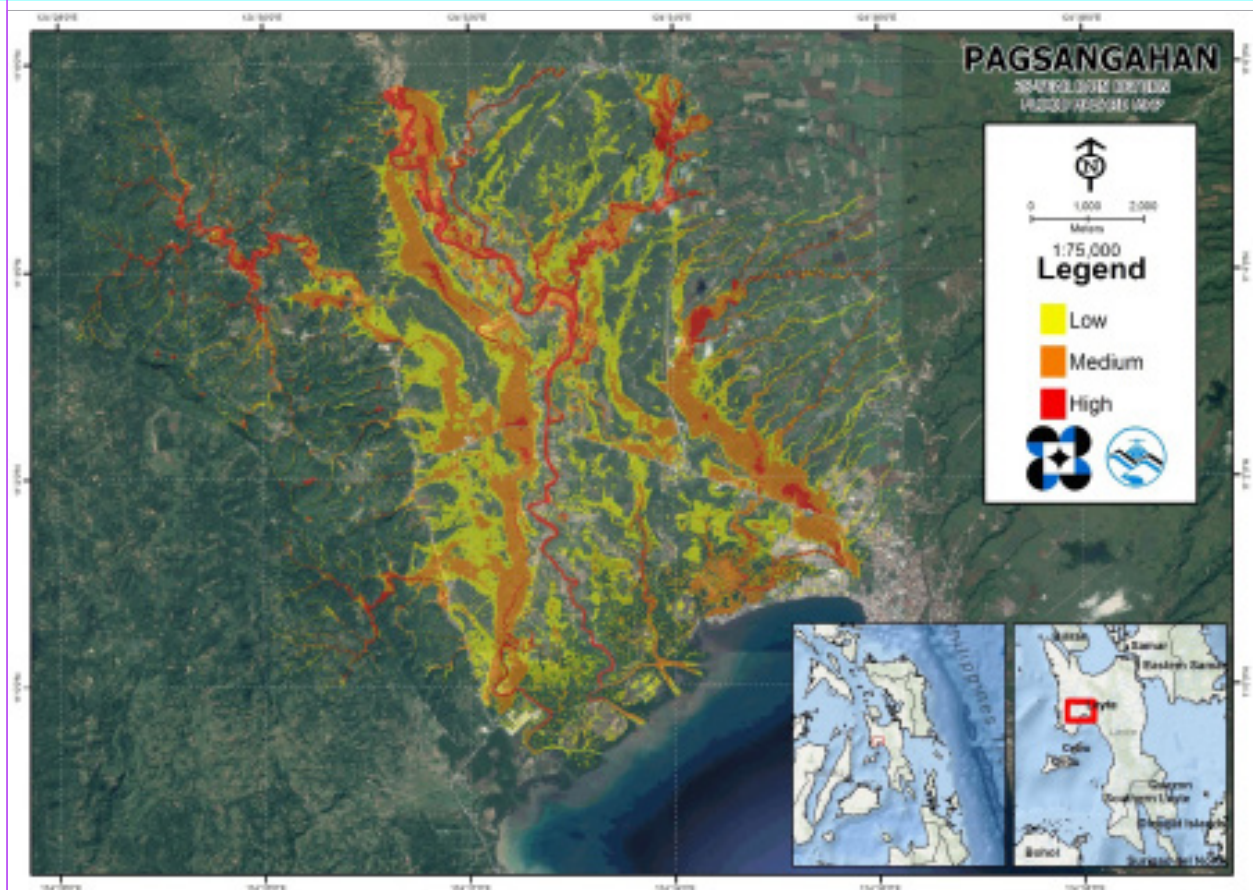


Figure 67. 25-year flood hazard map for the Pagsangahan floodplain

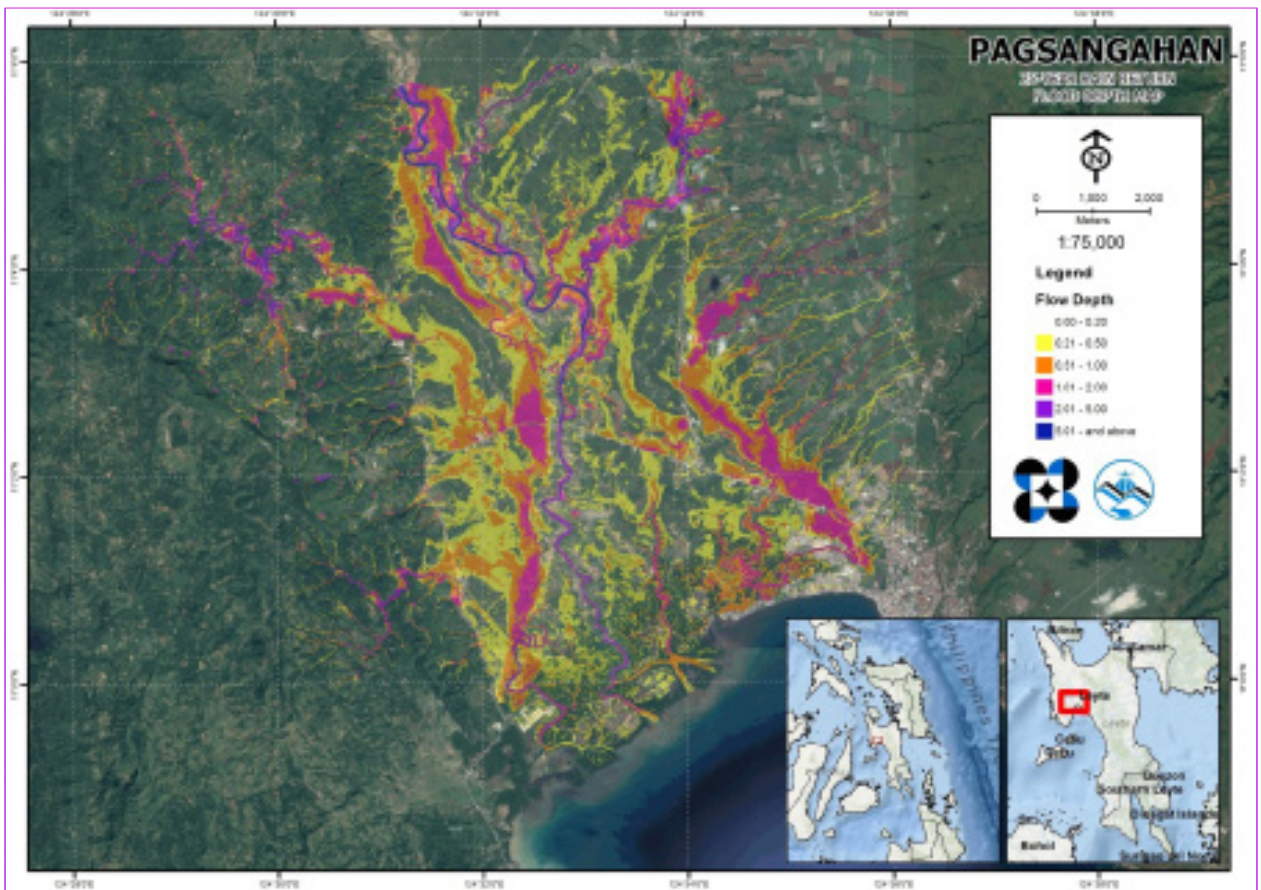


Figure 68. 25-year flow depth map for the Pagsangahan floodplain

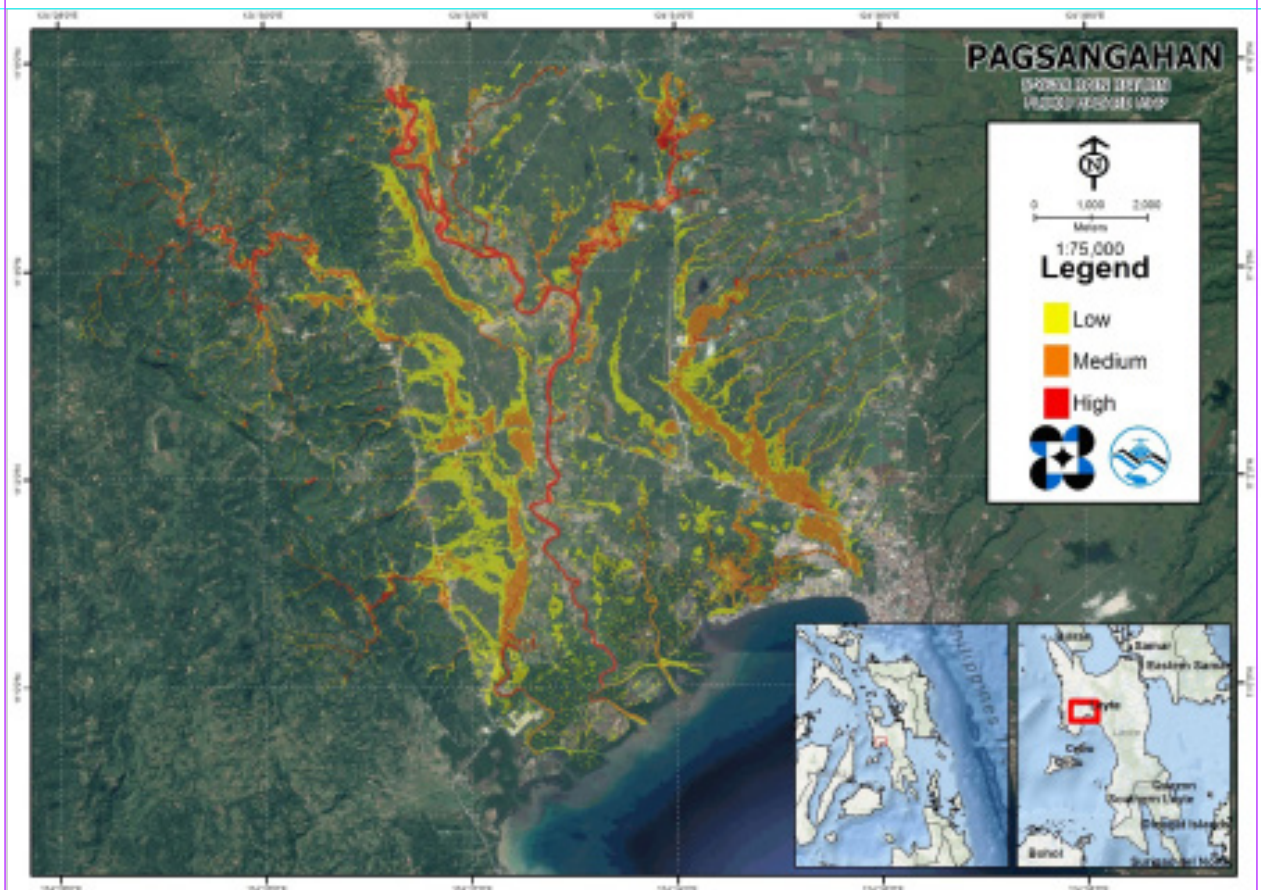


Figure 69. 5-year flood hazard map for the Pagsangahan floodplain



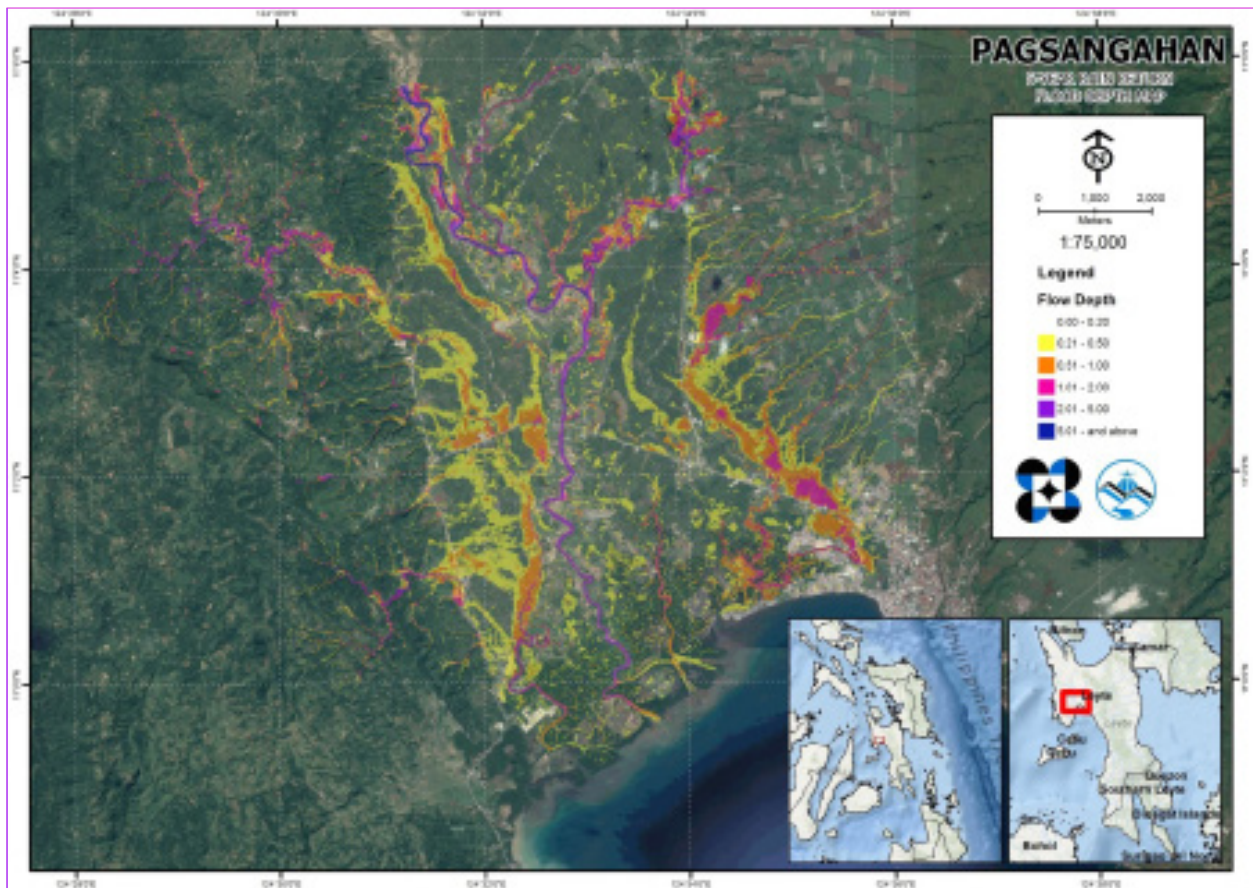


Figure 70. 5-year flow depth map for the Pagsangahan floodplain

### 5.10 Inventory of Areas Exposed to Flooding

Listed below are the barangays affected in the Pagsangahan River Basin, grouped accordingly by municipality. For the said basin, four (4) municipalities consisting of thirty (30) barangays are expected to experience flooding when subjected to a 5-year rainfall return period.

For the 5-year return period, 3.50% of the Municipality of Matag-Ob, with an area of 63.46 sq. km., will experience flood levels of less than 0.20 meters. 0.09% of the area will experience flood levels of 0.21 to 0.50 meters. Meanwhile, 0.05%, 0.03%, and 0.01% of the area will experience flood depths of 0.51 to 1 meter, 1.01 to 2 meters, and more than 2 meters, respectively. Table 45 depicts the areas affected in Matag-Ob, in square kilometers, by flood depth per barangay.

Table 45. Affected areas in Matag-Ob, Leyte during a 5-year rainfall return period

Affected area (sq. km.) by flood depth (in m.)	Area of affected barangays in Matag-Ob (in sq. km.)
	Santa Rosa
0.03-0.20	2.22
0.21-0.50	0.059
0.51-1.00	0.032
1.01-2.00	0.019
2.01-5.00	0.0082
> 5.00	0

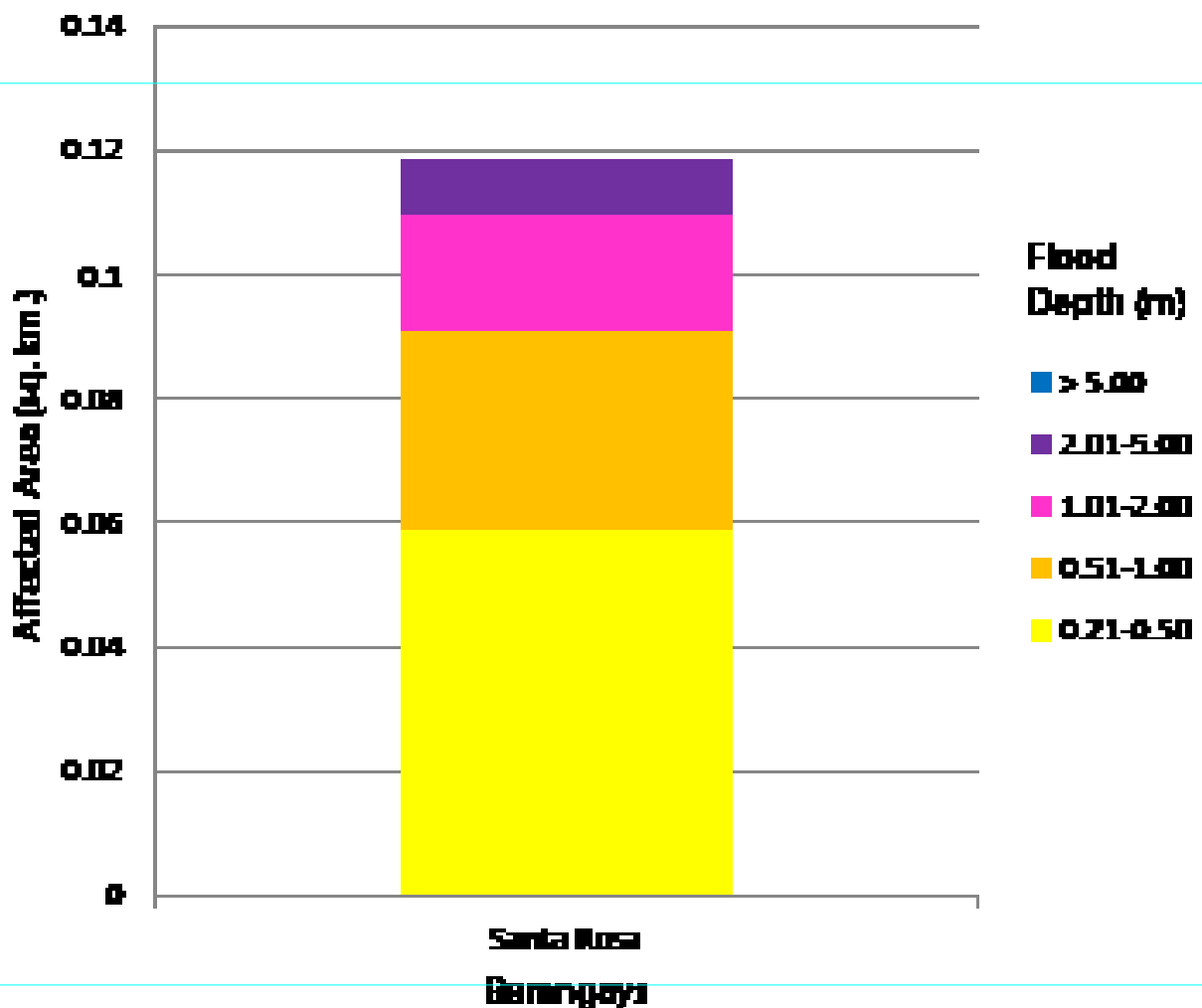


Figure 71. Affected areas in Matag-Ob, Leyte during a 5-year rainfall return period

For the Municipality of Merida, with an area of 101.48 sq. km., 12.38% will experience flood levels of less than 0.20 meters. 0.44% of the area will experience flood levels of 0.21 to 0.50 meters. Meanwhile, 0.22%, 0.18%, 0.10%, and 0.002% of the area will experience flood depths of 0.51 to 1 meter, 1.01 to 2 meters, 2.01 to 5 meters, and more than 5 meters, respectively.

[ ] depicts the affected areas, in square kilometers, by flood depth per barangay.

Table 46. Affected areas in Merida, Leyte during a 5-year rainfall return period

Affected area (sq. km.) by flood depth (in m.)	Area of affected barangays in Merida (in sq. km.)	
	Cabaliwan	Mahayag
0.03-0.20	5.91	6.65
0.21-0.50	0.22	0.23
0.51-1.00	0.11	0.11
1.01-2.00	0.093	0.089
2.01-5.00	0.049	0.052
> 5.00	0	0.002

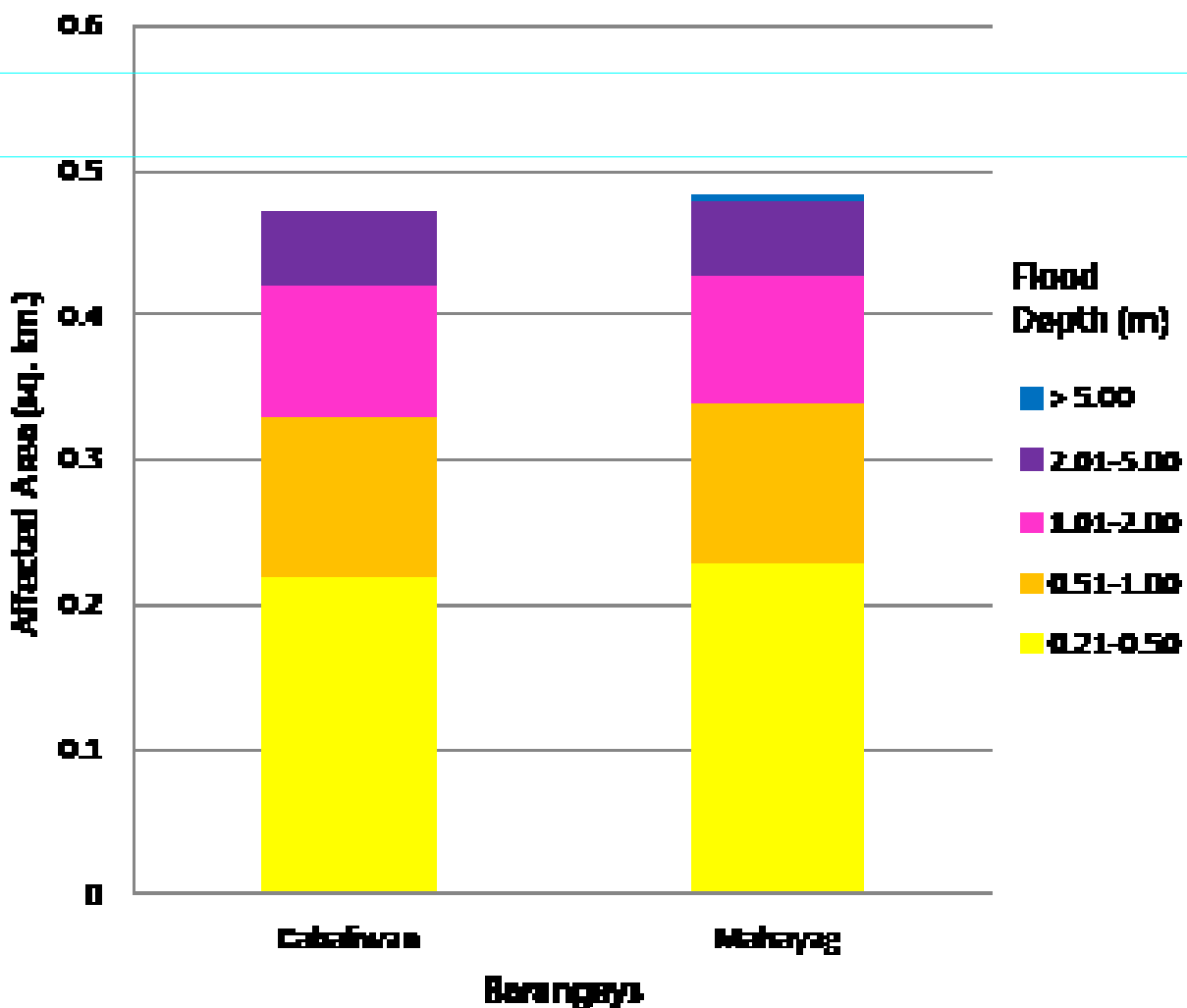


Figure 72. Affected areas in Merida, Leyte during a 5-year rainfall return period

For the Municipality of Ormoc City, with an area of 451.96 sq. km., 9.14% will experience flood levels of less than 0.20 meters. 2.23% of the area will experience flood levels of 0.21 to 0.50 meters. Meanwhile, 2.45%, 2.47%, 1.41%, and 0.16% of the area will experience flood depths of 0.51 to 1 meter, 1.01 to 2 meters, 2.01 to 5 meters, and more than 5 meters, respectively. Tables 47-49 depict the affected areas, in square kilometers, by flood depth per barangay.

Table 47. Affected areas in Ormoc City, Leyte during a 5-year rainfall return period

Affected area (sq. km.) by flood depth (in m.)	Area of affected barangays in Ormoc City (in sq. km.)							
	Airport	Bayog	Catmon	Curva	Domonar	Esperanza	Green Valley	Guintigui-An
0.03-0.20	1.11	0.19	1.56	2.08	0.44	5.35	1.4	0.039
0.21-0.50	0.16	0.14	0.2	0.36	0.16	0.27	0.37	0.0001
0.51-1.00	0.066	0.22	0.24	0.093	0.35	0.23	0.27	0
1.01-2.00	0.097	0.27	0.24	0.027	0.9	0.32	0.59	0
2.01-5.00	0.1	0.44	0.12	0.015	0.42	0.23	1.04	0
> 5.00	0.0045	0.024	0.0011	0	0.079	0	0.032	0

Table 48. Affected areas in Ormoc City, Leyte during a 5-year rainfall return period

Affected area (sq. km.) by flood depth (in m.)	Area of affected barangays in Ormoc City (in sq. km.)							
	Labrador	Lao	Leondoni	Libertad	Licama	Liloan	Mabato	Manlilinao
0.03-0.20	1.41	1.89	0.57	2.2	2.4	1.37	0.46	2.26
0.21-0.50	0.47	0.68	0.088	0.64	0.64	2.49	0.64	0.076
0.51-1.00	0.47	0.71	0.08	1.16	0.13	2.96	1.2	0.063
1.01-2.00	0.35	0.63	0.17	0.4	0.04	2.75	1.46	0.074
2.01-5.00	0.19	0.096	0.4	0.0008	0.0078	1.2	0.72	0.031
> 5.00	0.029	0.001	0.097	0	0.0021	0.21	0	0.0002

Table 49. Affected areas in Ormoc City, Leyte during a 5-year rainfall return period

Affected area (sq. km.) by flood depth (in m.)	Area of affected barangays in Ormoc City (in sq. km.)								
	Margen	Mas-In	Nasunogan	Nueva Sociedad	Rufina M. Tan	Sabang Bao	San Jose	San Juan	San Vicente
0.03-0.20	1.97	2.41	0.49	1.92	0.64	0.85	3.42	1.21	3.65
0.21-0.50	0.6	0.28	0.068	0.065	0.06	0.62	0.3	0.56	0.15
0.51-1.00	0.35	0.24	0.005	0.027	0.047	0.88	0.038	1.18	0.077
1.01-2.00	0.36	0.11	0.0059	0.015	0.24	0.63	0.017	1.41	0.041
2.01-5.00	0.23	0.0067	0.0043	0.0032	0.45	0.4	0.0017	0.24	0.0095
> 5.00	0	0	0	0	0.11	0.13	0	0	0.0001

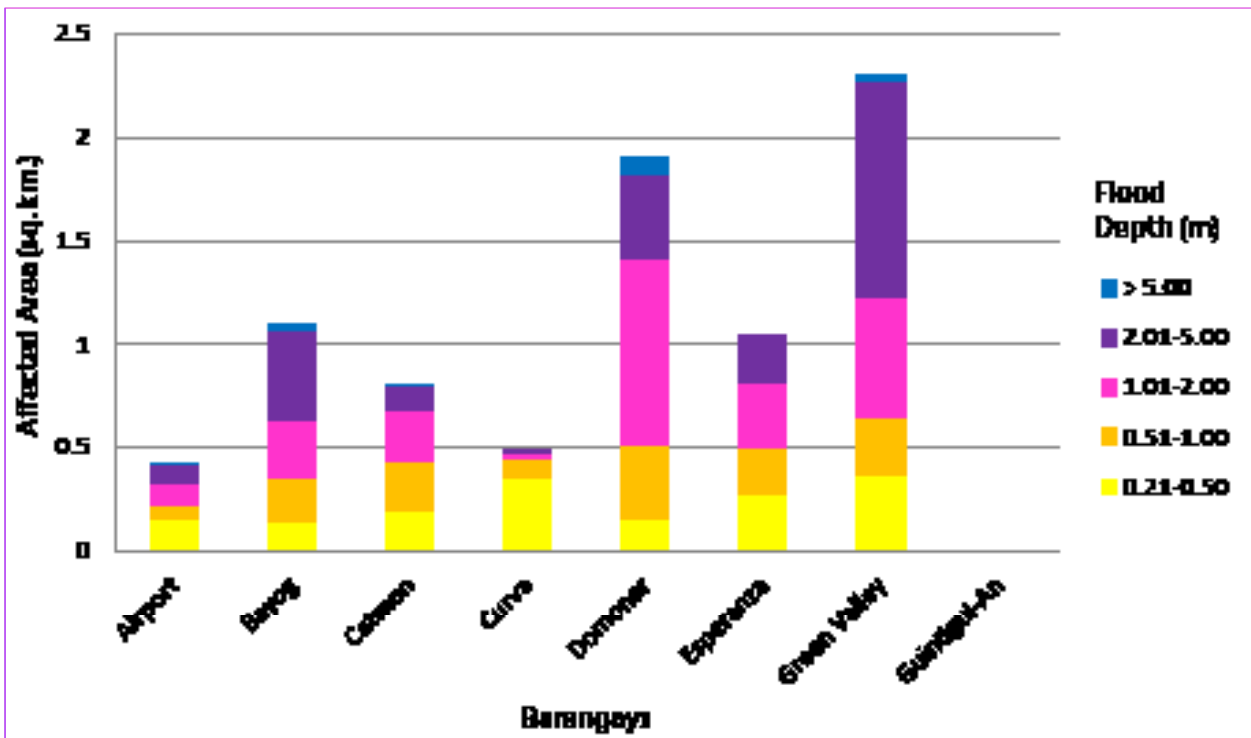


Figure 73. Affected areas in Ormoc City, Leyte during a 5-year rainfall return period

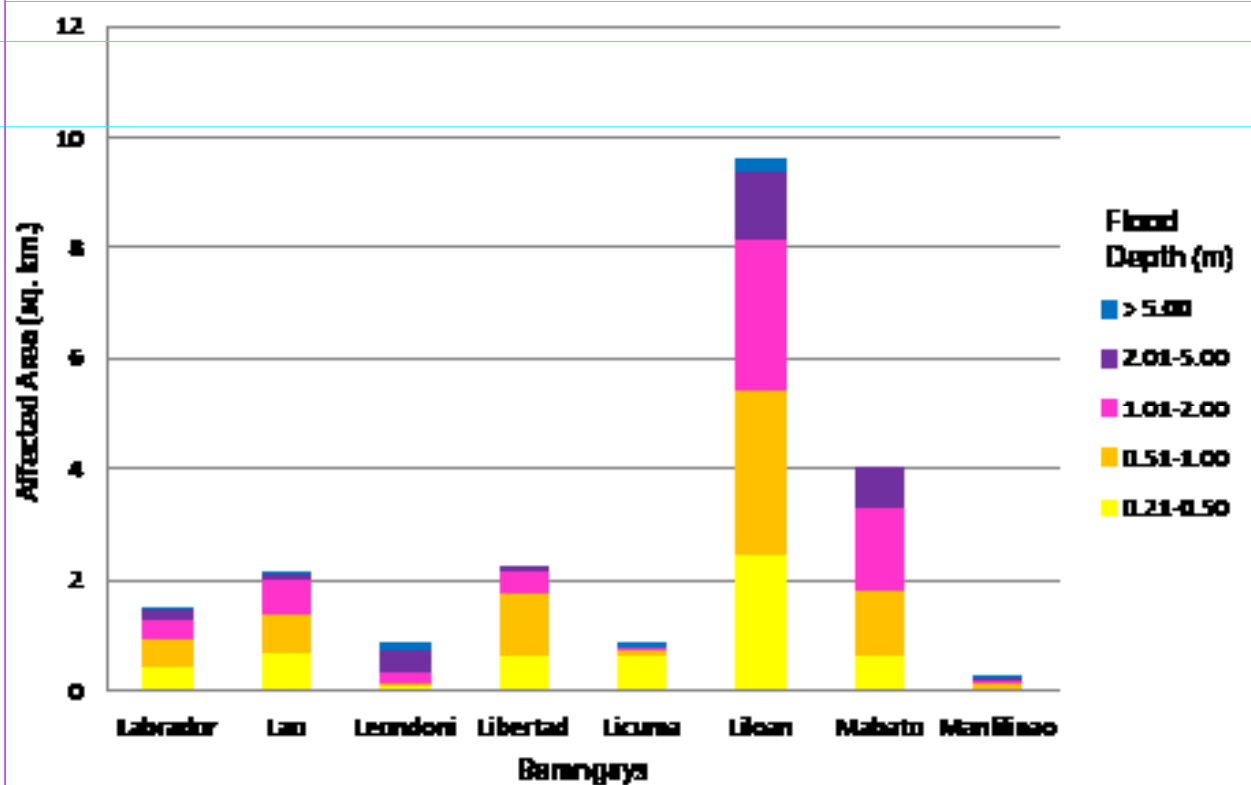


Figure 74. Affected areas in Ormoc City, Leyte during a 5-year rainfall return period

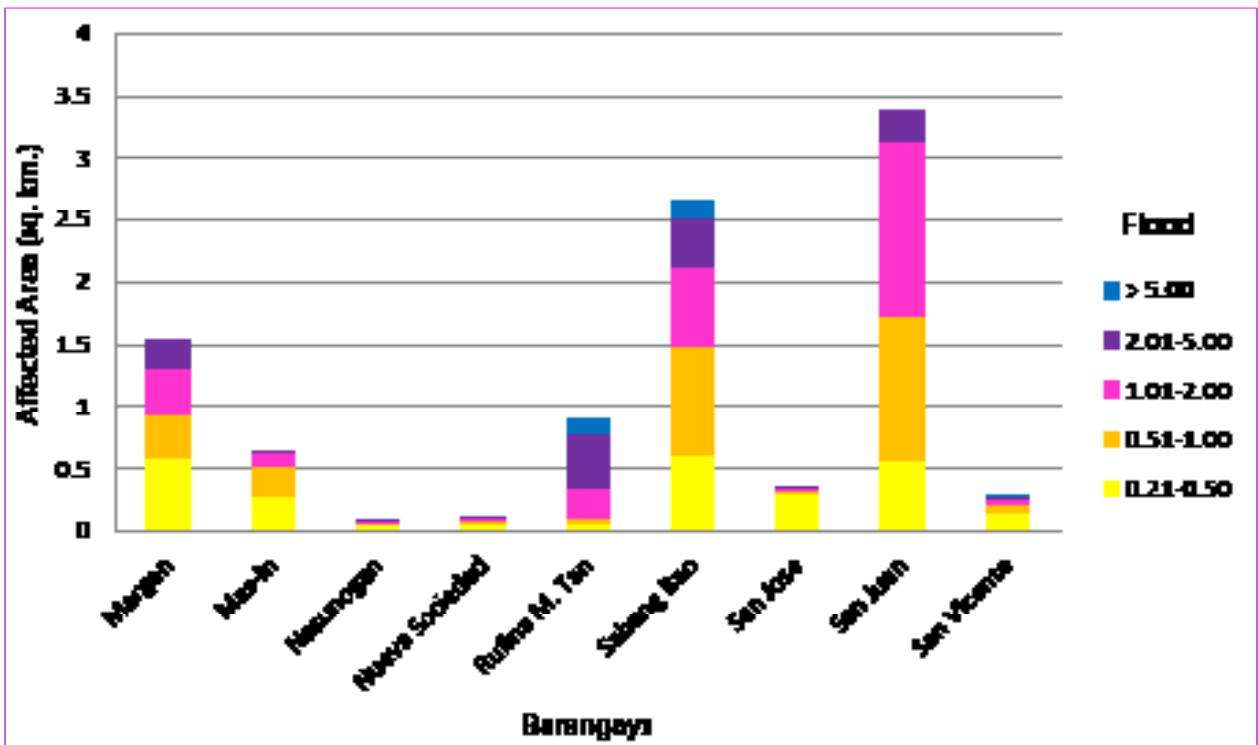


Figure 75. Affected areas in Ormoc City, Leyte during a 5-year rainfall return period

For the Municipality of Palompon, with an area of 125.87 sq. km., 0.09% will experience flood levels of less than 0.20 meters. 0.001% of the area will experience flood levels of 0.21 to 0.50 meters, and 0.0001% of the area will experience flood depths of 0.51 to 1 meter. Table 50 depicts the affected areas, in square kilometers, by flood depth per barangay.

Table 50. Affected areas in Palompon, Leyte during a 5-year rainfall return period

Affected area (sq. km.) by flood depth (in m.)	Area of affected barangays in Palompon (in sq. km.)	
	Cambakbak	Mabini
0.03-0.20	0.043	0.069
0.21-0.50	0.00016	0.0016
0.51-1.00	0.000013	0.00015
1.01-2.00	0	0
2.01-5.00	0	0
> 5.00	0	0

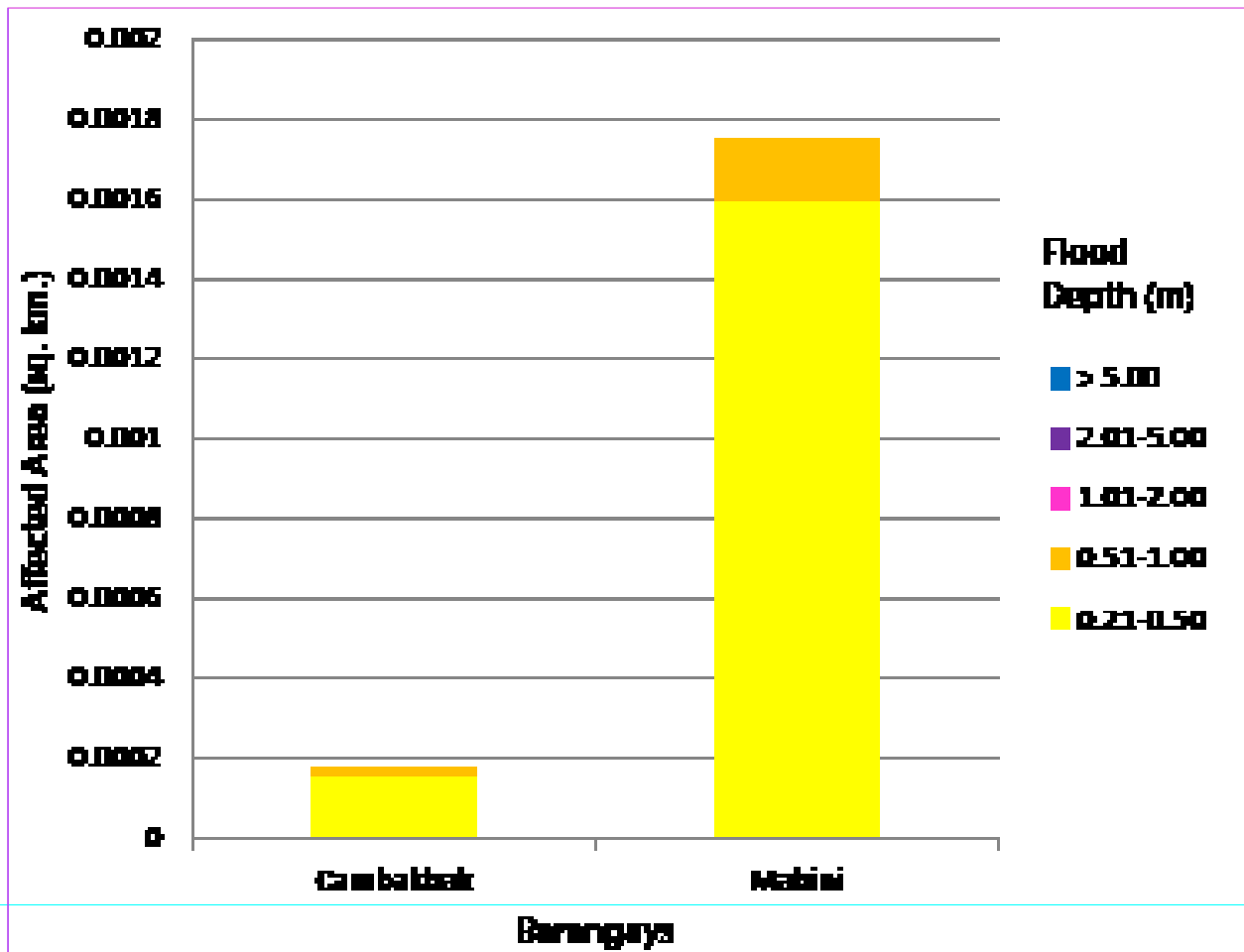


Figure 76. Affected areas in Palompon, Leyte during a 5-year rainfall return period

For the 25-year return period, 3.44% of the Municipality of Matag-Ob, with an area of 63.46 sq. km., will experience flood levels of less than 0.20 meters, while 0.11% of the area will experience flood levels of 0.21 to 0.50 meters. Meanwhile, 0.07%, 0.04%, 0.02%, and 0.0005% of the area will experience flood depths of 0.51 to 1 meter, 1.01 to 2 meters, 2.01 to 5 meters, and more than 5 meters, respectively. Table 51 depicts the areas affected in Matag-Ob, in square kilometers, by flood depth per barangay.

Table 51. Affected areas in Matag-Ob, Leyte during a 25-year rainfall return period

Affected area (sq. km.) by flood depth (in m.)	Area of affected barangays in Matag-Ob (in sq. km.)
	Santa Rosa
0.03-0.20	2.18
0.21-0.50	0.072
0.51-1.00	0.042
1.01-2.00	0.027
2.01-5.00	0.013
> 5.00	0.0003

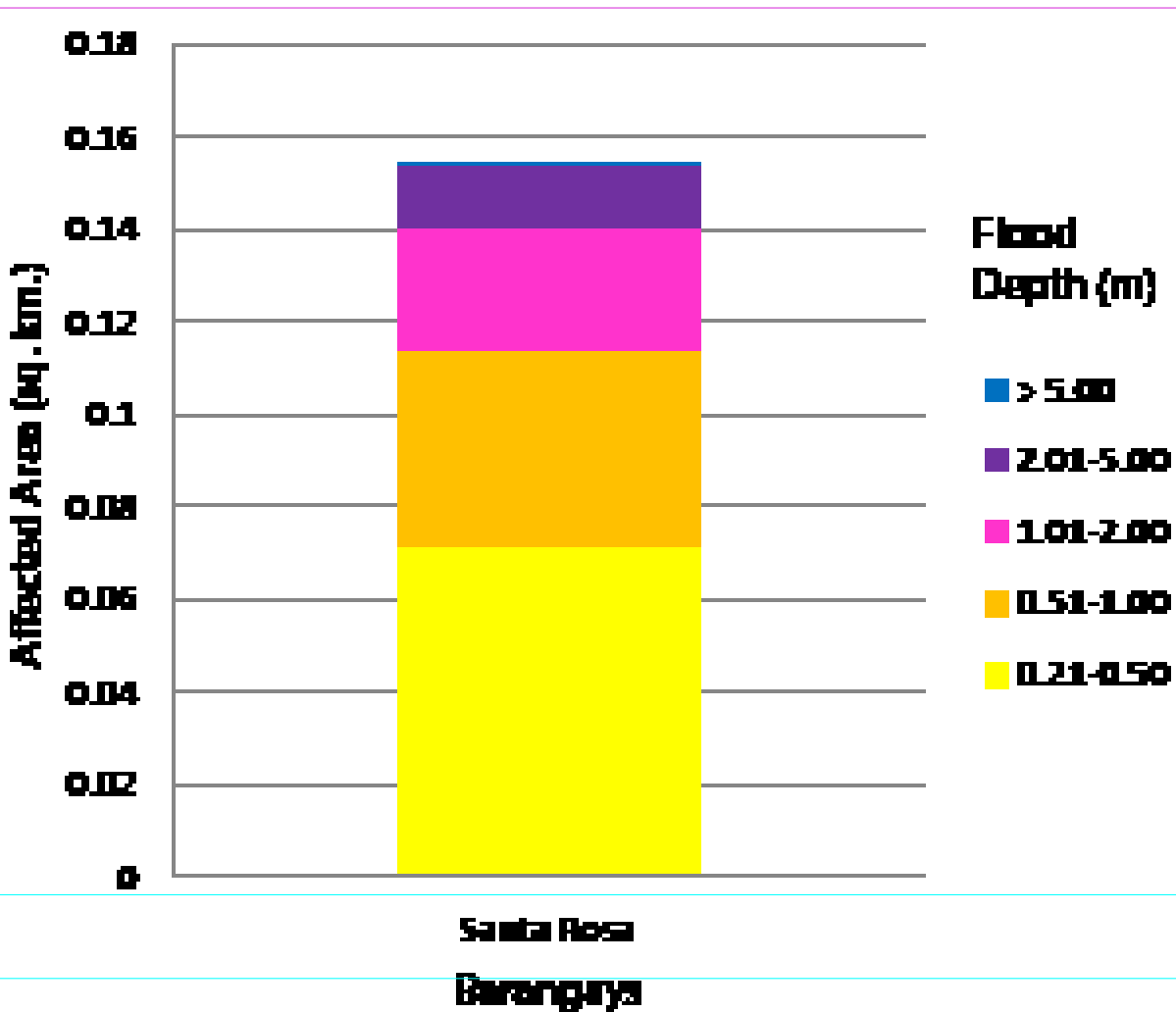


Figure 77. Affected areas in Matag-Ob, Leyte during a 25-year rainfall return period

For the Municipality of Merida, with an area of 101.48 sq. km., 12.09% will experience flood levels of less than 0.20 meters. 0.53% of the area will experience flood levels of 0.21 to 0.50 meters. Meanwhile, 0.29%, 0.21%, 0.18%, and 0.006% of the area will experience flood depths of 0.51 to 1 meter, 1.01 to 2 meters, 2.01 to 5 meters, and more than 5 meters, respectively. Table 52 depicts the affected areas, in square kilometers, by flood depth per barangay.

Table 52. Affected areas in Merida, Leyte during a 25-year rainfall return period

Affected area (sq. km.) by flood depth (in m.)	Area of affected barangays in Merida (in sq. km.)	
	Cabaliwan	Mahayag
0.03-0.20	5.77	6.5
0.21-0.50	0.26	0.28
0.51-1.00	0.14	0.15
1.01-2.00	0.11	0.1
2.01-5.00	0.091	0.091
> 5.00	0.0005	0.0057



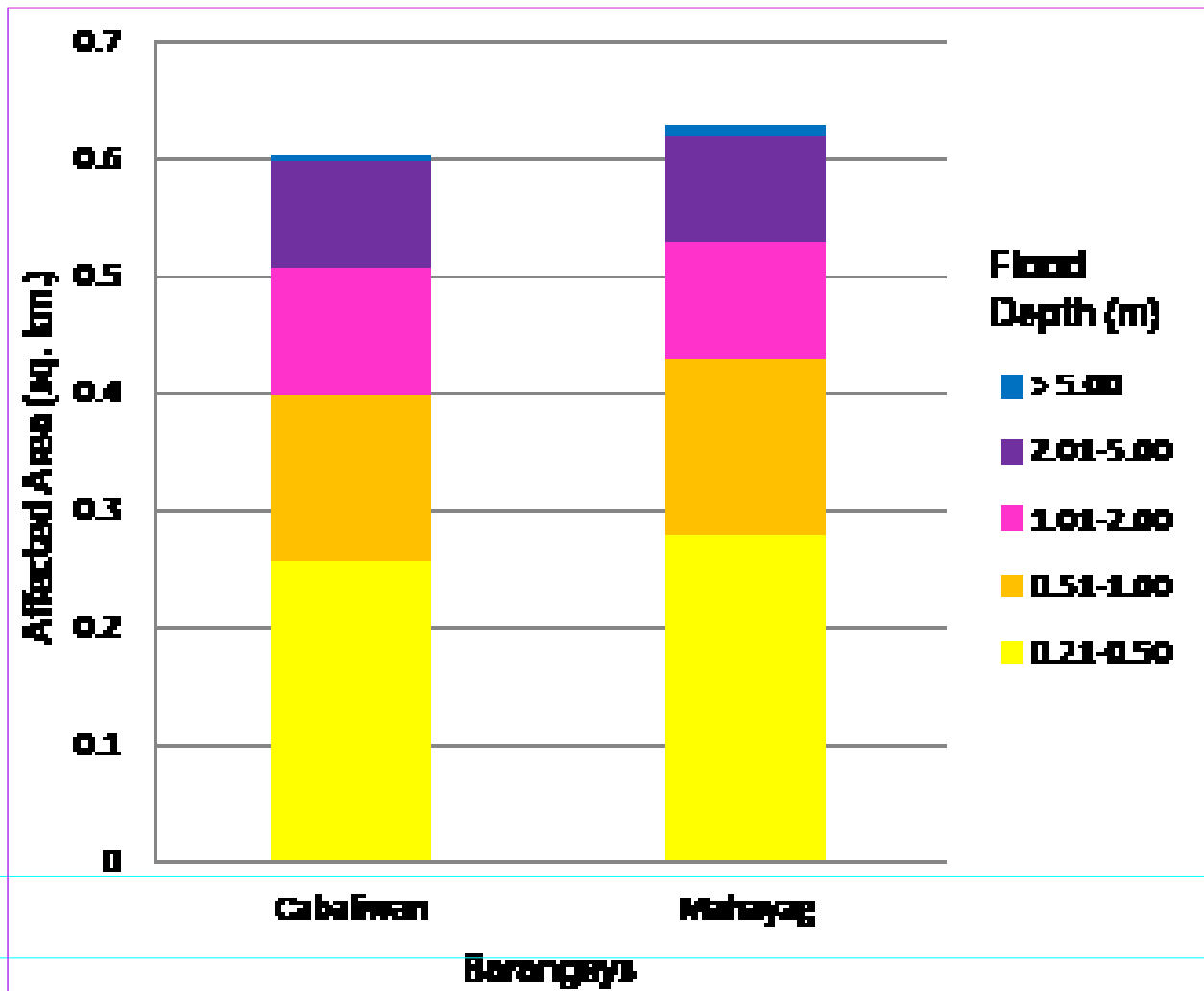


Figure 78. Affected areas in Merida, Leyte during a 25-year rainfall return period

For the Municipality of Ormoc City, with an area of 451.96 sq. km., 7.19% will experience flood levels of less than 0.20 meters. 1.78% of the area will experience flood levels of 0.21 to 0.50 meters. Meanwhile, 2.32%, 4.06%, 2.27%, and 0.22% of the area will experience flood depths of 0.51 to 1 meter, 1.01 to 2 meters, 2.01 to 5 meters, and more than 5 meters, respectively. Tables 53-55 depict the affected areas, in square kilometers, by flood depth per barangay.

Table 53. Affected areas in Ormoc City, Leyte during a 25-year rainfall return period

Affected area (sq. km.) by flood depth (in m.)	Area of affected barangays in Ormoc City (in sq. km.)							
	Airport	Bayog	Catmon	Curva	Domonar	Esperanza	Green Valley	Guintigui-An
0.03-0.20	0.73	0.042	1.15	1.72	0.23	5.01	1.21	0.039
0.21-0.50	0.33	0.037	0.36	0.48	0.19	0.23	0.28	0.00021
0.51-1.00	0.21	0.089	0.21	0.29	0.19	0.28	0.33	0
1.01-2.00	0.12	0.44	0.37	0.05	0.85	0.4	0.42	0
2.01-5.00	0.14	0.62	0.25	0.03	0.81	0.45	1.4	0
> 5.00	0.018	0.055	0.011	0.0002	0.086	0.016	0.043	0

Table 54. Affected areas in Ormoc City, Leyte during a 25-year rainfall return period

Affected area (sq. km.) by flood depth (in m.)	Area of affected barangays in Ormoc City (in sq. km.)							
	Labrador	Lao	Leondoni	Libertad	Licuma	Liloan	Mabato	Manlilinao
0.03-0.20	0.56	0.88	0.38	1.42	2.06	0.21	0.19	2.21
0.21-0.50	0.71	0.76	0.11	0.56	0.7	0.53	0.23	0.08
0.51-1.00	0.5	1.01	0.098	0.69	0.36	2.43	0.89	0.066
1.01-2.00	0.79	1.23	0.15	1.68	0.08	5.49	1.85	0.089
2.01-5.00	0.32	0.12	0.48	0.036	0.016	2.08	1.32	0.063
> 5.00	0.039	0.0006	0.17	0	0.0027	0.23	0.0005	0.0008

Table 55. Affected areas in Ormoc City, Leyte during a 25-year rainfall return period

Affected area (sq. km.) by flood depth (in m.)	Area of affected barangays in Ormoc City (in sq. km.)								
	Margen	Mas-In	Nasunogan	Nueva Sociedad	Rufina M. Tan	Sabang Bao	San Jose	San Juan	San Vicente
0.03-0.20	1.74	2.18	0.45	1.88	0.6	0.21	2.88	0.94	3.56
0.21-0.50	0.5	0.25	0.093	0.087	0.047	0.2	0.58	0.51	0.17
0.51-1.00	0.55	0.29	0.01	0.035	0.043	0.5	0.2	1.09	0.11
1.01-2.00	0.4	0.28	0.0047	0.02	0.07	1.66	0.11	1.75	0.058
2.01-5.00	0.32	0.056	0.0081	0.0082	0.65	0.77	0.022	0.29	0.021
> 5.00	0.0002	0	0	0	0.14	0.16	0	0	0.0001

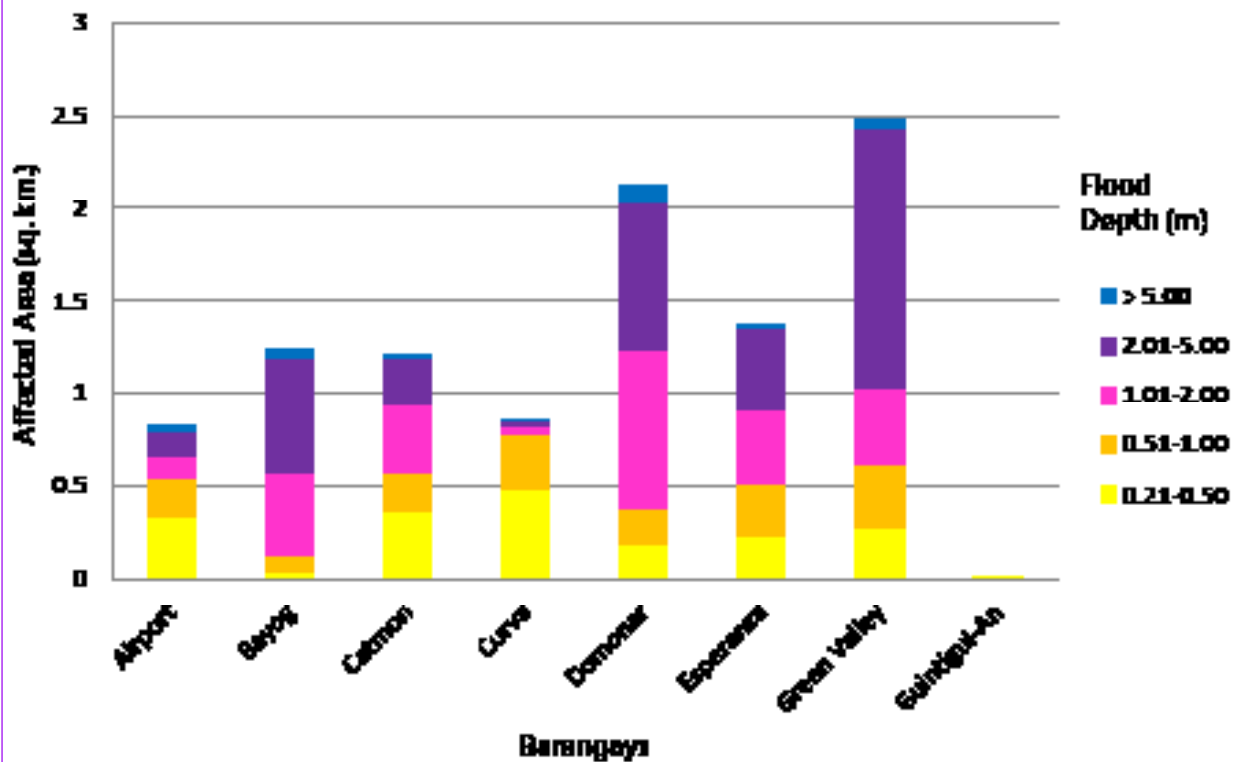


Figure 79. Affected areas in Ormoc City, Leyte during a 25-year rainfall return period

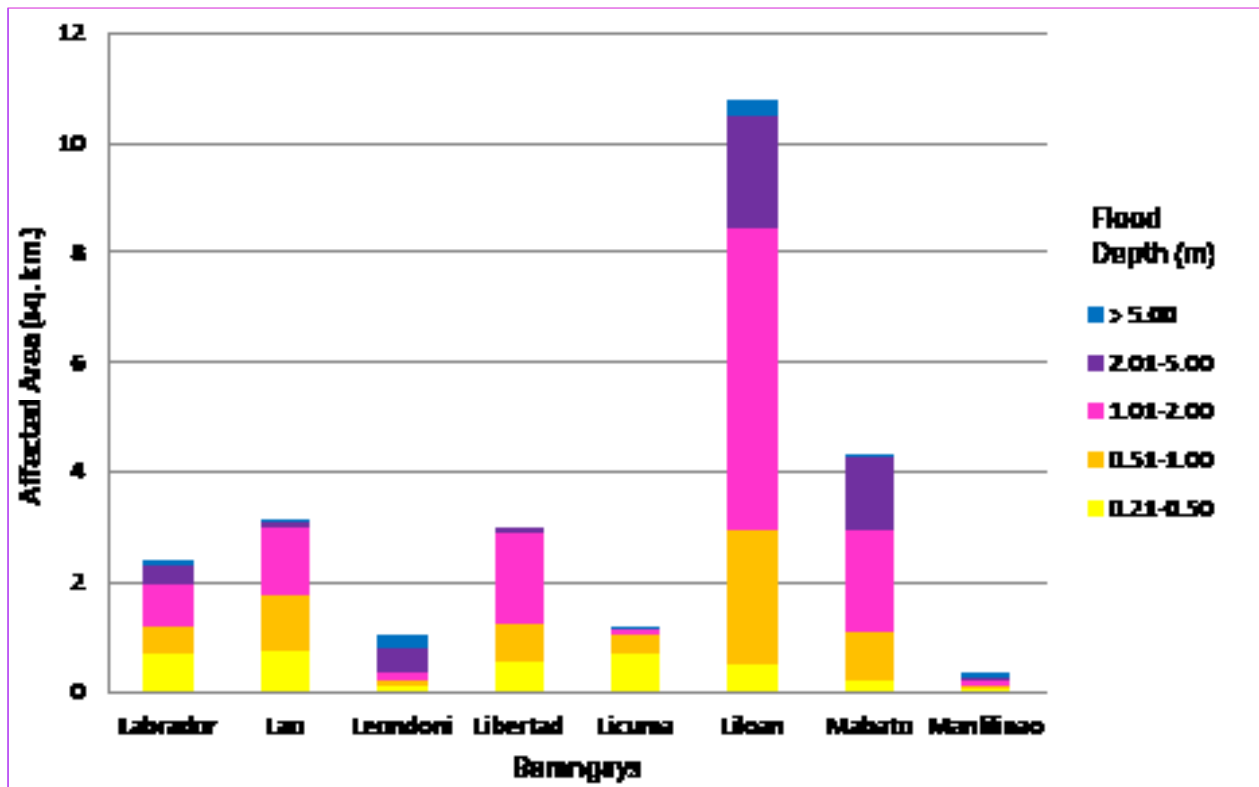


Figure 80. Affected areas in Ormoc City, Leyte during a 25-year rainfall return period

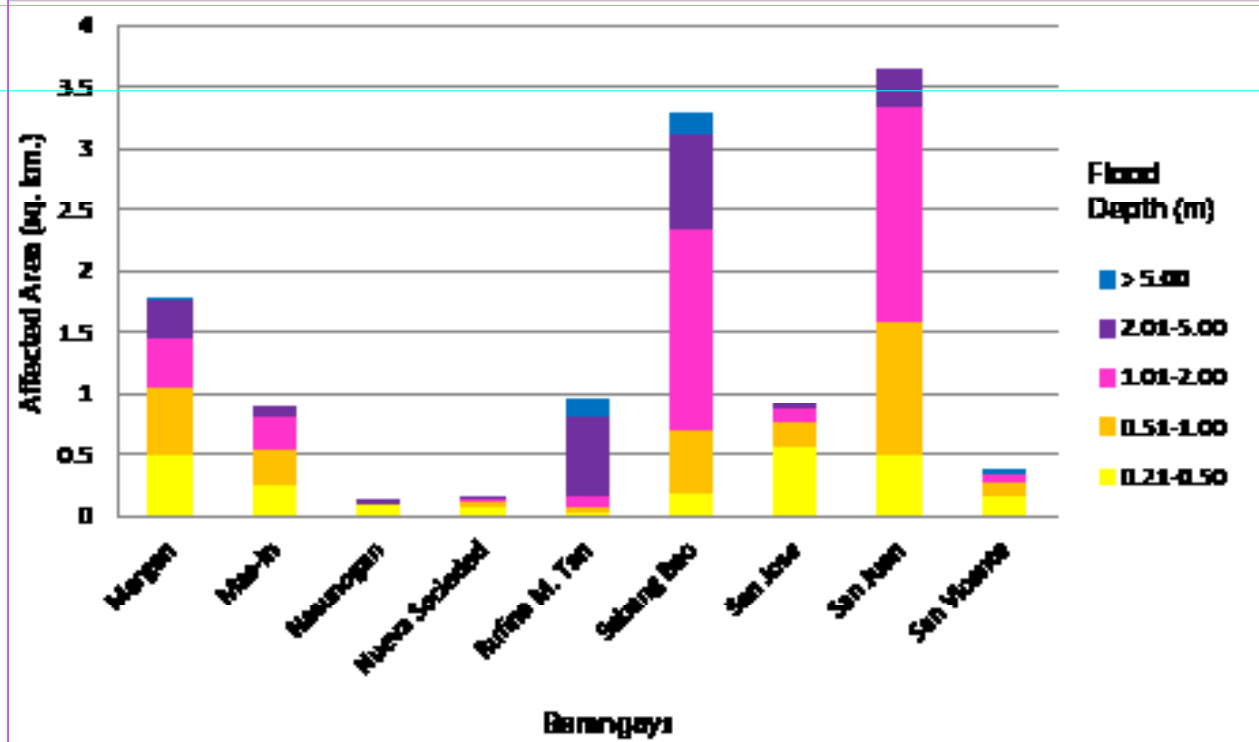


Figure 81. Affected areas in Ormoc City, Leyte during a 25-year rainfall return period

For the Municipality of Palompon, with an area of 125.87 sq. km., 0.09% will experience flood levels of less than 0.20 meters. 0.002% of the area will experience flood levels of 0.21 to 0.50 meters. Meanwhile, 0.0003%, and 0.00002% of the area will experience flood depths of 0.51 to 1 meter, and 1.01 to 2 meters, respectively. Table 56 depicts the affected areas, in square kilometers, by flood depth per barangay.

Table 56. Affected areas in Palompon, Leyte during a 25-year rainfall return period

Affected area (sq. km.) by flood depth (in m.)	Area of affected barangays in Palompon (in sq. km.)	
	Cambakbak	Mabini
0.03-0.20	0.043	0.068
0.21-0.50	0.00037	0.0024
0.51-1.00	0	0.00034
1.01-2.00	0.000013	0.000014
2.01-5.00	0	0
> 5.00	0	0

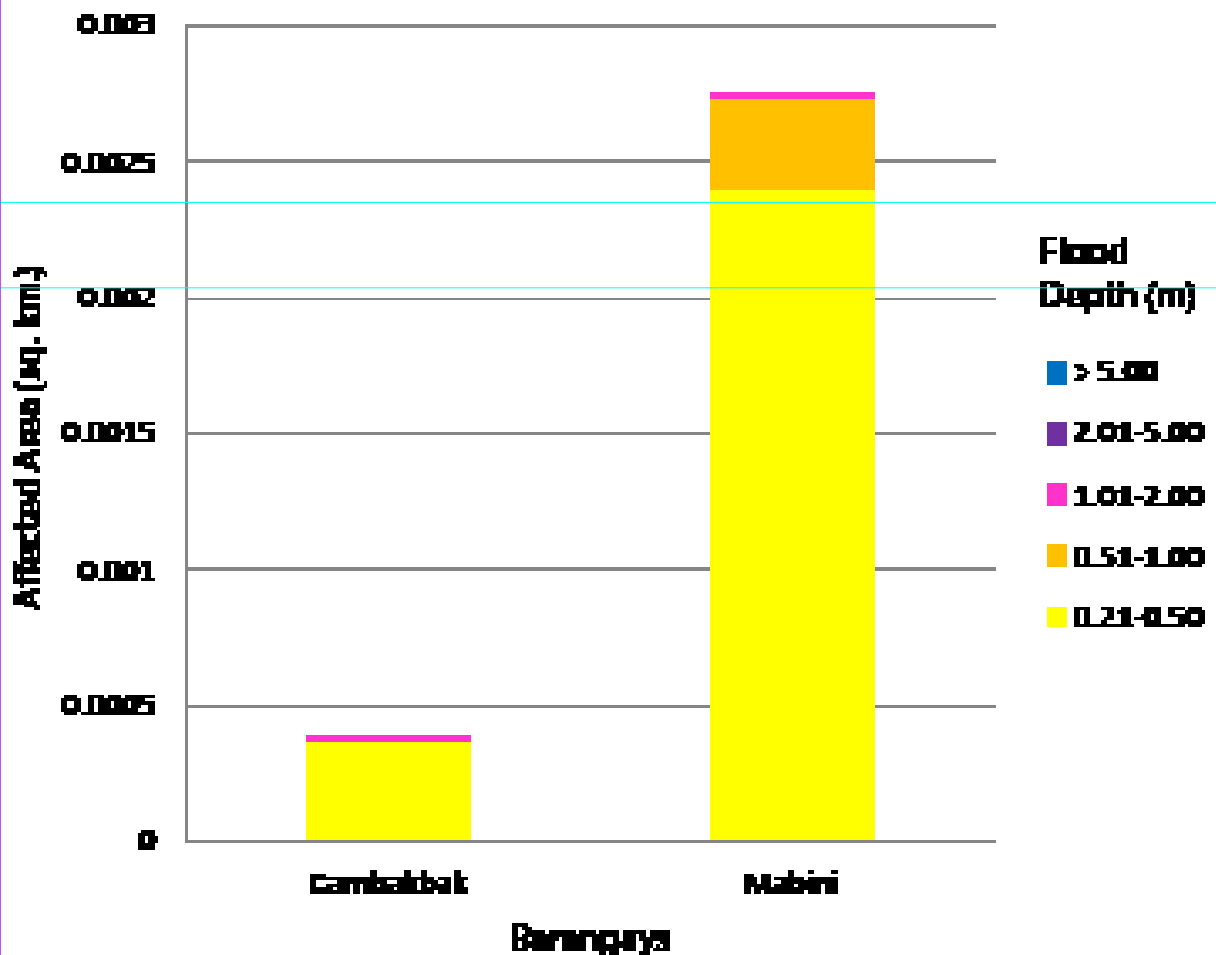


Figure 82. Affected areas in Palompon, Leyte during a 25-year rainfall return period

For the 100-year return period, 3.40% of the Municipality of Matag-Ob, with an area of 63.46 sq. km., will experience flood levels of less than 0.20 meters, while 0.12% of the area will experience flood levels of 0.21 to 0.50 meters. Meanwhile, 0.07%, 0.05%, 0.03%, and 0.0007% of the area will experience flood depths of 0.51 to 1 meter, 1.01 to 2 meters, 2.01 to 5 meters, and more than 5 meters, respectively. Table 57 depicts the areas affected in Matag-Ob, in square kilometers, by flood depth per barangay.

Table 57. Affected areas in Matag-Ob, Leyte during a 100-year rainfall return period

Affected area (sq. km.) by flood depth (in m.)	Area of affected barangays in Matag-Ob (in sq. km.)
	Santa Rosa
0.03-0.20	2.16
0.21-0.50	0.079
0.51-1.00	0.046
1.01-2.00	0.032
2.01-5.00	0.017
> 5.00	0.00047

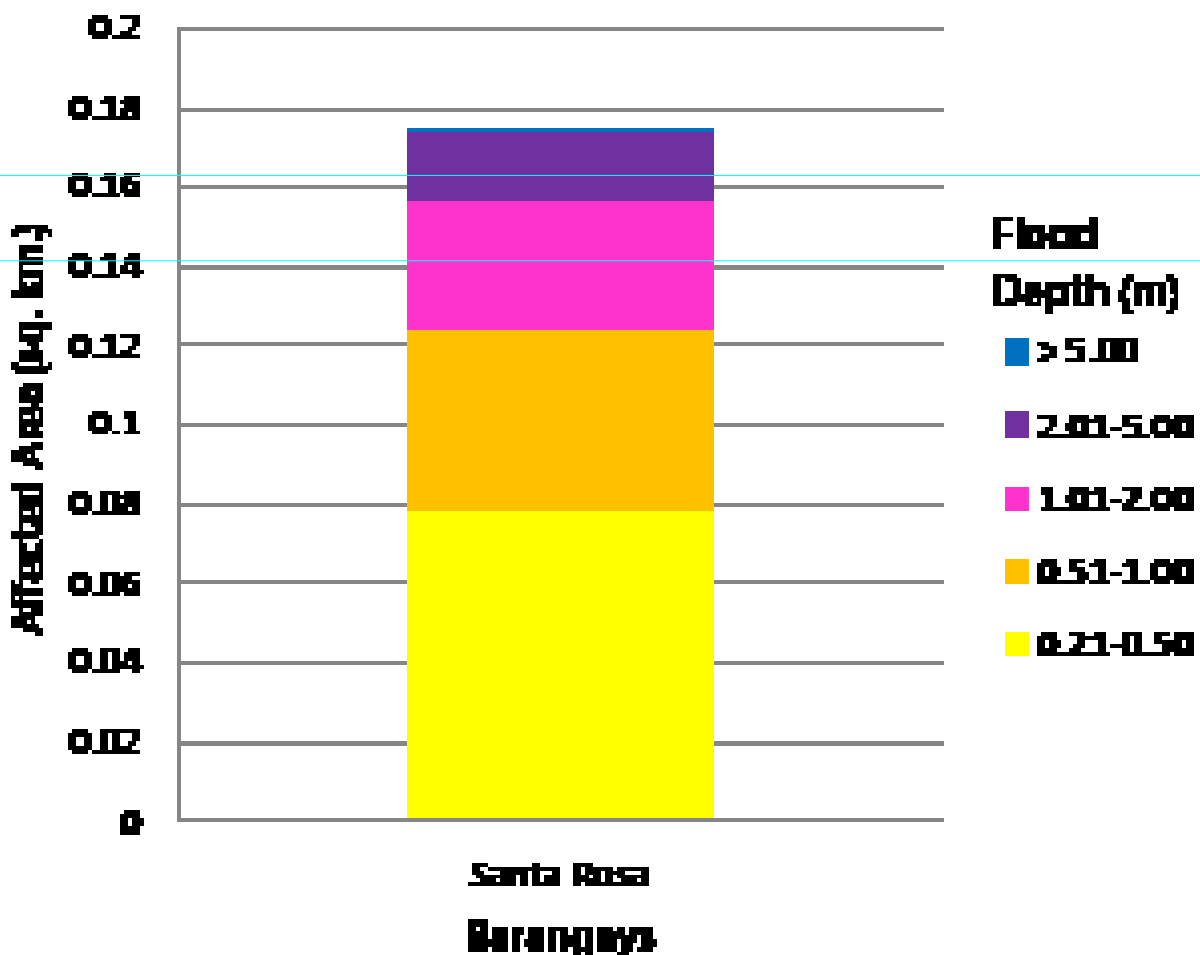


Figure 83. Affected areas in Matag-Ob, Leyte during a 100-year rainfall return period

For the Municipality of Merida, with an area of 101.48 sq. km., 11.93% will experience flood levels of less than 0.20 meters. 0.59% of the area will experience flood levels of 0.21 to 0.50 meters. Meanwhile, 0.33%, 0.23%, 0.23%, and 0.01% of the area will experience flood depths of 0.51 to 1 meter, 1.01 to 2 meters, 2.01 to 5 meters, and more than 5 meters, respectively. Table 58 depicts the affected areas, in square kilometers, by flood depth per barangay.

Table 58. Affected areas in Merida, Leyte during a 25-year rainfall return period

Affected area (sq. km.) by flood depth (in m.)	Area of affected barangays in Merida (in sq. km.)	
	Cabaliwan	Mahayag
0.03-0.20	5.7	6.41
0.21-0.50	0.29	0.31
0.51-1.00	0.16	0.17
1.01-2.00	0.12	0.11
2.01-5.00	0.12	0.11
> 5.00	0.0019	0.011

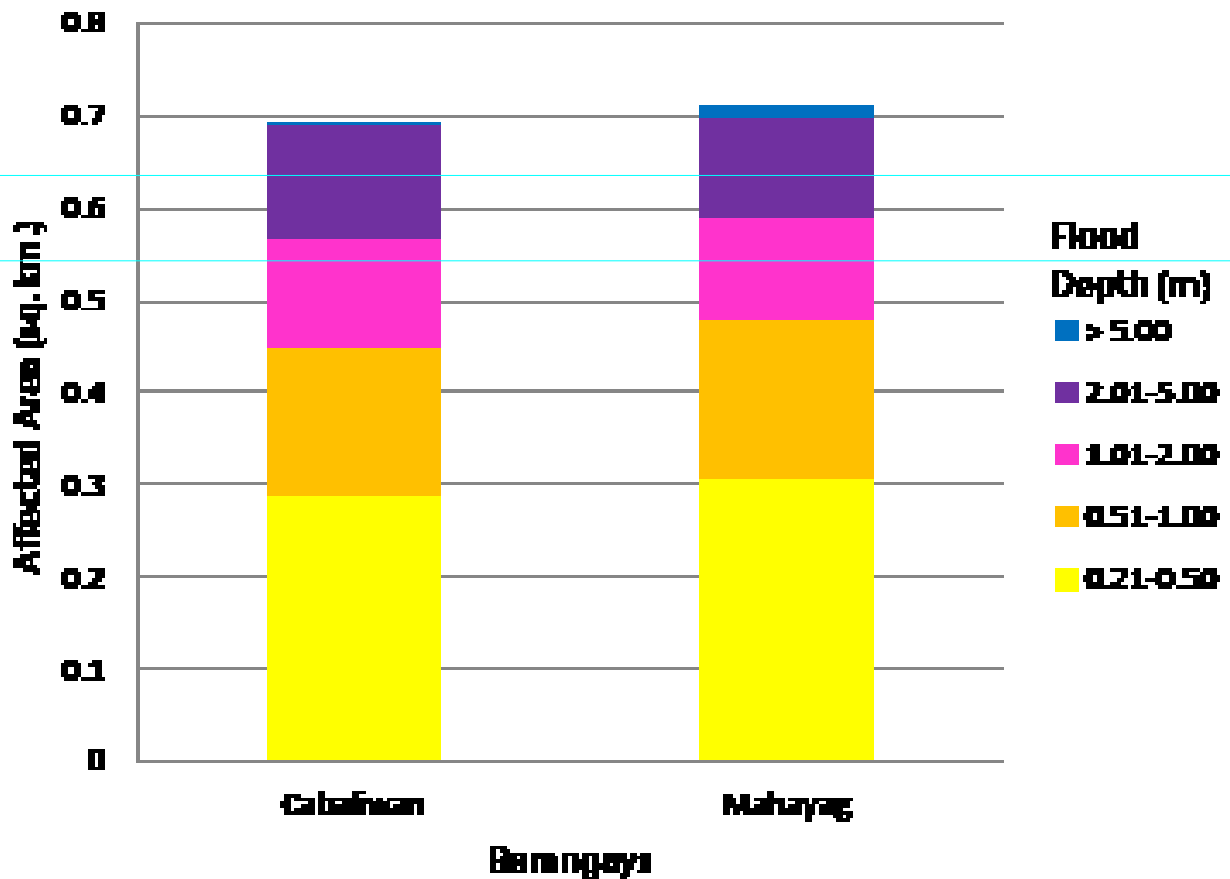


Figure 84. Affected areas in Merida, Leyte during a 25-year rainfall return period

For the Municipality of Ormoc City, with an area of 451.96 sq. km., 6.40% will experience flood levels of less than 0.20 meters. 1.64% of the area will experience flood levels of 0.21 to 0.50 meters. Meanwhile, 2%, 4.38%, 3.12%, and 0.30% of the area will experience flood depths of 0.51 to 1 meter, 1.01 to 2 meters, 2.01 to 5 meters, and more than 5 meters, respectively. Tables 59-61 depict the affected areas, in square kilometers, by flood depth per barangay.

Table 59. Affected areas in Ormoc City, Leyte during a 100-year rainfall return period

Affected area (sq. km.) by flood depth (in m.)	Area of affected barangays in Ormoc City (in sq. km.)							
	Airport	Bayog	Catmon	Curva	Domonar	Esperanza	Green Valley	Guintigui-An
<b>0.03-0.20</b>	0.64	0.0045	0.82	1.55	0.15	4.89	1.13	0.039
<b>0.21-0.50</b>	0.24	0.023	0.55	0.48	0.12	0.21	0.22	0.00025
<b>0.51-1.00</b>	0.36	0.054	0.27	0.39	0.24	0.2	0.39	0
<b>1.01-2.00</b>	0.11	0.35	0.38	0.11	0.61	0.45	0.36	0
<b>2.01-5.00</b>	0.17	0.74	0.33	0.041	1.14	0.59	1.54	0
<b>&gt; 5.00</b>	0.027	0.11	0.016	0.0026	0.092	0.05	0.055	0

Table 60. Affected areas in Ormoc City, Leyte during a 100-year rainfall return period

Affected area (sq. km.) by flood depth (in m.)	Area of affected barangays in Ormoc City (in sq. km.)							
	Labrador	Lao	Leondoni	Libertad	Licama	Liloan	Mabato	Manlilinao
<b>0.03-0.20</b>	0.28	0.52	0.27	1.04	1.86	0.075	0.063	2.18
<b>0.21-0.50</b>	0.64	0.64	0.091	0.59	0.67	0.19	0.14	0.085
<b>0.51-1.00</b>	0.48	1.09	0.13	0.59	0.53	1.14	0.55	0.067
<b>1.01-2.00</b>	0.9	1.57	0.16	1.82	0.14	6.28	1.92	0.09
<b>2.01-5.00</b>	0.57	0.19	0.46	0.35	0.023	3.03	1.81	0.086
<b>&gt; 5.00</b>	0.053	0.0005	0.28	0	0.0028	0.25	0.0015	0.0014

Table 61. Affected areas in Ormoc City, Leyte during a 100-year rainfall return period

Affected area (sq. km.) by flood depth (in m.)	Area of affected barangays in Ormoc City (in sq. km.)								
	Margen	Mas-In	Nasunogan	Nueva Sociedad	Rufina M. Tan	Sabang Bao	San Jose	San Juan	San Vicente
<b>0.03-0.20</b>	1.65	2.11	0.44	1.86	0.57	0.036	2.37	0.85	3.52
<b>0.21-0.50</b>	0.42	0.2	0.093	0.097	0.043	0.14	0.87	0.48	0.18
<b>0.51-1.00</b>	0.61	0.25	0.02	0.044	0.044	0.2	0.21	1.05	0.12
<b>1.01-2.00</b>	0.46	0.33	0.0051	0.022	0.047	1.44	0.29	1.87	0.074
<b>2.01-5.00</b>	0.37	0.15	0.0094	0.011	0.62	1.48	0.039	0.33	0.03
<b>&gt; 5.00</b>	0.0009	0	0	0	0.22	0.2	0.0001	0	0.0001

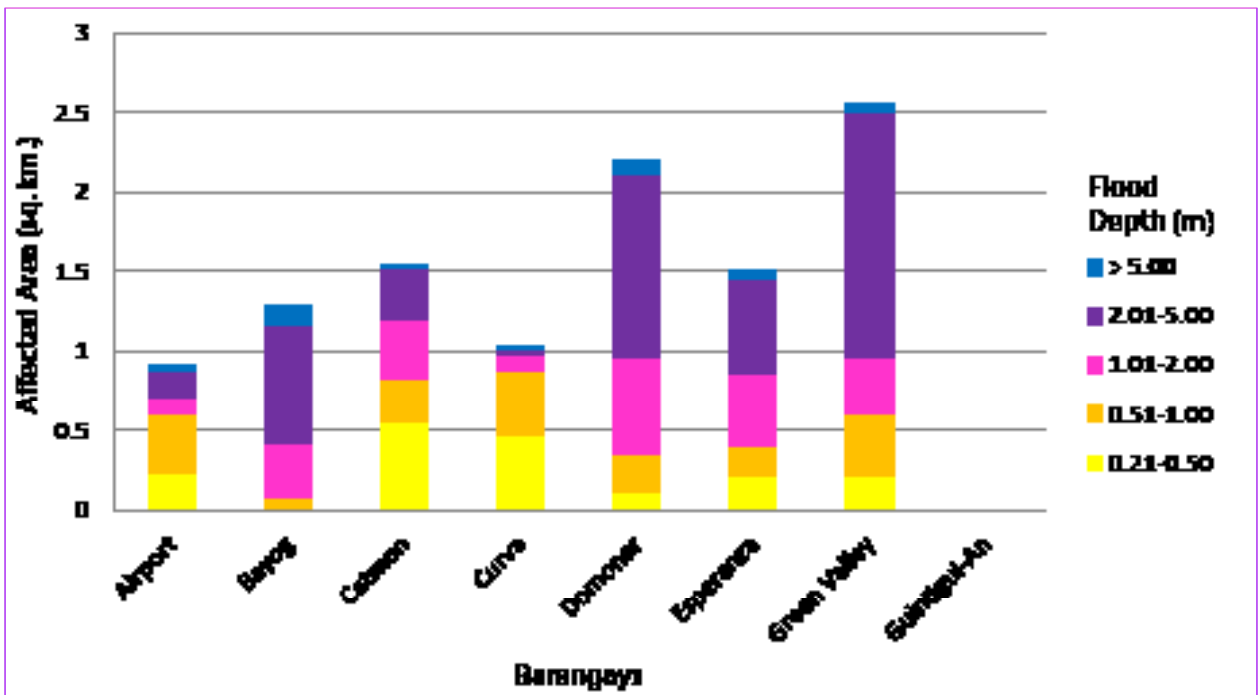


Figure 85. Affected areas in Ormoc City, Leyte during a 100-year rainfall return period

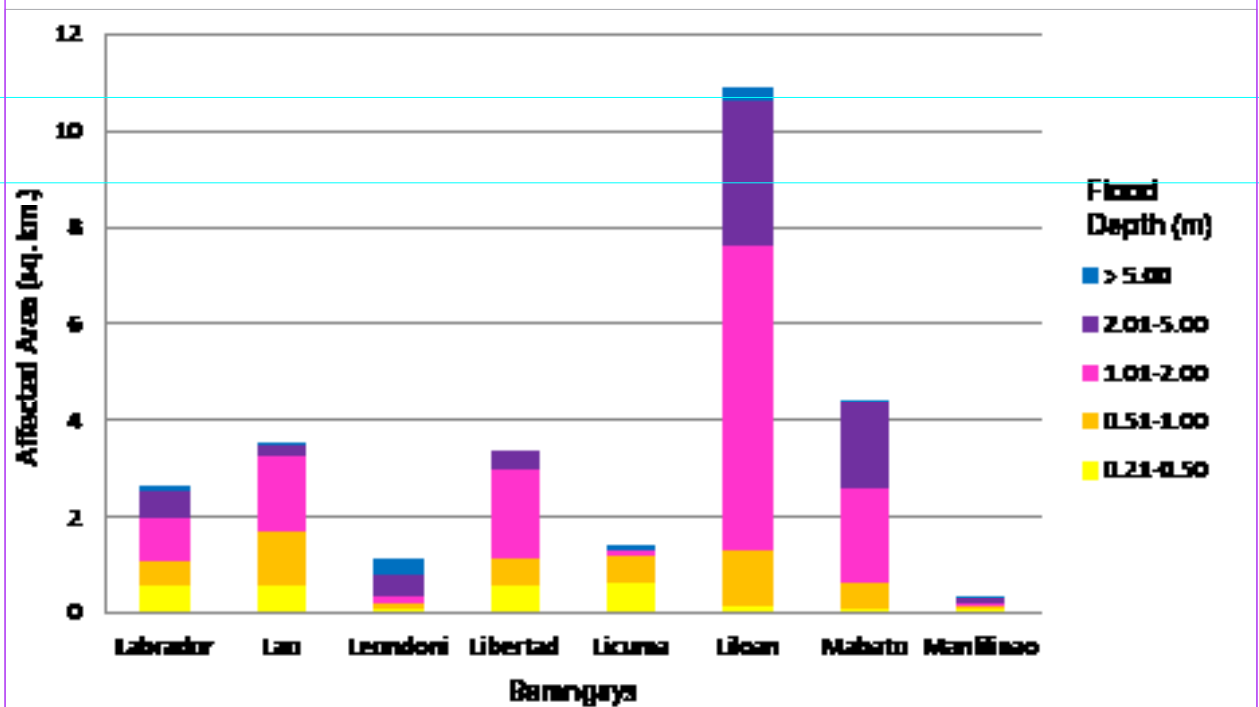


Figure 86. Affected areas in Ormoc City, Leyte during a 100-year rainfall return period



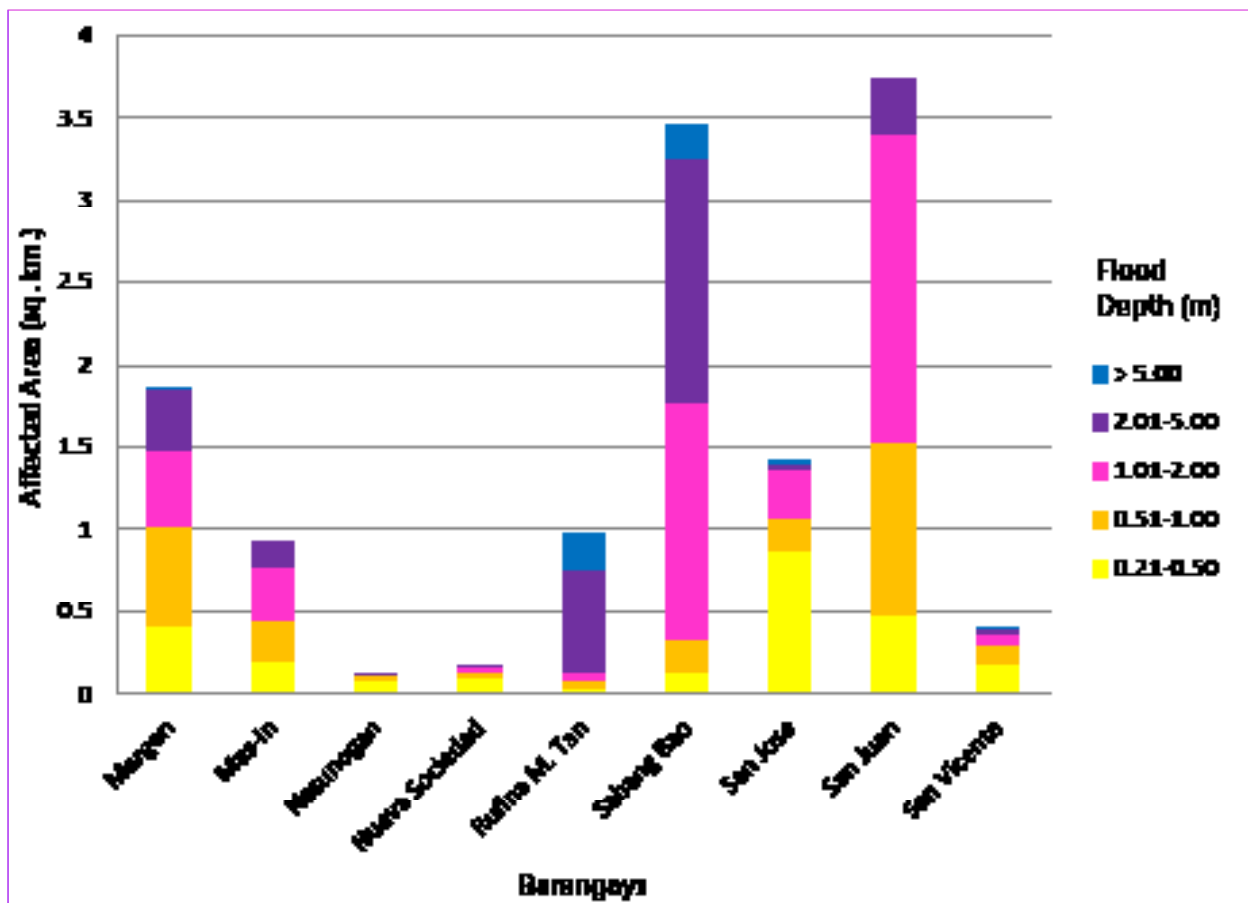


Figure 87. Affected areas in Ormoc City, Leyte during a 100-year rainfall return period

For the Municipality of Palompon, with an area of 125.87 sq. km., 0.09% will experience flood levels of less than 0.20 meters. 0.003% of the area will experience flood levels of 0.21 to 0.50 meters. Meanwhile, 0.0003%, and 0.00002% of the area will experience flood depths of 0.51 to 1 meter, and 1.01 to 2 meters, respectively. Table 62 depicts the affected areas, in square kilometers, by flood depth per barangay.

Table 62. Affected areas in Palompon, Leyte during a 100-year rainfall return period

Affected area (sq. km.) by flood depth (in m.)	Area of affected barangays in Palompon (in sq. km.)	
	Cambakbak	Mabini
0.03-0.20	0.042	0.066
0.21-0.50	0.0006	0.0037
0.51-1.00	0.000031	0.00034
1.01-2.00	0.000013	0.000014
2.01-5.00	0	0
> 5.00	0	0

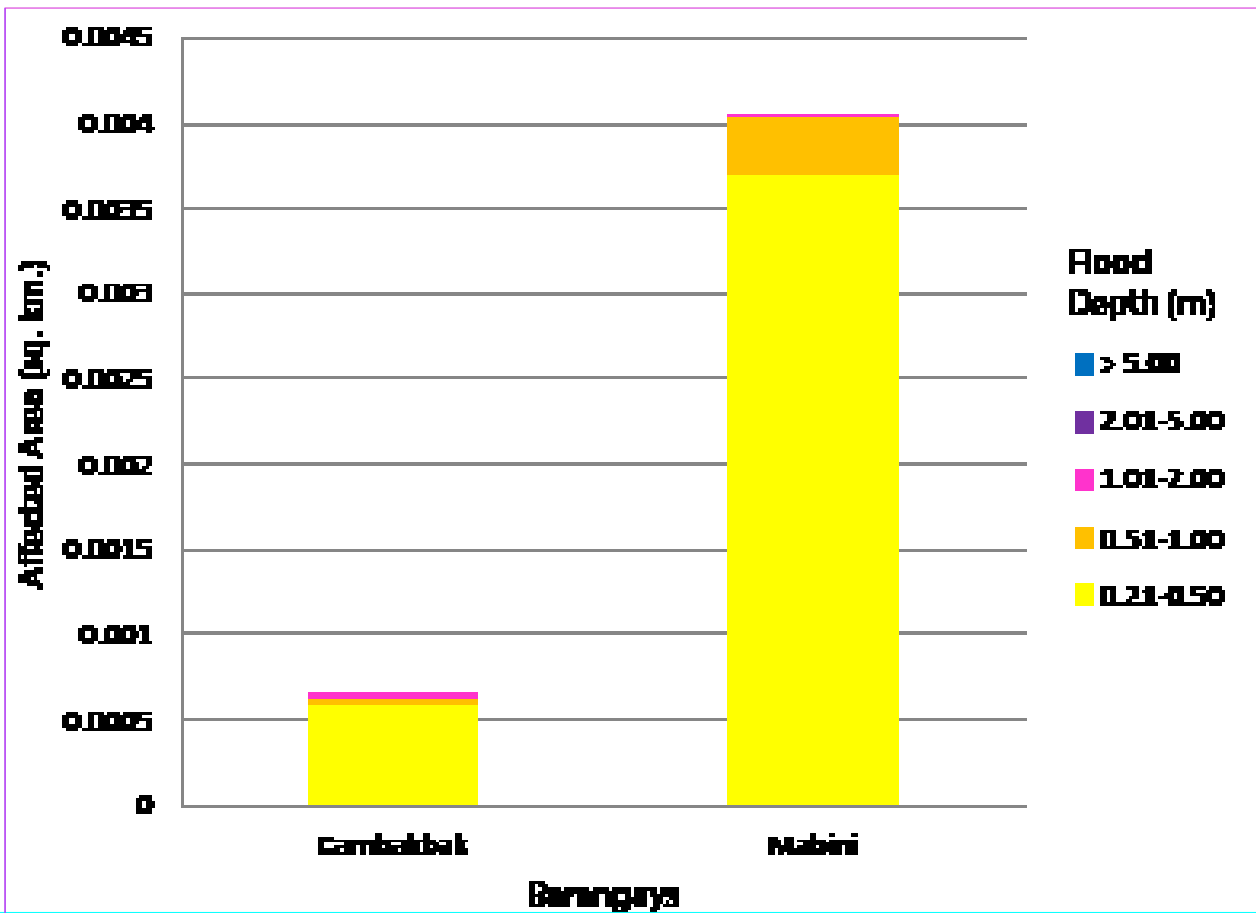


Figure 88. Affected areas in Palompon, Leyte during a 100-year rainfall return period

Among the barangays in the Municipality of Matag-Ob, Santa Rosa is projected to have the highest percentage of area that will experience flood levels, at 3.68%.

Among the barangays in the Municipality of Merida, Mahayag is projected to have the highest percentage of area that will experience flood levels, at 7.03%. On the other hand, Cabaliwan posted the second highest percentage of area that may be affected by flood depths, at 6.29%.

Among the barangays in the Municipality of Ormoc City, Liloan is projected to have the highest percentage of area that will experience flood levels, at 2.43%. On the other hand, Ezperanza posted the second highest percentage of area that may be affected by flood depths, at 1.42%.

Among the barangays in the Municipality of Palompon, Mabini is projected to have the highest percentage of area that will experience flood levels, at 0.06%. On the other hand, Cambakbak posted the second highest percentage of area that may be affected by flood depths, at 0.03%.

The generated flood hazard maps for the Pagsangahan floodplain were also used to assess the vulnerability of the educational and medical institutions in the floodplain. Using the flood depth units of PAGASA for the flood hazard maps – “Low”, “Medium”, and “High” – the affected institutions were given an individual assessment for each flood hazard scenario (i.e., 5-year, 25-year, and 100-year).

Table 63. Area covered by each warning level with respect to the rainfall scenario

Warning Level	Area Covered in sq. km		
	5 year	25 year	100 year
Low	10.60	8.66	8.13
Medium	18.42	22.40	19.65
High	11.48	18.55	25.59

Of the thirty (30) identified educational institutions in the Pagsangahan floodplain, seven (7) schools were assessed to be exposed to Low-level flooding during a 5-year scenario; while six (6) schools were assessed to be exposed to Medium-level flooding, and one (1) school was assessed to be exposed to High-level flooding in the same scenario. In the 25-year scenario, three (3) schools were assessed to be exposed to Low-level flooding, thirteen (13) to Medium-level flooding, and one (1) to High-level flooding. For the 100-year scenario, two (2) schools were assessed to be exposed to Low-level flooding, and fifteen (15) schools to Medium-level flooding. In the same scenario, three (3) schools are expected to be exposed to High-level flooding. See ANNEX 12 for a detailed enumeration of schools exposed to flooding within the Pagsangahan floodplain.

Of the eight (8) identified medical institutions in the Pagsangahan floodplain, four (4) were assessed to be exposed to Medium-level flooding during a 5-year scenario. In the 25-year scenario, three (3) institutions were assessed to be exposed to Medium-level flooding, while one (1) was assessed to be exposed to High-level flooding. For the 100-year scenario, two (2) centers were assessed to be exposed to Low-level flooding, and one (1) to Medium-level flooding. In the same scenario, three (3) were assessed to be subjected to High-level flooding, which are health centers in Barangay Green Valley, Liloan, and Mabato. See ANNEX 13 for a detailed enumeration of the medical institutions exposed to flooding within the Pagsangahan floodplain.

## 5.11 Flood Validation

In order to check and validate the extent of flooding in the different river systems, there is a need to perform validation survey work. For this purpose, field personnel gathered secondary data regarding flood occurrences in the respective areas within the major river systems in the Philippines.

From the flood depth maps produced by the Phil-LiDAR 1 Program, multiple points representing the different flood depths for different scenarios were identified for validation.

The validation personnel went to the specified points identified in a river basin to gather data regarding the actual flood levels in each location. Data gathering was conducted through assistance from a local DRRM office to obtain maps or situation reports about the past flooding events, or through interviews with some residents with knowledge or experience of flooding in a particular area.

After which, the actual data from the field were compared with the simulated data to assess the accuracy of the flood depth maps produced, and to improve on results of the flood map. The points in the flood maps versus the corresponding validation depths are illustrated in Figures 92-94.

The flood validation consists of 243 points, randomly selected all over the Pagsangahan floodplain. The points were grouped depending on the RIDF return period of the event. The field validation points are available in ANNEX 11.

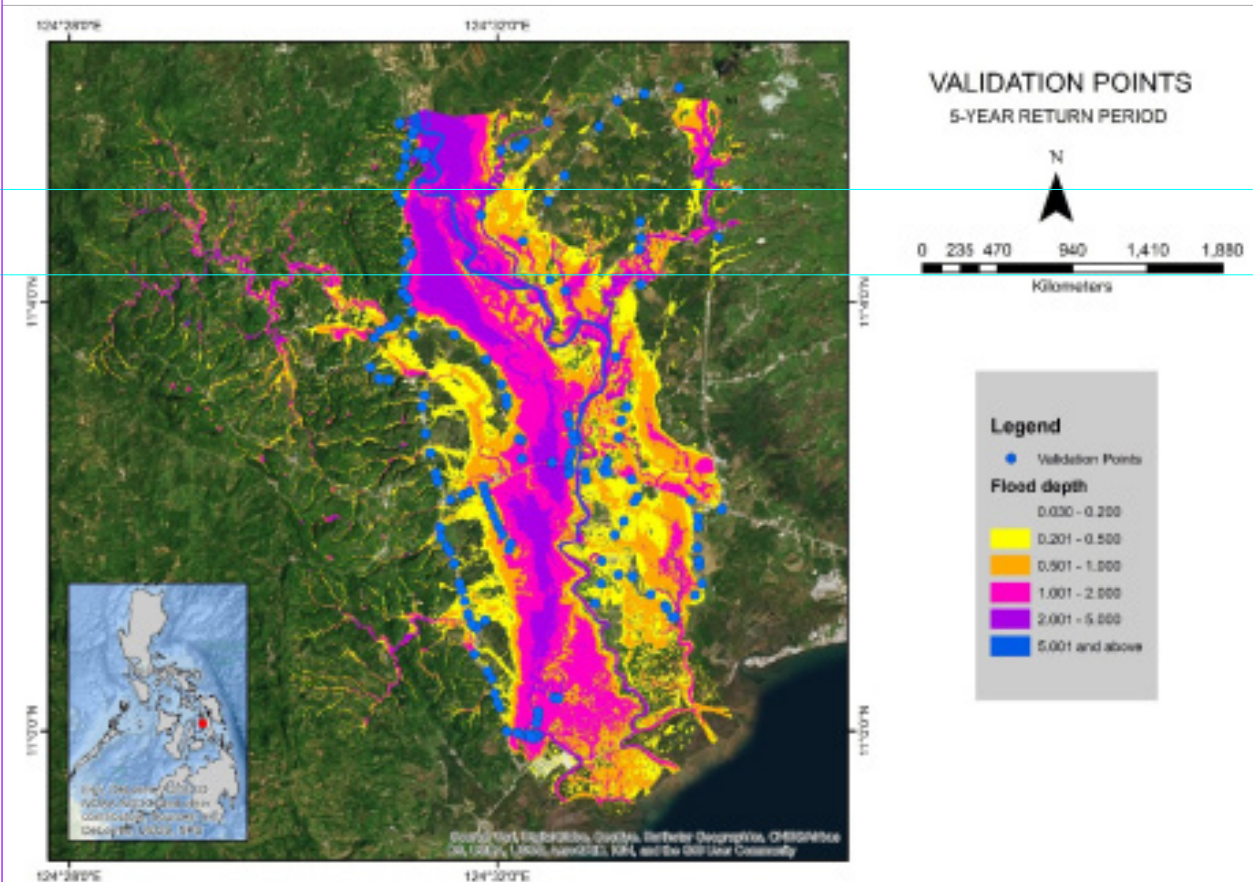


Figure 89. Validation points for the 5-year flood depth map of the Pagsangahan floodplain

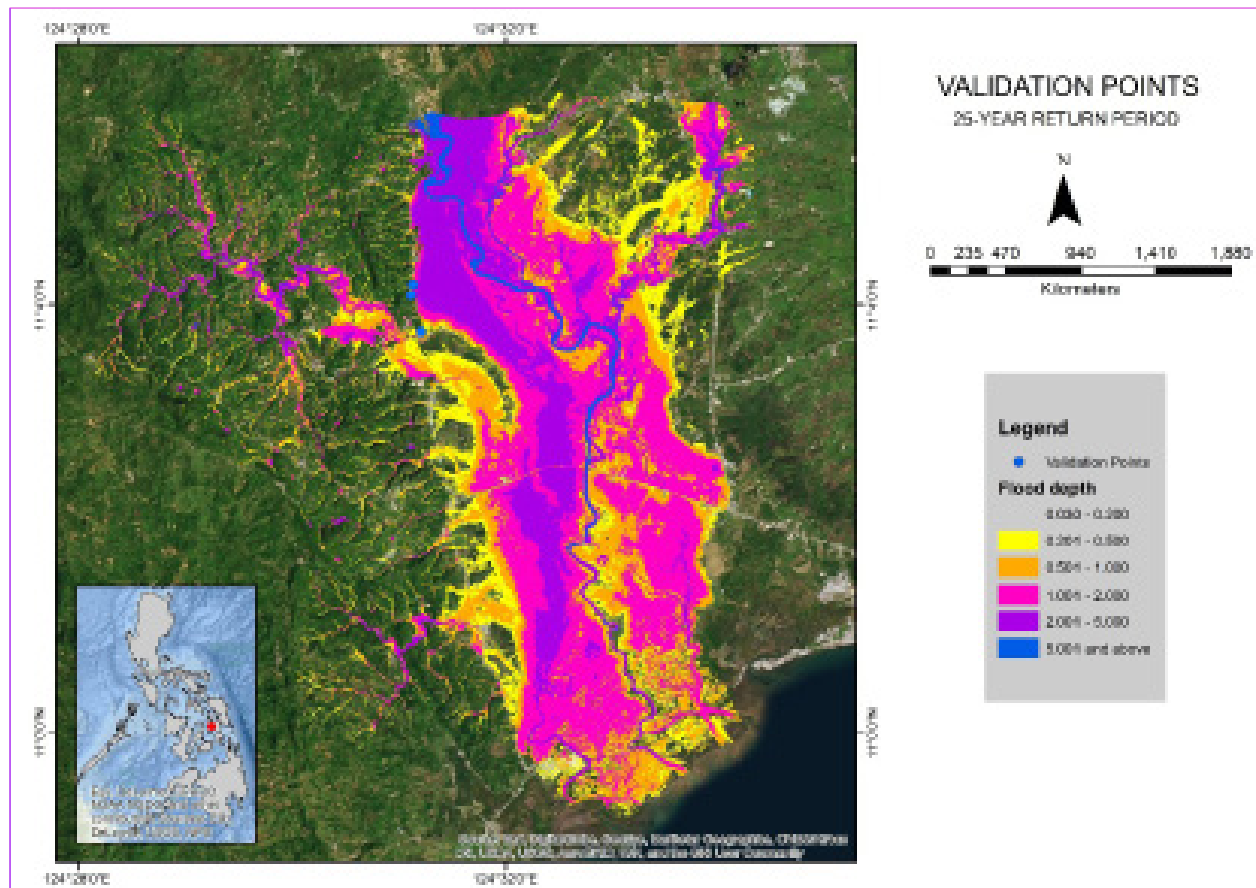


Figure 90. Validation points for the 25-year flood depth map of the Pagsangahan floodplain

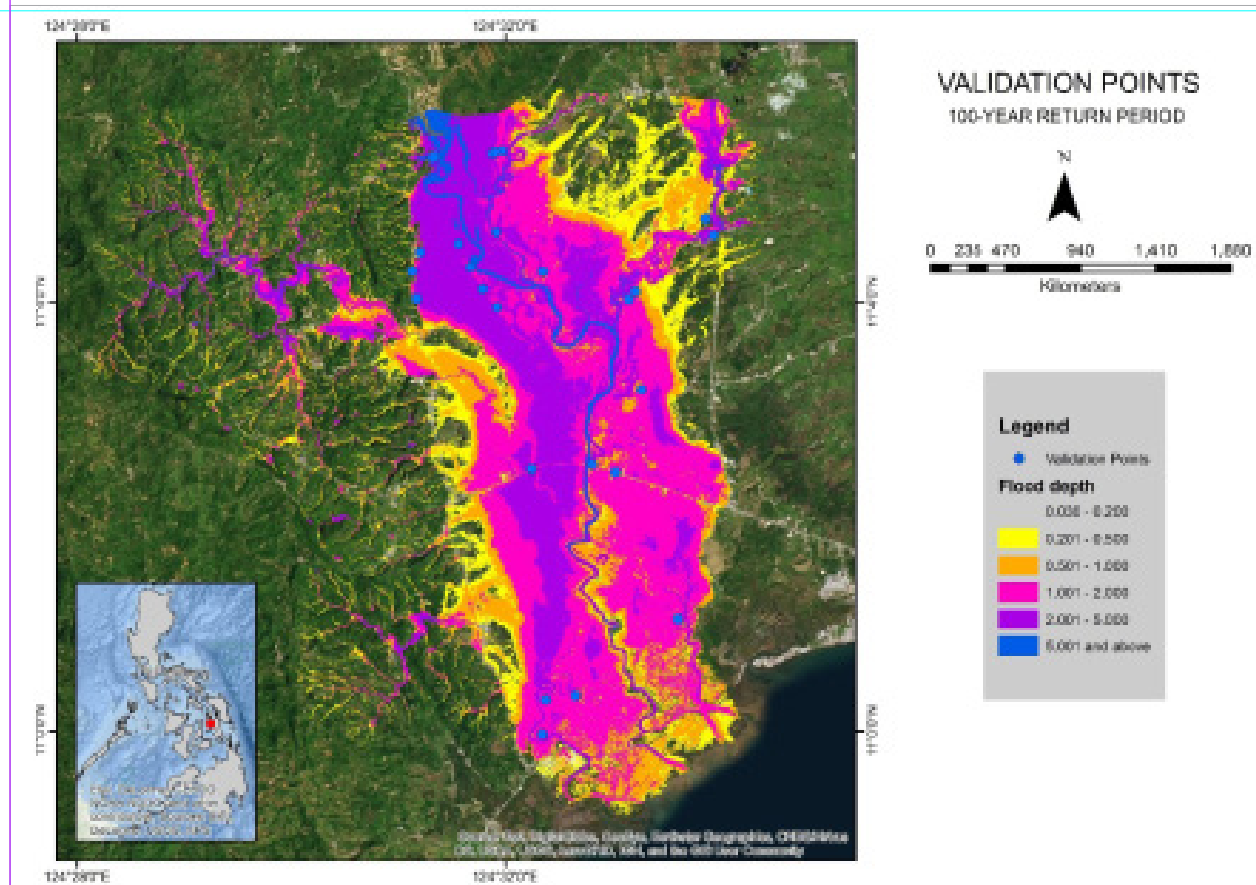


Figure 91. Validation points for the 100-year flood depth map of the Pagsangahan floodplain

The RMSE values for the flood depth maps are listed in Table 64:

Table 64. RMSE values for each return period of flood depth map

Return Period	RMSE
5-year	0.54
25-year	0.79
100-year	1.18

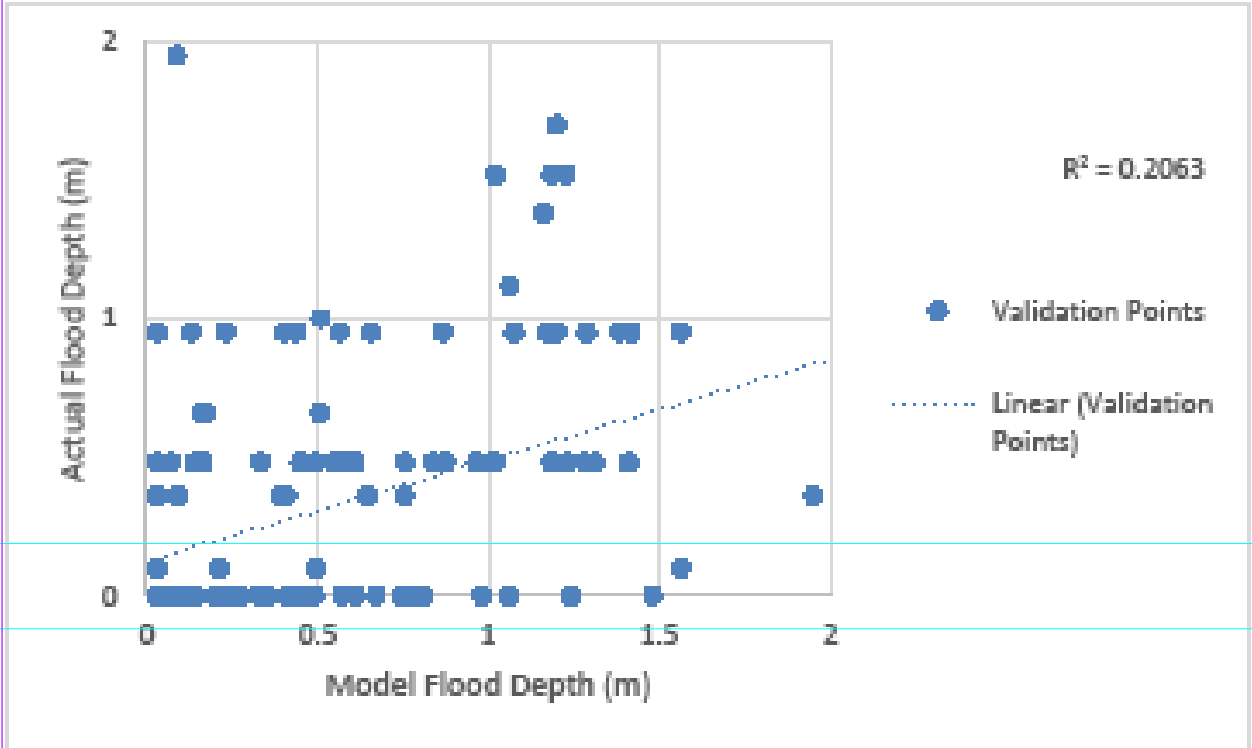


Figure 92. Flood map depth vs. actual flood depth for a 5-year return period

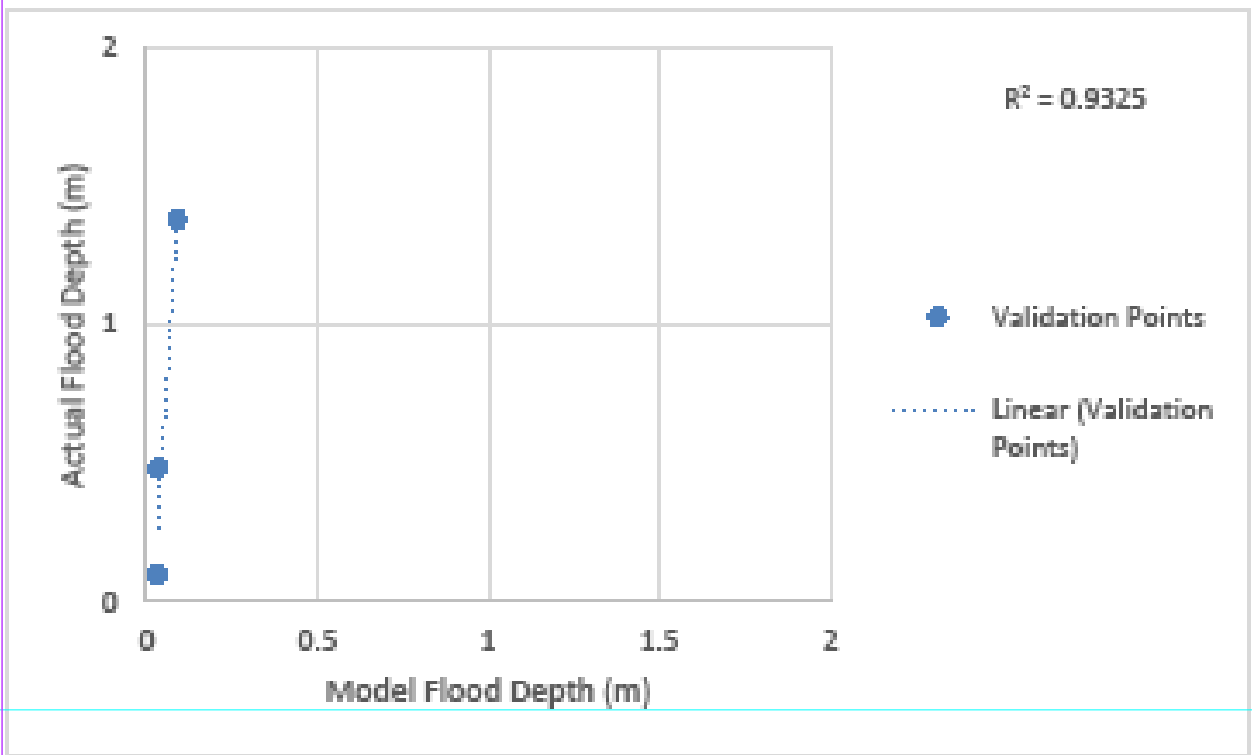


Figure 93. Flood map depth vs. actual flood depth for a 25-year return period

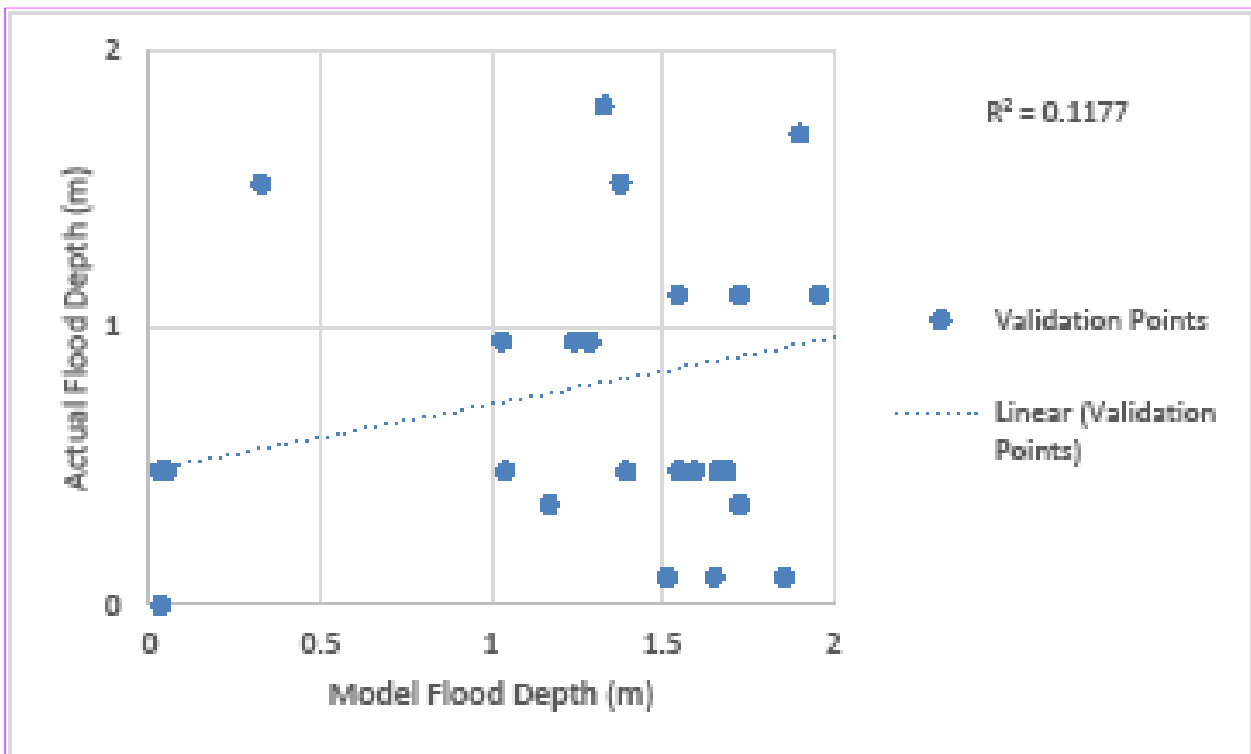


Figure 94. Flood map depth vs. actual flood depth for a 100-year return period

Table 65. Actual flood depth vs. Simulated flood depth in Pagsangahan, in the 5-year return scenario

PAGSANGAHAN BASIN		MODELED FLOOD DEPTH (m)						Total
		0-0.20	0.21-0.50	0.51-1.00	1.01-2.00	2.01-5.00	> 5.00	
Actual Flood Depth (m)	0-0.20	91	21	8	4	1	0	125
	0.21-0.50	14	5	11	8	3	0	41
	0.51-1.00	5	3	5	10	0	0	23
	1.01-2.00	1	0	0	6	0	0	7
	2.01-5.00	0	0	0	1	0	0	1
	> 5.00	0	0	0	0	0	0	0
	Total	111	29	24	29	4	0	197

The overall accuracy generated by the flood model in the 5-year return scenario is estimated at 54.31%. with one hundred and seven (107) points correctly matching the actual flood depths. There were fifty-seven (57) points estimated one (1) level above and below the correct flood depths. On the other hand, there were twenty-one (21) points and nine (9) points that were estimated two (2) levels above and below, and three (3) or more levels above and below the correct flood depths, respectively. A total of four (4) points were overestimated, while a total of twenty-four (24) points were underestimated in the modeled flood depths of the Pagsangahan floodplain.

Table 66. Summary of Accuracy Assessment in the Pagsangahan River Basin Survey for the 5-year return scenario

	No. of Points	%
Correct	81	44.75
Overestimated	56	30.94
Underestimated	44	24.31
<b>Total</b>	<b>181</b>	<b>100</b>

Table 67. Actual flood depth vs. Simulated flood depth in Pagsangahan, in the 25-year return scenario

PAGSANGAHAN BASIN		MODELED FLOOD DEPTH (m)						Total
		0-0.20	0.21-0.50	0.51-1.00	1.01-2.00	2.01-5.00	> 5.00	
Actual Flood Depth (m)	0-0.20	1	0	0	0	0	0	1
	0.21-0.50	1	0	0	0	0	0	1
	0.51-1.00	0	0	0	0	0	0	0
	1.01-2.00	1	0	0	0	0	0	1
	2.01-5.00	0	0	0	0	0	0	0
	> 5.00	0	0	0	0	0	0	0
	Total	3	0	0	0	0	0	3

The overall accuracy generated by the flood model for the 25-year return scenario is estimated at 33.33%, with one (1) point correctly matching the actual flood depths. There was one (1) point estimated one (1) level above and below the correct flood depths; while there were zero (0) points and one (1) point estimated two (2) levels above and below, and three (3) or more levels above and below the correct flood levels, respectively. A total of four (4) points were overestimated, while a total of two (2) points were underestimated in the modeled flood depths of the Pagsangahan floodplain.

Table 68. Summary of Accuracy Assessment in the Pagsangahan River Basin Survey for the 25-year return scenario

	No. of Points	%
Correct	1	33.33
Overestimated	0	0.00
Underestimated	2	66.67
<b>Total</b>	<b>3</b>	<b>100.00</b>



Table 69. Actual flood depth vs. Simulated flood depth in Pagsangahan, in the 25-year return scenario

PAGSANGAHAN BASIN		MODELED FLOOD DEPTH (m)						Total
		0-0.20	0.21-0.50	0.51-1.00	1.01-2.00	2.01-5.00	> 5.00	
Actual Flood Depth (m)	0-0.20	1	0	0	3	0	0	4
	0.21-0.50	2	0	0	9	2	0	13
	0.51-1.00	0	0	0	3	0	0	3
	1.01-2.00	0	1	0	6	4	0	11
	2.01-5.00	0	0	0	1	0	0	1
	> 5.00	0	0	0	0	0	0	0
	Total	3	1	0	22	6	0	32

The overall accuracy generated by the flood model for the 100-year return scenario is estimated at 21.88%, with seven (7) points correctly matching the actual flood depths. Additionally, there were ten (10) points estimated one (1) level above and below the correct flood depths. Meanwhile, there were ten (10) points and five (5) points estimated two (2) levels above and below, and three (3) or more levels above and below the correct flood depths, respectively. A total of four (4) points were overestimated, while a total of four (4) points were underestimated in the modeled flood depths of the Pagsangahan River Basin survey.

Table 70. Summary of Accuracy Assessment in the Pagsangahan River Basin Survey for the 100-year return scenario

	No. of Points	%
Correct	7	21.88
Overestimated	21	65.63
Underestimated	4	12.50
<b>Total</b>	<b>32</b>	<b>100.00</b>

## REFERENCES

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## ANNEX

### ANNEX 1. Technical Specifications of the LiDAR Sensors used in the Pagsangahan Floodplain Survey

#### 1. AQUARIUS SENSOR

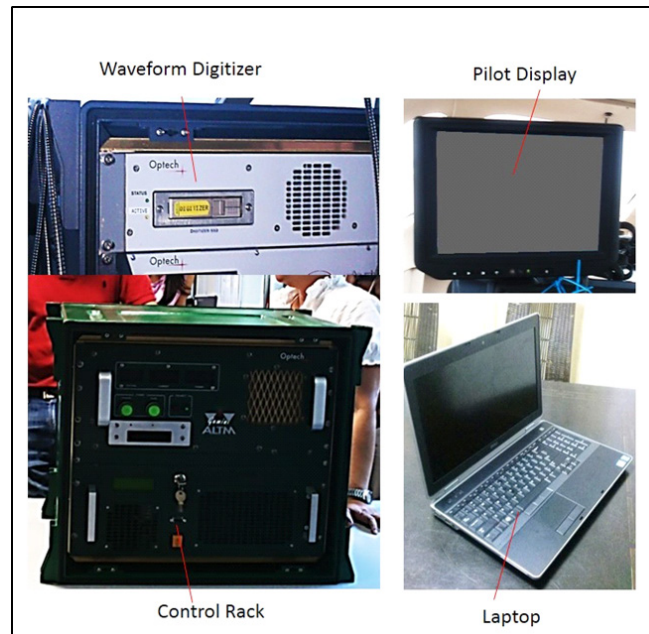


Table A-1.1. Technical specifications of the Aquarius sensor

Parameter	Specification
Operational altitude	300-600 m AGL
Laser pulse repetition rate	33, 50, 70 kHz
Scan rate	0-70 Hz
Scan half-angle	0 to $\pm 25^\circ$
Laser footprint on water surface	30-60 cm
Depth range	0 to > 10 m (for $k < 0.1/m$ )
Topographic mode	
Operational altitude	300-2500
Range Capture	Up to 4 range measurements, including 1 <sup>st</sup> , 2 <sup>nd</sup> , 3 <sup>rd</sup> , and last returns
Intensity capture	12-bit dynamic measurement range
Position and orientation system	POS AVTM 510 (OEM) includes embedded 72-channel GNSS receiver (GPS and GLONASS)
Data Storage	Ruggedized removable SSD hard disk (SATA III)
Power	28 V, 900 W, 35 A
Image capture	5 MP interline camera (standard); 60 MP full frame (optional)
Full waveform capture	12-bit Optech IWD-2 Intelligent Waveform Digitizer (optional)
Dimensions and weight	Sensor: 250 x 430 x 320 mm; 30 kg; Control rack: 591 x 485 x 578 mm; 53 kg
Operating temperature	0-35°C
Relative humidity	0-95% no-condensing

Table A-1.2. Technical specifications of the Gemini sensor

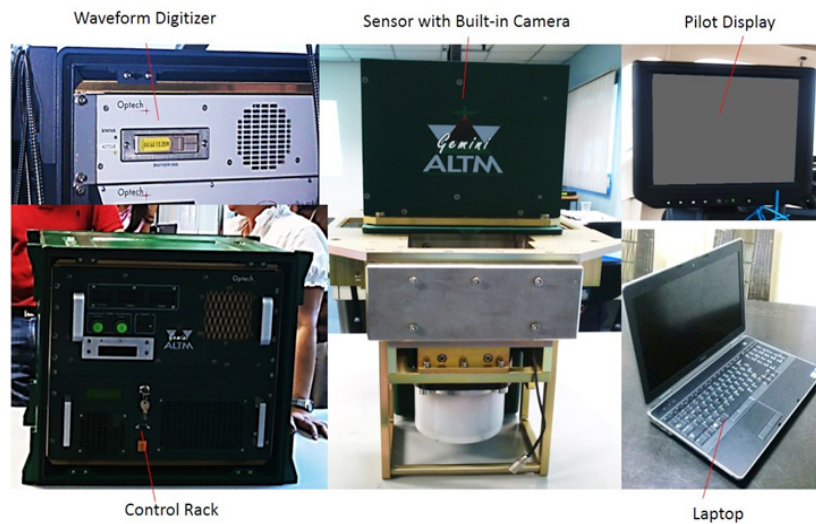



Figure A-1.2. Gemini Sensor

Table A-1.2. Technical specifications of the Gemini sensor

Parameter	Specification
Parameter	Specification
Operational envelope (1,2,3,4)	150-4000 m AGL, nominal
Laser wavelength	1064 nm
Horizontal accuracy (2)	1/5,500 x altitude, (m AGL)
Elevation accuracy (2)	<5-35 cm, 1 $\sigma$
Effective laser repetition rate	Programmable, 33-167 kHz
Position and orientation system	POS AV™ AP50 (OEM);
220-channel dual frequency GPS/ GNSS/Galileo/L-Band receiver	300-2500
Scan width (WOV)	Programmable, 0-50°
Scan frequency (5)	Programmable, 0-70 Hz (effective)
Sensor scan product	1000 maximum
Beam divergence	Dual divergence: 0.25 mrad (1/e) and 0.8 mrad (1/e), nominal
Roll compensation	Programmable, $\pm 5^\circ$ (FOV dependent)
Range capture	Up to 4 range measurements, including 1 <sup>st</sup> , 2 <sup>nd</sup> , 3 <sup>rd</sup> , and last returns
Intensity capture	Up to 4 intensity returns for each pulse, including last (12 bit)
Video Camera	Internal video camera (NTSC or PAL)
Image capture	Compatible with full Optech camera line (optional)
Full waveform capture	12-bit Optech IWD-2 Intelligent Waveform Digitizer (optional)
Data storage	Removable solid state disk SSD (SATA II)
Power requirements	28 V; 900 W; 35 A(peak)
Dimensions and weight	Sensor: 260 mm (w) x 190 mm (l) x 570 mm (h); 23 kg Control rack: 650 mm (w) x 590 mm (l) x 530 mm (h); 53 kg
Operating temperature	-10°C to +35°C (with insulating jacket)
Relative humidity	0-95% no-condensing

ANNEX 2. NAMRIA Certification of Reference Points used in the LiDAR Survey

1. LYT-37



Republic of the Philippines  
Department of Environment and Natural Resources  
**NATIONAL MAPPING AND RESOURCE INFORMATION AUTHORITY**

April 23, 2014

**CERTIFICATION**

To whom it may concern:

This is to certify that according to the records on file in this office, the requested survey information is as follows -

Province: <b>LEYTE</b>		
Station Name: <b>LYT-37</b>		
Order: <b>4th</b>		
Island: <b>VISAYAS</b>	Barangay: <b>POBLACION</b>	
Municipality: <b>LEYTE</b>		
<i>PRS92 Coordinates</i>		
Latitude: <b>11° 22' 17.79271"</b>	Longitude: <b>124° 29' 7.61910"</b>	Ellipsoidal Hgt: <b>5.33900 m.</b>
<i>WGS84 Coordinates</i>		
Latitude: <b>11° 22' 13.44918"</b>	Longitude: <b>124° 29' 12.76807"</b>	Ellipsoidal Hgt: <b>65.99800 m.</b>
<i>PTM Coordinates</i>		
Northing: <b>1257480.277 m.</b>	Easting: <b>443839.088 m.</b>	Zone: <b>5</b>
<i>UTM Coordinates</i>		
Northing: <b>1,257,404.79</b>	Easting: <b>662,088.45</b>	Zone: <b>51</b>

Location Description


**LYT-37**  
Is located at the town proper of Leyte, province of Northern Leyte. It is situated on the S corner of a 62 cm square concrete base foundation of a steel lamp post inside the town plaza in between the park and the basketball court. Station is about 22.3 mts. SSE of the centerline of Gabaldon Street, 75 cm SW of the CHB wall of the basketball court and 10 cm above the ground. Mark is the head of a 4" copper nail centered on a 10 cm square cement putty with inscription, LYT-37, 1997, NAMRIA.

Requesting Party: **Engr. Christopher Cruz/ UP-DREAM**


Purpose: **Reference**

OR Number: **8796021 A**


T.N.: **2014-918**



**RUEL M. BELEN, MNSA**  
Director, Mapping And Geodesy Branch



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Figure A-2.1. LYT-37

2. LYT-86



Republic of the Philippines  
 Department of Environment and Natural Resources  
**NATIONAL MAPPING AND RESOURCE INFORMATION AUTHORITY**

April 23, 2014

**CERTIFICATION**

To whom it may concern:

This is to certify that according to the records on file in this office, the requested survey information is as follows -

Province: <b>LEYTE</b>		
Station Name: <b>LYT-86 (686)</b>		
Order: <b>2nd</b>		
Island: <b>VISAYAS</b>	Barangay: <b>POBLACION</b>	
Municipality: <b>LEYTE</b>		
<b>PRS92 Coordinates</b>		
Latitude: <b>11° 22' 16.75118"</b>	Longitude: <b>124° 29' 8.10940"</b>	Ellipsoidal Hgt: <b>5.43100 m.</b>
<b>WGS84 Coordinates</b>		
Latitude: <b>11° 22' 12.40727"</b>	Longitude: <b>124° 29' 13.25847"</b>	Ellipsoidal Hgt: <b>66.09100 m.</b>
<b>PTM Coordinates</b>		
Northing: <b>1257448.25 m.</b>	Easting: <b>443853.897 m.</b>	Zone: <b>5</b>
<b>UTM Coordinates</b>		
Northing: <b>1,257,372.86</b>	Easting: <b>662,103.47</b>	Zone: <b>51</b>

**Location Description**

**LYT-86**  
 From Tacloban City, travel 78kms. NW to Leyte. Station is located in the town plaza southern part of the multi-purpose covered court SE of the municipal hall and NE of the church. Mark is the head of a copper nail embedded and set flush to a concrete monument 0.30m x 0.30m x 1.20m protruding 0.20m above the ground with inscriptions "LYT-86 2006 NAMRIA."

Requesting Party: **Engr. Christopher Cruz/ UP-DREAM**  
 Purpose: **Reference**  
 OR Number: **8796021 A**  
 T.N.: **2014-917**

  
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Figure A-2.2. LYT-86

3. LYT-89



Republic of the Philippines  
 Department of Environment and Natural Resources  
**NATIONAL MAPPING AND RESOURCE INFORMATION AUTHORITY**

March 11, 2016

**CERTIFICATION**

To whom it may concern:

This is to certify that according to the records on file in this office, the requested survey information is as follows -

Province: <b>LEYTE</b>		
Station Name: <b>LYT-89</b>		
Order: <b>1st</b>		
Island: <b>VISAYAS</b>	Barangay: <b>SANTO NIÑO (POB.)</b>	
Municipality: <b>ISABEL</b>	MSL Elevation:	
<b>PRS92 Coordinates</b>		
Latitude: <b>10° 55' 37.75929"</b>	Longitude: <b>124° 26' 59.22187"</b>	Ellipsoidal Hgt: <b>2.63400 m.</b>
<b>WGS84 Coordinates</b>		
Latitude: <b>10° 55' 33.52339"</b>	Longitude: <b>124° 26' 4.41045"</b>	Ellipsoidal Hgt: <b>64.14500 m.</b>
<b>PTM / PRS92 Coordinates</b>		
Northing: <b>1208330.431 m.</b>	Easting: <b>438033.007 m.</b>	Zone: <b>5</b>
<b>UTM / PRS92 Coordinates</b>		
Northing: <b>1,298,220.77</b>	Easting: <b>656,614.72</b>	Zone: <b>61</b>

**Location Description**

**LYT-89**  
 From Tacloban City travel SW to Isabel for 160km. Station is located on top of the pavement SW of the municipal hall, 14m away from the right side of Rizal monument. Mark is the head of a copper nail embedded on a cement putty 0.30m x 0.30m protruding 1" from the ground with inscription "LYT-89 2006 NAMRIA."

Requesting Party: **PHIL-LIDAR 1**  
 Purpose: **Reference**  
 OR Number: **8090013 1**  
 T.N.: **2016-0614**

  
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 Director, Mapping And Geodesy Branch



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Figure A-2.3. LYT-89

4. LYT-704



Republic of the Philippines  
Department of Environment and Natural Resources  
**NATIONAL MAPPING AND RESOURCE INFORMATION AUTHORITY**

April 23, 2014

### CERTIFICATION

To whom it may concern:

This is to certify that according to the records on file in this office, the requested survey information is as follows -

<b>Province: LEYTE</b>		
<b>Station Name: LYT-704</b>		
<b>Order: 2nd</b>		<b>Barangay: POBLACION</b>
<b>Island: VISAYAS</b>		
<b>Municipality: KANANGA</b>		
<i>PRS92 Coordinates</i>		
Latitude: <b>11° 11' 18.35419"</b>	Longitude: <b>124° 33' 36.47427"</b>	Ellipsoidal Hgt: <b>38.29100 m.</b>
<i>WGS84 Coordinates</i>		
Latitude: <b>11° 11' 12.06307"</b>	Longitude: <b>124° 33' 41.63876"</b>	Ellipsoidal Hgt: <b>99.58400 m.</b>
<i>PTM Coordinates</i>		
Northing: <b>1237144.819 m.</b>	Easting: <b>451959.944 m.</b>	Zone: <b>5</b>
<i>UTM Coordinates</i>		
Northing: <b>1,237,125.91</b>	Easting: <b>670,347.64</b>	Zone: <b>51</b>

**Location Description**

Mark is the head of a 4" copper nail embedded in a cement block with inscriptions "LYT 704, 2007, NAMRIA."

From the Municipality of Kananga, the NAMRIA monument was established about 25 m. north inside Kananga Elementary School, 4 m. northwest away from the school's entrance gate, 4 m. northwest near the basketball court, 15 m. away from the school building, 20 m. away from the school stage and entrance gate going to National Road, and along the way going to Ormoc City and to Brgy. Lemon about 5 m. north.

Requesting Party: **Engr. Christopher Cruz/ UP-DREAM**


Purpose: **Reference**

OR Number: **8796021 A**

T.N.: **2014-916**



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Figure A-2.4. LYT-704



5. LYT-731



Republic of the Philippines  
 Department of Environment and Natural Resources  
**NATIONAL MAPPING AND RESOURCE INFORMATION AUTHORITY**

February 05, 2015

**CERTIFICATION**

To whom it may concern:

This is to certify that according to the records on file in this office, the requested survey information is as follows -

Province: <b>LEYTE</b>		
Station Name: <b>LYT-731</b>		
Order: <b>2nd</b>		
Barangay: <b>KANSUNGKA</b>		
MSL Elevation:		
<b>PRS92 Coordinates</b>		
Latitude: <b>10° 42' 47.59464"</b>	Longitude: <b>124° 48' 34.34385"</b>	Ellipsoidal Hgt: <b>15.61000 m.</b>
<b>WGS84 Coordinates</b>		
Latitude: <b>10° 42' 43.44572"</b>	Longitude: <b>124° 48' 39.54791"</b>	Ellipsoidal Hgt: <b>78.65700 m.</b>
<b>PTM / PRS92 Coordinates</b>		
Northing: <b>1184617.338 m.</b>	Easting: <b>479165.977 m.</b>	Zone: <b>5</b>
<b>UTM / PRS92 Coordinates</b>		
Northing: <b>1,184,777.35</b>	Easting: <b>697,902.97</b>	Zone: <b>51</b>

**Location Description**

**LYT-731**  
 From Babay City going to municipality of Albuera, from a bridge near babay city, Brgy. Kansungka is located on the 3rd junction on the right side of the highway, then passing thru Brgy. Candadau straight to a steel bridge near brgy. San Isidro then left to Brgy. Kasungka the control point is located near the house of ex-brgy. captain aring. The mark is a 3 inches concrete nail, embedded on a 40x40x100 cm. concrete monument having 40 cm height above the ground and is marked with LYT-731, 2007, LAMP.

Requesting Party: **PHIL-LIDAR I**  
 Purpose: **Reference**  
 OR Number: **8077605 I**  
 T.N.: **2015-0216**

**RUEL DM. BELEN, MNSA**  
 Director, Mapping And Geodesy Branch



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Figure A-2.5. LYT-731

6. LY-606



Republic of the Philippines  
Department of Environment and Natural Resources  
**NATIONAL MAPPING AND RESOURCE INFORMATION AUTHORITY**

February 04, 2014

**CERTIFICATION**

To whom it may concern:

This is to certify that according to the records on file in this office, the requested survey information is as follows -

Province: <b>LEYTE</b>	Station Name: <b>LY-606</b>	
Island: <b>Visayas</b>	Municipality: <b>KANANGA</b>	Barangay: <b>POBLACION</b>
Elevation: <b>42.0860 m.</b>	Order: <b>1st Order</b>	Datum: <b>Mean Sea Level</b>

Location Description

BM LY-606 is located in the Municipality Kanangga, Leyte, Brgy. Ionoy. Located at the concrete sidewalk of 40m. long bridge, 4.1 m. South West from the centerline of the road.

Mark is the head of a "copper nail, set and centered on a 10 cm x 10 cm cement putty protruding about 1.0 cm above the surface of the concrete sidewalk of Canawagan bridge with inscriptions, "LY-606, 2008, NAMRIA".

It can be reached approximately by 1hr. and 52 minutes drive from Tacloban City going to Capocan to Kanangga.

Requesting Party:	<b>UP-DREAM</b>
Purpose:	<b>Reference</b>
OR Number:	<b>8795255 A</b>
T.N.:	<b>2014-195</b>



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Director, Mapping And Geodesy Branch



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Figure A-2.6. LY-606

7. 7. LY-672



Republic of the Philippines  
Department of Environment and Natural Resources  
**NATIONAL MAPPING AND RESOURCE INFORMATION AUTHORITY**

June 06, 2014

**CERTIFICATION**

To whom it may concern:

This is to certify that according to the records on file in this office, the requested survey information is as follows -

Province: <b>BILIRAN</b>	Station Name: <b>LY-672</b>	
Island: <b>Visayas</b>	Municipality: <b>BILIRAN</b>	Barangay:
Elevation: <b>19.7522 m.</b>	Order: <b>1st Order</b>	Datum: <b>Mean Sea Level</b>

Location Description

(RECOMPUTED MARCH 2014)

LY-672

Is located in the Municipality Biliran, Brgy. Bachaw. Located at the concrete sidewalk of the bridge, 30m after KM post 1006, 3.5m from the centerline of the road. Mark is the head of a 4" copper nail, set and centered on a 10cm x 10cm cement putty protruding about 1.0cm above the surface of the concrete sidewalk of Biliran bridge, with inscriptions, "LY-672, 2008 NAMRIA". It can be reached approximately by 3 hours and 27 minutes drive from Tacloban City going to Capoccan to Biliran.

Requesting Party: **UP-TCAGP**  
Pupose: **Reference**  
OR Number: **8796290 A**  
T.N.: **2014-1294**

*for*   
**RUEL DM. BELEN, MNSA**  
Director, Mapping And Geodesy Branch



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Figure A-2.7. LY-672

## ANNEX 3. Baseline Processing Reports of Control Points used in the LiDAR Survey

## 1. LY-606

Table A-3.1. LY-606

LY-606 - LYT-704 (7:59:03 AM-1:36:37 PM) (S1)	
Baseline observation:	LY-606 -- LYT-704 (B1)
Processed:	10/21/2014 5:29:42 PM
Solution type:	Fixed
Frequency used:	Dual Frequency (L1, L2)
Horizontal precision:	0.001 m
Vertical precision:	0.002 m
RMS:	0.000 m
Maximum PDOP:	2.520
Ephemeris used:	Broadcast
Antenna model:	Trimble Relative
Processing start time:	1/28/2014 7:59:03 AM (Local: UTC+8hr)
Processing stop time:	1/28/2014 1:36:37 PM (Local: UTC+8hr)
Processing duration:	05:37:34
Processing interval:	1 second

## Vector Components (Mark to Mark)

From: LYT-704					
Grid		Local		Global	
Easting	670347.639 m	Latitude	N11°11'16.32664"	Latitude	N11°11'12.03642"
Northing	1237125.056 m	Longitude	E124°33'36.47427"	Longitude	E124°33'41.63876"
Elevation	37.077 m	Height	38.292 m	Height	99.584 m
To: LY-606					
Grid		Local		Global	
Easting	670395.829 m	Latitude	N11°11'28.07069"	Latitude	N11°11'23.77869"
Northing	1237486.135 m	Longitude	E124°33'38.12565"	Longitude	E124°33'43.28985"
Elevation	40.281 m	Height	41.477 m	Height	102.763 m
Vector					
$\Delta$ Easting	48.190 m	NS Fwd Azimuth	7°54'17"	$\Delta$ X	-3.302 m
$\Delta$ Northing	361.079 m	Ellipsoid Dist.	364.296 m	$\Delta$ Y	-83.507 m
$\Delta$ Elevation	3.184 m	$\Delta$ Height	3.186 m	$\Delta$ Z	354.597 m

## Standard Errors

Vector errors:					
$\sigma$ $\Delta$ Easting	0.000 m	$\sigma$ NS fwd Azimuth	0°00'00"	$\sigma$ $\Delta$ X	0.001 m
$\sigma$ $\Delta$ Northing	0.000 m	$\sigma$ Ellipsoid Dist.	0.000 m	$\sigma$ $\Delta$ Y	0.001 m
$\sigma$ $\Delta$ Elevation	0.001 m	$\sigma$ $\Delta$ Height	0.001 m	$\sigma$ $\Delta$ Z	0.000 m

2. LY-672

Table A-3.2. LY-672

LYT-37 - LY-672 (8:25:12 AM-1:23:02 PM) (S1)

Baseline observation:	LYT-37 -- LY-672 (B1)
Processed:	6/17/2014 10:02:52 AM
Solution type:	Fixed
Frequency used:	Dual Frequency (L1, L2)
Horizontal precision:	0.004 m
Vertical precision:	0.015 m
RMS:	0.003 m
Maximum PDOP:	2.424
Ephemeric used:	Broadcast
Antenna model:	Trimble Relative
Processing start time:	5/19/2014 8:25:27 AM (Local: UTC+8hr)
Processing stop time:	6/19/2014 1:23:02 PM (Local: UTC+8hr)
Processing duration:	04:57:35
Processing interval:	1 second

Vector Components (Mark to Mark)

From: LYT-37					
Grid		Local		Global	
Easting	662088.439 m	Latitude	N11°22'17.79317"	Latitude	N11°22'13.44918"
Northing	1257404.801 m	Longitude	E124°29'07.61902"	Longitude	E124°29'12.76807"
Elevation	4.299 m	Height	5.339 m	Height	65.998 m

To: LY-672					
Grid		Local		Global	
Easting	661172.874 m	Latitude	N11°27'22.51942"	Latitude	N11°27'18.15341"
Northing	1266762.334 m	Longitude	E124°28'38.99619"	Longitude	E124°28'44.13687"
Elevation	19.616 m	Height	20.793 m	Height	61.224 m

Vector					
ΔEasting	-915.666 m	NS Fwd Azimuth	354°42'21"	ΔX	1755.906 m
ΔNorthing	9357.533 m	Ellipsoid Dist.	9402.938 m	ΔY	-1023.439 m
ΔElevation	15.317 m	ΔHeight	15.454 m	ΔZ	9180.687 m

Standard Errors

Vector errors:					
σ ΔEasting	0.002 m	σ NS fwd Azimuth	0°00'00"	σ ΔX	0.004 m
σ ΔNorthing	0.001 m	σ Ellipsoid Dist.	0.001 m	σ ΔY	0.006 m
σ ΔElevation	0.007 m	σ ΔHeight	0.007 m	σ ΔZ	0.002 m

3. LYT-90

Table A-3.3. LYT-90

Vector Components (Mark to Mark)

From: CBU-340					
Grid		Local		Global	
Easting	660577.527 m	Latitude	N10°38'14.87646"	Latitude	N10°38'10.71737"
Northing	1176200.458 m	Longitude	E124°28'04.68006"	Longitude	E124°28'09.89389"
Elevation	14.571 m	Height	15.533 m	Height	77.920 m

To: LYT-90					
Grid		Local		Global	
Easting	675667.875 m	Latitude	N11°00'17.75728"	Latitude	N11°00'13.51665"
Northing	1216919.360 m	Longitude	E124°36'28.24066"	Longitude	E124°36'33.42083"
Elevation	14.187 m	Height	15.532 m	Height	77.386 m

Vector					
ΔEasting	15090.348 m	NS Fwd Azimuth	20°36'38"	ΔX	-8272.921 m
ΔNorthing	40718.902 m	Ellipsoid Dist.	43427.367 m	ΔY	-14957.504 m
ΔElevation	-0.384 m	ΔHeight	-0.001 m	ΔZ	39921.998 m

4. LYT-690

Table A-3.4. LYT-690

Vector Components (Mark to Mark)

From: LYT-704					
Grid		Local		Global	
Easting	870347.634 m	Latitude	N11°11'16.35419"	Latitude	N11°11'12.06307"
Northing	1237125.905 m	Longitude	E124°33'36.47427"	Longitude	E124°33'41.63876"
Elevation	37.077 m	Height	38.292 m	Height	99.584 m

To: LYT-690					
Grid		Local		Global	
Easting	675668.331 m	Latitude	N11°00'17.68909"	Latitude	N11°00'13.44846"
Northing	1216917.267 m	Longitude	E124°36'28.25530"	Longitude	E124°36'33.43548"
Elevation	3.015 m	Height	4.361 m	Height	66.214 m

Vector					
ΔEasting	5320.697 m	NS Fwd Azimuth	165°32'59"	ΔX	-6484.391 m
ΔNorthing	-20208.638 m	Ellipsoid Dist.	20697.960 m	ΔY	219.769 m
ΔElevation	-34.062 m	ΔHeight	-33.931 m	ΔZ	-19865.343 m

Standard Errors					
Vector errors:					
σ ΔEasting	0.002 m	σ NS fwd Azimuth	0°00'00"	σ ΔX	0.003 m
σ ΔNorthing	0.001 m	σ Ellipsoid Dist.	0.001 m	σ ΔY	0.005 m
σ ΔElevation	0.006 m	σ ΔHeight	0.006 m	σ ΔZ	0.002 m

5. RM-9

Table A-3.5. RM-9

**RM-9 - LYT-690 (1:21:40 PM-5:25:55 PM) (S1)**

Baseline observation:	RM-9 --- LYT-690 (B1)
Processed:	2/25/2015 4:28:35 PM
Solution type:	Fixed
Frequency used:	Dual Frequency (L1, L2)
Horizontal precision:	0.002 m
Vertical precision:	0.003 m
RMS:	0.002 m
Maximum PDOP:	2.189
Ephemeris used:	Broadcast
Antenna model:	Trimble Relative
Processing start time:	1/25/2015 1:22:03 PM (Local: UTC+8hr)
Processing stop time:	1/25/2015 5:25:55 PM (Local: UTC+8hr)
Processing duration:	04:03:52
Processing interval:	1 second

**Vector Components (Mark to Mark)**

From: LYT-690					
Grid		Local		Global	
Easting	675668.340 m	Latitude	N11°00'17.68890"	Latitude	N11°00'13.44827"
Northing	1216817.262 m	Longitude	E124°36'28.25559"	Longitude	E124°36'33.43578"
Elevation	3.039 m	Height	4.384 m	Height	66.238 m

To: RM-9					
Grid		Local		Global	
Easting	675879.222 m	Latitude	N11°00'18.53023"	Latitude	N11°00'14.28954"
Northing	1216843.169 m	Longitude	E124°36'28.61863"	Longitude	E124°36'33.79880"
Elevation	1.915 m	Height	3.260 m	Height	65.114 m

<b>Vector</b>					
$\Delta$ Easting	10.882 m	NS Fixed Azimuth	23°05'26"	$\Delta$ X	-5.641 m
$\Delta$ Northing	25.908 m	Ellipsoid Dist.	28.101 m	$\Delta$ Y	-11.228 m
$\Delta$ Elevation	-1.124 m	$\Delta$ Height	-1.123 m	$\Delta$ Z	25.180 m

**Standard Errors**

<b>Vector errors:</b>					
$\sigma$ $\Delta$ Easting	0.001 m	$\sigma$ NS fixed Azimuth	0°00'05"	$\sigma$ $\Delta$ X	0.001 m
$\sigma$ $\Delta$ Northing	0.001 m	$\sigma$ Ellipsoid Dist.	0.001 m	$\sigma$ $\Delta$ Y	0.001 m
$\sigma$ $\Delta$ Elevation	0.002 m	$\sigma$ $\Delta$ Height	0.002 m	$\sigma$ $\Delta$ Z	0.001 m

6. LYT-704bak

Table A-3.6. LYT-704bak

**Vector Components (Mark to Mark)**

From: LYT-704					
Grid		Local		Global	
Easting	670347.634 m	Latitude	N11°11'16.35419"	Latitude	N11°11'12.06307"
Northing	1237125.905 m	Longitude	E124°33'38.47427"	Longitude	E124°33'41.83876"
Elevation	37.077 m	Height	38.282 m	Height	89.584 m

To: LYT-704bak					
Grid		Local		Global	
Easting	670363.675 m	Latitude	N11°11'16.44188"	Latitude	N11°11'12.15076"
Northing	1237128.684 m	Longitude	E124°33'37.00349"	Longitude	E124°33'42.16798"
Elevation	36.879 m	Height	38.093 m	Height	89.385 m

Vector					
$\Delta$ Easting	16.041 m	NS Fed Azimuth	80°28'28"	$\Delta$ X	-12.816 m
$\Delta$ Northing	2.779 m	Ellipsoid Dist.	16.281 m	$\Delta$ Y	-9.899 m
$\Delta$ Elevation	-0.188 m	$\Delta$ Height	-0.188 m	$\Delta$ Z	2.605 m

**Standard Errors**

Vector errors:					
$\sigma$ $\Delta$ Easting	0.001 m	$\sigma$ NS Fed Azimuth	0°00'04"	$\sigma$ $\Delta$ X	0.001 m
$\sigma$ $\Delta$ Northing	0.000 m	$\sigma$ Ellipsoid Dist.	0.001 m	$\sigma$ $\Delta$ Y	0.001 m
$\sigma$ $\Delta$ Elevation	0.001 m	$\sigma$ $\Delta$ Height	0.001 m	$\sigma$ $\Delta$ Z	0.000 m

**Aposteriori Covariance Matrix (Meter<sup>2</sup>)**

	X	Y	Z
X	0.0000004270		
Y	-0.0000001498	0.0000005232	
Z	-0.0000000477	0.0000000726	0.0000001116



7. CBU-340

Table A-3.7. CBU-340

**LYT-89 - CBU-340 (11:38:45 AM-4:56:27 PM) (S3)**

<b>Baseline observation:</b>	LYT-89 --- CBU-340 (B3)
<b>Processed:</b>	3/30/2016 6:34:43 PM
<b>Solution type:</b>	Fixed
<b>Frequency used:</b>	Dual Frequency (L1, L2)
<b>Horizontal precision:</b>	0.003 m
<b>Vertical precision:</b>	0.013 m
<b>RMS:</b>	0.003 m
<b>Maximum PDOP:</b>	2.938
<b>Ephemeric used:</b>	Broadcast
<b>Antenna model:</b>	NGS Absolute
<b>Processing start time:</b>	3/19/2016 11:38:45 AM (Local: UTC+8hr)
<b>Processing stop time:</b>	3/19/2016 4:56:27 PM (Local: UTC+8hr)
<b>Processing duration:</b>	05:17:42
<b>Processing interval:</b>	1 second

**Vector Components (Mark to Mark)**

<b>From: CBU-340</b>					
	<b>Grid</b>		<b>Local</b>		<b>Global</b>
<b>Easting</b>	660577.527 m	<b>Latitude</b>	N10°38'14.87646"	<b>Latitude</b>	N10°38'10.71737"
<b>Northing</b>	1176200.458 m	<b>Longitude</b>	E124°28'04.68006"	<b>Longitude</b>	E124°28'09.89389"
<b>Elevation</b>	14.571 m	<b>Height</b>	15.533 m	<b>Height</b>	77.920 m

<b>To: LYT-89</b>					
	<b>Grid</b>		<b>Local</b>		<b>Global</b>
<b>Easting</b>	658814.280 m	<b>Latitude</b>	N10°55'37.82577"	<b>Latitude</b>	N10°55'33.58987"
<b>Northing</b>	1208222.807 m	<b>Longitude</b>	E124°26'59.20715"	<b>Longitude</b>	E124°28'04.39573"
<b>Elevation</b>	12.453 m	<b>Height</b>	13.758 m	<b>Height</b>	75.369 m

<b>Vector</b>					
<b>ΔEasting</b>	-3963.267 m	<b>NS Fixed Azimuth</b>	353°13'09"	<b>ΔX</b>	6536.228 m
<b>ΔNorthing</b>	32022.348 m	<b>Ellipsoid Dist.</b>	32269.539 m	<b>ΔY</b>	-2767.852 m
<b>ΔElevation</b>	-2.118 m	<b>ΔHeight</b>	-1.775 m	<b>ΔZ</b>	31477.438 m

**Standard Errors**

<b>Vector errors:</b>					
<b>σ ΔEasting</b>	0.001 m	<b>σ NS fixed Azimuth</b>	0°00'00"	<b>σ ΔX</b>	0.004 m
<b>σ ΔNorthing</b>	0.001 m	<b>σ Ellipsoid Dist.</b>	0.001 m	<b>σ ΔY</b>	0.006 m
<b>σ ΔElevation</b>	0.007 m	<b>σ ΔHeight</b>	0.007 m	<b>σ ΔZ</b>	0.002 m

8. W-22

Table A-3.8. W-22

Vector Components (Mark to Mark)

From: W-22					
Grid		Local		Global	
Easting	675563.750 m	Latitude	N11°00'18.93705"	Latitude	N11°00'14.69624"
Northing	1216955.050 m	Longitude	E124°36'24.81698"	Longitude	E124°36'29.99714"
Elevation	6.321 m	Height	7.666 m	Height	69.516 m

To: LYT-89					
Grid		Local		Global	
Easting	656614.289 m	Latitude	N10°55'37.85585"	Latitude	N10°55'33.61994"
Northing	1208223.732 m	Longitude	E124°25'59.20825"	Longitude	E124°26'04.39683"
Elevation	6.075 m	Height	7.380 m	Height	68.991 m

Vector					
ΔEasting	-18949.461 m	NS Fwd Azimuth	245°34'01"	ΔX	14718.902 m
ΔNorthing	-8731.318 m	Ellipsoid Dist.	20865.492 m	ΔY	12117.344 m
ΔElevation	-0.246 m	ΔHeight	-0.286 m	ΔZ	-8478.938 m

## ANNEX 4. The LiDAR Survey Team Composition

Table A-4.1. LiDAR Survey Team Composition

Data Acquisition Component Sub-Team	Designation	Name	Agency / Affiliation
<b>PHIL-LIDAR 1</b>	Program Leader	ENRICO C. PARINGIT, D.ENG	UP-TCAGP
<b>Data Acquisition Component Leader</b>	Data Component Project Leader – I	ENGR. CZAR JAKIRI SARMIENTO	UP-TCAGP
		ENGR. LOUIE P. BALICANTA	UP-TCAGP
<b>Survey Supervisor</b>	Chief Science Research Specialist (CSRS)	ENGR. CHRISTOPHER CRUZ	UP-TCAGP
	Supervising Science Research Specialist (Supervising SRS)	LOVELY GRACIA ACUNA	UP-TCAGP
		ENGR. LOVELYN ASUNCION	UP-TCAGP
<b>FIELD TEAM</b>			
	Senior Science Research Specialist (SSRS)	JULIE PEARL MARS	UP-TCAGP
		JASMINE ALVIAR	UP-TCAGP
		PAULINE JOANNE ARCEO	UP-TCAGP
		PAULINE JOANNE ARCEO	UP-TCAGP
<b>LiDAR Operation</b>	Research Associate (RA)	MARY CATHERINE ELIZABETH BALIGUAS	UP-TCAGP
		GRACE SINDJAN	UP-TCAGP
		LARAH KRISSELLE PARAGAS	UP-TCAGP
		JONALYN GONZALES	UP-TCAGP
		FRANK NICOLAS ILEJAY	UP-TCAGP
<b>Ground Survey, Data Download and Transfer</b>	RA	IRO NIEL ROXAS	UP-TCAGP
		FRANK NICOLAS ILEJAY	UP-TCAPG
		DAN CHRISTOFFER ALDOVINO	UP-TCAGP
		JERIEL PAUL ALAMBAN, GEOL.	UP-TCAPG
<b>LiDAR Operation</b>	Airborne Security	SSG. RAYMUND DOMINE	PHILIPPINE AIR FORCE (PAF)
		SSG. RANDY SISON	PAF
		TSG. SANDY UY	PAF
	Pilot	CAPT. JACKSON JAVIER	ASIAN AEROSPACE CORPORATION (AAC)
		CAPT. JEFFREY JEREMY ALAJAR	AAC
		CAPT. NIEL ACHILLES AGAWIN	AAC
		CAPT. JEROME MOONEY	AAC
		CAPT. ANTHONY DAYO	AAC
		CAPT. FERDINAND DE OCAMPO	AAC

ANNEX 5. Data Transfer Sheets for the Pagsangahan Floodplain Flights

DATA TRANSFER SHEET																	
Feb 3, 2014																	
DATE	FLIGHT NO.	MISSION NAME	SENSOR	RAW LAS		LOGS	POS	RAW IMAGES	MISSION LOG	RANGE	DIGITIZER	BASE		OPERATOR LOGS (OPLO)	FLIGHT PLAN		SERVER LOCATION
				Output LAS	KML ( swath)							BASE STATIC (NS)	Base Info (Jed)		Actual	KML	
28-Jan-14	3032A	28UK3AC28A	Aquarius	N/A	N/A	937 KB	54.6 MB	249 GB	246 KB	13.7 GB	90.1 GB	10.8 MB	88 BYTES	651 BYTES	4.08 KB	548 KB	Y:\Airborne_Raw\11232A
29-Jan-14	3034A	28UK3AC28A	Aquarius	N/A	N/A	943 KB	11.7 MB	27.2 GB	201 KB	6.12 GB	28.7 GB	18.2 MB	71 BYTES	369 BYTES	2.86 KB	243 KB	Y:\Airborne_Raw\11235A
30-Jan-14	1840A	28UK3AC28A	Aquarius	N/A	N/A	738 KB	31.7 MB	35.3 GB	302 KB	3.33 GB	1.14 GB	11.7 MB	305 BYTES	1.46 KB	8.85 KB	395 KB	Y:\Airborne_Raw\11236A

Received from

Name Rhicia Alcantara

Position CA

Signature [Signature]

Received by

Name JOYDA F. PRYTO

Position SSRS

Signature \_\_\_\_\_

Figure A-5.1. Data Transfer Sheet for Pagsangahan Floodplain – A



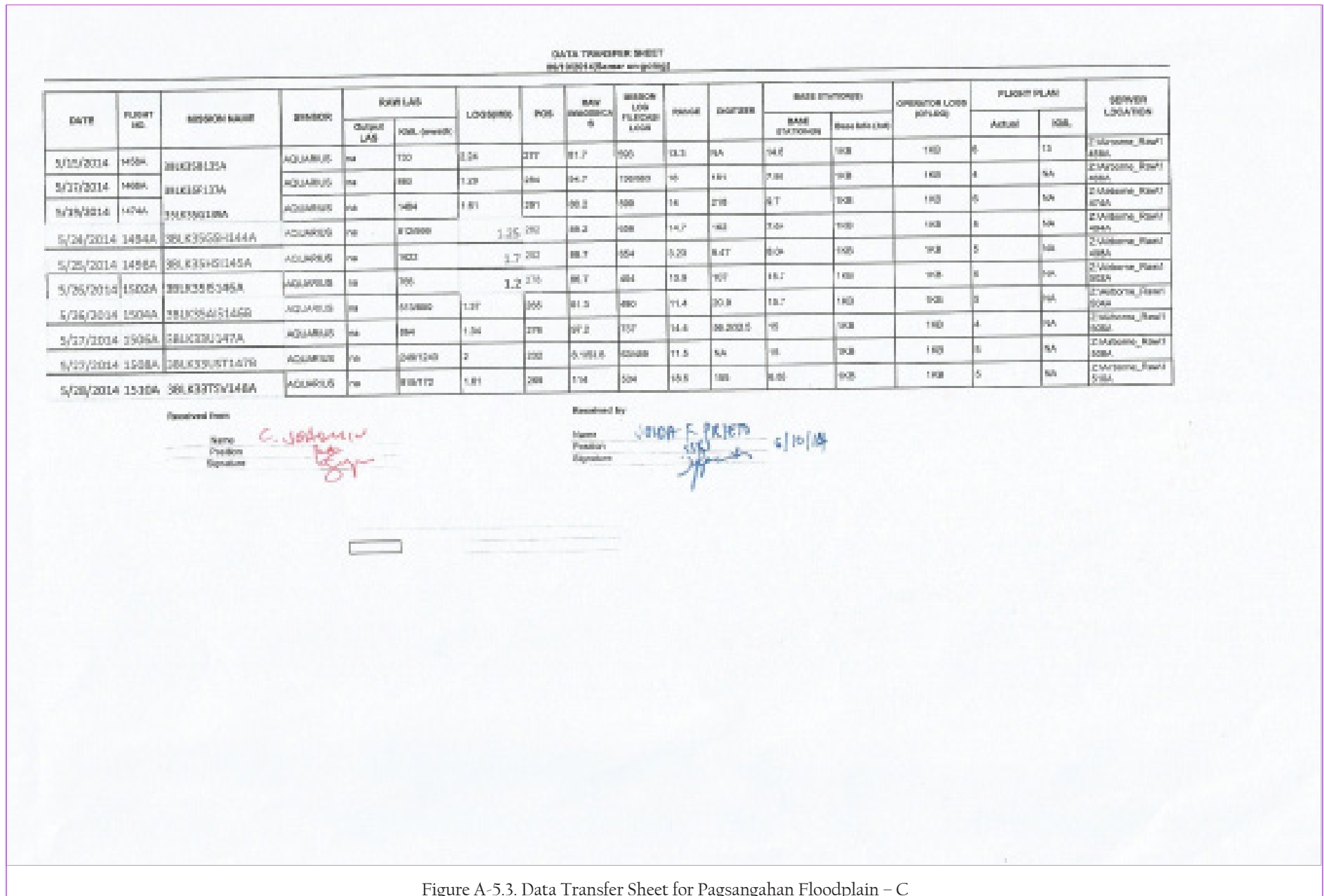


Figure A-5.3. Data Transfer Sheet for Pagsangahan Floodplain – C

## ANNEX 6. Flight Logs for the Flight Missions

### 1. Flight Log for 1032A Mission

Flight Log No.: 1032A

**DREAM Data Acquisition Flight Log**

1 LIDAR Operator: <u>Faith Sabilo</u>		2 ALTM Model: <u>Leica</u>		3 Mission Name: <u>1032A</u>		4 Type: <u>VIR</u>		5 Aircraft Type: <u>Cessna T300H</u>		6 Aircraft Identification: <u>RP-1902</u>	
7 Pilot:		8 Co-Pilot:		9 Route:							
10 Date: <u>Jan 28, 2019</u>				12 Airport of Departure (Airport, City/Province): <u>Tacolban City</u>				13 Airport of Arrival (Airport, City/Province): <u>Tacolban City</u>			
11 Engine On: <u>5:59</u>		14 Engine Off: <u>13:40</u>		15 Total Engine Time: <u>4:41</u>		16 Take off:		17 Landing:		18 Total Flight Time:	
19 Weather:											
20 Remarks:  <p style="text-align: center; font-size: 1.2em;">Successful flight</p>											
21 Problems and Solutions:											

<p>Acquisition Flight Approved by</p>  <p>Signature over Printed Name (End User Representative)</p>	<p>Acquisition Flight Certified by</p>  <p>Signature over Printed Name (PRP Representative)</p>	<p>Pilot-in-Command</p>  <p>Signature over Printed Name</p>	<p>Lidar Operator</p>  <p>Signature over Printed Name</p>
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Figure A-6.1. Flight Log for Mission 1032A

2. Flight Log for 1458A Mission


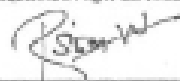


DCAM Data Acquisition Flight Log						Flight Log No. 1458
1 LIDAR Operator: <u>Joe Rosal</u>	2 ALTM Model: <u>DQA</u>	3 Mission Name: <u>PHILBYA 135A</u>	4 Type: <u>VFR</u>	5 Aircraft Type: <u>Cessna T206H</u>	6 Aircraft Identification:	
7 Pilot: <u>J. Rosal</u>	8 Co-Pilot: <u>R. Dizon</u>	9 Route:		12 Airport of Arrival (Airport, City/Province):		
10 Date: <u>16 May 2014</u>	12 Airport of Departure (Airport, City/Province):		18 Total Flight Time:			
13 Engine On: <u>7:51</u>	14 Engine Off: <u>12:26</u>	15 Total Engine Time: <u>4:35</u>	16 Take off:	17 Landing:		
19 Weather:						
20 Remarks:  <p style="text-align: center;">Completed mission over BL303B</p>						
21 Problems and Solutions:						
Acquisition Flight Approved by  _____ Signature over Printed Name (End User Representative)		Acquisition Flight Certified by  _____ Signature over Printed Name (PIF Representative)		Pilot-in-Command  _____ Signature over Printed Name		Lidar Operator  _____ Signature over Printed Name

Figure A-6.2. Flight Log for Mission 1458A



3. Flight Log for 1460A Mission

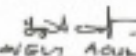
DREAM Data Acquisition Flight Log Flight Log No.: 1460

1 LIDAR Operator: F. AACB	2 ALTM Model: A424	3 Mission Name: Bk25C	4 Type: VFR	5 Aircraft Type: Cessna 120B	6 Aircraft Identification: 9142
7 Pilot: U. AYUER	8 Co-Pilot: N. AGANIN	9 Route:			
10 Date: 15 MAY 2014	11 Airport of Departure (Airport, City/Province):		12 Airport of Arrival (Airport, City/Province):		
13 Engine On: 13:32	14 Engine Off: 14:09	15 Total Engine Time: 4:35	16 Take off:	17 Landing:	18 Total Flight Time:

19 Weather

20 Remarks:  
 Completed mission over Bk25C and some lines over Bk25D.

21 Problems and Solutions:

Acquisition Flight Approved by  
  
 Signature over Printed Name  
 (End User Representative)

Acquisition Flight Certified by  
  
 Signature over Printed Name  
 (PAF Representative)

Pilot-in-Command  
  
 Signature over Printed Name


Lidar Operator  
  
 Signature over Printed Name



Figure A-6.3. Flight Log for Mission 1460A

4. Flight Log for 1462A Mission

Flight Log No.: 1462

**DREAM Data Acquisition Flight Log**

1 LIDAR Operator: <u>F. JAMES</u>	2 ALTM Model: <u>APHA</u>	3 Mission Name: <u>BLK 350 1364</u>	4 Type: <u>VFR</u>	5 Aircraft Type: <u>Cesna T206H</u>	6 Aircraft Identification: <u>9112</u>
7 Pilot: <u>J. JAMES</u>	8 Co-Pilot: <u>N. A. A. A. A. A.</u>	9 Route:			
10 Date: <u>14 MAY 2014</u>		12 Airport of Departure (Airport, City/Province):		12 Airport of Arrival (Airport, City/Province):	
13 Engine On: <u>0806</u>	14 Engine Off: <u>1247</u>	15 Total Engine Time: <u>441</u>	16 Take off:	17 Landing:	18 Total Flight Time:
19 Weather:					
20 Remarks:  <p style="text-align: center;">Completed mission over BLK 350 and to base over BLK 356</p>					
21 Problems and Solutions:					

Acquisition Flight Approved by  Signature over Printed Name (End User Representative)	Acquisition Flight Certified by  Signature over Printed Name (PAF Representative)	Pilot-in-Command  Signature over Printed Name	Lidar Operator  Signature over Printed Name
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Figure A-6.4. Flight Log for Mission 1462A

5. Flight Log for 1464A Mission

Flight Log No: 1464

**DREAM Data Acquisition Flight Log**

1 LIDAR Operator: P. JAYAR	2 ALTM Model: A1004	3 Mission Name: 1464A	4 Type: VFR	5 Aircraft Type: Cessna T206H	6 Aircraft Identification: 9122
7 Pilot: U. JAYAR	8 Co-Pilot: N. ALANON	9 Route:			
10 Date: 16 MAY 2014	11 Airport of Departure (Airport, City/Province):		12 Airport of Arrival (Airport, City/Province):		
13 Engine On: 1344	14 Engine Off: 1355	15 Total Engine Time: 4:11	16 Take off:	17 Landing:	18 Total Flight Time:
19 Weather:					
20 Remarks:  Completed 4/8 lines left over 1464B					
21 Problems and Solutions:					

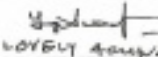



Acquisition Flight Approved by  Signature over Printed Name (End User Representative)	Acquisition Flight Certified by  Signature over Printed Name (PAF Representative)	Pilot-in-Command  Signature over Printed Name	Lidar Operator  Signature over Printed Name
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Figure A-6.5. Flight Log for Mission 1464A

6. Flight Log for 1466A Mission

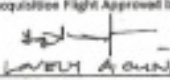
DREAM Data Acquisition Flight Log Flight Log No. 1466

1 LIDAR Operator: P. Acosta	2 ALTM Model: Aeva	3 Mission Name: BULSEP 1466A	4 Type: VFR	5 Aircraft Type: Cessna T206H	6 Aircraft Identification: 7133
7 Pilot: M. JAVIER	8 Co-Pilot: M. Acosta	9 Route:			
10 Date: 17 MAY 14	12 Airport of Departure (Airport, City/Province):		12 Airport of Arrival (Airport, City/Province):		
13 Engine On: 0743	14 Engine Off: 0830	15 Total Engine Time: 477	16 Take off:	17 Landing:	18 Total Flight Time:

19 Weather

20 Remarks:  
 Completed mission over BULSEP with wpts due to strong winds.

21 Problems and Solutions:

Acquisition Flight Approved by  
  
 Signature over Printed Name  
 (End User Representative)

Acquisition Flight Certified by  
  
 Signature over Printed Name  
 (PIA Representative)

Pilot-in-Command  
  
 Signature over Printed Name

Lidar Operator  
  
 Signature over Printed Name



Figure A-6.6. Flight Log for Mission 1466A

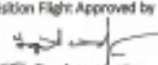
7. Flight Log for 1474A Mission

Flight Log No.: 1474

**DREAM Data Acquisition Flight Log**


1 LIDAR Operator: F. JAVIER	2 ALTM Model: 400A	3 Mission Name: BLK 35 G 130A	4 Type: VFR	5 Aircraft Type: Cessna T206H	6 Aircraft Identification: 0112
7 Pilot: F. JAVIER	8 Co-Pilot: N. ALARIN	9 Route:	12 Airport of Arrival (Airport, City/Province):		
10 Date: 09 May 14	12 Airport of Departure (Airport, City/Province):		13 Total Flight Time:		
13 Engine On: 0730	14 Engine Off: 1425	15 Total Engine Time: 0755	16 Take off:	17 Landing:	18 Total Flight Time:
19 Weather					
20 Remarks: Completed with coverage from BLK L, D, E & F and G line from BLK 35 G.					
21 Problems and Solutions:					

Acquisition Flight Approved by



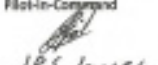
LOPEL A. ALARIN  
Signature over Printed Name  
(End User Representative)

Acquisition Flight Certified by



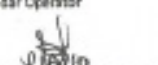
Signature over Printed Name  
(RNF Representative)

Pilot-in-Command




F. JAVIER  
Signature over Printed Name

Lidar Operator



Signature over Printed Name

**DREAM** 

Disaster Risk and Exposure Assessment for Mitigation

Figure A-6.7. Flight Log for Mission 1474A

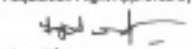
8. Flight Log for 1494A Mission

Flight Log No: PL 017

**DREAM Data Acquisition Flight Log**


1 LIDAR Operator: <u>E. ARCELO</u>	2 ALTM Model: <u>BAI-1</u>	3 Mission Name: <u>BAR356</u>	4 Mission Type: <u>VFR</u>	5 Aircraft Type: <u>Cessna T206H</u>	6 Aircraft Identification: <u>W20</u>
7 Pilot: <u>J. JAVIER</u>	8 Co-Pilot: <u>N. ALAMIN</u>	9 Route:			
10 Date: <u>24 APR 14</u>	11 Airport of Departure (Airport, City/Province):		12 Airport of Arrival (Airport, City/Province):		
13 Engine On: <u>0743</u>	14 Engine Off: <u>1239</u>	15 Total Engine Time: <u>4953</u>	16 Take off:	17 Landing:	18 Total Flight Time:
19 Weather:					
20 Remarks:  Completed mission over BAR356 and 4 hrs over BAR358.					
21 Problems and Solutions:					

Acquisition Flight Approved by




E. ARCELO  
Signature over Printed Name  
(End User Representative)

Acquisition Flight Certified by




ESTHER J. LARUA  
Signature over Printed Name  
(PAF Representative)

Pilot-in-Command




J. JAVIER  
Signature over Printed Name

Lidar Operator



E. ARCELO  
Signature over Printed Name



**DREAM**  
Disaster Risk and Exposure Assessment for Mitigation

Figure A-6.8. Flight Log for Mission 1494A

9. Flight Log for 1498A Mission

DREAM Data Acquisition Flight Log Flight Log No. 1498A

1 LIDAR Operator: <u>P. JAVIER</u>	2 ALTM Model: <u>AcuX</u>	3 Mission Name: <u>34-R359A</u>	4 Type: <u>VFR</u>	5 Aircraft Type: <u>Cessna T208H</u>	6 Aircraft Identification: <u>9142</u>
7 Pilot: <u>P. JAVIER</u>	8 Co-Pilot: <u>N. SCARVIN</u>	9 Route:			
10 Date: <u>20 MAY 14</u>	11 Airport of Departure (Airport, City/Province):		12 Airport of Arrival (Airport, City/Province):		
13 Engine On: <u>0750</u>	14 Engine Off: <u>1231</u>	15 Total Engine Time: <u>441</u>	16 Take off:	17 Landing:	18 Total Flight Time:

19 Weather: \_\_\_\_\_

20 Remarks:  
 Completed mission over 34-R359A and 4 lines over 34-R352I.

21 Problems and Solutions:

Acquisition Flight Approved by  
  
Levent ACUNA  
 Signature over Printed Name  
 (End User Representative)

Acquisition Flight Certified by  
  
P. JAVIER  
 Signature over Printed Name  
 (Pilot Representative)

Pilot-in-Command  
  
P. JAVIER  
 Signature over Printed Name

Lidar Operator  
  
CHRISTINE BARRAS  
 Signature over Printed Name



Figure A-6.9. Flight Log for Mission 1498A

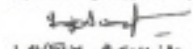
10. Flight Log for 1502A Mission

Flight Log No. 1502A

**DREAM Data Acquisition Flight Log**

1 LIDAR Operator: <u>MOE BENCURT</u>	2 ALTM Model: <u>ADWA</u>	3 Mission Name: <u>BUKUSA</u>	4 Type: <u>VFR</u>	5 Aircraft Type: <u>Cessna T206H</u>	6 Aircraft Identification: <u>91332</u>
7 Pilot: <u>J. JAVIER</u>	8 Co-Pilot: <u>J. AGANAW</u>	9 Route:			
10 Date: <u>26 MAY 14</u>	12 Airport of Departure (Airport, City/Province):		12 Airport of Arrival (Airport, City/Province):		
13 Engine On: <u>0504</u>	14 Engine Off: <u>047</u>	15 Total Engine Time: <u>044</u>	16 Take off:	17 Landing:	18 Total Flight Time:
19 Weather					
20 Remarks:  <p style="text-align: center;">Completed mission over BUKUSA and 2 lines over BUKUSI</p>					
21 Problems and Solutions:					

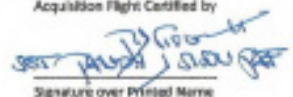
Acquisition Flight Approved by



LOVELY ACUÑA

Signature over Printed Name  
(End User Representative)


Acquisition Flight Certified by



J. AGANAW

Signature over Printed Name  
(NAF Representative)


Pilot-in-Command



JRS JAVIER


Signature over Printed Name

Lidar Operator



MOIE BENCURT

Signature over Printed Name



**DREAM**  
Disaster Risk and Exposure Assessment for Mitigation

Figure A-6.10. Flight Log for Mission 1502A



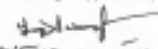
11. Flight Log for 1504A Mission

Flight Log No. 1504A

**DREAM Data Acquisition Flight Log** 1504A/1504A

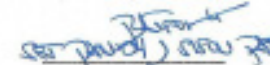
1 LIDAR Operator: <u>NICE DUMOLIN</u>	2 ALTM Model: <u>ALTA</u>	3 Mission Name: <u>1504A/1504A</u>	4 Type: <u>VFR</u>	5 Aircraft Type: <u>Cessna T206H</u>	6 Aircraft Identification: <u>N142</u>
7 Pilot: <u>J. JAVIER</u>	8 Co-Pilot: <u>M. ALARCON</u>	9 Route:			
10 Date: <u>26 MAR 14</u>	12 Airport of Departure (Airport, City/Province):		12 Airport of Arrival (Airport, City/Province):		
13 Engine On: <u>13:18</u>	14 Engine Off: <u>14:11</u>	15 Total Engine Time: <u>47:23</u>	16 Take off:	17 Landing:	18 Total Flight Time:
19 Weather					
20 Remarks:  <p style="text-align: center;">Completed mission over BUKAY.</p>					
21 Problems and Solutions:					

Acquisition Flight Approved by




LOVELY BONGIA  
Signature over Printed Name  
(End User Representative)

Acquisition Flight Certified by




JOY PANGILO  
Signature over Printed Name  
(PAF Representative)

Pilot-in-Command




JRS JAVIER  
Signature over Printed Name

Lidar Operator



ART MANSUETO  
Signature over Printed Name



**DREAM**  
Disaster Risk and Exposure Assessment for Mitigation


Figure A-6.11. Flight Log for Mission 1504A

12. Flight Log for 7753AC Mission

PHIL-LIDAR 1 Data Acquisition Flight Log

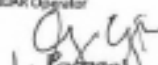
Flight Log No.: 7753AC

1 LIDAR Operator: L. Paragas	2 ALTM Model: Aqueduct	3 Mission Name: 384-753021A	4 Type: VFR	5 Aircraft Type: Cessna T206H	6 Aircraft Identification: RP-C9422
7 Pilot: F. De Ocampo	8 Co-Pilot: N. Arroyo	9 Route: Olongapo	12 Airport of Arrival (Airport, City/Province):		
10 Date: Jan 21, 2015	12 Airport of Departure (Airport, City/Province):		18 Total Flight Time: 0410		
13 Engine On: 0619	14 Engine Off: 1028	15 Total Engine Time: 0411	16 Take off: 0624	17 Landing: 1035	
19 Weather					
20 Flight Classification			21 Remarks		
20.a Billable <input checked="" type="checkbox"/> Acquisition Flight <input type="checkbox"/> Ferry Flight <input type="checkbox"/> System Test Flight <input type="checkbox"/> Calibration Flight			Completed 14 lines of BUK 358		
20.b Non Billable <input type="checkbox"/> Aircraft Test Flight <input type="checkbox"/> AAC Admin Flight <input type="checkbox"/> Others: _____					
20.c Others <input type="checkbox"/> LIDAR System Maintenance <input type="checkbox"/> Aircraft Maintenance <input type="checkbox"/> Phil-LIDAR Admin Activities					
22 Problems and Solutions					
<input type="checkbox"/> Weather Problem <input type="checkbox"/> Systems Problem <input type="checkbox"/> Aircraft Problem <input type="checkbox"/> Pilot Problem <input type="checkbox"/> Others: _____					

Acquisition Flight Approved by  
  
 Peter Nolas  
 Signature over Printed Name  
 (End User Representative)

Acquisition Flight Certified by  
  
 SGT. RANDY OREN  
 Signature over Printed Name  
 (PMF Representative)

Pilot is Certified  
  
 F. De Ocampo  
 Signature over Printed Name

LIDAR Operator  
  
 L. Paragas  
 Signature over Printed Name

Aircraft Mechanic/ LIDAR Technician  
 \_\_\_\_\_  
 Signature over Printed Name

Figure A-6.12. Flight Log for Mission 7753AC

13. Flight Log for 7760AC Mission

Flight Log No.: 7760

PHIL-LIDAR 1 Data Acquisition Flight Log					
1 LIDAR Operator: <u>S. Smedjan</u>	2 ALTM Model: <u>ATC</u>	3 Mission Name: <u>30A 35A</u>	4 Type: <u>VFR</u>	5 Aircraft Type: <u>Cessna T20GH</u>	6 Aircraft Identification: <u>9322</u>
7 Pilot: <u>N. Rajawin</u>	8 Co-Pilot: <u>Ar. Ocampo</u>	9 Route:			
10 Date: <u>01-25-15</u>	11 Airport of Departure (Airport, City/Province): <u>Omanec</u>		12 Airport of Arrival (Airport, City/Province): <u>Omanec</u>		
13 Engine On: <u>13:28</u>	14 Engine Off: <u>17:39</u>	15 Total Engine Time: <u>4:11</u>	16 Take off: <u>13:32</u>	17 Landing: <u>17:54</u>	18 Total Flight Time: <u>4:01</u>
19 Weather: <u>Fair</u>					
20 Remarks:  <p style="text-align: center;">Completed Bk 35A with Digitizer NO CASI</p>					
21 Problems and Solutions:					
<p>Acquisition Flight Approved by: <u>[Signature]</u> Signature over Printed Name (End User Representative)</p> <p>Acquisition Flight Certified by: <u>[Signature]</u> Signature over Printed Name (PWF Representative)</p> <p>Site-in-Charge: <u>[Signature]</u> Signature over Printed Name</p> <p>Lidar Operator: <u>[Signature]</u> Signature over Printed Name</p>					

Figure A-6.13. Flight Log for Mission 7760AC

14. Flight Log for 7780AC Mission

Flight Log No.: 7780

PHIL-LIDAR 1 Data Acquisition Flight Log					
1 LIDAR Operator: <u>S. P. [Signature]</u>	2 ALTM Model: <u>ATC</u>	3 Mission Name: <u>30N JCAR</u>	4 Type: <u>VFR</u>	5 Aircraft Type: <u>Cessna T206H</u>	6 Aircraft Identification:
7 Pilot:	8 Co-Pilot:	9 Route: <u>035A</u>	12 Airport of Arrival (Airport, City/Province): <u>Ormoc</u>		
10 Date: <u>02-04-95</u>	11 Airport of Departure (Airport, City/Province): <u>Boac</u>	13 Engine On: <u>9:54</u>	14 Engine Off: <u>11:11</u>	15 Total Engine Time: <u>1:17</u>	18 Total Flight Time: <u>1:08</u>
16 Take off: <u>9:59</u>	17 Landing: <u>11:07</u>	19 Weather: <u>Fair &amp; Windy</u>			
20 Remarks: <p style="text-align: center;"><i>Flight aborted due to strong wind</i></p>					
21 Problems and Solutions:					

<p>Acquisition Flight Approved by</p> <p><u>[Signature]</u></p> <p>Signature over Printed Name (Civil User Representative)</p>	<p>Acquisition Flight Certified by</p> <p><u>[Signature]</u></p> <p>Signature over Printed Name (PAF Representative)</p>	<p>Pilot-in-Command</p> <p><u>[Signature]</u></p> <p>Signature over Printed Name</p>	<p>Lidar Operator</p> <p><u>[Signature]</u></p> <p>Signature over Printed Name</p>
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Figure A-6.14. Flight Log for Mission 7780AC

15. Flight Log for 7782AC Mission

Flight Log No: 7782

PHIL-LIDAR Lidar Data Acquisition Flight Log

1 LIDAR Operator: <u>LK Paragas</u>	2 ALTM Model: <u>ATC</u>	3 Mission Name: <u>Blk 35 AX</u>	4 Type: <u>VFR</u>	5 Aircraft Type: <u>Cessna T208H</u>	6 Aircraft Identification:
7 Pilot: <u>P. KERRIN</u>	8 Co-Pilot: <u>F. DEOCAMPID</u>	9 Route:			
10 Date: <u>02-05-15</u>	12 Airport of Departure (Airport, City/Province): <u>Ormoc</u>		12 Airport of Arrival (Airport, City/Province): <u>Ormoc</u>		
13 Engine On: <u>9+13</u>	14 Engine Off: <u>13+36</u>	15 Total Engine Time: <u>4+23</u>	16 Take off: <u>9+18</u>	17 Landing: <u>13+32</u>	18 Total Flight Time: <u>4+14</u>
19 Weather: <u>Fair &amp; windy</u>					
20 Remarks: <u>Completed Blk 35 AX, curvy swath due to strong wind. N/A Dig. No CAS!</u>					
21 Problems and Solutions:					

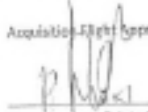
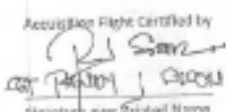


Acquisition Flight Approved by  Signature over Printed Name (and Lidar Representative)	Acquisition Flight Certified by  Signature over Printed Name (NIP Representative)	Pilot in Command  Signature over Printed Name	Lidar Operator  Signature over Printed Name
--	--	--	--

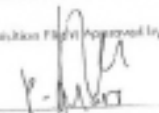
Figure A-6.15. Flight Log for Mission 7782AC

16. Flight Log for 7802AC Mission

Flight Log No.: 7802

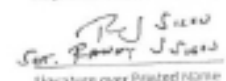
Phil-LIDAR 1 Data Acquisition Flight Log					
1 Lidar Operator: <u>UK PANGOS</u>	2 ALTM Model: <u>A+C</u>	3 Mission Name: <u>301KASV06A</u>	4 Type: <u>VFR</u>	5 Aircraft Type: <u>Cesna T200H</u>	6 Aircraft Identification: <u>9322</u>
7 Pilot: <u>N. ACANIN</u>	8 Co-Pilot: <u>F. YB ALMAD</u>	9 Route:	12 Airport of Arrival (Airport, City/Province): <u>TRINIDAD</u>		
10 Date: <u>02-05-15</u>	11 Airport of Departure (Airport, City/Province): <u>DLMN</u>		13 Engine On: <u>9+40</u>	14 Engine Off: <u>13+57</u>	15 Total Engine Time: <u>9+11</u>
16 Weather: <u>cloudy</u>			16 Take off:	17 Landing:	18 Total Flight Time:
20 Remarks: <p style="text-align: center;">* surveyed voids &amp; short ranges of BLK 30 w/ digitizer.          NO cast.</p>					
21 Problems and Solutions:					

Acquisition Flight Approved by




Signature over Printed Name  
(End User Representative)

Acquisition Flight Certified by




Signature over Printed Name  
(PAF Representative)

Pilot in Command



Signature over Printed Name

Lidar Operator



Signature over Printed Name

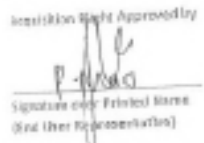
Figure A-6.16. Flight Log for Mission 7802AC

17. Flight Log for 7806AC Mission

Flight Log No: 786

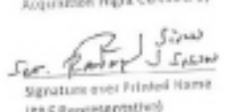
1. Date: 02-17-15						2. Mission Name: 7806AC		3. Flight Type: VFR		4. Aircraft Type: Cessna T200H		5. Aircraft Identification: 9322	
6. Pilot: N. MANNIN				7. Co-Pilot: P. DE GUARDIA				8. Route:					
9. Airport of Departure (Airport, City/Province):				10. Airport of Arrival (Airport, City/Province):				11. Total Flight Time:					
12. Engine On: 9:15				13. Engine Off: 11:26				14. Total Engine Time: 3:23					
15. Weather: Cloudy				16. Take off:				17. Landing:					
18. Remarks: Surveyed BLK 35 with digitizer. NO CASI.													
19. Problems and Solutions:													

Acquisition Flight Approved by



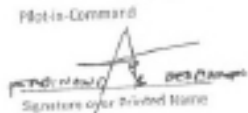
Signature over Printed Name  
(Not User Representation)

Acquisition Flight Certified by




Signature over Printed Name  
(PAF Representative)

Pilot-in-Command



Signature over Printed Name

Lidar Operator



Signature over Printed Name

Figure A-6.17. Flight Log for Mission 7806AC

18. Flight Log for 8389AC Mission

PHIL-LIDAR 1 Data Acquisition Flight Log

Flight Log No.: 8389AC

1 LIDAR Operator: <u>L. Parnagos</u>	2 ALTM Model: <u>Aguninis</u>	3 Mission Name: <u>SALV-35A-009A</u>	4 Type: <u>VFR</u>	5 Aircraft Type: <u>Cessna T206H</u>	6 Aircraft Identification: <u>RP-C9302</u>
7 Pilot: <u>C. Alfonso III</u>	8 Co-Pilot: <u>J. Javier</u>	9 Route: <u>Ormae</u>			
10 Date: <u>03-09-2016</u>	11 Airport of Departure (Airport, City/Province):		12 Airport of Arrival (Airport, City/Province):		
13 Engine On: <u>0730</u>	14 Engine Off: <u>1147</u>	15 Total Engine Time: <u>0417</u>	16 Take off: <u>0730</u>	17 Landing: <u>1142</u>	18 Total Flight Time: <u>0407</u>
19 Weather					
20 Flight Classification			21 Remarks		
20.a. Billable	20.b. Non Billable	20.c. Others	<u>Surveyed Pagiangahan PP @ 500 m</u>		
<input checked="" type="checkbox"/> Acquisition Flight <input type="checkbox"/> Ferry Flight <input type="checkbox"/> System Test Flight <input type="checkbox"/> Calibration Flight	<input type="checkbox"/> Aircraft Test Flight <input type="checkbox"/> AAC Admin Flight <input type="checkbox"/> Others: _____	<input type="checkbox"/> LIDAR System Maintenance <input type="checkbox"/> Aircraft Maintenance <input type="checkbox"/> Phil-LIDAR Admin Activities			
22 Problems and Solutions					
<input type="checkbox"/> Weather Problem <input type="checkbox"/> System Problem <input type="checkbox"/> Aircraft Problem <input type="checkbox"/> Pilot Problem <input type="checkbox"/> Others: _____					

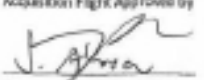
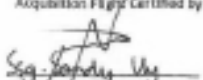
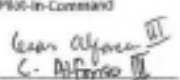

Acquisition Flight Approved by  Signature over Printed Name (End User Representative)	Acquisition Flight Certified by  Signature over Printed Name (PAF Representative)	Pilot-in-Command  Signature over Printed Name	LIDAR Operator  Signature over Printed Name	Aircraft Mechanic/ LIDAR Technician _____ Signature over Printed Name
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Figure A-6.18. Flight Log for Mission 8389AC



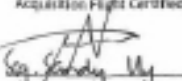
19. Flight Log for 8391AC Mission

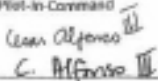
Flight Log No: 8391AC

**PHI-LIDAR I Data Acquisition Flight Log**

1 LIDAR Operator: <u>J. Gonzales</u>		2 ALTM Model: <u>Apollon-CAS</u>		3 Mission Name: <u>304-350090A</u>		4 Type: <u>VFR</u>		5 Aircraft Type: <u>Cessna T200H</u>		6 Aircraft Identification: <u>RP-C9392</u>	
7 Pilot: <u>C. Alfonso III</u>		8 Co-Pilot: <u>J. Seziel</u>		9 Route: <u>Ormos</u>							
10 Date: <u>03-10-2016</u>		11 Airport of Departure (Airport, City/Province):				12 Airport of Arrival (Airport, City/Province):					
13 Engine On: <u>0728</u>		14 Engine Off: <u>1151</u>		15 Total Engine Time: <u>0423</u>		16 Take off: <u>0733</u>		17 Landing: <u>1146</u>		18 Total Flight Time: <u>0415</u>	
19 Weather											
20 Flight Classification								21 Remarks			
20.a. Billable		20.b Non Billable			20.c Others			Surveyed Pagsangahan RP and Palampun			
<input checked="" type="checkbox"/> Acquisition Flight <input type="checkbox"/> Ferry Flight <input type="checkbox"/> System Test Flight <input type="checkbox"/> Calibration Flight		<input type="checkbox"/> Aircraft Test Flight <input type="checkbox"/> AAC Admin Flight <input type="checkbox"/> Others: _____			<input type="checkbox"/> LIDAR System Maintenance <input type="checkbox"/> Aircraft Maintenance <input type="checkbox"/> PHI-LIDAR Admin Activities						
22 Problems and Solutions											
<input type="checkbox"/> Weather Problem <input type="checkbox"/> System Problem <input type="checkbox"/> Aircraft Problem <input type="checkbox"/> Pilot Problem <input type="checkbox"/> Others: _____											

Acquisition Flight Approved by  
  
 Signature over Printed Name  
 (End User Representative)

Acquisition Flight Certified by  
  
 Signature over Printed Name  
 (PIAF Representative)

Pilot-in-Command  
  
 Signature over Printed Name

LIDAR Operator  
  
 Signature over Printed Name

Aircraft Mechanic/ LIDAR Technician  
 \_\_\_\_\_  
 Signature over Printed Name

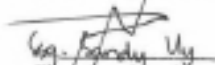
Figure A-6.19. Flight Log for Mission 8391AC

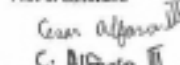
20. Flight Log for 8392AC Mission

PHI-LIDAR 1 Data Acquisition Flight Log

1 LIDAR Operator: <u>L. Peralta</u>	2 ALTM Model: <u>Aquest CNA</u>	3 Mission Name: <u>30K05000908</u>	4 Type: <u>VFR</u>	5 Aircraft Type: <u>Cessna T30GH</u>	6 Aircraft Identification: <u>RP-C9302</u>
7 Pilot: <u>C. Alfonso III</u>	8 Co-Pilot: <u>J. Javier</u>	9 Route: <u>Ormae</u>	Flight Log No.: <u>8392AC</u>		
10 Date: <u>03-10-2016</u>	12 Airport of Departure (Airport, City/Province):		12 Airport of Arrival (Airport, City/Province):		
13 Engine On: <u>1423</u>	14 Engine Off: <u>1752</u>	15 Total Engine Time: <u>03:29</u>	16 Take off: <u>1423</u>	17 Landing: <u>1747</u>	18 Total Flight Time: <u>03:19</u>
19 Weather					
20 Flight Classification			21 Remarks		
20.a Billable <input checked="" type="checkbox"/> Acquisition Flight <input type="checkbox"/> Ferry Flight <input type="checkbox"/> System Test Flight <input type="checkbox"/> Calibration Flight			20.b Non Billable <input type="checkbox"/> Aircraft Test Flight <input type="checkbox"/> AAC Admin Flight <input type="checkbox"/> Others: _____		
20.c Others <input type="checkbox"/> LIDAR System Maintenance <input type="checkbox"/> Aircraft Maintenance <input type="checkbox"/> PHI-LIDAR Admin Activities			Surveyed Western Leyte Coast		
22 Problems and Solutions					
<input type="checkbox"/> Weather Problem <input type="checkbox"/> System Problem <input type="checkbox"/> Aircraft Problem <input type="checkbox"/> Pilot Problem <input type="checkbox"/> Others: _____					

Acquisition Flight approved by  
  
 Signature over Printed Name  
 (Erik User Representative)

Acquisition Flight Certified by  
  
 Signature over Printed Name  
 (PAF Representative)

Pilot-in-Command  
  
 Signature over Printed Name

LIDAR Operator  
  
 Signature over Printed Name

Aircraft Mechanic/ LIDAR Technician  
 \_\_\_\_\_  
 Signature over Printed Name

Figure A-6.20. Flight Log for Mission 8392AC

21. Flight Log for 8394AC Mission

PHIL-LIDAR 1 Data Acquisition Flight Log Flight Log No. \_\_\_\_\_

Agua 4 CAS1      0811351800018

1 LIDAR Operator: <u>J. Gonzalez</u>		2 ALTM Model:		3 Mission Name:		4 Type: <u>VFR</u>		5 Aircraft Type: <u>Cessna T206H</u>		6 Aircraft Identification:	
7 Pilot: <u>C. Alfonso</u>		8 Co-Pilot: <u>J. Jesus</u>		9 Route: <u>Ormae</u>							
10 Date: <u>03-11-2016</u>		12 Airport of Departure (Airport, City/Province):				12 Airport of Arrival (Airport, City/Province):					
13 Engine On: <u>1650</u>		14 Engine Off: <u>1337</u>		15 Total Engine Time: <u>02 + 17</u>		16 Take off: <u>1653</u>		17 Landing: <u>1332</u>		18 Total Flight Time: <u>02 + 37</u>	
19 Weather											
20 Flight Classification								21 Remarks			
20.a. <u>Billable</u>		20.b. <u>Non Billable</u>		20.c. <u>Others</u>		<u>Surveyed But 14ED</u>					
<input checked="" type="checkbox"/> Acquisition Flight <input type="checkbox"/> Ferry Flight <input type="checkbox"/> System Test Flight <input type="checkbox"/> Calibration Flight		<input type="checkbox"/> Aircraft Test Flight <input type="checkbox"/> AAC Admin Flight <input type="checkbox"/> Others: _____		<input type="checkbox"/> LIDAR System Maintenance <input type="checkbox"/> Aircraft Maintenance <input type="checkbox"/> Phil-LIDAR Admin Activities							
22 Problems and Solutions											
<input type="checkbox"/> Weather Problem <input type="checkbox"/> System Problem <input type="checkbox"/> Aircraft Problem <input type="checkbox"/> Pilot Problem <input type="checkbox"/> Others: _____											

Figure A-6.21. Flight Log for Mission 8394AC

22. Flight Log for 8408AC Mission

Flight Log No.: 5408

Data Acquisition Flight Log

1 LIDAR Operator: <i>M. Baligosa</i>	2 ALTM Model: <i>HOJA + CBS</i>	3 Mission Name: <i>8408AC</i>	4 Type: <i>VFR</i>	5 Aircraft Type: <i>Cessna T206H</i>	6 Aircraft Identification: <i>7J22</i>						
7 Pilot: <i>C. Alfonso</i>	8 Co-Pilot: <i>J. Dela Cruz</i>	9 Route: <i>Ormoc - Ormoc</i>									
10 Date: <i>Nov. 19, 2016</i>	11 Airport of Departure (Airport, City/Province): <i>Ormoc</i>	12 Airport of Arrival (Airport, City/Province): <i>Ormoc</i>									
13 Engine On: <i>0710 H</i>	14 Engine Off: <i>1045 H</i>	15 Total Engine Time: <i>3+35</i>	16 Take off: <i>0715 H</i>	17 Landing: <i>1040 H</i>	18 Total Flight Time: <i>3+25</i>						
19 Weather: <i>partly cloudy</i>											
20 Flight Classification			21 Remarks								
20.a. <input checked="" type="checkbox"/> <b>Billable</b> <input type="checkbox"/> Acquisition Flight <input type="checkbox"/> Ferry Flight <input type="checkbox"/> System Test Flight <input type="checkbox"/> Calibration Flight			20.b. <input type="checkbox"/> <b>Non Billable</b> <input type="checkbox"/> Aircraft Test Flight <input type="checkbox"/> AAC Admin Flight <input type="checkbox"/> Others: _____			20.c. <input type="checkbox"/> <b>Others</b> <input type="checkbox"/> LIDAR System Maintenance <input type="checkbox"/> Aircraft Maintenance <input type="checkbox"/> Phil-LIDAR Admin Activities			21 Remarks: <i>Scanned gaps in Blk 34</i>		
22 Problems and Solutions											
<input type="checkbox"/> Weather Problem <input type="checkbox"/> System Problem <input type="checkbox"/> Aircraft Problem <input type="checkbox"/> Pilot Problem <input type="checkbox"/> Others: _____											

Acquisition Flight Approved by

*[Signature]*  
Signature over Printed Name  
(Eng. User Representative)

Acquisition Flight Certified by

*[Signature]*  
*PS SORON V WY*  
Signature over Printed Name  
(RAF Representative)

Pilot-in-Command

*[Signature]*  
*C. ALFONSO*  
Signature over Printed Name

LIDAR Operator

*[Signature]*  
*M. Baligosa*  
Signature over Printed Name

Aircraft Mechanic/ Technician

*[Signature]*  
Signature over Printed Name

Figure A-6.22. Flight Log for Mission 8408AC

23. Flight Log for 8409AC Mission

Flight Log No: 8409

Data Acquisition Flight Log					
1 LIDAR Operator: <i>J. Gonzales</i>	2 ALTM Model: <i>Agua</i>	3 Mission Name: <i>BLK704</i>	4 Type: <i>VFR</i>	5 Aircraft Type: <i>Cessna T206H</i>	6 Aircraft Identification: <i>8343</i>
7 Pilot: <i>C. ALPONSO</i>	8 Co-Pilot: <i>J. VECIEL</i>	9 Route: <i>Ormoc - Ormoc</i>			
10 Date: <i>Nov. 19, 2016</i>	11 Airport of Departure (Airport, City/Province): <i>Ormoc</i>		12 Airport of Arrival (Airport, City/Province): <i>Ormoc</i>		
13 Engine On: <i>1340H</i>	14 Engine Off: <i>1545H</i>	15 Total Engine Time: <i>2:05</i>	16 Take off: <i>1345H</i>	17 Landing: <i>1540H</i>	18 Total Flight Time: <i>1:55</i>
19 Weather: <i>Fair</i>					
20 Flight Classification			21 Remarks: <i>Surveyed BLK704</i>		
20.a Billable		20.b Non Billable		20.c Other	
<input type="checkbox"/> Acquisition Flight <input type="checkbox"/> Ferry Flight <input type="checkbox"/> System Test Flight <input type="checkbox"/> Calibration Flight		<input type="checkbox"/> Aircraft Test Flight <input type="checkbox"/> AAC Admin Flight <input type="checkbox"/> Others: _____		<input type="checkbox"/> LIDAR System Maintenance <input type="checkbox"/> Aircraft Maintenance <input type="checkbox"/> PNH-LIDAR Admin Activities	
22 Problems and Solutions					
<input type="checkbox"/> Weather Problem <input type="checkbox"/> Systems Problem <input type="checkbox"/> Aircraft Problem <input type="checkbox"/> Pilot Problem <input type="checkbox"/> Others: _____					
Acquisition Flight Approved by <i>[Signature]</i> Signature over Printed Name (End User Representative)	Acquisition Flight Certified by <i>[Signature]</i> <i>8343 SOPHON V. VECIEL</i> Signature over Printed Name (RAF Representative)	PHO-in-Charge <i>[Signature]</i> <i>C. ALPONSO</i> Signature over Printed Name	Lidar Operator <i>[Signature]</i> <i>J. Gonzales</i> Signature over Printed Name	Aircraft Mechanic/ Technician <i>[Signature]</i> Signature over Printed Name	

Figure A-6.23. Flight Log for Mission 8409AC

24. Flight Log for 3945G Mission

Flight Log No.: 3945G

1 LIDAR Operator: N. Hejary		2 ALTM Model: hmd 4i		3 Mission Name: 3945G		4 Type: VFR		5 Aircraft Type: Casine T208H		6 Aircraft Identification: PCC-9022	
7 Pilot: J. Moron		8 Co-Pilot: A. Dely		9 Route: Mace Boat							
10 Date: 4-16-16		11 Airport of Departure (Airport, City/Province): OF Mac				12 Airport of Arrival (Airport, City/Province): MEMOC					
13 Engine On: 8:04		14 Engine Off: 12:30		15 Total Engine Time: 4:27		16 Take off: 8:29		17 Landing: 12:31		18 Total Flight Time: 04:12	
19 Weather											
20 Flight Classification						21 Remarks					
20.a Billable		20.b Non Billable		20.c Others		Successful flight. bracketed Bck 35A ↓ 35B					
<input checked="" type="radio"/> Acquisition Flight <input type="radio"/> Ferry Flight <input type="radio"/> System Test Flight <input type="radio"/> Calibration Flight		<input type="radio"/> Aircraft Test Flight <input type="radio"/> AAC Admin Flight <input type="radio"/> Others: _____		<input type="radio"/> LIDAR System Maintenance <input type="radio"/> Aircraft Maintenance <input type="radio"/> Phil-LIDAR Admin Activities							
22 Problems and Solutions											
<input type="radio"/> Weather Problem <input type="radio"/> System Problem <input type="radio"/> Aircraft Problem <input type="radio"/> Pilot Problem <input type="radio"/> Others: _____											

Acquisition Flight Approved by

*P. Hejary*  
 Signature over Printed Name  
 (End User Representative)

Acquisition Flight Certified by

*Sgt. Raymond B. Romina*  
 Signature over Printed Name  
 (FAF Representative)

Pilot-in-Command

*J. Moron*  
 Signature over Printed Name

LIDAR Operator

*N. Hejary*  
 Signature over Printed Name

Aircraft Mechanic/ LIDAR Technician

\_\_\_\_\_  
 Signature over Printed Name

Figure A-6.24. Flight Log for Mission 3945G

25. Flight Log for 3947G Mission

PHIL-LIDAR 1 Data Acquisition Flight Log Flight Log No.: 3947G

1 UDNR Operator: <u>F. Arce</u>		2 ALTM Model: <u>Trimble</u>		3 Mission Name: <u>DRAC</u>		4 Type: <u>VFR</u>		5 Aircraft Type: <u>Cessna T206H</u>		6 Aircraft Identification: <u>3PC-2823</u>	
7 Pilot: <u>J. Mooney</u>		8 Co-Pilot: <u>A. Dello</u>		9 Route: <u>DRAC LOCAL</u>							
10 Date: <u>4-18-16</u>		11 Airport of Departure (Airport, City/Province): <u>DRAC</u>				12 Airport of Arrival (Airport, City/Province): <u>DRAC</u>					
13 Engine On: <u>15:26</u>		14 Engine Off: <u>17:43</u>		15 Total Engine Time: <u>2:17</u>		16 Take off: <u>15:31</u>		17 Landing: <u>17:48</u>		18 Total Flight Time: <u>4:17</u>	
19 Weather											
20 Flight Classification								21 Remarks			
20.a Billable		20.b Non Billable		20.c Others		Successful flight. Enclosed BSBTC ↓ overid winds over 35 A & 35 B.					
<input checked="" type="checkbox"/> Acquisition Flight <input type="checkbox"/> Ferry Flight <input type="checkbox"/> System Test Flight <input type="checkbox"/> Calibration Flight		<input type="checkbox"/> Aircraft Test Flight <input type="checkbox"/> AAC Admin Flight <input type="checkbox"/> Others: _____		<input type="checkbox"/> LIDAR System Maintenance <input type="checkbox"/> Aircraft Maintenance <input type="checkbox"/> PHIL-LIDAR Admin Activities							
22 Problems and Solutions											
<input type="checkbox"/> Weather Problem <input type="checkbox"/> System Problem <input type="checkbox"/> Aircraft Problem <input type="checkbox"/> Pilot Problem <input type="checkbox"/> Others: _____											

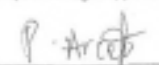

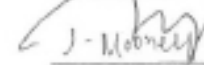
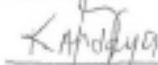
Acquisition Flight Approved by  Signature over Printed Name (End User Representative)	Acquisition Flight Certified by  Signature over Printed Name (PAF Representative)	Flight Co-lead  Signature over Printed Name	LIDAR Operator  Signature over Printed Name	Aircraft Mechanic/ LIDAR Technician _____ Signature over Printed Name
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Figure A-6.25. Flight Log for Mission 3947G

## ANNEX 7. Flight Status Reports

Table A-7-1. Flight Status Report

## PAGSANGAHAN FLOODPLAIN

(January 28, May 15-26, 2014; January 21-February 17, 2015; March 9-19, April 16, 2016)

Flight No	Area	Mission	Operator	Date Flown	Remarks
1032A	BLK 35A	2BLK35A028A	F. Sable	28-Jan-14	Successful flight
1458A	BLK 35B	3BLK35B135A	I. Roxas	15-May-14	Completed mission over BLK35B
1460A	BLK 35C & 35D	3BLK35CD135B	P. Arceo	15-May-14	Completed mission over BLK35C and some lines over BLK35D
1462A	BLK 35D & 35E	3BLK35DSE136A	P. Arceo	16-May-14	Completed mission over BLK35D and 6 lines over BLK35E
1464A	BLK 35E	3BLK35ES136B	P. Arceo	16-May-14	Completed 14/22 lines left over BLK35E
1466A	BLK 35F	3BLK35F137A	P. Arceo	17-May-14	Completed mission over BLK35F with voids due to strong winds.
1474A	BLK 35G	3BLK35G139A	P. Arceo	19-May-14	Completed voids coverage from BLK C, D, E & F AND 6 lines from BLK 35G.
1494A	BLK 35G & 35H	3BLK35GSH144A	P. Arceo	24-May-14	Completed mission over BLK 35G and four lines over BLK 35H.
1498A	BLK 35H & 35I	3BLK35HSI145A	P. Arceo	25-May-14	Completed mission over BLK 35H and four lines over BLK 35I.
1502A	BLK 35I	3BLK35IS146A	P. Arceo	26-May-14	Completed mission over BLK 35I
1504A	BLK 35A & 35I	3BLK35AIS146B	M. Baliguas	26-May-14	Completed mission over BLK 35A and 2 lines over BLK 35I
7753AC	BLK 35B	3BLK35B021A	L. Paragas	21-Jan-15	Completed 14 lines of Blk35B. Experienced red swath (short ranges).
7760AC	BLK 35A	3BLK35A025A	G. Sinadjan	25-Jan-15	Completed Blk35A with digitizer. Experienced red swath (short ranges) No CASI
7780AC	BLK 35A	3BLK35AX035A	G. Sinadjan	04-Feb-15	Completed 3 lines. Flight aborted due to strong winds. With digitizer. No CASI
7782AC	BLK 35A	3BLK35AX036A	L. Paragas	05-Feb-15	Over Ormoc. Flight aborted due to strong winds. With digitizer. No CASI
7802AC	BLK 35 Voids	3BLK35SV046A	L. Paragas	15-Feb-15	Surveyed voids and short ranges of BLK35 with digitizer. No CASI
7806AC	BLK 35 Voids	3BLK35X1048A	L. Paragas	17-Feb-15	Surveyed voids and short ranges of BLK35 with digitizer. No CASI
8389AC	BLK 35A	3BLK35A069A	L. Paragas	09-Mar-16	Surveyed BLK 35A
8391AC	BLK 35EC	3BLK35EC070A	J. Gonzales	10-Mar-16	Surveyed BLK 35EC
8392AC	BLK 35BD	3BLK35BD070B	L. Paragas	10-Mar-16	Surveyed BLK 35BD



Flight No	Area	Mission	Operator	Date Flown	Remarks
8394AC	BLK 35BD	3BLK35BD071B	J. Gonzales	11-Mar-16	Surveyed BLK 35BD
8408AC	BLK 35DCE	3BLK48BD079A	M. Baliguas	19-Mar-16	Surveyed BLK 35DCE
8409AC	BLK 48DS	3BLK34079B	J. Gonzales	19-Mar-16	Surveyed coastal area west of Ormoc Bay
3945G	BLK 35AB	2BLK35AB107A	F. Ilejay	16-Apr-16	Surveyed BLK 35A and 35B
3947G	BLK 35CS	2BLK35CS107B	K. Andaya	16-Apr-16	Surveyed BLK 35C and covered voids over BLK 35A and 35B

**SWATH PER FLIGHT MISSION**

Flight No. : 1032A  
 Area: BLK 35A  
 Mission Name: 2BLK35A028A  
 Parameters:  
     Altitude: 600  
     Scan Frequency: 40  
     Scan Angle: 25  
     Overlap: 30

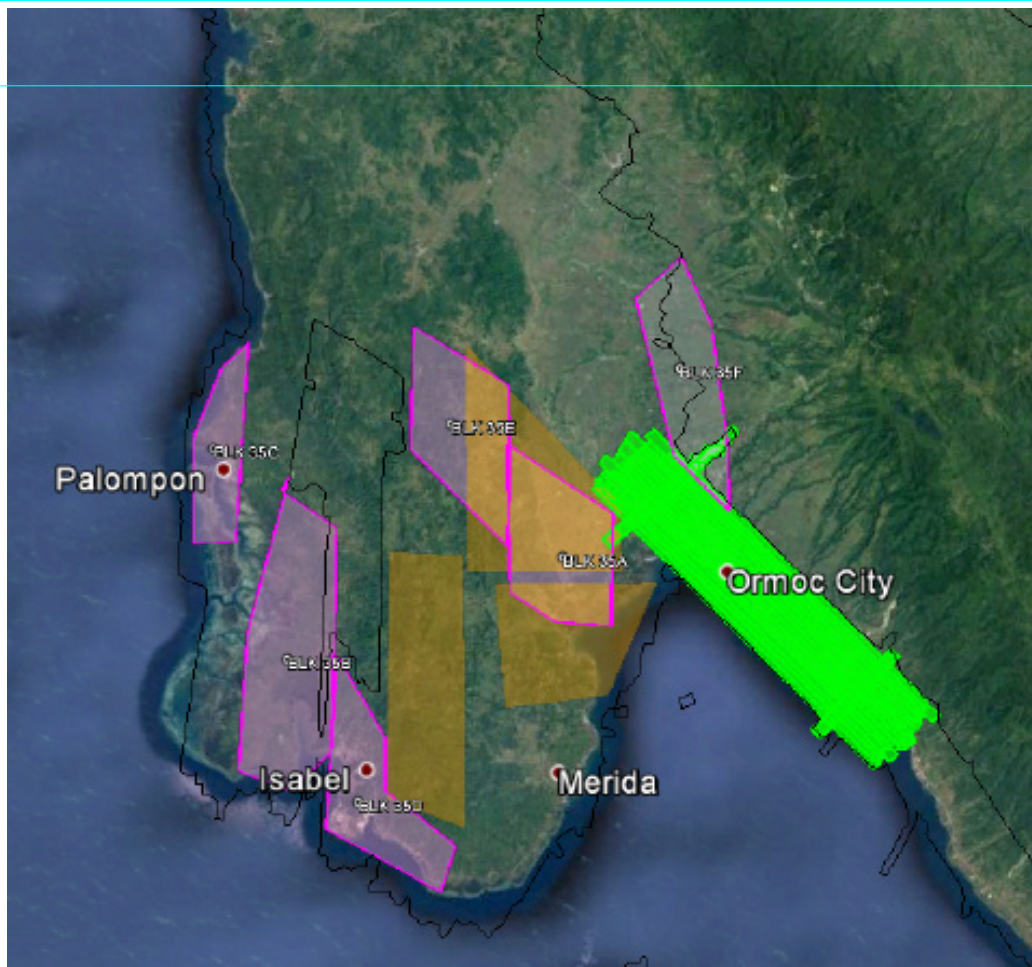


Figure A-7.1. Swath for Flight No. 1032A

Flight No. : 1458A  
Area: BLK 35B  
Mission Name: 3BLK35B135A  
Parameters:  
Altitude: 700  
Scan Frequency: 50  
Scan Angle: 18  
Overlap: 30

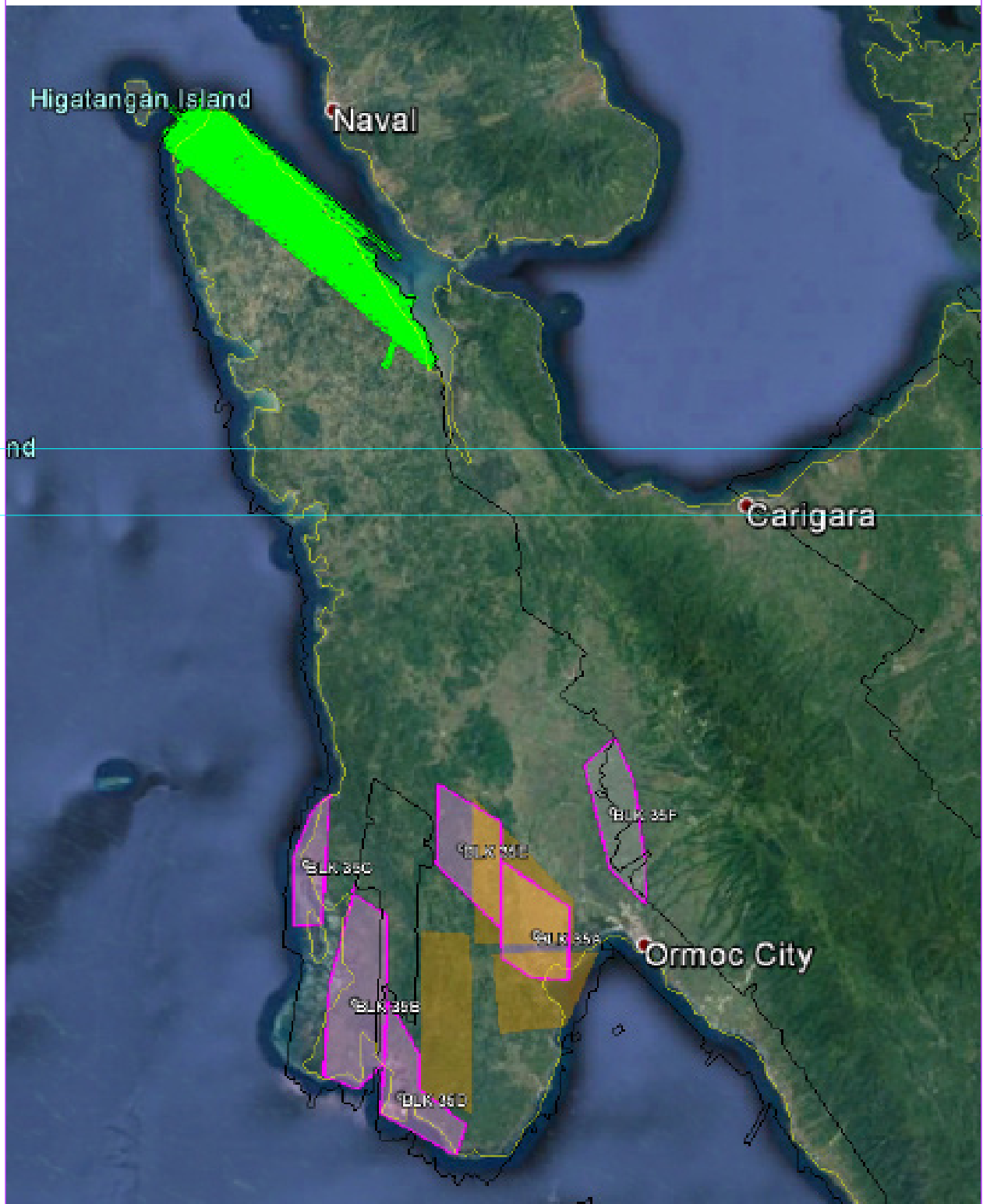


Figure A-7.2. Swath for Flight No. 1458A

Flight No. : 1460A  
Area: BLK 35C & 35D  
Mission Name: 3BLK35CD135B  
Parameters:  
Altitude: 700  
Scan Frequency: 50  
Scan Angle: 18  
Overlap: 30

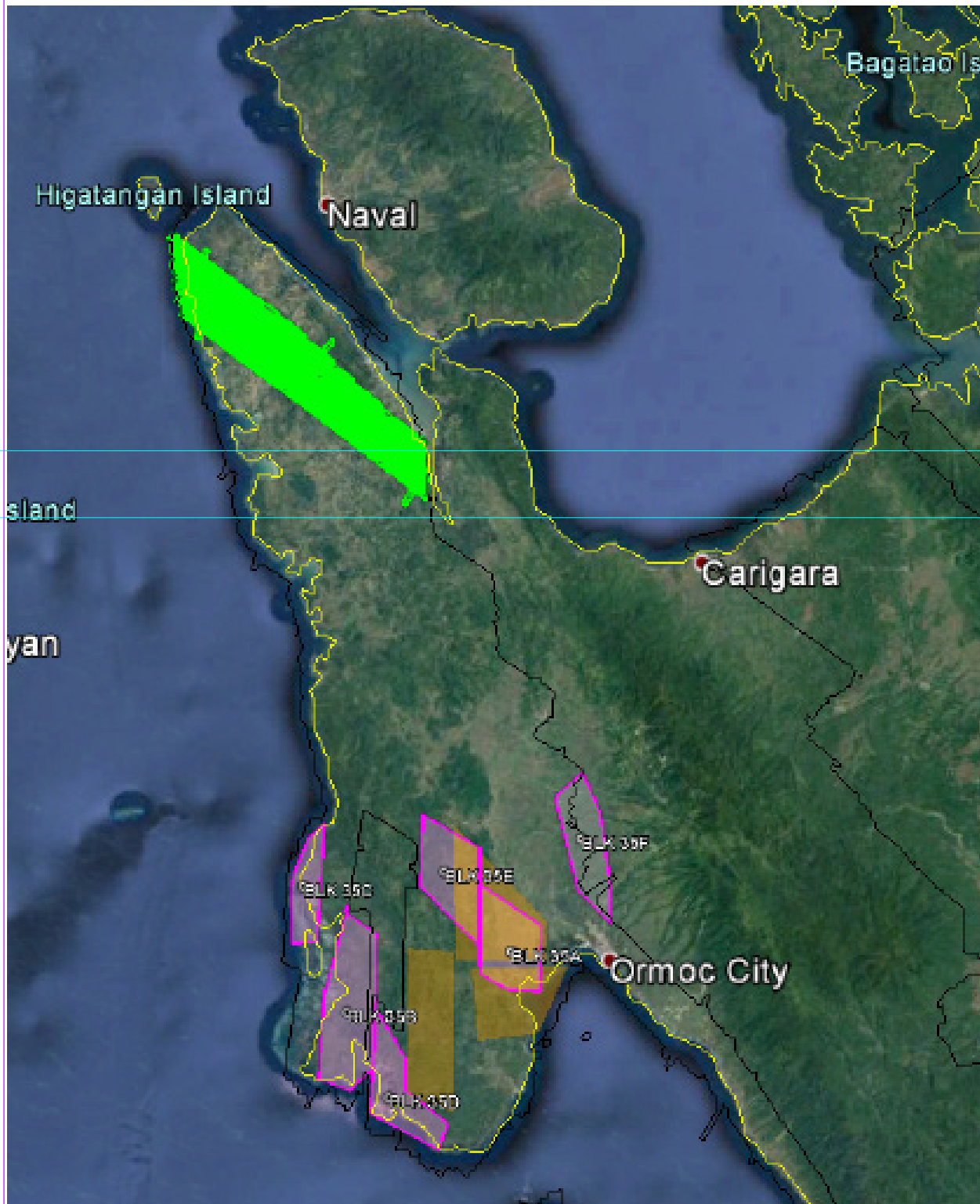


Figure A-7.3. Swath for Flight No. 1460A

Flight No. : 1462A  
Area: BLK 35D & 35E  
Mission Name: 3BLK35DSE136A  
Parameters:  
Altitude: 700  
Scan Frequency: 50  
Scan Angle: 18  
Overlap: 30

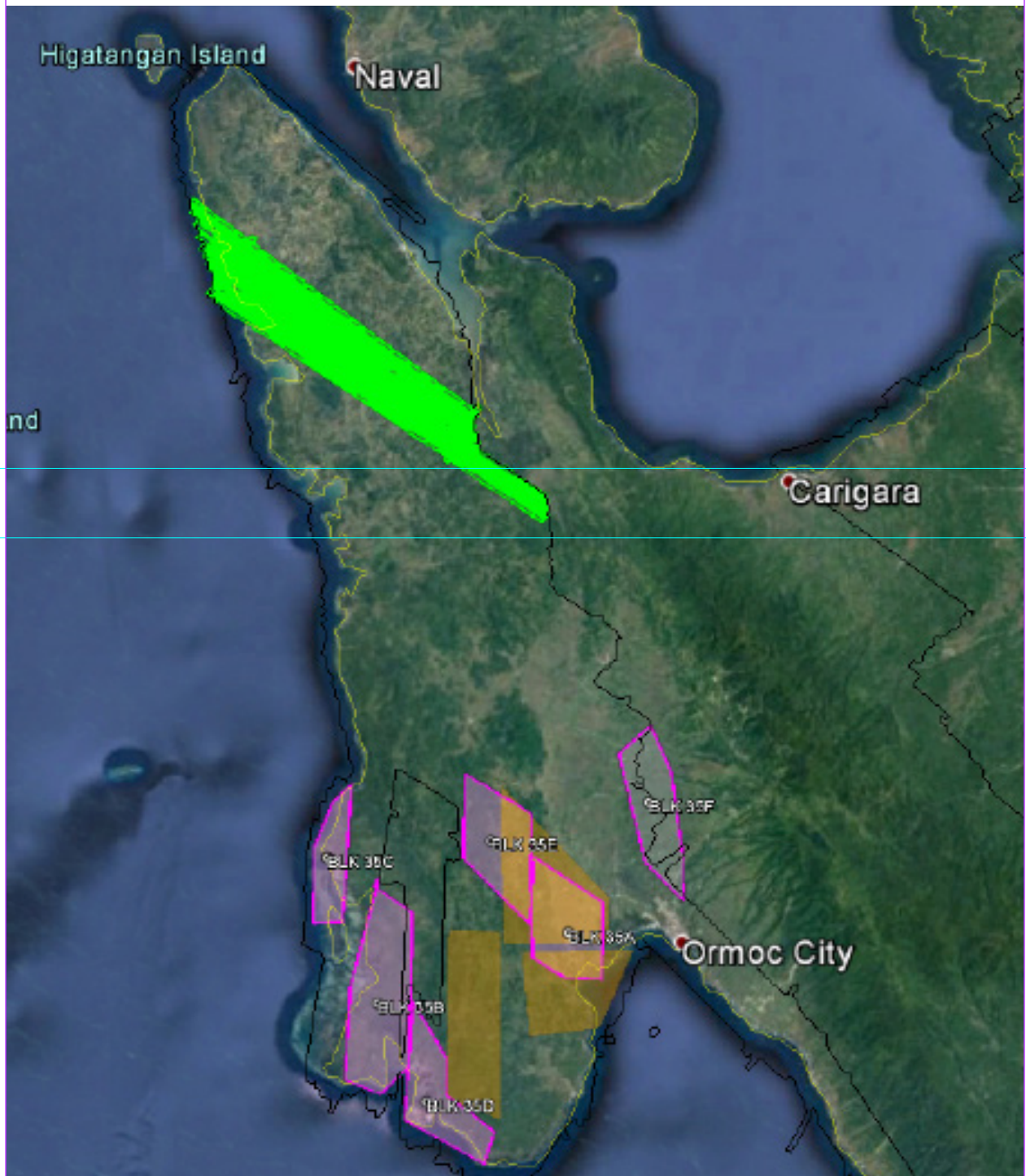


Figure A-7.4. Swath for Flight No. 1462A

Flight No. : 1464A  
Area: BLK 35E  
Mission Name: 3BLK35ES136B  
Parameters:  
Altitude: 700  
Scan Frequency: 50  
Scan Angle: 18  
Overlap: 30

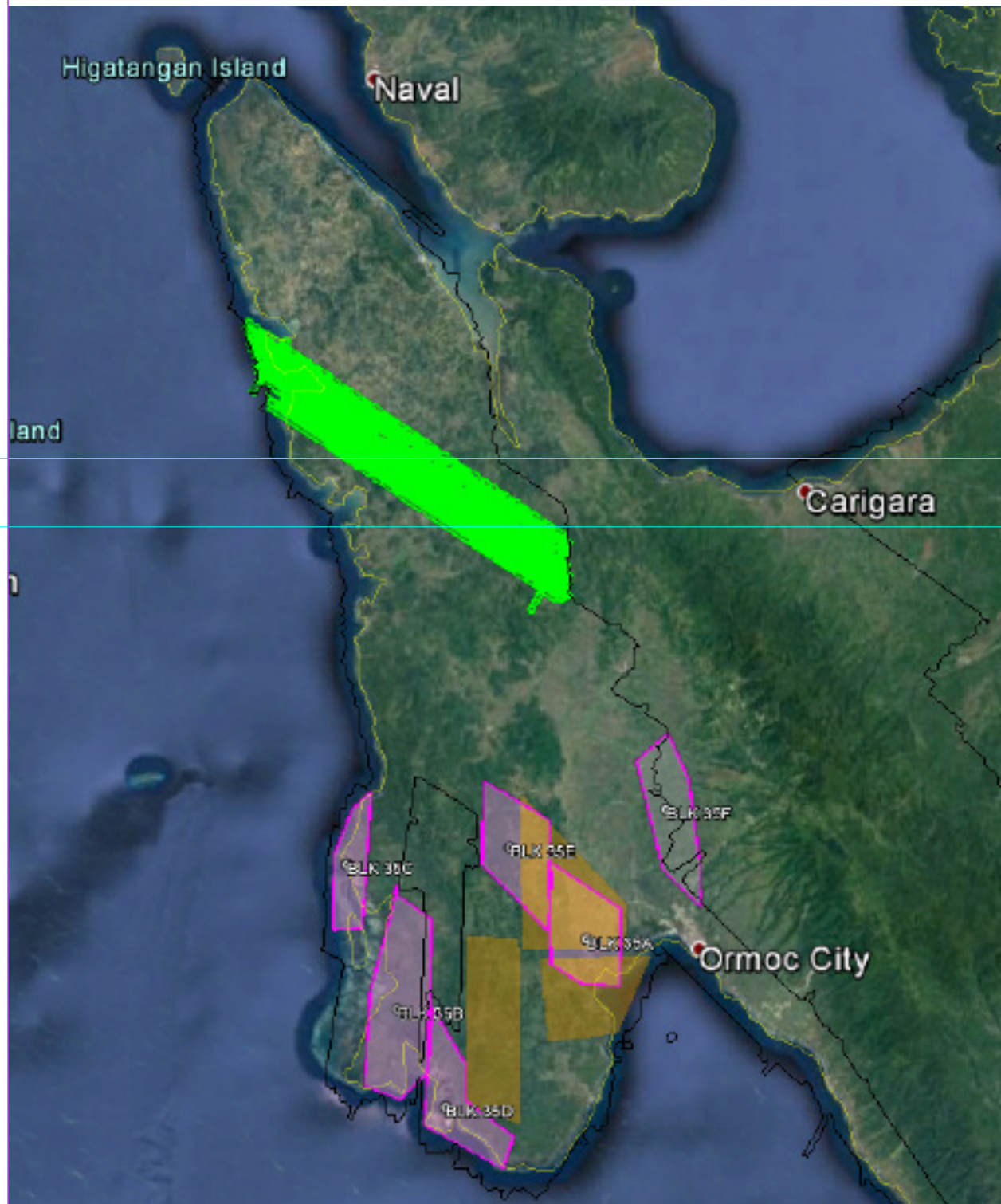


Figure A-7.5. Swath for Flight No. 1464A

Flight No. : 1466A  
Area: BLK 35F  
Mission Name: 3BLK35F137A  
Parameters:  
Altitude: 600  
Scan Frequency: 50  
Scan Angle: 18  
Overlap: 30



Figure A-7.6. Swath for Flight No. 1466A

Flight No. : 1474A  
Area: BLK 35G  
Mission Name: 3BLK35G139A  
Parameters:  
Altitude: 700  
Scan Frequency: 50  
Scan Angle: 18  
Overlap: 30

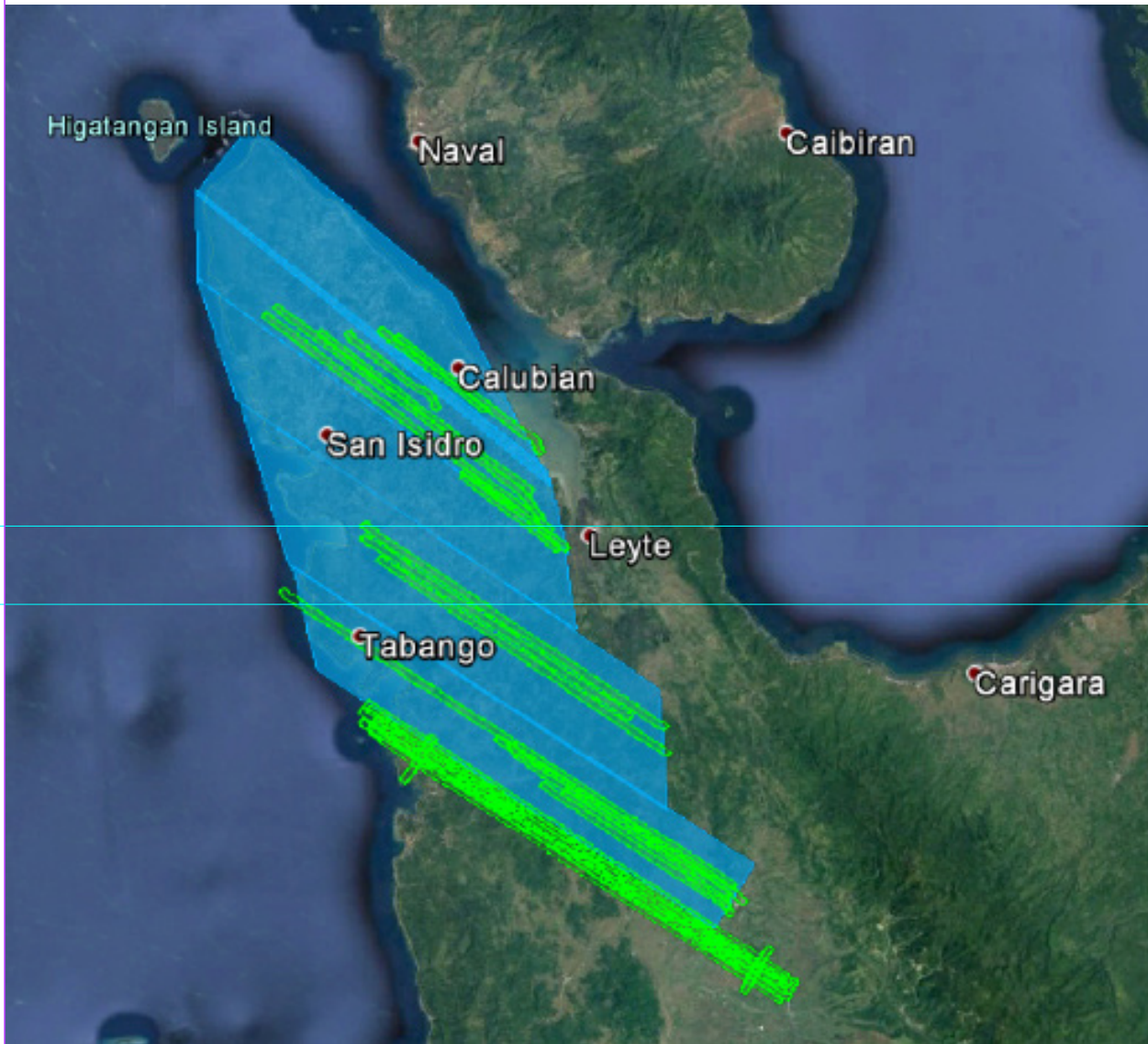


Figure A-7.7. Swath for Flight No. 1474A

Flight No. : 1494A  
Area: BLK 35G & 35H  
Mission Name: 3BLK35GSH144A  
Parameters:  
Altitude: 700  
Scan Frequency: 50  
Scan Angle: 18  
Overlap: 30

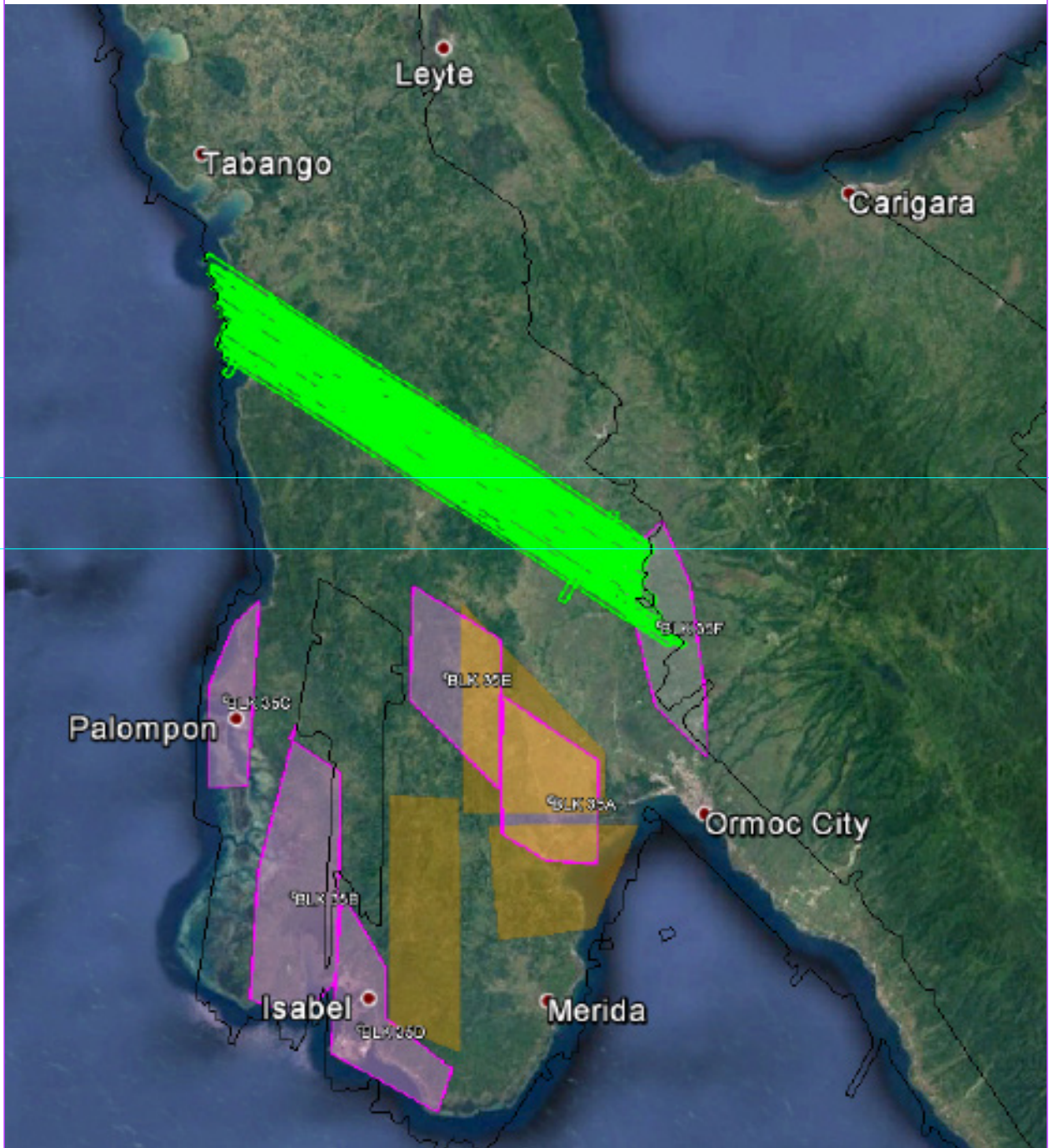


Figure A-7.8. Swath for Flight No. 1494A



Flight No. : 1498A  
Area: BLK 35H & 35I  
Mission Name: 3BLK35HSI145A  
Parameters:  
Altitude: 800  
Scan Frequency: 50  
Scan Angle: 18  
Overlap: 30

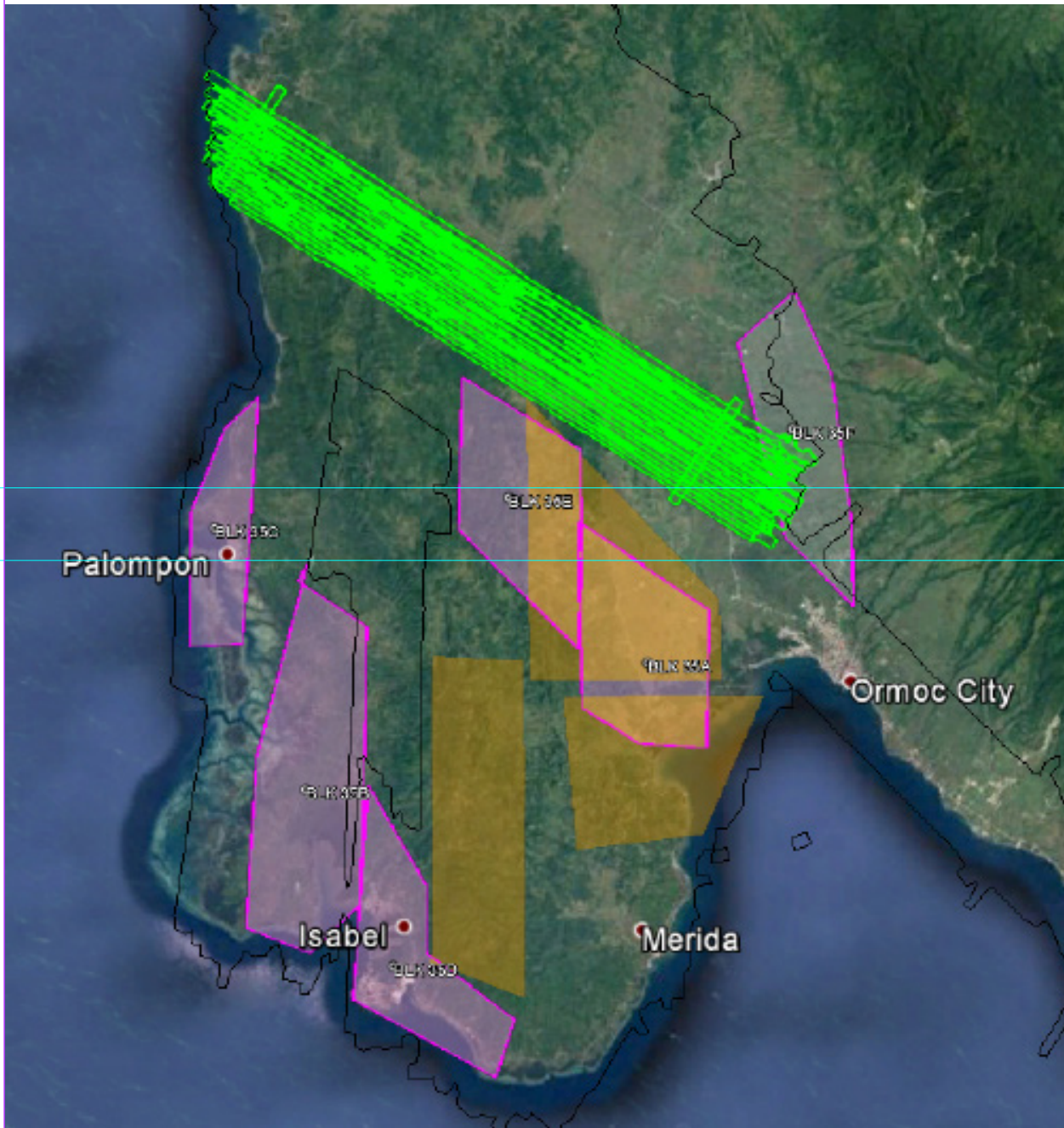


Figure A-7.9. Swath for Flight No. 1498A

Flight No. : 1502A  
Area: BLK 35A & 35I  
Mission Name: 3BLK35AIS146B  
Parameters:  
Altitude: 700  
Scan Frequency: 50  
Scan Angle: 18  
Overlap: 55, 40, 50



Figure A-7.10. Swath for Flight No. 1502A

Flight No. : 1504A  
Area: BLK 35I  
Mission Name: 3BLK35IS146A  
Parameters:  
Altitude: 600  
Scan Frequency: 50  
Scan Angle: 18  
Overlap: 30

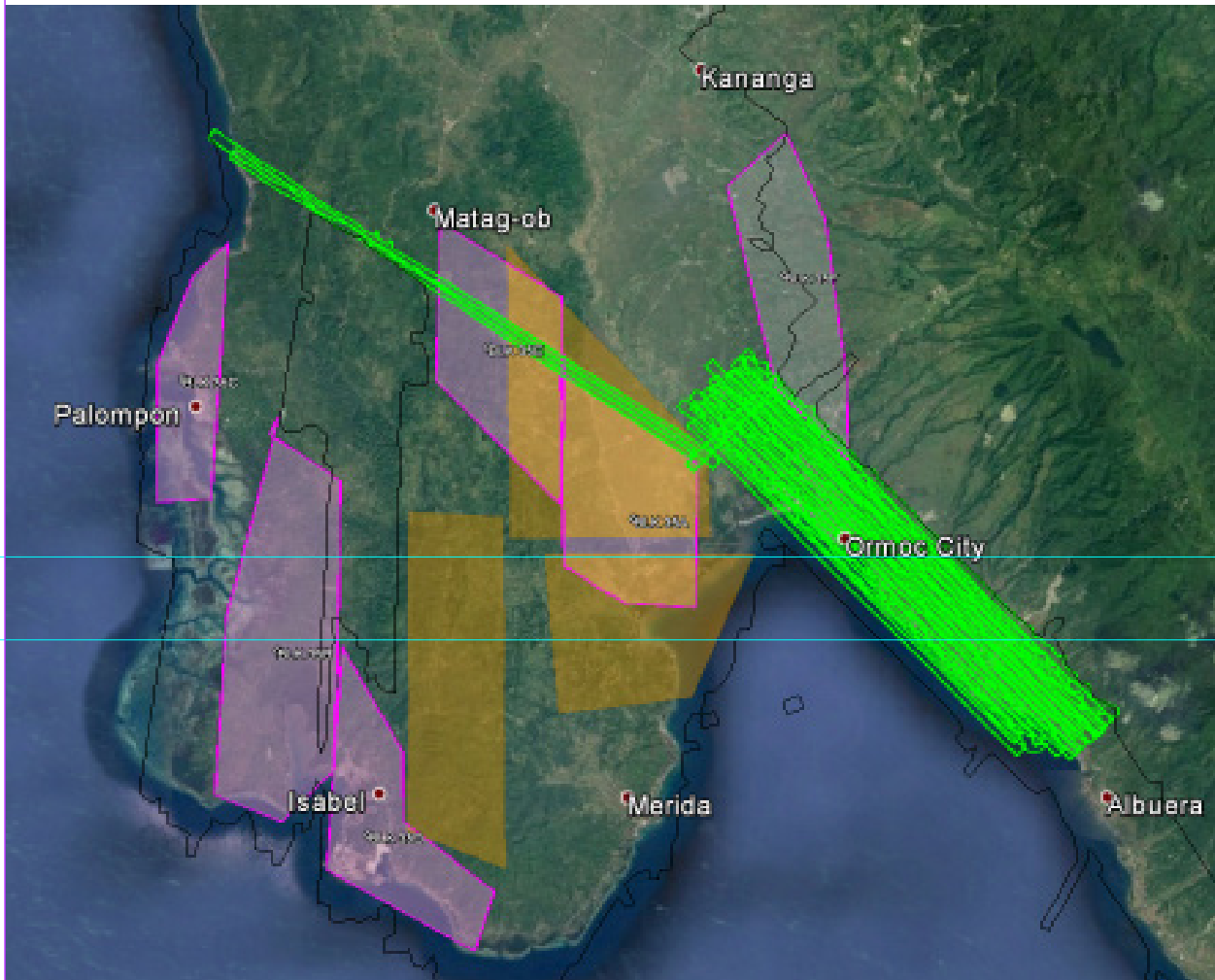


Figure A-7.11. Swath for Flight No. 1504A

Flight No. : 7753AC  
Area: BLK 35B  
Mission Name: 3BLK35B21A  
Parameters:  
Altitude: 600 m  
Scan Frequency: 45  
Scan Angle: 18  
Overlap: 35

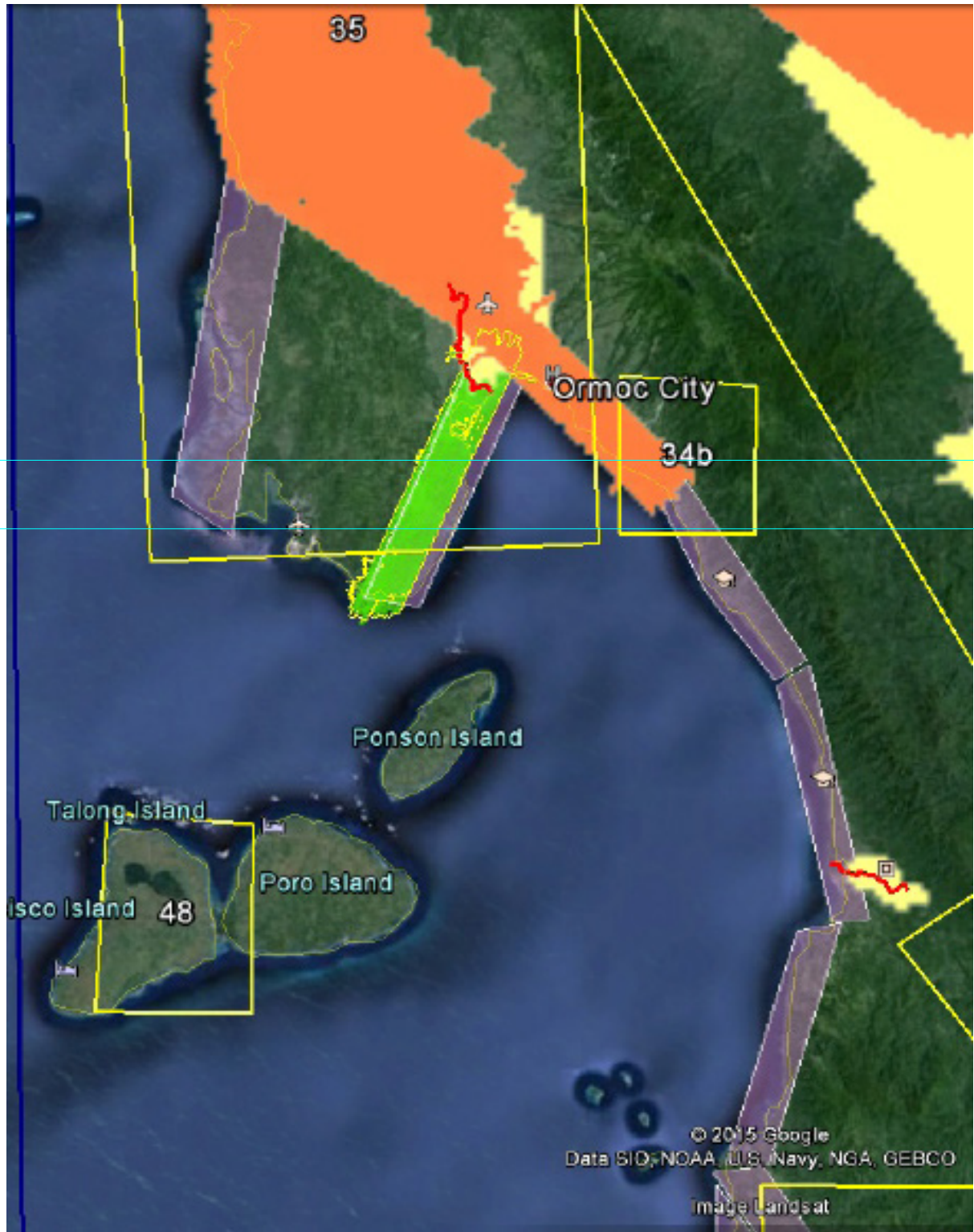


Figure A-7.12. Swath for Flight No. 7753AC

Flight No. : 7760AC  
Area: BLK 35A  
Mission Name: 3BLK35A025A  
Parameters:  
Altitude: 550  
Scan Frequency: 45  
Scan Angle: 18  
Overlap: 35



Figure A-7.13. Swath for Flight No. 7760AC

Flight No. : 7780AC  
Area: BLK 35A  
Mission Name: 3BLK35AX035A  
Parameters:  
Altitude: 500  
Scan Frequency: 45  
Scan Angle: 18  
Overlap: 35



Figure A-7.14. Swath for Flight No. 7780AC

Flight No. : 7782AC  
Area: BLK 35A  
Mission Name: 3BLK35AX036A  
Parameters:  
Altitude: 600  
Scan Frequency: 45  
Scan Angle: 18  
Overlap: 35

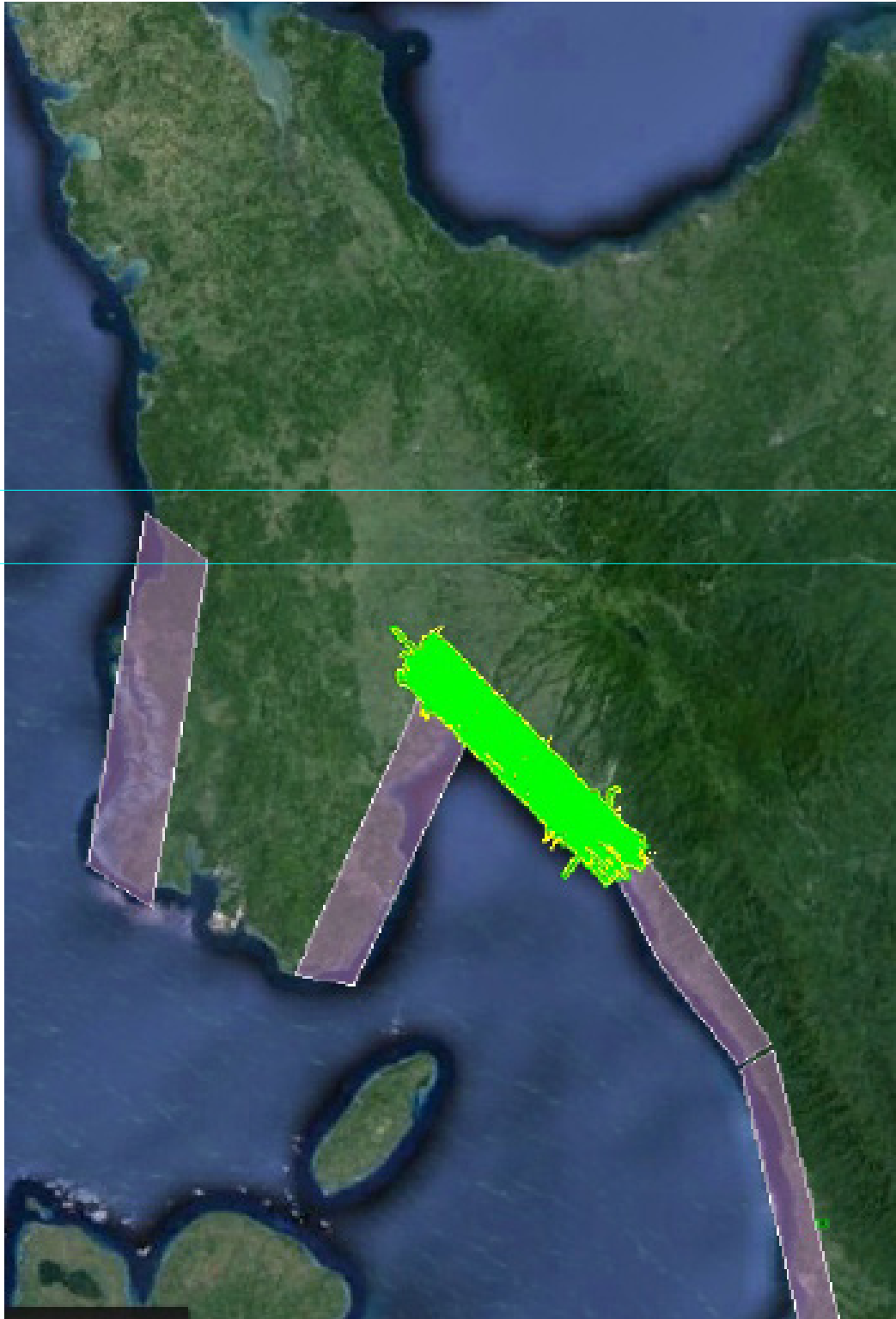


Figure A-7.15. Swath for Flight No. 7782AC

Flight No. : 7802AC  
Area: BLK 35 Voids  
Mission Name: 3BLK35SV046A  
Parameters:  
Altitude: 600  
Scan Frequency: 45  
Scan Angle: 18  
Overlap: 35



Figure A-7.16. Swath for Flight No. 7802AC



Flight No. : 7806AC  
Area: BLK 35 Voids  
Mission Name: 3BLK35X1048A  
Parameters:  
Altitude: 600  
Scan Frequency: 45  
Scan Angle: 18  
Overlap: 35

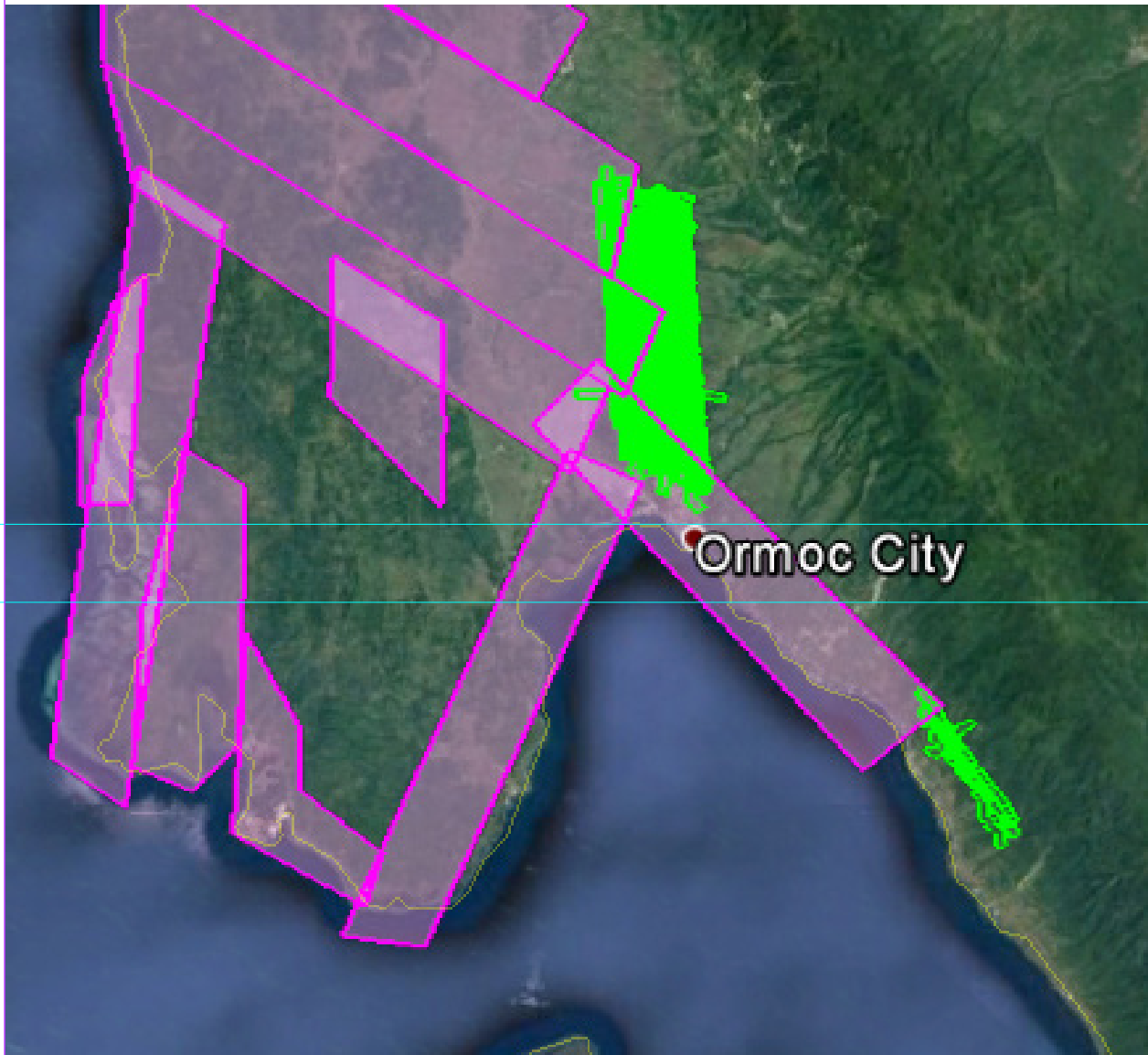


Figure A-7.17. Swath for Flight No. 7806AC

Flight No. : 8389AC  
Area: BLK 35A  
Mission Name: 3BLK35A068A  
Parameters:  
Altitude: 600  
Scan Frequency: 45  
Scan Angle: 18  
Overlap: 30

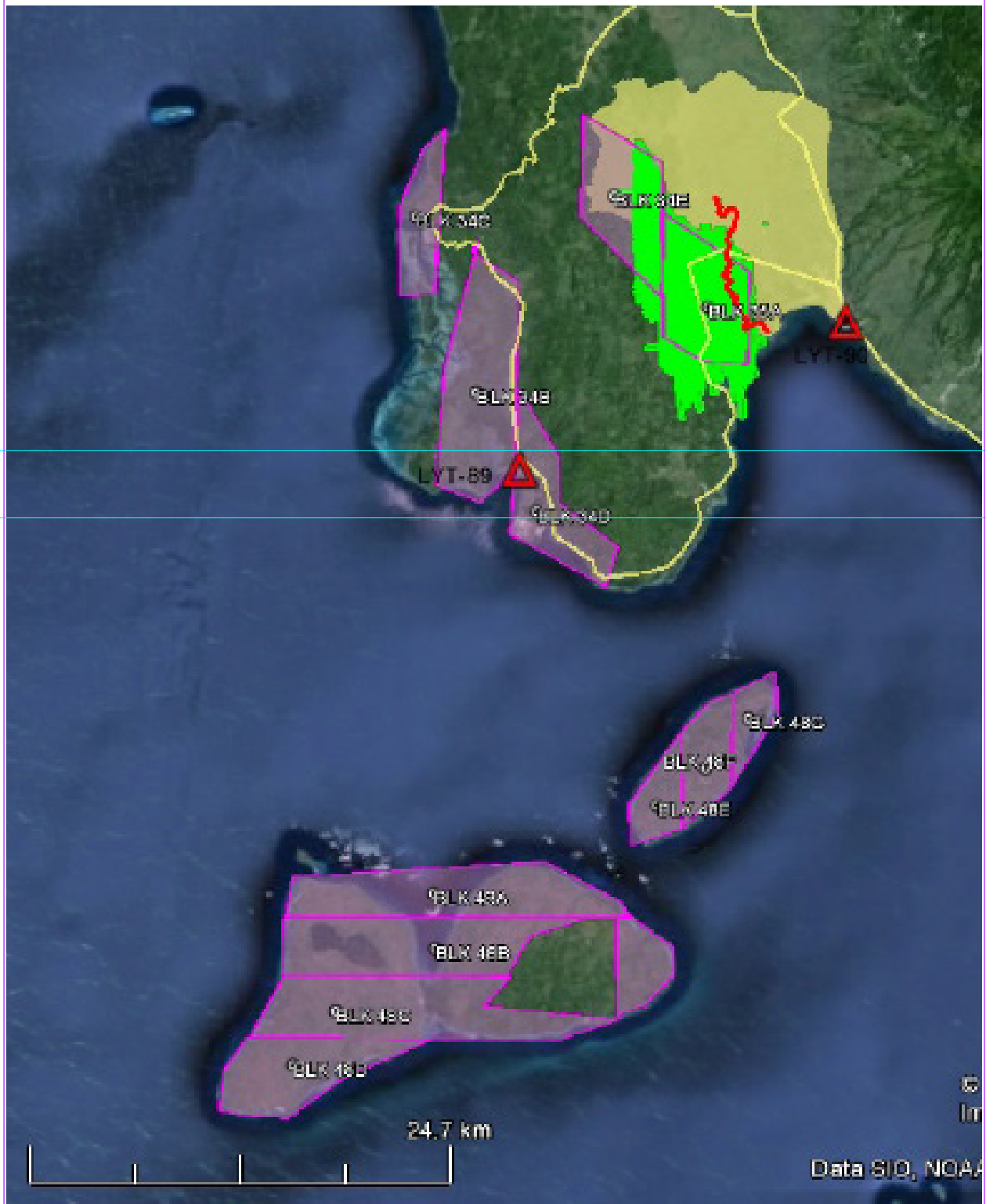


Figure A-7.18. Swath for Flight No. 8389AC

Flight No. : 8391AC  
Area: BLK 35EC  
Mission Name: 3BLK35EC069A  
Parameters:  
Altitude: 550  
Scan Frequency: 45  
Scan Angle: 18  
Overlap: 30

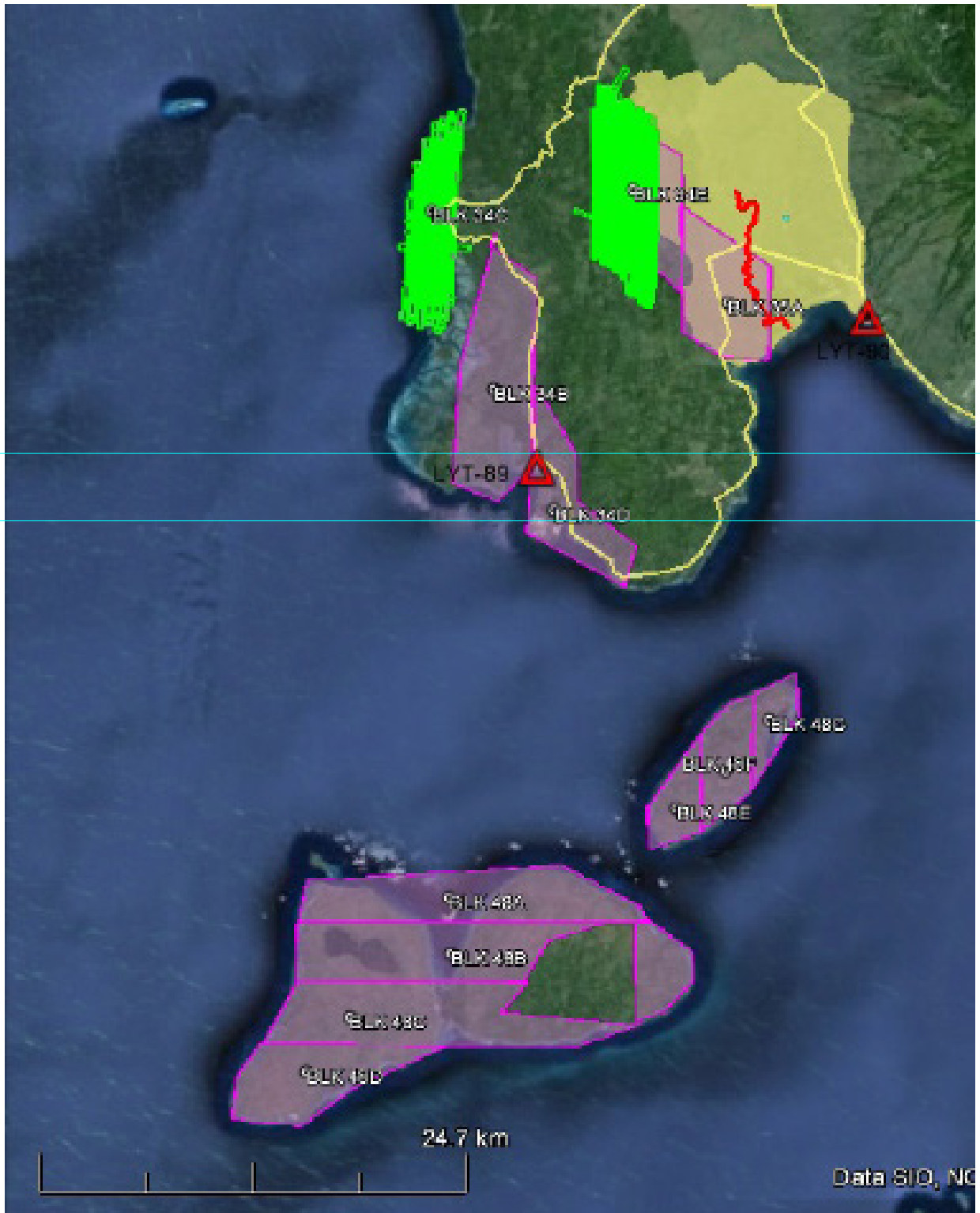


Figure A-7.19. Swath for Flight No. 8391AC

Flight No. : 8392AC  
Area: BLK 35BD  
Mission Name: 3BLK35BD069B  
Parameters:  
Altitude: 550  
Scan Frequency: 45  
Scan Angle: 18  
Overlap: 30



Figure A-7.20. Swath for Flight No. 8392AC

Flight No. : 8394AC  
Area: BLK 35BD  
Mission Name: 3BLK35BD070B  
Parameters:  
Altitude: 550  
Scan Frequency: 45  
Scan Angle: 18  
Overlap: 30

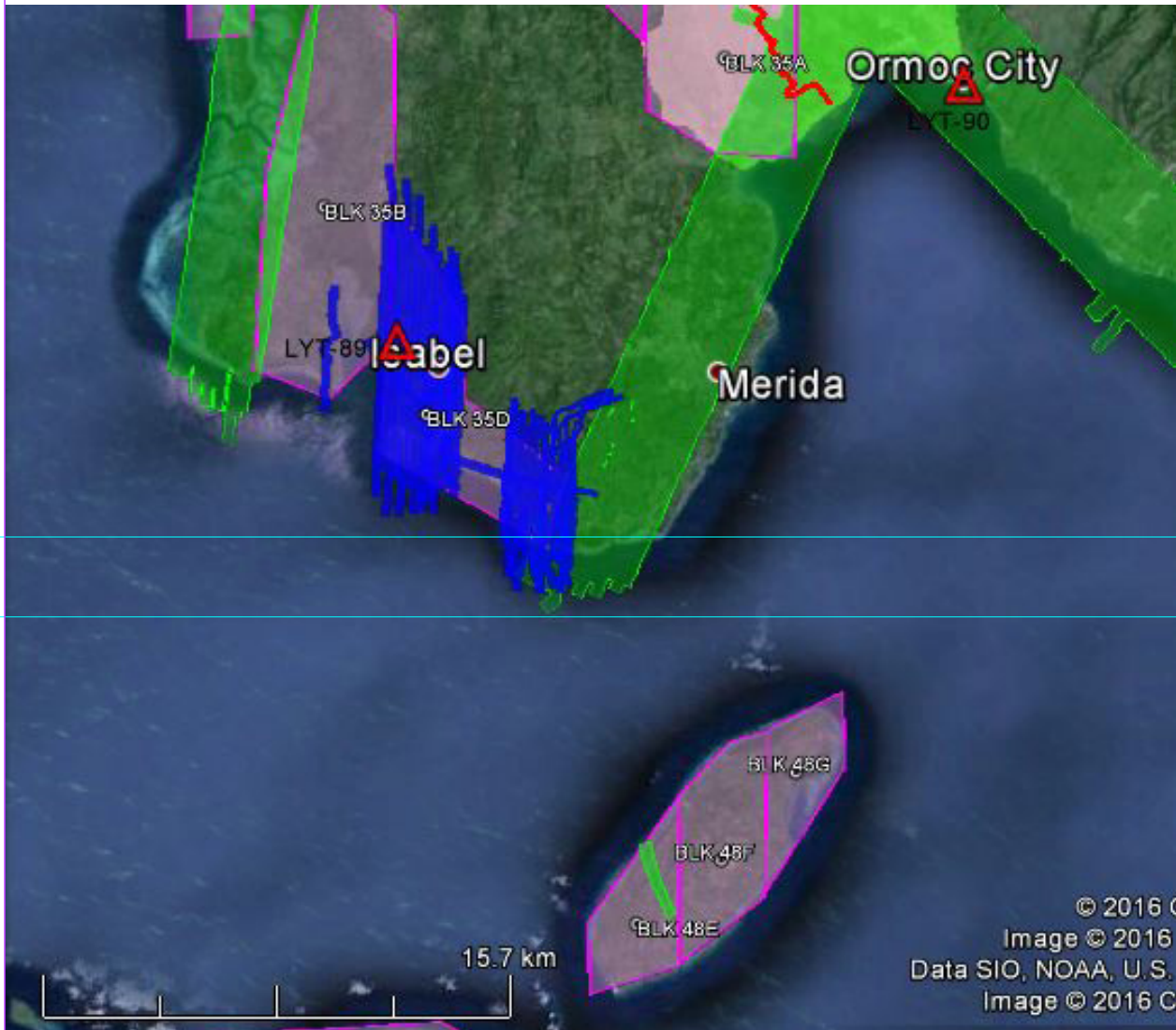


Figure A-7.21. Swath for Flight No. 8394AC

Flight No. : 8408AC  
Area: BLK 35DCE  
Mission Name: 3BLK35S079A  
Parameters:  
Altitude: 600  
Scan Frequency: 45  
Scan Angle: 18  
Overlap: 30

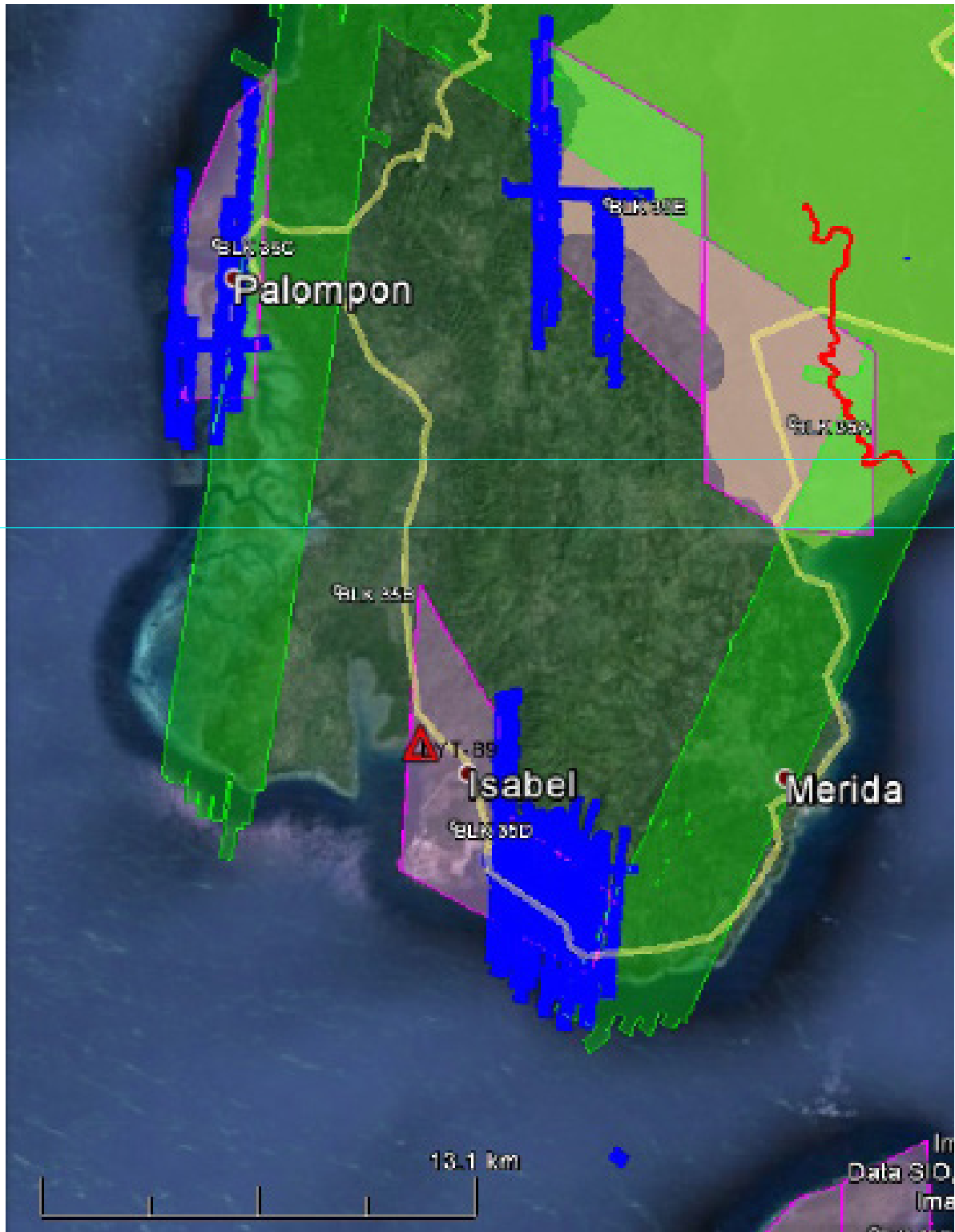


Figure A-7.22. Swath for Flight No. 8408AC

Flight No. : 8409AC  
Area: BLK 48DS  
Mission Name: 3BLK35S079B  
Parameters:  
Altitude: 600  
Scan Frequency: 45  
Scan Angle: 18  
Overlap: 30

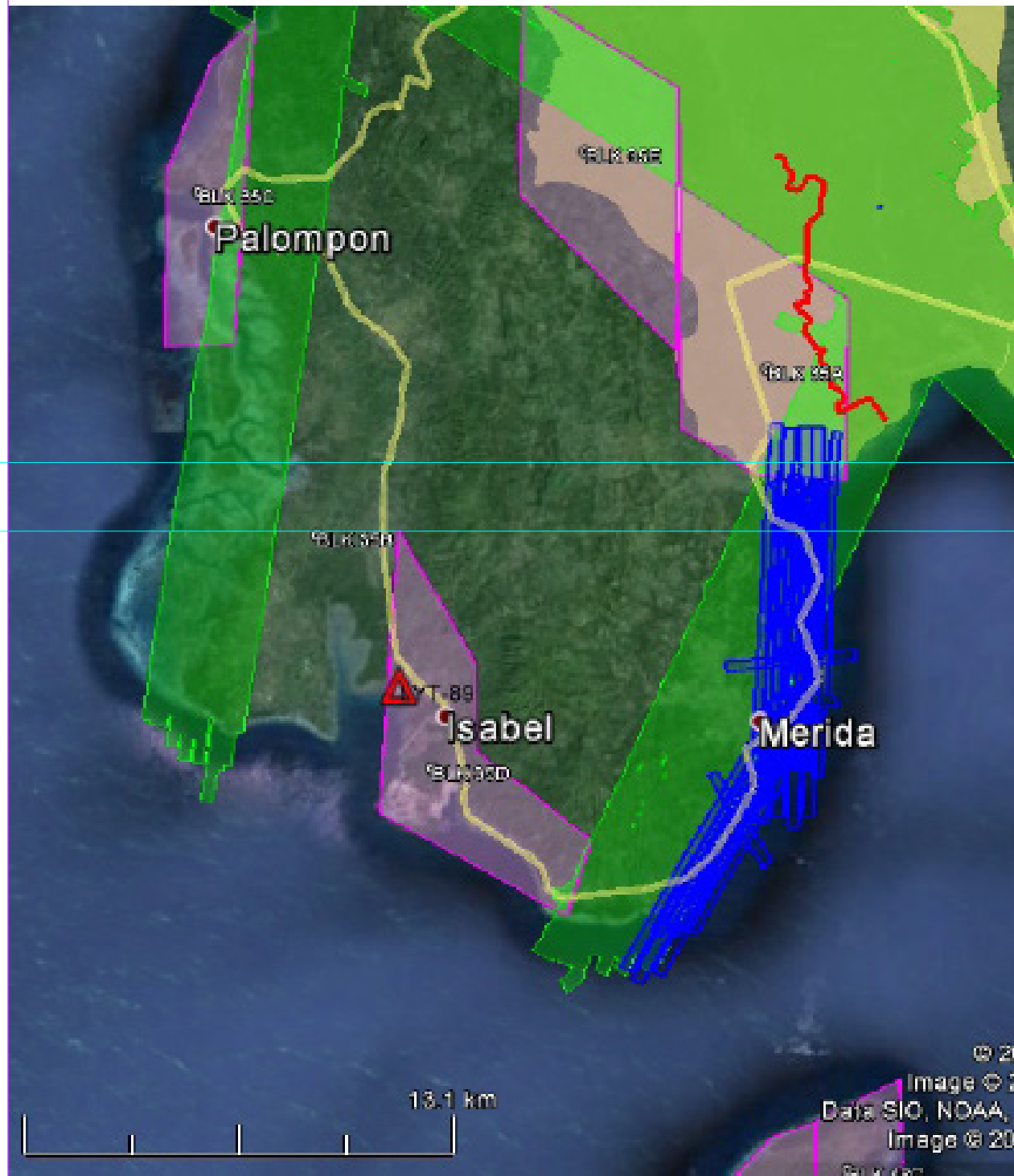


Figure A-7.23. Swath for Flight No. 8409AC

Flight No. : 3945G  
Area: BLK 35A and 35B  
Mission Name: 2BLK35AB107A  
Parameters:  
Altitude: 800, 1000  
Scan Frequency: 45  
Scan Angle: 20  
Overlap: 30

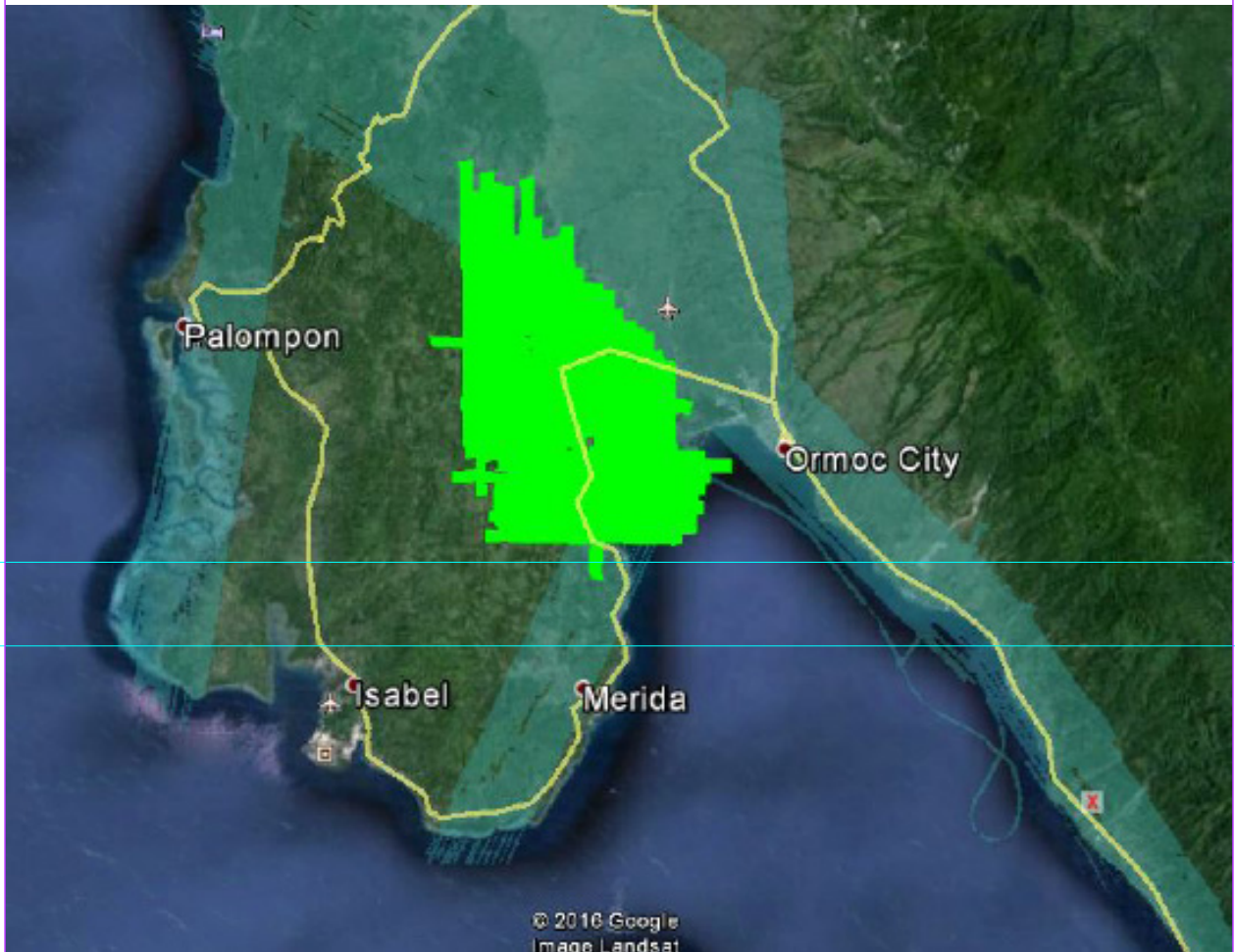


Figure A-7.24. Swath for Flight No. 3945G



Flight No. : 3947G  
Area: BLK 35CS  
Mission Name: 2BLK35CS107B  
Parameters:  
Altitude: 1100  
Scan Frequency: 45  
Scan Angle: 20  
Overlap: 30

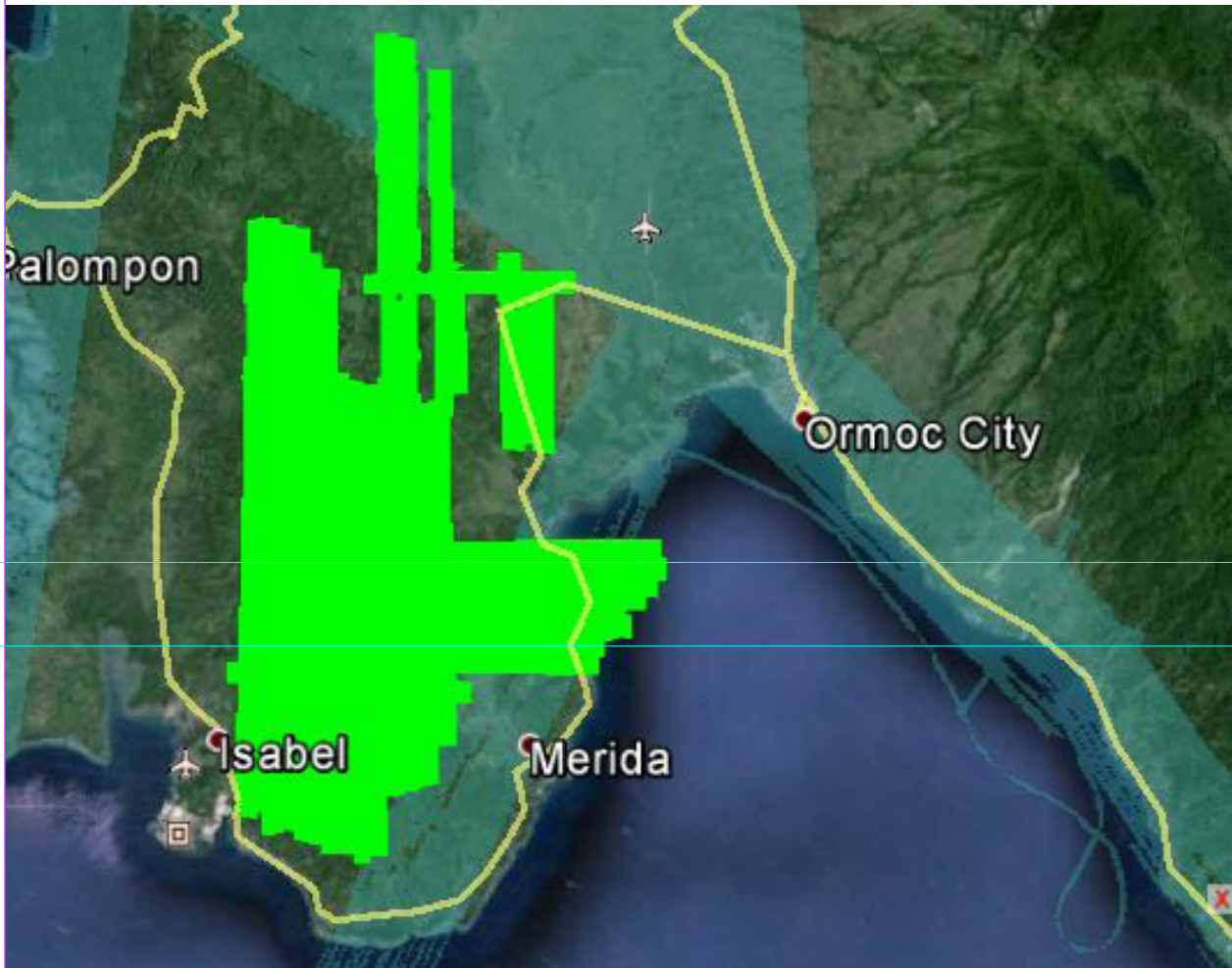


Figure A-7.25. Swath for Flight No. 3947G

## ANNEX 8. Mission Summary Reports

Table A-8.1. Mission Summary Report for Mission Blk35A

Flight Area	Samar-Leyte
<b>Mission Name</b>	Blk35A
<b>Inclusive Flights</b>	1504A
<b>Range data size</b>	11.4 GB
<b>POS</b>	265 MB
<b>Image</b>	15.7 MB
<b>Transfer date</b>	61.3 GB
	June 10, 2014
<i>Solution Status</i>	
<b>Number of Satellites (&gt;6)</b>	
<b>PDOP (&lt;3)</b>	Yes
<b>Baseline Length (&lt;30km)</b>	Yes
<b>Processing Mode (&lt;=1)</b>	Yes
	No
<i>Smoothed Performance Metrics (in cm)</i>	
<b>RMSE for North Position (&lt;4.0 cm)</b>	
<b>RMSE for East Position (&lt;4.0 cm)</b>	1.4
<b>RMSE for Down Position (&lt;8.0 cm)</b>	1.9
	2.5
<b>Boresight correction stdev (&lt;0.001deg)</b>	
<b>IMU attitude correction stdev (&lt;0.001deg)</b>	0.000264
<b>GPS position stdev (&lt;0.01m)</b>	0.001690
	0.0085
<b>Minimum % overlap (&gt;25)</b>	
<b>Ave point cloud density per sq.m. (&gt;2.0)</b>	52.02%
<b>Elevation difference between strips (&lt;0.20 m)</b>	3.13
	Yes
<b>Number of 1km x 1km blocks</b>	
<b>Maximum Height</b>	107
<b>Minimum Height</b>	184.83 m
	57.11 m
<i>Classification (# of points)</i>	
<b>Ground</b>	
<b>Low vegetation</b>	51,584,742
<b>Medium vegetation</b>	65,607,742
<b>High vegetation</b>	63,615,309
<b>Building</b>	9,673,867
	5,271,987
<b>Orthophoto</b>	Yes
<b>Processed by</b>	Engr. Irish Cortez, Engr. Chelou Prado, Engr. Jeffrey Delica

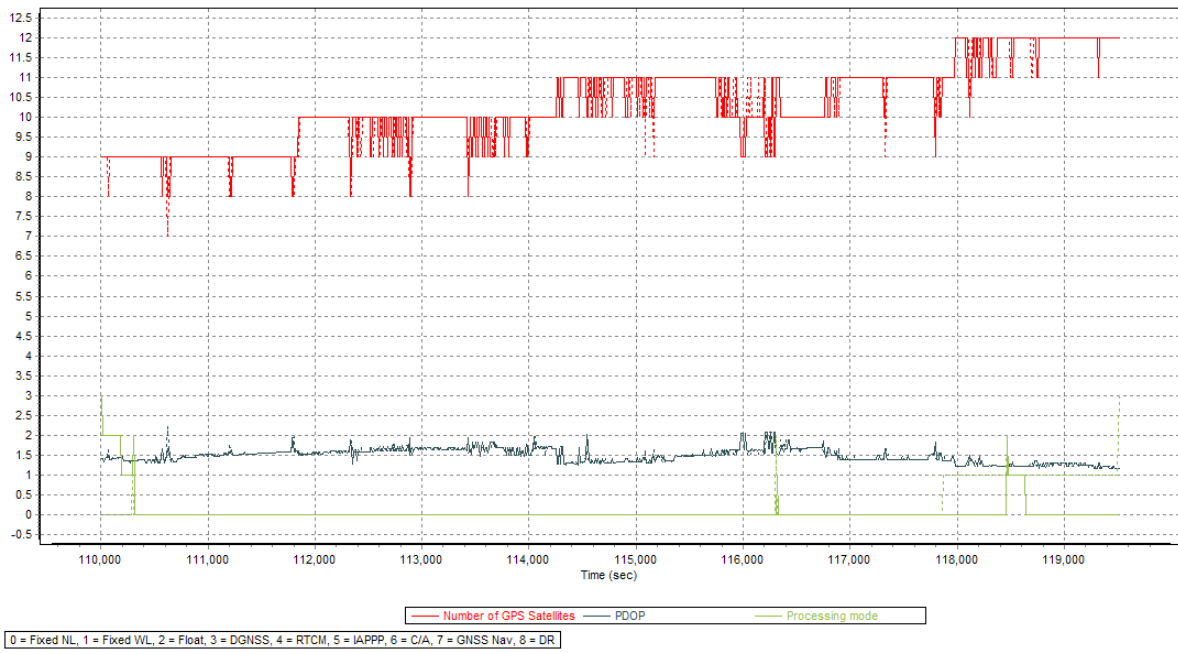


Figure A-8.1. Solution Status

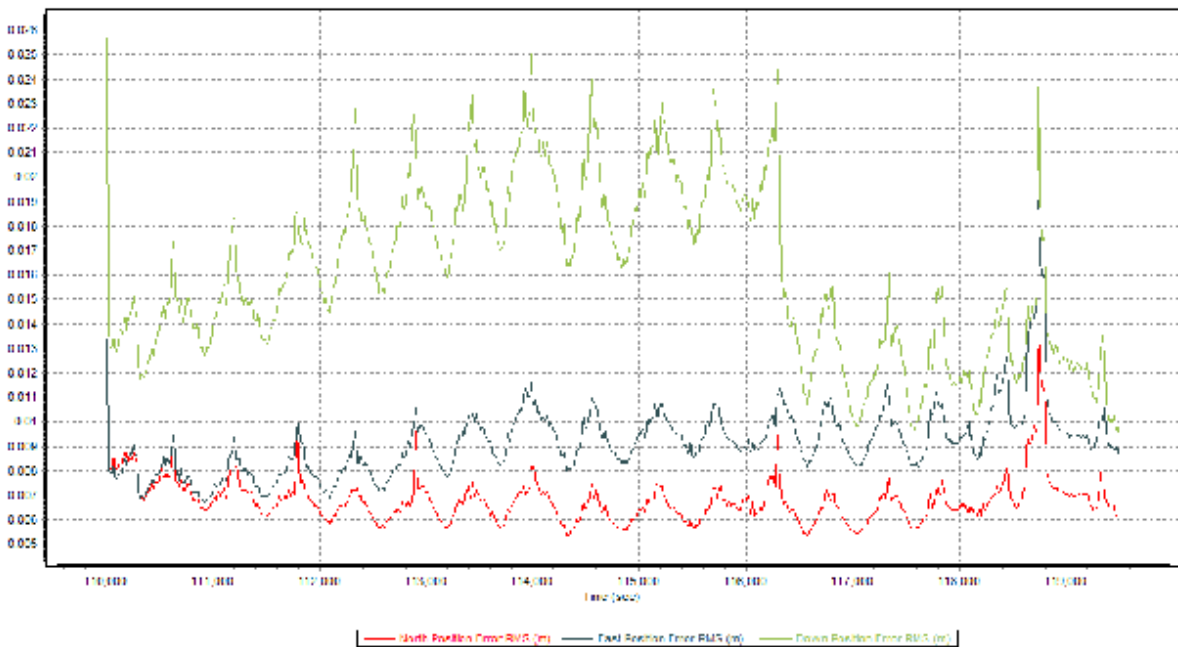


Figure A-8.2. Smoothed Performance Metrics Parameters

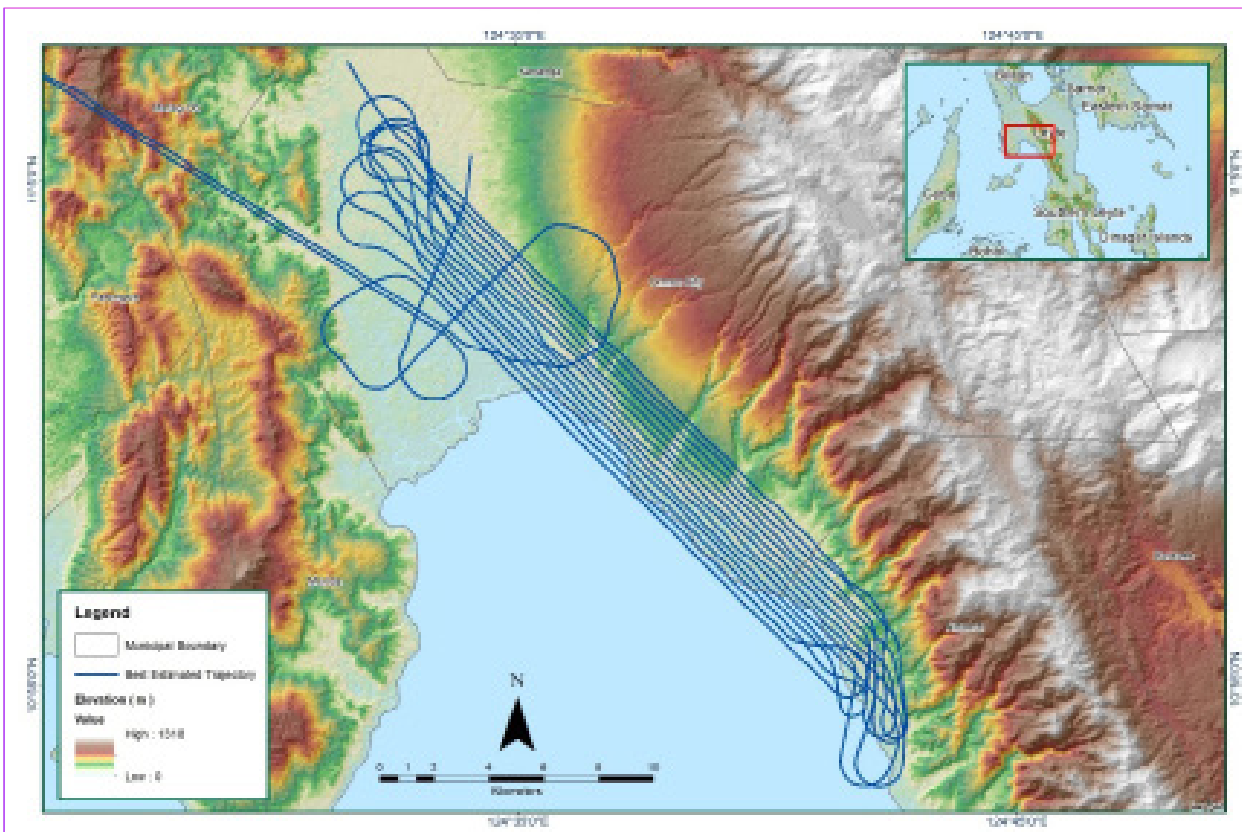


Figure A-8.3. Best Estimated Trajectory

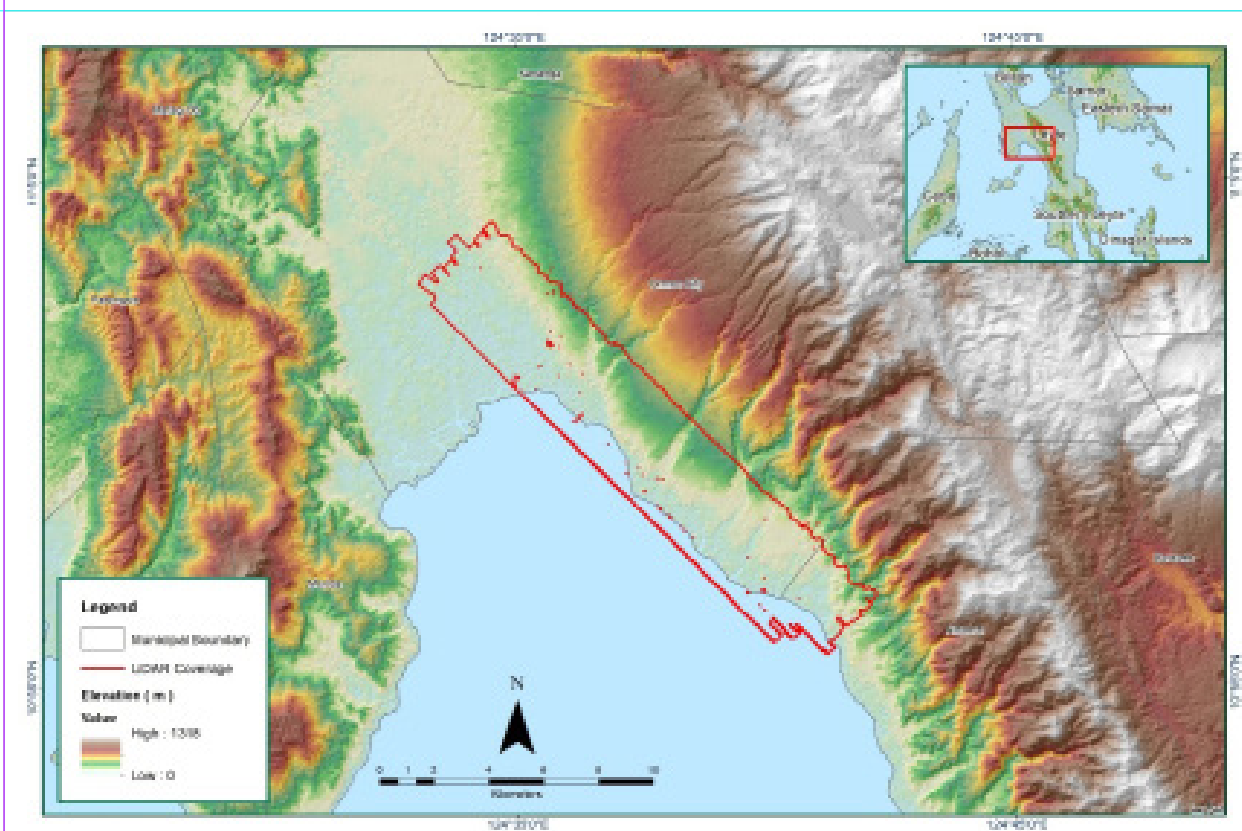


Figure A-8.3. Best Estimated Trajectory

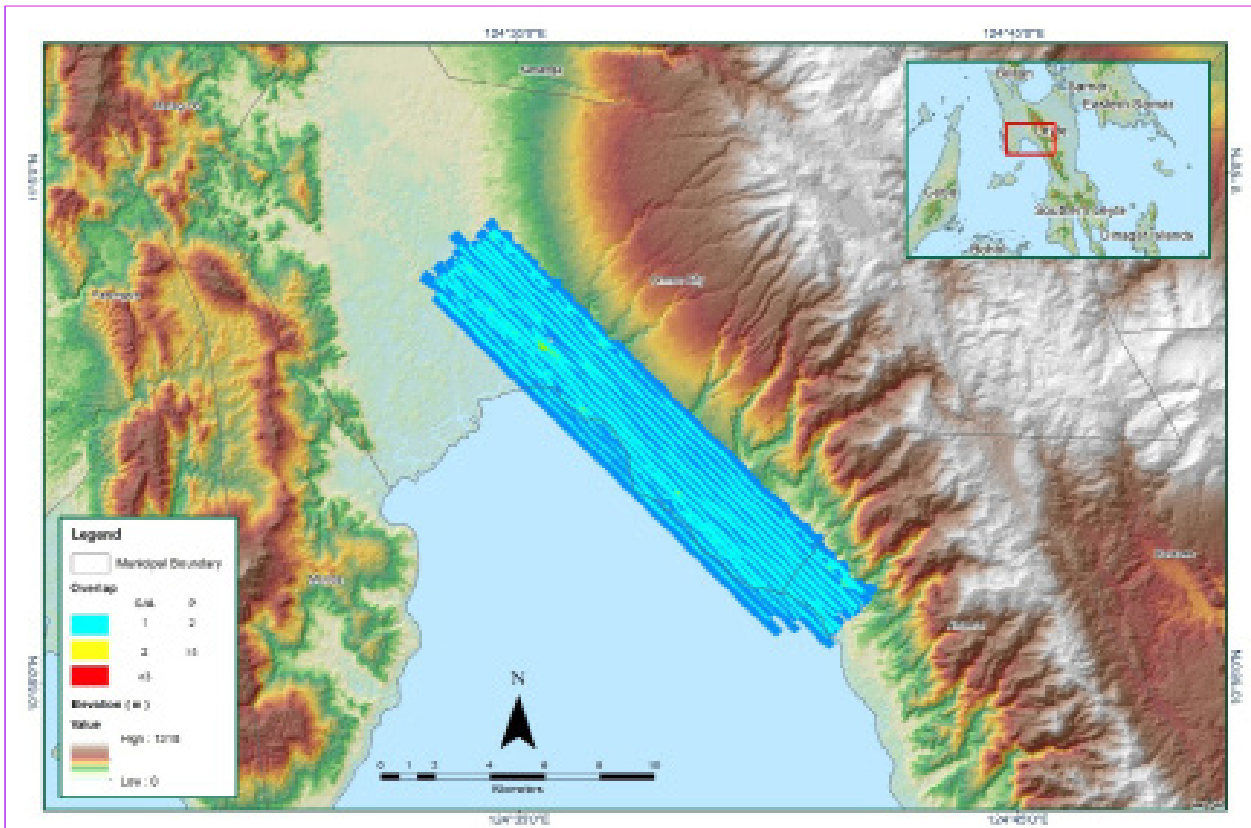


Figure A-8.5. Image of data overlap

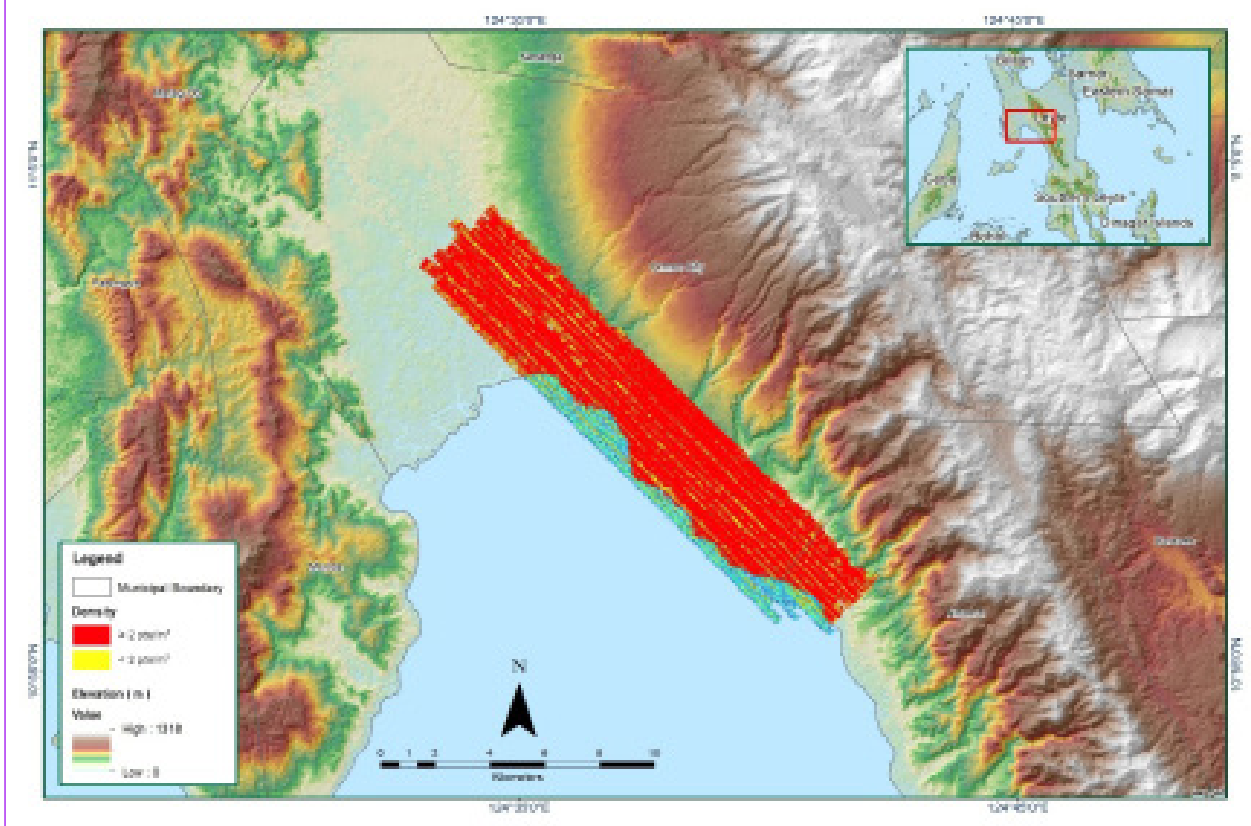


Figure A-8.6. Density map of merged LiDAR data

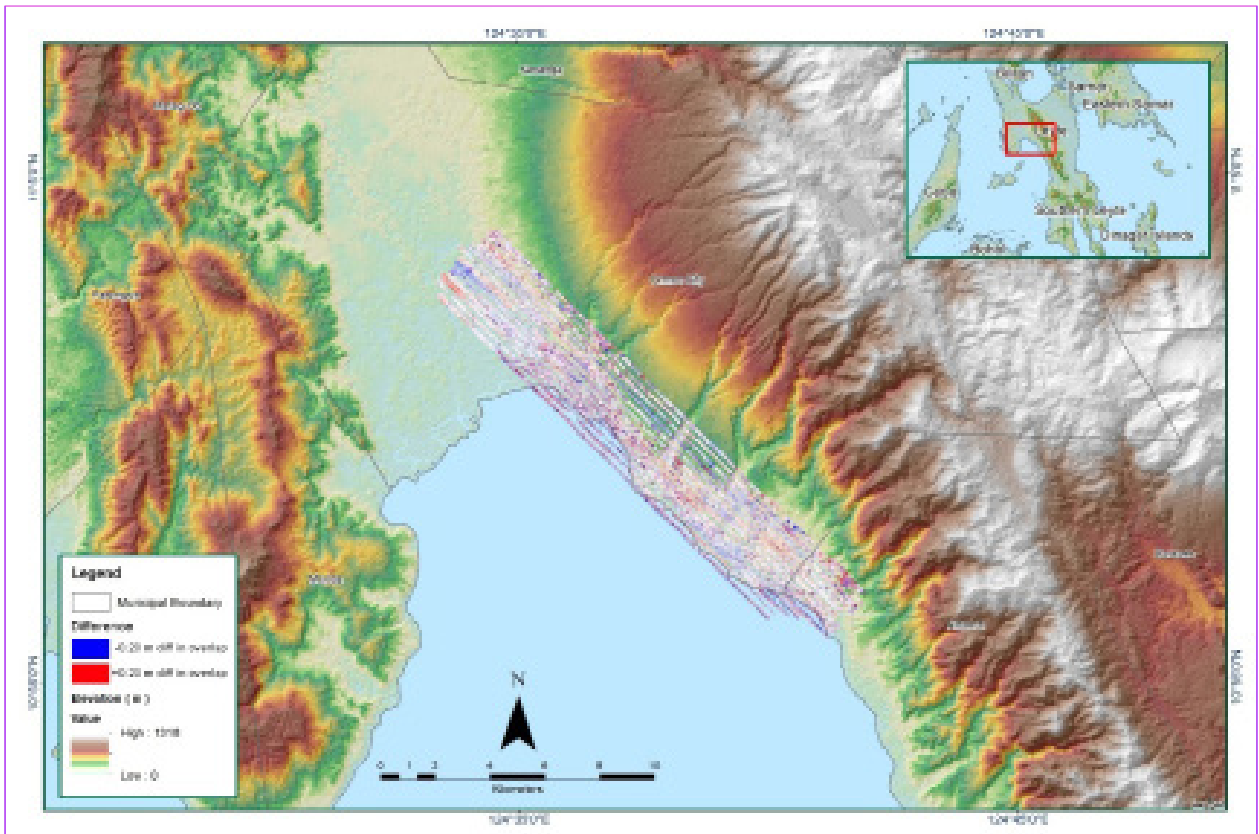


Figure A-8.7. Elevation difference between flight lines

Table A-8.2. Mission Summary Report for Mission Blk35I

<b>Flight Area</b>	<b>Samar-Leyte</b>
<b>Mission Name</b>	Blk35I
<b>Inclusive Flights</b>	1502A, 1504A
<b>Range data size</b>	25.3 GB
<b>POS data size</b>	543 MB
<b>Base data size</b>	31.4 MB
<b>Image</b>	148 GB
<b>Transfer date</b>	June 10, 2014
<i>Solution Status</i>	
<b>Number of Satellites (&gt;6)</b>	Yes
<b>PDOP (&lt;3)</b>	Yes
<b>Baseline Length (&lt;30km)</b>	No
<b>Processing Mode (&lt;=1)</b>	No
<i>Smoothed Performance Metrics (in cm)      Figure A-8.1. Solution Status</i>	
<b>RMSE for North Position (&lt;4.0 cm)</b>	2.945
<b>RMSE for East Position (&lt;4.0 cm)</b>	2.56
<b>RMSE for Down Position (&lt;8.0 cm)</b>	5.176
<i>Boresight correction stdev (&lt;0.001deg)</i>	
<i>IMU attitude correction stdev (&lt;0.001deg)</i>	
<i>GPS position stdev (&lt;0.01m)</i>	
<b>Minimum % overlap (&gt;25)</b>	68.60%
<b>Ave point cloud density per sq.m. (&gt;2.0)</b>	5.18
<b>Elevation difference between strips (&lt;0.20 m)</b>	Yes
<b>Number of 1km x 1km blocks</b>	109
<b>Maximum Height</b>	514.41 m
<b>Minimum Height</b>	52.26 m
<i>Classification (# of points)</i>	
<b>Ground</b>	55,725,687
<b>Low vegetation</b>	70,544,651
<b>Medium vegetation</b>	140,006,924
<b>High vegetation</b>	51,430,148
<b>Building</b>	1,264,171
<i>Figure A-8.2. Smoothed Performance Metrics Parameters</i>	
<b>Orthophoto</b>	No
<b>Processed by</b>	Engr. Irish Cortez, Engr. Harmond Santos, Engr. Gladys Mae Apat

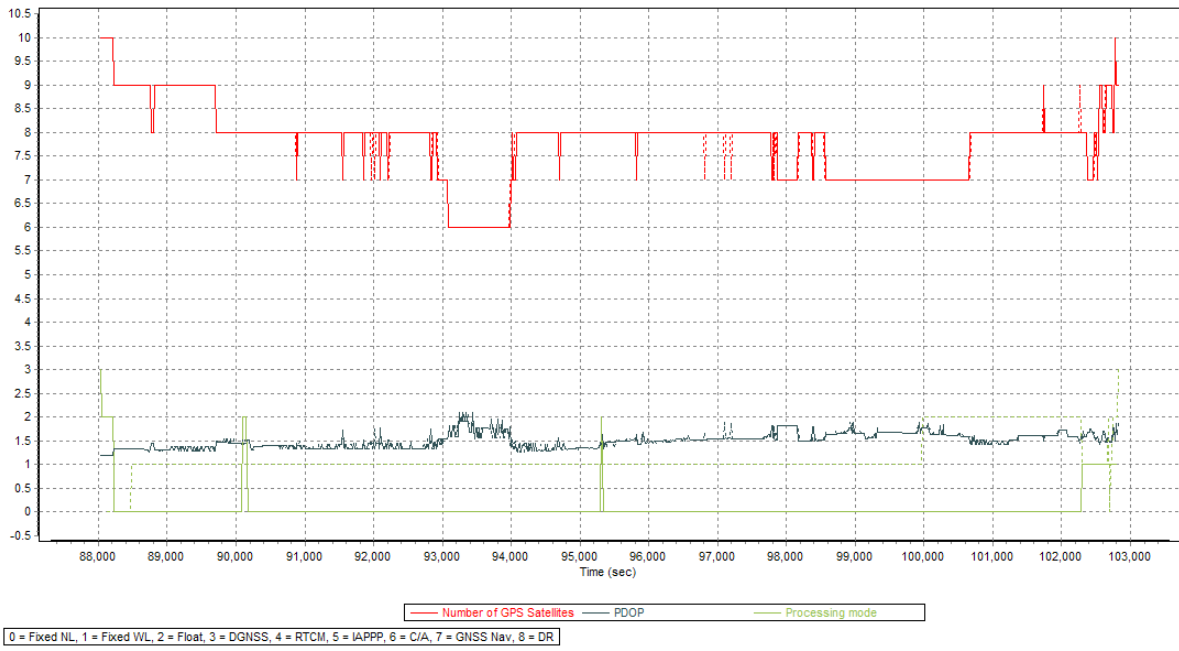


Figure A-8.8. Solution Status

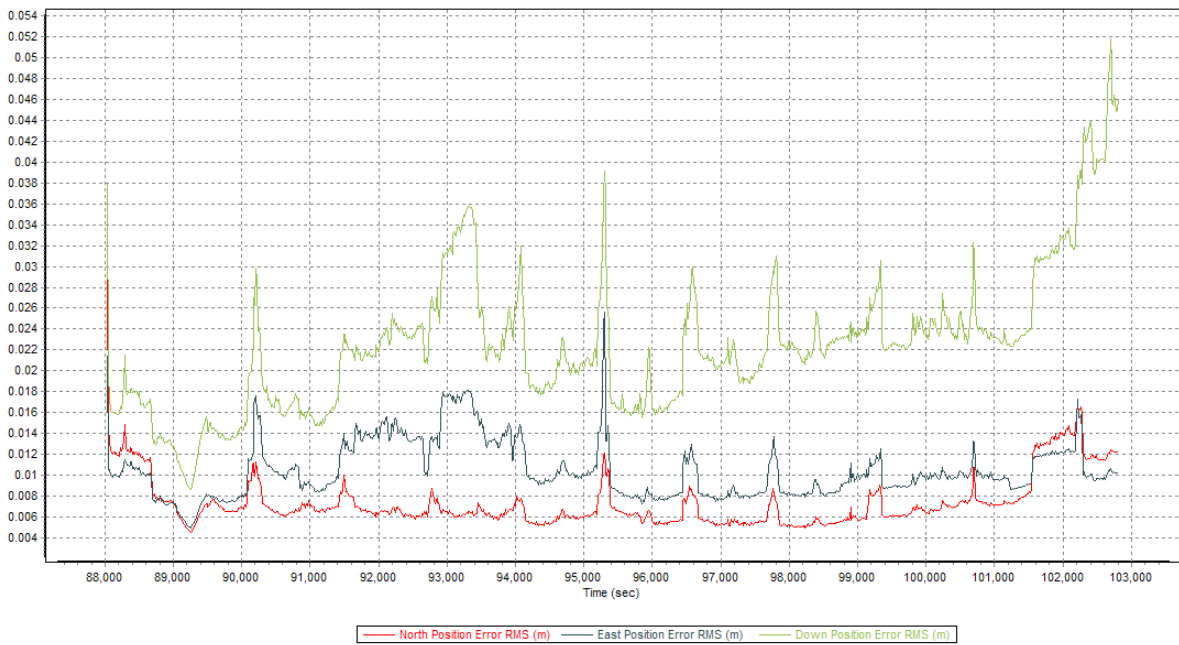


Figure A-8.9. Smoothed Performance Metrics Parameters



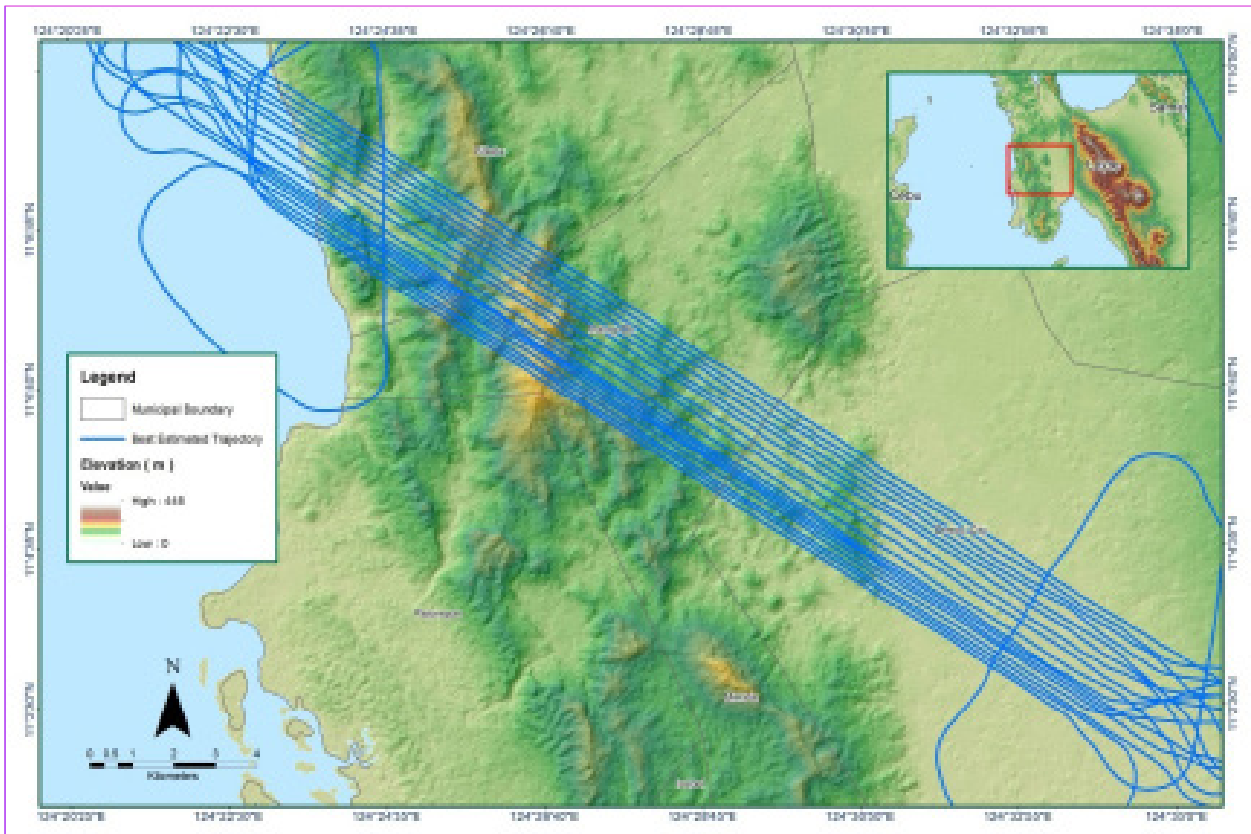


Figure A-8.10. Best Estimated Trajectory

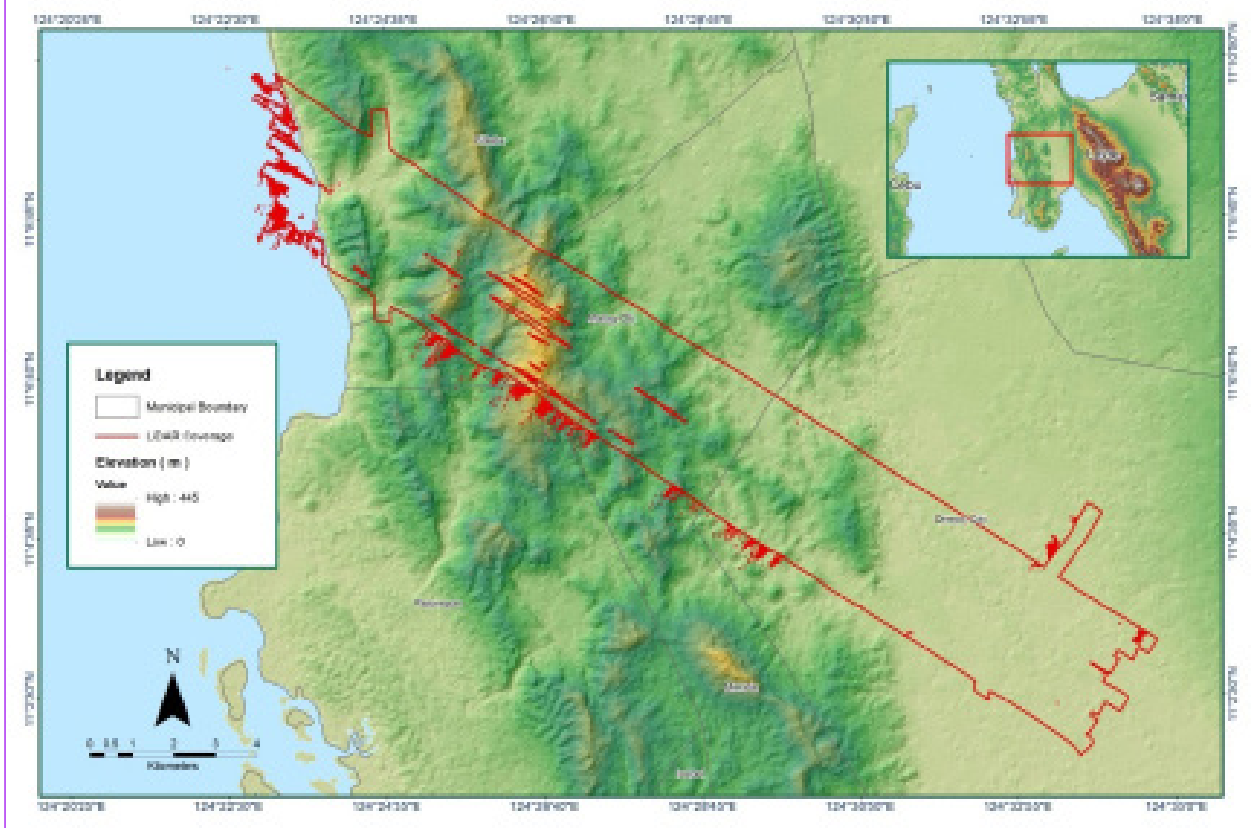


Figure A-8.11. Coverage of LiDAR data

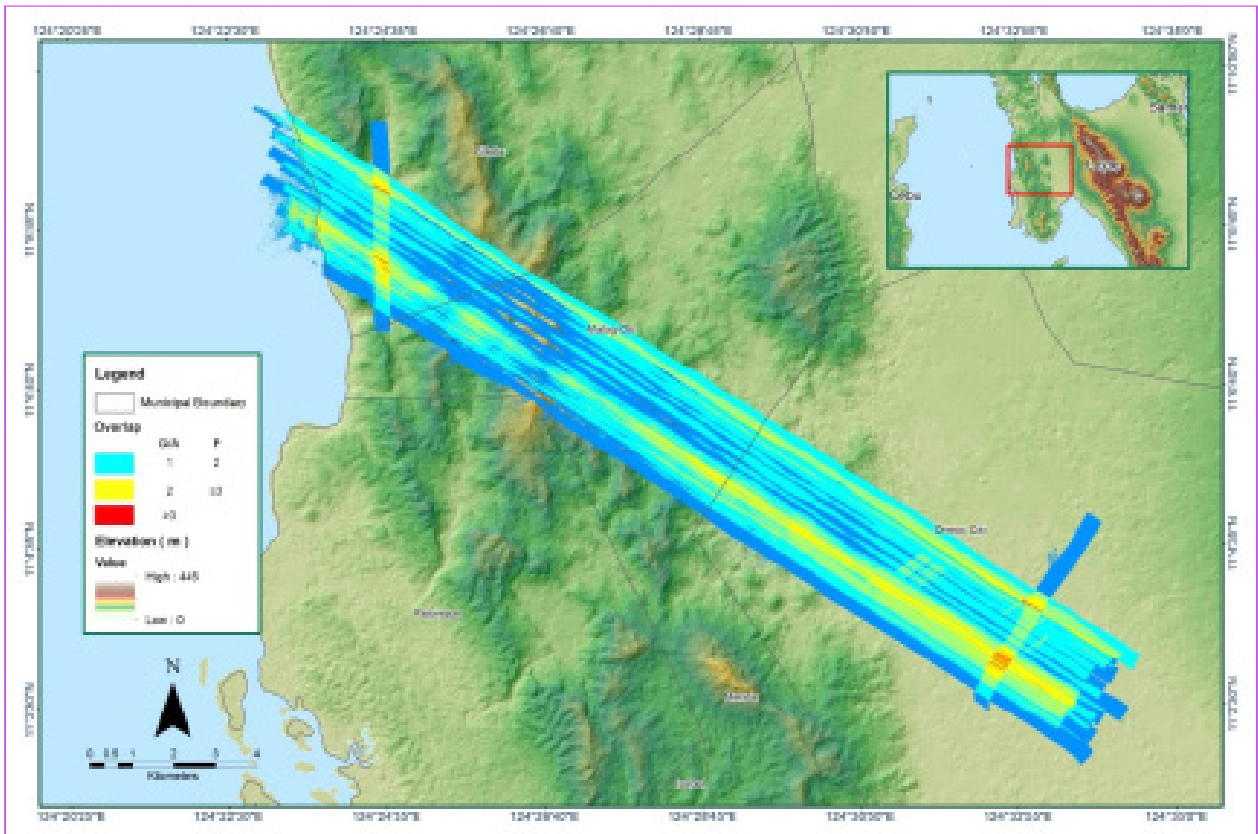


Figure A-8.12. Image of data overlap

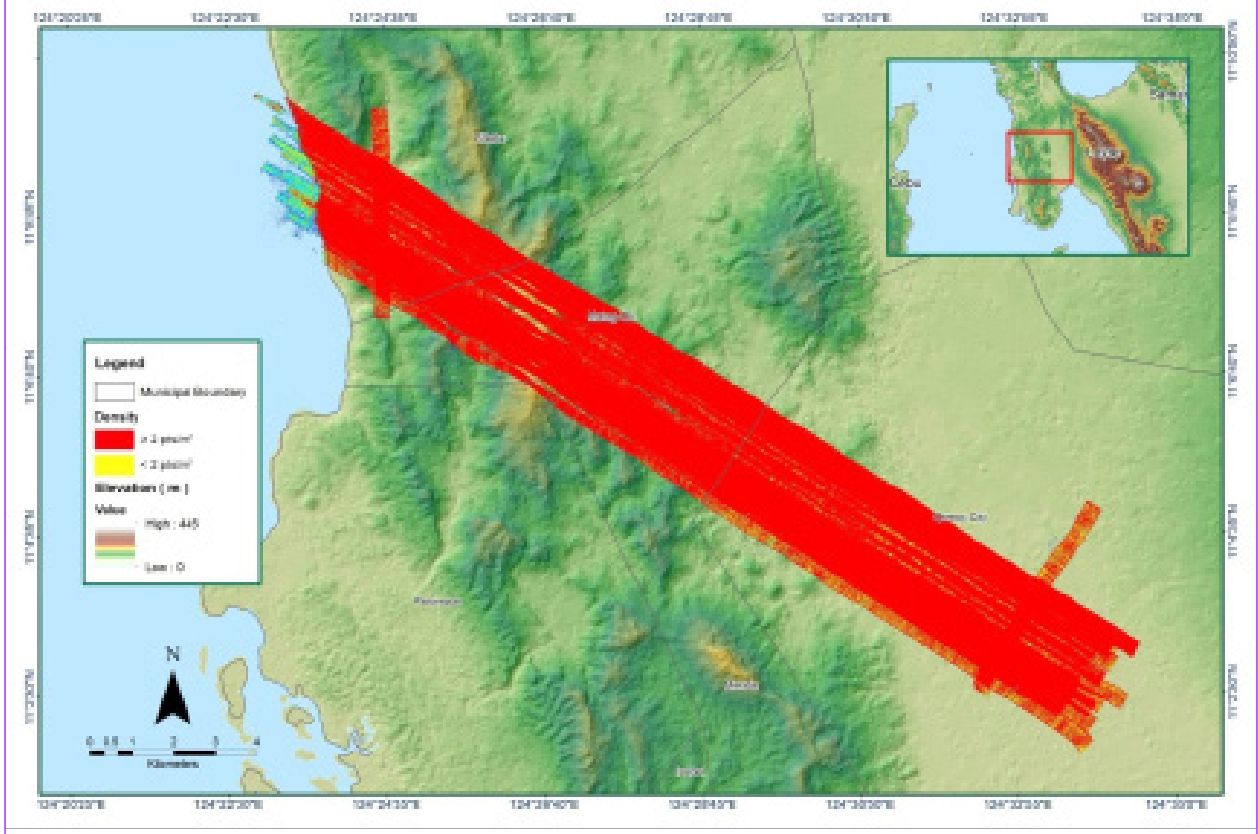


Figure A-8.13. Density map of merged LiDAR data

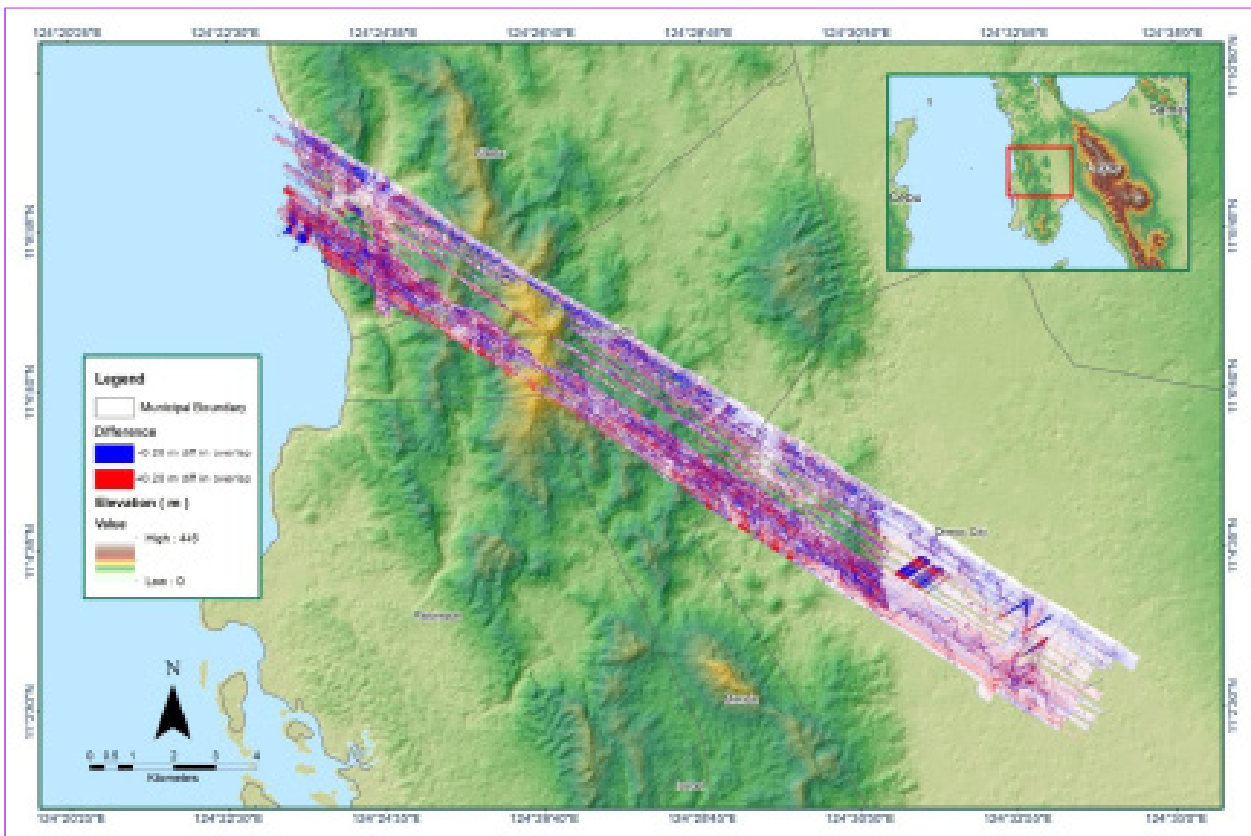


Figure A-8.14. Elevation difference between flight lines

Table A-8.3. Mission Summary Report for Mission Blk35H\_Supplement

<b>Flight Area</b>	<b>Samar-Leyte</b>
<b>Mission Name</b>	Blk35H_Supplement
<b>Inclusive Flights</b>	1498A
<b>Range data size</b>	3.23 GB
<b>POS data size</b>	282 MB
<b>Base data size</b>	8.04 MB
<b>Image</b>	88.7 GB
<b>Transfer date</b>	June 10, 2014
<i>Solution Status</i>	
<b>Number of Satellites (&gt;6)</b>	Yes
<b>PDOP (&lt;3)</b>	Yes
<b>Baseline Length (&lt;30km)</b>	No
<b>Processing Mode (&lt;=1)</b>	No
<i>Smoothed Performance Metrics (in cm)</i>	
<b>RMSE for North Position (&lt;4.0 cm)</b>	3.34
<b>RMSE for East Position (&lt;4.0 cm)</b>	3.776
<b>RMSE for Down Position (&lt;8.0 cm)</b>	4.315
<b>Boresight correction stdev (&lt;0.001deg)</b>	0.000283
<b>IMU attitude correction stdev (&lt;0.001deg)</b>	0.000568
<b>GPS position stdev (&lt;0.01m)</b>	0.0028
<b>Minimum % overlap (&gt;25)</b>	51.18%
<b>Ave point cloud density per sq.m. (&gt;2.0)</b>	3.66
<b>Elevation difference between strips (&lt;0.20 m)</b>	Yes
<b>Number of 1km x 1km blocks</b>	151
<b>Maximum Height</b>	433.53 m
<b>Minimum Height</b>	53.21 m
<i>Classification (# of points)</i>	
<b>Ground</b>	77,606,477
<b>Low vegetation</b>	87,206,288
<b>Medium vegetation</b>	130,999,621
<b>High vegetation</b>	43,330,044
<b>Building</b>	1,222,961
<b>Orthophoto</b>	No
<b>Processed by</b>	Engr. Irish Cortez, Engr. Melanie Hingpit, Jovy Narisma

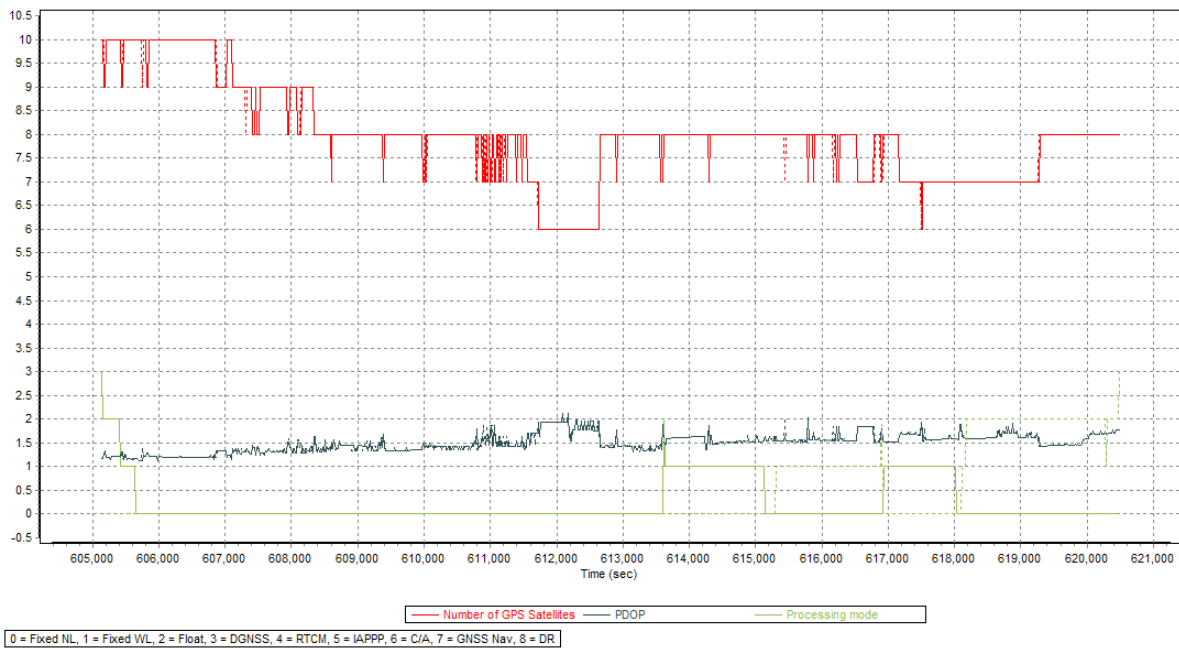


Figure A-8.15. Solution Status

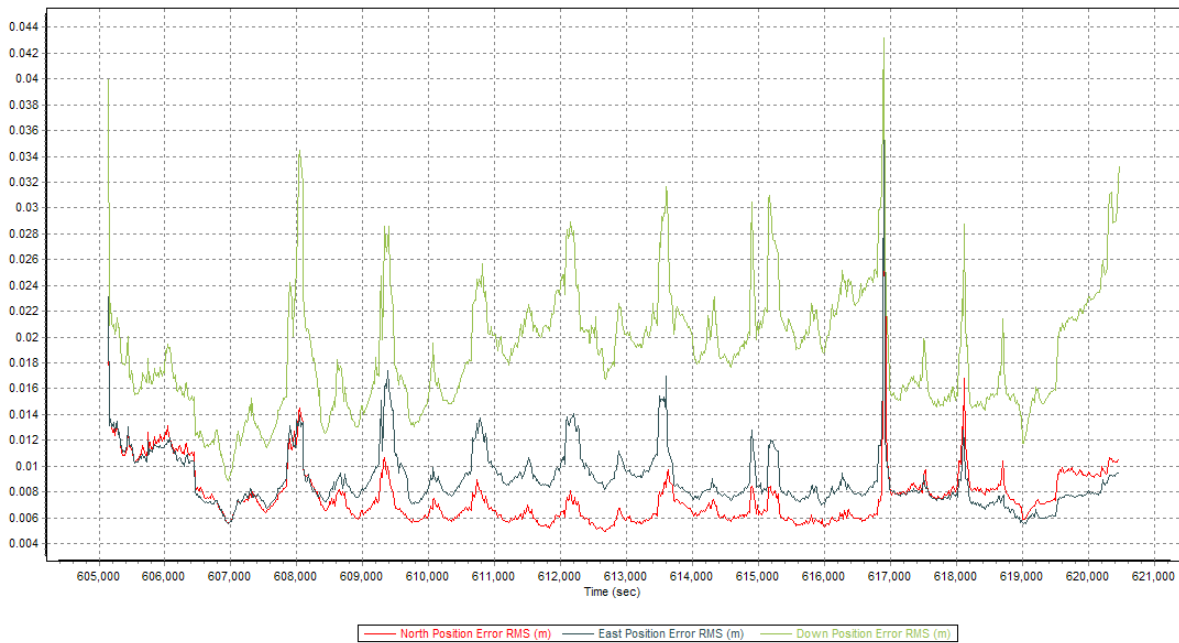


Figure A-8.16. Smoothed Performance Metrics Parameters

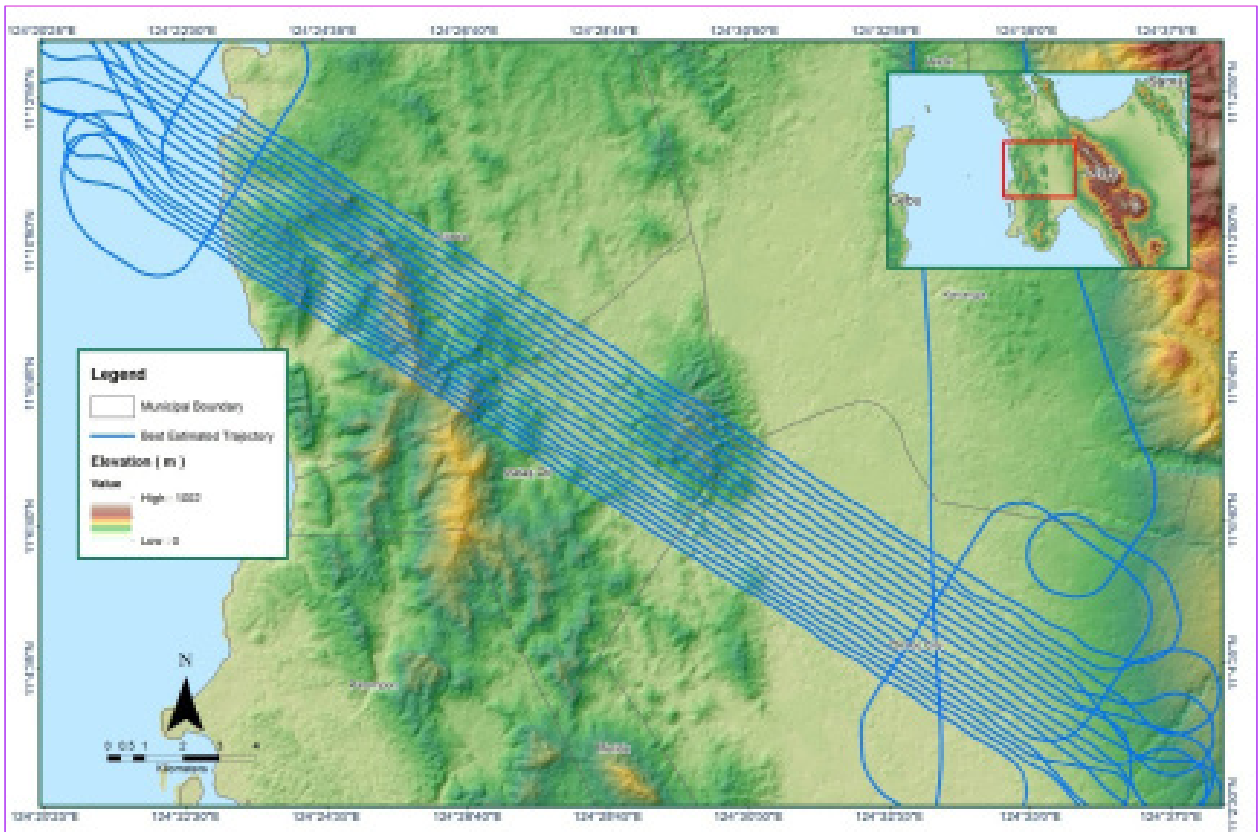


Figure A-8.17. Best Estimated Trajectory

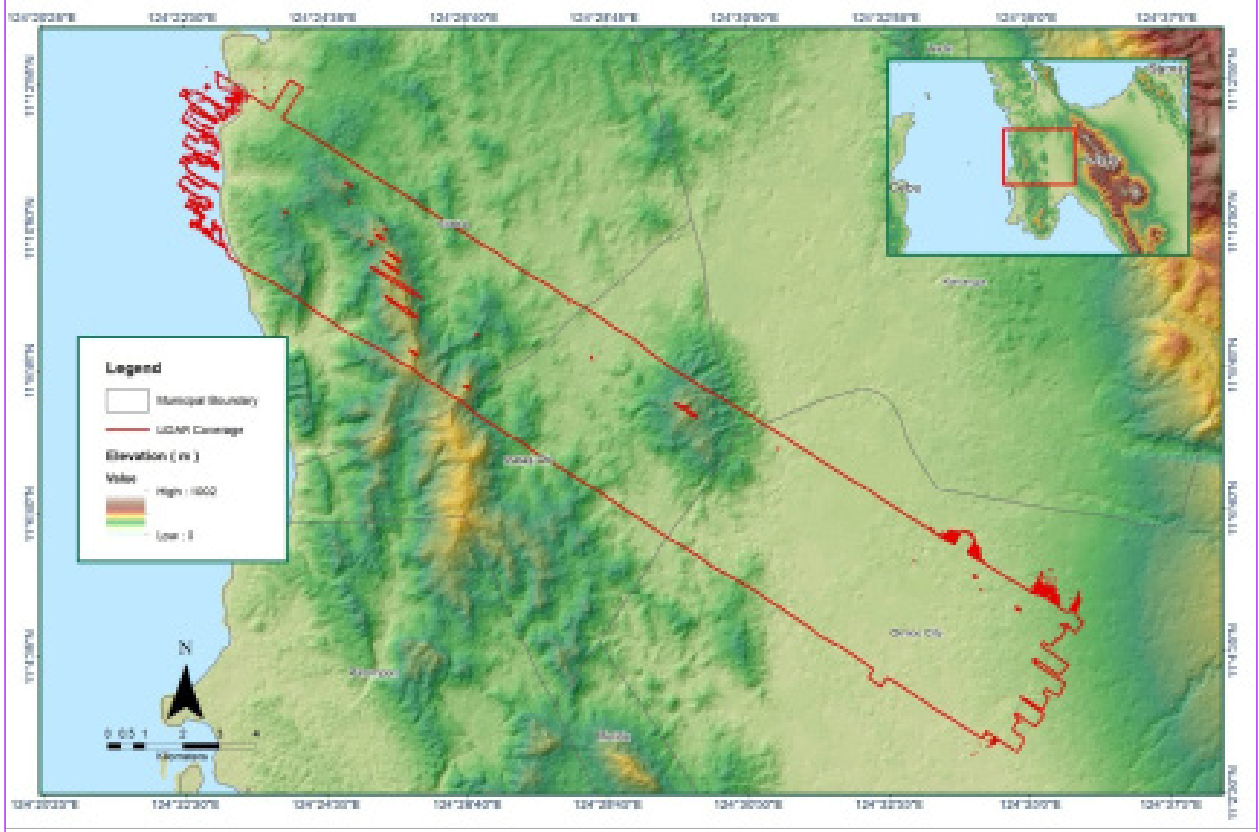


Figure A-8.18. Best Estimated Trajectory

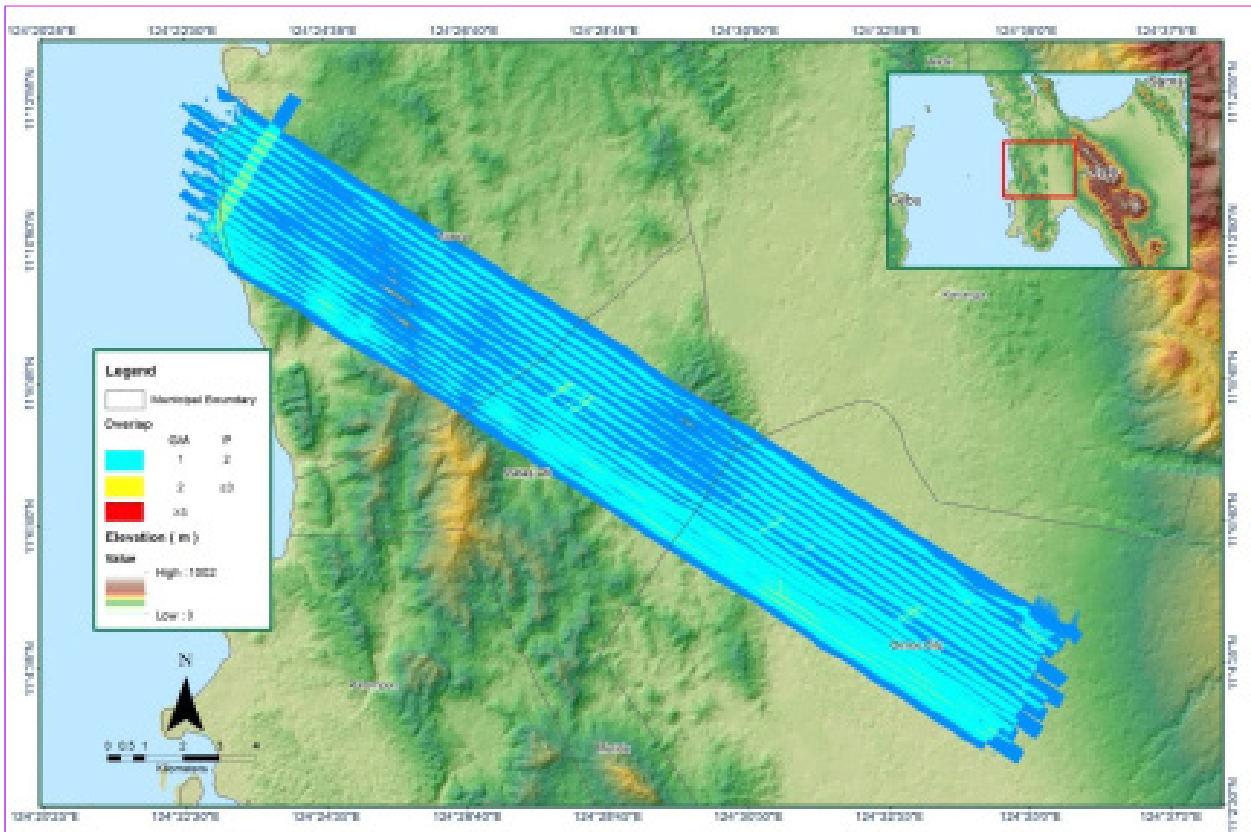


Figure A-8.19. Image of data overlap

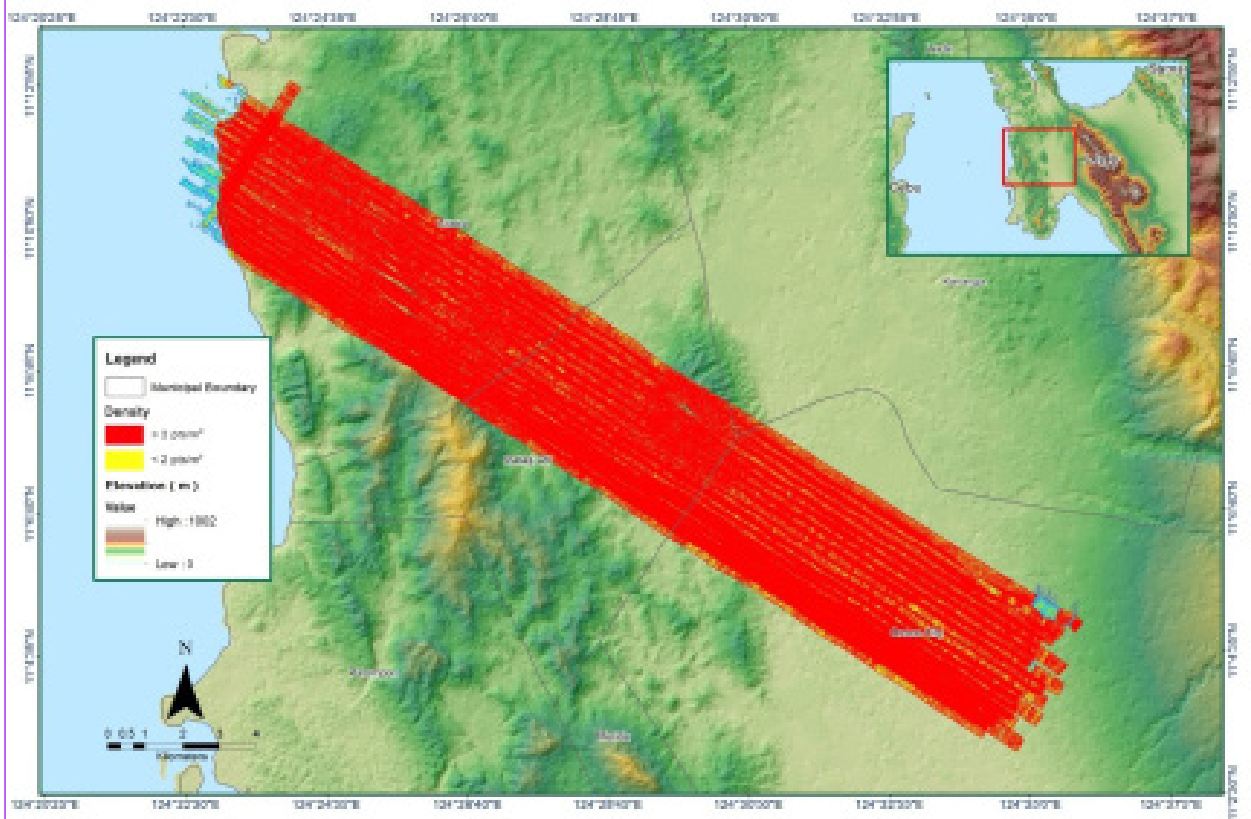


Figure A-8.20. Density map of merged LiDAR data

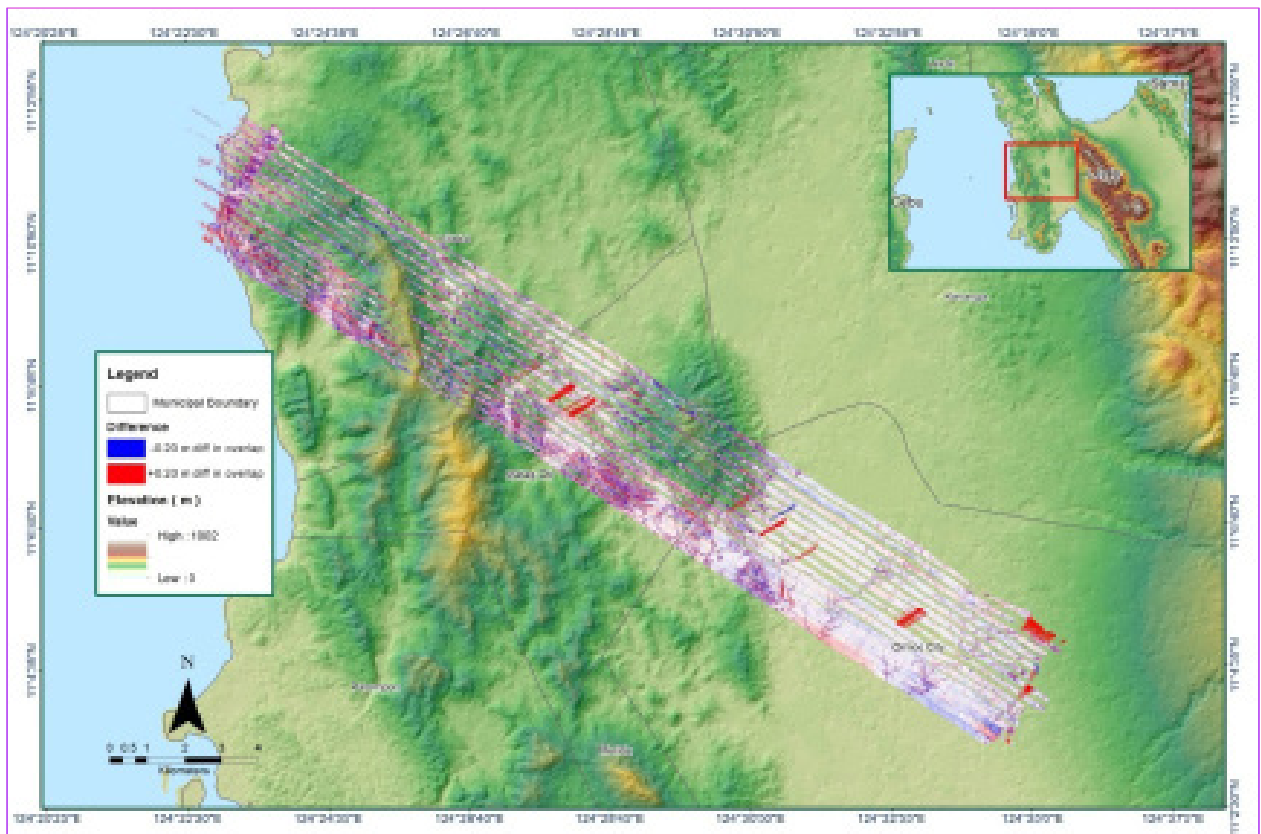


Figure A-8.21. Elevation difference between flight lines



Table A-8.4. Mission Summary Report for Mission Blk 35F

<b>Flight Area</b>	<b>Samar-Leyte</b>
<b>Mission Name</b>	Blk 35F
<b>Inclusive Flights</b>	1474A,1466A
<b>Range data size</b>	30 GB
<b>POS data size</b>	575 MB
<b>Base data size</b>	17.65 MB
<b>Image</b>	174.9 GB
<b>Transfer date</b>	June 10, 2014
<i>Solution Status</i>	
<b>Number of Satellites (&gt;6)</b>	Yes
<b>PDOP (&lt;3)</b>	Yes
<b>Baseline Length (&lt;30km)</b>	Yes
<b>Processing Mode (&lt;=1)</b>	Yes
<i>Smoothed Performance Metrics (in cm)</i>	
<b>RMSE for North Position (&lt;4.0 cm)</b>	1.9
<b>RMSE for East Position (&lt;4.0 cm)</b>	1.6
<b>RMSE for Down Position (&lt;8.0 cm)</b>	3.5
<b>Boresight correction stdev (&lt;0.001deg)</b>	0.000407
<b>IMU attitude correction stdev (&lt;0.001deg)</b>	0.002146
<b>GPS position stdev (&lt;0.01m)</b>	0.0037
<b>Minimum % overlap (&gt;25)</b>	56.25%
<b>Ave point cloud density per sq.m. (&gt;2.0)</b>	3.81
<b>Elevation difference between strips (&lt;0.20 m)</b>	Yes
<b>Number of 1km x 1km blocks</b>	223
<b>Maximum Height</b>	311.59 m
<b>Minimum Height</b>	53.60 m
<i>Classification (# of points)</i>	
<b>Ground</b>	116,883,933
<b>Low vegetation</b>	125,309,279
<b>Medium vegetation</b>	226,434,578
<b>High vegetation</b>	62,847,226
<b>Building</b>	1,471,558
<b>Orthophoto</b>	Yes
<b>Processed by</b>	Engr. Angelo Carlo Bongat, Engr. Melanie Hingpit, Engr. Gladys Mae Apat

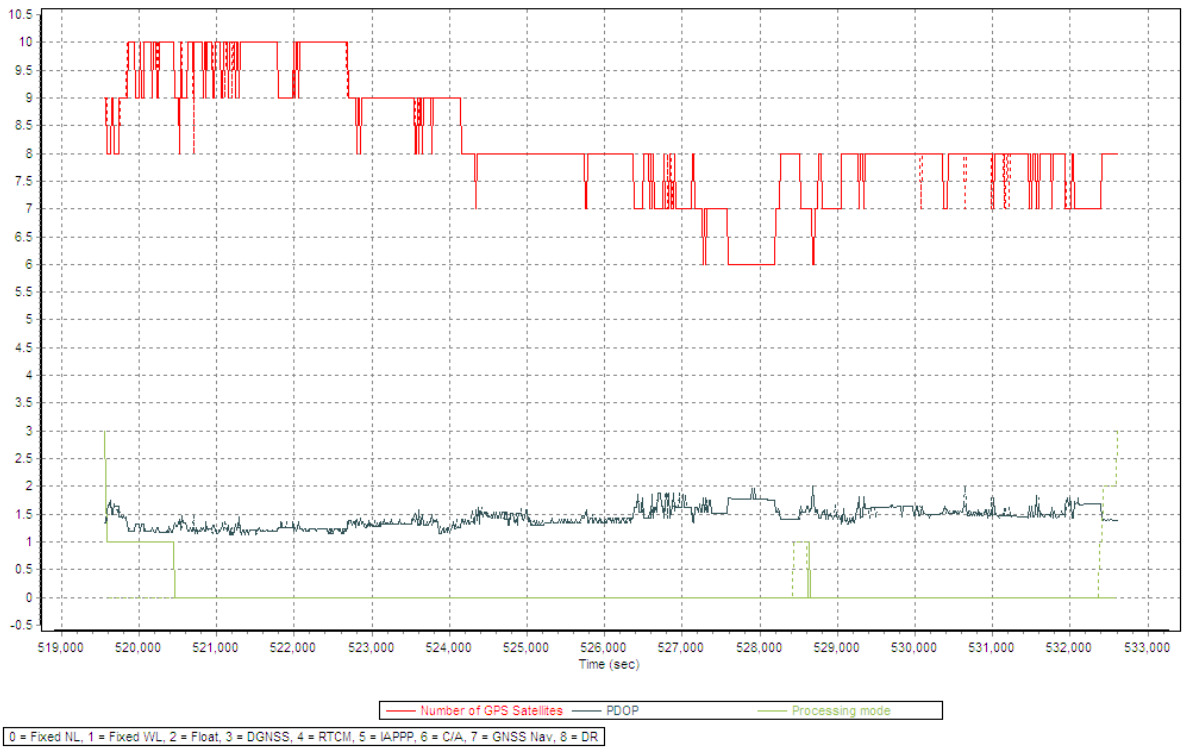


Figure A-8.22. Solution Status

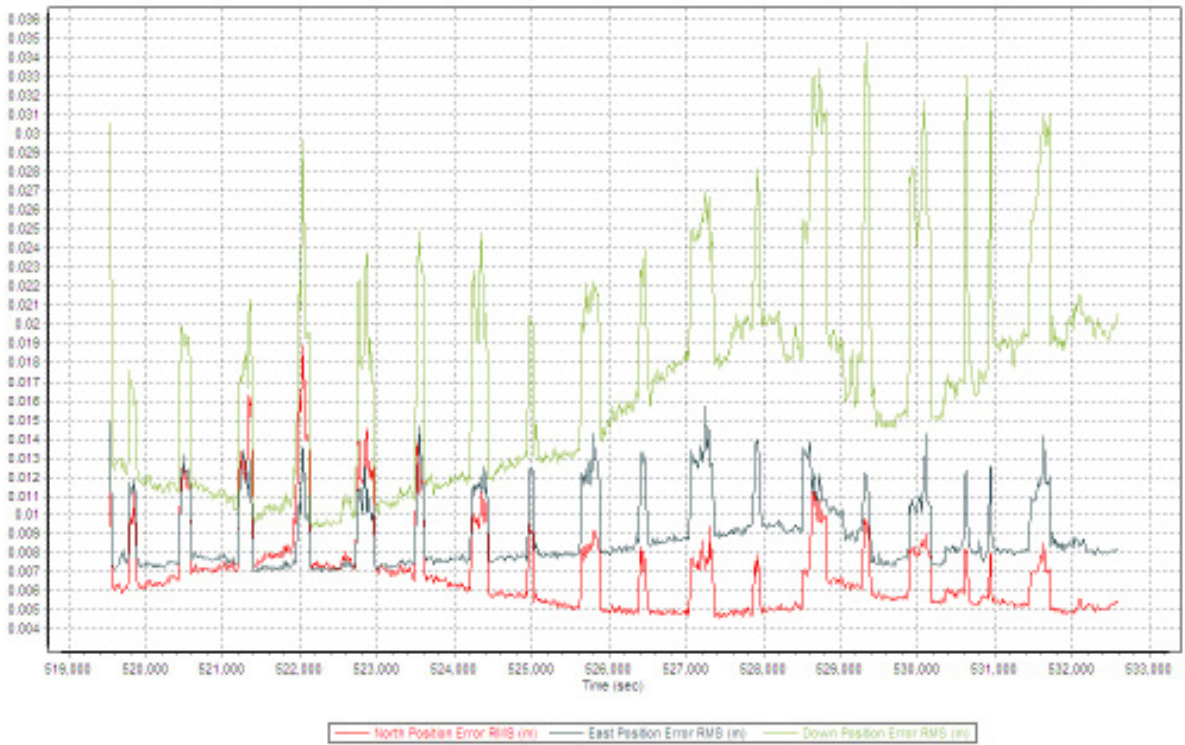


Figure A-8.23. Smoothed Performance Metrics Parameters

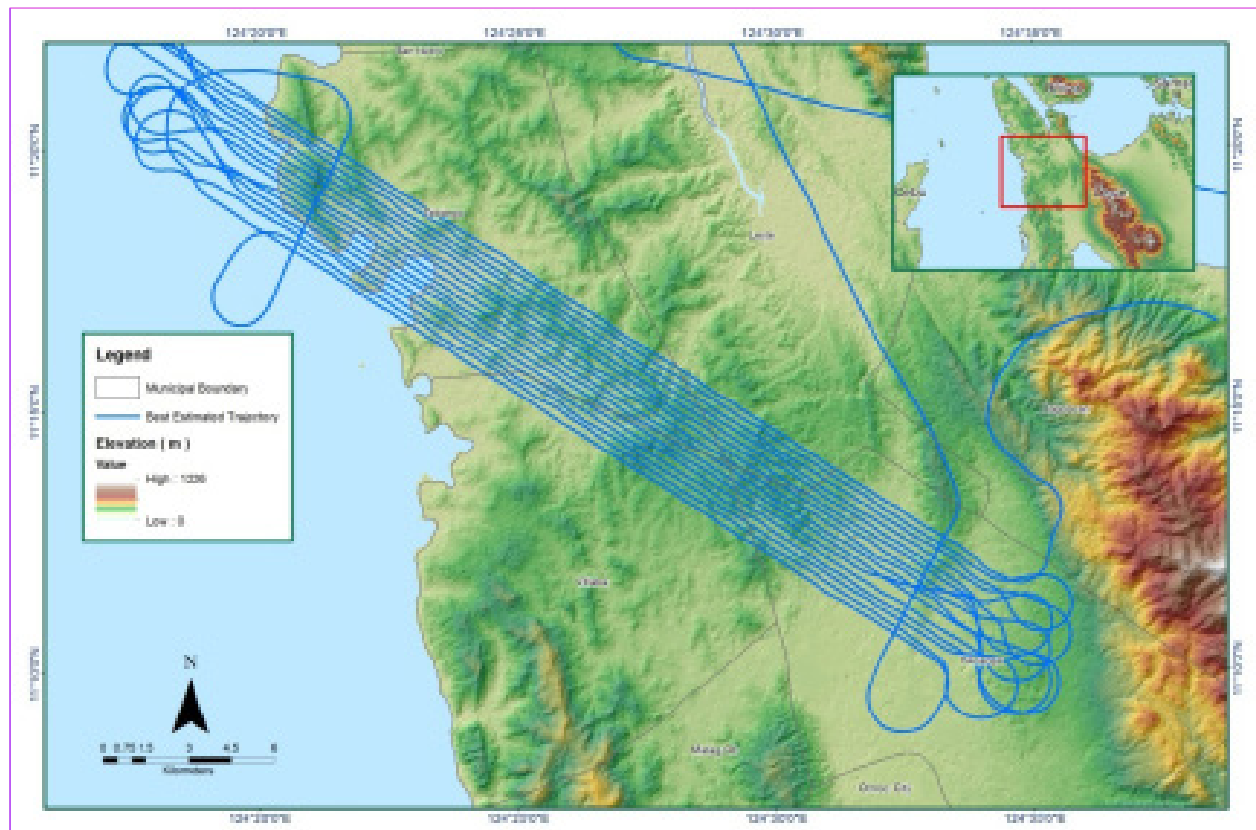


Figure A-8.24. Best Estimated Trajectory

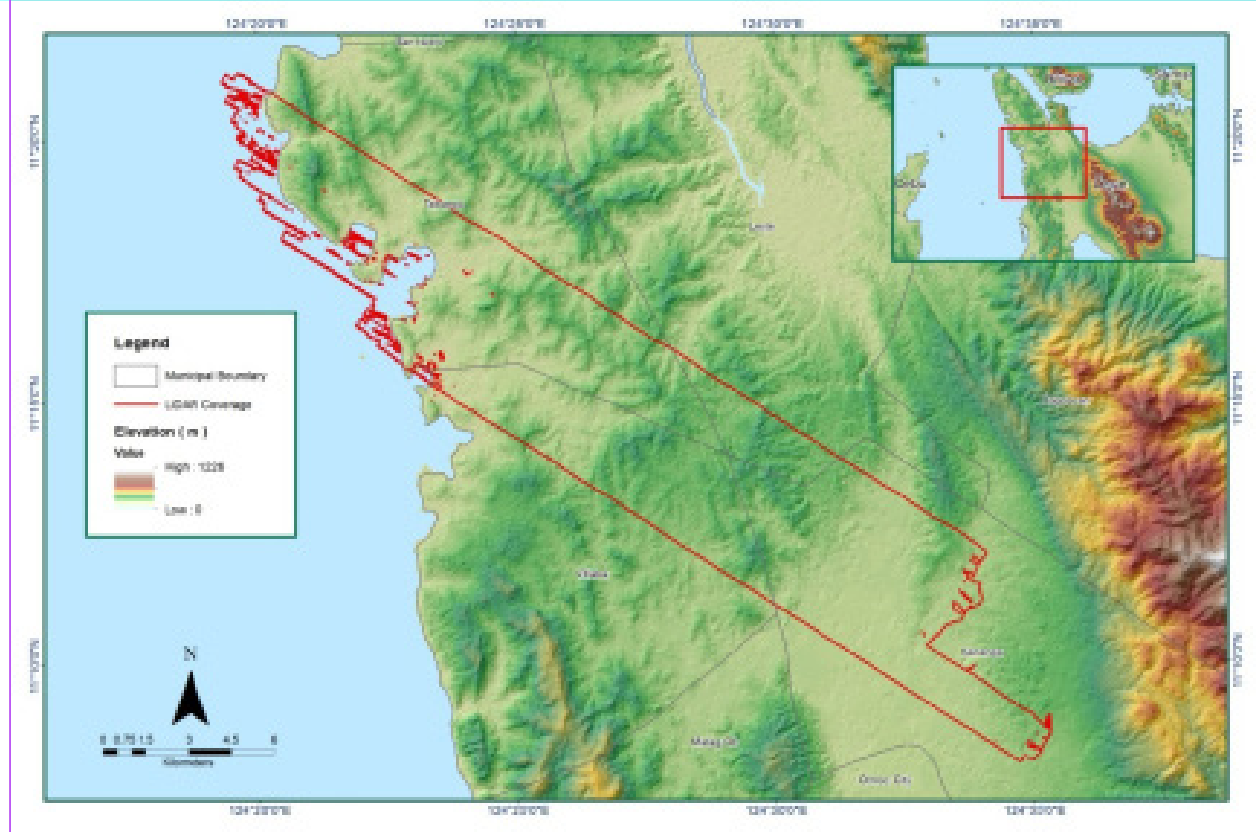


Figure A-8.25. Coverage of LiDAR data

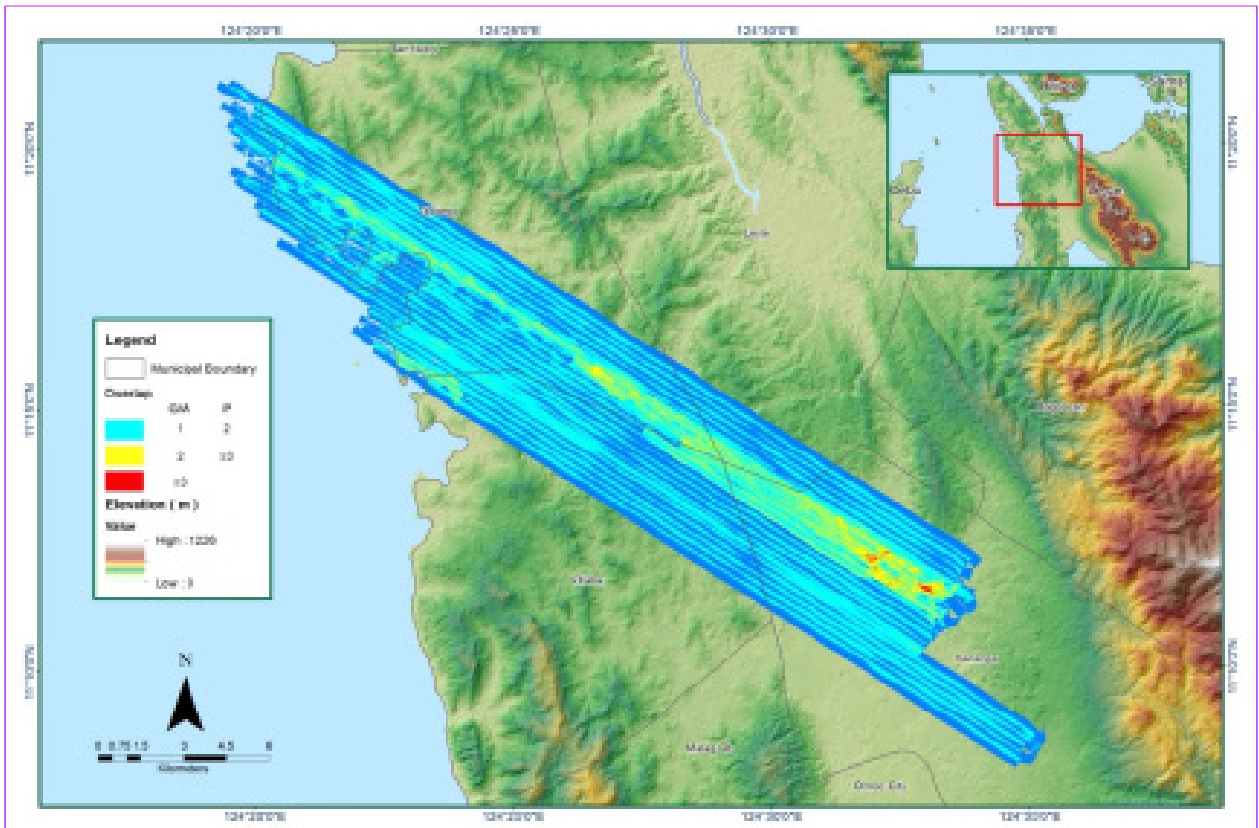


Figure A-8.26. Image of data overlap

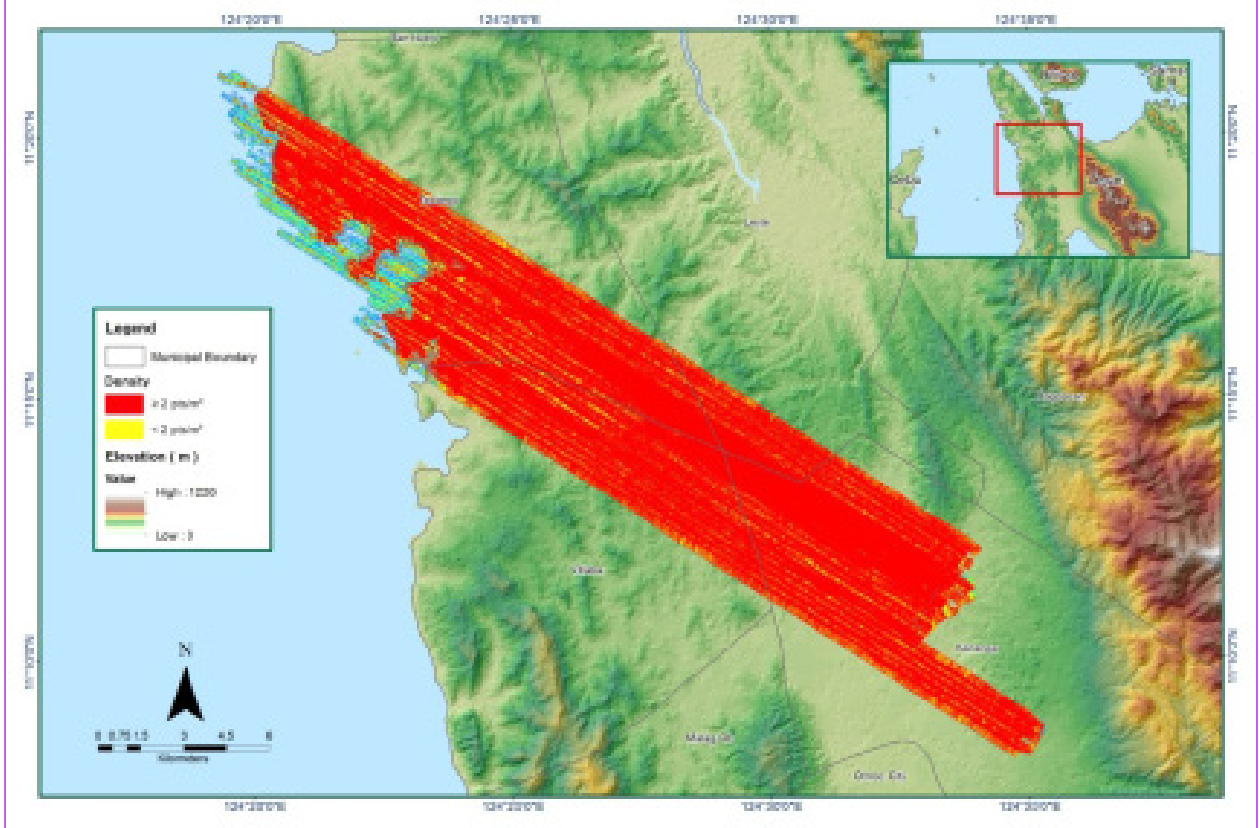


Figure A-8.27. Density map of merged LiDAR data

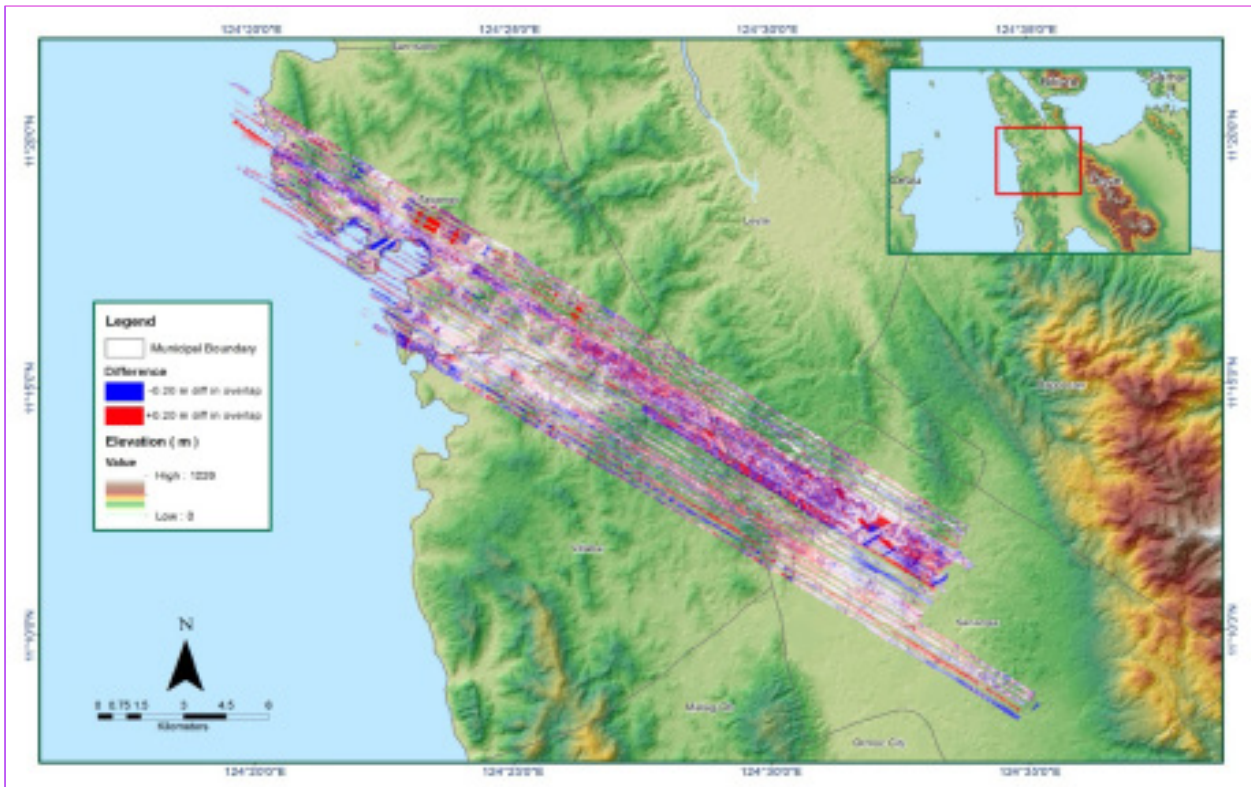


Figure A-8.28. Elevation difference between flight lines

Table A-8.5. Mission Summary Report for Mission Blk 35E

<b>Flight Area</b>	<b>Samar-Leyte</b>
<b>Mission Name</b>	Blk 35E
<b>Inclusive Flights</b>	1464A,1474A
<b>Range data size</b>	28 GB
<b>POS data size</b>	542 MB
<b>Base data size</b>	21.1 MB
<b>Image</b>	157.1 GB
<b>Transfer date</b>	May 28, 2014
<i>Solution Status</i>	
<b>Number of Satellites (&gt;6)</b>	Yes
<b>PDOP (&lt;3)</b>	Yes
<b>Baseline Length (&lt;30km)</b>	Yes
<b>Processing Mode (&lt;=1)</b>	No
<i>Smoothed Performance Metrics (in cm)</i>	
<b>RMSE for North Position (&lt;4.0 cm)</b>	1.4
<b>RMSE for East Position (&lt;4.0 cm)</b>	1.7
<b>RMSE for Down Position (&lt;8.0 cm)</b>	2.6
<b>Boresight correction stdev (&lt;0.001deg)</b>	0.000213
<b>IMU attitude correction stdev (&lt;0.001deg)</b>	0.001121
<b>GPS position stdev (&lt;0.01m)</b>	0.0095
<b>Minimum % overlap (&gt;25)</b>	46.83%
<b>Ave point cloud density per sq.m. (&gt;2.0)</b>	3.43
<b>Elevation difference between strips (&lt;0.20 m)</b>	Yes
<b>Number of 1km x 1km blocks</b>	163
<b>Maximum Height</b>	349.46 m
<b>Minimum Height</b>	51.38 m
<i>Classification (# of points)</i>	
<b>Ground</b>	79,052,774
<b>Low vegetation</b>	66,377,258
<b>Medium vegetation</b>	141,587,277
<b>High vegetation</b>	63,584,547
<b>Building</b>	638,371
<b>Orthophoto</b>	Yes
<b>Processed by</b>	Engr. Jommer Medina, Engr. Angelo Carlo Bongat, Engr. Melanie Hingpit, Engr. Gladys Mae Apat

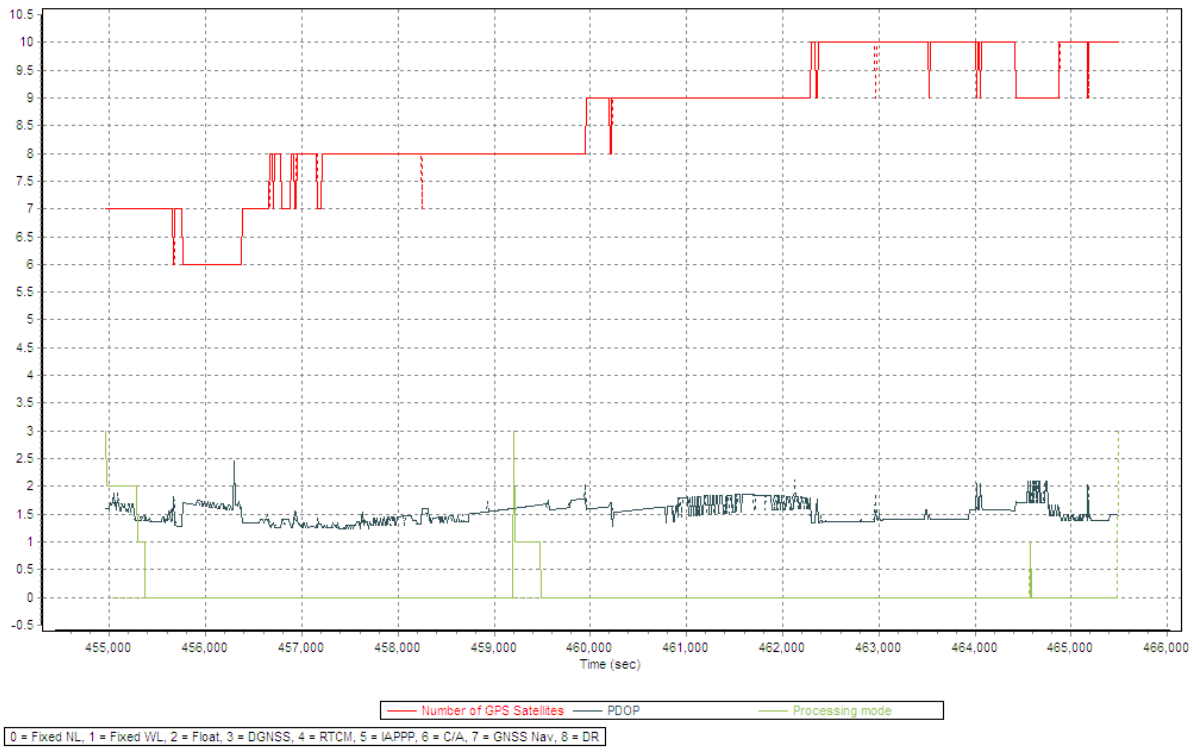


Figure A-8.29. Solution Status

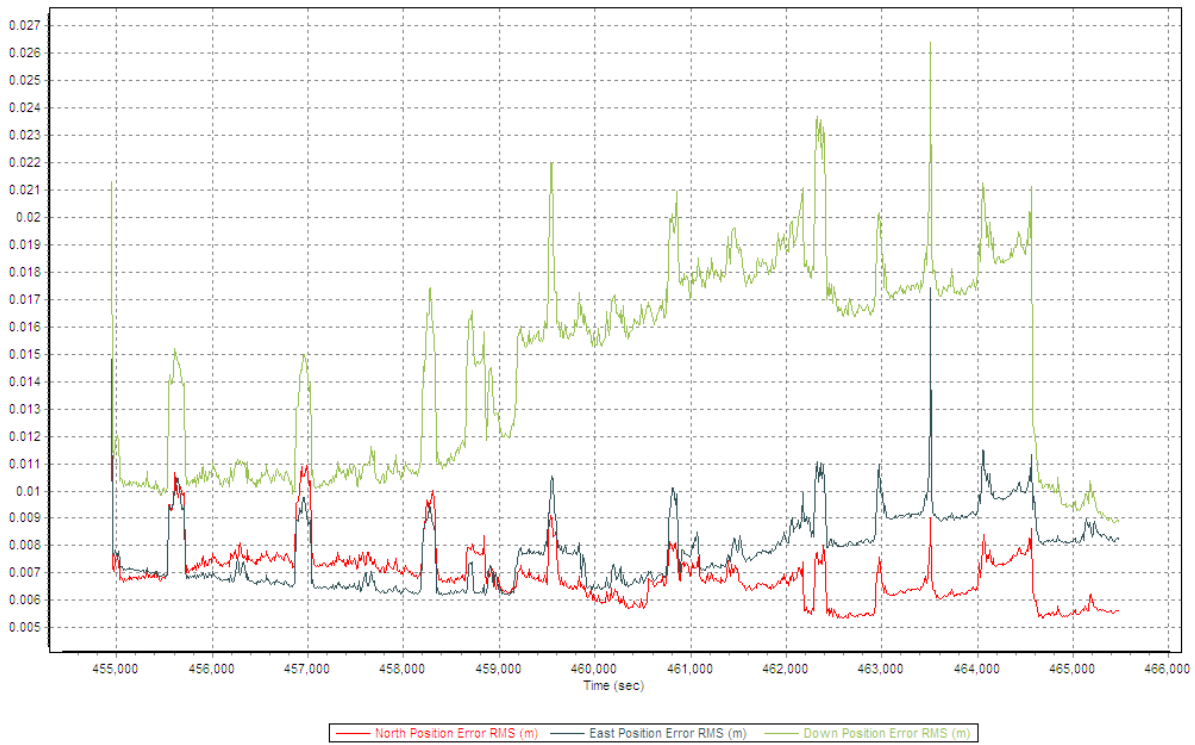


Figure A-8.30. Smoothed Performance Metrics Parameters

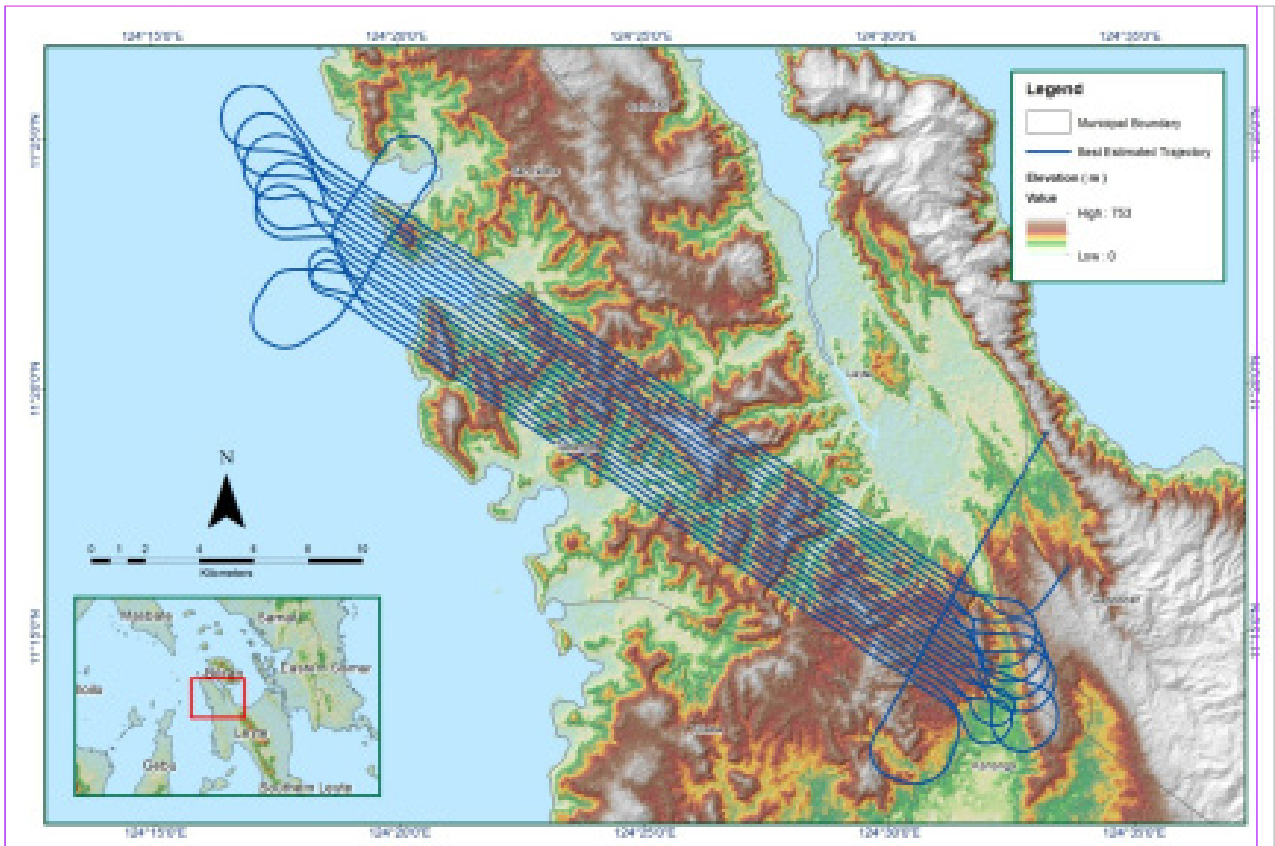


Figure A-8.31. Best Estimated Trajectory

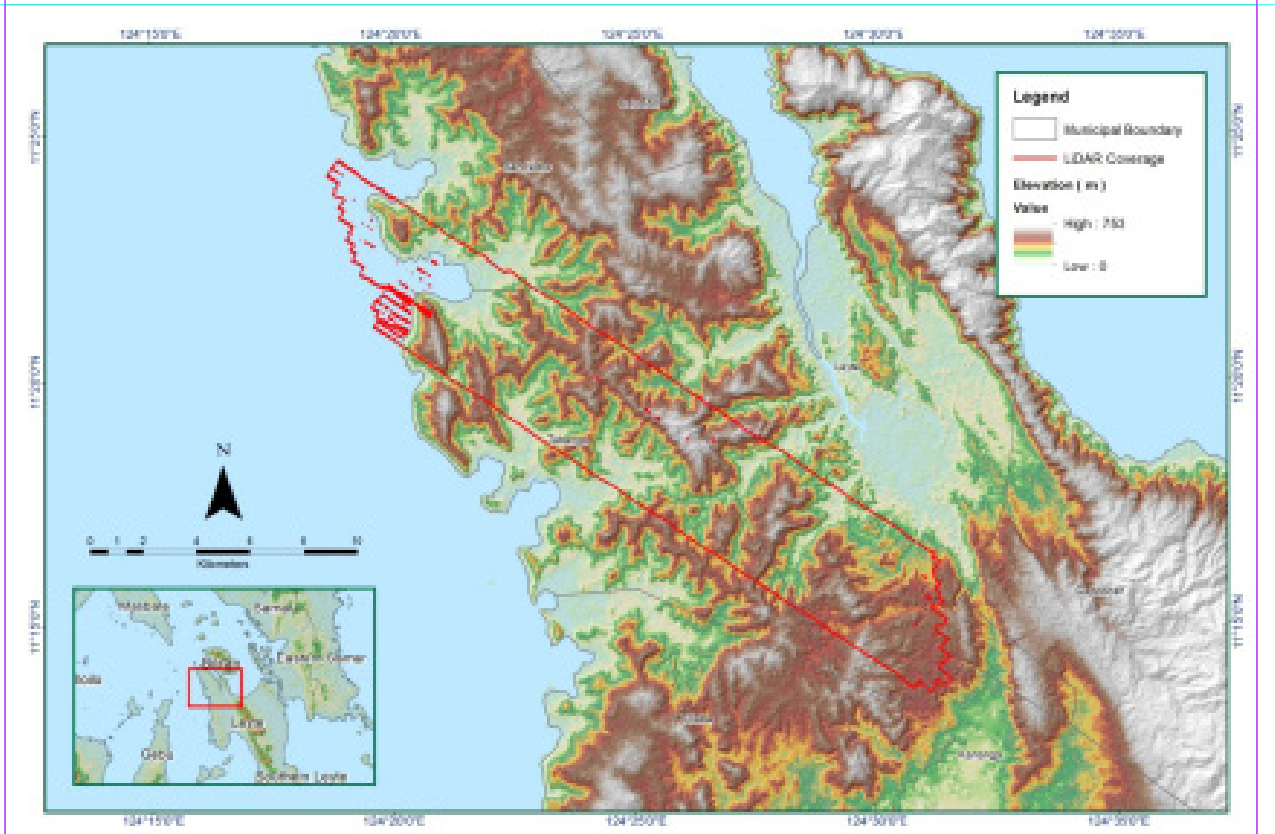


Figure A-8.32. Best Estimated Trajectory



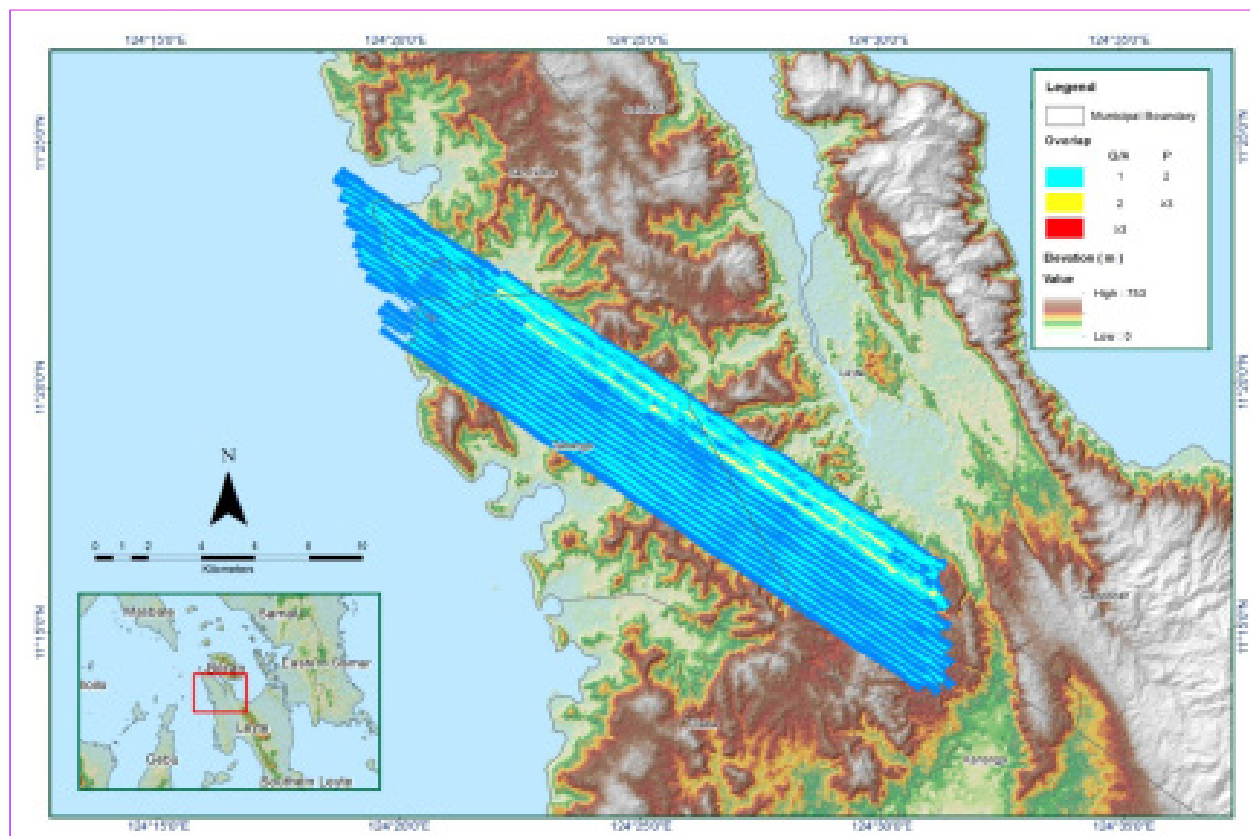


Figure A-8.33. Image of data overlap

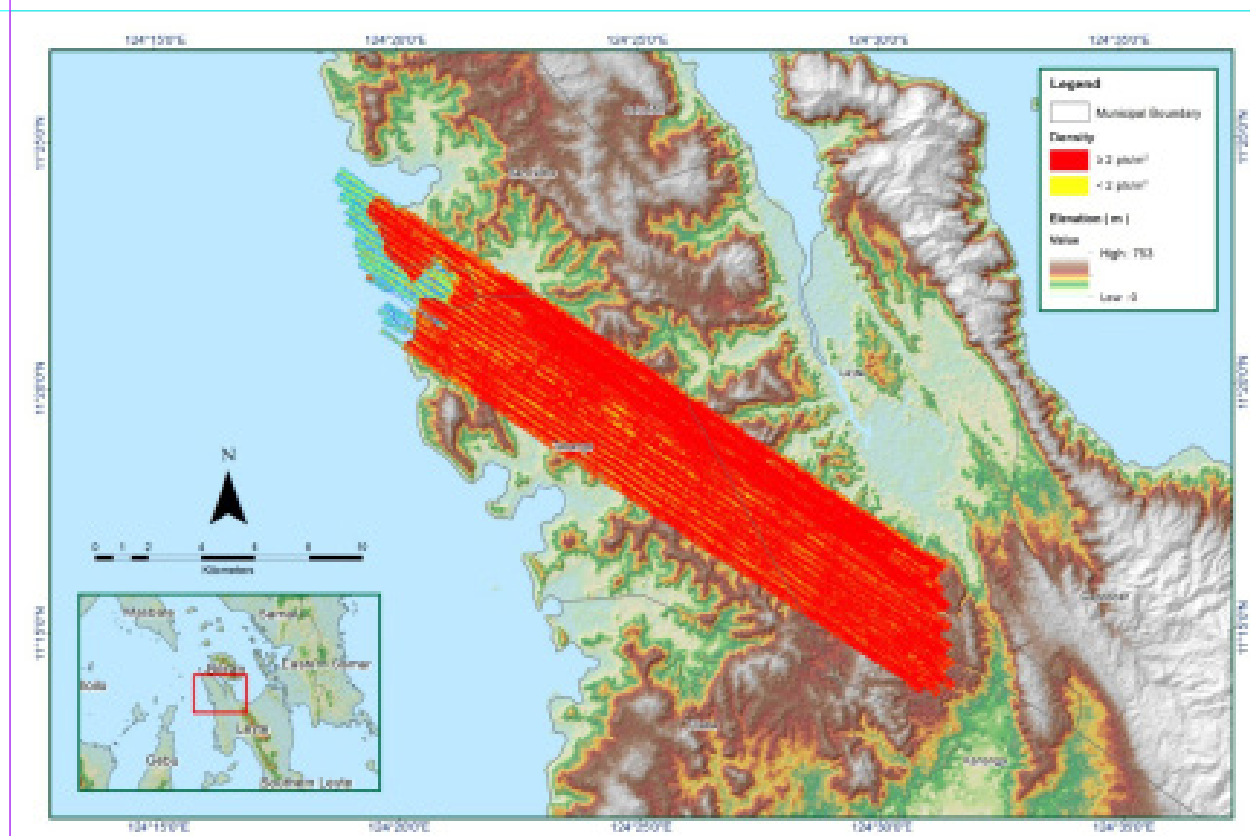


Figure A-8.34. Density map of merged LiDAR data

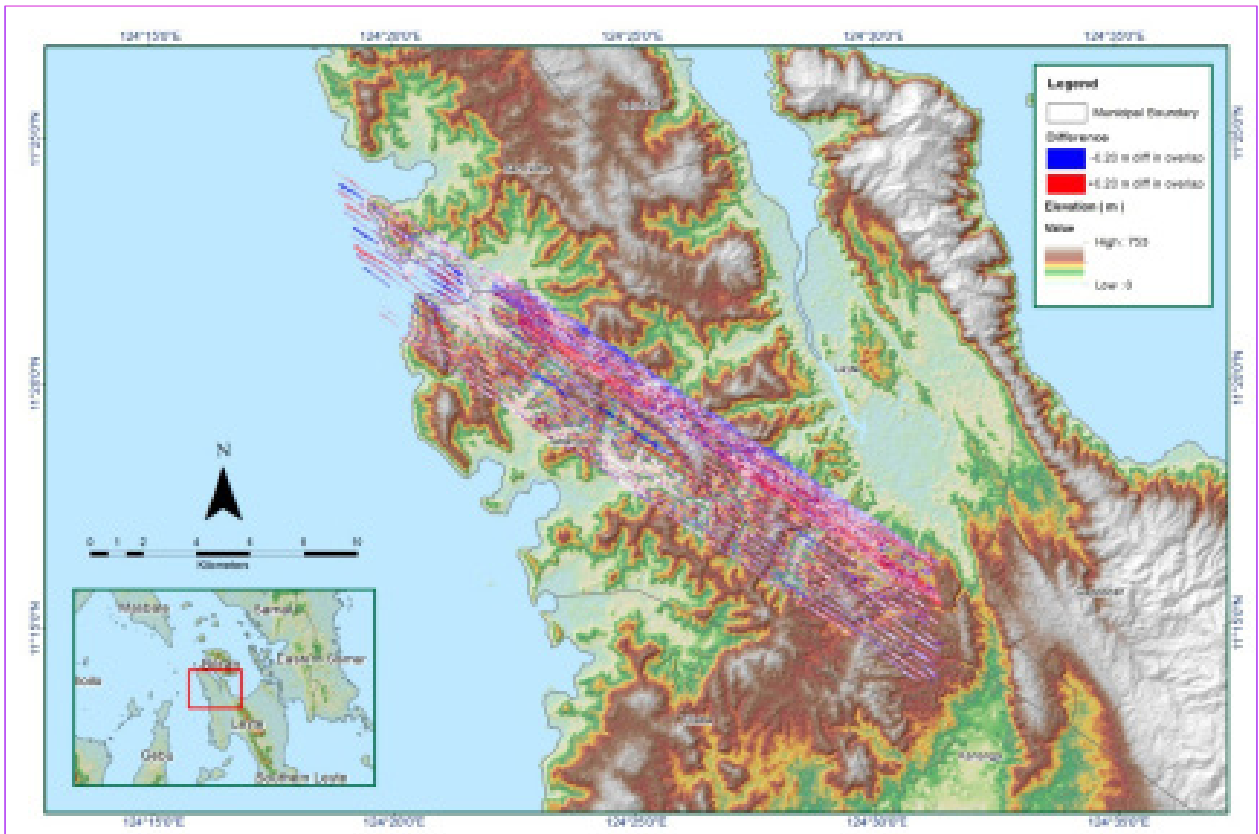


Figure A-8.35. Elevation difference between flight lines

Table A-8.6. Mission Summary Report for Mission Blk 35D

<b>Flight Area</b>	<b>Samar-Leyte</b>
<b>Mission Name</b>	Blk 35D
<b>Inclusive Flights</b>	1462A
<b>Range data size</b>	15.2 GB
<b>POS data size</b>	275 MB
<b>Base data size</b>	11.6 MB
<b>Image</b>	91.2 GB
<b>Transfer date</b>	May 28, 2014
<i>Solution Status</i>	
<b>Number of Satellites (&gt;6)</b>	No
<b>PDOP (&lt;3)</b>	Yes
<b>Baseline Length (&lt;30km)</b>	Yes
<b>Processing Mode (&lt;=1)</b>	Yes
<i>Smoothed Performance Metrics (in cm)</i>	
<b>RMSE for North Position (&lt;4.0 cm)</b>	1.4
<b>RMSE for East Position (&lt;4.0 cm)</b>	3.2
<b>RMSE for Down Position (&lt;8.0 cm)</b>	6.5
<b>Boresight correction stdev (&lt;0.001deg)</b>	0.000208
<b>IMU attitude correction stdev (&lt;0.001deg)</b>	0.000943
<b>GPS position stdev (&lt;0.01m)</b>	0.0082
<b>Minimum % overlap (&gt;25)</b>	43.84%
<b>Ave point cloud density per sq.m. (&gt;2.0)</b>	3.43
<b>Elevation difference between strips (&lt;0.20 m)</b>	Yes
<b>Number of 1km x 1km blocks</b>	169
<b>Maximum Height</b>	302.81 m
<b>Minimum Height</b>	52.60 m
<i>Classification (# of points)</i>	
<b>Ground</b>	53,485,834
<b>Low vegetation</b>	77,120,403
<b>Medium vegetation</b>	115,497,563
<b>High vegetation</b>	68,908,955
<b>Building</b>	1,177,955
<b>Orthophoto</b>	Yes
<b>Processed by</b>	Engr. Jommer Medina, Engr. Chelou Prado, Engr. Gladys Mae Apat

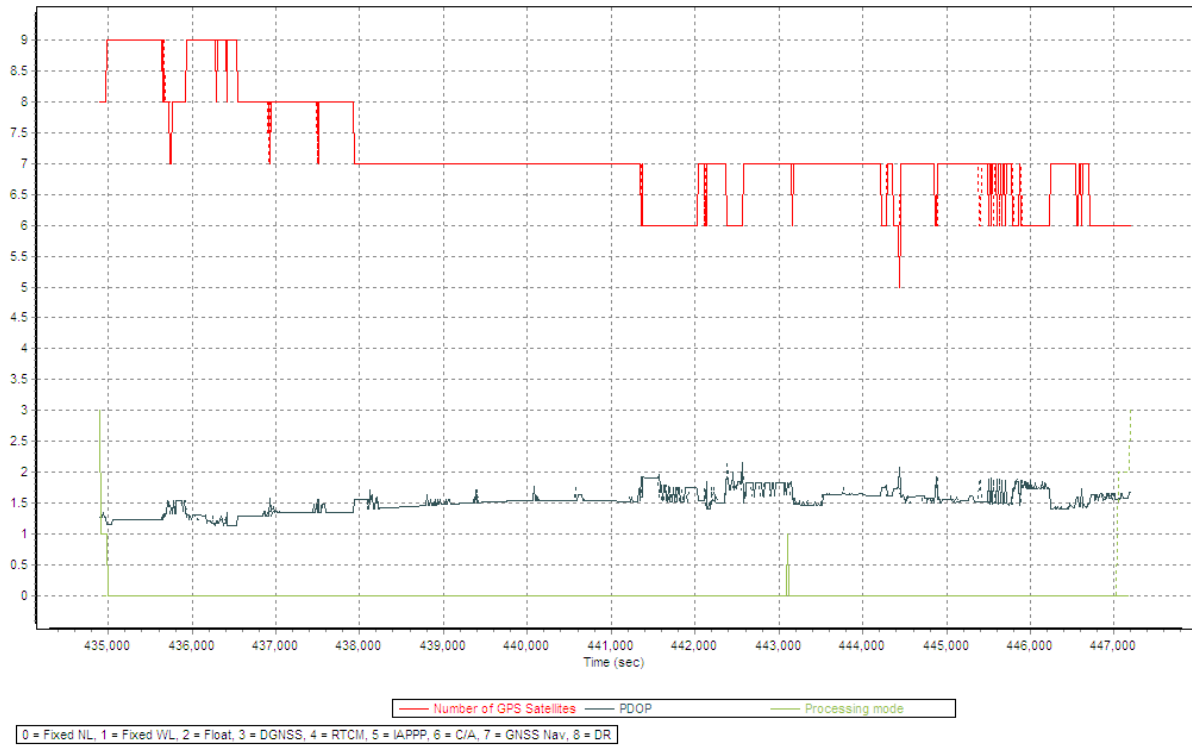


Figure A-8.36. Solution Status

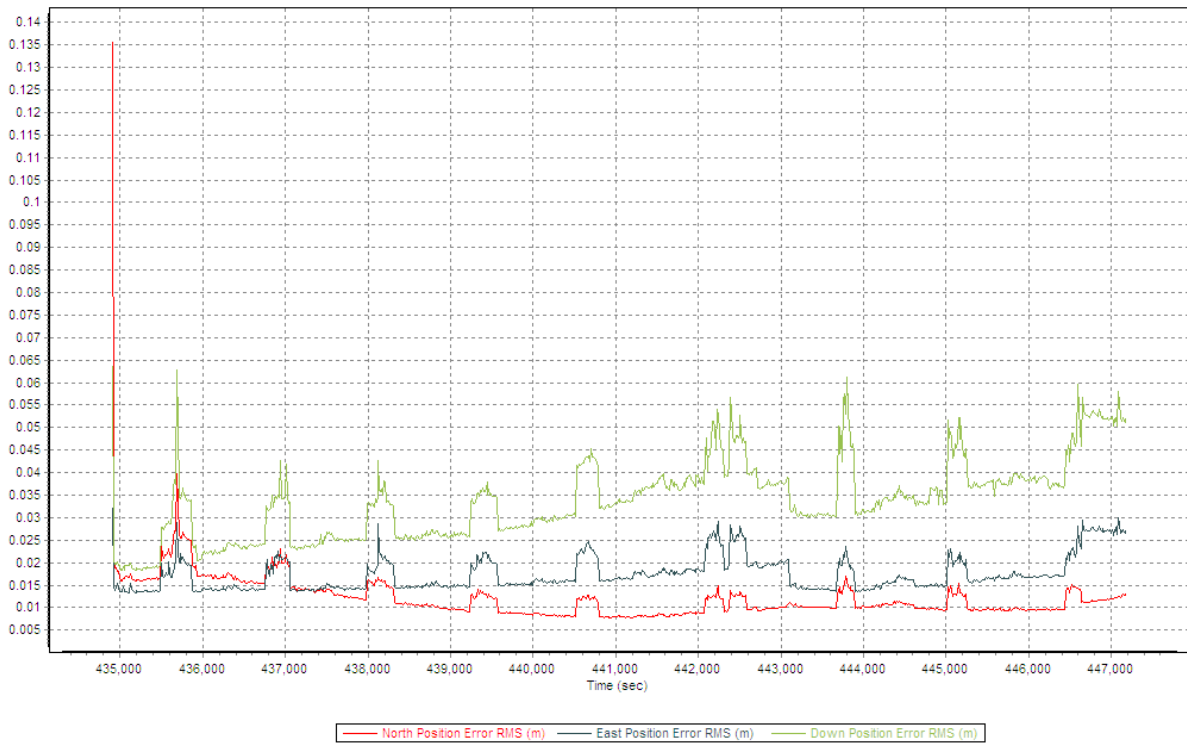


Figure A-8.37. Smoothed Performance Metrics Parameters

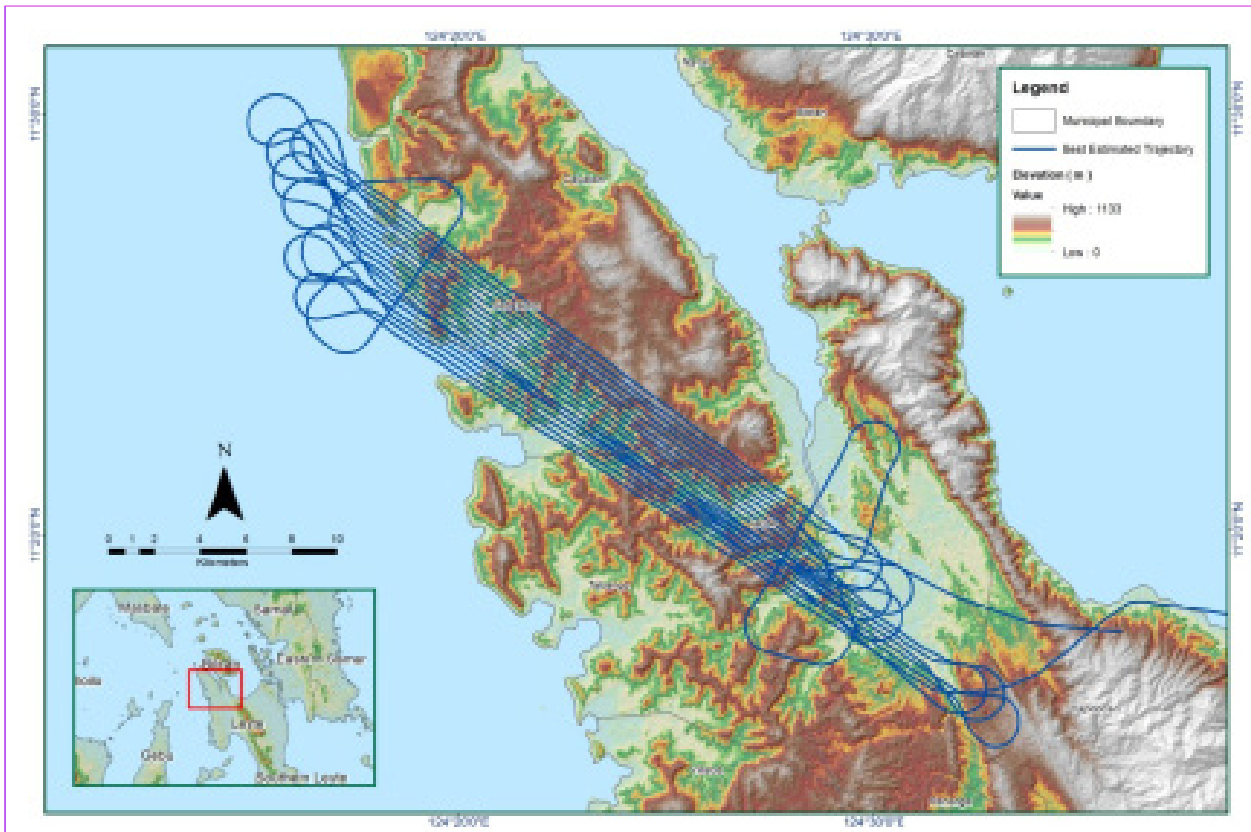


Figure A-8.38. Best Estimated Trajectory

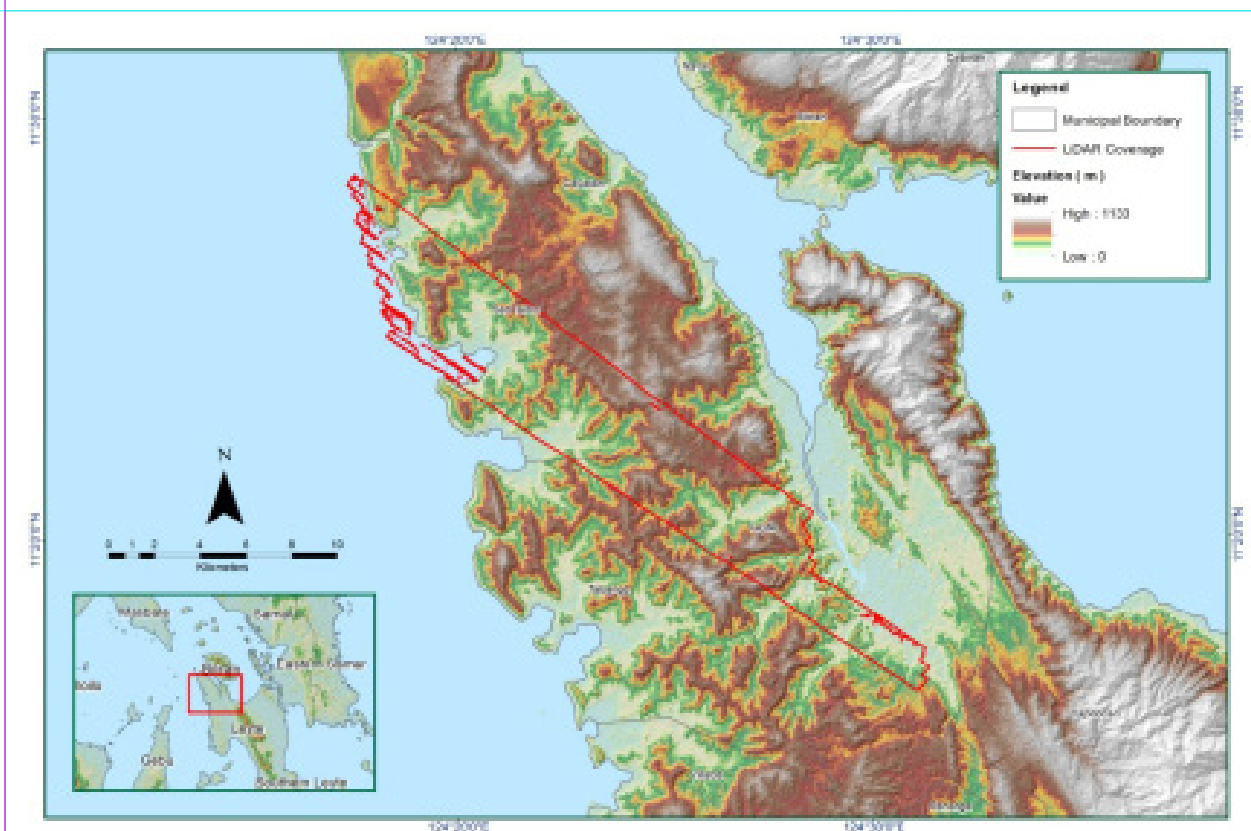


Figure A-8.39. Coverage of LiDAR data

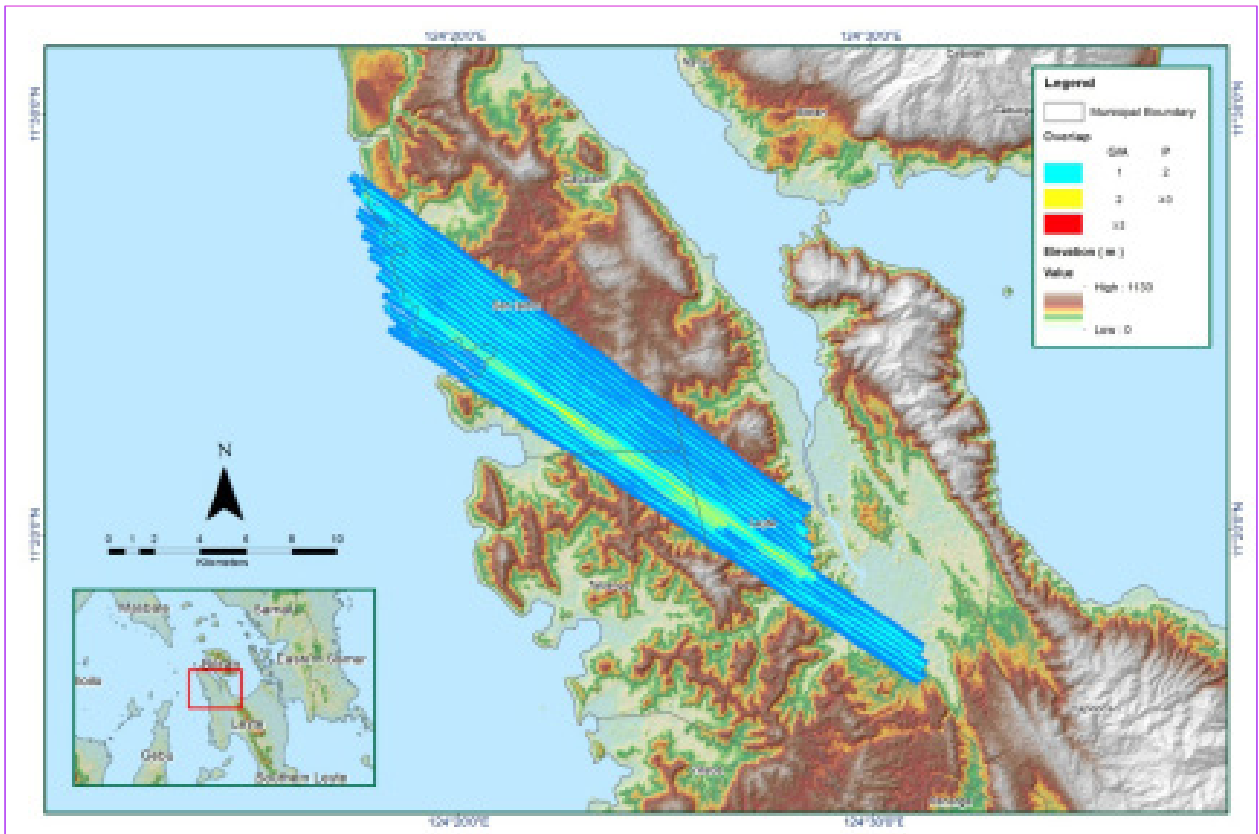


Figure A-8.40. Image of data overlap

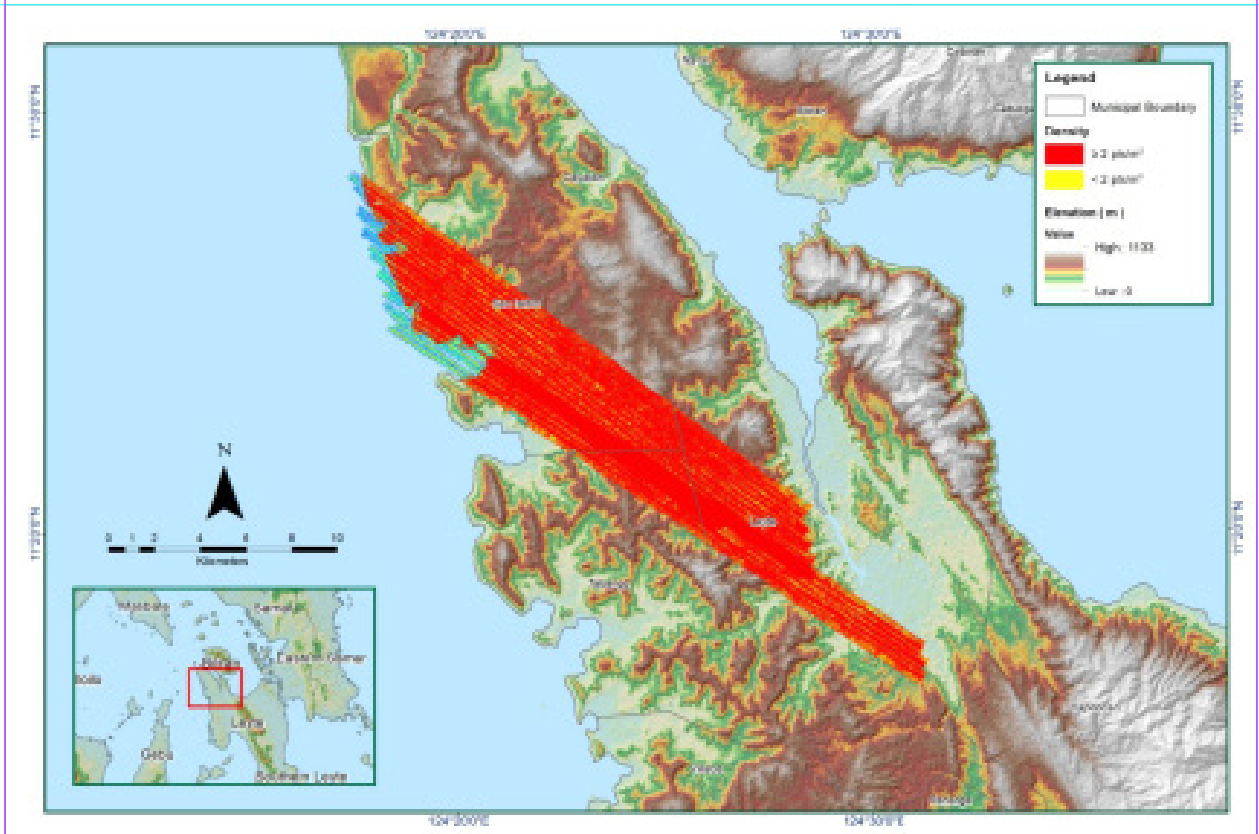


Figure A-8.41. Density map of merged LiDAR data

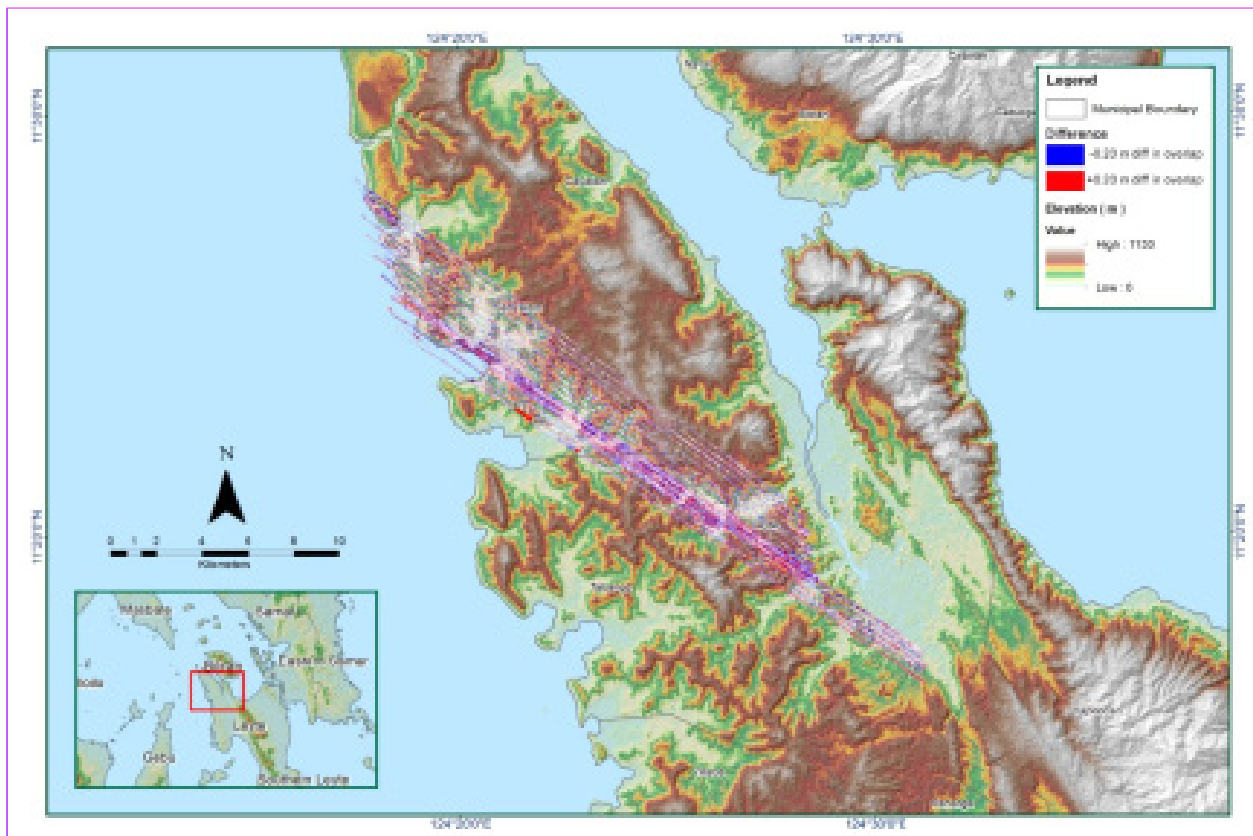


Figure A-8.42. Elevation difference between flight lines

Table A-8.7. Mission Summary Report for Mission Blk 35C

<b>Flight Area</b>	<b>Samar-Leyte</b>
<b>Mission Name</b>	Blk 35C
<b>Inclusive Flights</b>	1460A,1474A
<b>Range data size</b>	28.1 GB
<b>POS data size</b>	564 MB
<b>Base data size</b>	21.1 MB
<b>Image</b>	155 GB
<b>Transfer date</b>	May 28, 2014
<i>Solution Status</i>	
<b>Number of Satellites (&gt;6)</b>	Yes
<b>PDOP (&lt;3)</b>	No
<b>Baseline Length (&lt;30km)</b>	No
<b>Processing Mode (&lt;=1)</b>	Yes
<i>Smoothed Performance Metrics (in cm)</i>	
<b>RMSE for North Position (&lt;4.0 cm)</b>	1.5
<b>RMSE for East Position (&lt;4.0 cm)</b>	1.7
<b>RMSE for Down Position (&lt;8.0 cm)</b>	3.1
<b>Boresight correction stdev (&lt;0.001deg)</b>	0.000328
<b>IMU attitude correction stdev (&lt;0.001deg)</b>	0.002158
<b>GPS position stdev (&lt;0.01m)</b>	0.0033
<b>Minimum % overlap (&gt;25)</b>	44.94%
<b>Ave point cloud density per sq.m. (&gt;2.0)</b>	3.84
<b>Elevation difference between strips (&lt;0.20 m)</b>	Yes
<b>Number of 1km x 1km blocks</b>	174
<b>Maximum Height</b>	387.55 m
<b>Minimum Height</b>	50.52 m
<i>Classification (# of points)</i>	
<b>Ground</b>	96,313,140
<b>Low vegetation</b>	89,828,817
<b>Medium vegetation</b>	138,400,766
<b>High vegetation</b>	97,602,353
<b>Building</b>	1,270,216
<b>Orthophoto</b>	Yes
<b>Processed by</b>	Engr. Angelo Carlo Bongat, Engr. Chelou Prado, Engr. Gladys Mae Apat



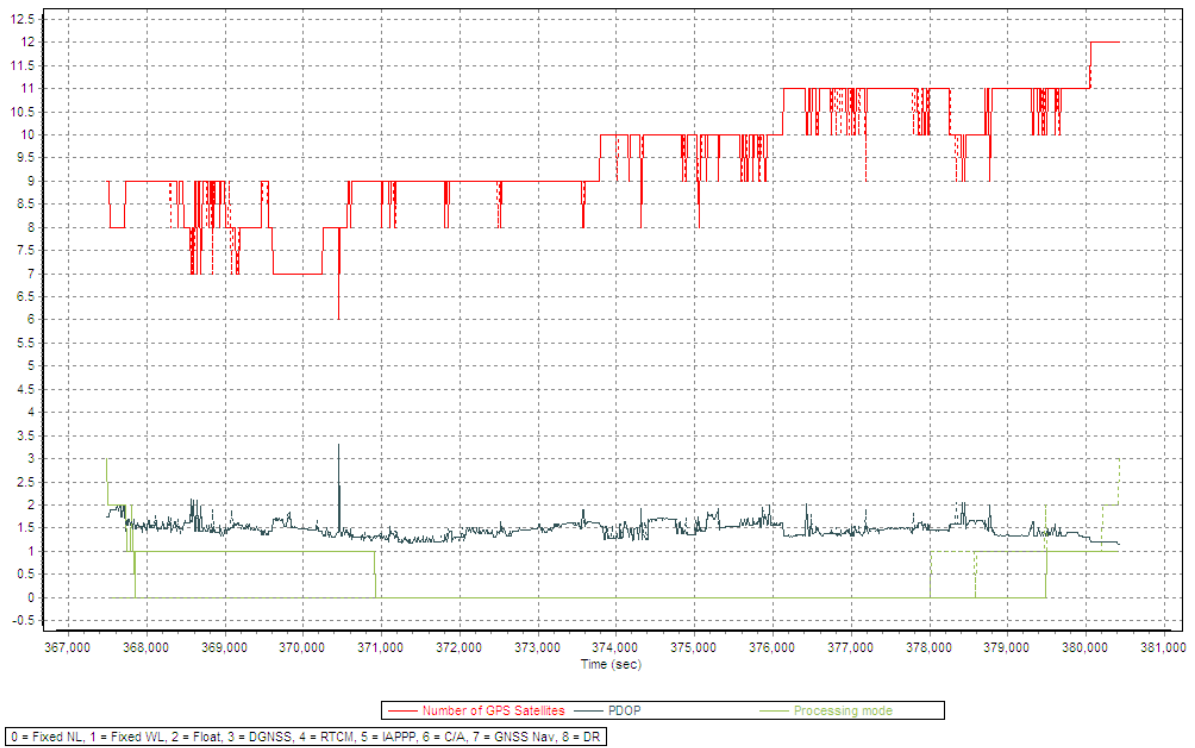


Figure A-8.43. Solution Status

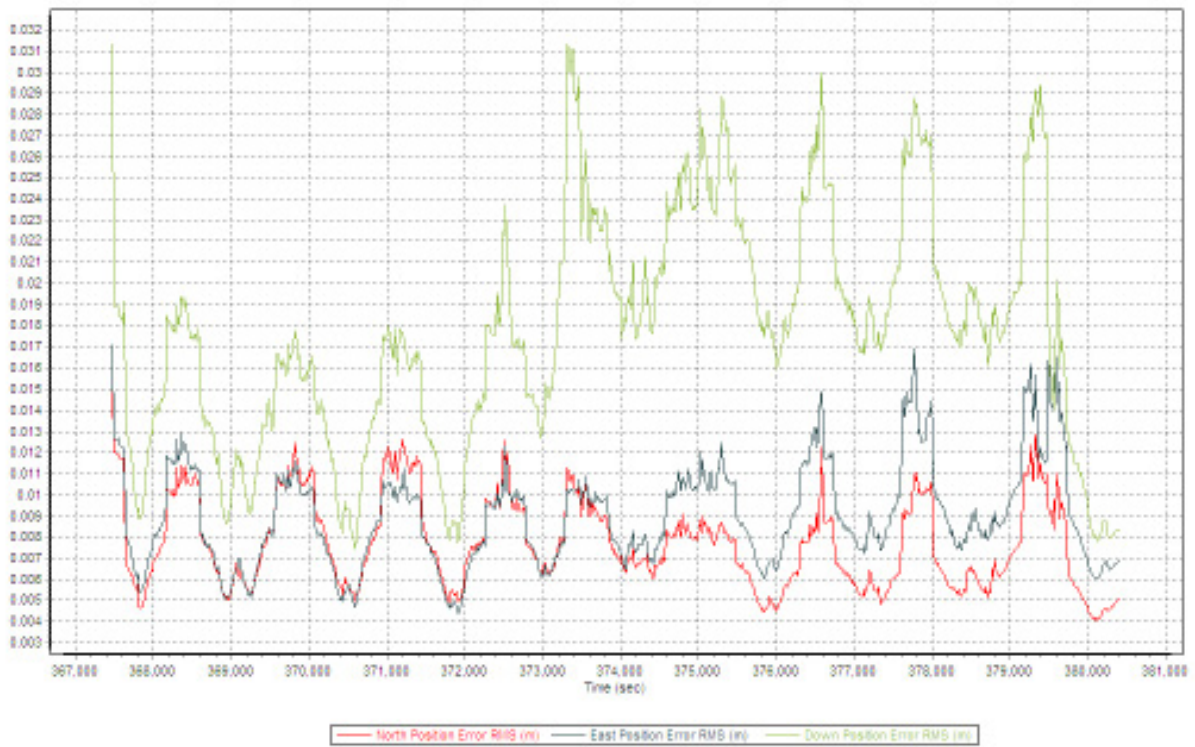


Figure A-8.44. Smoothed Performance Metrics Parameters

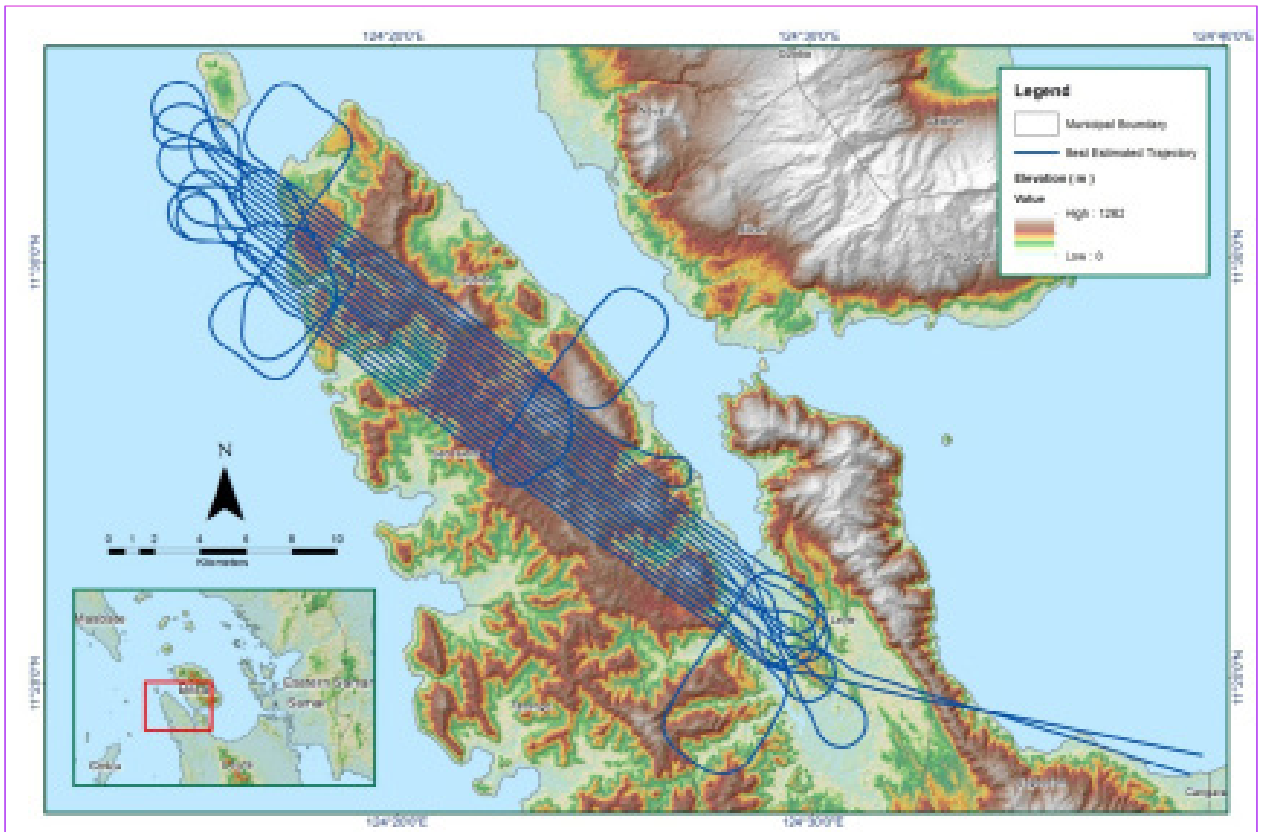


Figure A-8.45. Best Estimated Trajectory

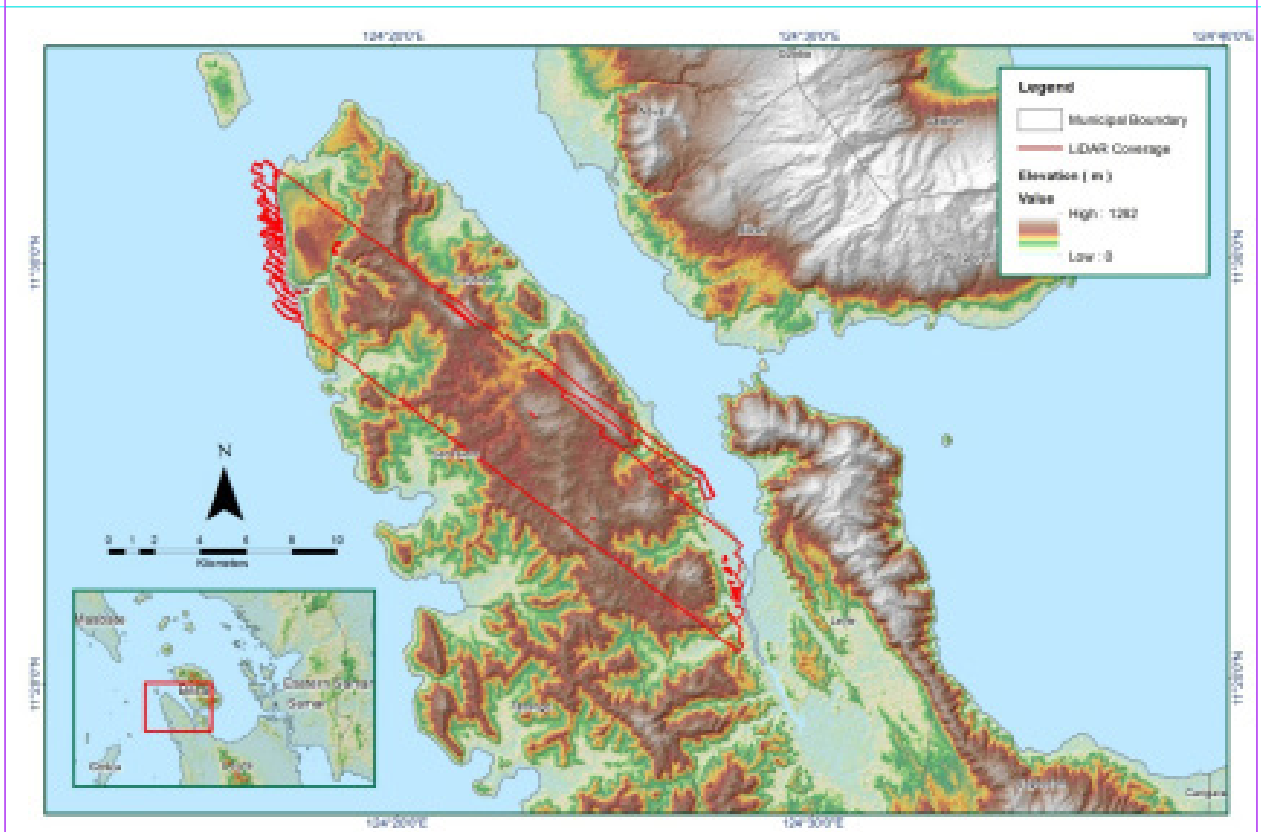


Figure A-8.46. Best Estimated Trajectory

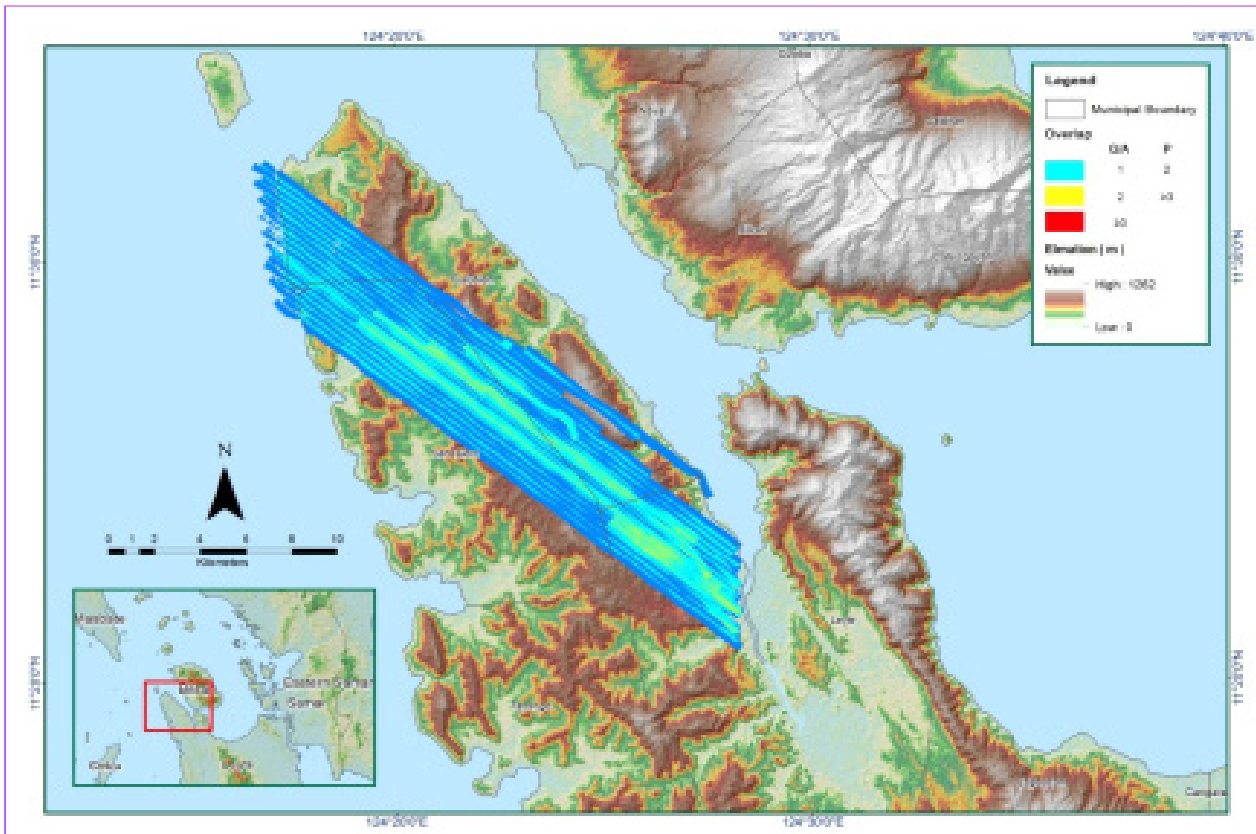


Figure A-8.47. Image of data overlap

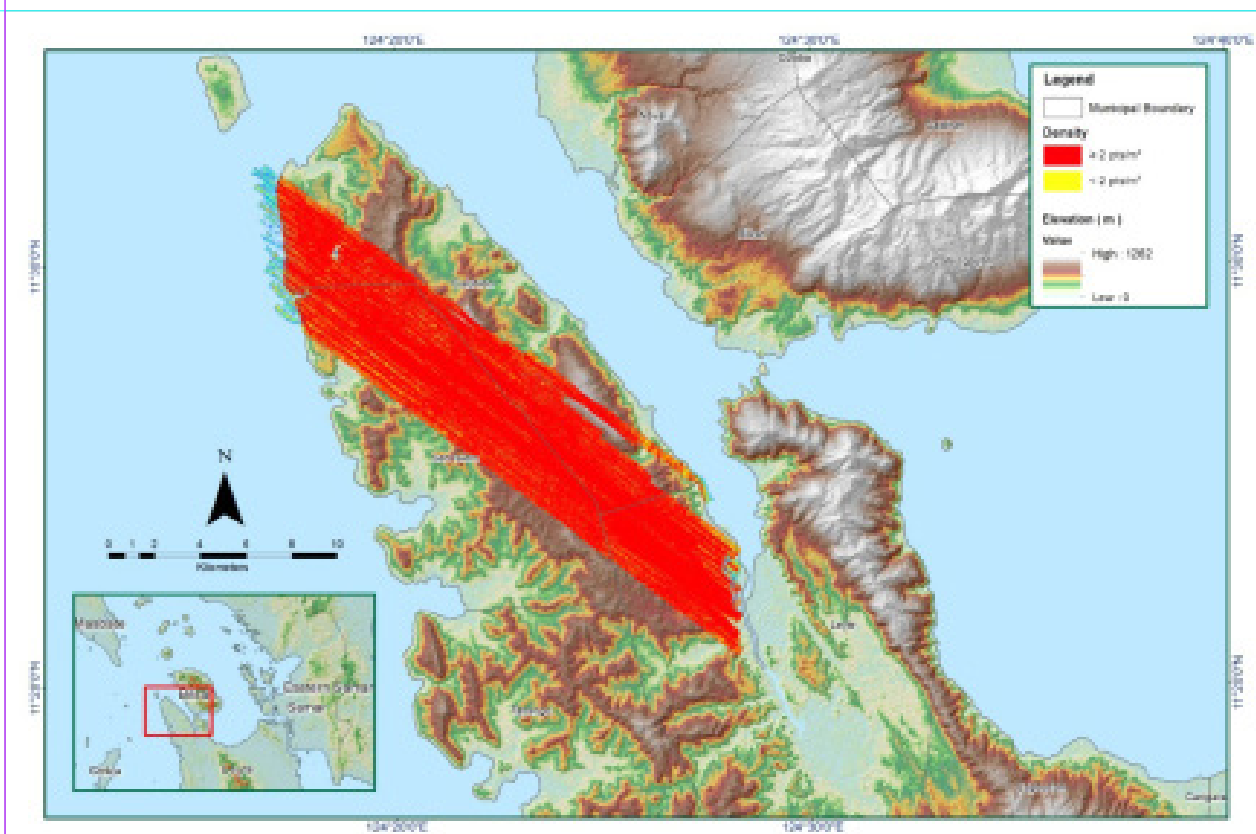


Figure A-8.48. Density map of merged LiDAR data

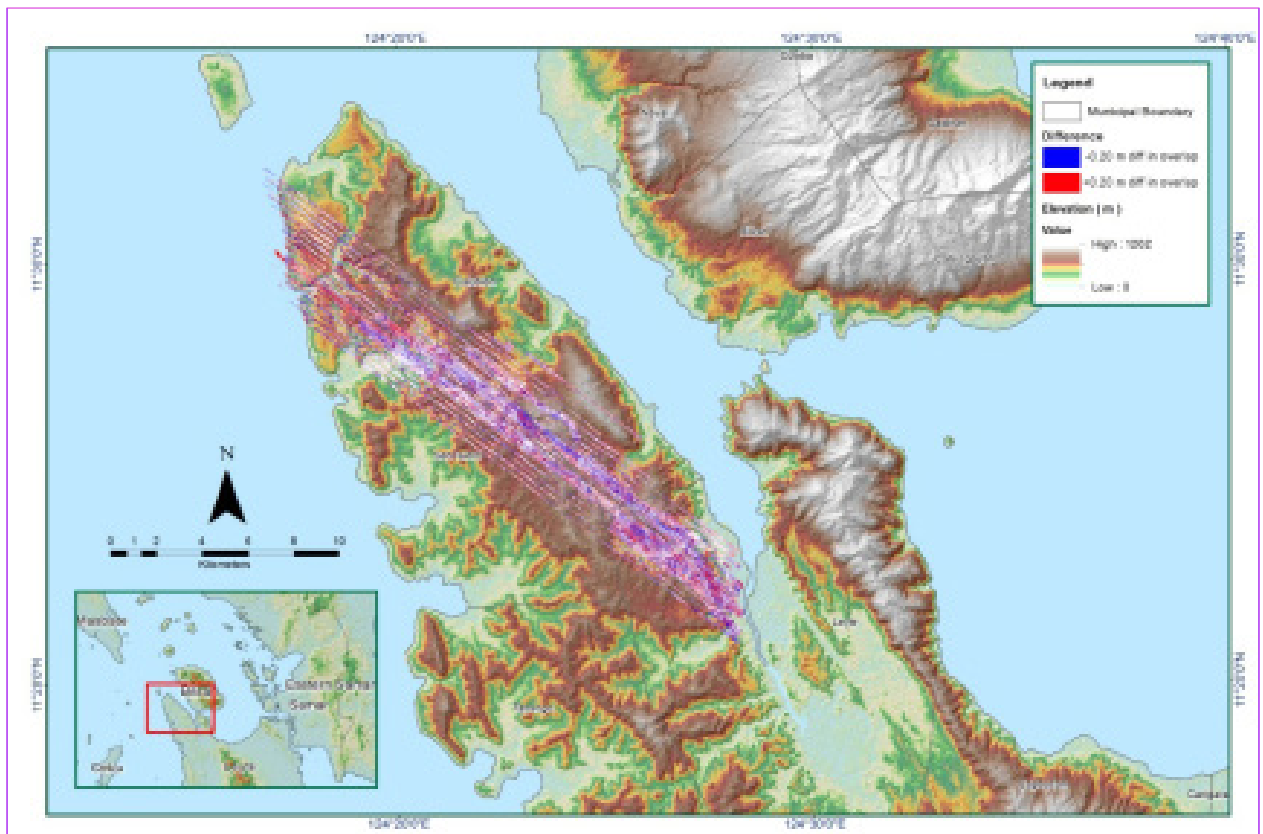


Figure A-8.49. Elevation difference between flight lines

Table A-8.8. Mission Summary Report for Mission Blk 35B

<b>Flight Area</b>	<b>Samar-Leyte</b>
<b>Mission Name</b>	Blk 35B
<b>Inclusive Flights</b>	1458A
<b>Range data size</b>	13.3 GB
<b>POS data size</b>	277 MB
<b>Base data size</b>	14.6 MB
<b>Image</b>	81.7 GB
<b>Transfer date</b>	June 10, 2014
<i>Solution Status</i>	
<b>Number of Satellites (&gt;6)</b>	Yes
<b>PDOP (&lt;3)</b>	Yes
<b>Baseline Length (&lt;30km)</b>	No
<b>Processing Mode (&lt;=1)</b>	Yes
<i>Smoothed Performance Metrics (in cm)</i>	
<b>RMSE for North Position (&lt;4.0 cm)</b>	1.6
<b>RMSE for East Position (&lt;4.0 cm)</b>	1.6
<b>RMSE for Down Position (&lt;8.0 cm)</b>	3.4
<b>Boresight correction stdev (&lt;0.001deg)</b>	0.000294
<b>IMU attitude correction stdev (&lt;0.001deg)</b>	0.006535
<b>GPS position stdev (&lt;0.01m)</b>	0.0036
<b>Minimum % overlap (&gt;25)</b>	33.13%
<b>Ave point cloud density per sq.m. (&gt;2.0)</b>	2.90
<b>Elevation difference between strips (&lt;0.20 m)</b>	Yes
<b>Number of 1km x 1km blocks</b>	147
<b>Maximum Height</b>	387.51 m
<b>Minimum Height</b>	51.24 m
<i>Classification (# of points)</i>	
<b>Ground</b>	94,275,309
<b>Low vegetation</b>	78,485,696
<b>Medium vegetation</b>	117,061,039
<b>High vegetation</b>	90,631,637
<b>Building</b>	2,390,506
<b>Orthophoto</b>	Yes
<b>Processed by</b>	Engr. Angelo Carlo Bongat, Engr. Chelou Prado, Engr. Gladys Mae Apat

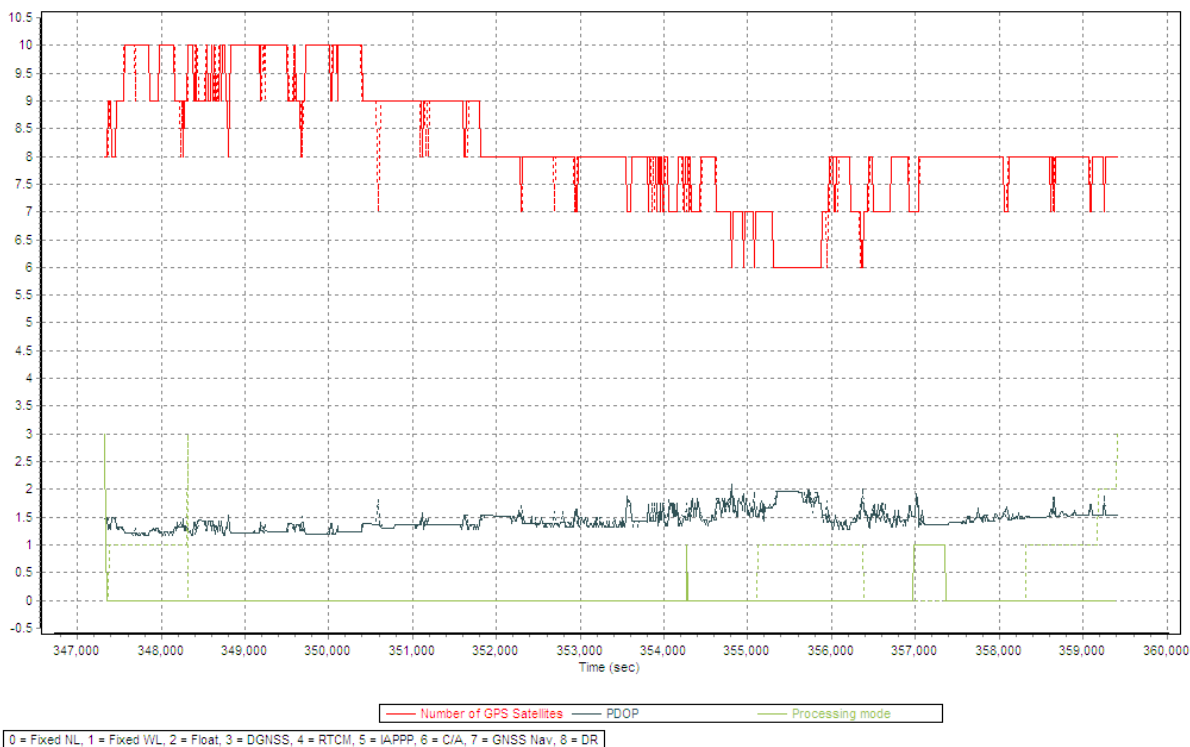


Figure A-8.50. Solution Status

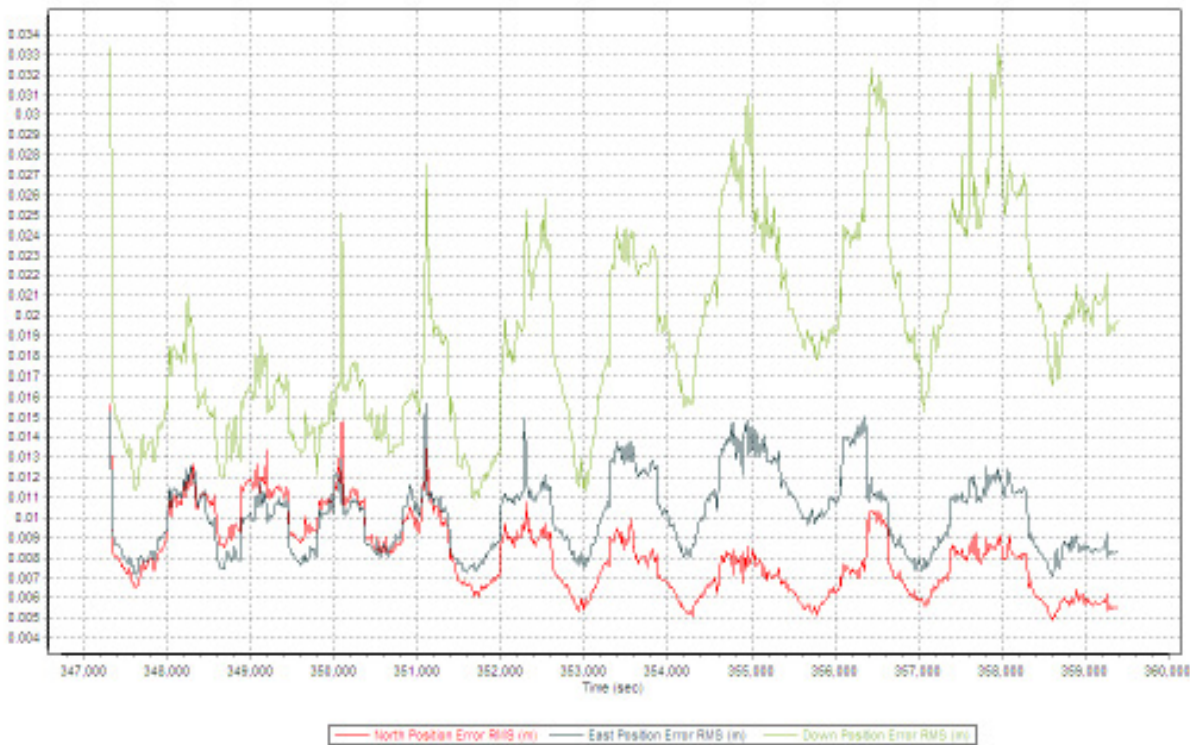


Figure A-8.51. Smoothed Performance Metrics Parameters

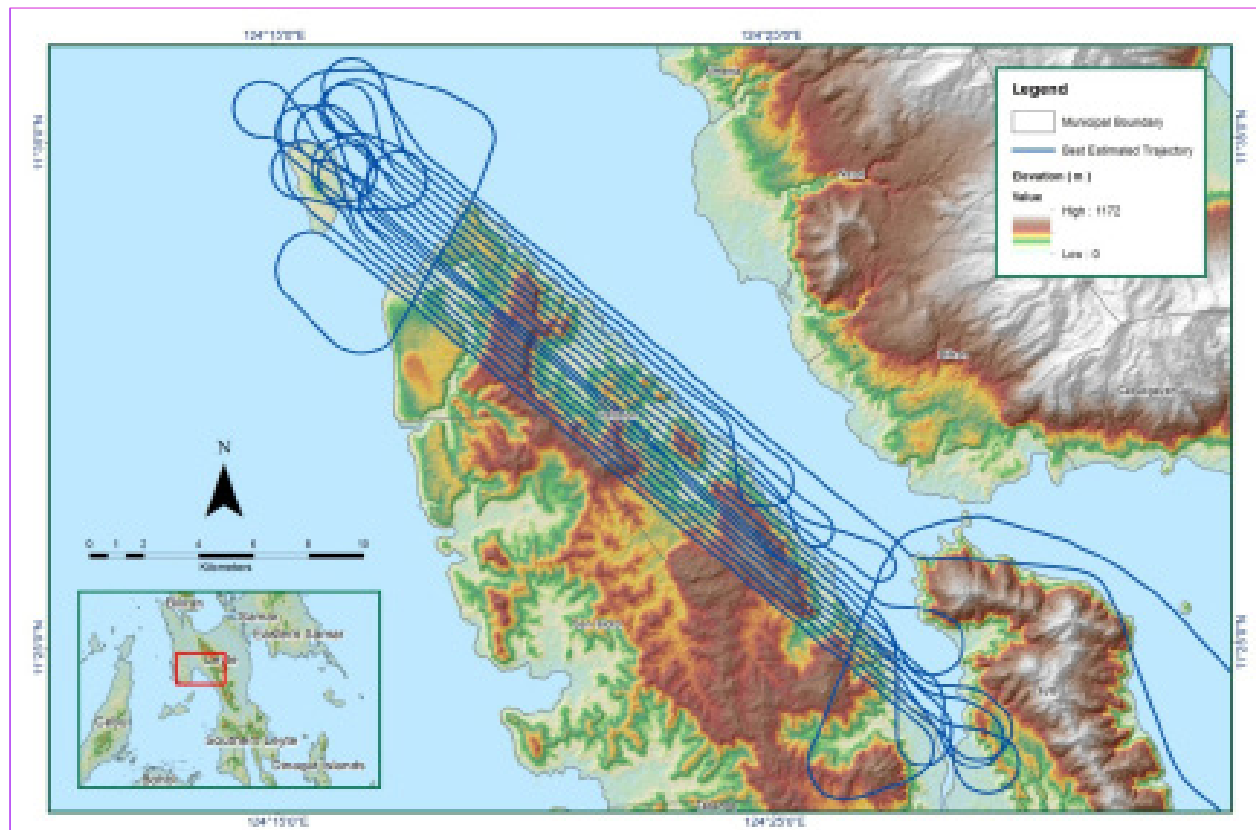


Figure A-8.52. Best Estimated Trajectory

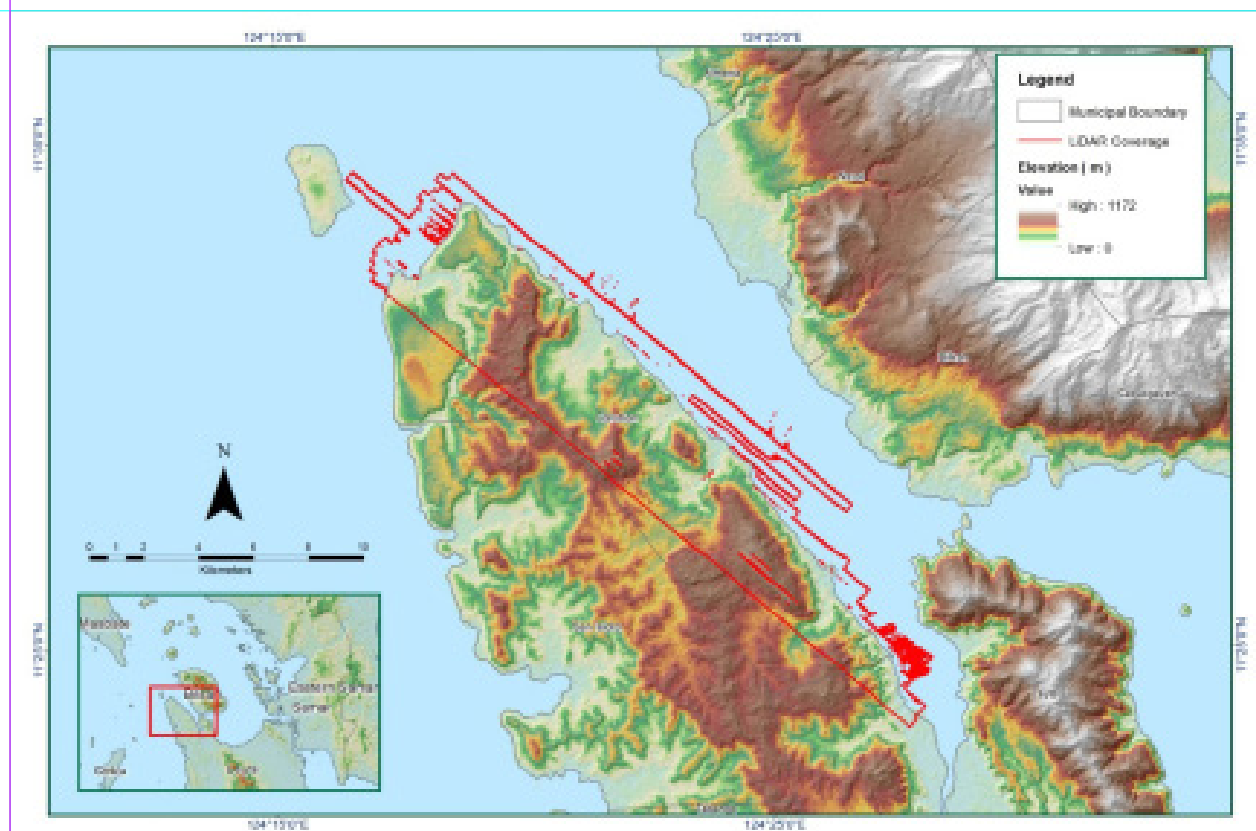


Figure A-8.53. Coverage of LiDAR data

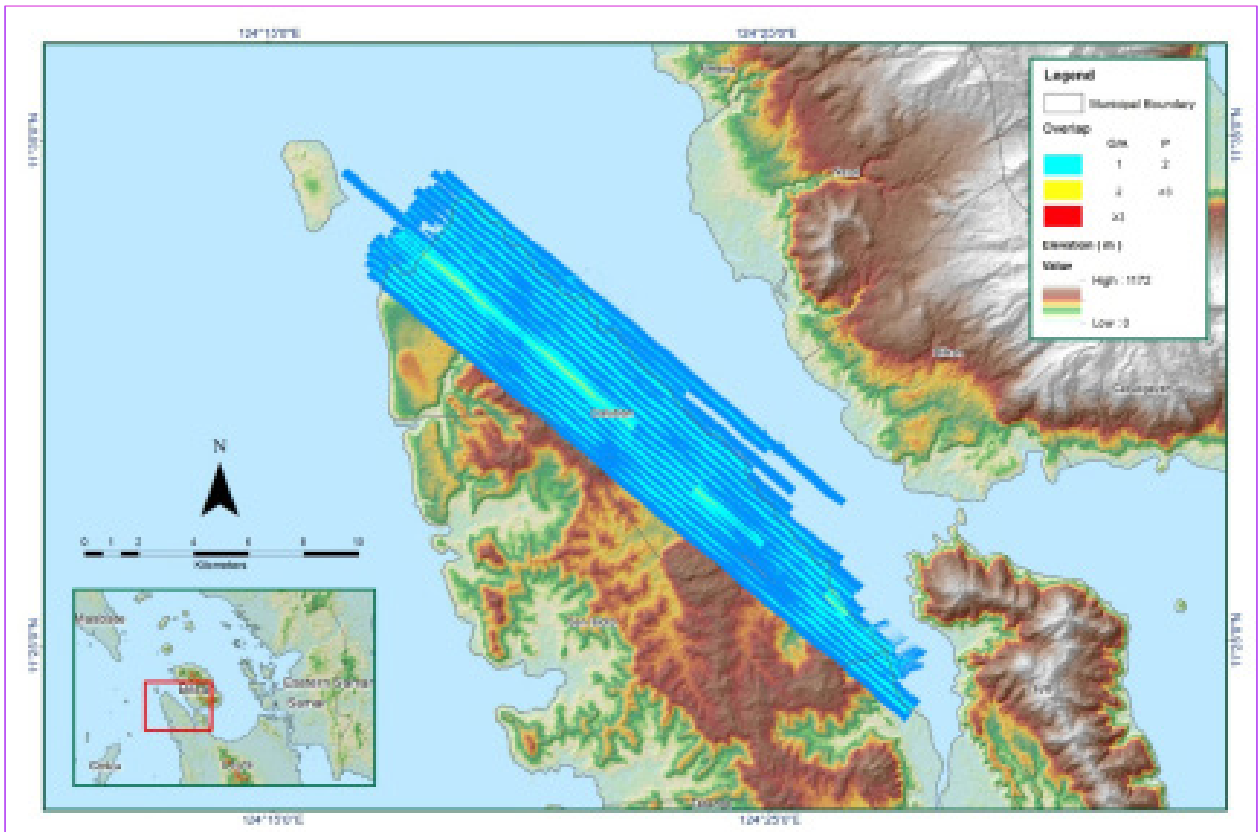


Figure A-8.54. Image of data overlap

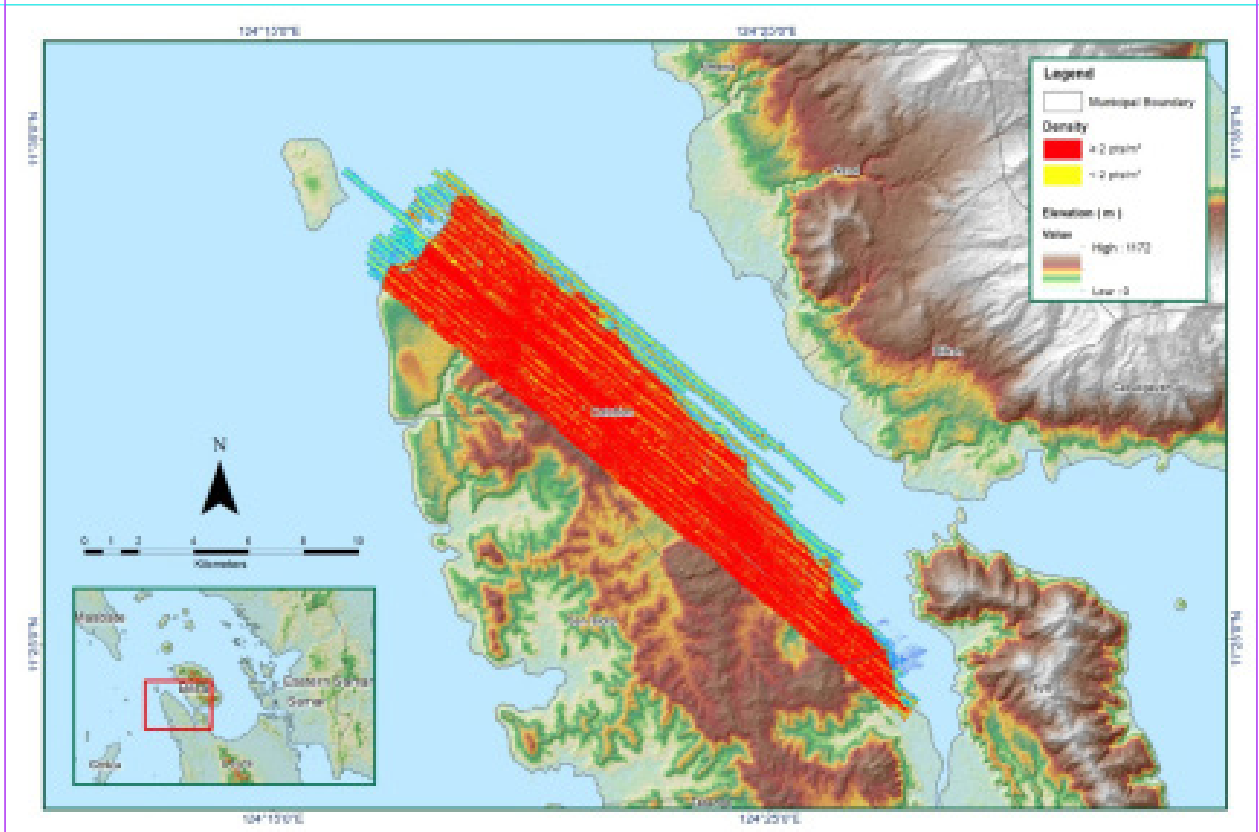


Figure A-8.55. Density map of merged LiDAR data



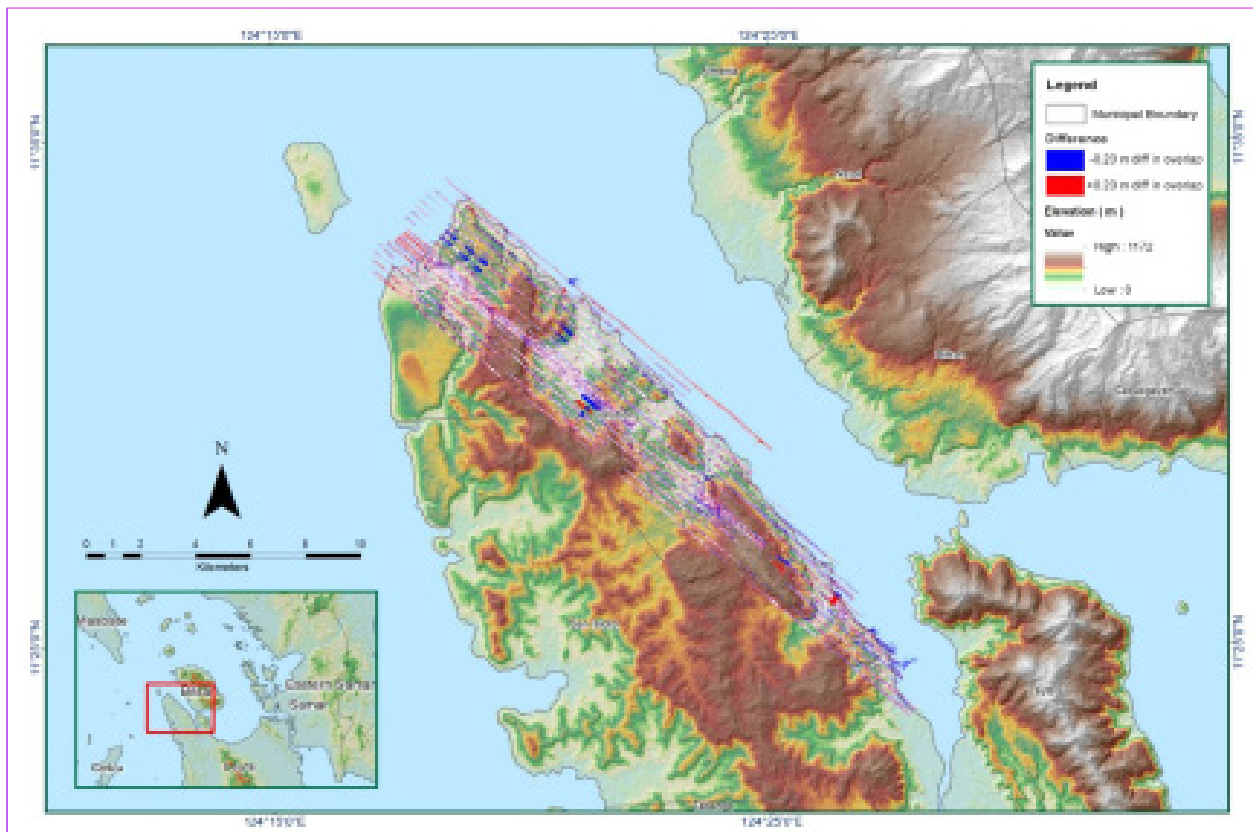


Table A-8.9. Mission Summary Report for Mission Blk35H

<b>Flight Area</b>	<b>Samar-Leyte</b>
<b>Mission Name</b>	Blk35H
<b>Inclusive Flights</b>	1494A
<b>Range data size</b>	14.7 GB
<b>POS data size</b>	282 MB
<b>Base data size</b>	7.64 MB
<b>Image</b>	89.2 GB
<b>Transfer date</b>	June 10, 2014
<i>Solution Status</i>	
<b>Number of Satellites (&gt;6)</b>	Yes
<b>PDOP (&lt;3)</b>	Yes
<b>Baseline Length (&lt;30km)</b>	Yes
<b>Processing Mode (&lt;=1)</b>	No
<i>Smoothed Performance Metrics (in cm)</i>	
<b>RMSE for North Position (&lt;4.0 cm)</b>	2.5
<b>RMSE for East Position (&lt;4.0 cm)</b>	1.674
<b>RMSE for Down Position (&lt;8.0 cm)</b>	4.64
<b>Boresight correction stdev (&lt;0.001deg)</b>	0.000283
<b>IMU attitude correction stdev (&lt;0.001deg)</b>	0.000568
<b>GPS position stdev (&lt;0.01m)</b>	0.0028
<b>Minimum % overlap (&gt;25)</b>	52.72%
<b>Ave point cloud density per sq.m. (&gt;2.0)</b>	3.48
<b>Elevation difference between strips (&lt;0.20 m)</b>	Yes
<b>Number of 1km x 1km blocks</b>	158
<b>Maximum Height</b>	376.65 m
<b>Minimum Height</b>	36.39 m
<i>Classification (# of points)</i>	
<b>Ground</b>	82,689,374
<b>Low vegetation</b>	99,097,253
<b>Medium vegetation</b>	126,198,163
<b>High vegetation</b>	25,741,043
<b>Building</b>	1,206,583
<b>Orthophoto</b>	Yes
<b>Processed by</b>	Engr. Irish Cortez, Engr. Melanie Hingpit, Engr. Gladys Mae Apat

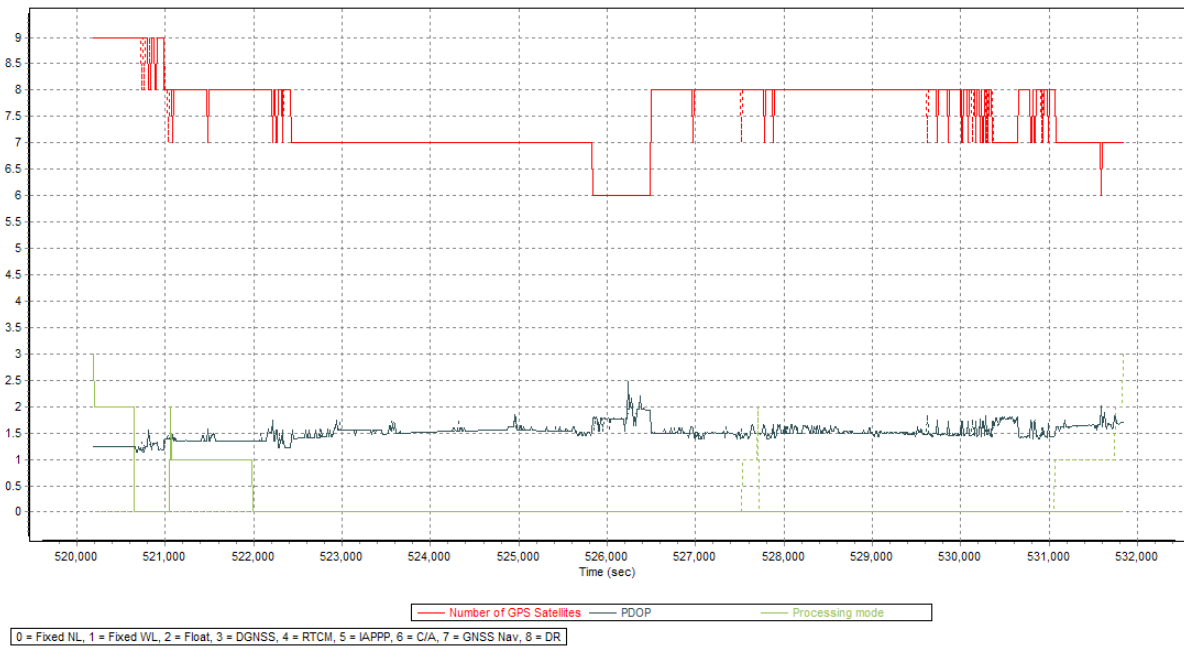


Figure A-8.57. Solution Status

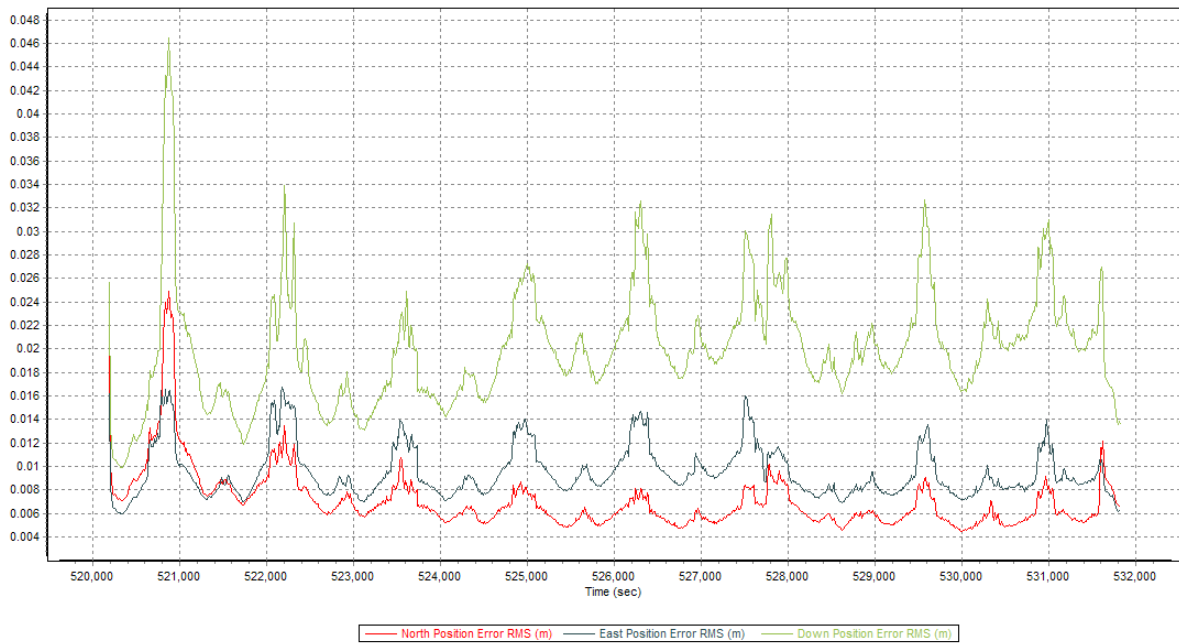


Figure A-8.58. Smoothed Performance Metrics Parameters

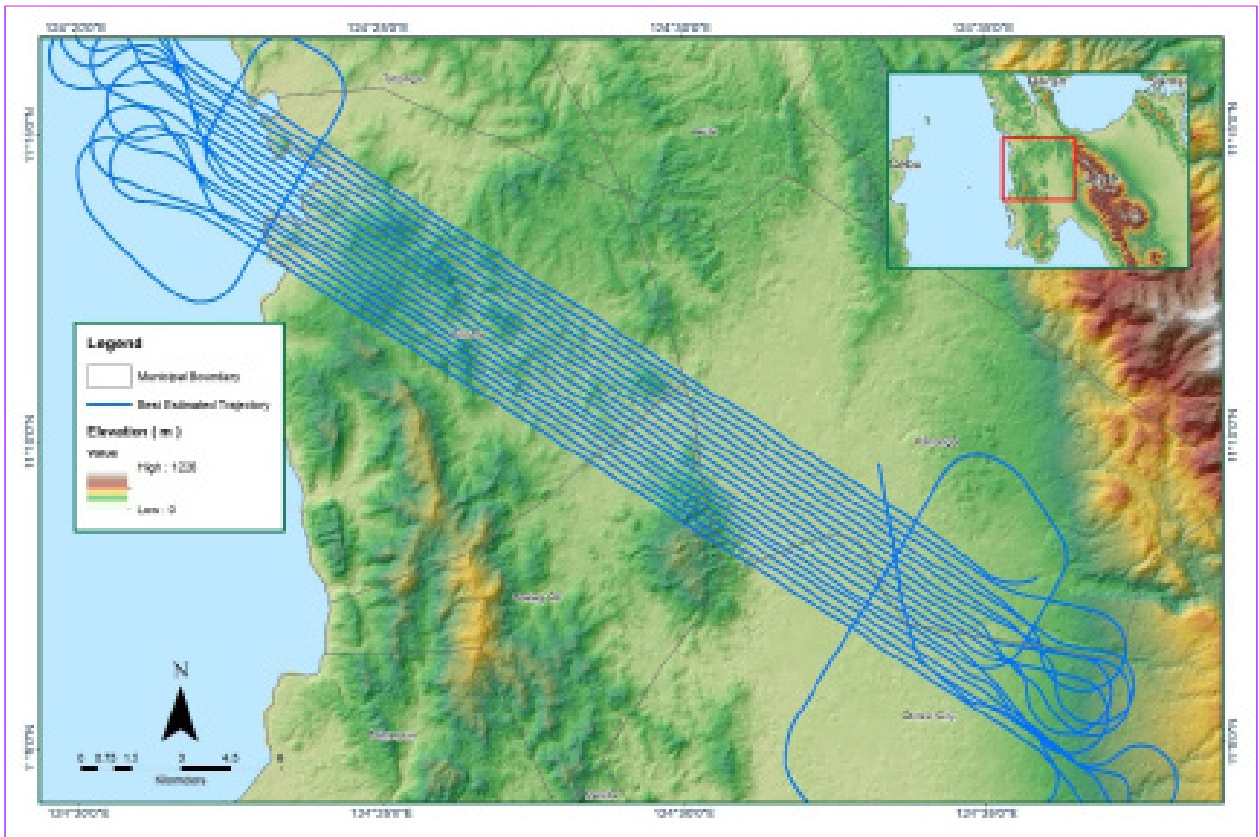


Figure A-8.59. Best Estimated Trajectory

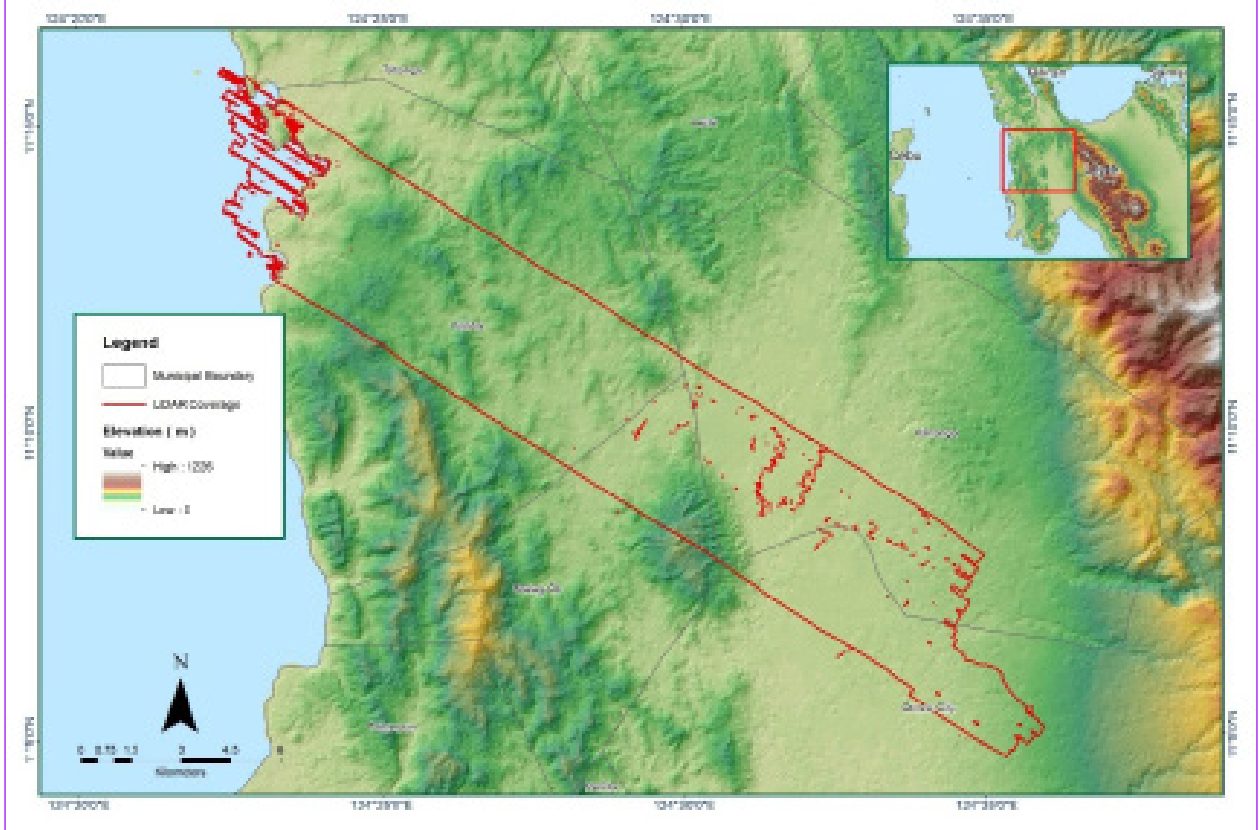


Figure A-8.60. Best Estimated Trajectory

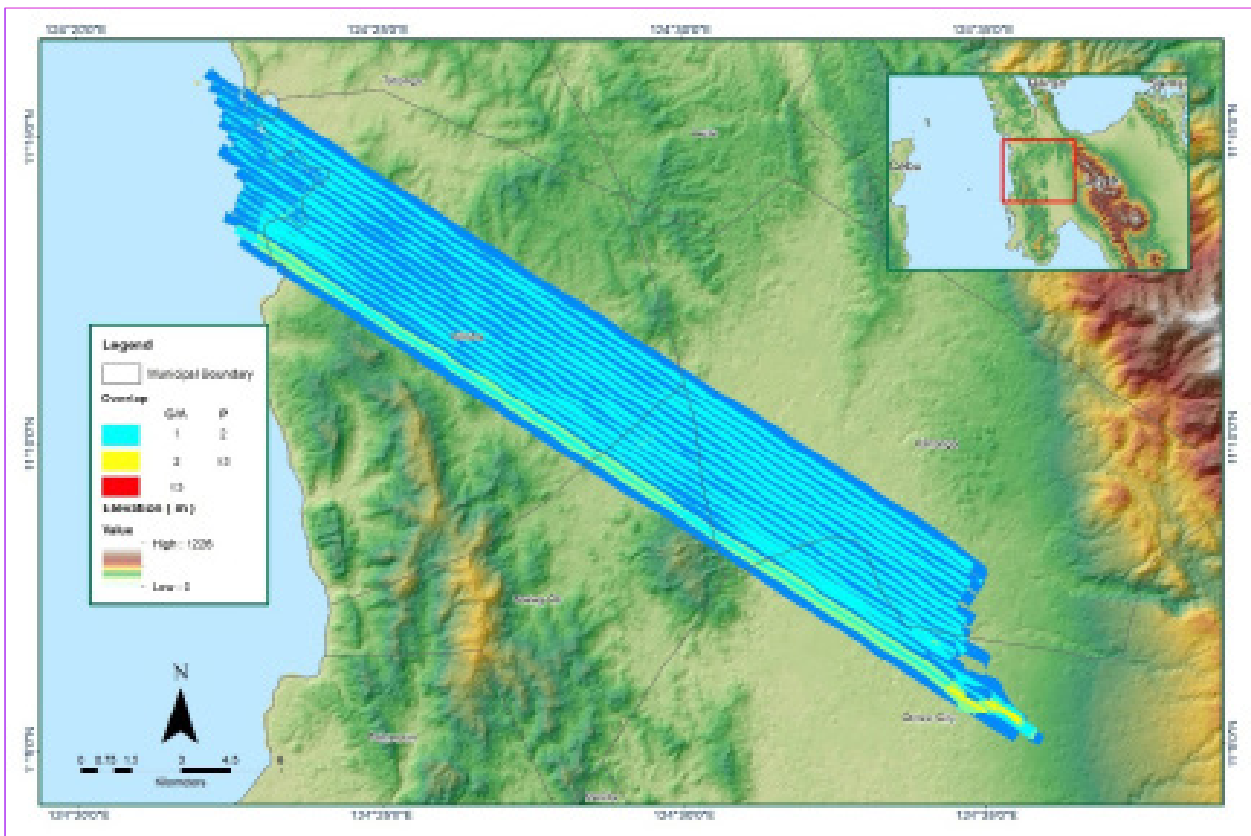


Figure A-8.61. Image of data overlap

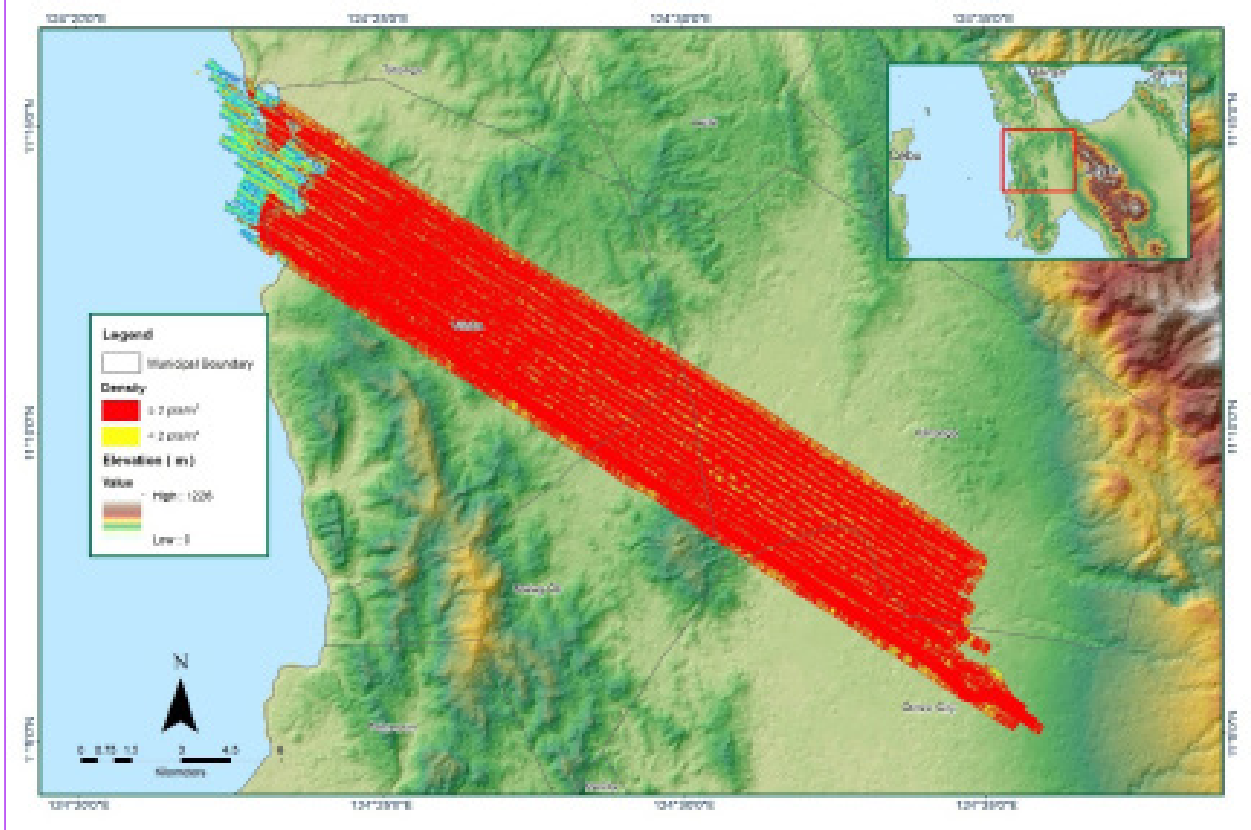


Figure A-8.62. Density map of merged LiDAR data

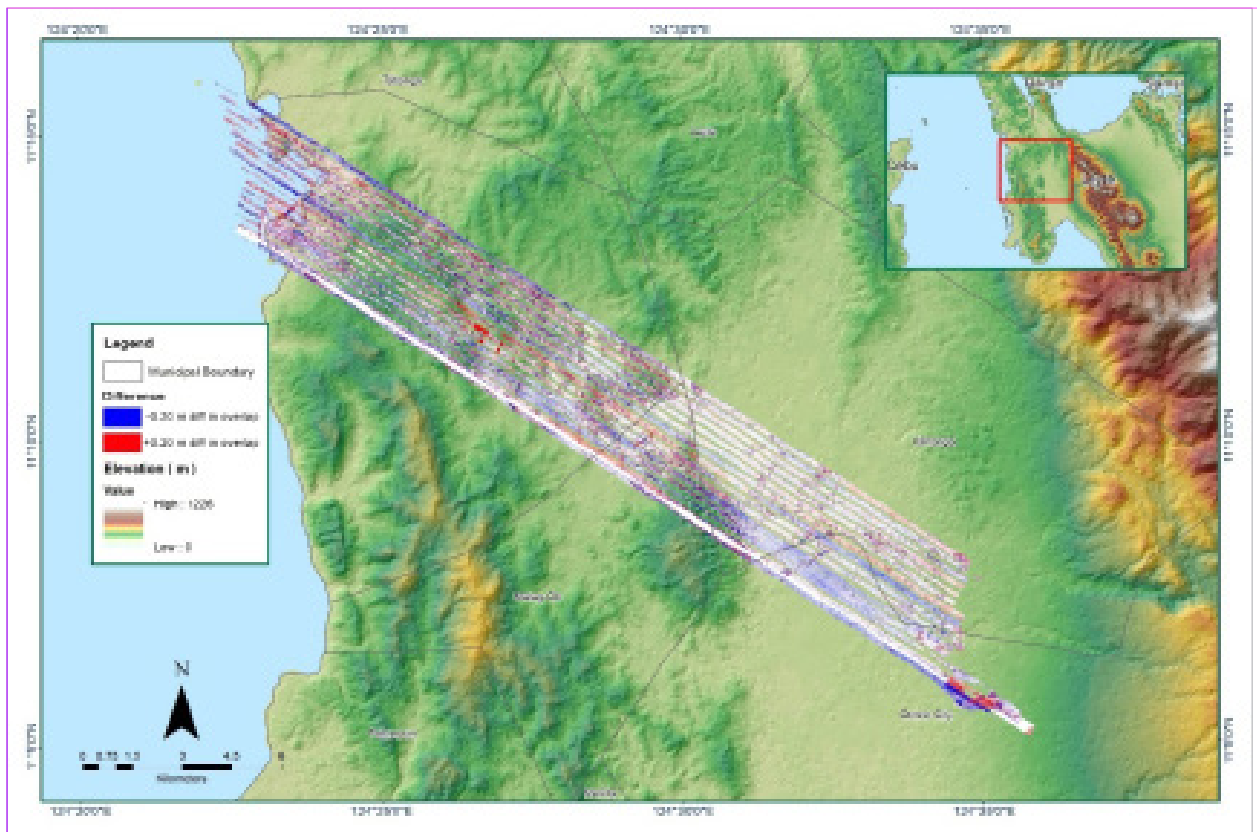


Figure A-8.63. Elevation difference between flight lines

Table A-8.10. Mission Summary Report for Mission Blk35H\_Supplement2

<b>Flight Area</b>	<b>Samar-Leyte</b>
<b>Mission Name</b>	Blk35H_Supplement2
<b>Inclusive Flights</b>	1498A
<b>Range data size</b>	3.23 GB
<b>POS data size</b>	282 MB
<b>Base data size</b>	8.04 MB
<b>Image</b>	88.7 GB
<b>Transfer date</b>	June 10, 2014
<i>Solution Status</i>	
<b>Number of Satellites (&gt;6)</b>	Yes
<b>PDOP (&lt;3)</b>	Yes
<b>Baseline Length (&lt;30km)</b>	No
<b>Processing Mode (&lt;=1)</b>	No
<i>Smoothed Performance Metrics (in cm)</i>	
<b>RMSE for North Position (&lt;4.0 cm)</b>	3.3
<b>RMSE for East Position (&lt;4.0 cm)</b>	3.7
<b>RMSE for Down Position (&lt;8.0 cm)</b>	4.3
<b>Boresight correction stdev (&lt;0.001deg)</b>	0.000283
<b>IMU attitude correction stdev (&lt;0.001deg)</b>	0.000568
<b>GPS position stdev (&lt;0.01m)</b>	0.0028
<b>Minimum % overlap (&gt;25)</b>	11.00%
<b>Ave point cloud density per sq.m. (&gt;2.0)</b>	2.40
<b>Elevation difference between strips (&lt;0.20 m)</b>	Yes
<b>Number of 1km x 1km blocks</b>	3
<b>Maximum Height</b>	107.84 m
<b>Minimum Height</b>	80.85 m
<i>Classification (# of points)</i>	
<b>Ground</b>	121,532
<b>Low vegetation</b>	138,860
<b>Medium vegetation</b>	116,706
<b>High vegetation</b>	15,470
<b>Building</b>	1,666
<b>Orthophoto</b>	No
<b>Processed by</b>	Engr. Irish Cortez, Aljon Rie Araneta, Engr. Gladys Mae Apat

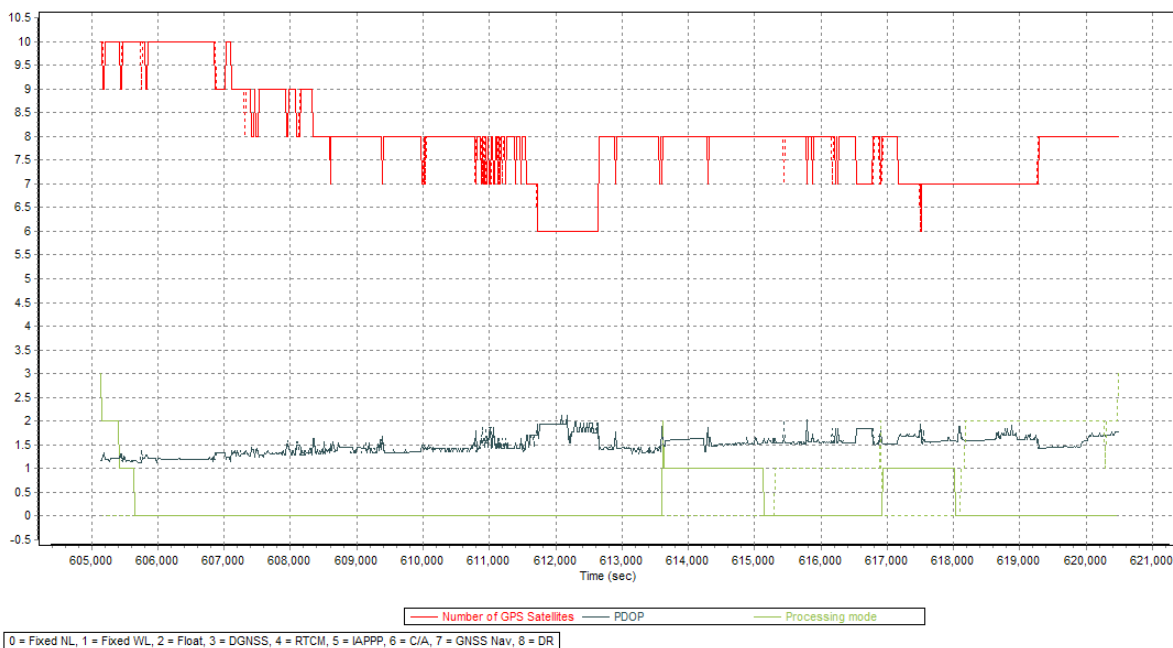


Figure A-8.64. Solution Status

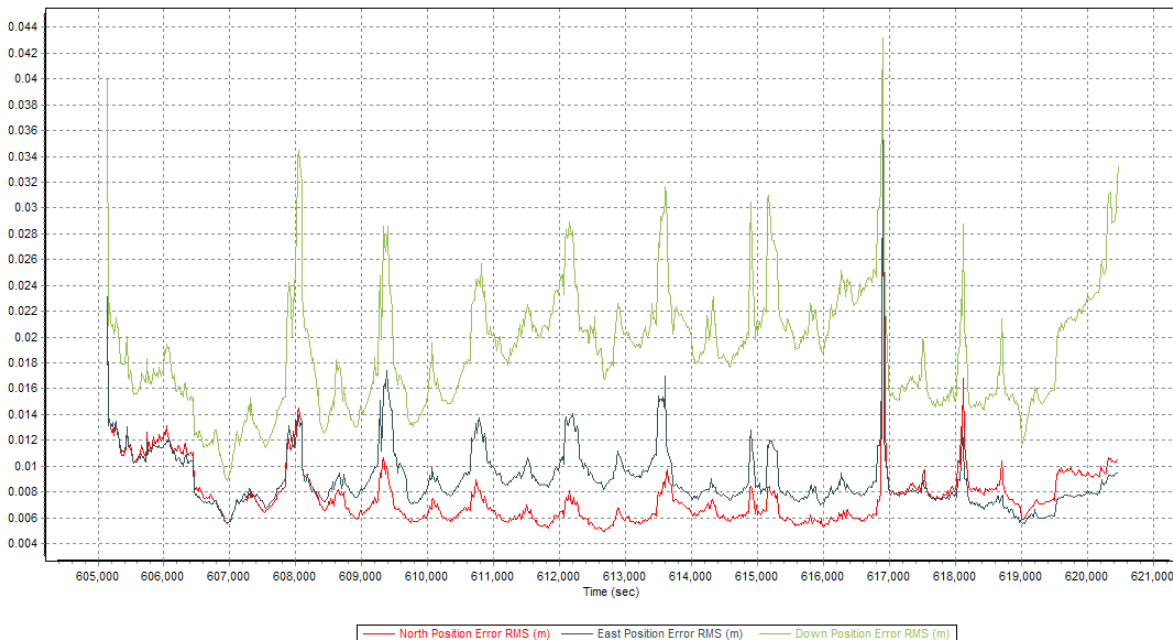


Figure A-8.65. Smoothed Performance Metrics Parameters



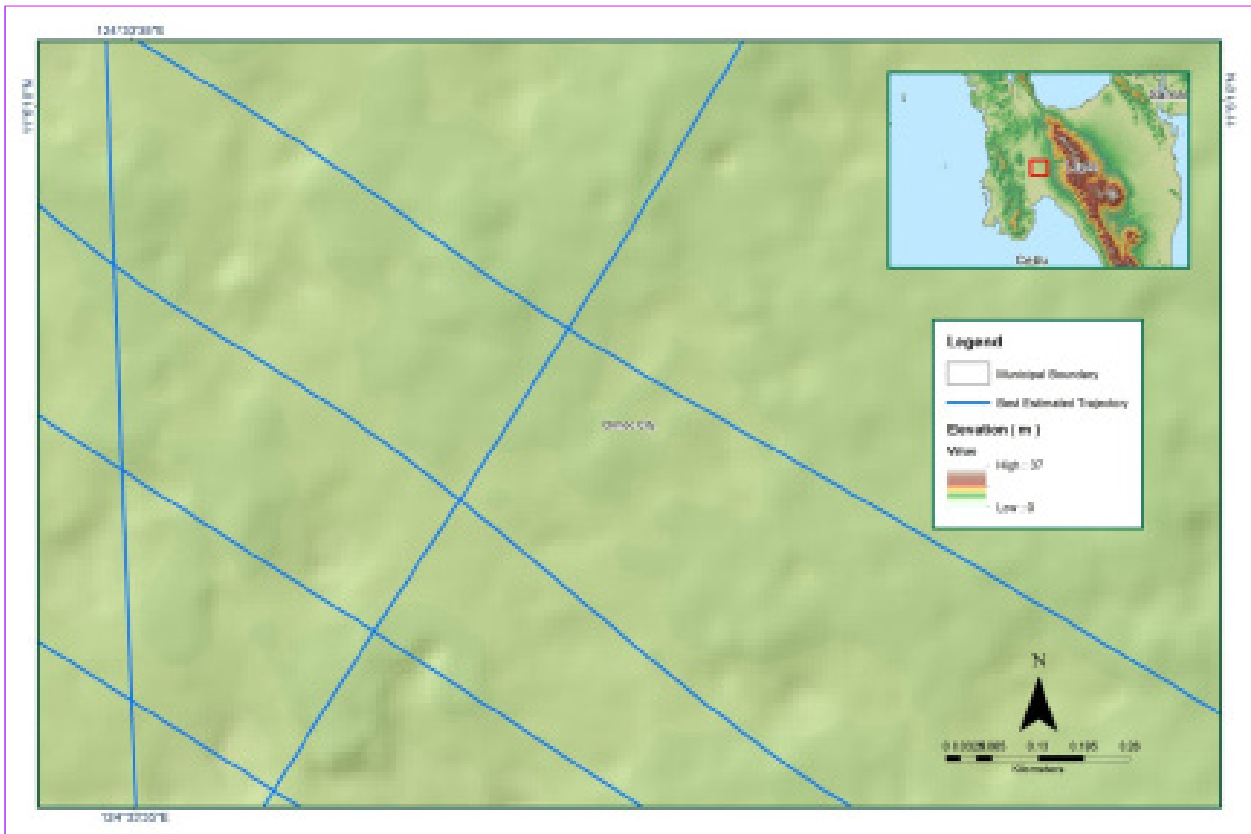


Figure A-8.66. Best Estimated Trajectory

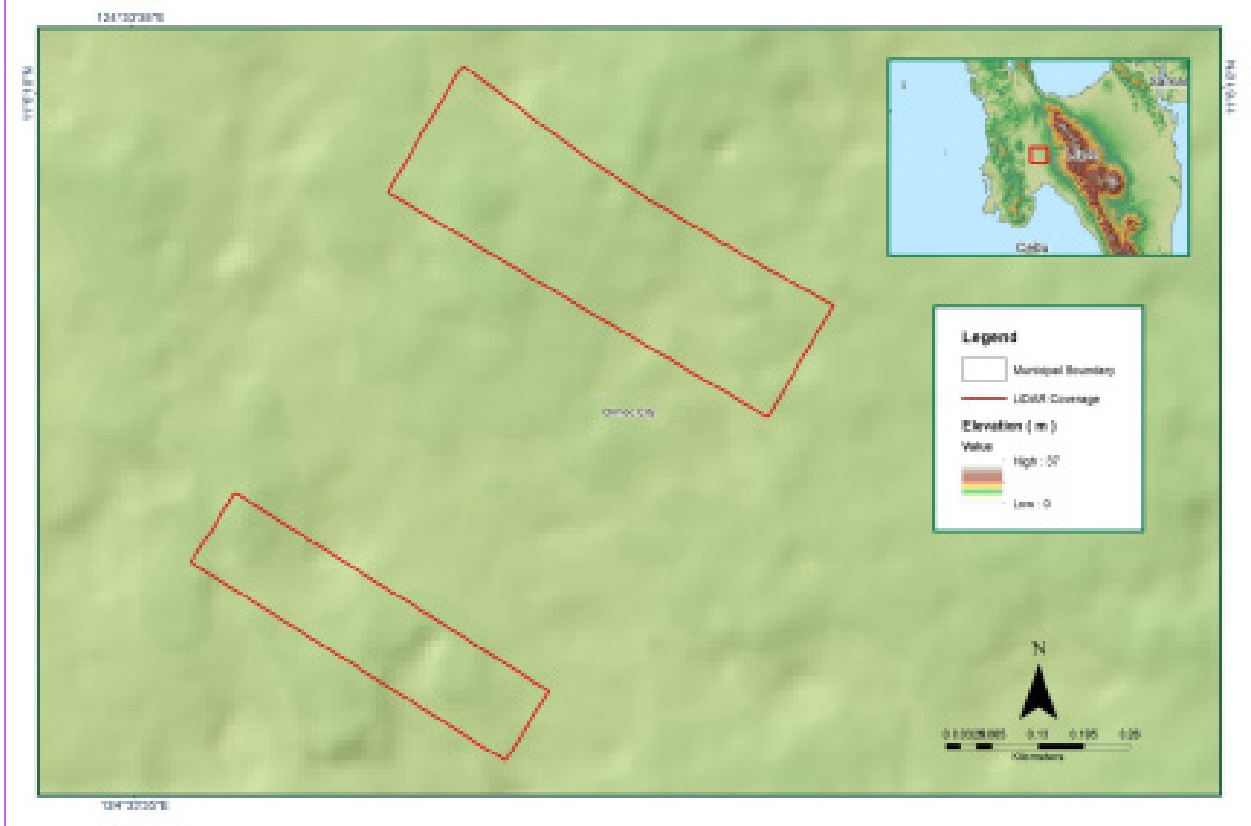


Figure A-8.67. Coverage of LiDAR data

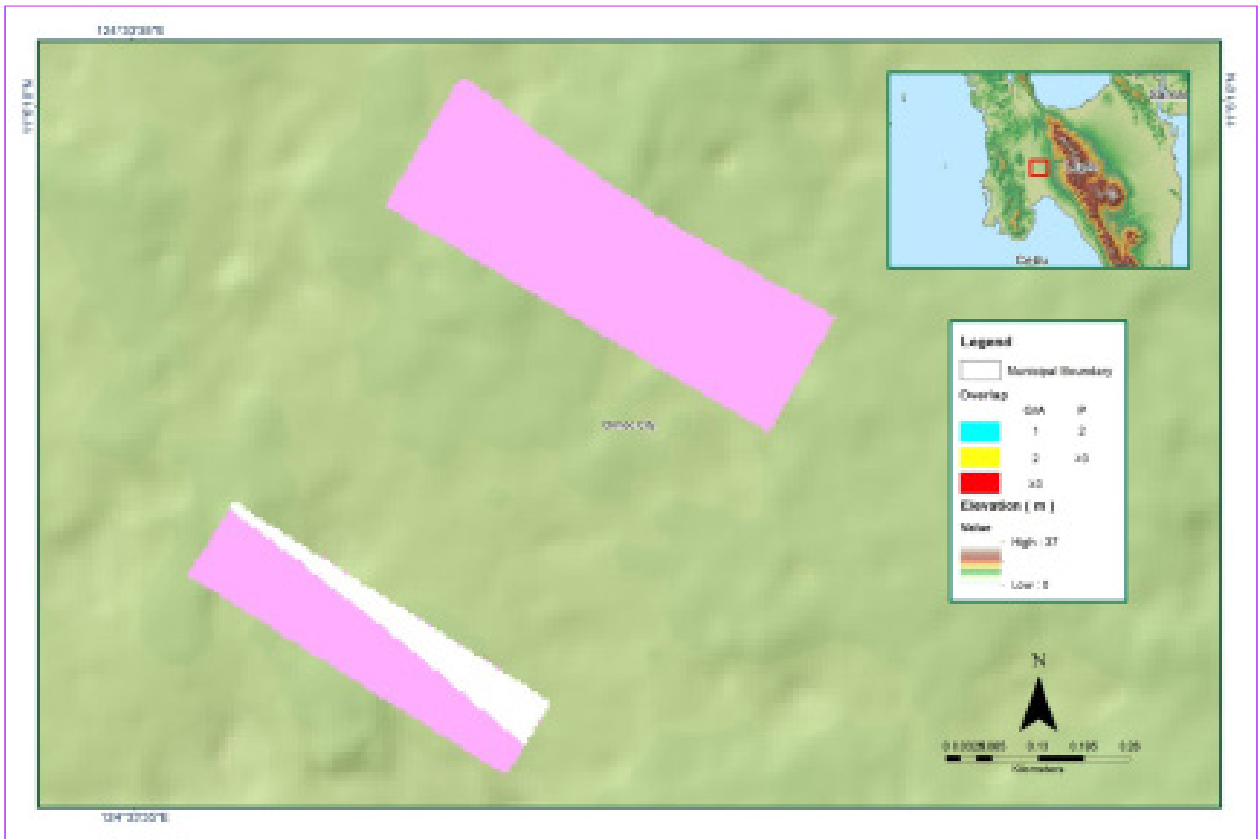


Figure A-8.68. Image of data overlap

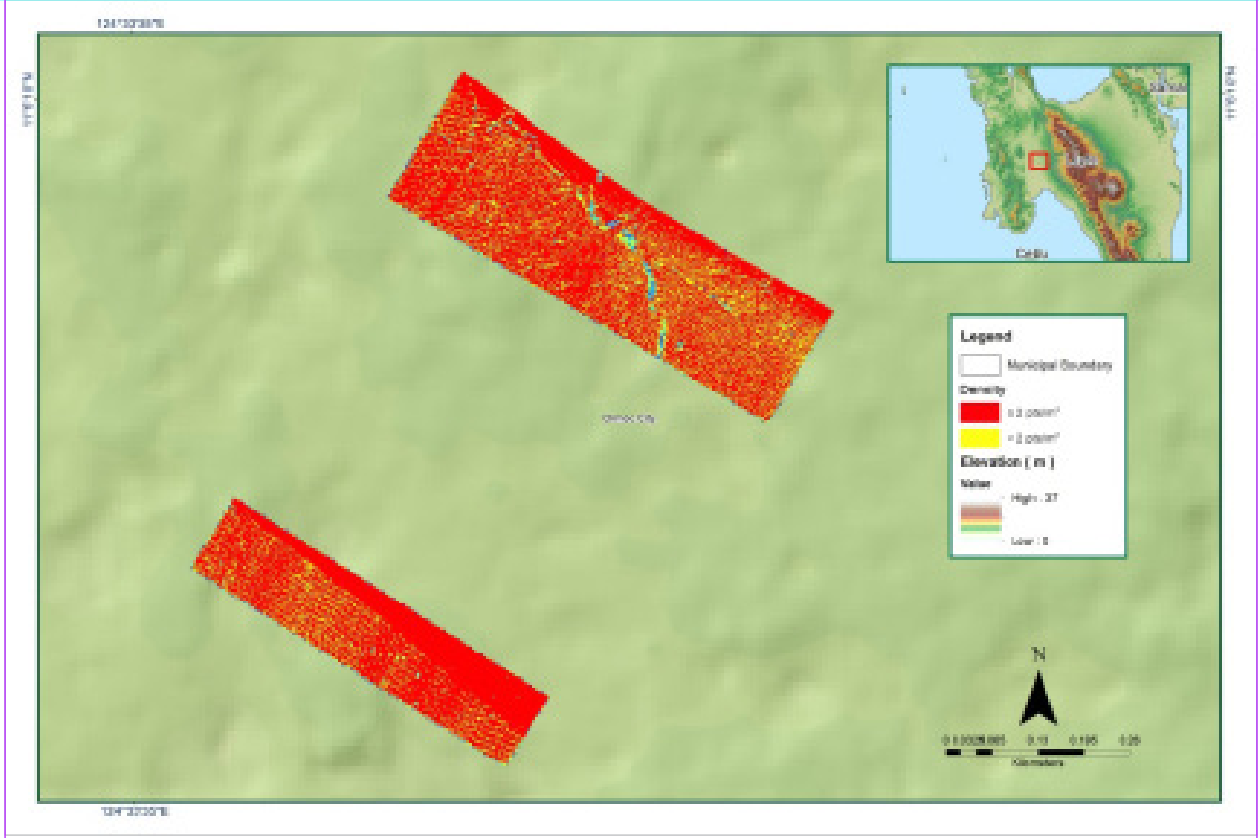


Figure A-8.69. Density map of merged LiDAR data

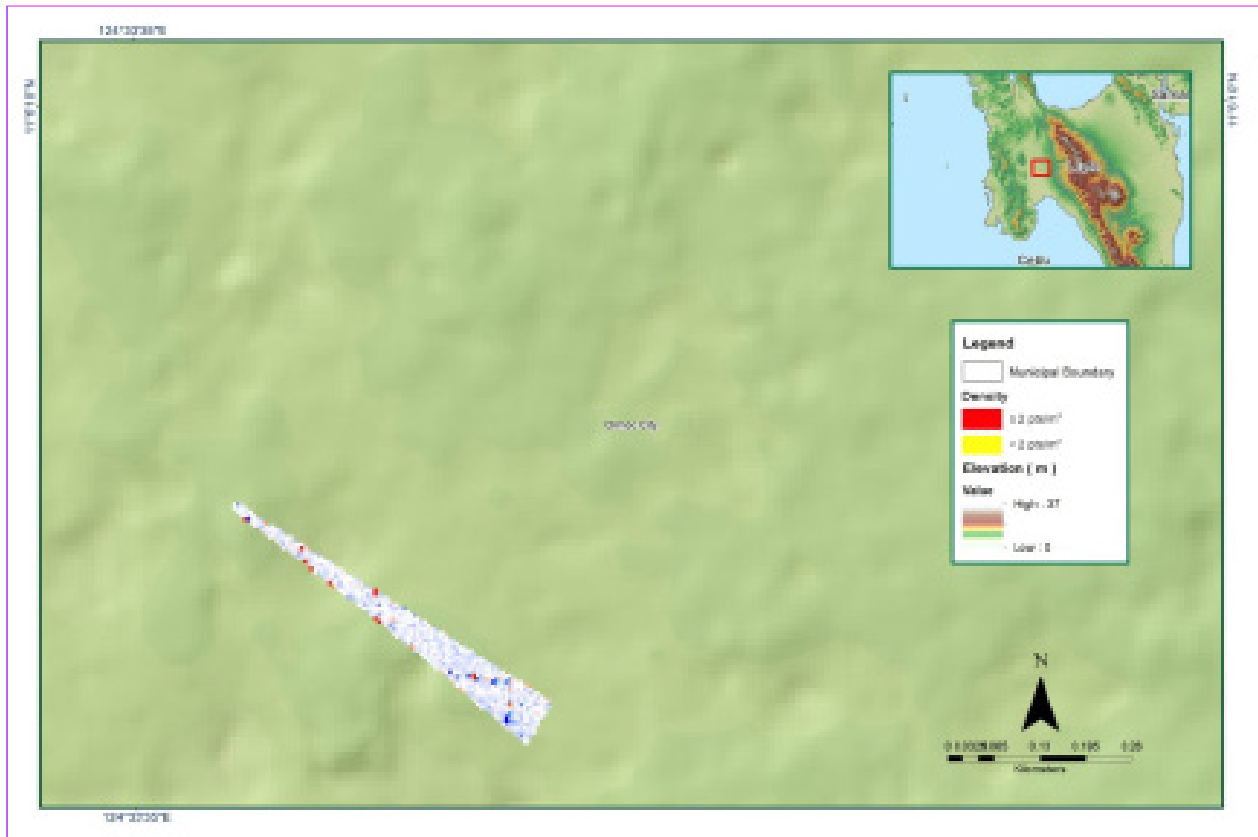


Figure A-8.70. Elevation difference between flight lines

Table A-8.II. Mission Summary Report for Mission Blk35A\_supplement

Flight Area	Ormoc
<b>Mission Name</b>	Blk35A_supplement
<b>Inclusive Flights</b>	7806AC
<b>Range data size</b>	8.2 GB
<b>POS data size</b>	195 MB
<b>Base data size</b>	27 MB
<b>Image</b>	NA
<b>Transfer date</b>	February 25, 2015
<i>Solution Status</i>	
<b>Number of Satellites (&gt;6)</b>	Yes
<b>PDOP (&lt;3)</b>	Yes
<b>Baseline Length (&lt;30km)</b>	Yes
<b>Processing Mode (&lt;=1)</b>	Yes
<i>Smoothed Performance Metrics (in cm)</i>	
<b>RMSE for North Position (&lt;4.0 cm)</b>	1.398
<b>RMSE for East Position (&lt;4.0 cm)</b>	1.825
<b>RMSE for Down Position (&lt;8.0 cm)</b>	2.963
<i>Boresight correction stdev (&lt;0.001deg)</i>	
<b>IMU attitude correction stdev (&lt;0.001deg)</b>	0.000619
<b>GPS position stdev (&lt;0.01m)</b>	0.0071
<i>Minimum % overlap (&gt;25)</i>	
<b>Ave point cloud density per sq.m. (&gt;2.0)</b>	3.58
<b>Elevation difference between strips (&lt;0.20 m)</b>	Yes
<i>Number of 1km x 1km blocks</i>	
<b>Maximum Height</b>	273.06
<b>Minimum Height</b>	57.10
<i>Classification (# of points)</i>	
<b>Ground</b>	48,561,341
<b>Low vegetation</b>	55,772,317
<b>Medium vegetation</b>	72,199,910
<b>High vegetation</b>	12,108,287
<b>Building</b>	5,014,837
<b>Orthophoto</b>	None
<b>Processed by</b>	Engr. Abigail Joy Ching, Engr. Antonio Chua, Jr., Engr. Krisha Marie Bautista

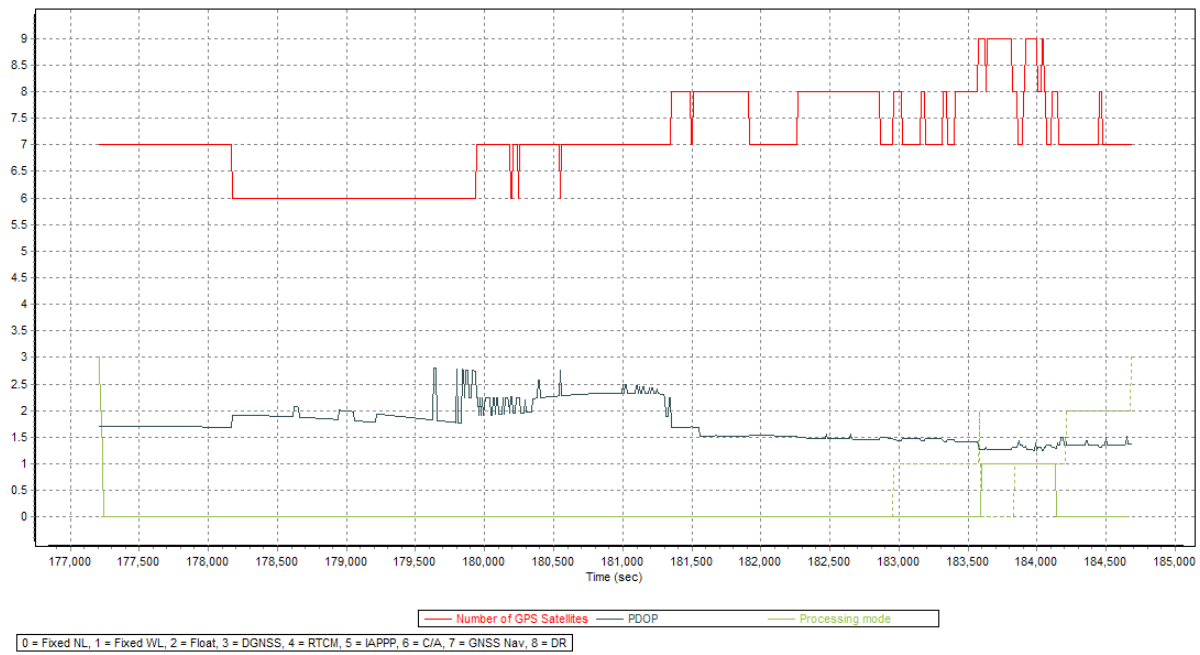


Figure A-8.71. Solution Status

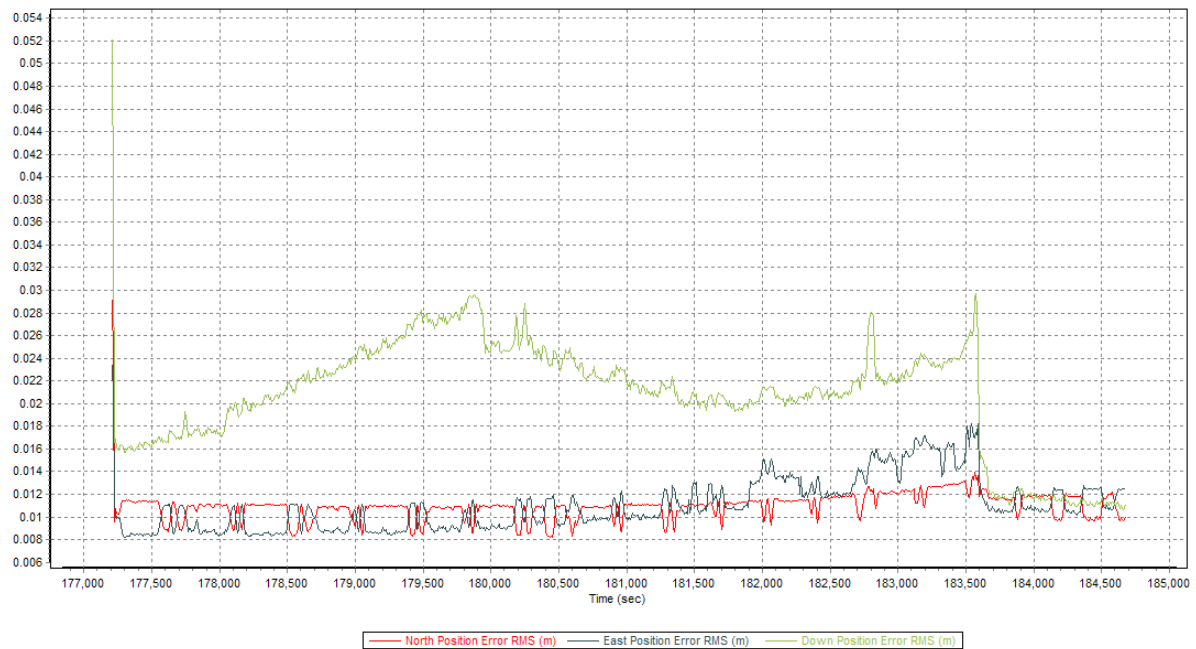


Figure A-8.72. Smoothed Performance Metrics Parameters

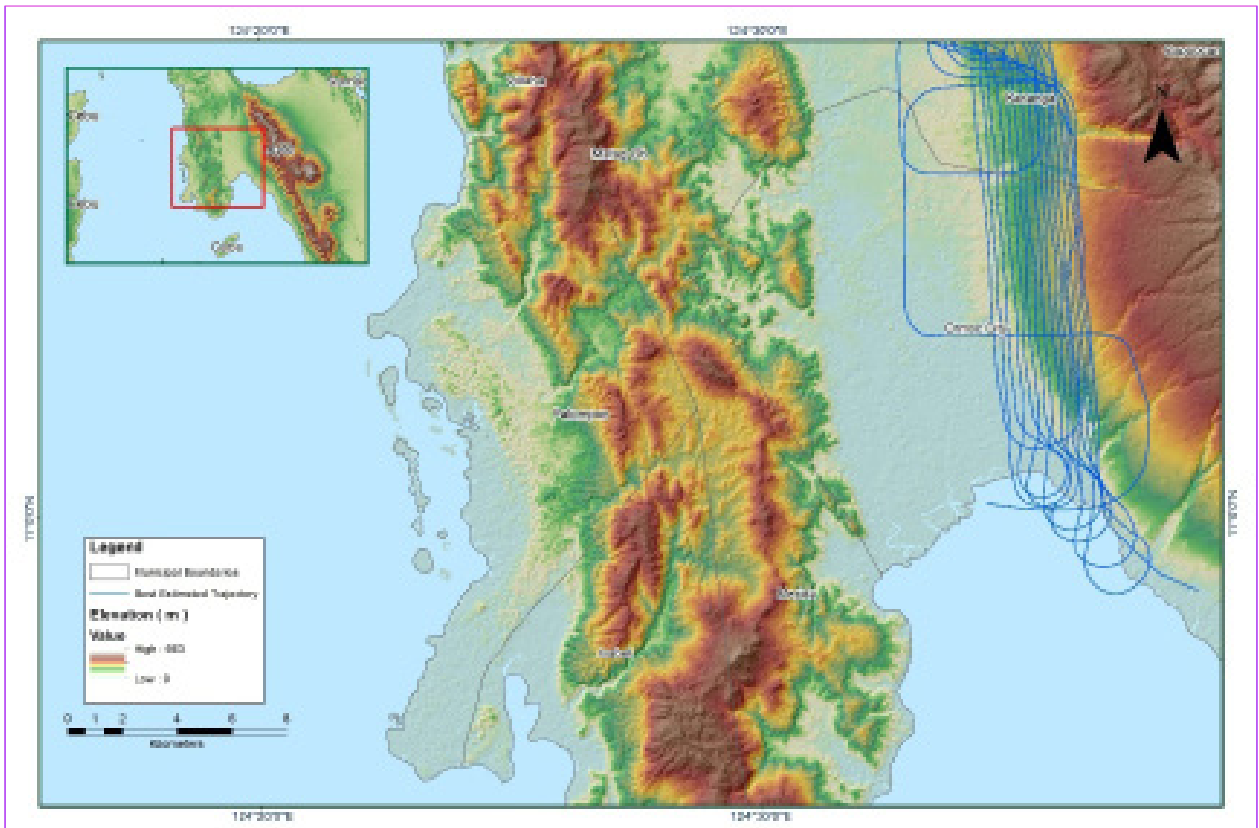


Figure A-8.73. Best Estimated Trajectory

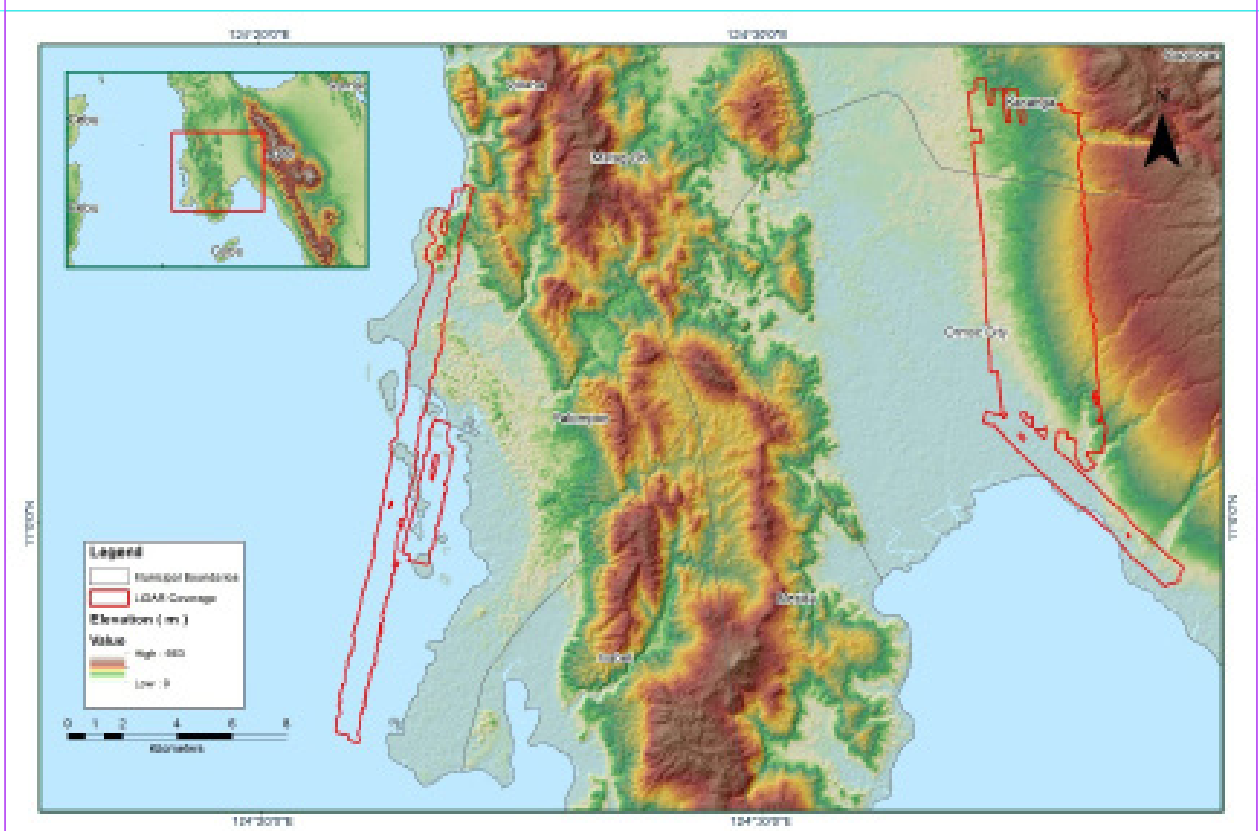


Figure A-8.74. Best Estimated Trajectory

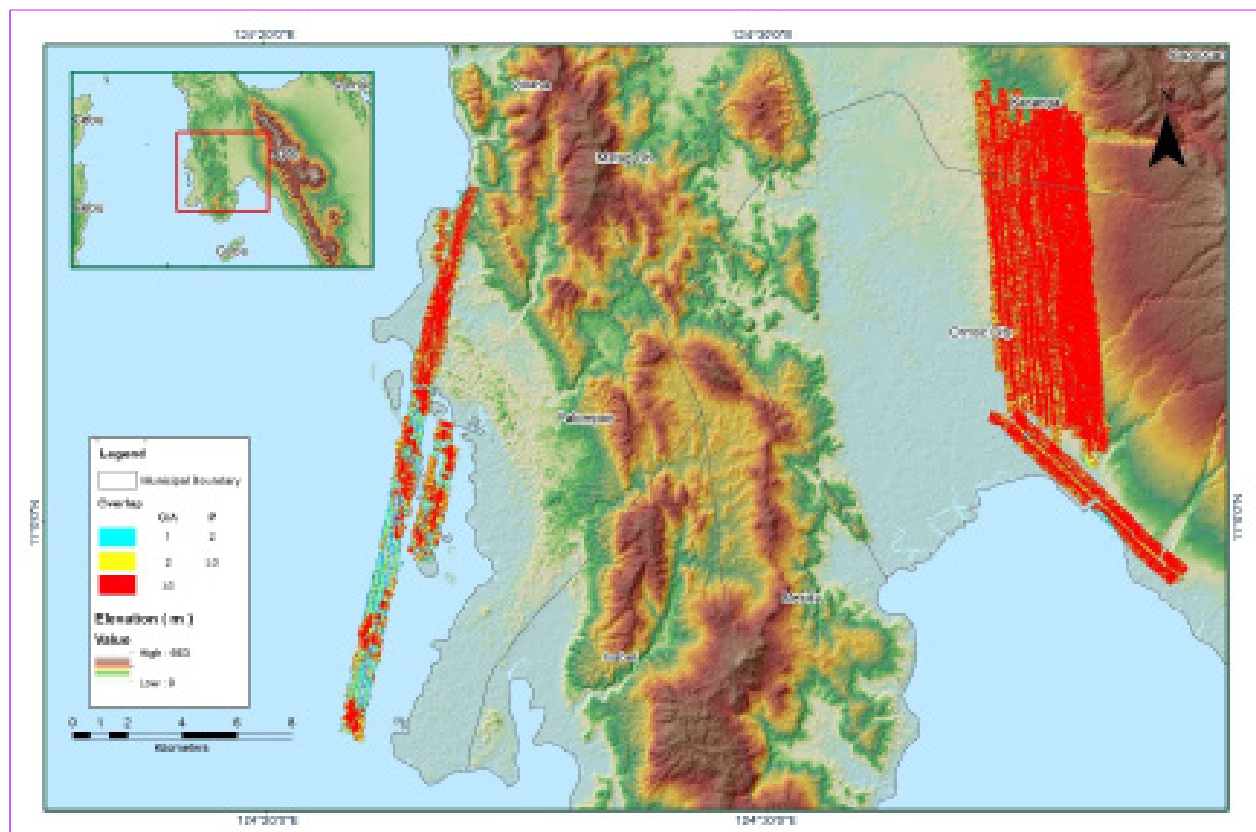


Figure A-8.75. Image of data overlap

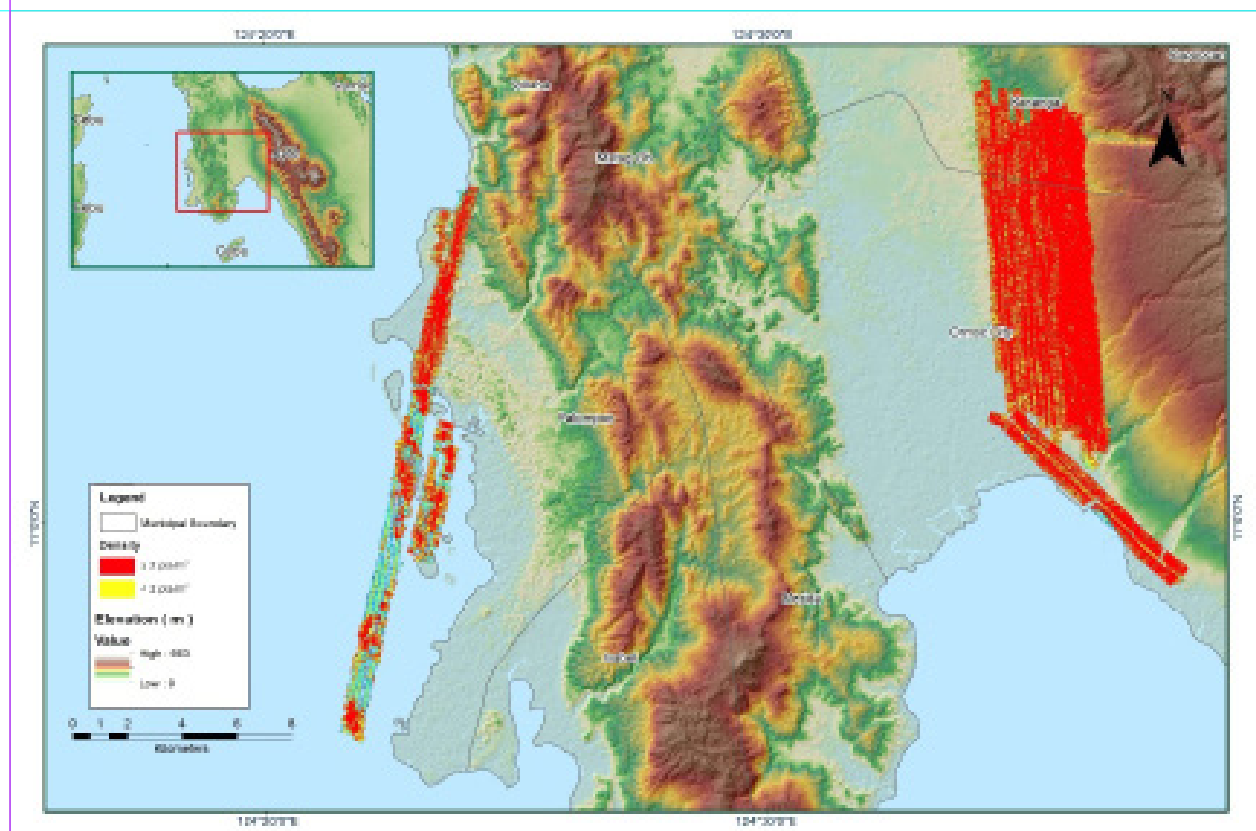


Figure A-8.76. Density map of merged LiDAR data

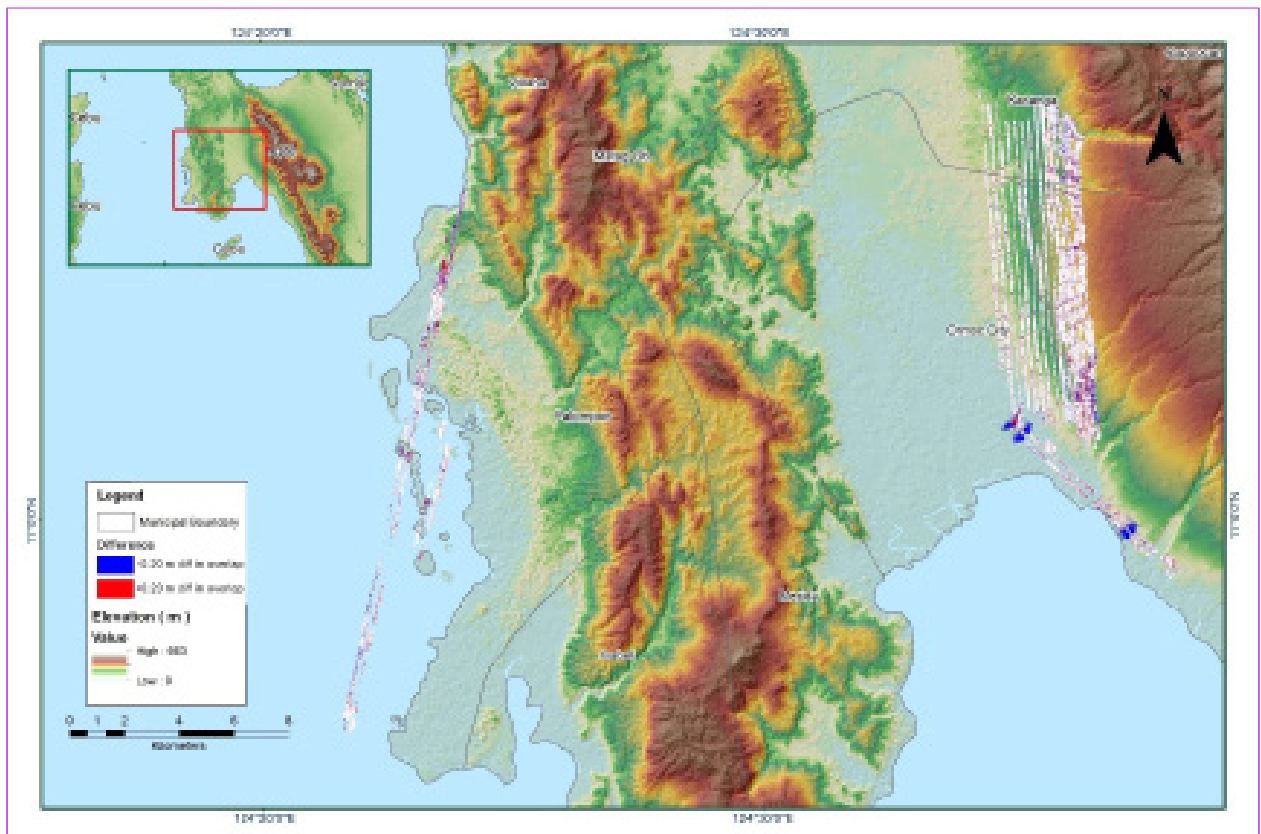


Figure A-8.77. Elevation difference between flight lines



Table A-8.12. Mission Summary Report for Mission Blk35A

Flight Area	Ormoc
Mission Name	Blk35A
Inclusive Flights	7780AC, 7782AC
Range data size	18.92 GB
POS	314.4 MB
Image	0 GB
Transfer date	March 9 2015
<i>Solution Status</i>	
Number of Satellites (>6)	No
PDOP (<3)	Yes
Baseline Length (<30km)	Yes
Processing Mode (<=1)	Yes
<i>Smoothed Performance Metrics (in cm)</i>	
RMSE for North Position (<4.0 cm)	1.19
RMSE for East Position (<4.0 cm)	1.51
RMSE for Down Position (<8.0 cm)	3.00
<i>Boresight correction stdev (&lt;0.001deg)</i>	
IMU attitude correction stdev (<0.001deg)	0.002289
GPS position stdev (<0.01m)	0.0035
<i>Minimum % overlap (&gt;25)</i>	
Ave point cloud density per sq.m. (>2.0)	68.46
Elevation difference between strips (<0.20 m)	4.24
<i>Number of 1km x 1km blocks</i>	
Maximum Height	Yes
Minimum Height	160
<i>Classification (# of points)</i>	
Ground	178.37 m
Low vegetation	57.53 m
Medium vegetation	72,108,209
High vegetation	118,219,687
Building	115,199,347
Orthophoto	21,276,179
Processed by	10,881,118
Engr. Irish Cortez, Engr. Christy Lubiano, Kathryn Claudyn Zarate	

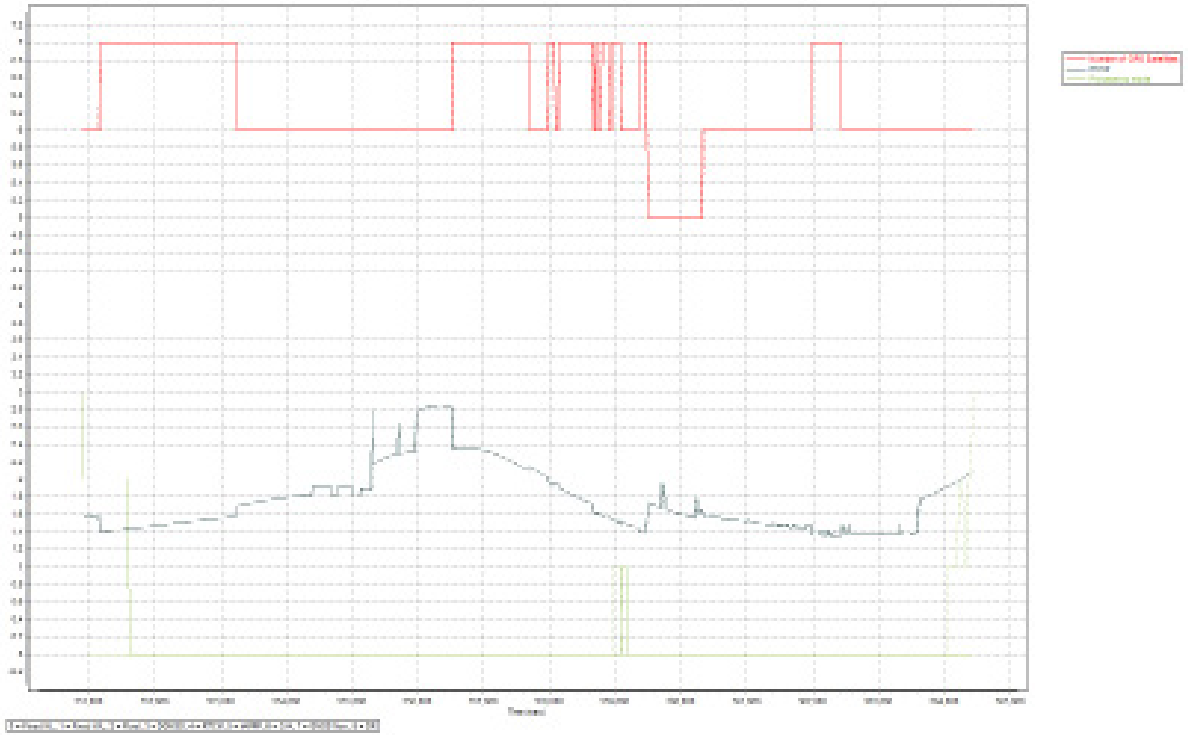


Figure A-8.78. Solution Status

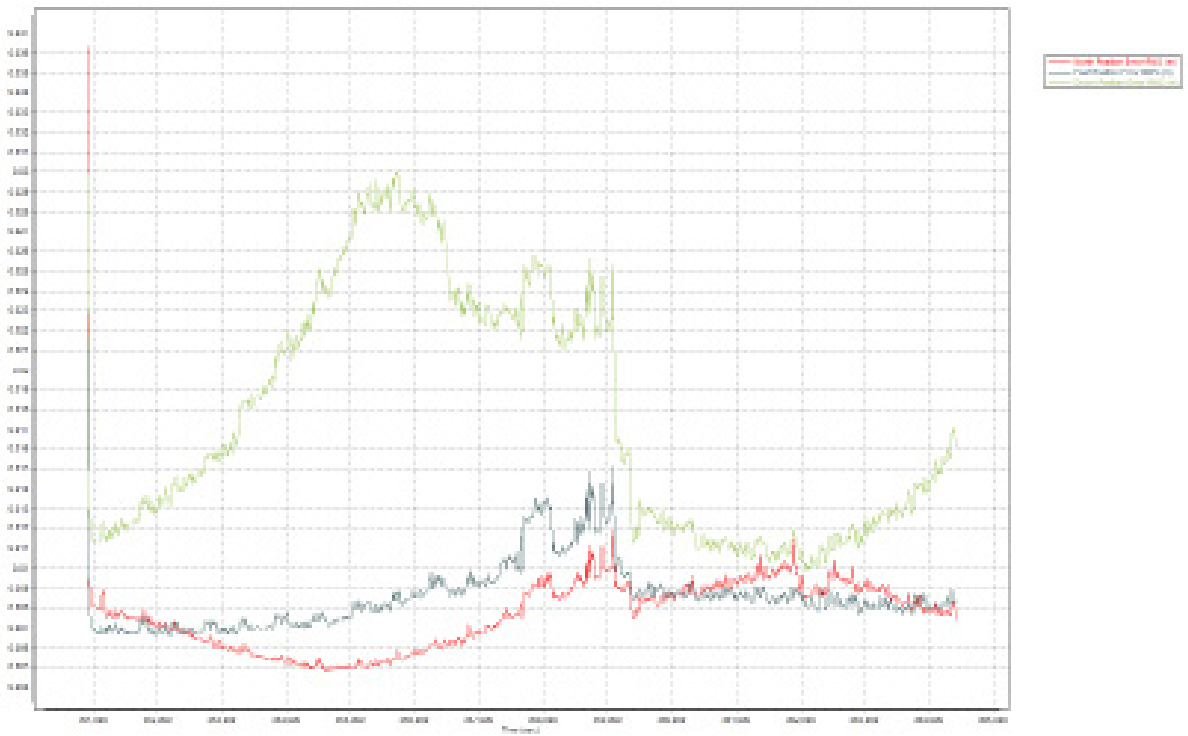


Figure A-8.79. Smoothed Performance Metrics Parameters

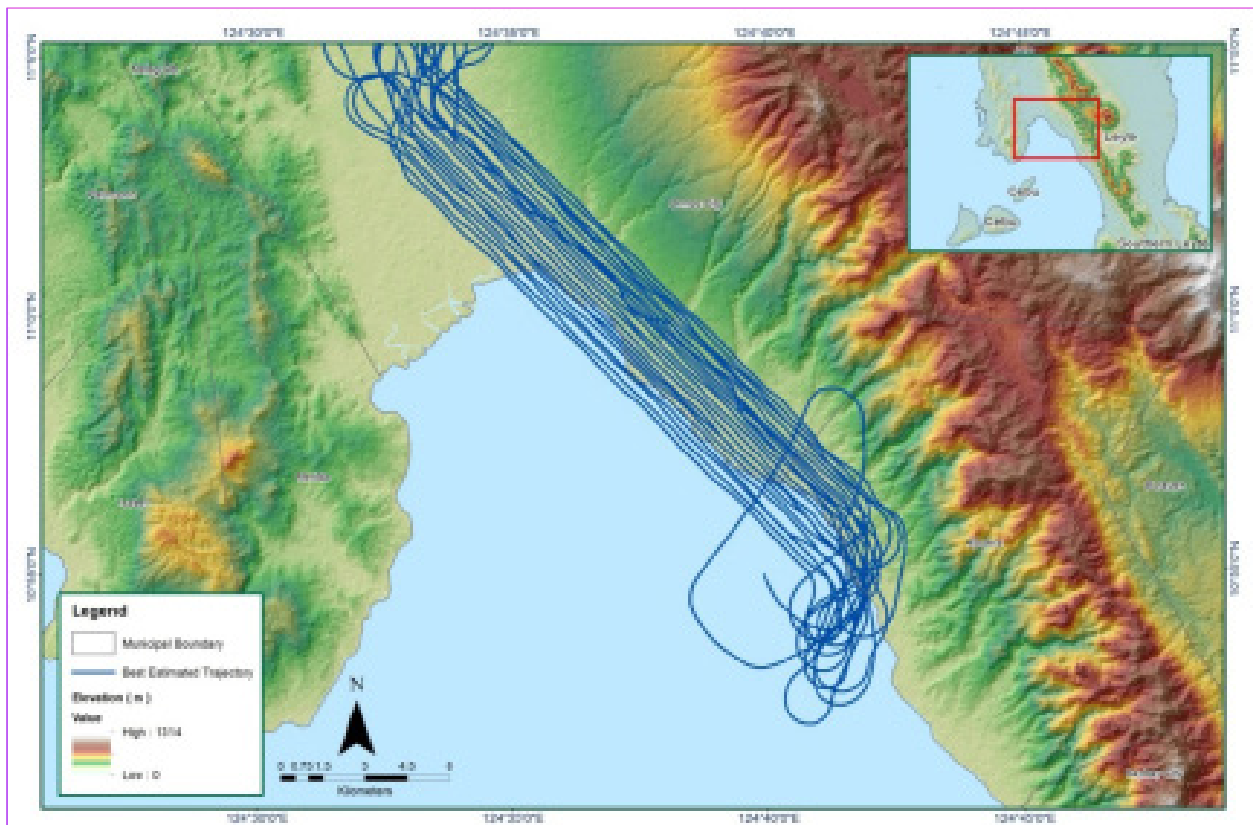


Figure A-8.80. Best Estimated Trajectory

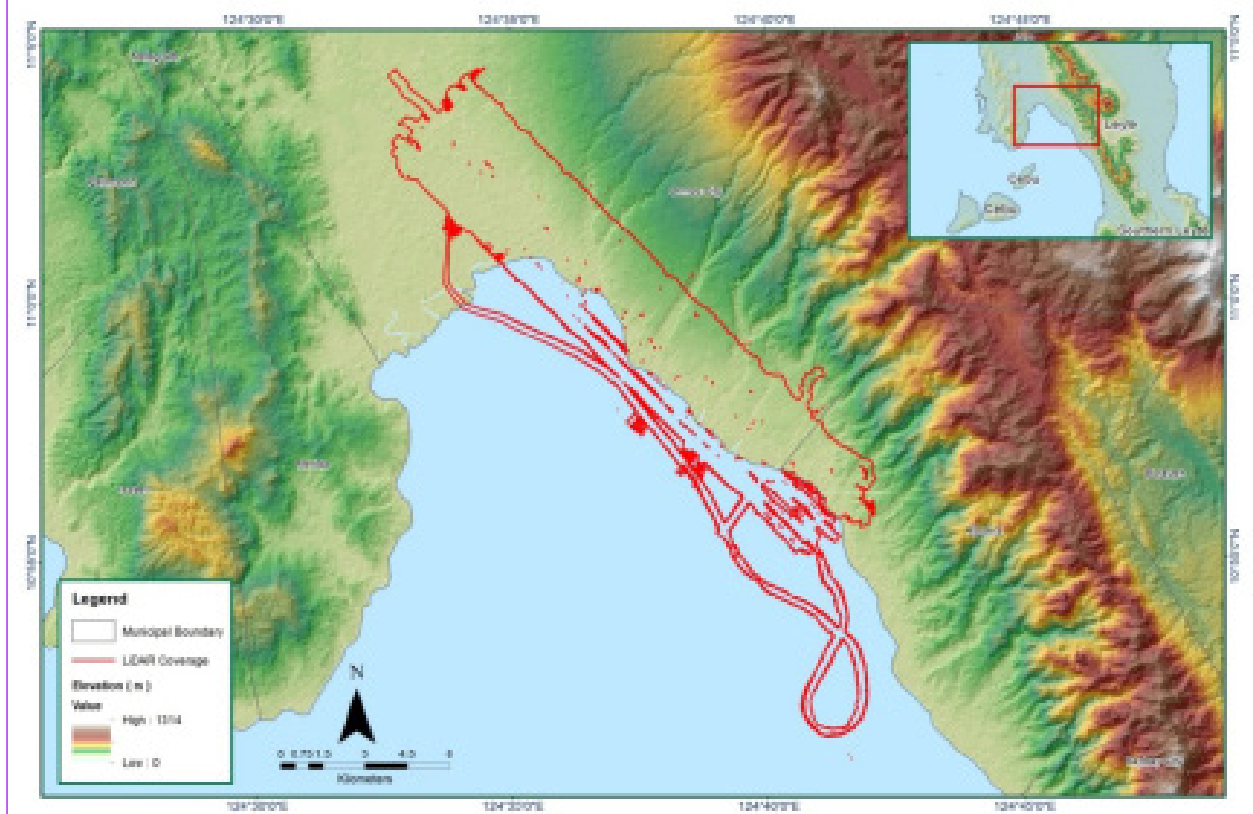


Figure A-8.81. Coverage of LiDAR data

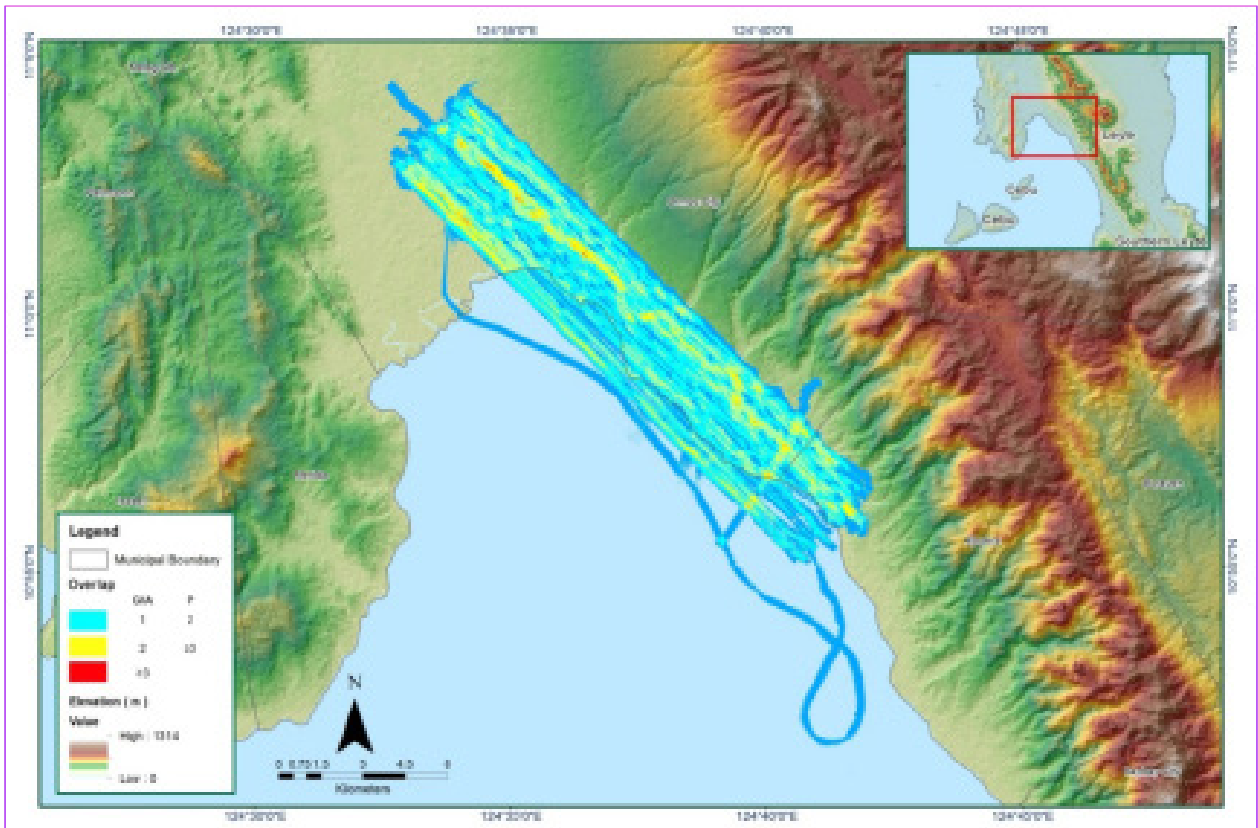


Figure A-8.82. Image of data overlap

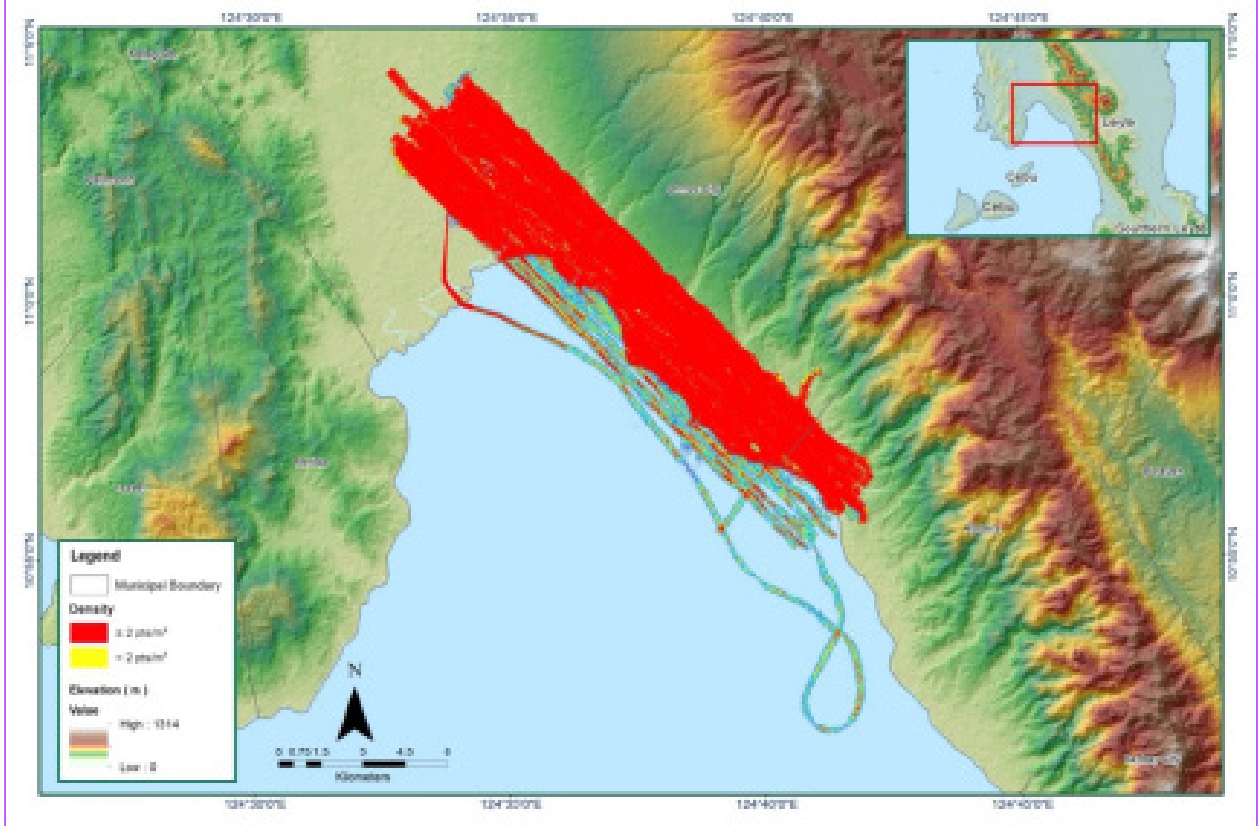


Figure A-8.83. Density map of merged LiDAR data

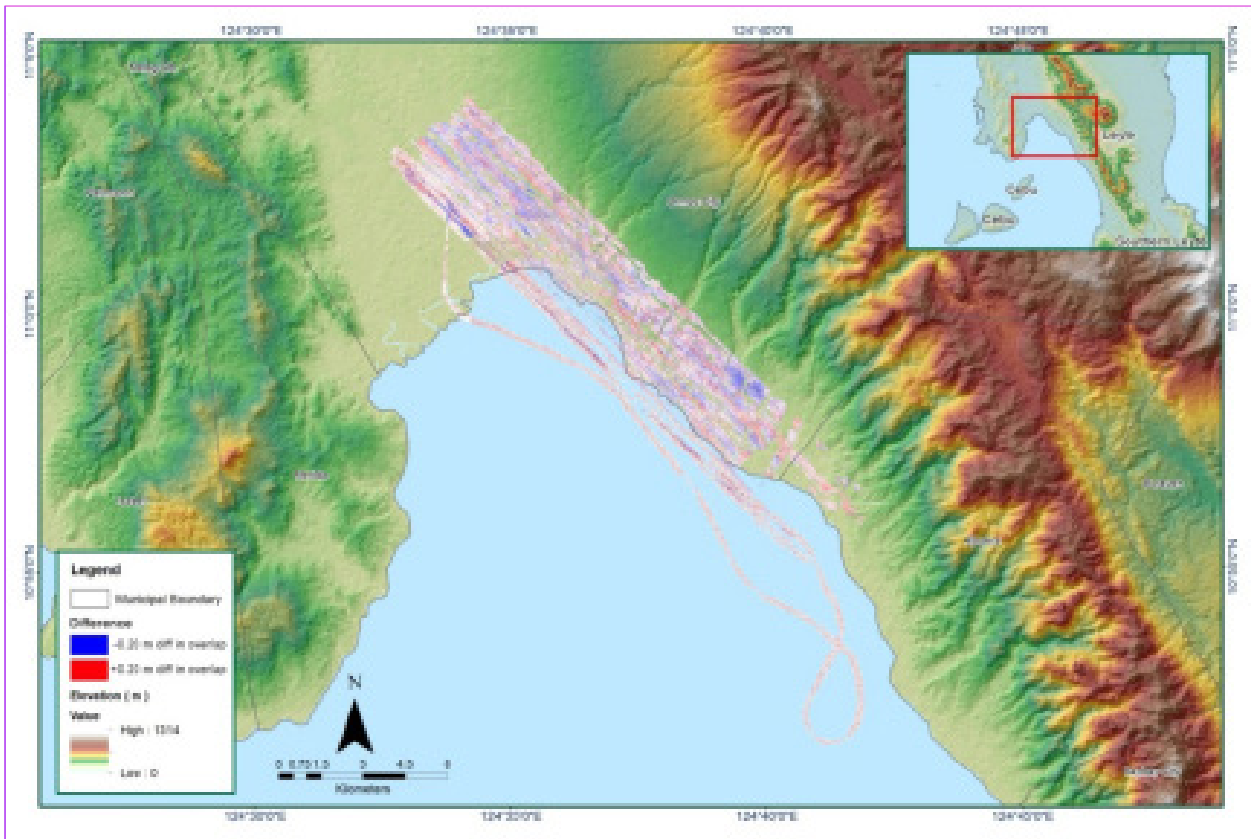


Figure A-8.84. Elevation difference between flight lines

Table A-8.13. Mission Summary Report for Mission Blk35B

Flight Area	Ormoc
<b>Mission Name</b>	Blk35B
<b>Inclusive Flights</b>	7753AC
<b>Range data size</b>	11.1 GB
<b>POS</b>	167 MB
<b>Image</b>	0 GB
<b>Transfer date</b>	March 9 2015
<b>Solution Status</b>	
<b>Number of Satellites (&gt;6)</b>	No
<b>PDOP (&lt;3)</b>	Yes
<b>Baseline Length (&lt;30km)</b>	Yes
<b>Processing Mode (&lt;=1)</b>	No
<b>Smoothed Performance Metrics (in cm)</b>	
<b>RMSE for North Position (&lt;4.0 cm)</b>	1.75
<b>RMSE for East Position (&lt;4.0 cm)</b>	1.37
<b>RMSE for Down Position (&lt;8.0 cm)</b>	3.50
<b>Boresight correction stdev (&lt;0.001deg)</b>	0.000324
<b>IMU attitude correction stdev (&lt;0.001deg)</b>	0.001085
<b>GPS position stdev (&lt;0.01m)</b>	0.0103
<b>Minimum % overlap (&gt;25)</b>	57.13
<b>Ave point cloud density per sq.m. (&gt;2.0)</b>	3.49
<b>Elevation difference between strips (&lt;0.20 m)</b>	Yes
<b>Number of 1km x 1km blocks</b>	110
<b>Maximum Height</b>	425.68 m
<b>Minimum Height</b>	52.98 m
<b>Classification (# of points)</b>	
<b>Ground</b>	45,306,584
<b>Low vegetation</b>	54,011,189
<b>Medium vegetation</b>	95,593,512
<b>High vegetation</b>	50,856,382
<b>Building</b>	2,030,444
<b>Orthophoto</b>	No
<b>Processed by</b>	Engr. Jommer Medina, Engr. Melanie Hingpit, Engr. Krisha Marie Bautista

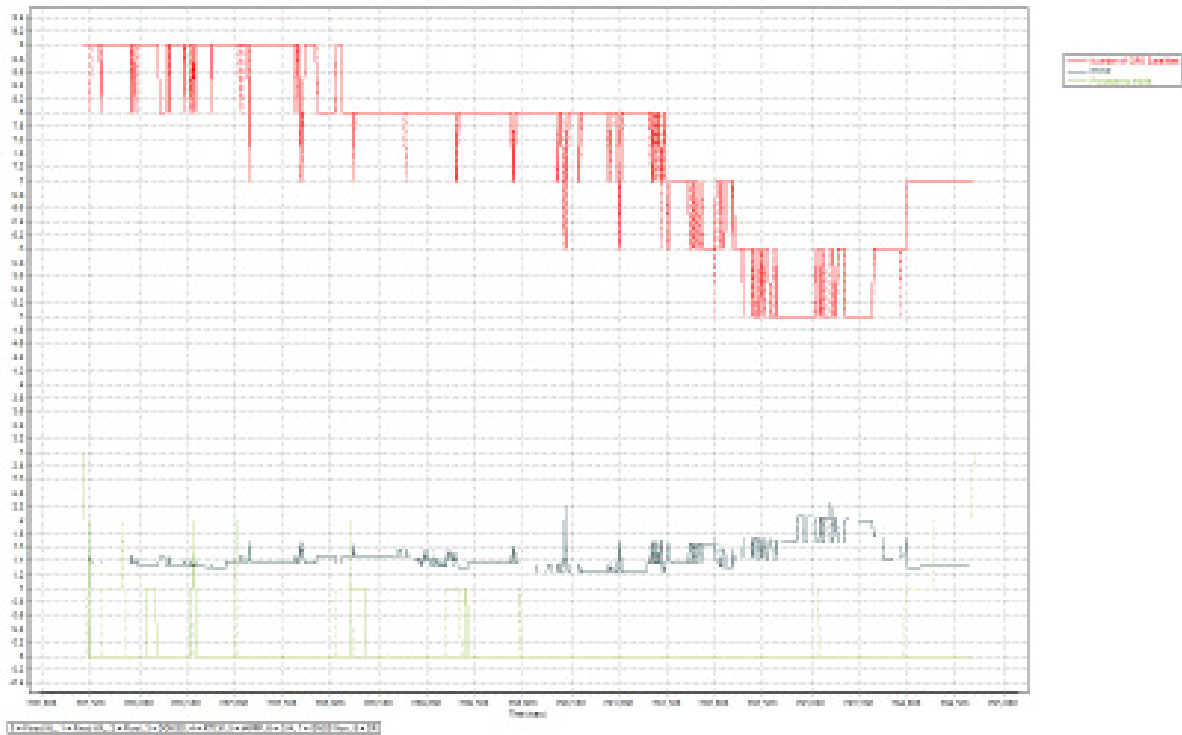


Figure A-8.85. Solution Status

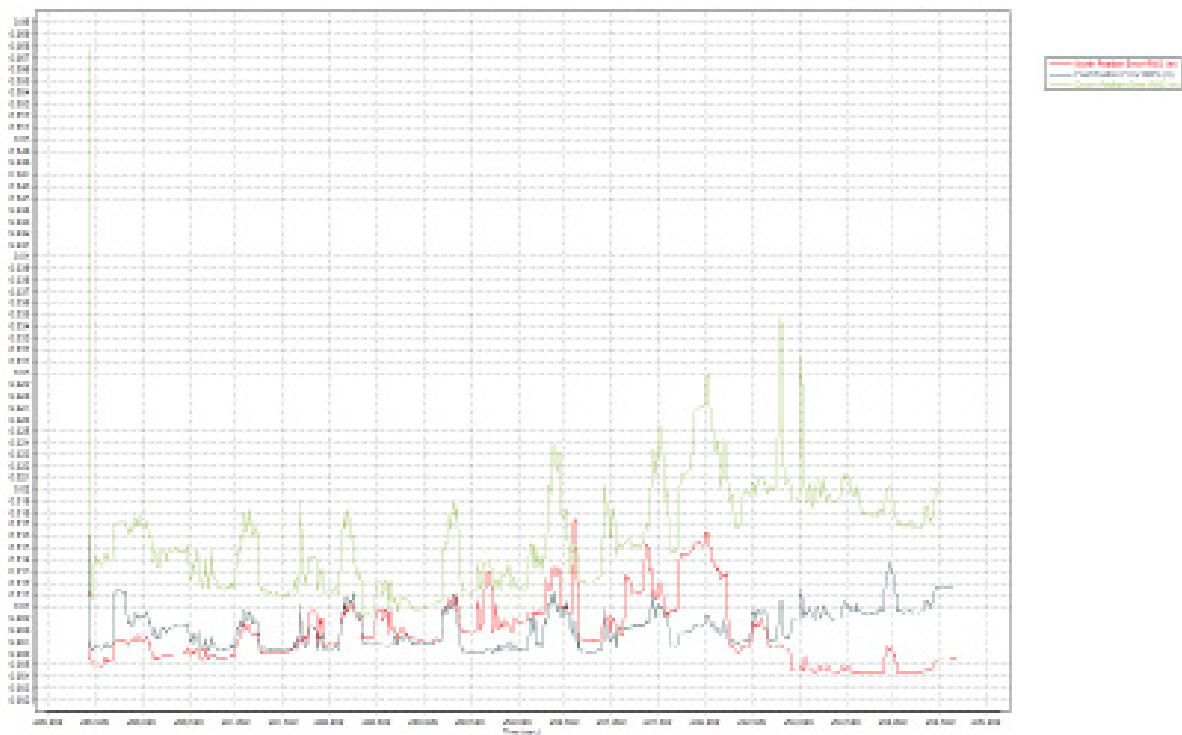


Figure A-8.86. Smoothed Performance Metrics Parameters

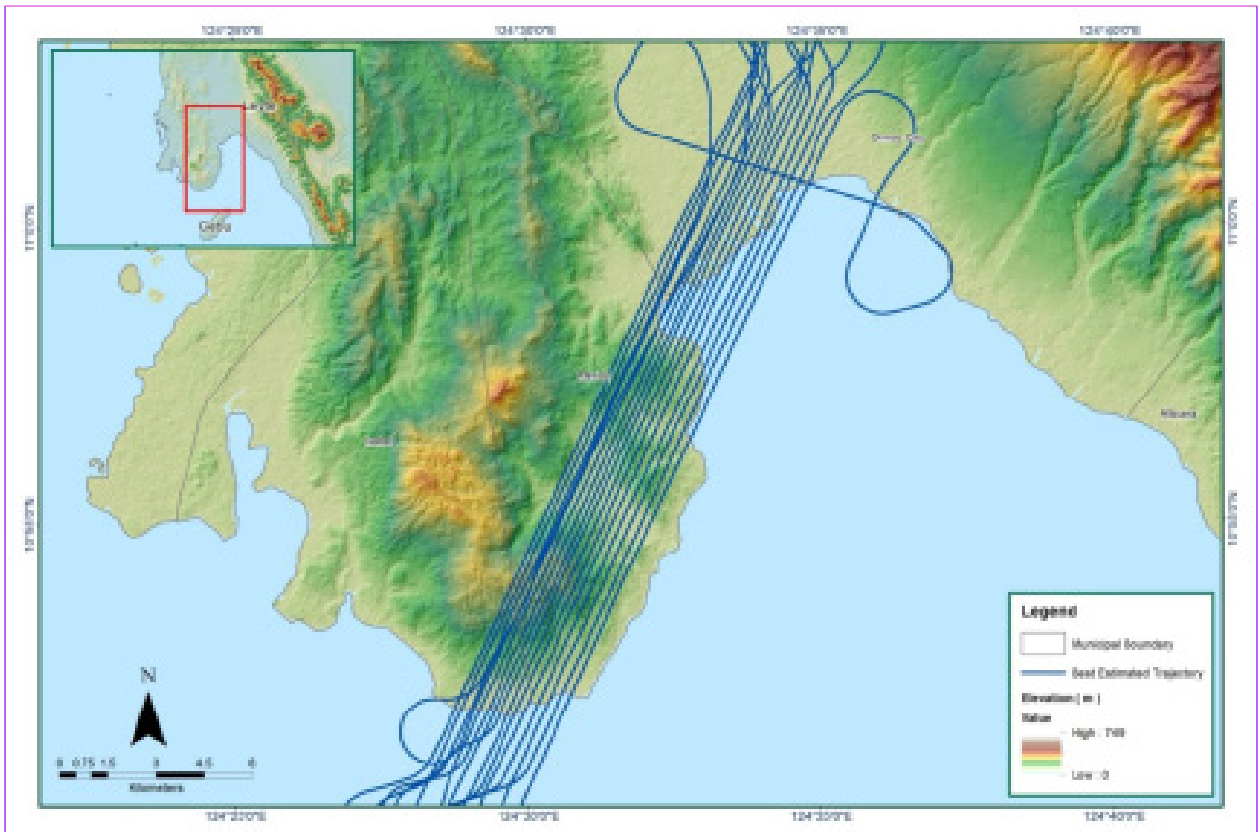


Figure A-8.87. Best Estimated Trajectory

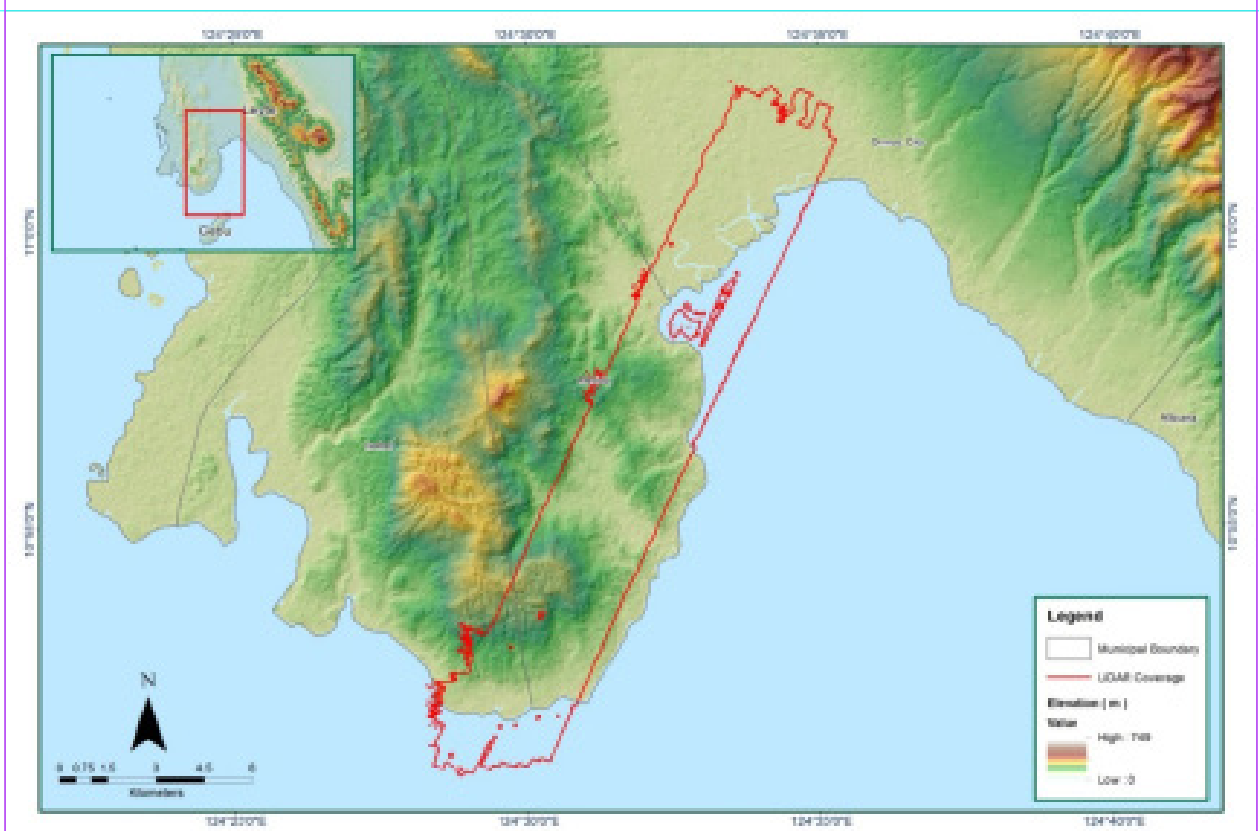


Figure A-8.88. Best Estimated Trajectory



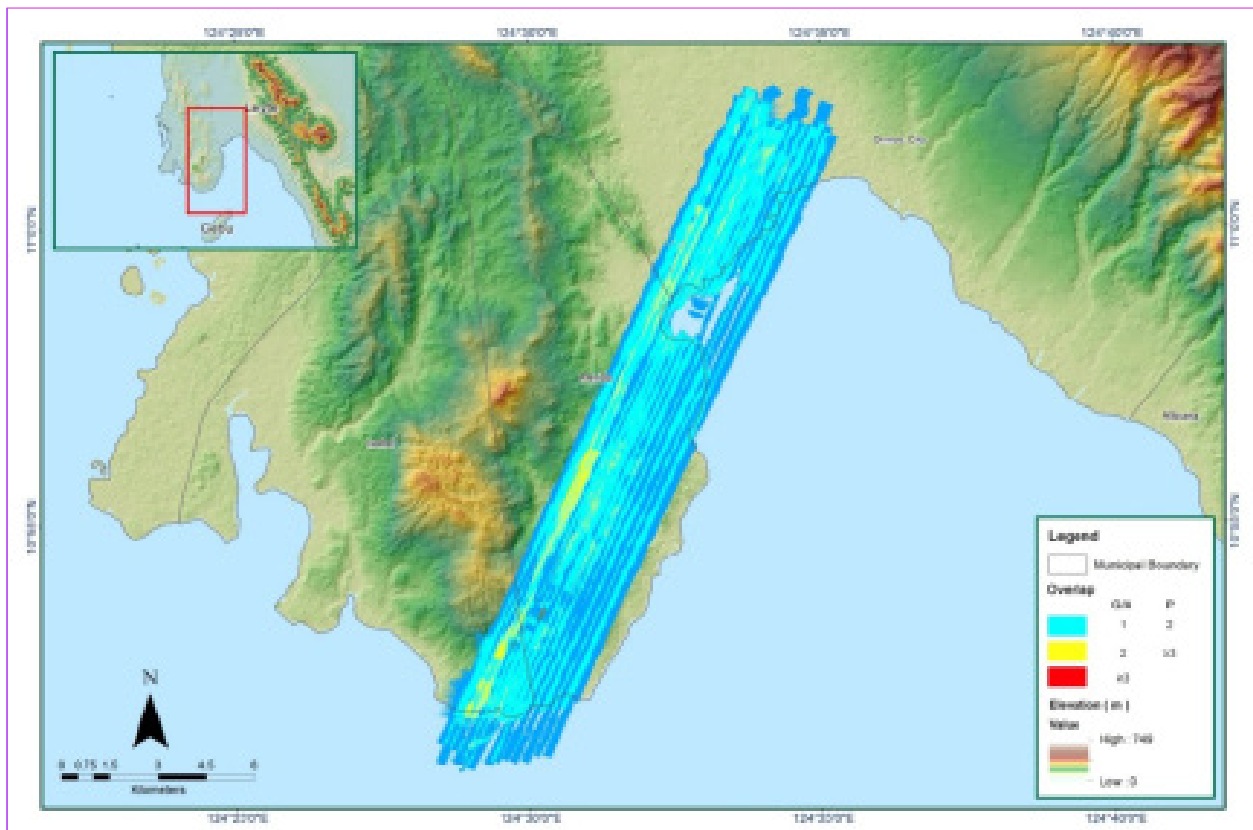


Figure A-8.89. Image of data overlap

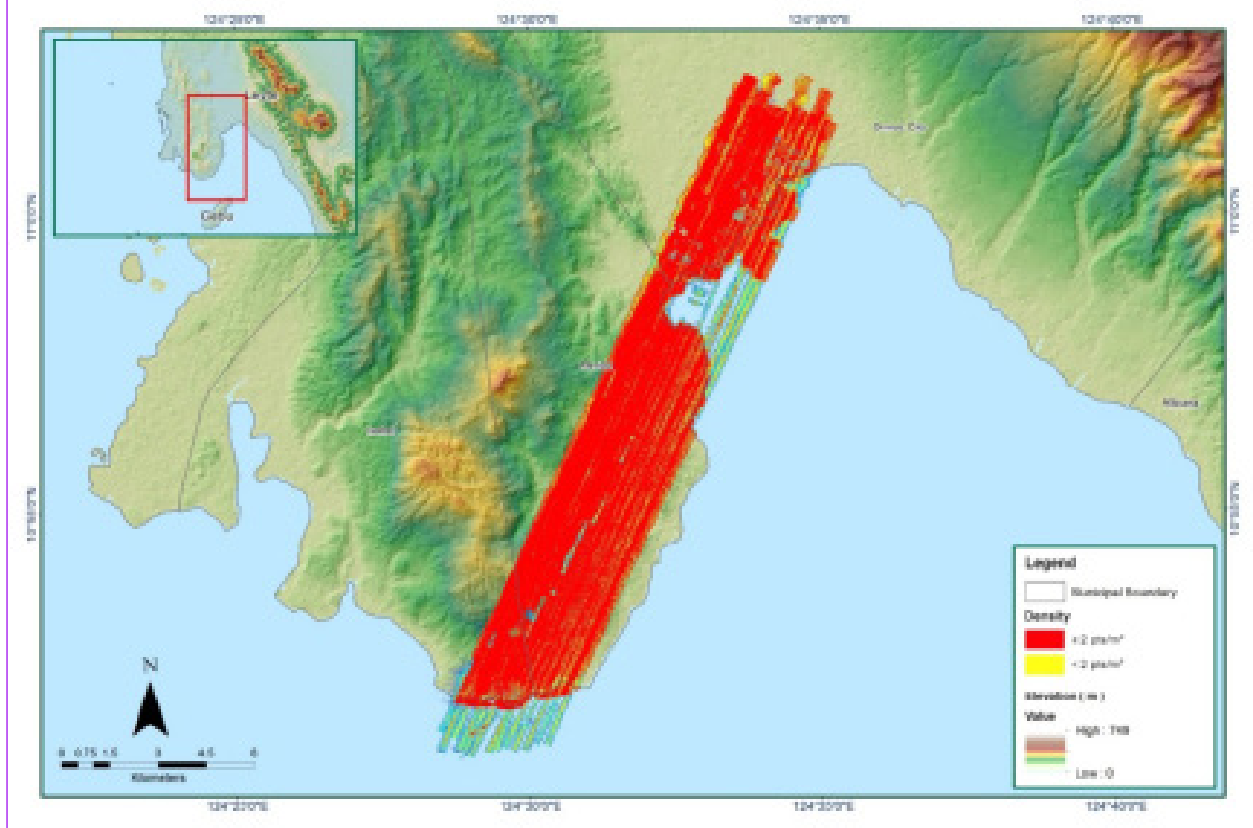


Figure A-8.90. Density map of merged LiDAR data

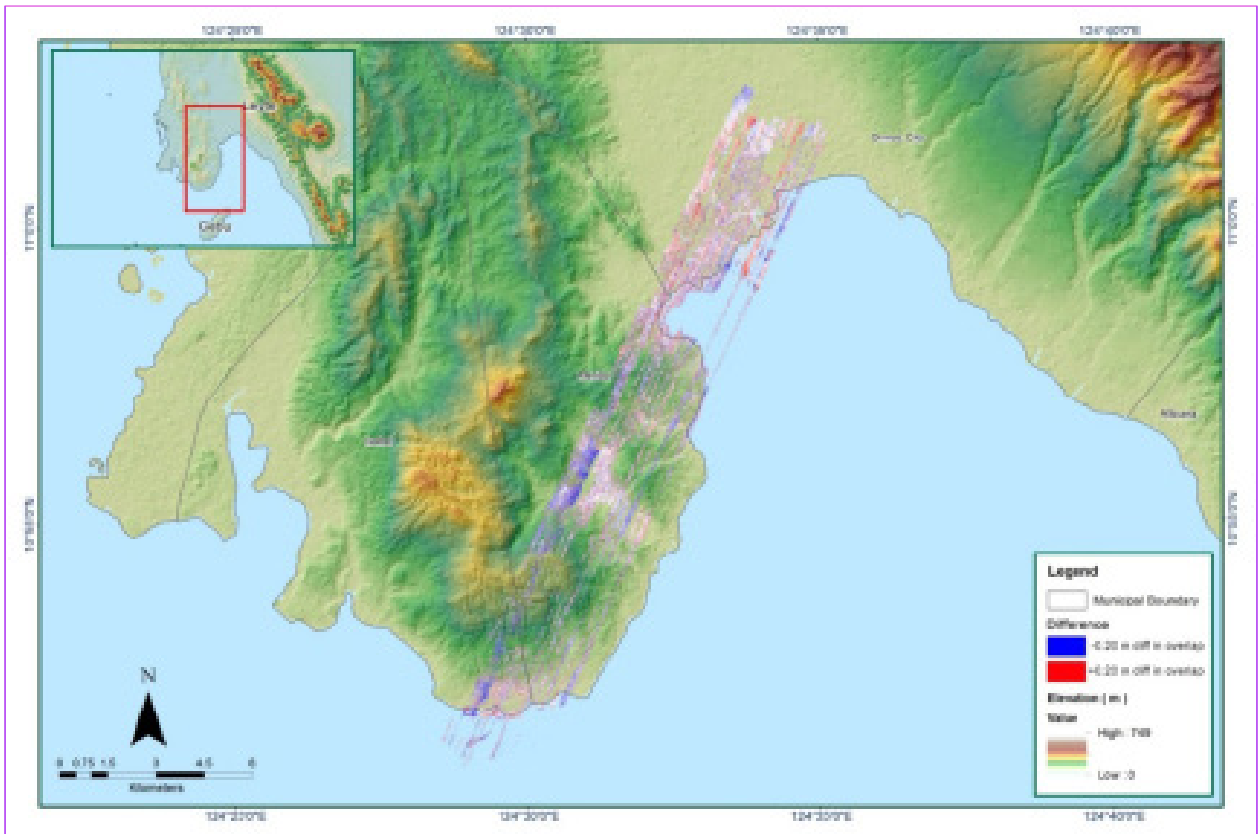


Figure A-8.91. Elevation difference between flight lines

Table A-8.14. Mission Summary Report for Mission Blk35A\_additional

Flight Area	Ormoc
Mission Name	Blk35A_additional
Inclusive Flights	7760AC
Range data size	12.3 GB
POS	243 MB
Image	0 GB
Transfer date	March 9 2015
Solution Status	
Number of Satellites (>6)	Yes
PDOP (<3)	Yes
Baseline Length (<30km)	Yes
Processing Mode (<=1)	No
Smoothed Performance Metrics (in cm)	
RMSE for North Position (<4.0 cm)	1.17
RMSE for East Position (<4.0 cm)	1.48
RMSE for Down Position (<8.0 cm)	3.67
Boresight correction stdev (<0.001deg)	0.000414
IMU attitude correction stdev (<0.001deg)	0.000958
GPS position stdev (<0.01m)	0.0030
Minimum % overlap (>25)	54.20
Ave point cloud density per sq.m. (>2.0)	3.63
Elevation difference between strips (<0.20 m)	Yes
Number of 1km x 1km blocks	116
Maximum Height	389.88 m
Minimum Height	50.29 m
Classification (# of points)	
Ground	42,406,724
Low vegetation	50,448,477
Medium vegetation	104,381,565
High vegetation	58,830,359
Building	2,371,309
Orthophoto	No
Processed by	Engr. Irish Cortez, Engr. Chelou Prado, Kathryn Claudyn Zarate

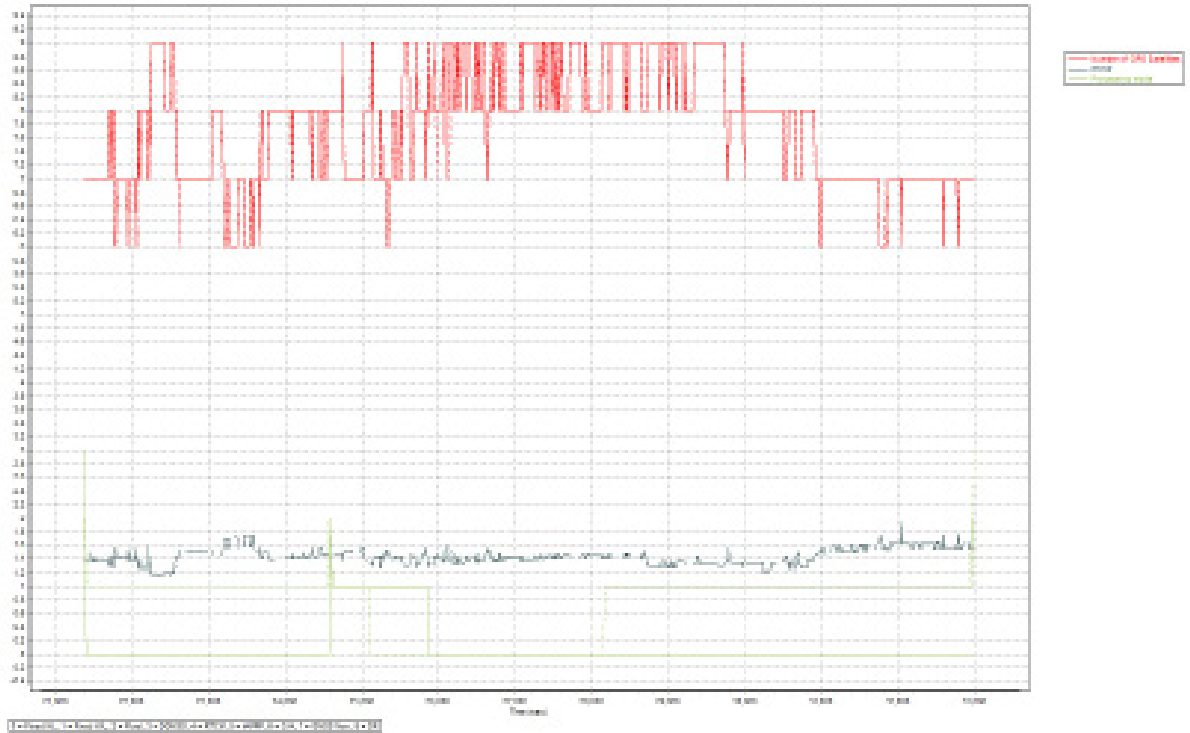


Figure A-8.92. Solution Status

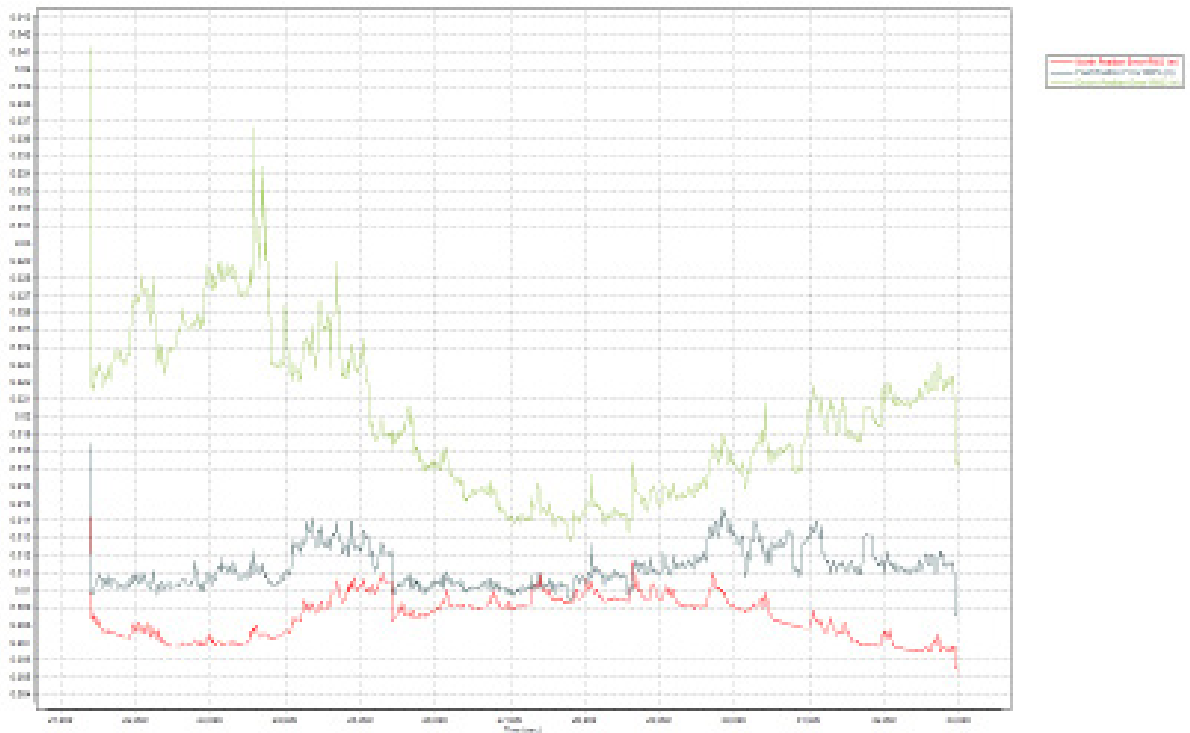


Figure A-8.93. Smoothed Performance Metrics Parameters

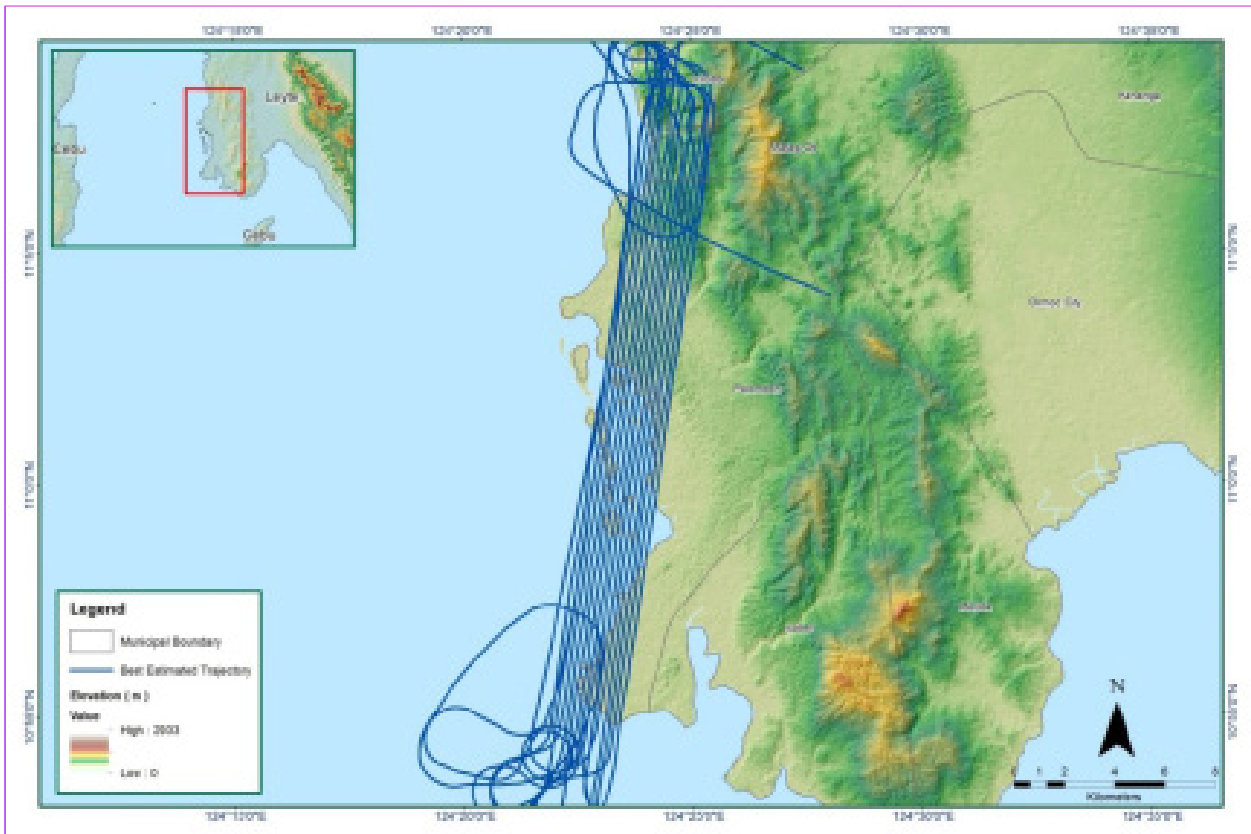


Figure A-8.94. Best Estimated Trajectory

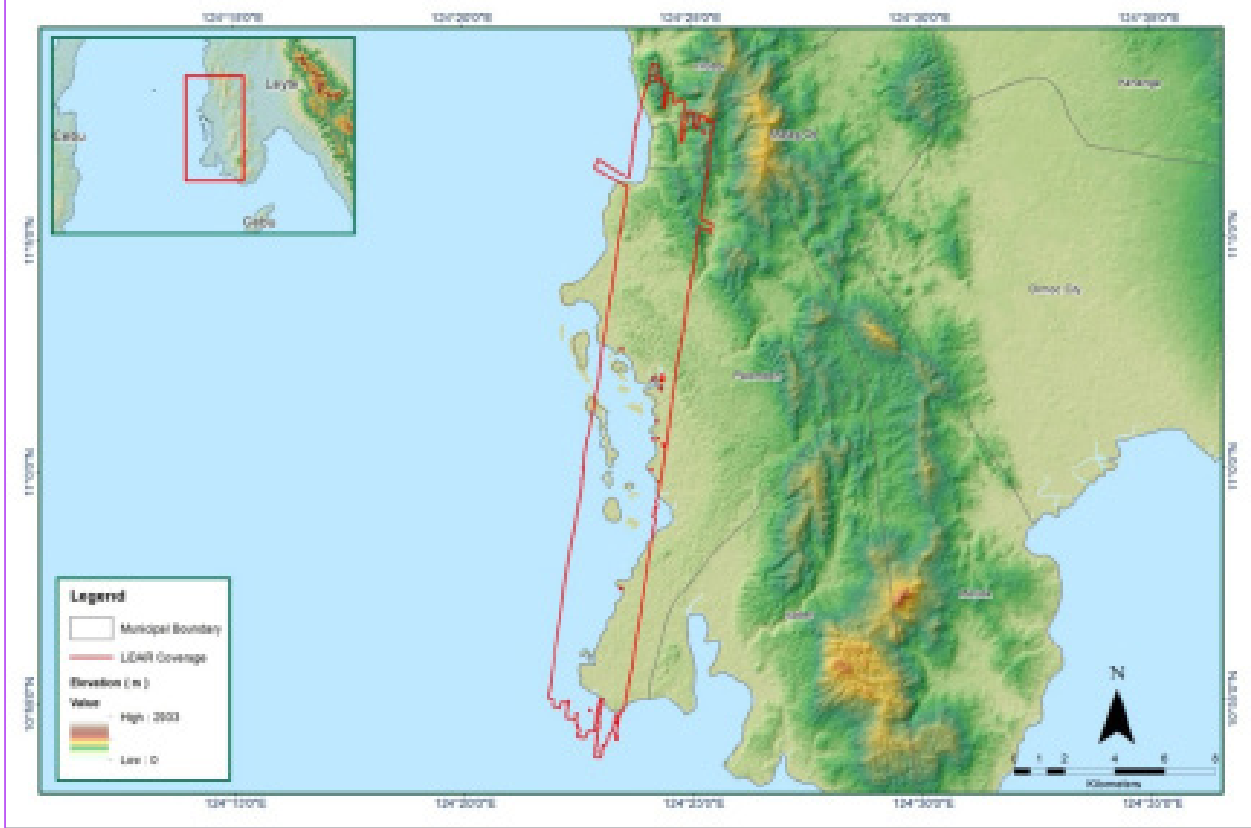


Figure A-8.95. Coverage of LiDAR data

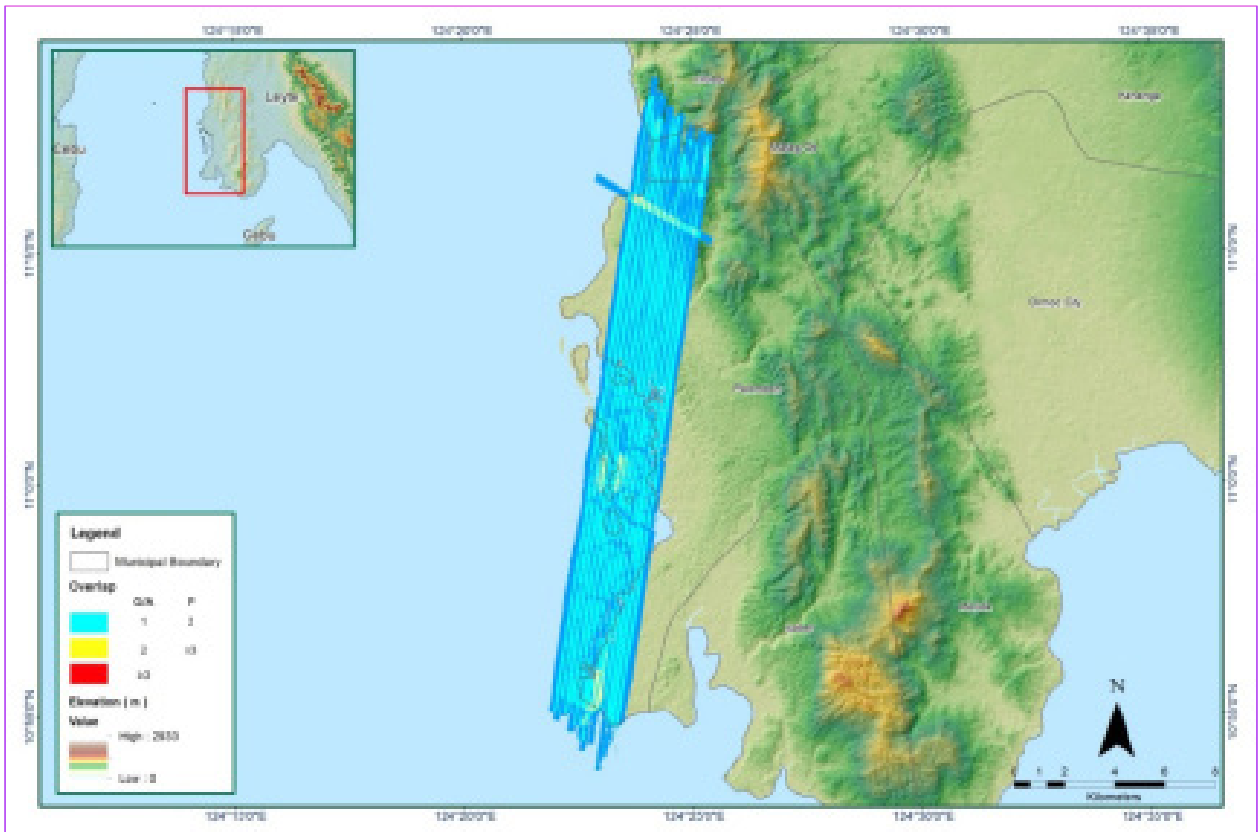


Figure A-8.96. Image of data overlap

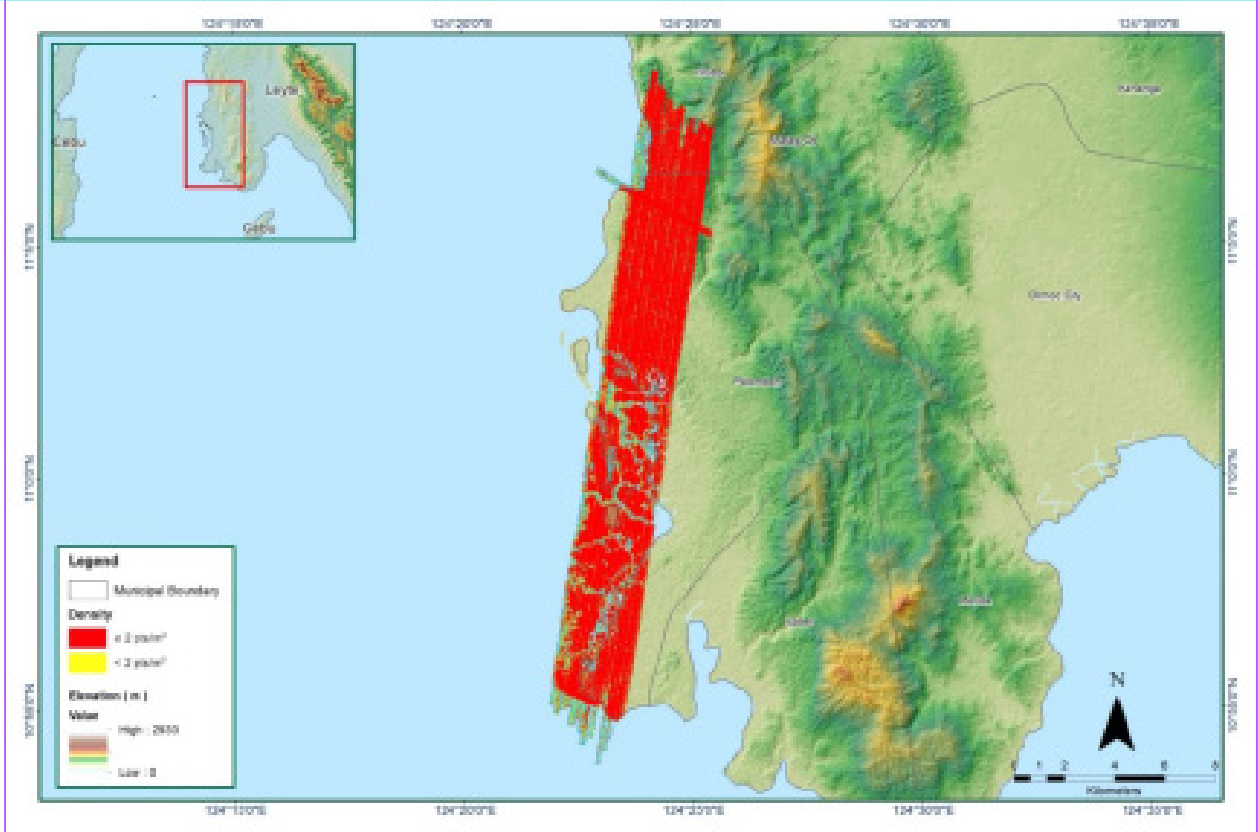


Figure A-8.97. Density map of merged LiDAR data

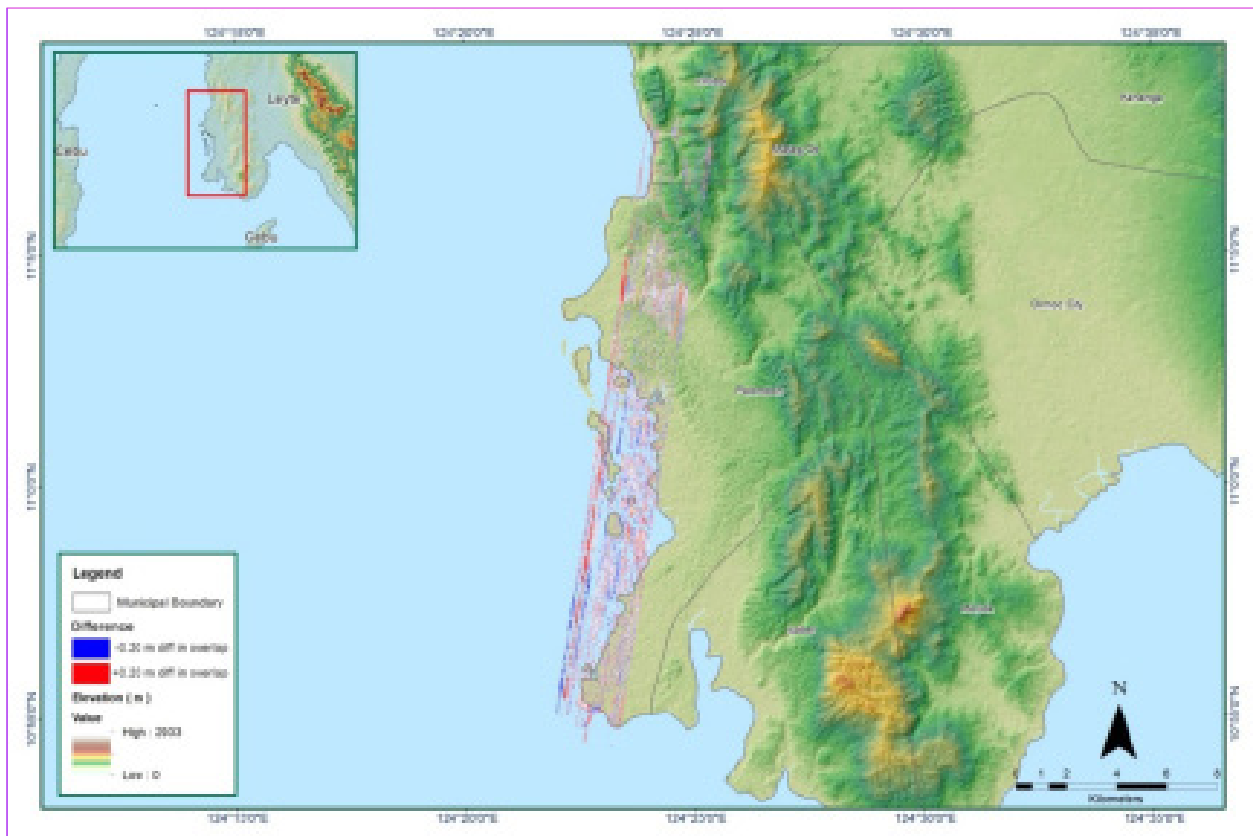


Figure A-8.98. Elevation difference between flight lines

Table A-8.15. Mission Summary Report for Mission Blk35B\_additional

Table A-8.15. Mission Summary Report for Mission Blk35B_additional	
Flight Area	Ormoc
Mission Name	Blk35B_additional
Inclusive Flights	7802AC
Range data size	9.94 GB
POS data size	254 MB
Base data size	35.4 MB
Image	NA
Transfer date	February 25, 2015
Solution Status	
Number of Satellites (>6)	Yes
PDOP (<3)	Yes
Baseline Length (<30km)	Yes
Processing Mode (<=1)	Yes
Smoothed Performance Metrics (in cm)	
RMSE for North Position (<4.0 cm)	2.349
RMSE for East Position (<4.0 cm)	1.998
RMSE for Down Position (<8.0 cm)	2.512
Boresight correction stdev (<0.001deg)	0.000216
IMU attitude correction stdev (<0.001deg)	0
GPS position stdev (<0.01m)	0.0153
Minimum % overlap (>25)	43.97
Ave point cloud density per sq.m. (>2.0)	3.71
Elevation difference between strips (<0.20 m)	Yes
Number of 1km x 1km blocks	61
Maximum Height	399.07
Minimum Height	55.36
Classification (# of points)	
Ground	14,773,181
Low vegetation	13,469,860
Medium vegetation	34,698,250
High vegetation	19,171,212
Building	948,615
Orthophoto	None
Processed by	Engr. Regis Guhiting, Engr. Erica Erin Elazegui, Alex John Escobido



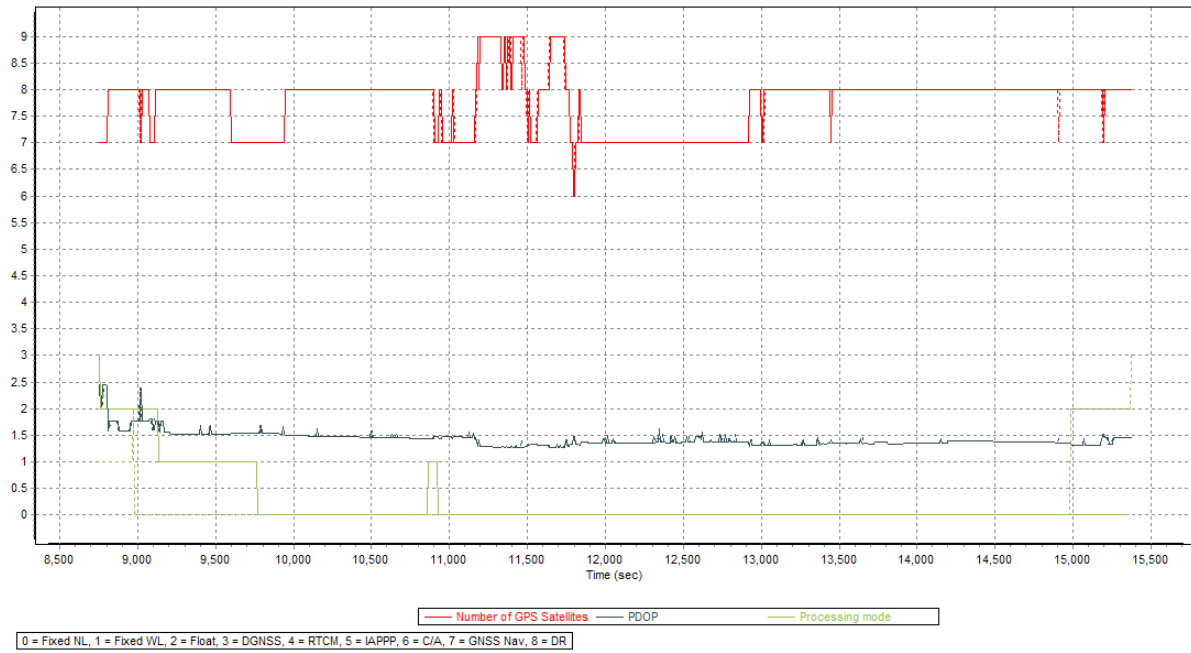


Figure A-8.99. Solution Status

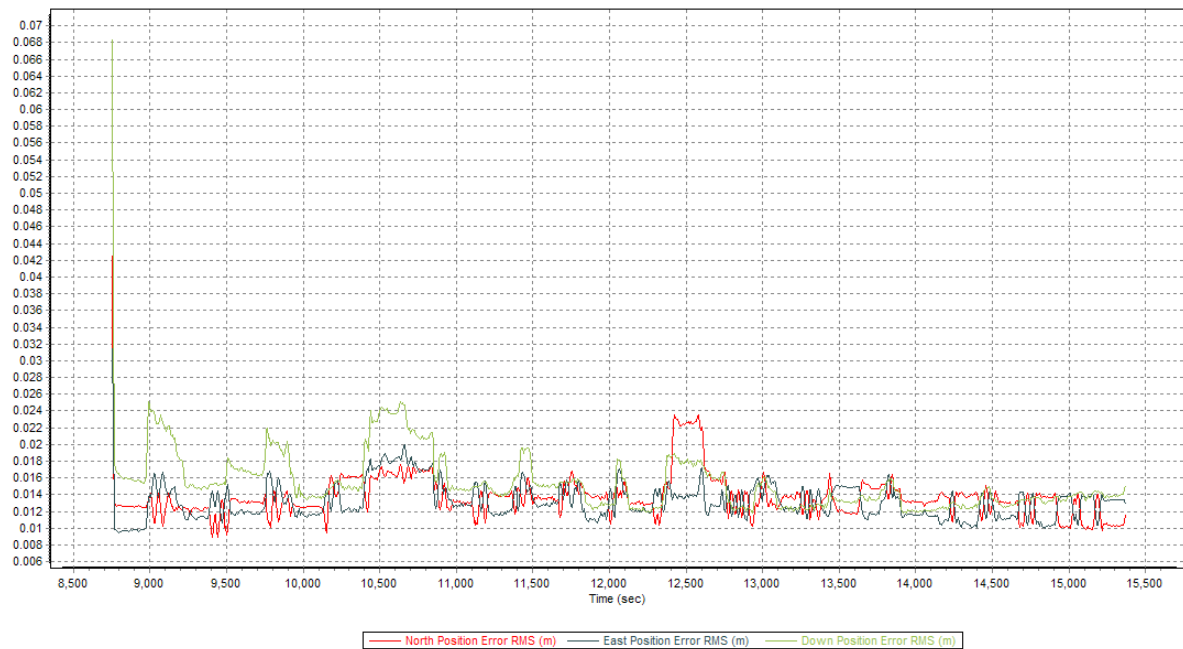


Figure A-8.100. Smoothed Performance Metrics Parameters

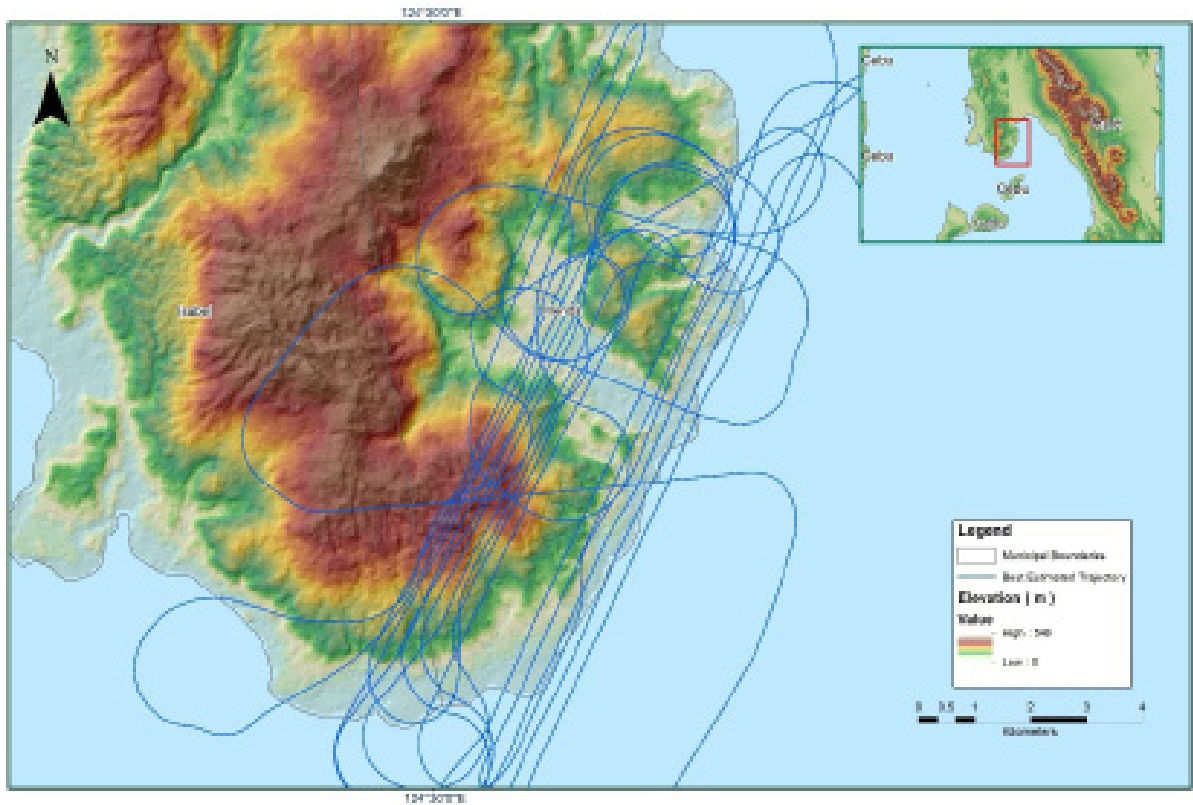


Figure A-8.101. Best Estimated Trajectory

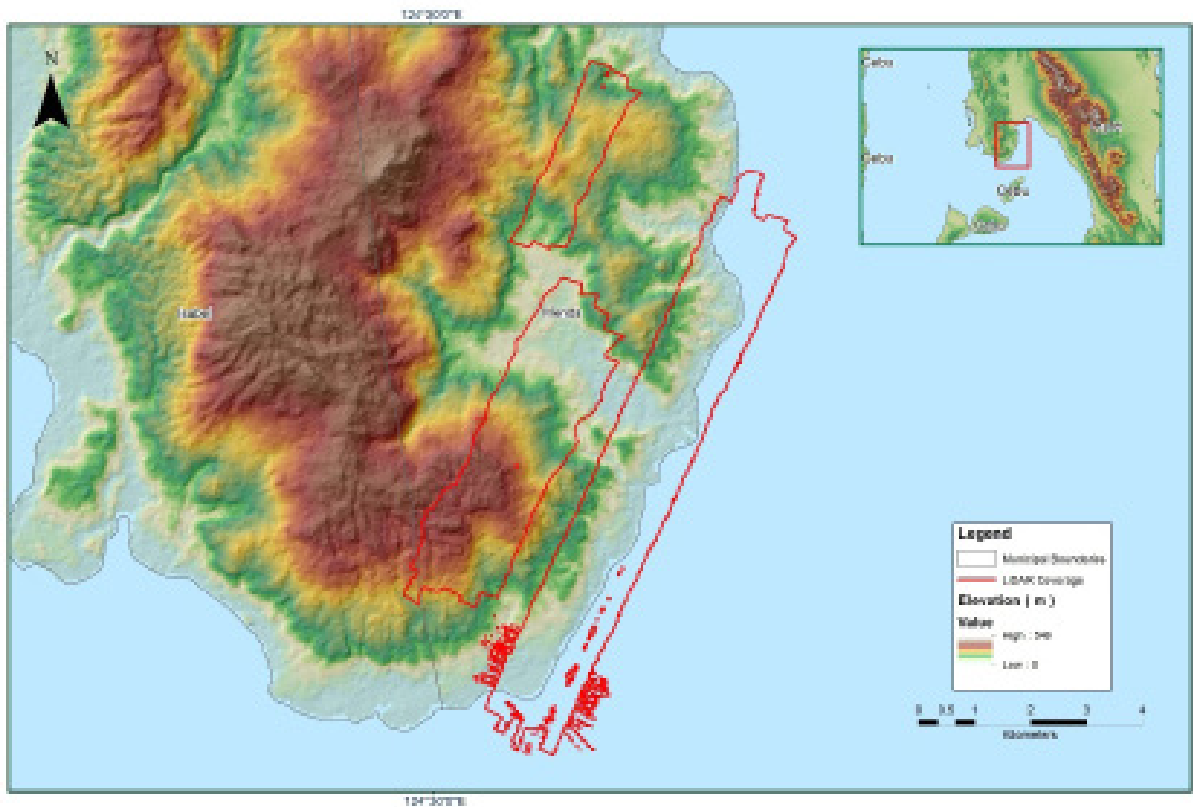


Figure A-8.102. Best Estimated Trajectory

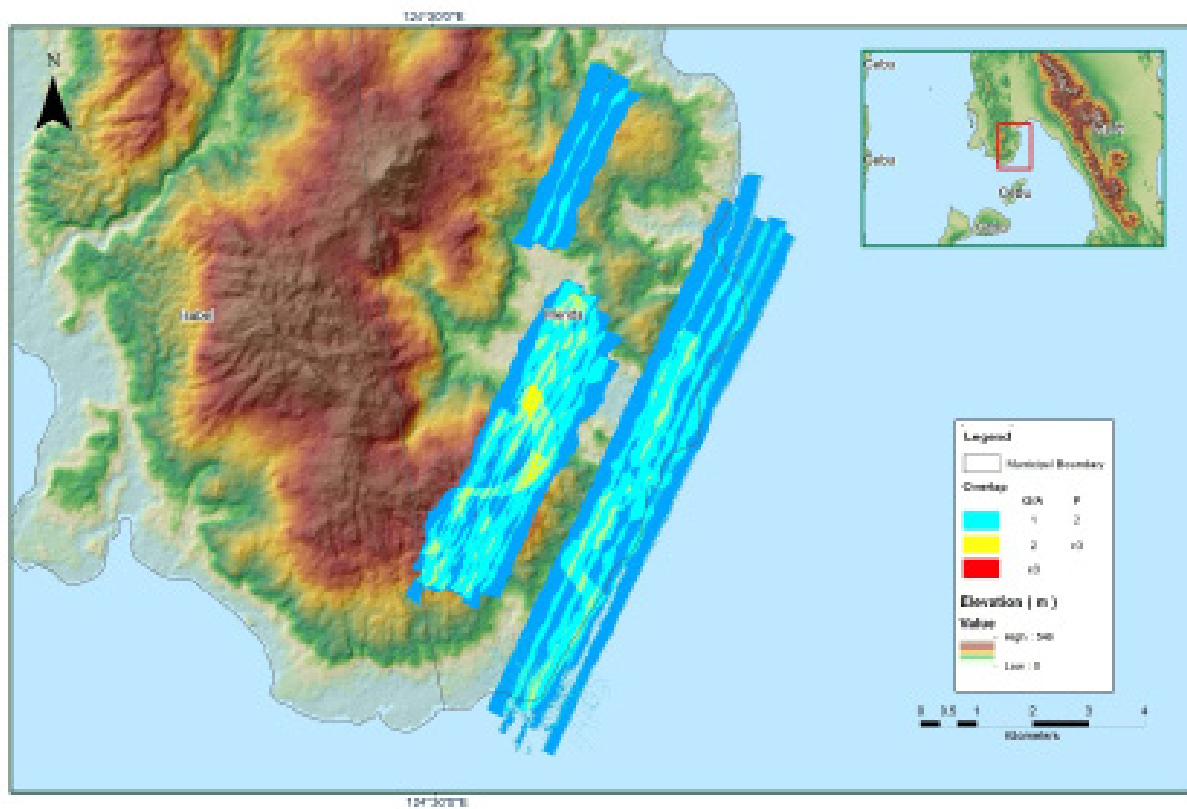


Figure A-8.103. Image of data overlap

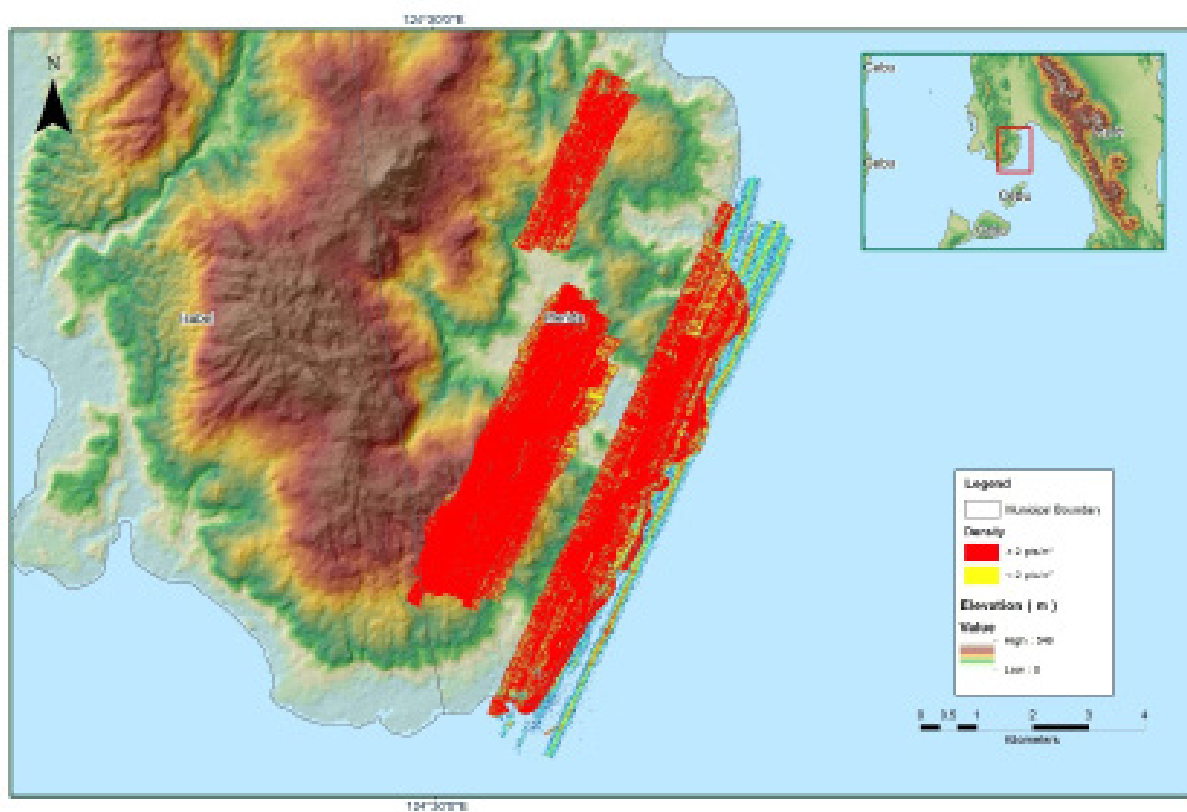


Figure A-8.104. Density map of merged LiDAR data

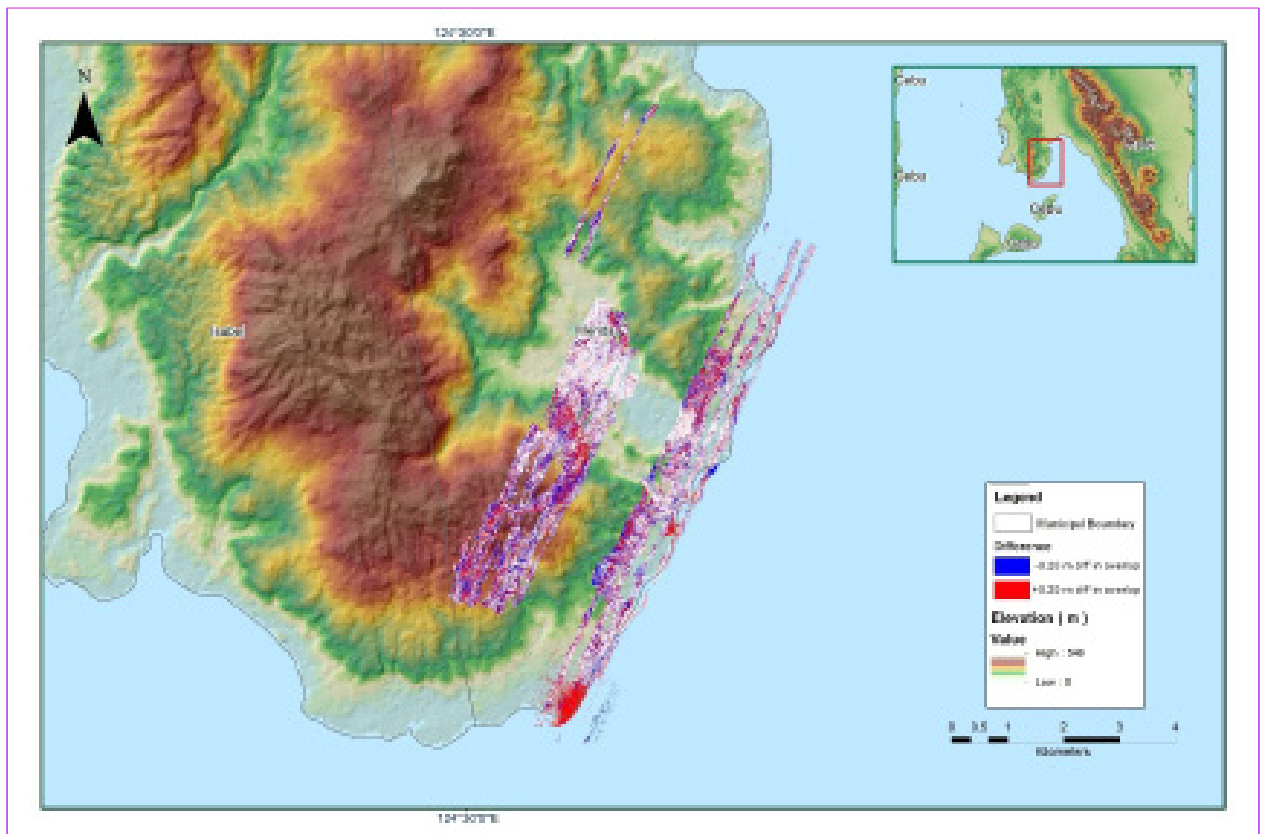


Table A-8.16. Mission Summary Report for Mission Blk35CD\_additional

<b>Flight Area</b>	<b>Ormoc</b>
<b>Mission Name</b>	Blk35CD_additional
<b>Inclusive Flights</b>	7806AC
<b>Range data size</b>	8.2 GB
<b>POS data size</b>	195 MB
<b>Base data size</b>	27 MB
<b>Image</b>	NA
<b>Transfer date</b>	February 25, 2015
<b>Solution Status</b>	
<b>Number of Satellites (&gt;6)</b>	Yes
<b>PDOP (&lt;3)</b>	Yes
<b>Baseline Length (&lt;30km)</b>	Yes
<b>Processing Mode (&lt;=1)</b>	Yes
<b>Smoothed Performance Metrics (in cm)</b>	
<b>RMSE for North Position (&lt;4.0 cm)</b>	4.103
<b>RMSE for East Position (&lt;4.0 cm)</b>	5.754
<b>RMSE for Down Position (&lt;8.0 cm)</b>	7.546
<b>Boresight correction stdev (&lt;0.001deg)</b>	0.000271
<b>IMU attitude correction stdev (&lt;0.001deg)</b>	0.000619
<b>GPS position stdev (&lt;0.01m)</b>	0.0071
<b>Minimum % overlap (&gt;25)</b>	19.58
<b>Ave point cloud density per sq.m. (&gt;2.0)</b>	2.34
<b>Elevation difference between strips (&lt;0.20 m)</b>	Yes
<b>Number of 1km x 1km blocks</b>	19
<b>Maximum Height</b>	294.94
<b>Minimum Height</b>	75.43
<b>Classification (# of points)</b>	
<b>Ground</b>	2,556,122
<b>Low vegetation</b>	1,524,276
<b>Medium vegetation</b>	4,461,264
<b>High vegetation</b>	3,251,822
<b>Building</b>	31,704
<b>Orthophoto</b>	None
<b>Processed by</b>	Engr. Abigail Joy Ching, Engr. Melanie Hingpit, Engr. Melissa Fernandez

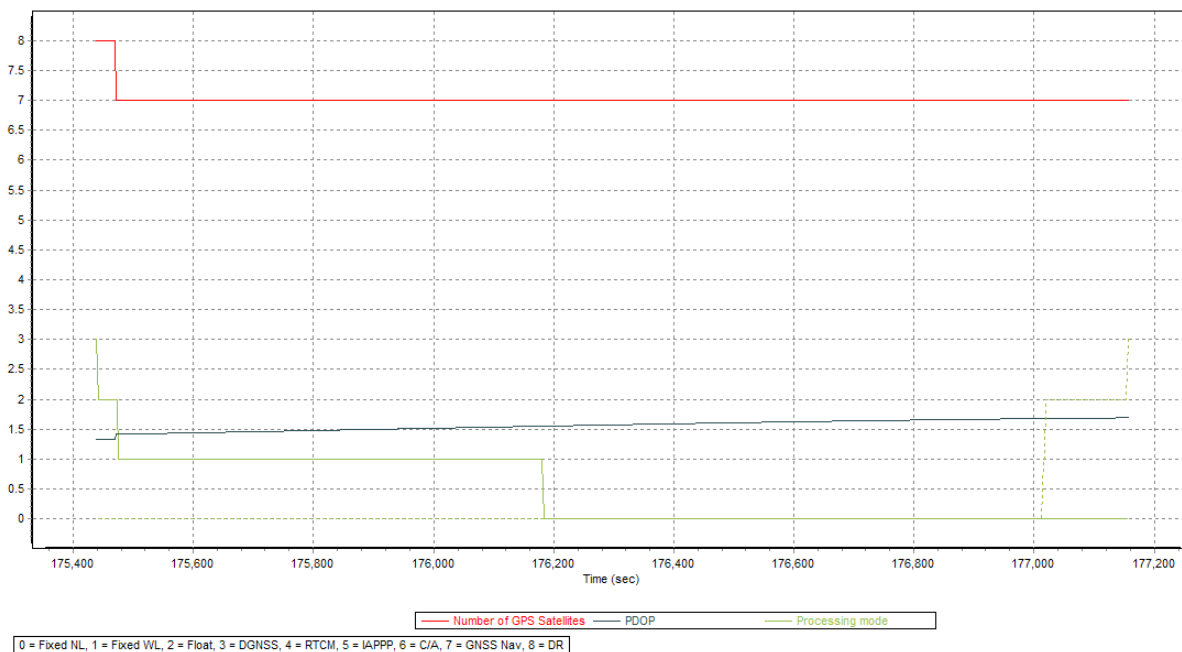


Figure A-8.106. Solution Status

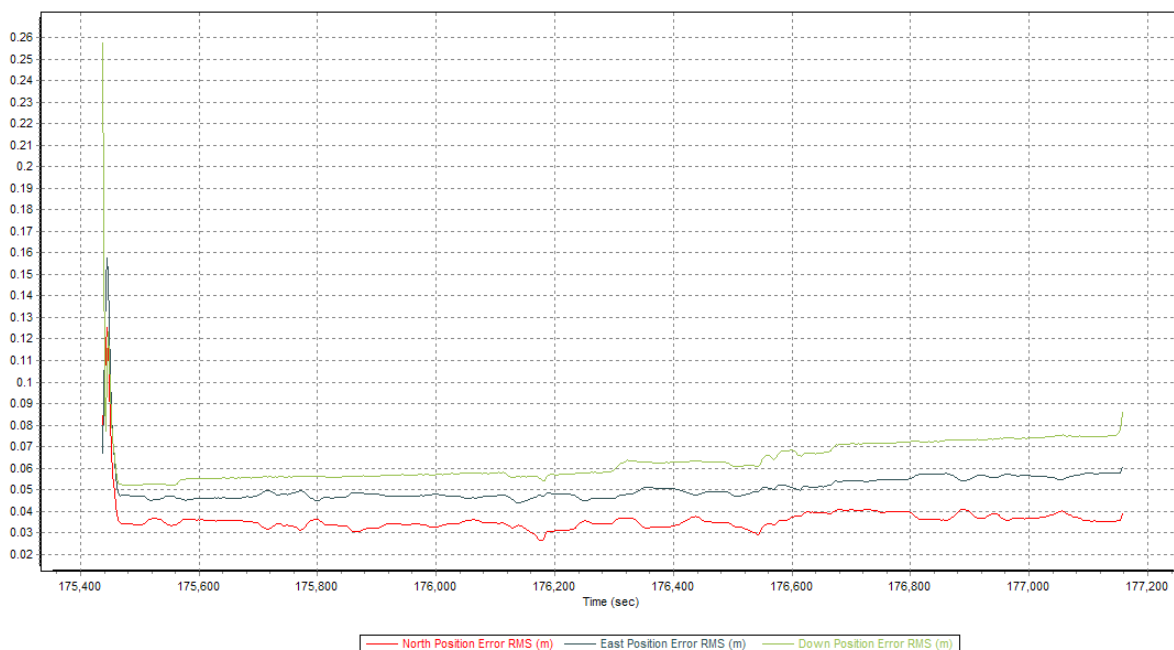


Figure A-8.107. Smoothed Performance Metrics Parameters

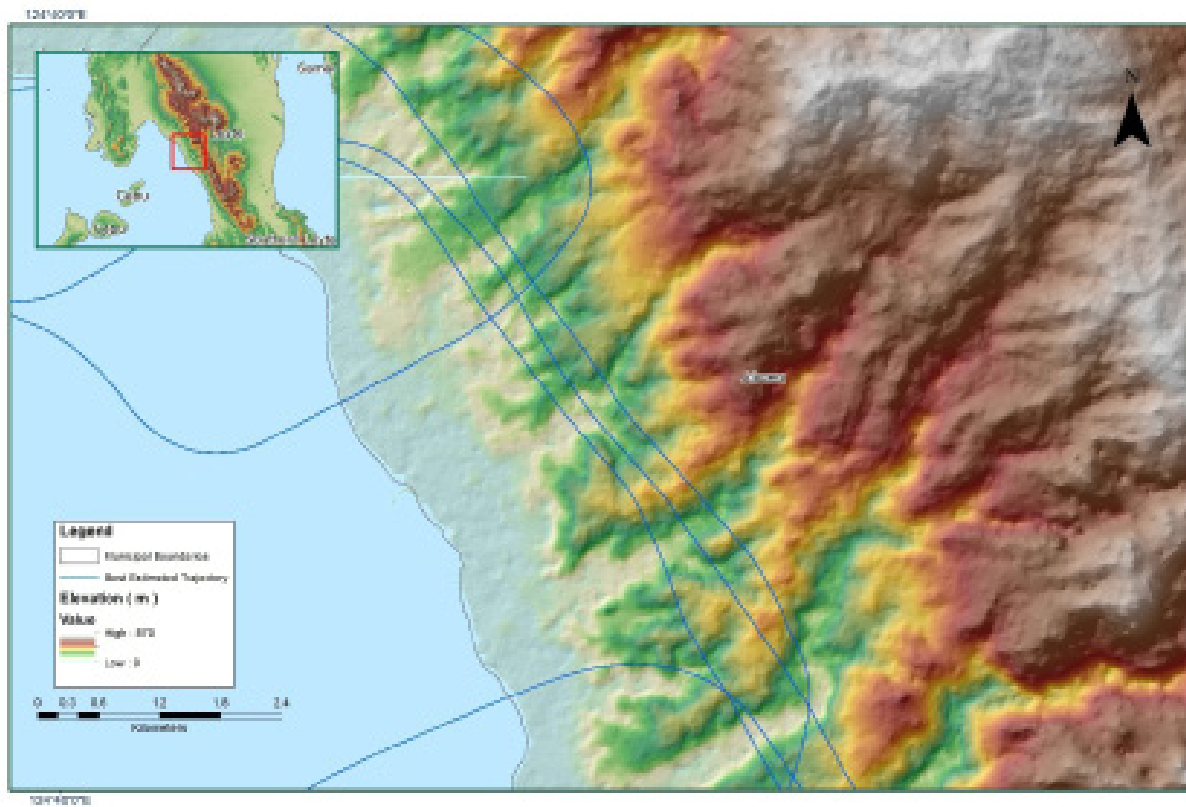


Figure A-8.108. Best Estimated Trajectory

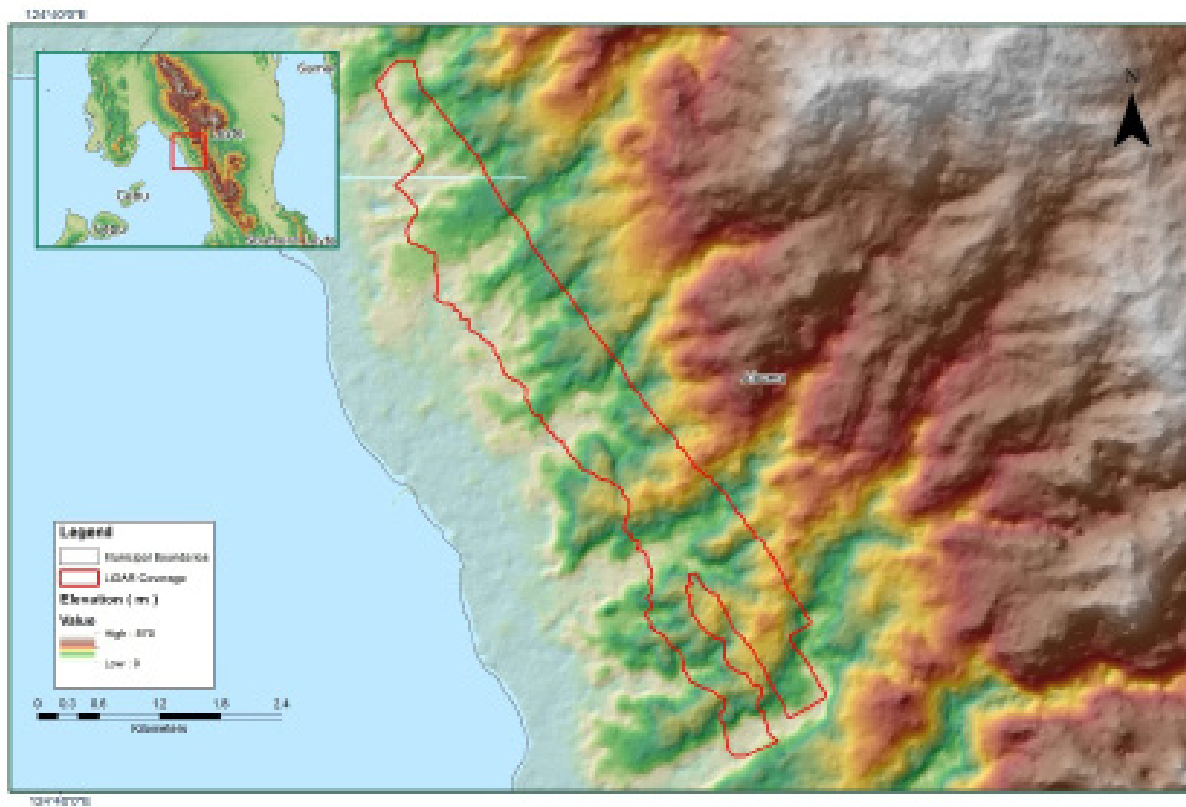


Figure A-8.109. Coverage of LiDAR data

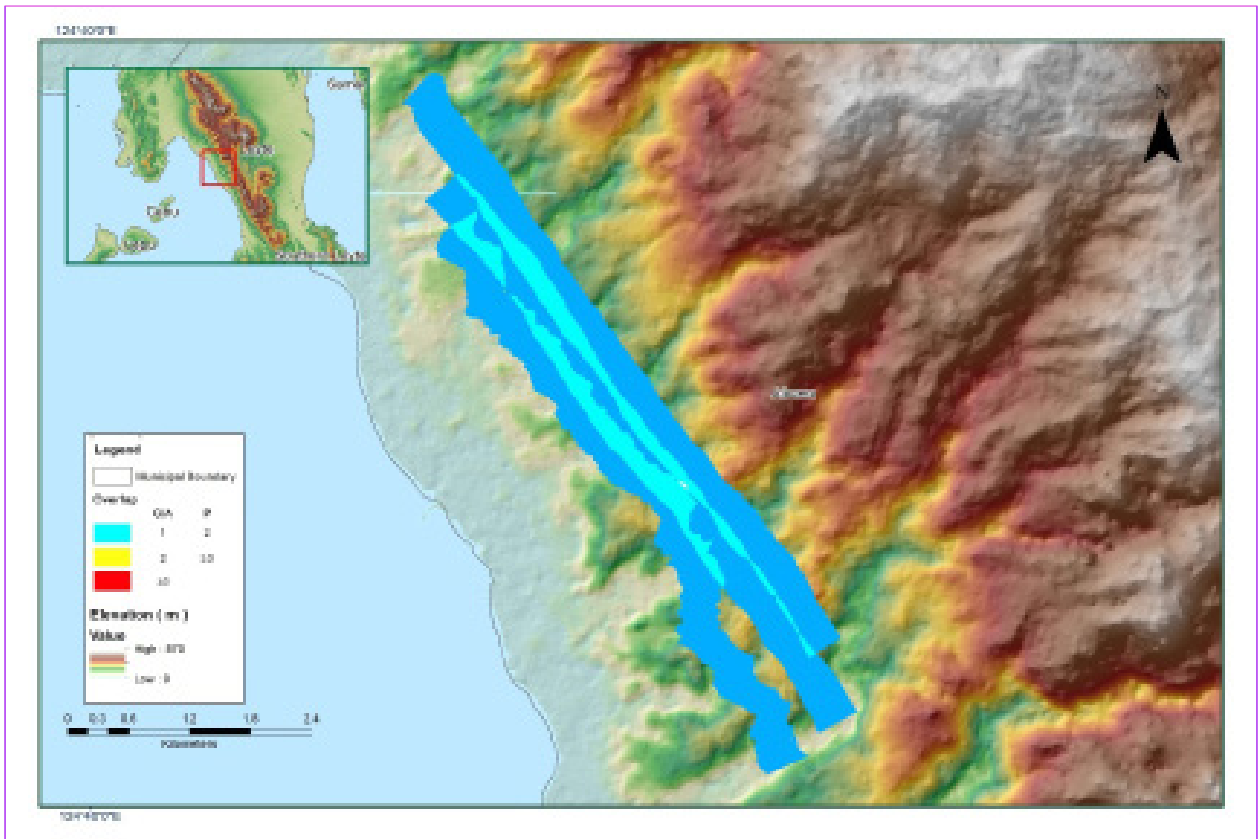


Figure A-8.III. Image of data overlap

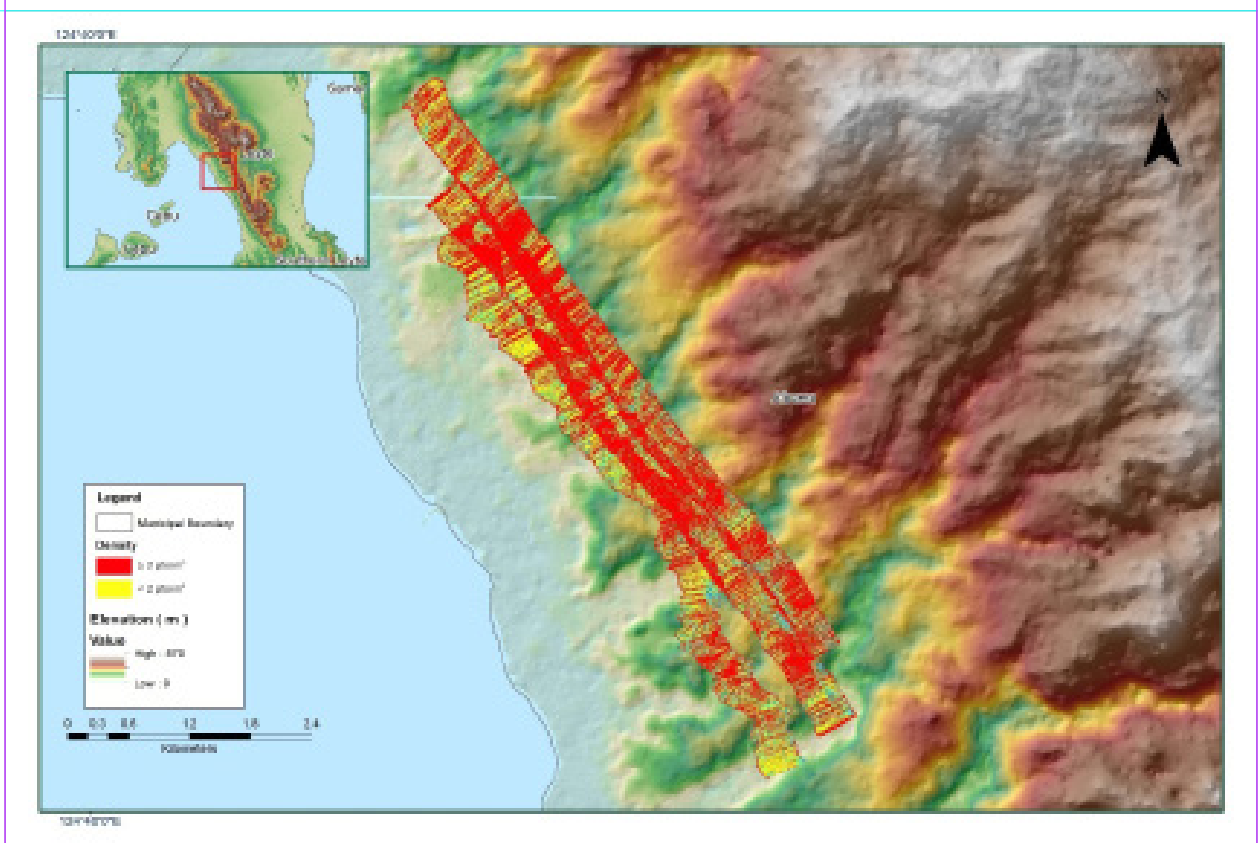


Figure A-8.IV. Density map of merged LiDAR data



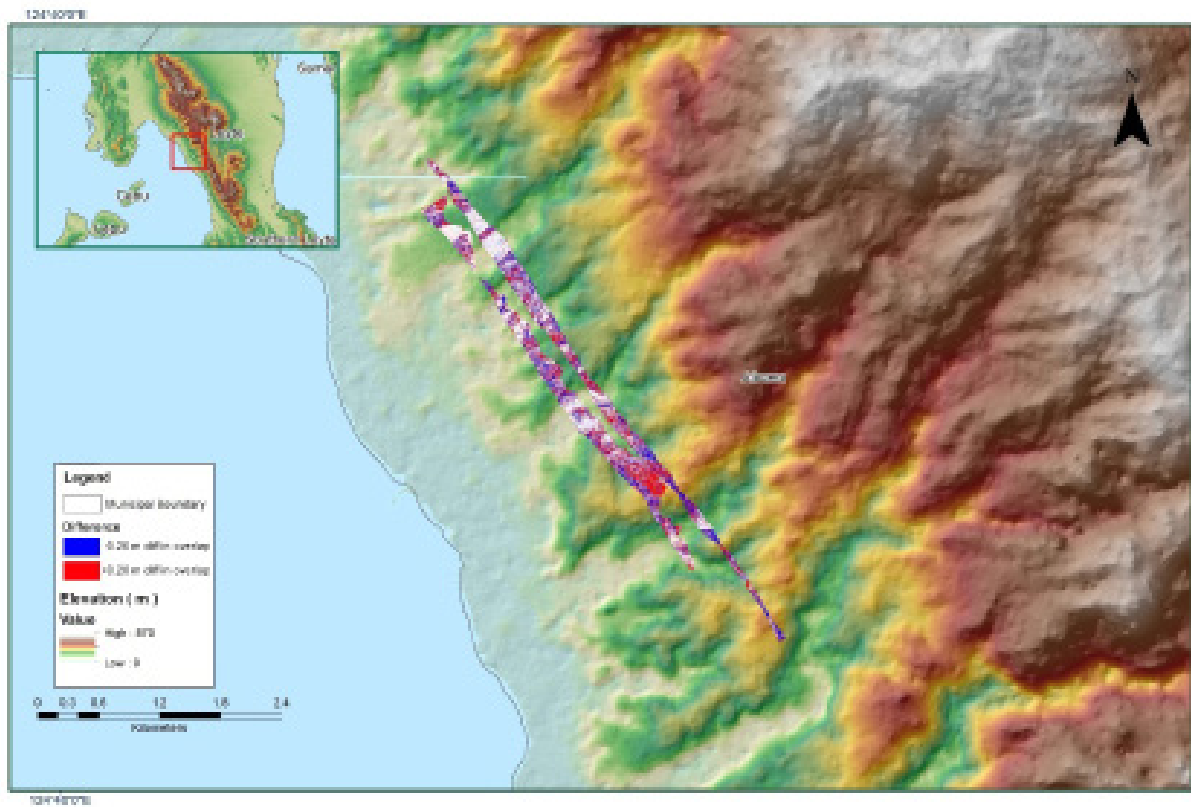


Figure A-8.112. Elevation difference between flight lines

Table A-8.17. Mission Summary Report for Mission Blk35E

Flight Area	Ormoc_Camotes
<b>Mission Name</b>	Blk35E
<b>Inclusive Flights</b>	8391AC
<b>Range data size</b>	11.2 GB
<b>POS</b>	263 MB
<b>Image</b>	35.5 MB
<b>Base Station</b>	265 MB
<b>Transfer date</b>	March 28, 2016
<b>Solution Status</b>	
<b>Number of Satellites (&gt;6)</b>	Yes
<b>PDOP (&lt;3)</b>	Yes
<b>Baseline Length (&lt;30km)</b>	Yes
<b>Processing Mode (&lt;=1)</b>	Yes
<b>Smoothed Performance Metrics (in cm)</b>	
<b>RMSE for North Position (&lt;4.0 cm)</b>	1.16
<b>RMSE for East Position (&lt;4.0 cm)</b>	1.24
<b>RMSE for Down Position (&lt;8.0 cm)</b>	2.64
<b>Boresight correction stdev (&lt;0.001deg)</b>	0.000304
<b>IMU attitude correction stdev (&lt;0.001deg)</b>	0.001996
<b>GPS position stdev (&lt;0.01m)</b>	0.0106
<b>Minimum % overlap (&gt;25)</b>	48.98
<b>Ave point cloud density per sq.m. (&gt;2.0)</b>	4.99
<b>Elevation difference between strips (&lt;0.20 m)</b>	Yes
<b>Number of 1km x 1km blocks</b>	60
<b>Maximum Height</b>	480.27
<b>Minimum Height</b>	75.57
<b>Classification (# of points)</b>	
<b>Ground</b>	30,839,262
<b>Low vegetation</b>	17,960,389
<b>Medium vegetation</b>	48,134,275
<b>High vegetation</b>	73,775,914
<b>Building</b>	4,266,466
<b>Orthophoto</b>	None
<b>Processed by</b>	Engr. Kenneth Solidum, Engr. Chelou Prado, Marie Denise Bueno

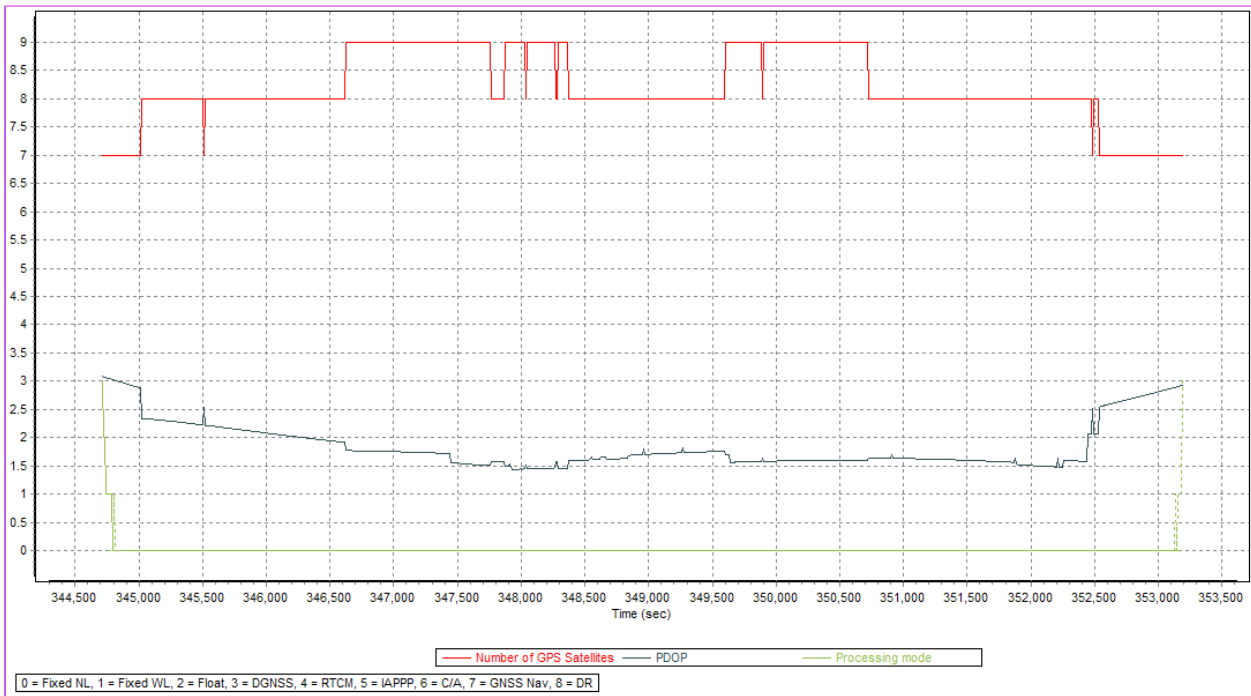


Figure A-8.113. Solution Status

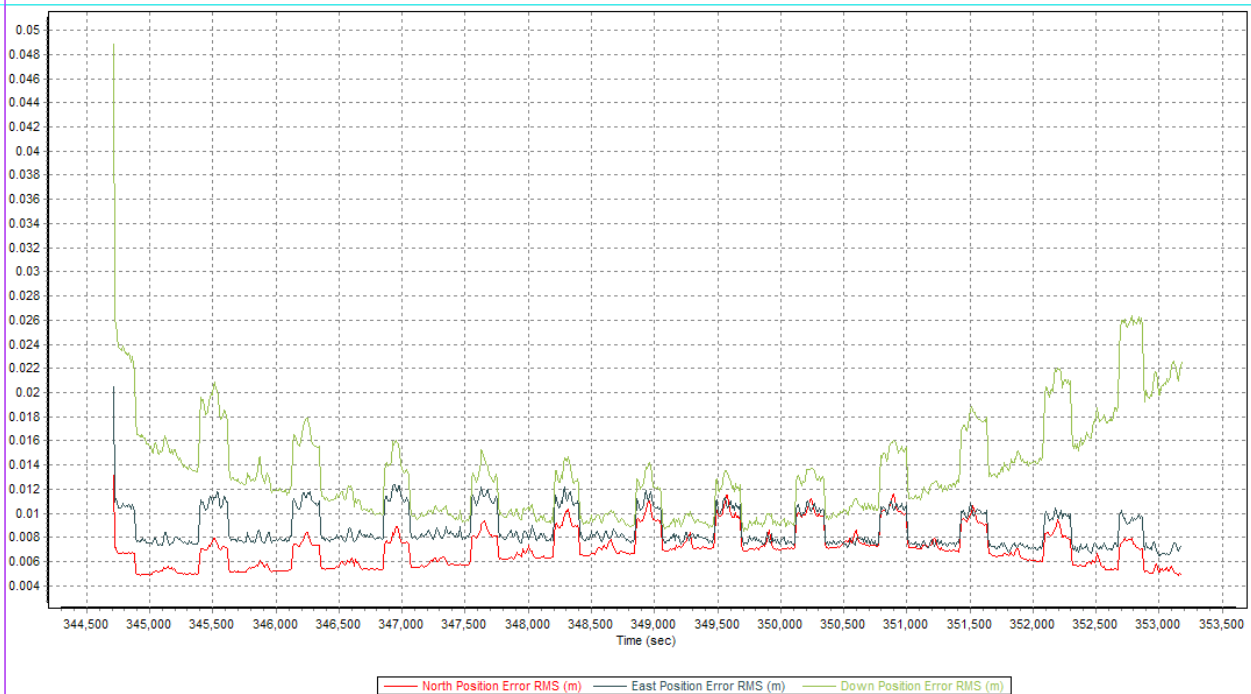


Figure A-8.114. Smoothed Performance Metrics Parameters

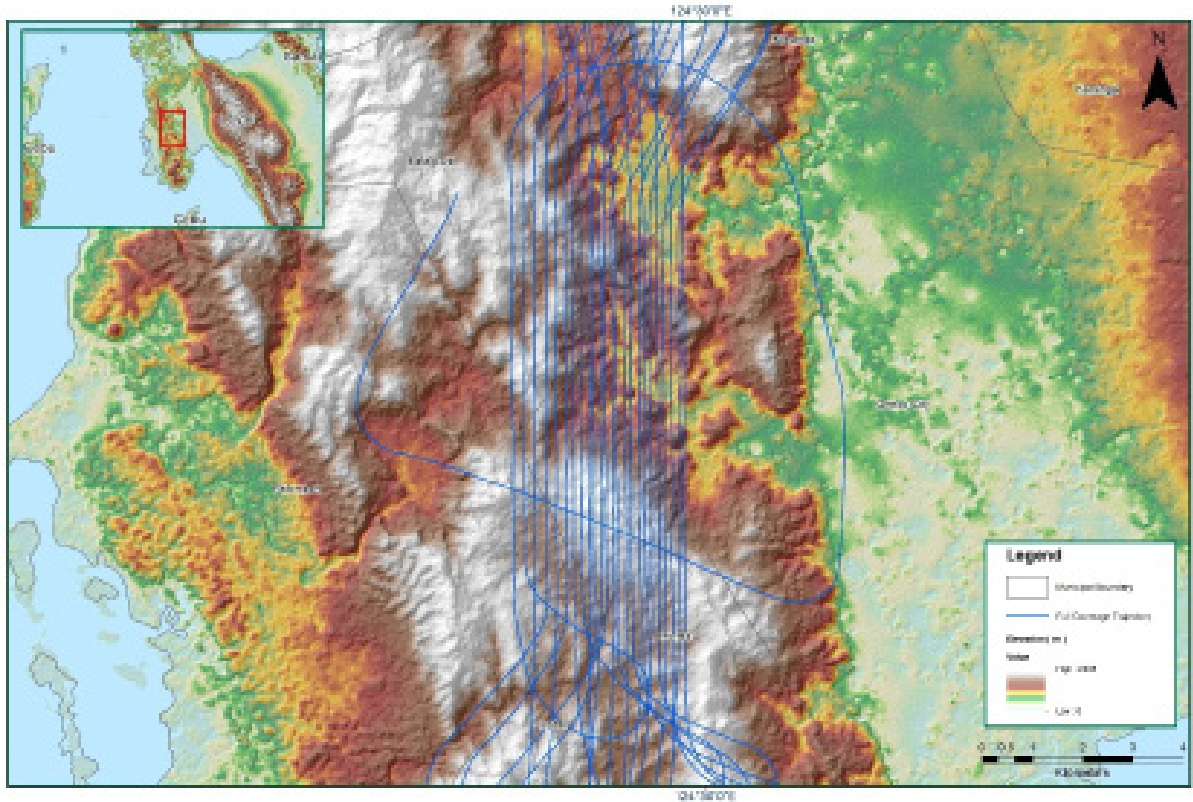


Figure A-8.115. Best Estimated Trajectory

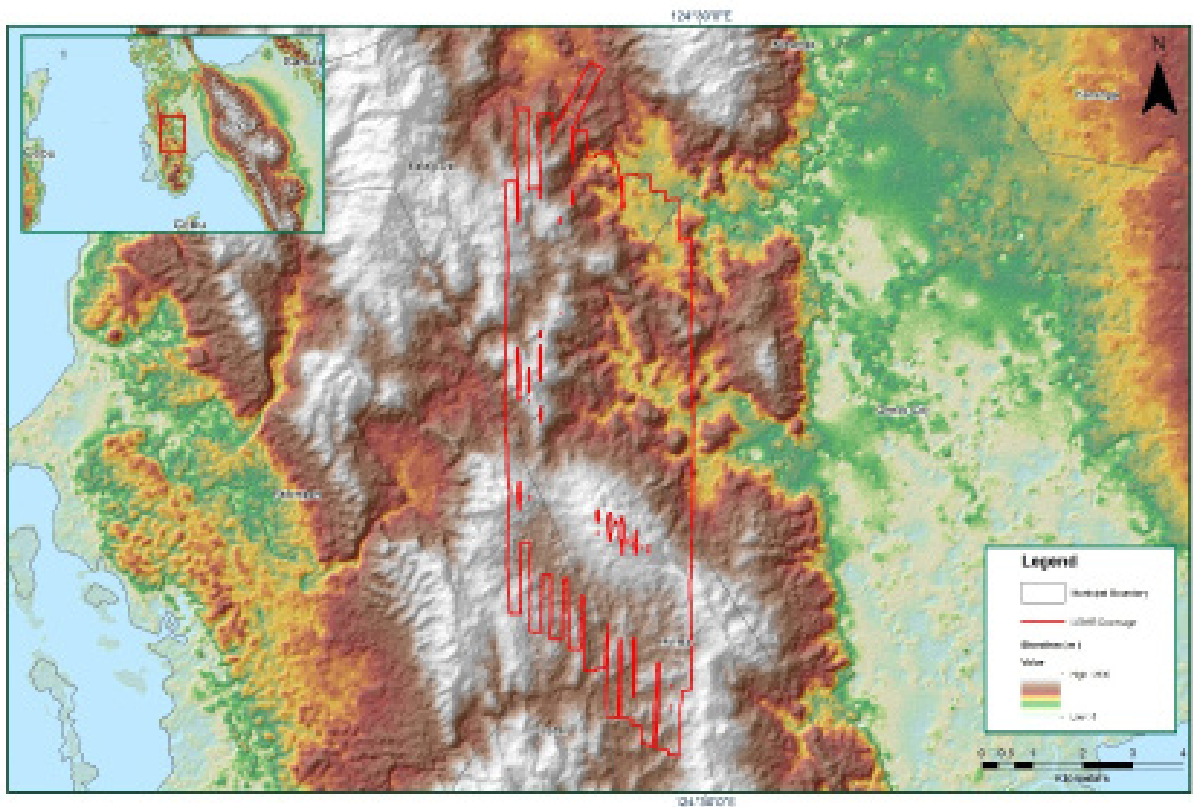


Figure A-8.116. Best Estimated Trajectory

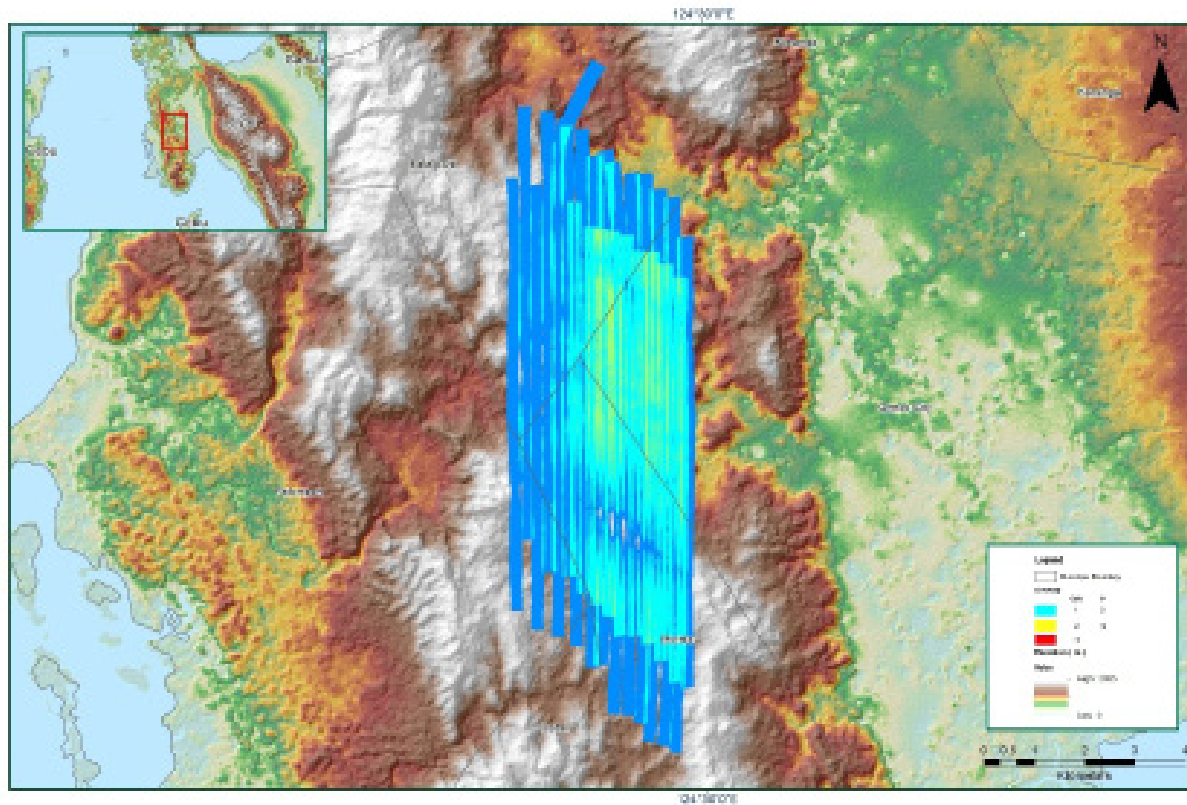


Figure A-8.117. Image of data overlap

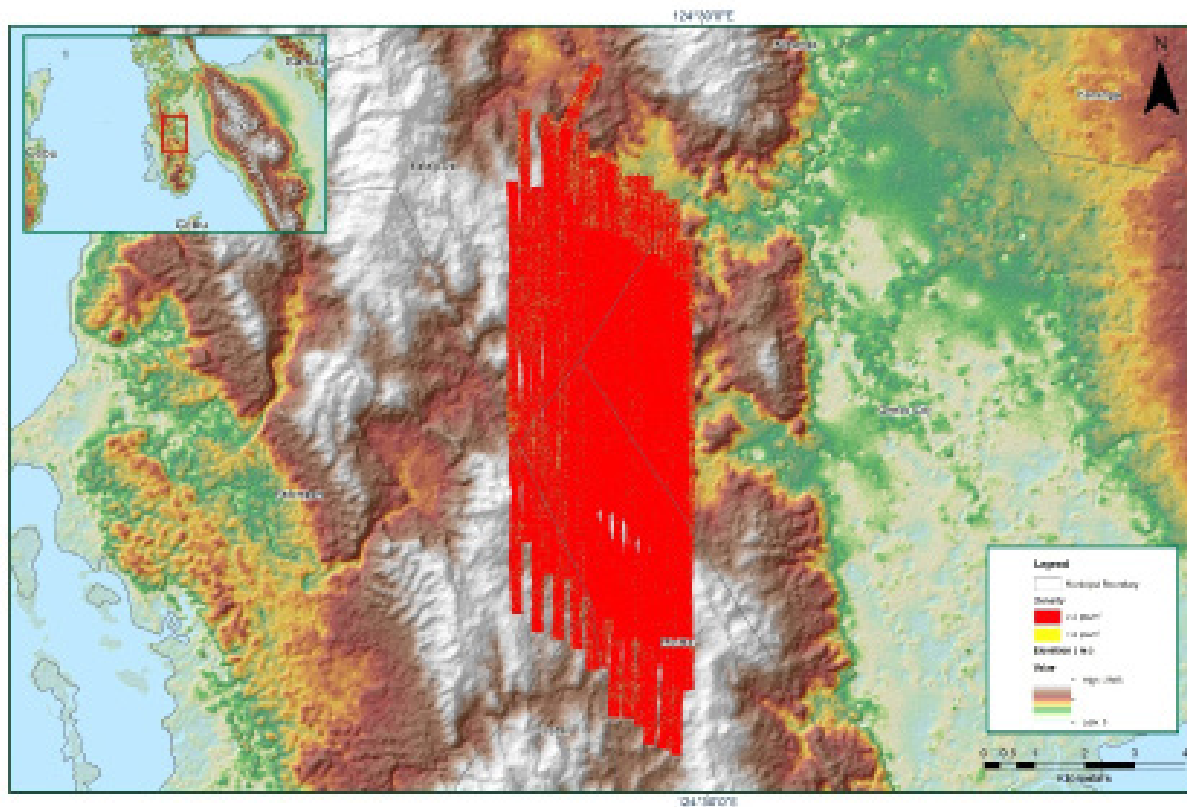


Figure A-8.118. Density map of merged LiDAR data

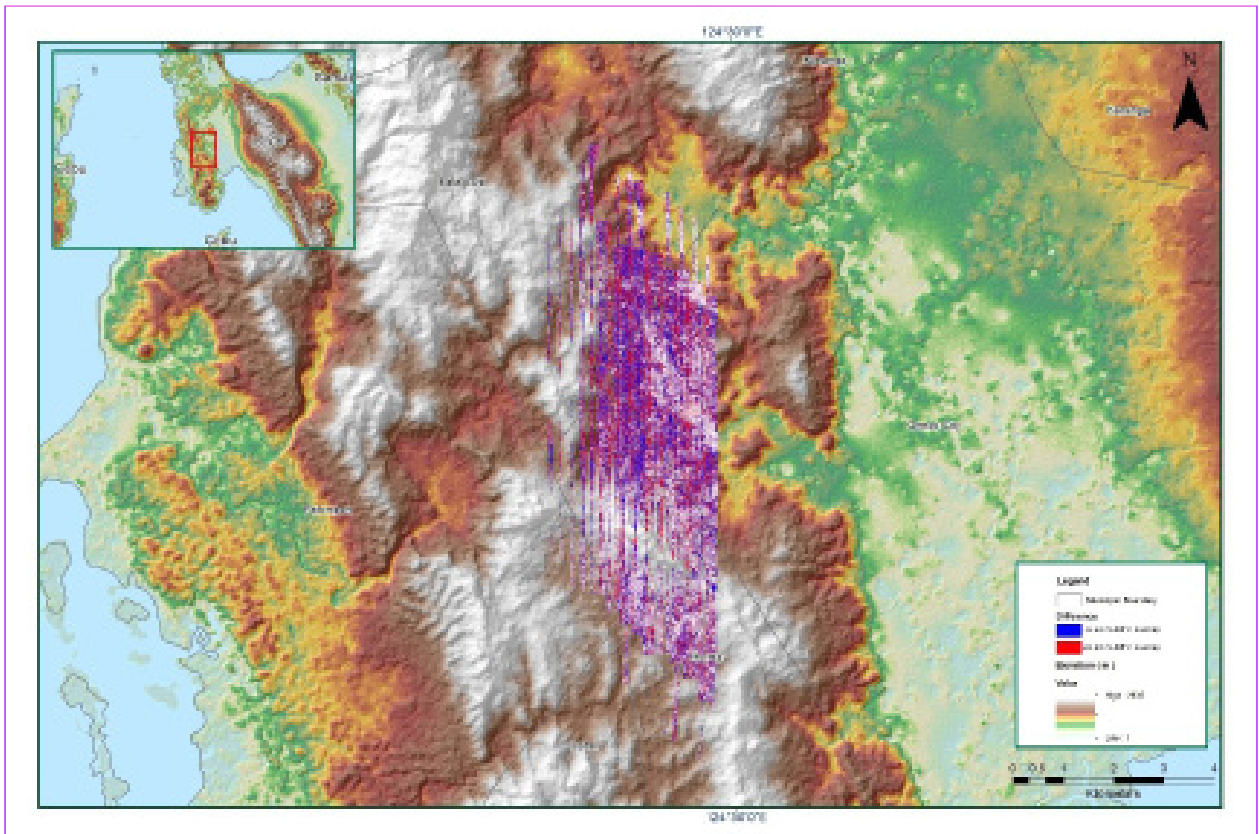


Figure A-8.119. Elevation difference between flight lines

Table A-8.18. Mission Summary Report for Mission Blk35E\_Additional

Flight Area	Ormoc_Camotes
<b>Mission Name</b>	Blk35E_Additional
<b>Inclusive Flights</b>	8408AC
<b>Range data size</b>	5.14 GB
<b>POS</b>	208 MB
<b>Image</b>	56.3 MB
<b>Base Station</b>	263 MB
<b>Transfer date</b>	April 22, 2016
<b>Solution Status</b>	
<b>Number of Satellites (&gt;6)</b>	Yes
<b>PDOP (&lt;3)</b>	Yes
<b>Baseline Length (&lt;30km)</b>	Yes
<b>Processing Mode (&lt;=1)</b>	Yes
<b>Smoothed Performance Metrics (in cm)</b>	
<b>RMSE for North Position (&lt;4.0 cm)</b>	1.03
<b>RMSE for East Position (&lt;4.0 cm)</b>	1.24
<b>RMSE for Down Position (&lt;8.0 cm)</b>	3.59
<b>Boresight correction stdev (&lt;0.001deg)</b>	N/A
<b>IMU attitude correction stdev (&lt;0.001deg)</b>	N/A
<b>GPS position stdev (&lt;0.01m)</b>	N/A
<b>Minimum % overlap (&gt;25)</b>	20.63
<b>Ave point cloud density per sq.m. (&gt;2.0)</b>	3.20
<b>Elevation difference between strips (&lt;0.20 m)</b>	Yes
<b>Number of 1km x 1km blocks</b>	30
<b>Maximum Height</b>	480.27
<b>Minimum Height</b>	75.57
<b>Classification (# of points)</b>	
<b>Ground</b>	30,839,262
<b>Low vegetation</b>	17,960,389
<b>Medium vegetation</b>	48,134,275
<b>High vegetation</b>	73,775,914
<b>Building</b>	4,266,466
<b>Orthophoto</b>	None
<b>Processed by</b>	Engr. Regis Guhiting, Aljon Rie Araneta, Marie Denise Bueno

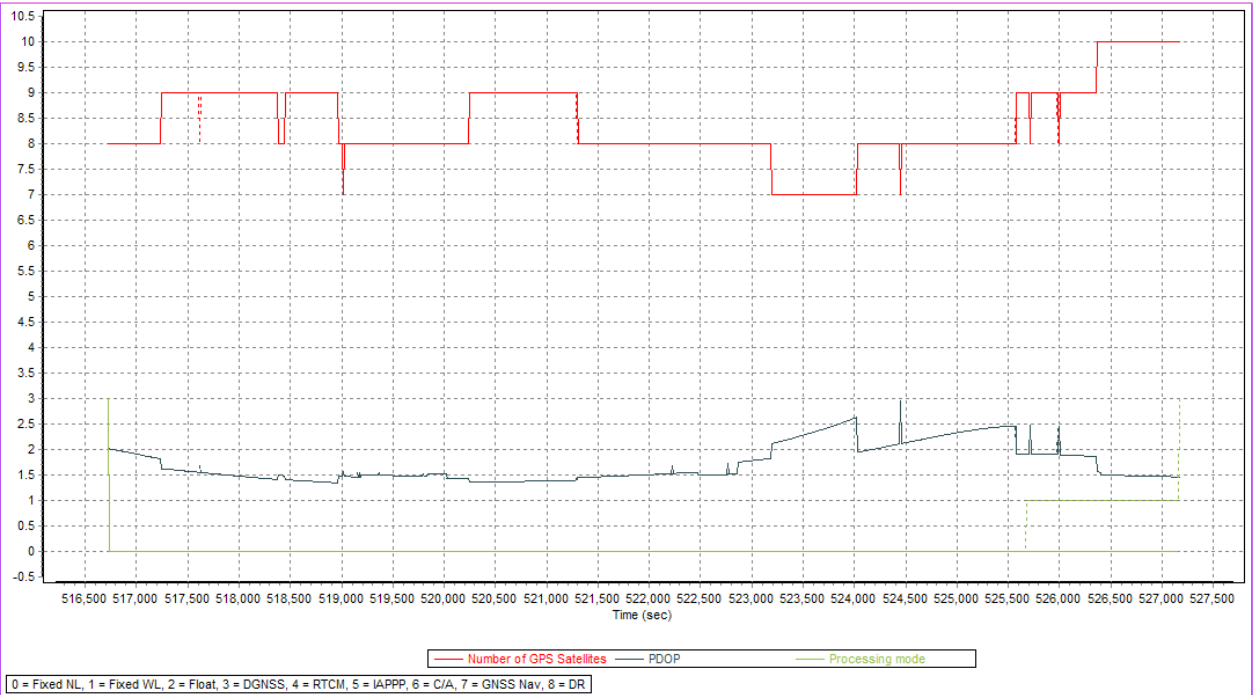


Figure A-8.120. Solution Status

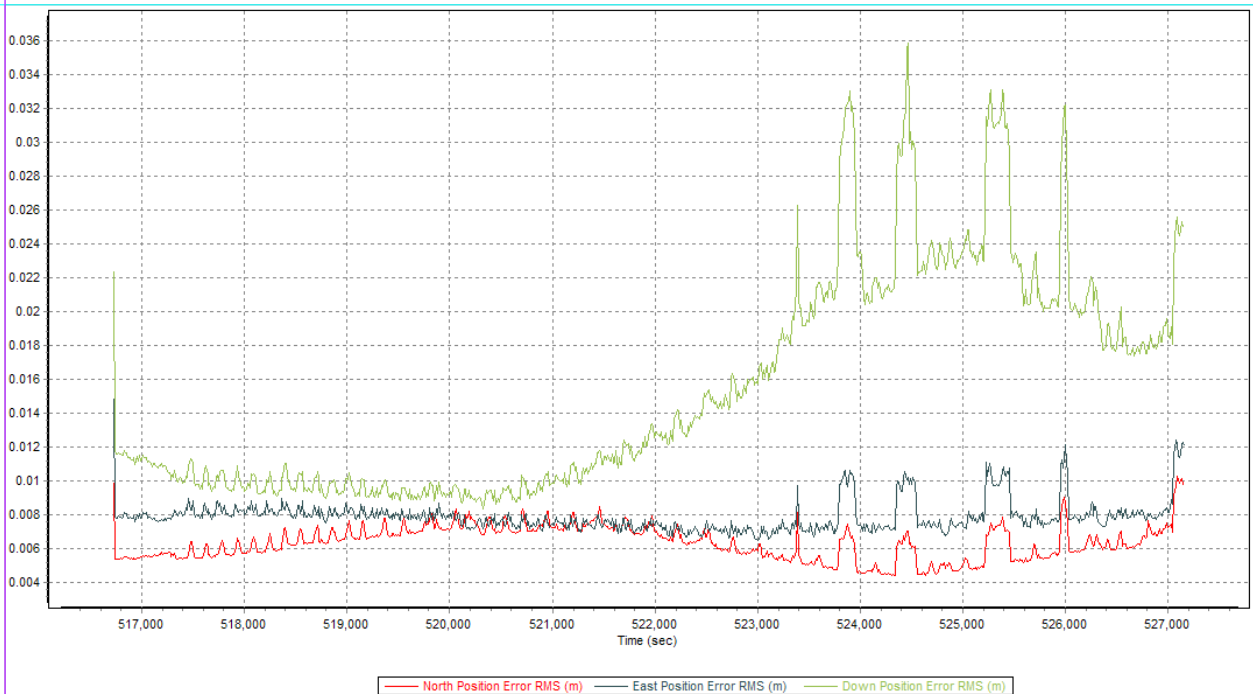


Figure A-8.121. Smoothed Performance Metrics Parameters



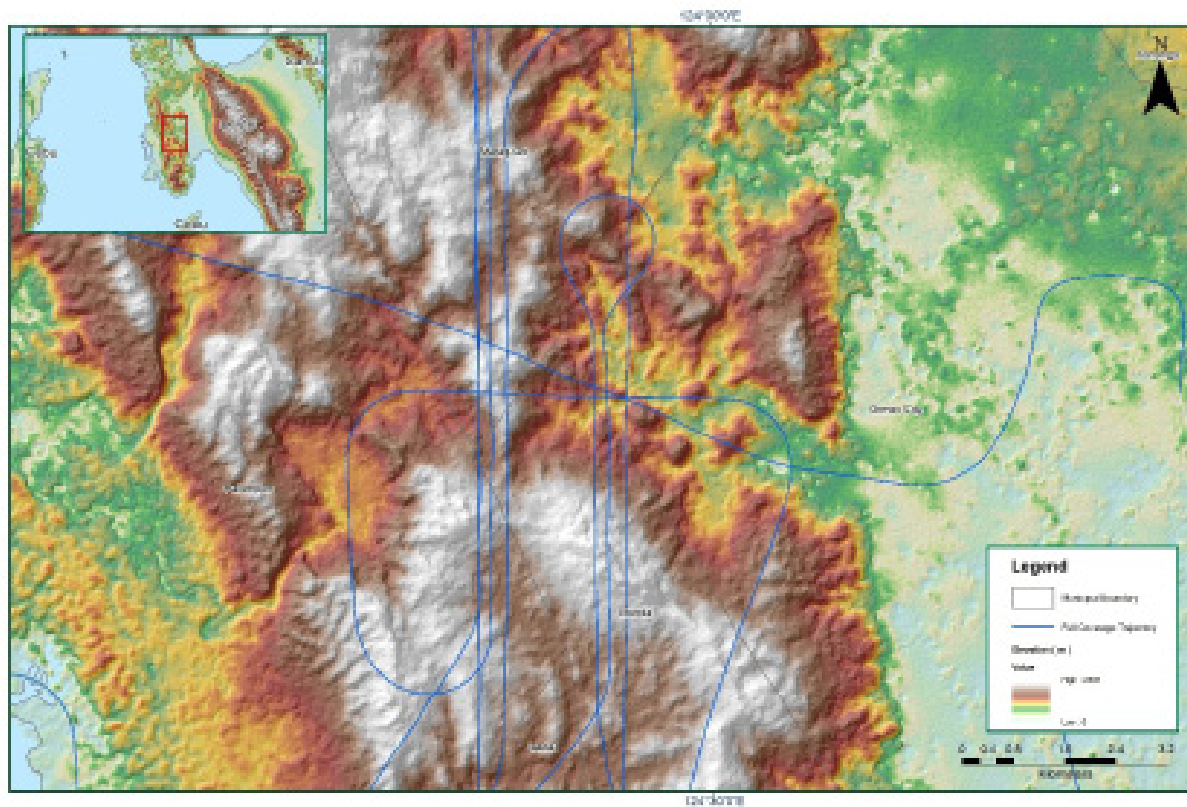


Figure A-8.122. Best Estimated Trajectory

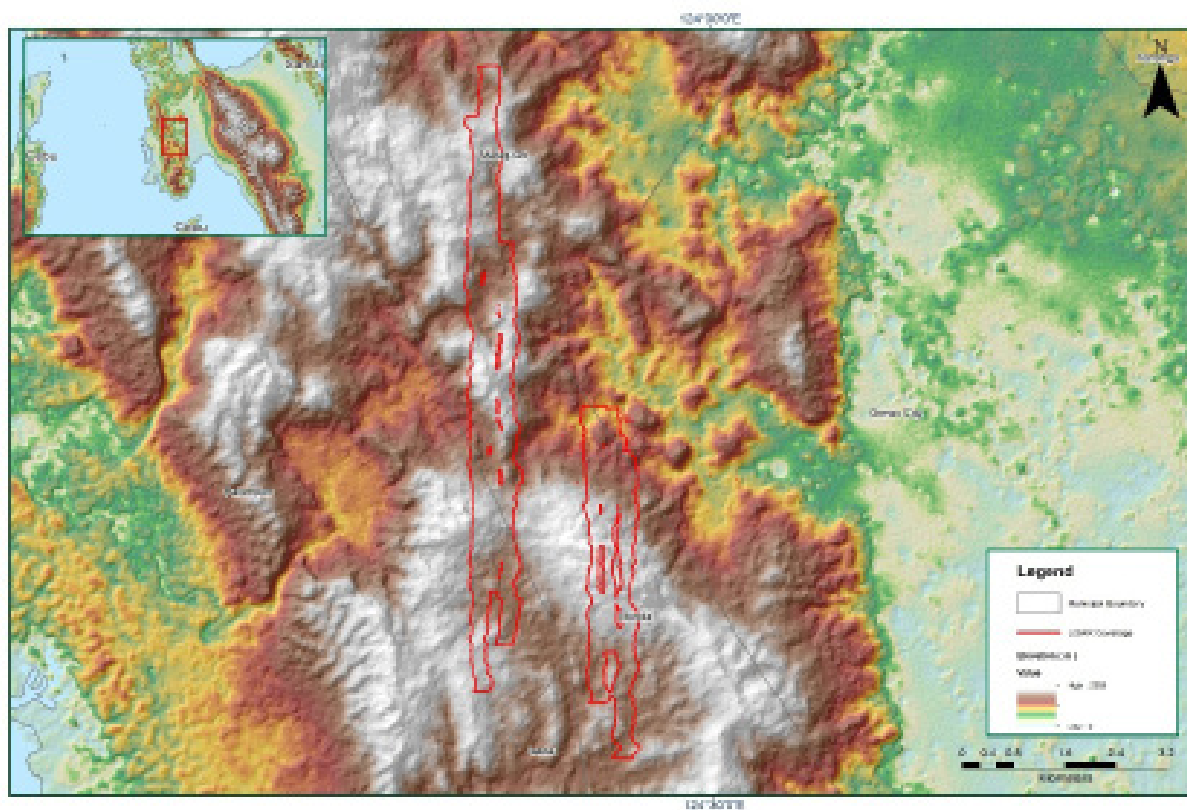


Figure A-8.123. Coverage of LiDAR data

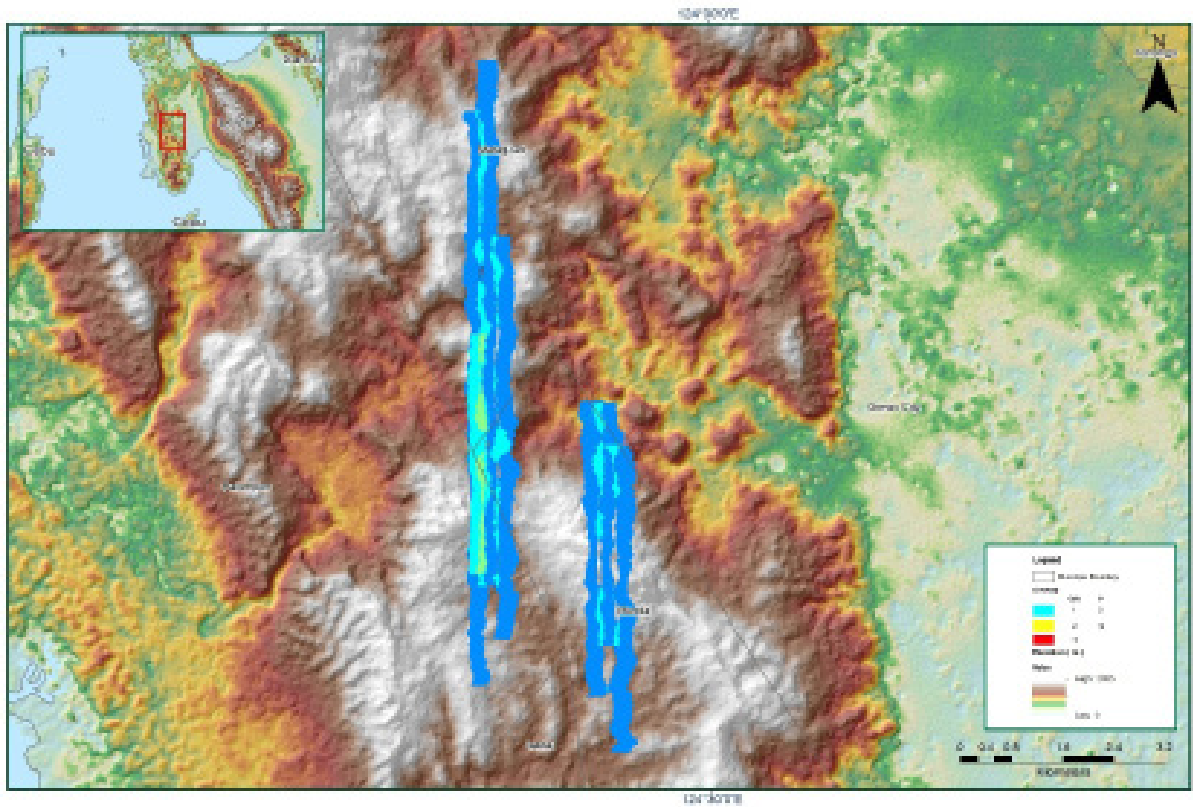


Figure A-8.124. Image of data overlap

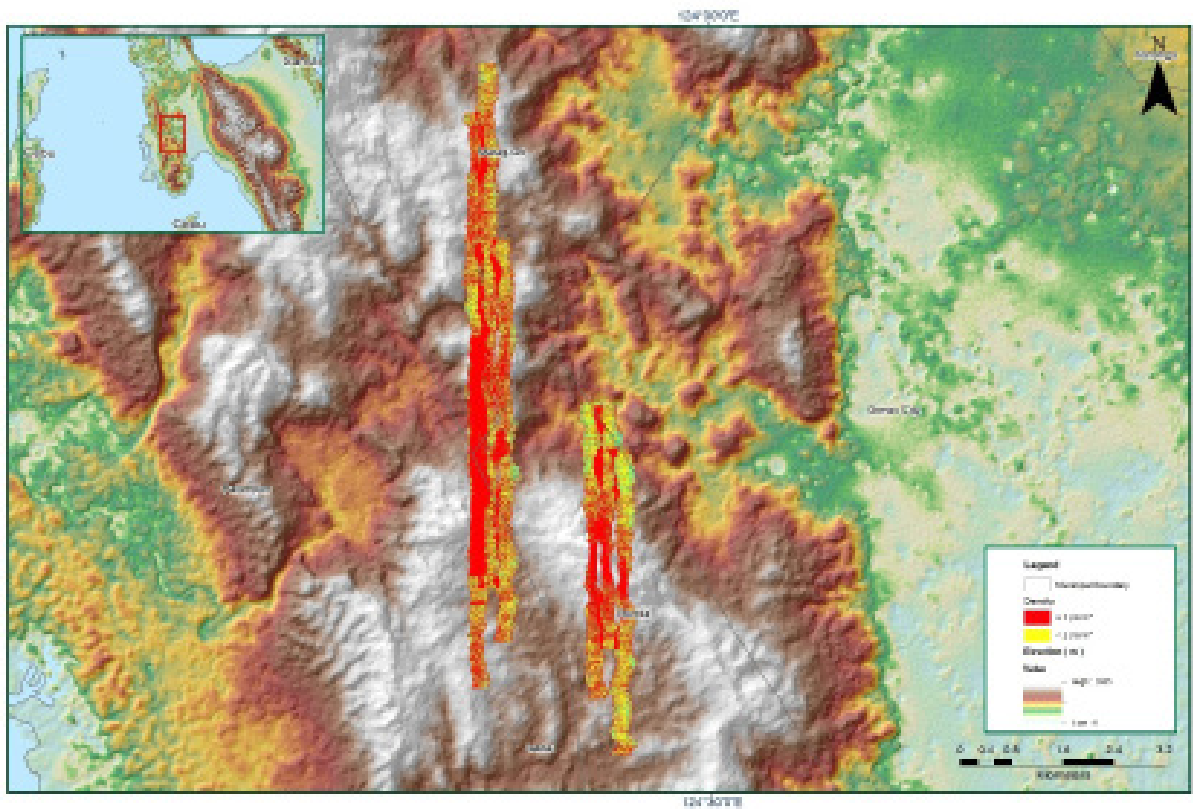


Figure A-8.125. Density map of merged LIDAR data

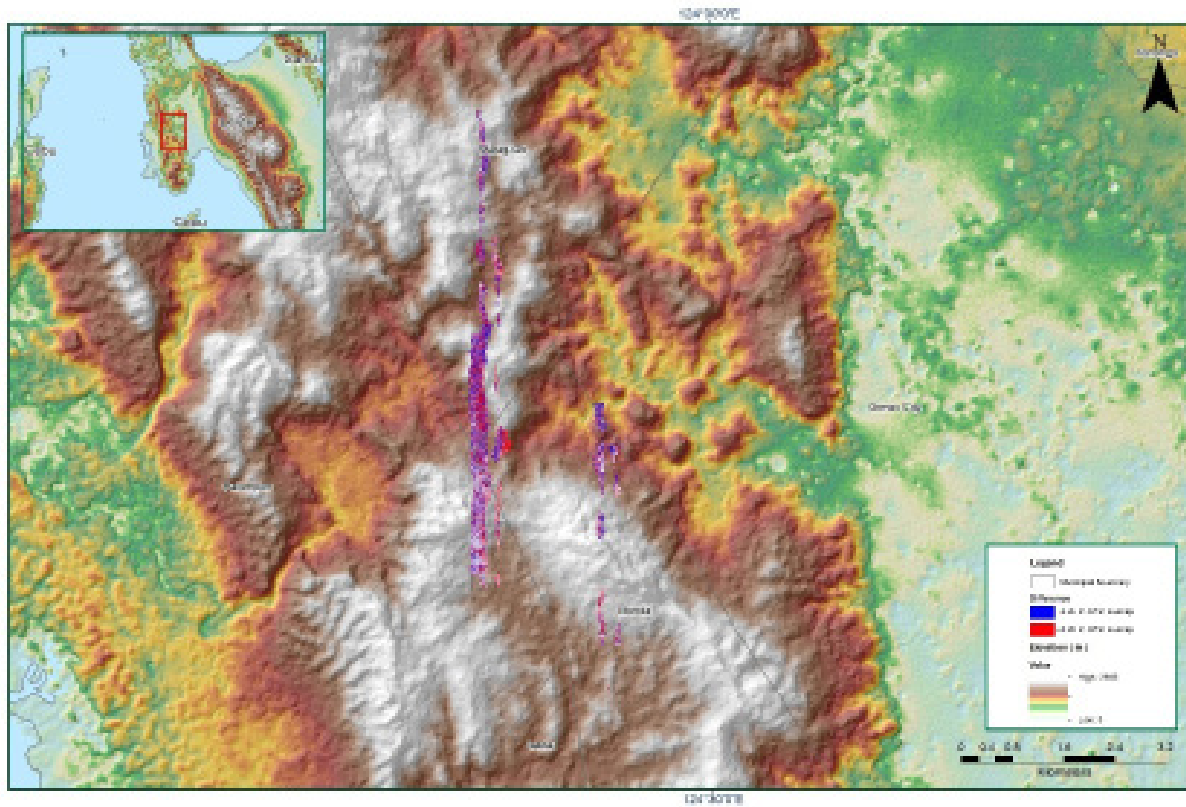


Figure A-8.126. Elevation difference between flight lines

Table A-8.19. Mission Summary Report for Mission Blk35E\_Supplement

Flight Area	Ormoc_Camotes
<b>Mission Name</b>	Blk35E_Supplement
<b>Inclusive Flights</b>	8389AC
<b>Range data size</b>	10.7 GB
<b>POS</b>	259 MB
<b>Image</b>	44.9 MB
<b>Base Station</b>	228 MB
<b>Transfer date</b>	March 28, 2016
<b>Solution Status</b>	
<b>Number of Satellites (&gt;6)</b>	No
<b>PDOP (&lt;3)</b>	No
<b>Baseline Length (&lt;30km)</b>	Yes
<b>Processing Mode (&lt;=1)</b>	No
<b>Smoothed Performance Metrics (in cm)</b>	
<b>RMSE for North Position (&lt;4.0 cm)</b>	1.21
<b>RMSE for East Position (&lt;4.0 cm)</b>	1.65
<b>RMSE for Down Position (&lt;8.0 cm)</b>	4.13
<b>Boresight correction stdev (&lt;0.001deg)</b>	0.000431
<b>IMU attitude correction stdev (&lt;0.001deg)</b>	0.006621
<b>GPS position stdev (&lt;0.01m)</b>	0.0098
<b>Minimum % overlap (&gt;25)</b>	51.84
<b>Ave point cloud density per sq.m. (&gt;2.0)</b>	4.13
<b>Elevation difference between strips (&lt;0.20 m)</b>	Yes
<b>Number of 1km x 1km blocks</b>	89
<b>Maximum Height</b>	377.21
<b>Minimum Height</b>	57.60
<b>Classification (# of points)</b>	
<b>Ground</b>	52,094,139
<b>Low vegetation</b>	63,380,558
<b>Medium vegetation</b>	67,477,309
<b>High vegetation</b>	83,244,354
<b>Building</b>	6,560,538
<b>Orthophoto</b>	None
<b>Processed by</b>	Engr. Kenneth Solidum, Aljon Rie Araneta, Engr. Krisha Marie Bautista

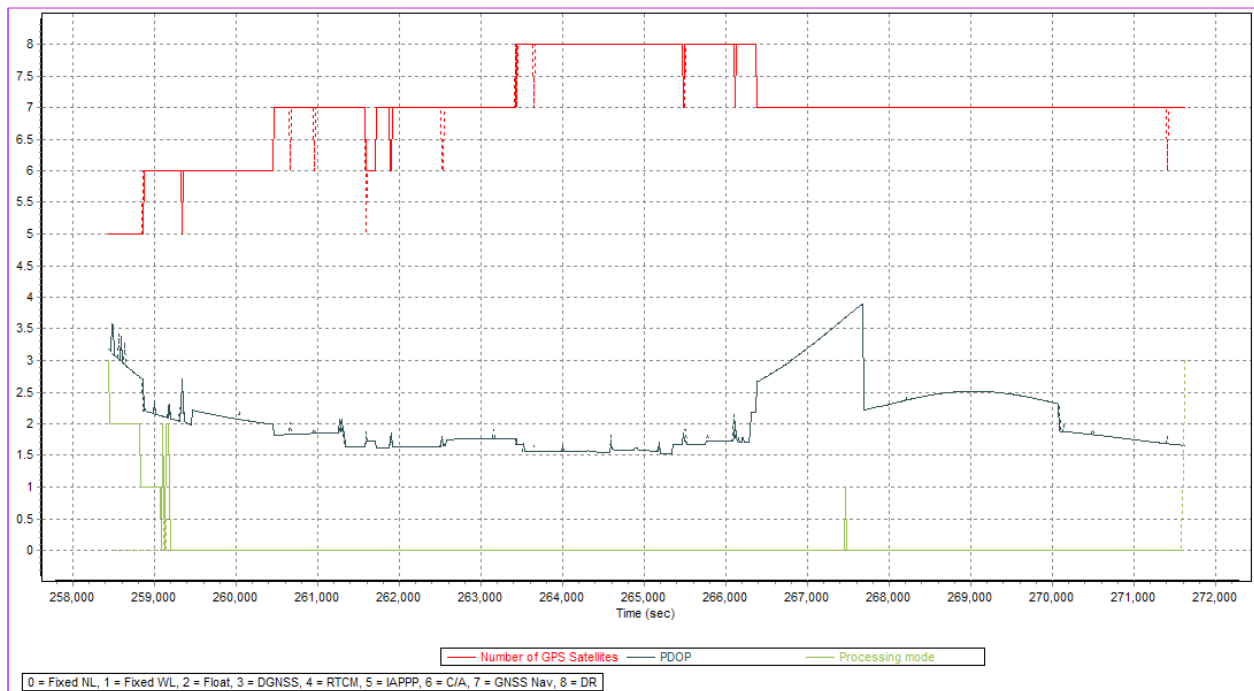


Figure A-8.127. Solution Status

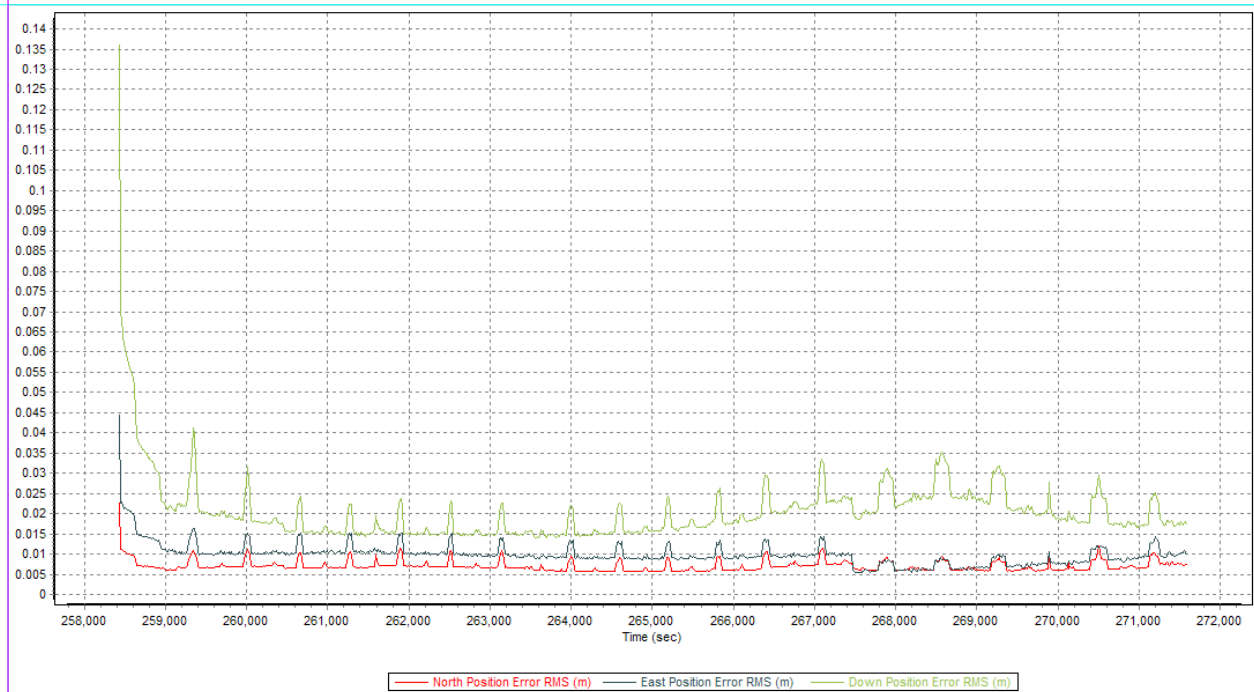


Figure A-8.128. Smoothed Performance Metrics Parameters

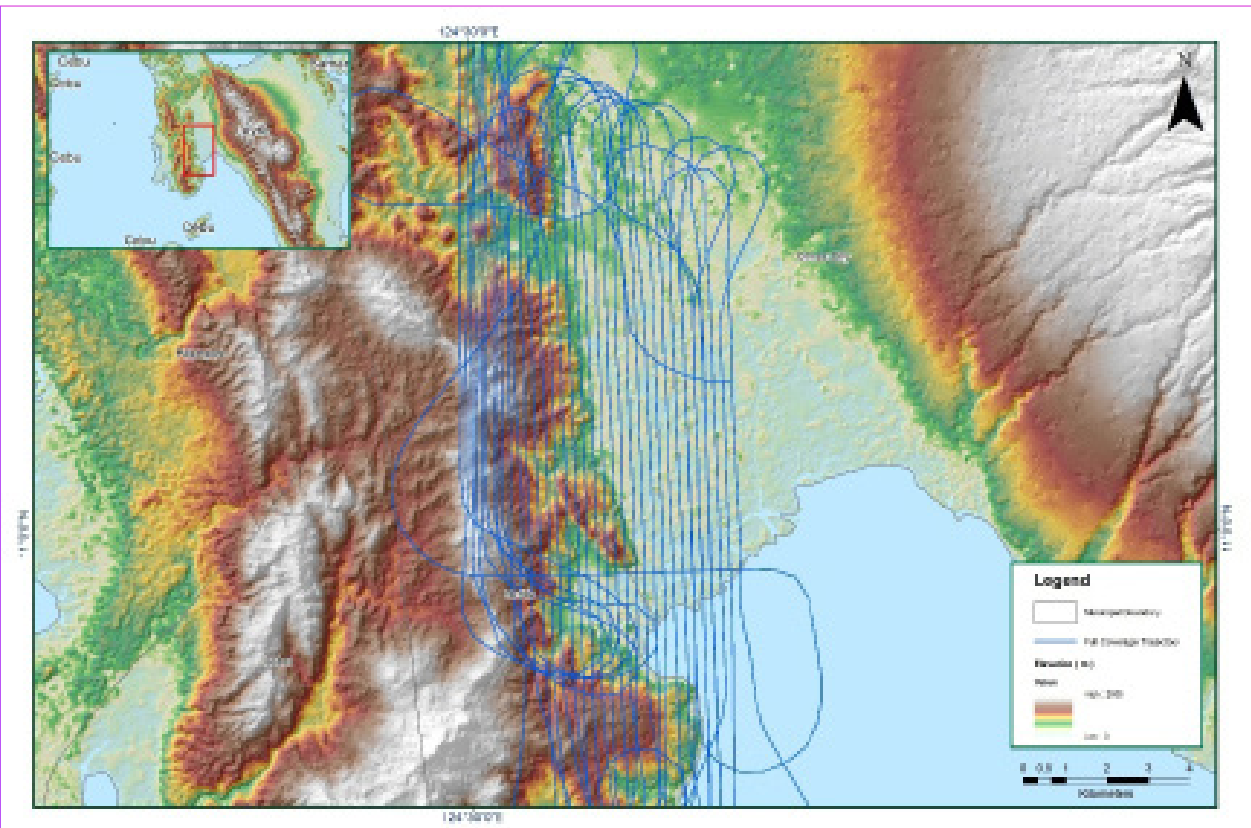


Figure A-8.129. Best Estimated Trajectory

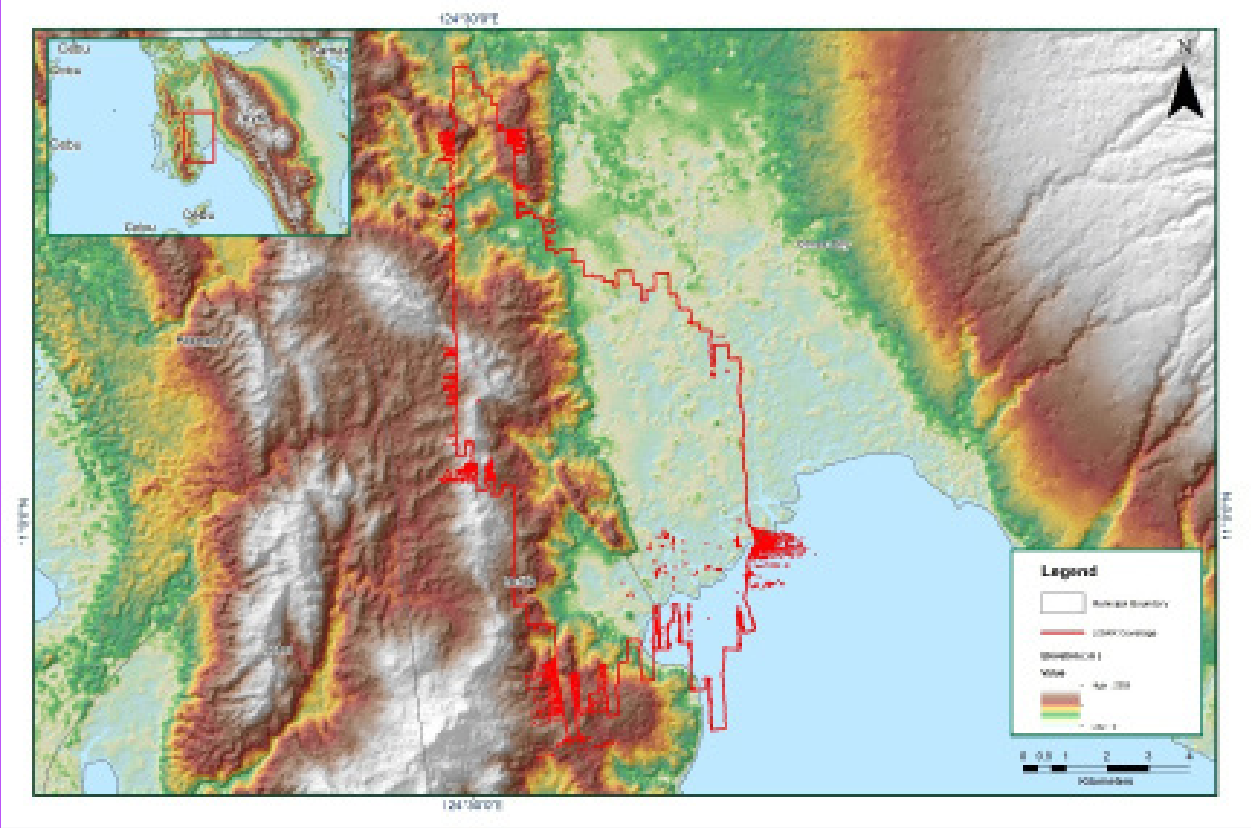


Figure A-8.130. Best Estimated Trajectory

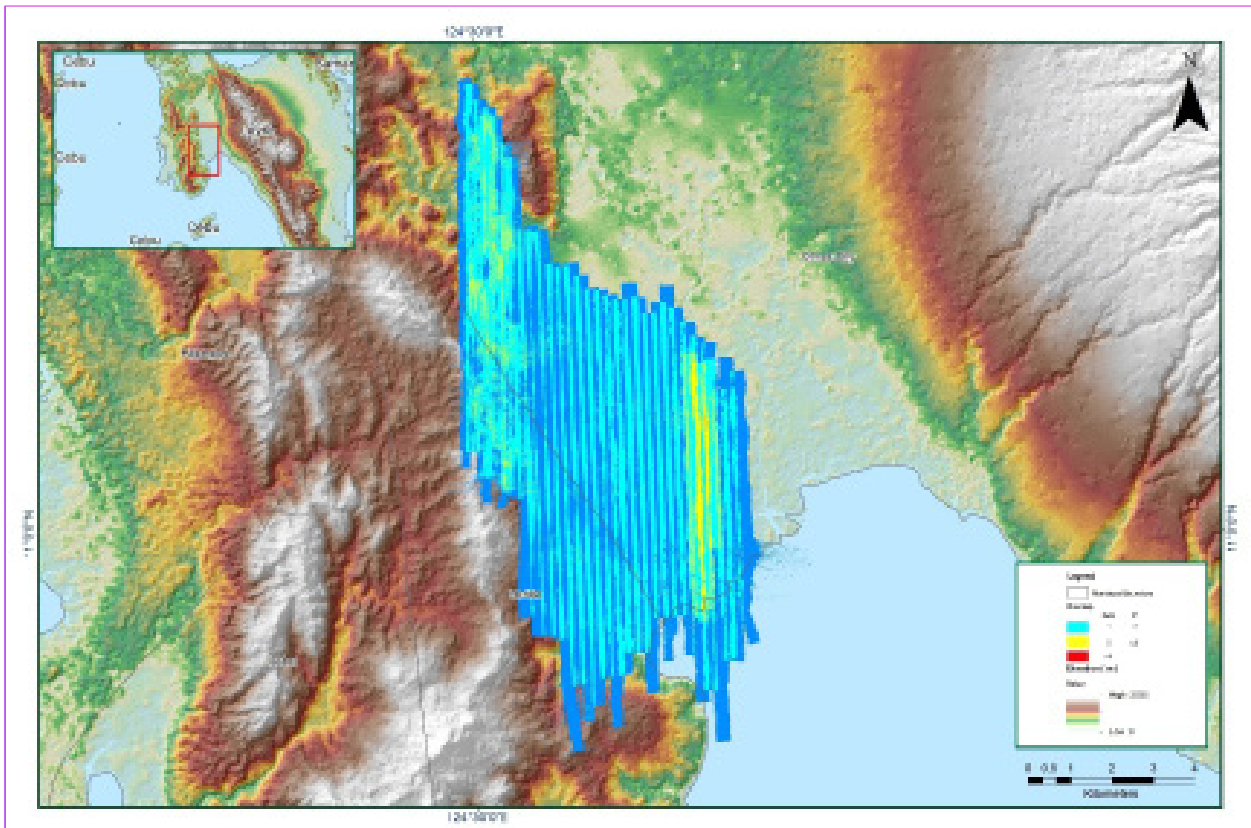


Figure A-8.131. Image of data overlap

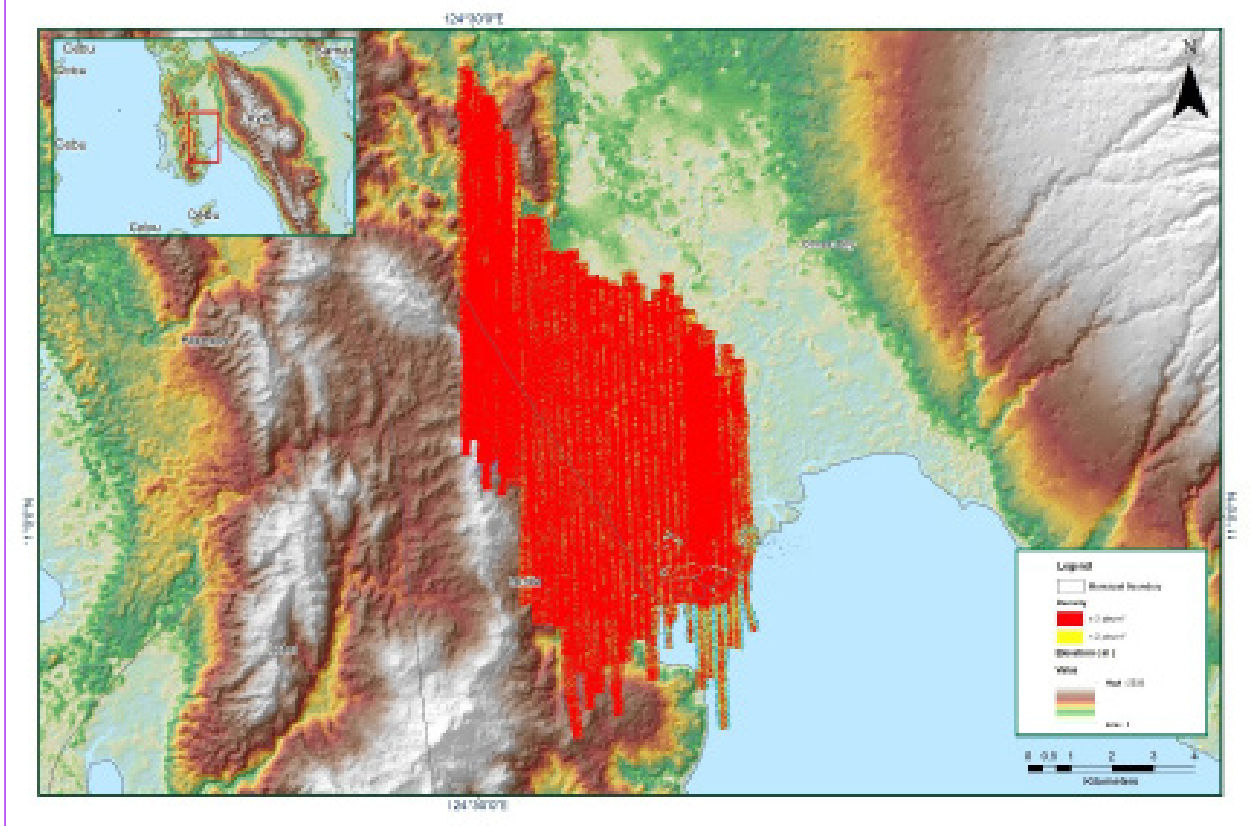


Figure A-8.132. Density map of merged LiDAR data

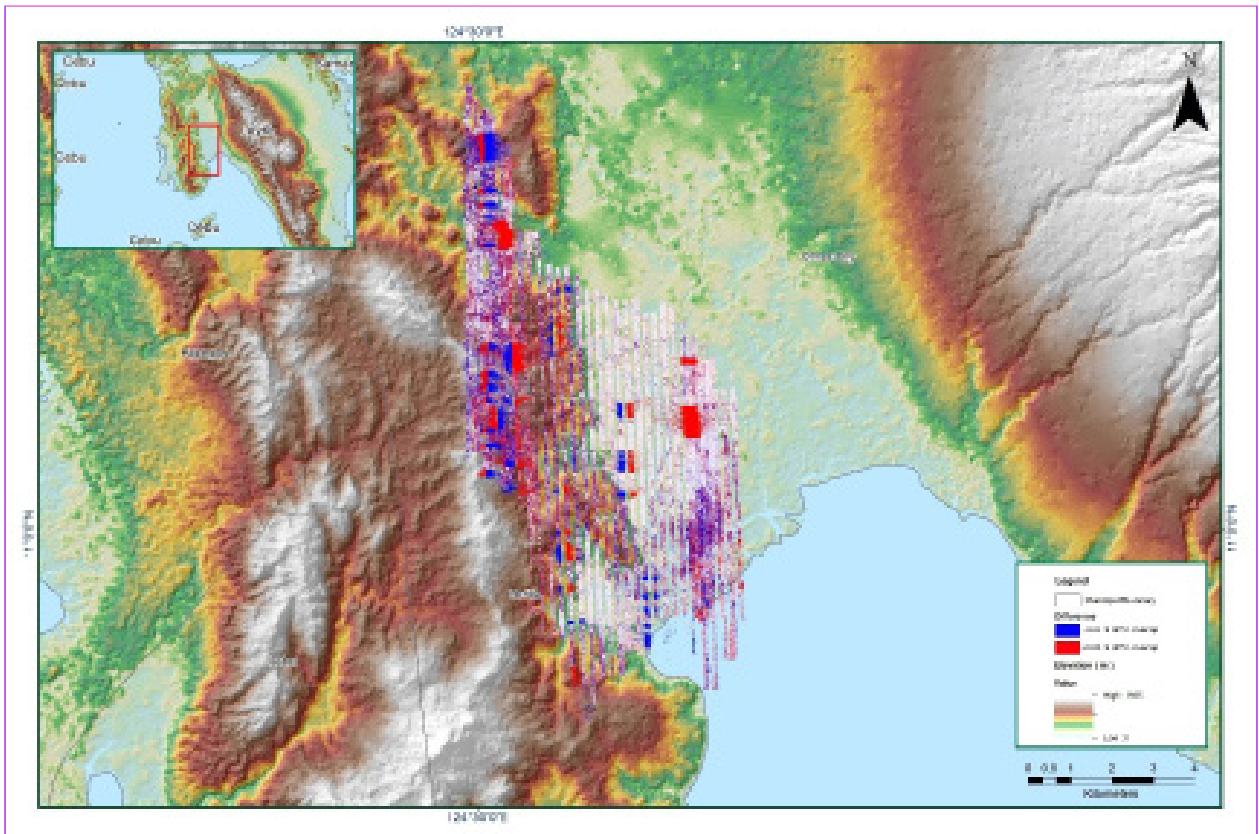


Figure A-8.133. Elevation difference between flight lines



Table A-8.20. Mission Summary Report for Mission Blk35F

Flight Area	Ormoc_Camotes
<b>Mission Name</b>	Blk35F
<b>Inclusive Flights</b>	8391AC
<b>Range data size</b>	11.2 GB
<b>POS</b>	263 MB
<b>Image</b>	35.5 MB
<b>Base Station</b>	265 MB
<b>Transfer date</b>	March 28, 2016
<b>Solution Status</b>	
<b>Number of Satellites (&gt;6)</b>	Yes
<b>PDOP (&lt;3)</b>	Yes
<b>Baseline Length (&lt;30km)</b>	Yes
<b>Processing Mode (&lt;=1)</b>	No
<b>Smoothed Performance Metrics (in cm)</b>	
<b>RMSE for North Position (&lt;4.0 cm)</b>	0.93
<b>RMSE for East Position (&lt;4.0 cm)</b>	1.02
<b>RMSE for Down Position (&lt;8.0 cm)</b>	3.06
<b>Boresight correction stdev (&lt;0.001deg)</b>	0.001039
<b>IMU attitude correction stdev (&lt;0.001deg)</b>	0.008915
<b>GPS position stdev (&lt;0.01m)</b>	0.0151
<b>Minimum % overlap (&gt;25)</b>	23.34
<b>Ave point cloud density per sq.m. (&gt;2.0)</b>	2.41
<b>Elevation difference between strips (&lt;0.20 m)</b>	Yes
<b>Number of 1km x 1km blocks</b>	51
<b>Maximum Height</b>	152.26
<b>Minimum Height</b>	52.15
<b>Classification (# of points)</b>	
<b>Ground</b>	13,689,498
<b>Low vegetation</b>	16,455,690
<b>Medium vegetation</b>	12,313,010
<b>High vegetation</b>	6,985,085
<b>Building</b>	2,211,564
<b>Orthophoto</b>	None
<b>Processed by</b>	Engr. Analyn Naldo, Aljon Rie Araneta, Alex John Escobido

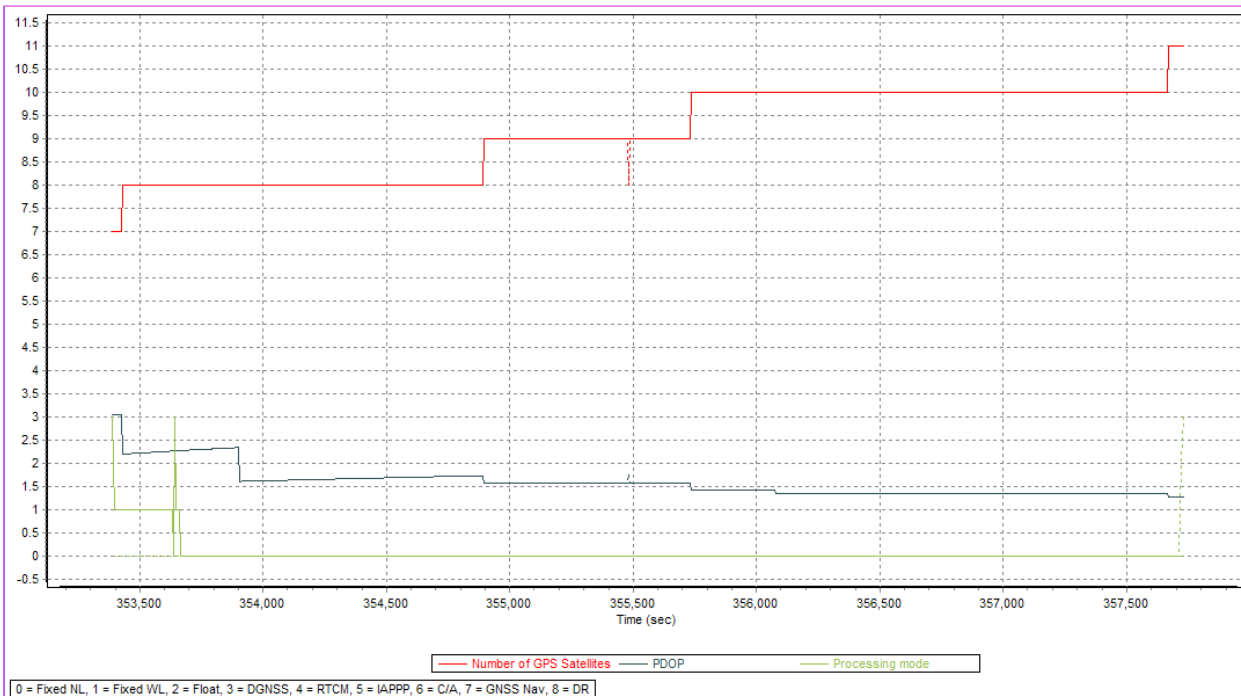


Figure A-8.134. Solution Status

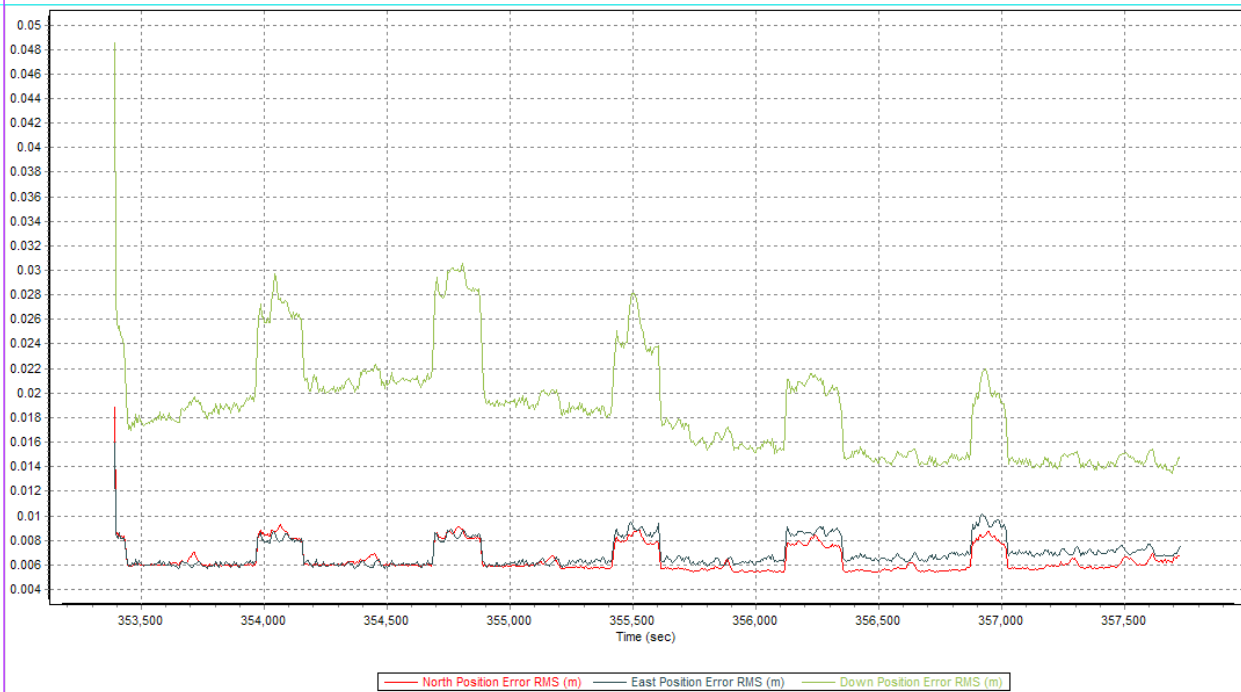


Figure A-8.135. Smoothed Performance Metrics Parameters

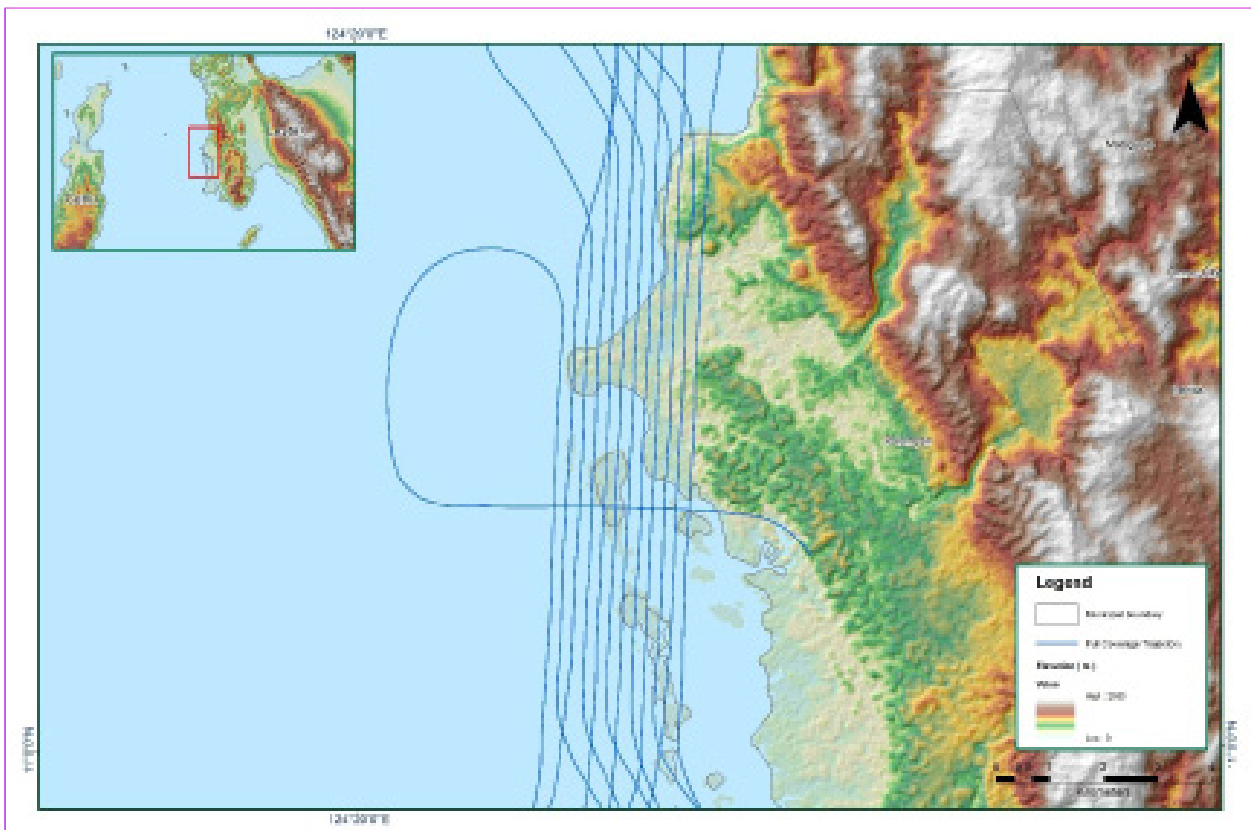


Figure A-8.136. Best Estimated Trajectory

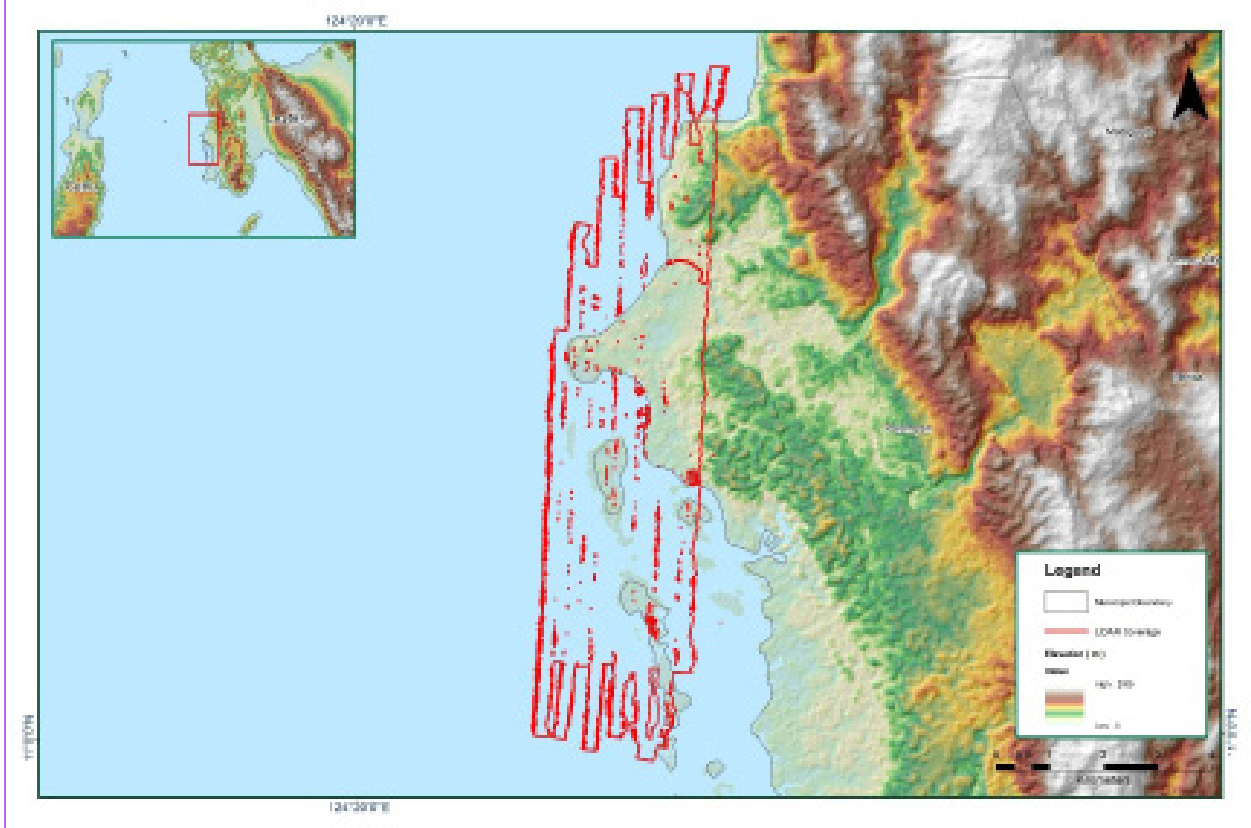


Figure A-8.137. Coverage of LiDAR data

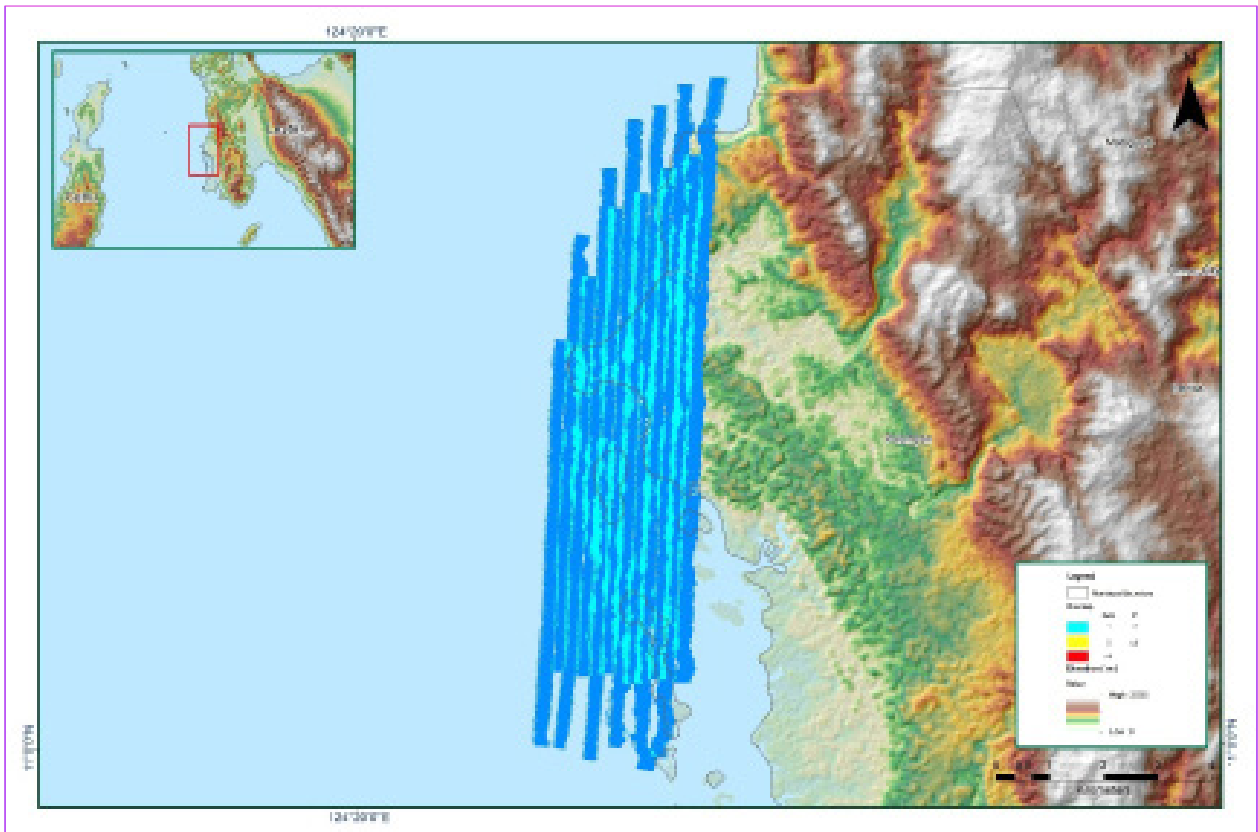


Figure A-8.138. Image of data overlap

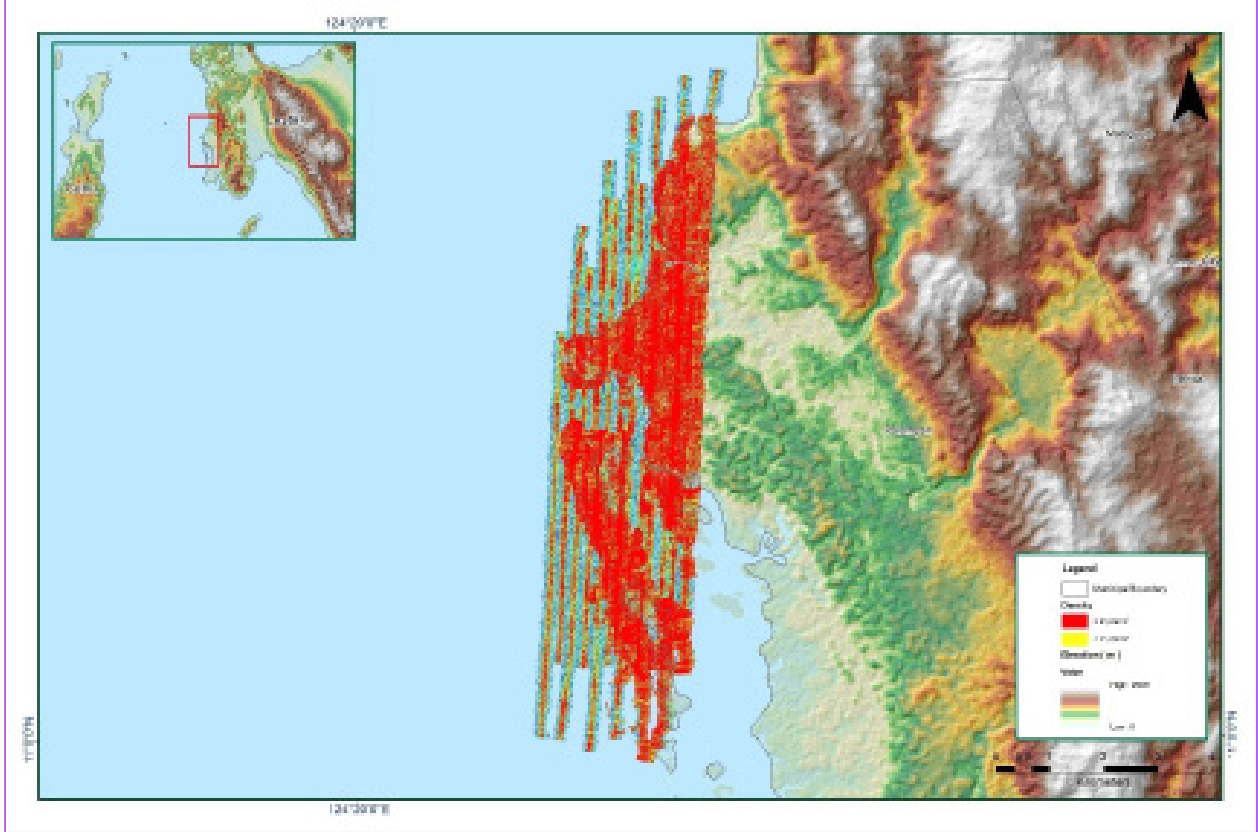


Figure A-8.139. Density map of merged LIDAR data

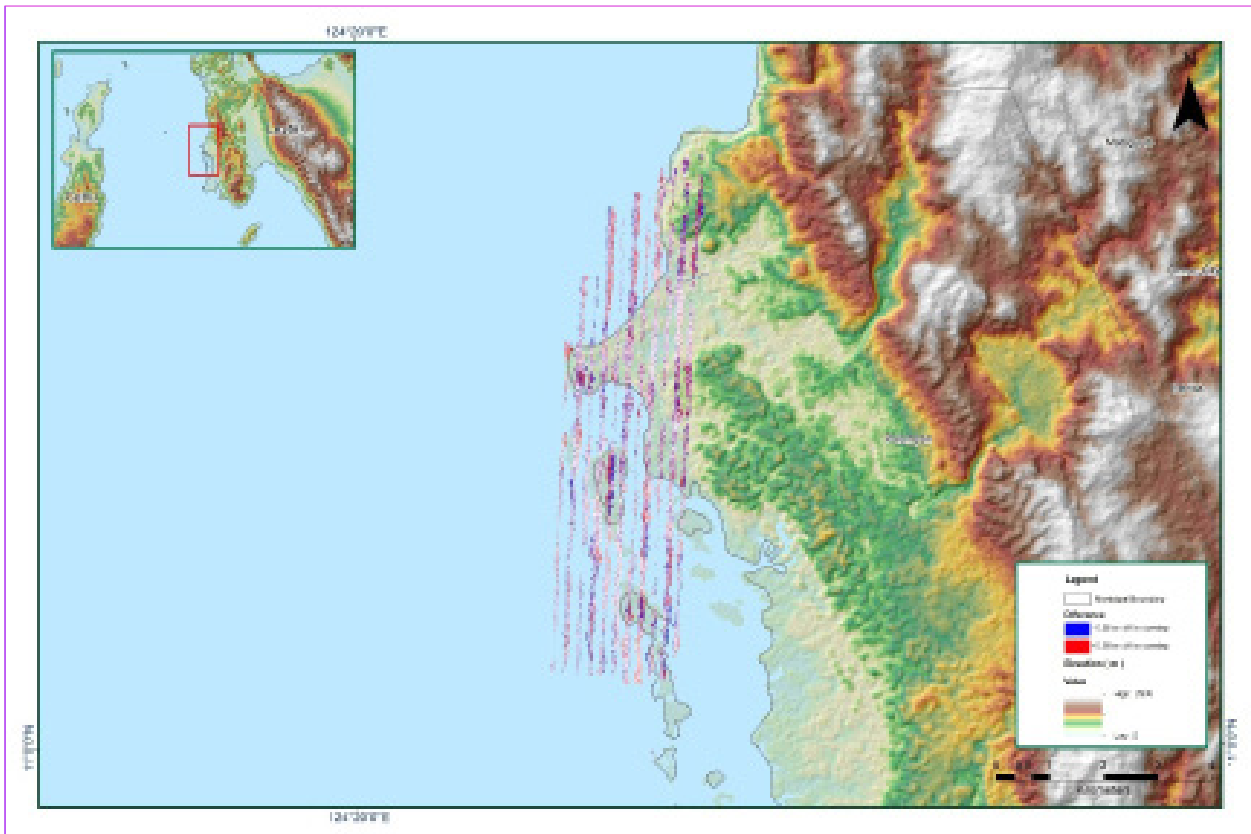


Figure A-8.140. Elevation difference between flight lines

Table A-8.21. Mission Summary Report for Mission Blk35F\_Additional

Flight Area	Ormoc_Camotes
<b>Mission Name</b>	Blk35F_Additional
<b>Inclusive Flights</b>	8408AC
<b>Range data size</b>	5.14 GB
<b>POS</b>	208 MB
<b>Image</b>	56.3 MB
<b>Base Station</b>	263 MB
<b>Transfer date</b>	April 22, 2016
<b>Solution Status</b>	
<b>Number of Satellites (&gt;6)</b>	Yes
<b>PDOP (&lt;3)</b>	Yes
<b>Baseline Length (&lt;30km)</b>	Yes
<b>Processing Mode (&lt;=1)</b>	Yes
<b>Smoothed Performance Metrics (in cm)</b>	
<b>RMSE for North Position (&lt;4.0 cm)</b>	1.03
<b>RMSE for East Position (&lt;4.0 cm)</b>	1.24
<b>RMSE for Down Position (&lt;8.0 cm)</b>	3.59
<b>Boresight correction stdev (&lt;0.001deg)</b>	N/A
<b>IMU attitude correction stdev (&lt;0.001deg)</b>	N/A
<b>GPS position stdev (&lt;0.01m)</b>	N/A
<b>Minimum % overlap (&gt;25)</b>	0.51
<b>Ave point cloud density per sq.m. (&gt;2.0)</b>	1.53
<b>Elevation difference between strips (&lt;0.20 m)</b>	Yes
<b>Number of 1km x 1km blocks</b>	29
<b>Maximum Height</b>	115.99
<b>Minimum Height</b>	47.35
<b>Classification (# of points)</b>	
<b>Ground</b>	5,179,756
<b>Low vegetation</b>	2,398,009
<b>Medium vegetation</b>	1,450,198
<b>High vegetation</b>	1,916,365
<b>Building</b>	532,466
<b>Orthophoto</b>	None
<b>Processed by</b>	Engr. Regis Guhiting, Engr. Jovelle Anjeanette Canlas, Engr. Melissa Fernandez

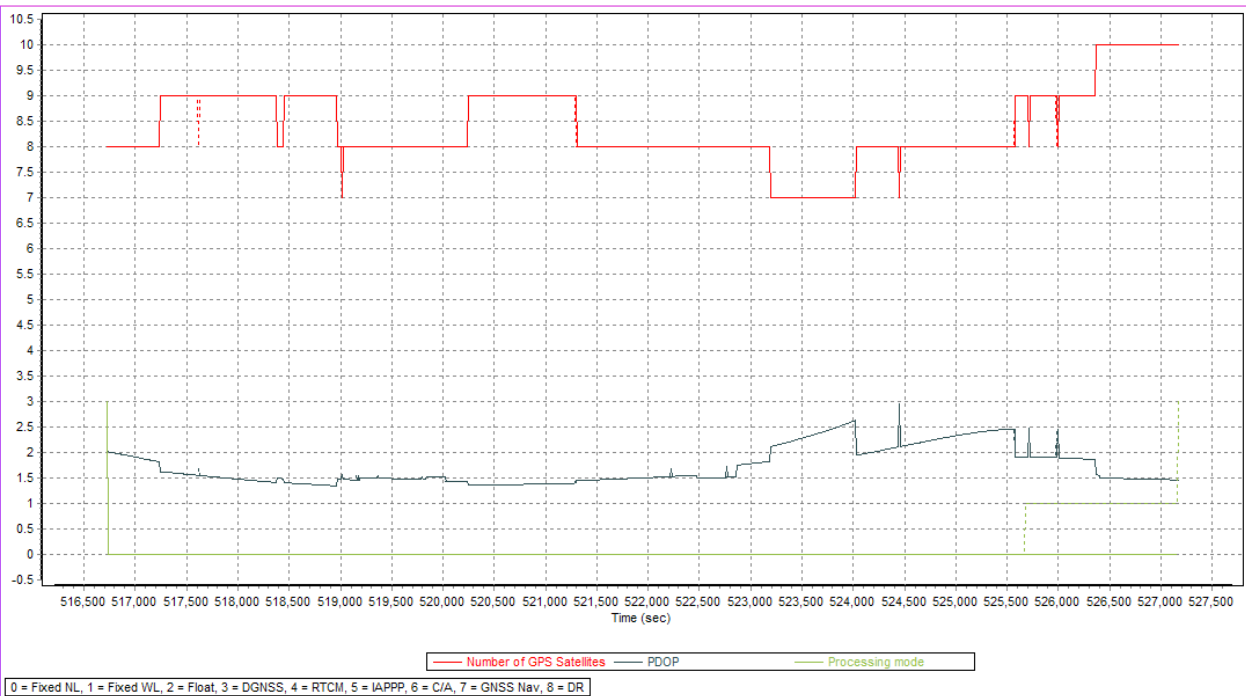


Figure A-8.141. Solution Status

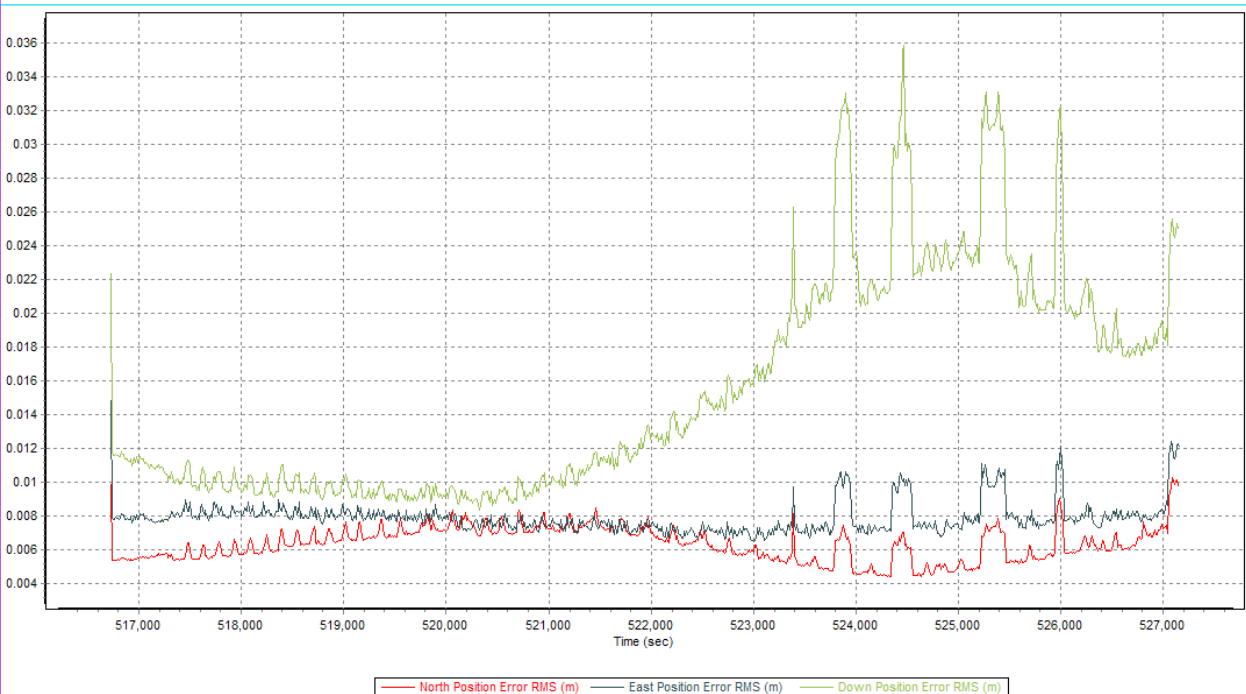


Figure A-8.142. Smoothed Performance Metrics Parameters

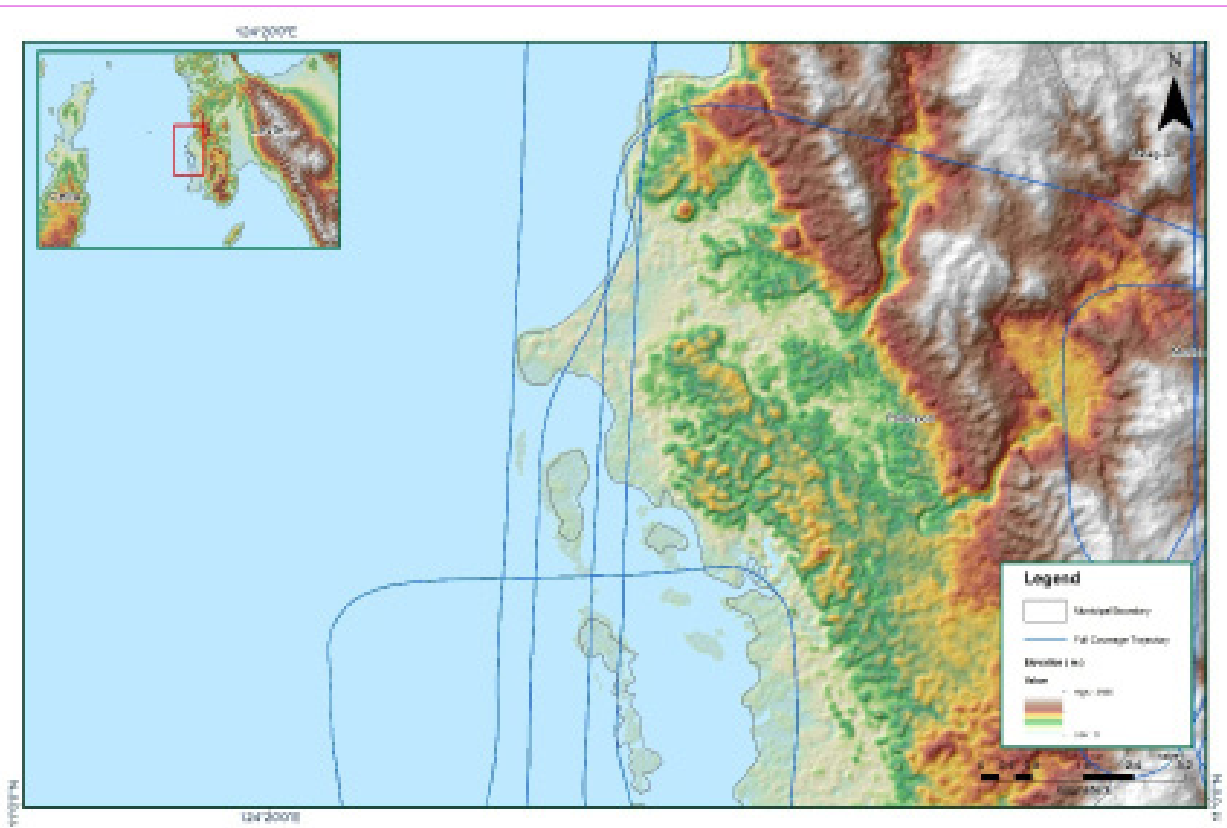


Figure A-8.143. Best Estimated Trajectory

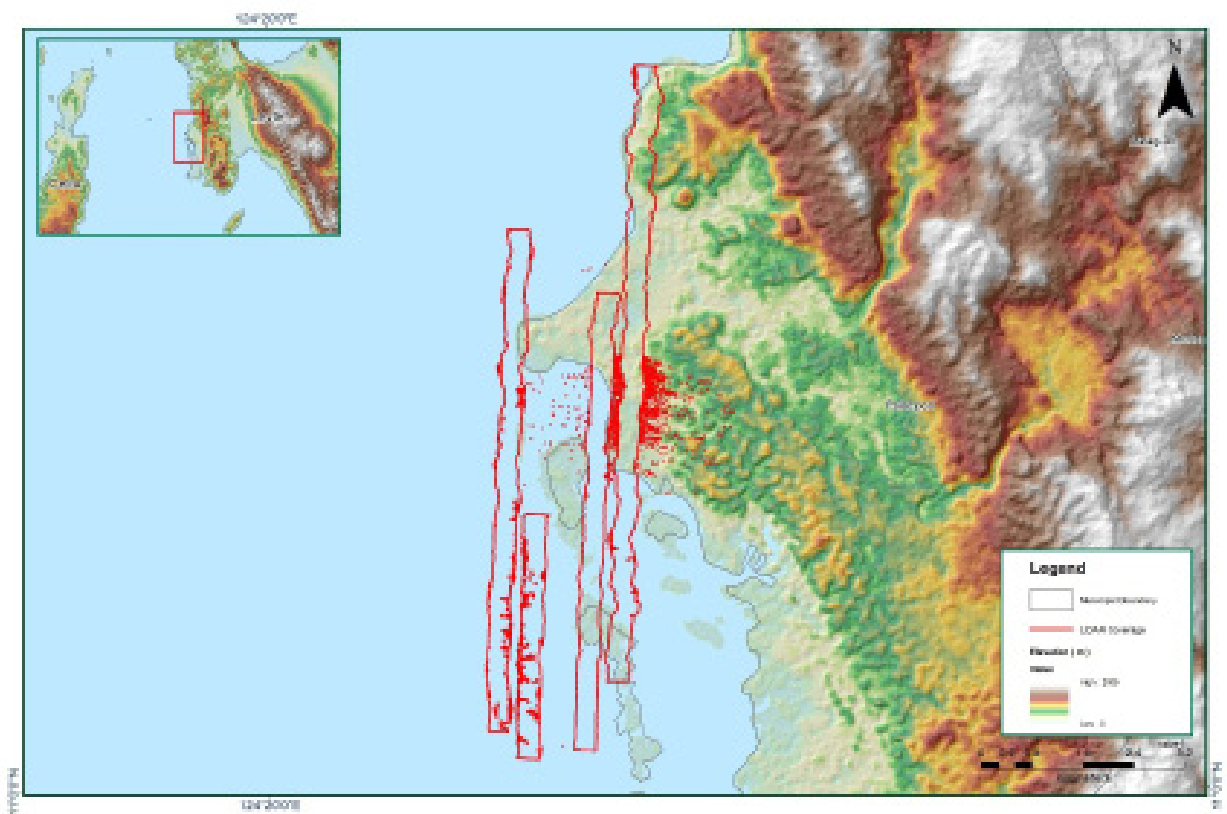


Figure A-8.144. Best Estimated Trajectory



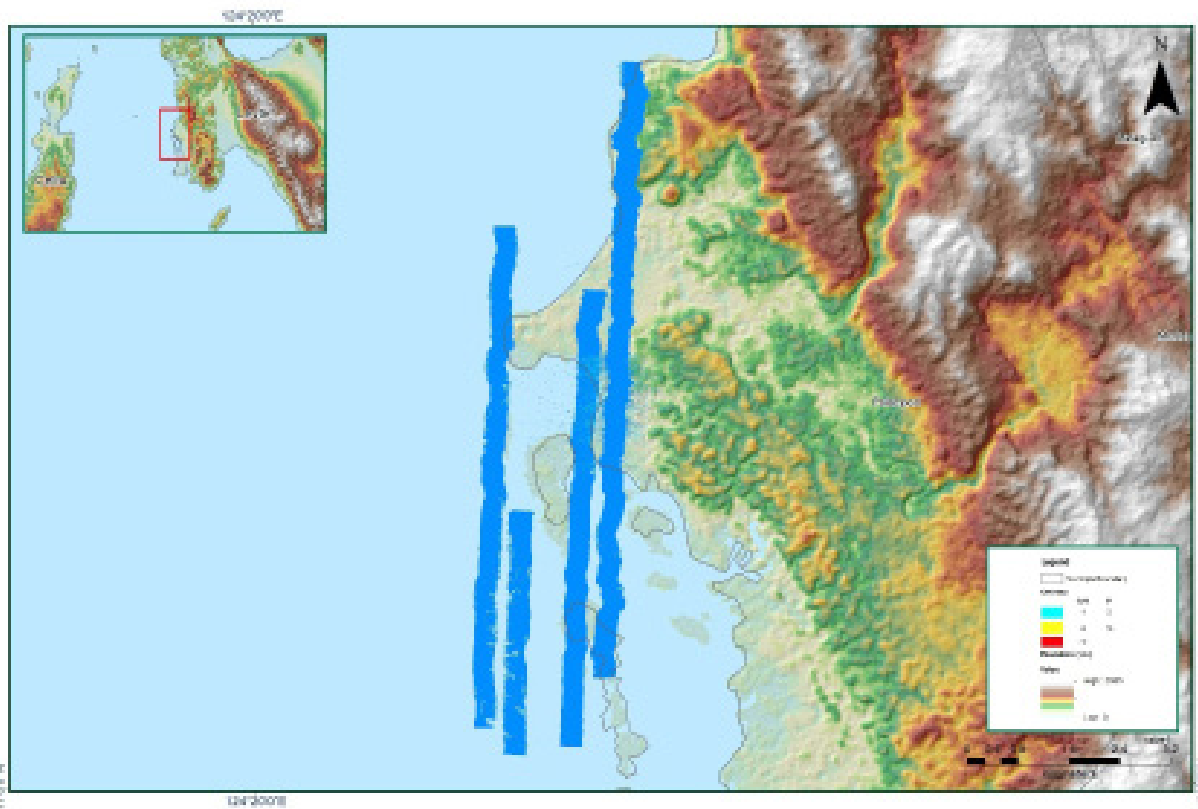


Figure A-8.145. Image of data overlap

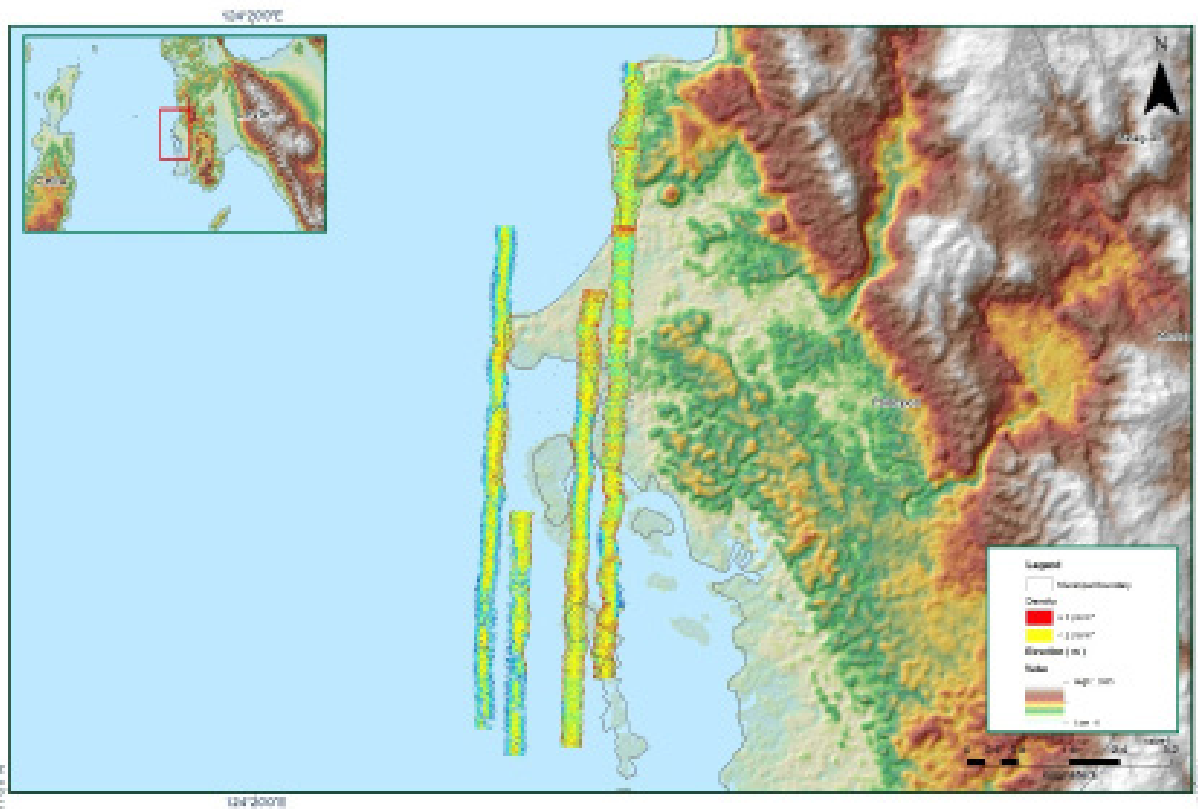


Figure A-8.146. Density map of merged LiDAR data

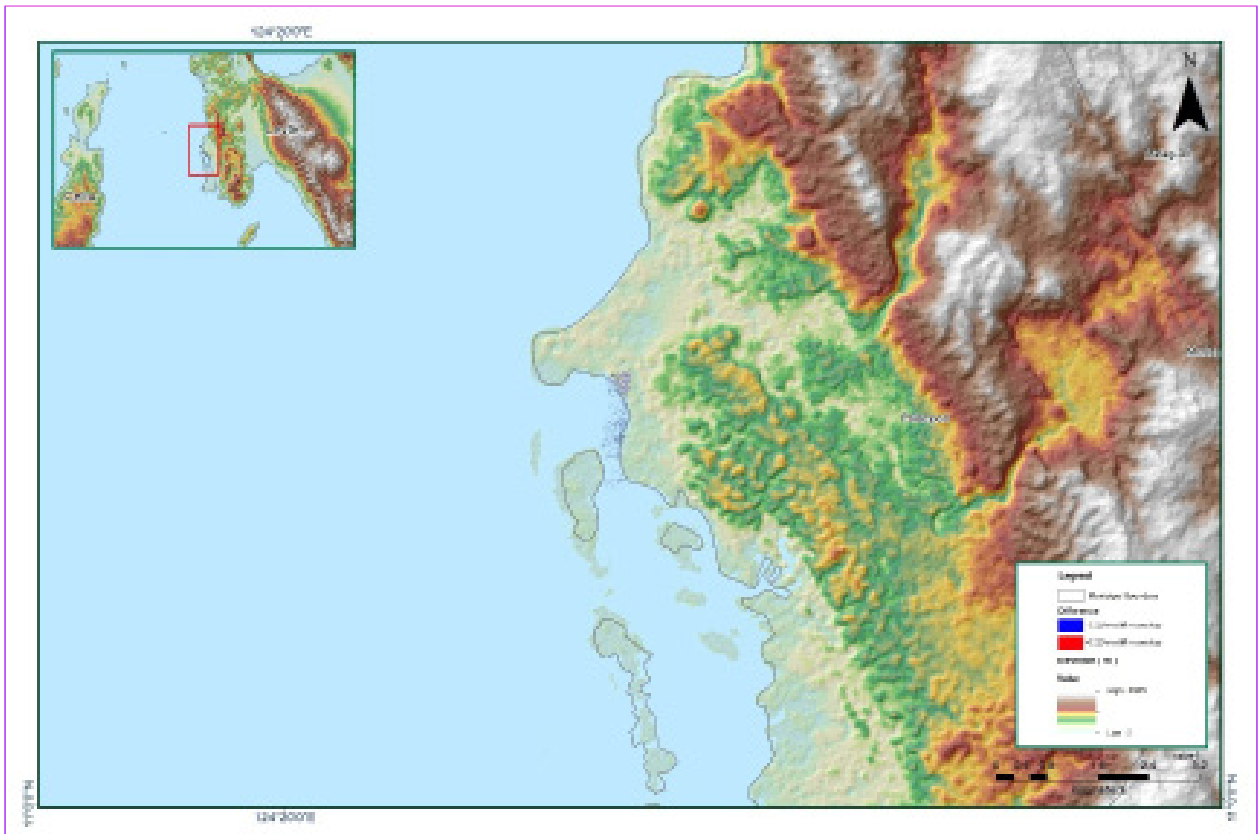


Figure A-8.147. Elevation difference between flight lines

Table A-8.22. Mission Summary Report for Mission Blk35G

<b>Flight Area</b>	<b>Ormoc_Camotes</b>
<b>Mission Name</b>	Blk35G
<b>Inclusive Flights</b>	8392AC
<b>Range data size</b>	9.68 GB
<b>POS</b>	198 MB
<b>Image</b>	37.6 MB
<b>Base Station</b>	265 MB
<b>Transfer date</b>	March 28, 2016
<b>Solution Status</b>	
<b>Number of Satellites (&gt;6)</b>	Yes
<b>PDOP (&lt;3)</b>	No
<b>Baseline Length (&lt;30km)</b>	Yes
<b>Processing Mode (&lt;=1)</b>	No
<b>Smoothed Performance Metrics (in cm)</b>	
<b>RMSE for North Position (&lt;4.0 cm)</b>	1.04
<b>RMSE for East Position (&lt;4.0 cm)</b>	1.09
<b>RMSE for Down Position (&lt;8.0 cm)</b>	2.63
<b>Boresight correction stdev (&lt;0.001deg)</b>	0.000461
<b>IMU attitude correction stdev (&lt;0.001deg)</b>	0.002204
<b>GPS position stdev (&lt;0.01m)</b>	0.0028
<b>Minimum % overlap (&gt;25)</b>	37.05
<b>Ave point cloud density per sq.m. (&gt;2.0)</b>	3.00
<b>Elevation difference between strips (&lt;0.20 m)</b>	Yes
<b>Number of 1km x 1km blocks</b>	76
<b>Maximum Height</b>	167.26
<b>Minimum Height</b>	51.39
<b>Classification (# of points)</b>	
<b>Ground</b>	23,865,146
<b>Low vegetation</b>	25,929,146
<b>Medium vegetation</b>	44,569,409
<b>High vegetation</b>	34,437,062
<b>Building</b>	780,530
<b>Orthophoto</b>	None
<b>Processed by</b>	Engr. Irish Cortez, Engr. Christy Lubiano, Jovy Narisma

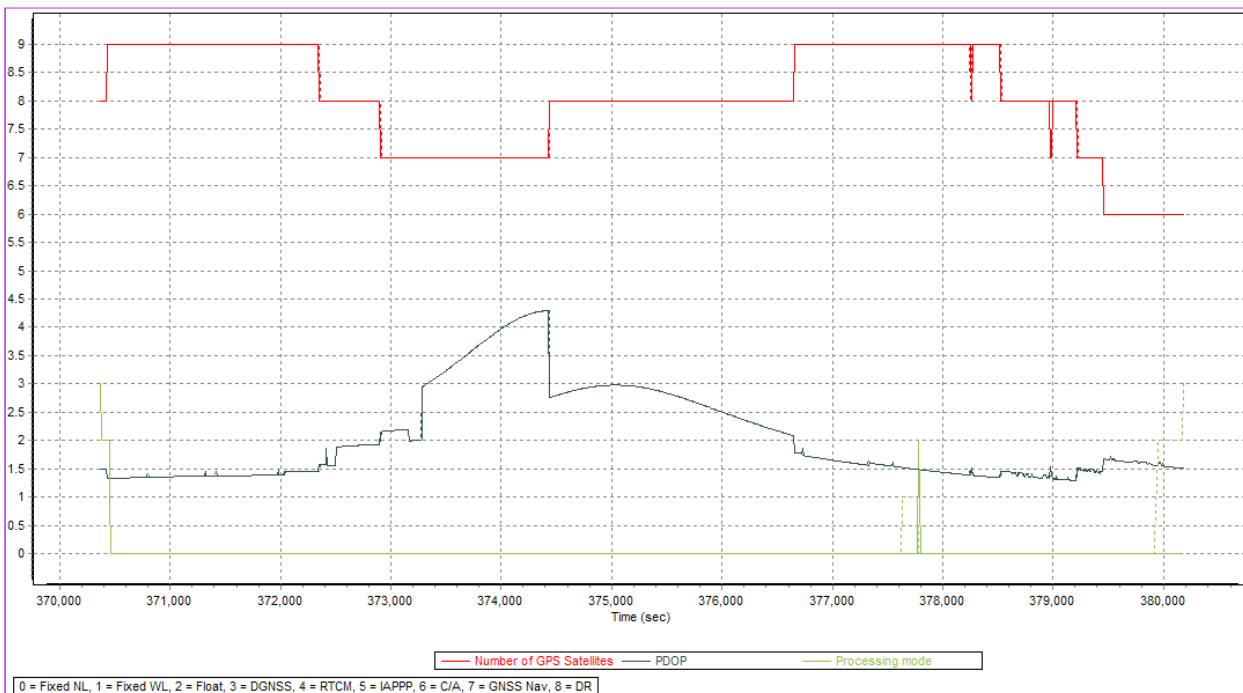


Figure A-8.148. Solution Status

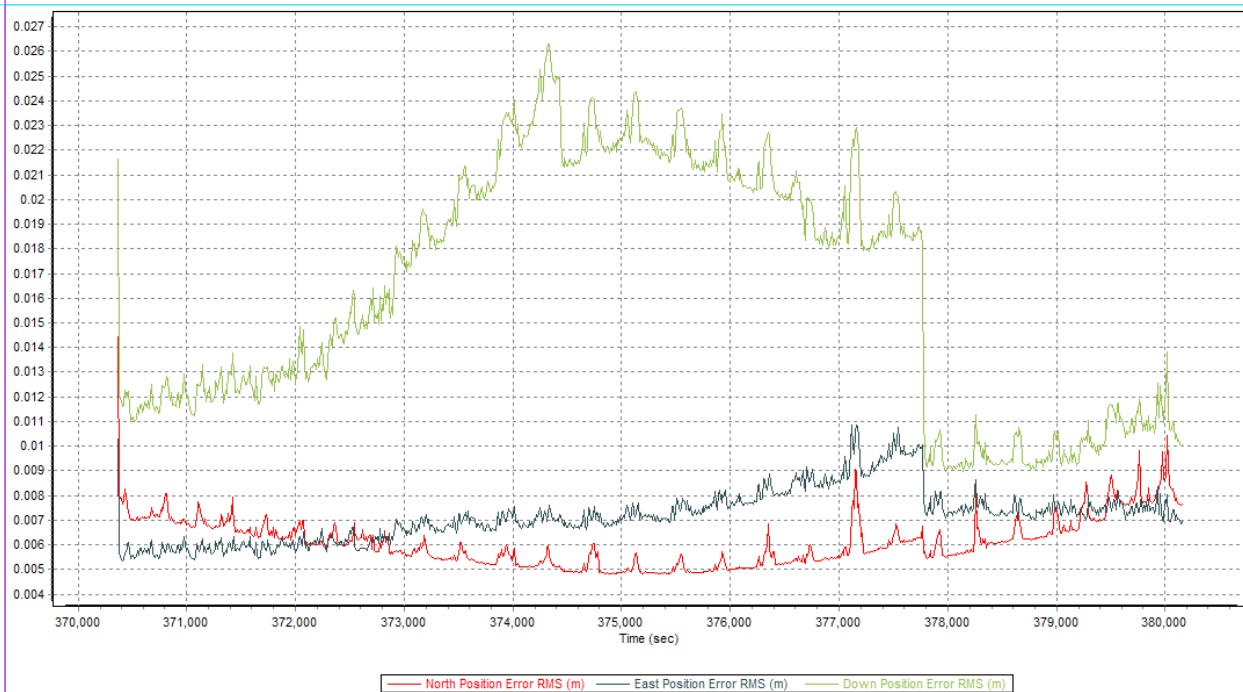


Figure A-8.149. Smoothed Performance Metrics Parameters

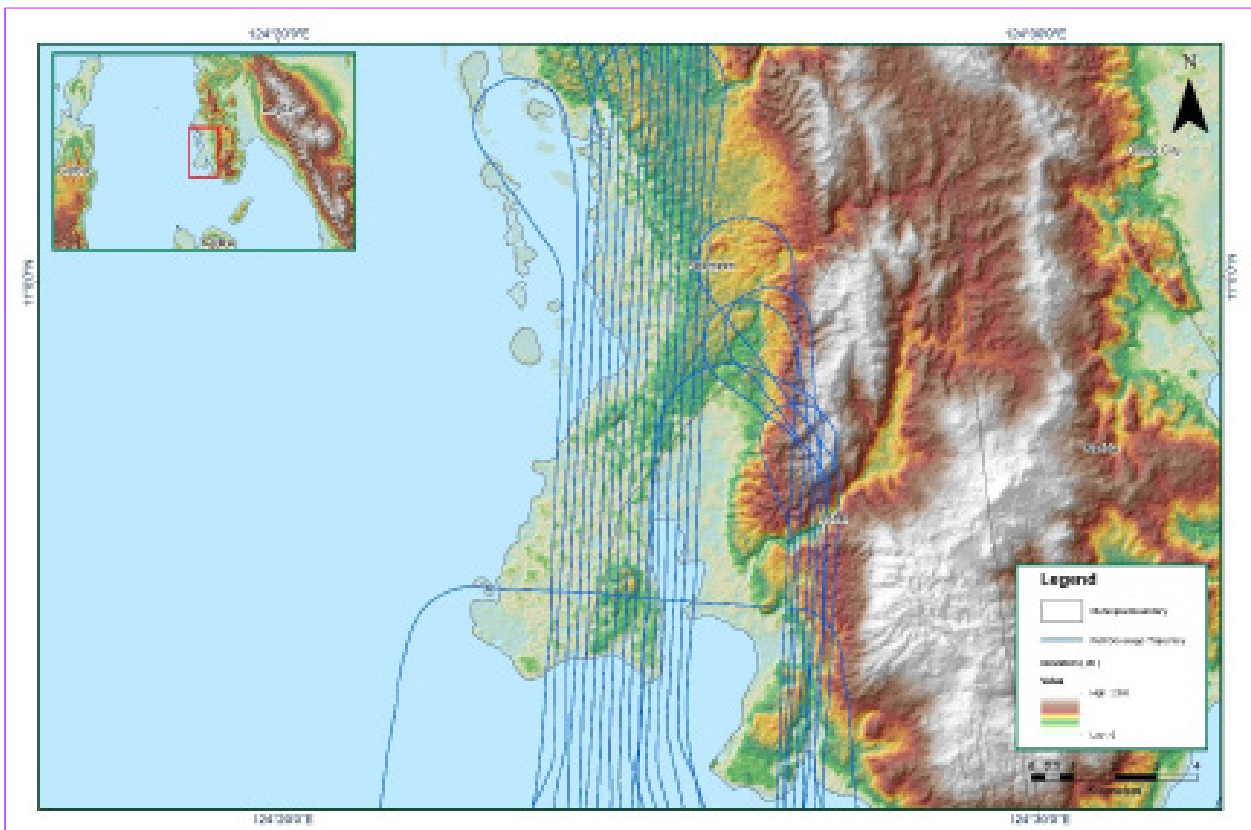


Figure A-8.150. Best Estimated Trajectory

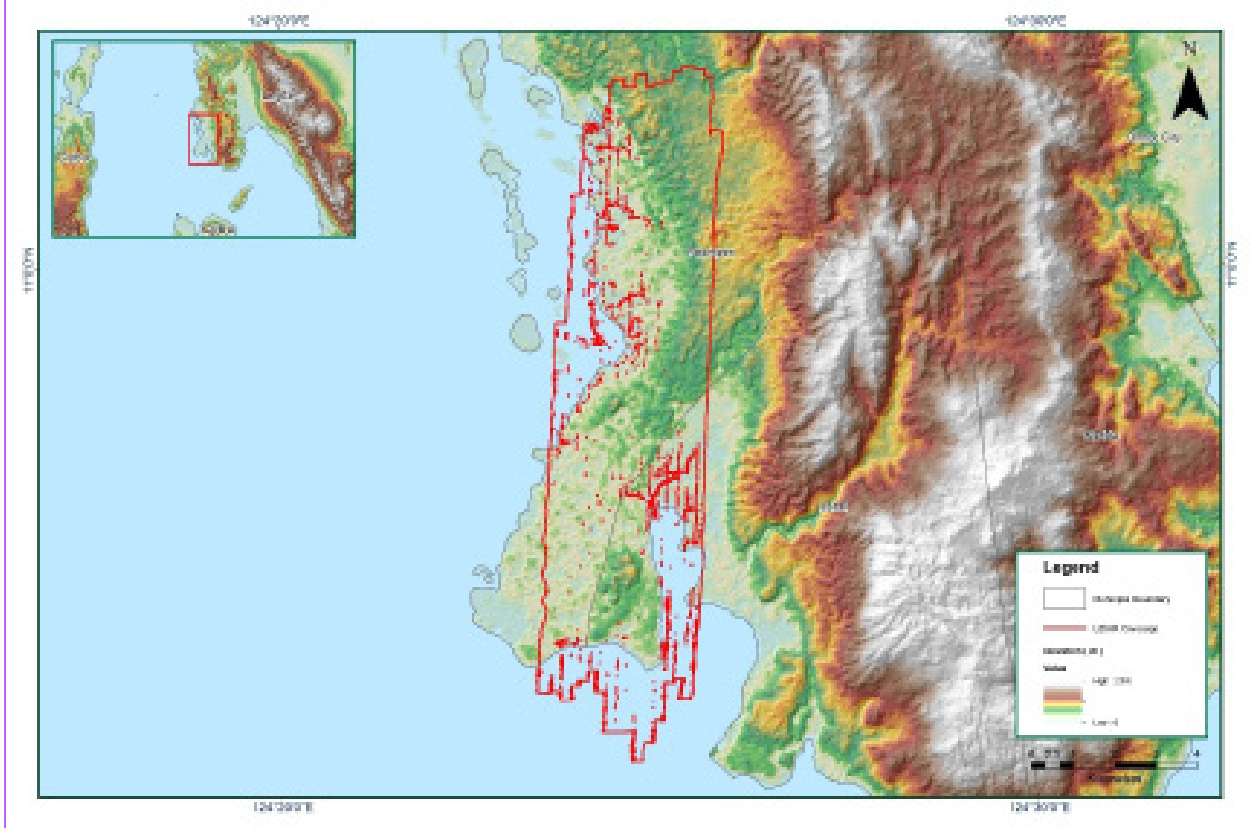


Figure A-8.151. Coverage of LiDAR data

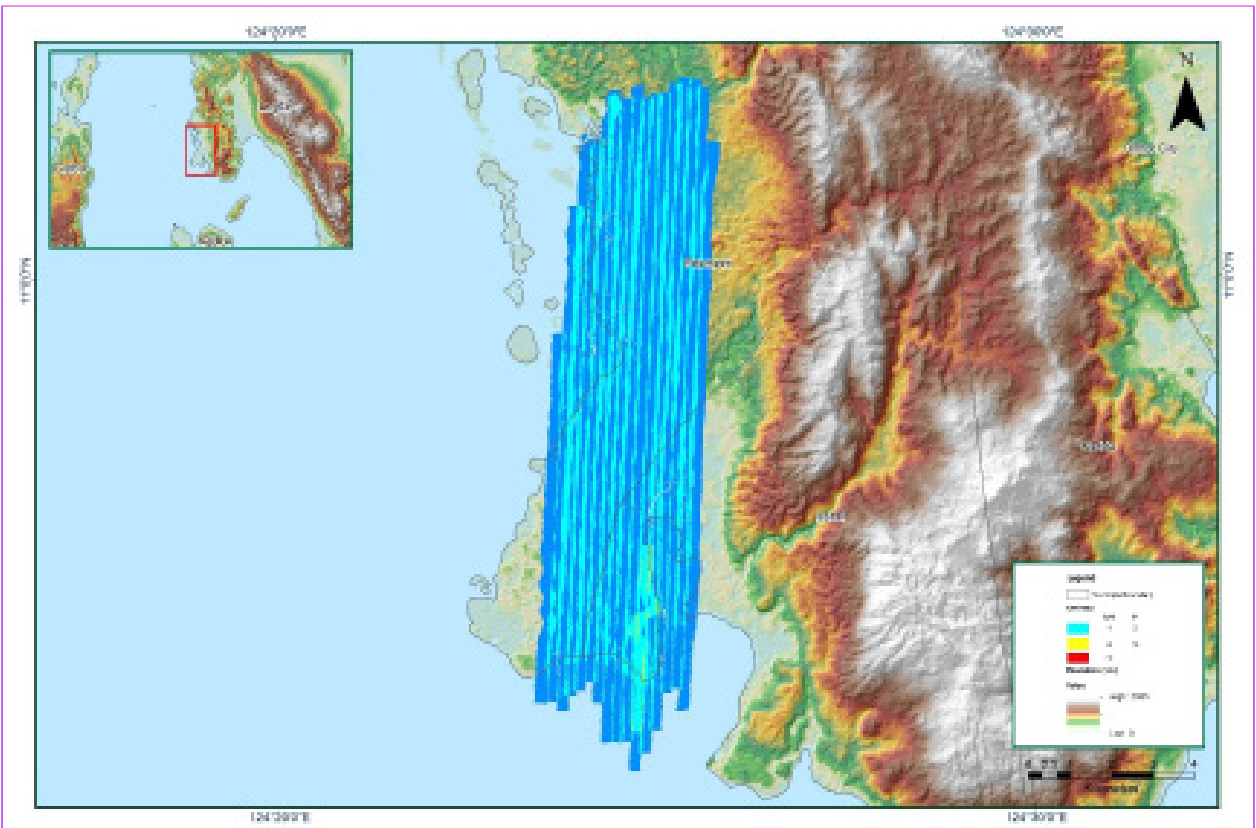


Figure A-8.152. Image of data overlap

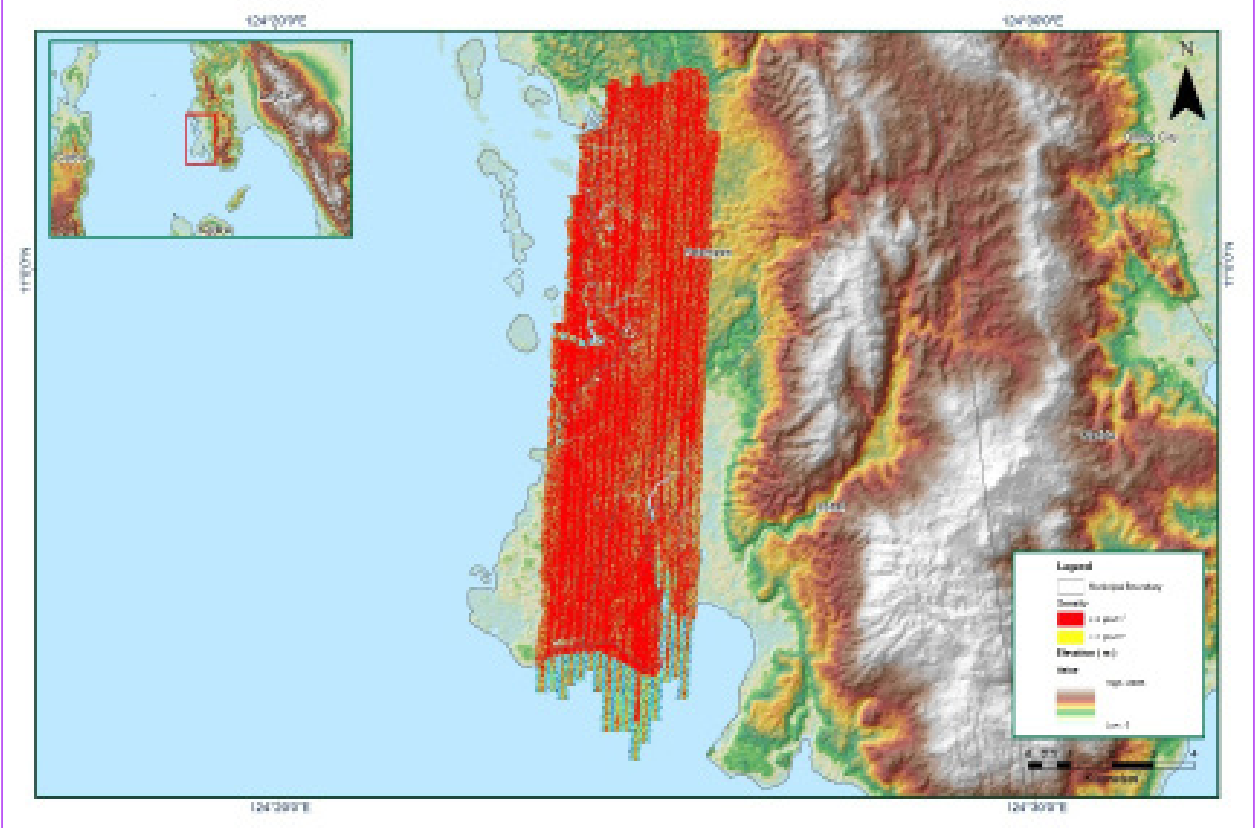


Figure A-8.153. Density map of merged LIDAR data

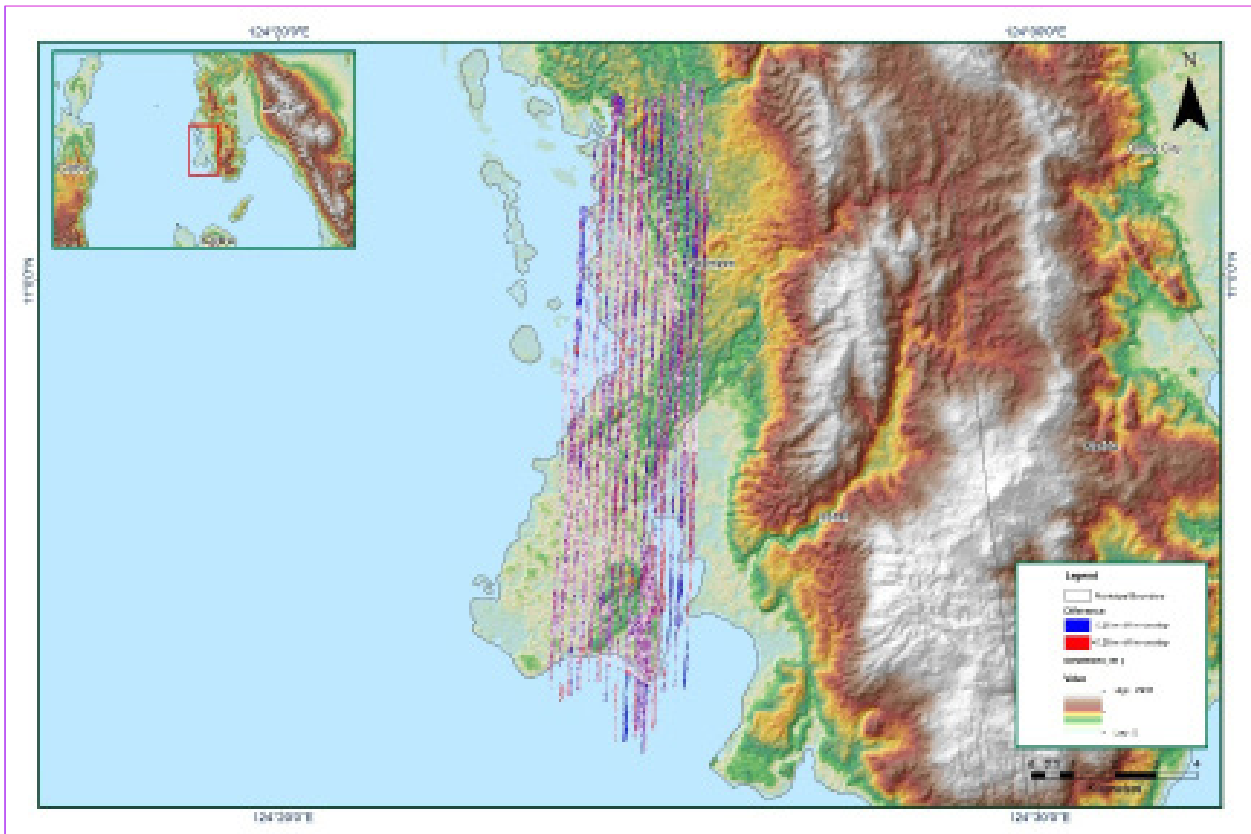


Figure A-8.154. Elevation difference between flight lines

Table A-8.23. Mission Summary Report for Mission Blk35H

Flight Area	Ormoc_Camotes
<b>Mission Name</b>	Blk35H
<b>Inclusive Flights</b>	8392A
<b>Range data size</b>	9.68 GB
<b>POS</b>	198 MB
<b>Image</b>	37.6 MB
<b>Base Station</b>	265 MB
<b>Transfer date</b>	March 28, 2016
<b>Solution Status</b>	
<b>Number of Satellites (&gt;6)</b>	Yes
<b>PDOP (&lt;3)</b>	No
<b>Baseline Length (&lt;30km)</b>	Yes
<b>Processing Mode (&lt;=1)</b>	No
<b>Smoothed Performance Metrics (in cm)</b>	
<b>RMSE for North Position (&lt;4.0 cm)</b>	1.04
<b>RMSE for East Position (&lt;4.0 cm)</b>	1.09
<b>RMSE for Down Position (&lt;8.0 cm)</b>	2.63
<b>Boresight correction stdev (&lt;0.001deg)</b>	0.000461
<b>IMU attitude correction stdev (&lt;0.001deg)</b>	0.002204
<b>GPS position stdev (&lt;0.01m)</b>	0.0028
<b>Minimum % overlap (&gt;25)</b>	56.10
<b>Ave point cloud density per sq.m. (&gt;2.0)</b>	3.96
<b>Elevation difference between strips (&lt;0.20 m)</b>	Yes
<b>Number of 1km x 1km blocks</b>	28
<b>Maximum Height</b>	277.27
<b>Minimum Height</b>	56.77
<b>Classification (# of points)</b>	
<b>Ground</b>	8,304,789
<b>Low vegetation</b>	8,090,694
<b>Medium vegetation</b>	12,141,801
<b>High vegetation</b>	16,625,105
<b>Building</b>	1,890,226
<b>Orthophoto</b>	None
<b>Processed by</b>	Engr. Irish Cortez, Engr. Chelou Prado, Engr. Elaine Lopez



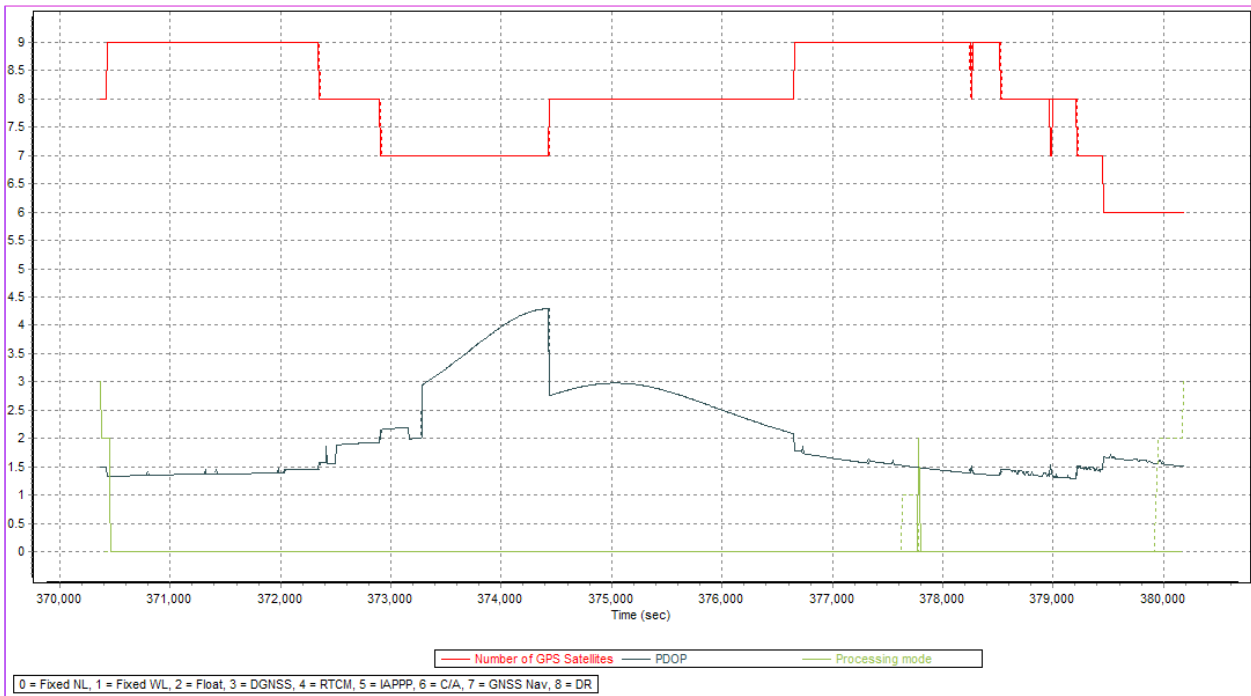


Figure A-8.155. Solution Status

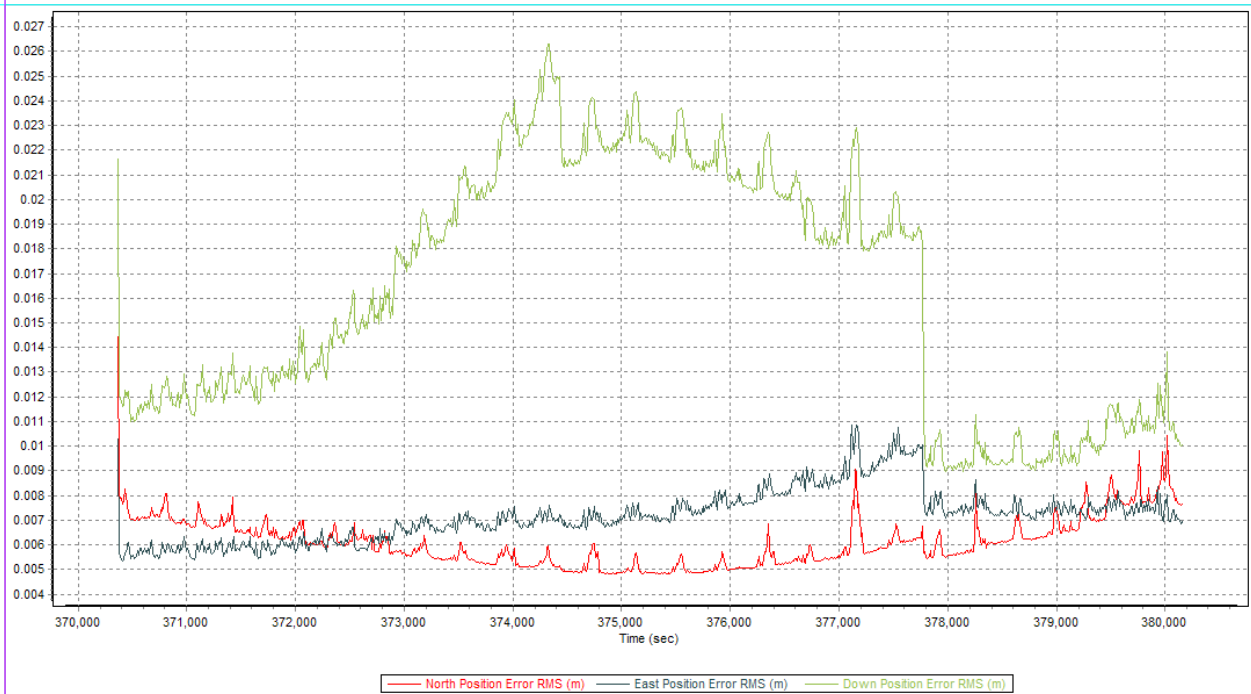


Figure A-8.156. Smoothed Performance Metrics Parameters

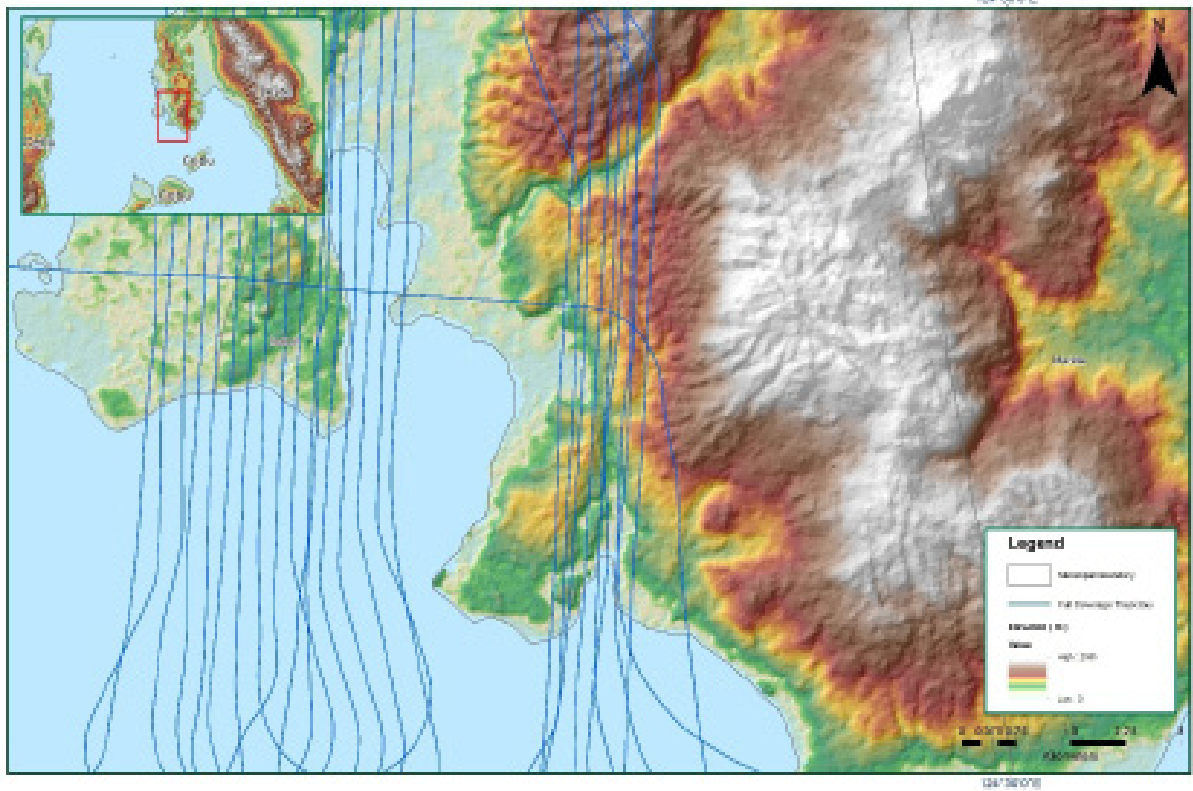


Figure A-8.157. Best Estimated Trajectory

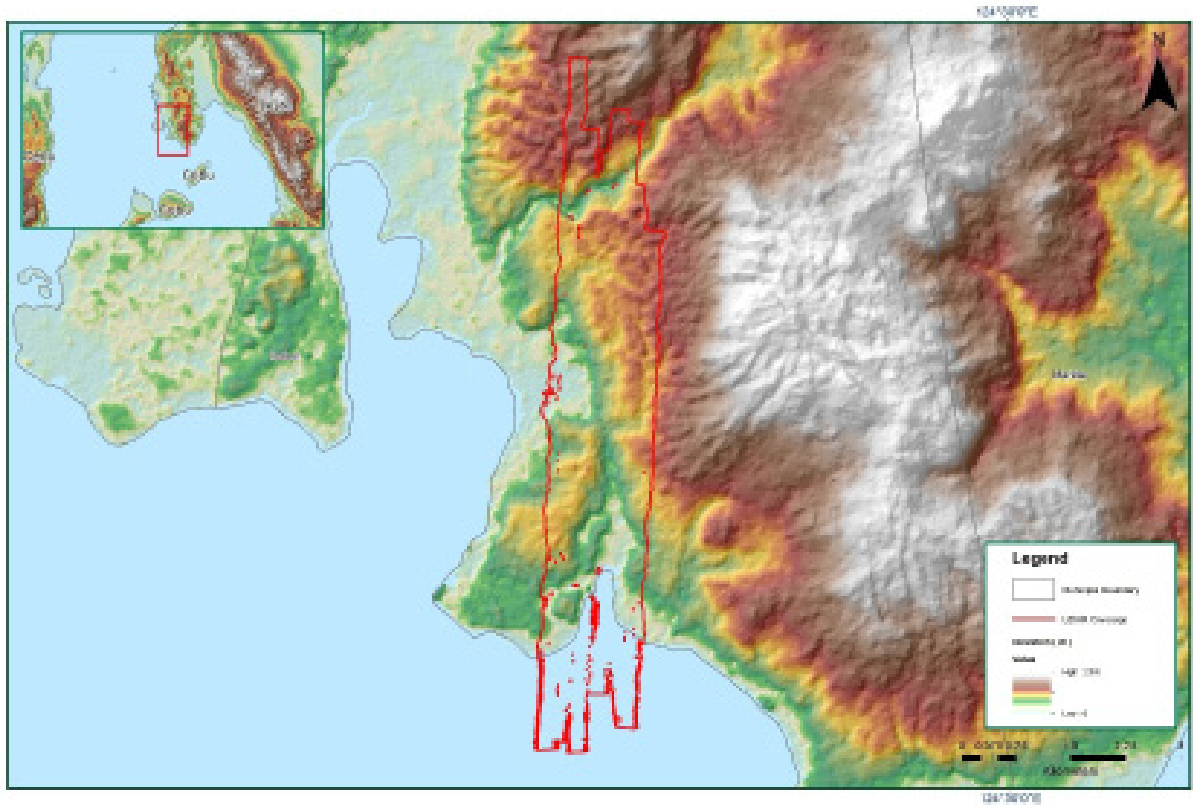


Figure A-8.158. Best Estimated Trajectory

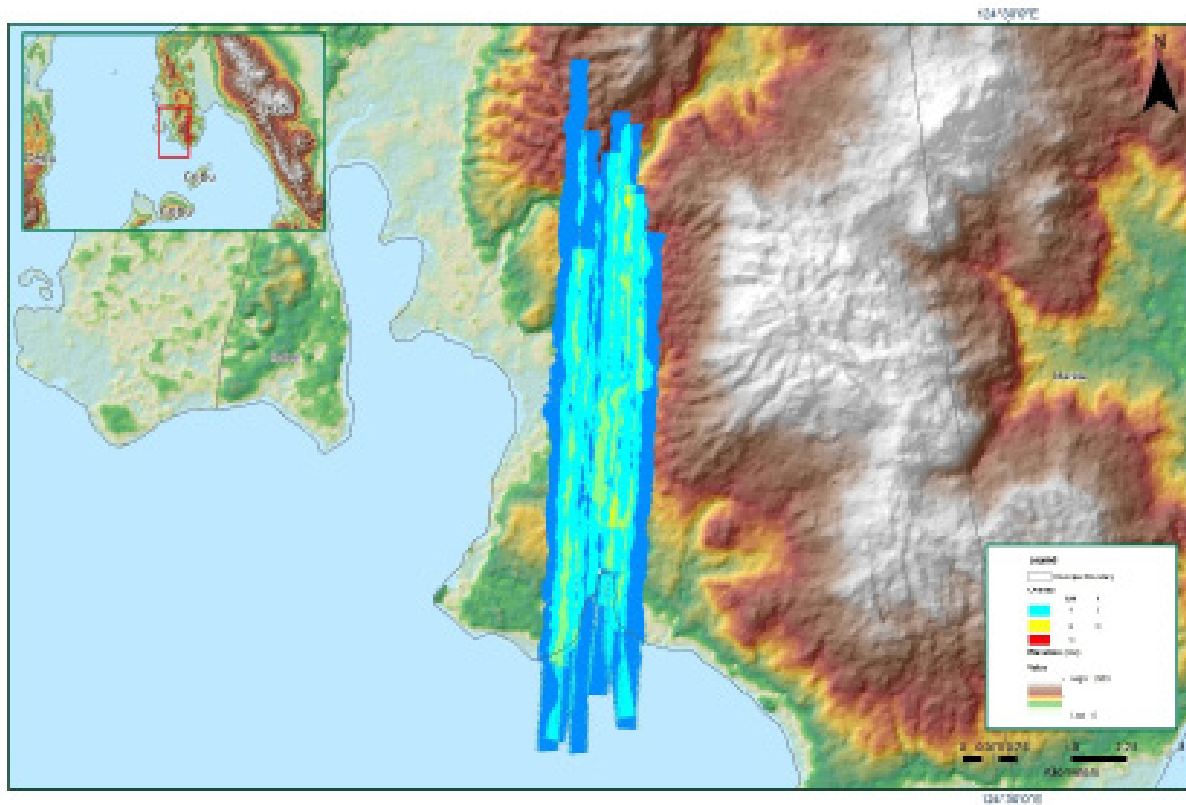


Figure A-8.159. Image of data overlap

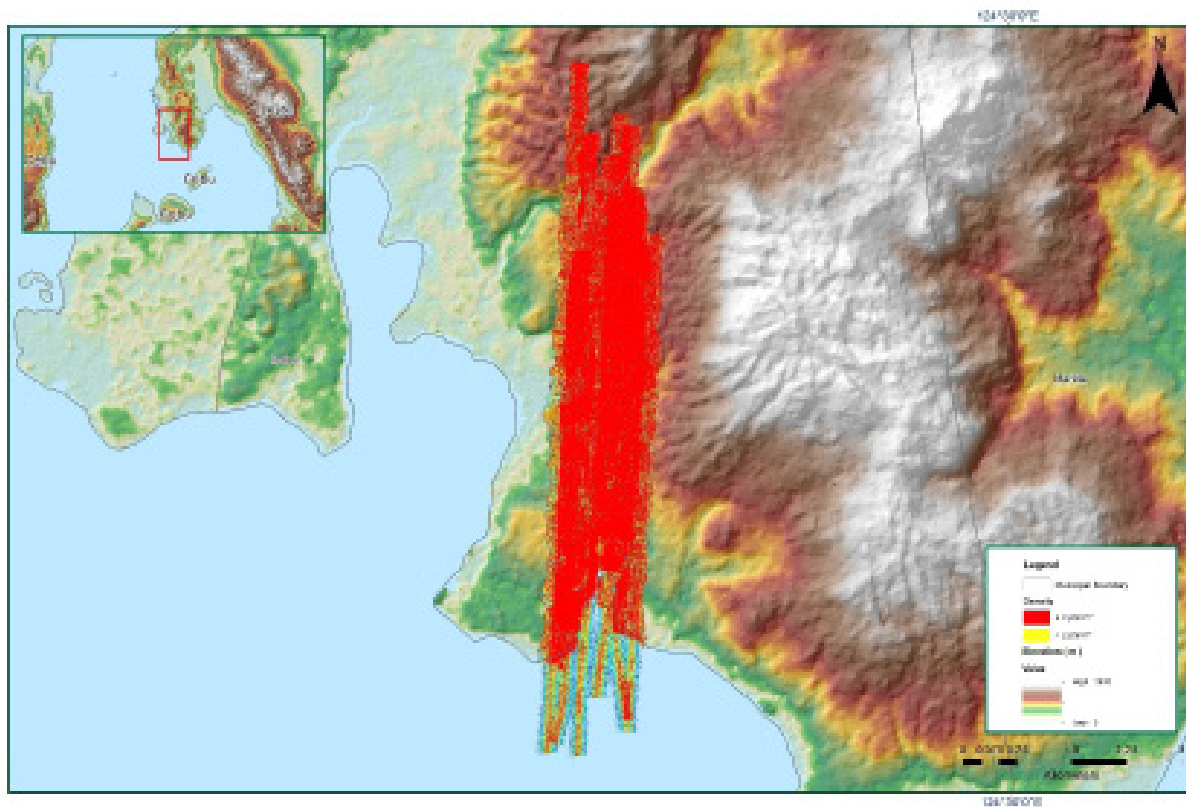


Figure A-8.160. Density map of merged LiDAR data

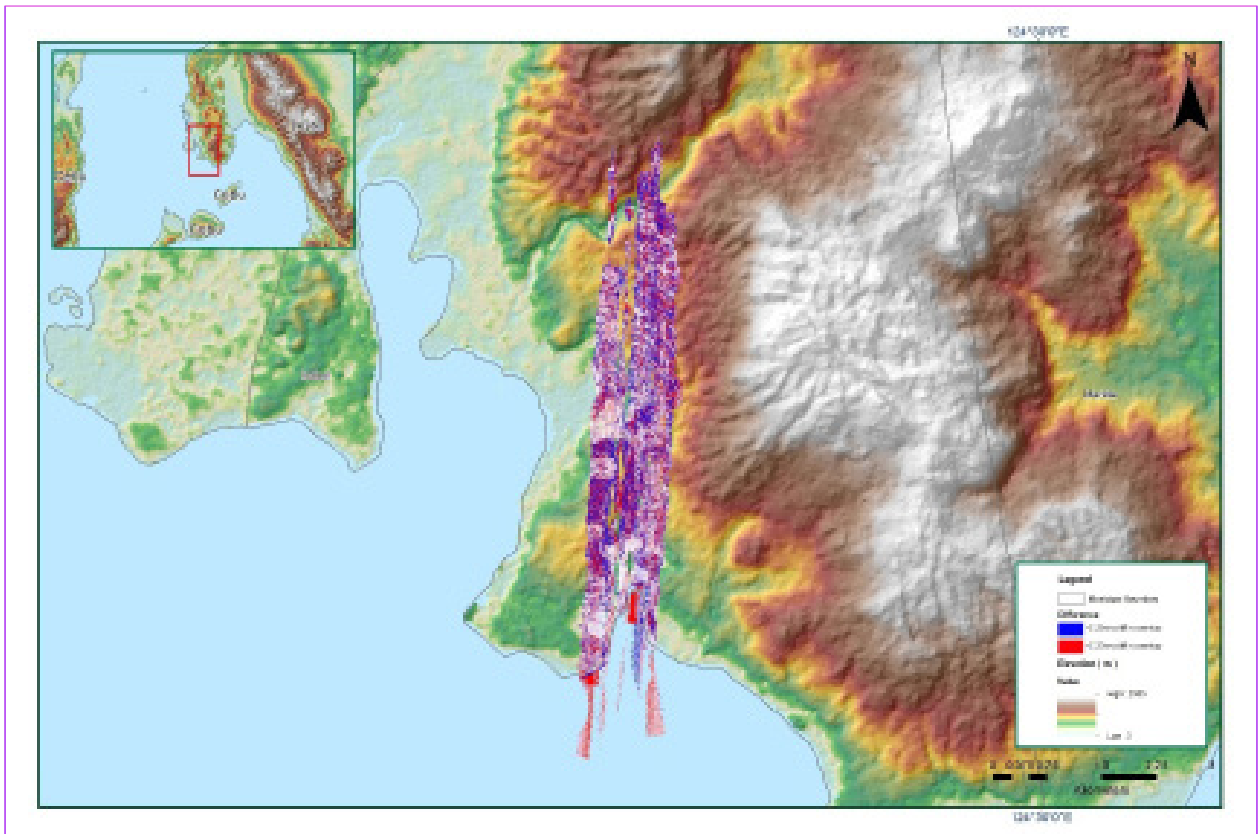


Figure A-8.161. Elevation difference between flight lines

Table A-8.24. Mission Summary Report for Mission Blk35H\_Supplement

<b>Flight Area</b>	<b>Ormoc_Camotes</b>
<b>Mission Name</b>	Blk35H_Supplement
<b>Inclusive Flights</b>	8408AC
<b>Range data size</b>	5.14 GB
<b>POS</b>	208 MB
<b>Image</b>	56.3 MB
<b>Base Station</b>	263 MB
<b>Transfer date</b>	April 22, 2016
<b>Solution Status</b>	
<b>Number of Satellites (&gt;6)</b>	Yes
<b>PDOP (&lt;3)</b>	Yes
<b>Baseline Length (&lt;30km)</b>	Yes
<b>Processing Mode (&lt;=1)</b>	Yes
<b>Smoothed Performance Metrics (in cm)</b>	
<b>RMSE for North Position (&lt;4.0 cm)</b>	1.03
<b>RMSE for East Position (&lt;4.0 cm)</b>	1.24
<b>RMSE for Down Position (&lt;8.0 cm)</b>	3.59
<b>Boresight correction stdev (&lt;0.001deg)</b>	N/A
<b>IMU attitude correction stdev (&lt;0.001deg)</b>	N/A
<b>GPS position stdev (&lt;0.01m)</b>	N/A
<b>Minimum % overlap (&gt;25)</b>	41.06
<b>Ave point cloud density per sq.m. (&gt;2.0)</b>	2.81
<b>Elevation difference between strips (&lt;0.20 m)</b>	Yes
<b>Number of 1km x 1km blocks</b>	42
<b>Maximum Height</b>	438.66
<b>Minimum Height</b>	45.93
<b>Classification (# of points)</b>	
<b>Ground</b>	13,820,590
<b>Low vegetation</b>	6,300,170
<b>Medium vegetation</b>	12,967,315
<b>High vegetation</b>	22,021,720
<b>Building</b>	859,613
<b>Orthophoto</b>	None
<b>Processed by</b>	Engr. Regis Guhiting, Aljon Rie Araneta, Engr. Czarina Jean Añonuevo

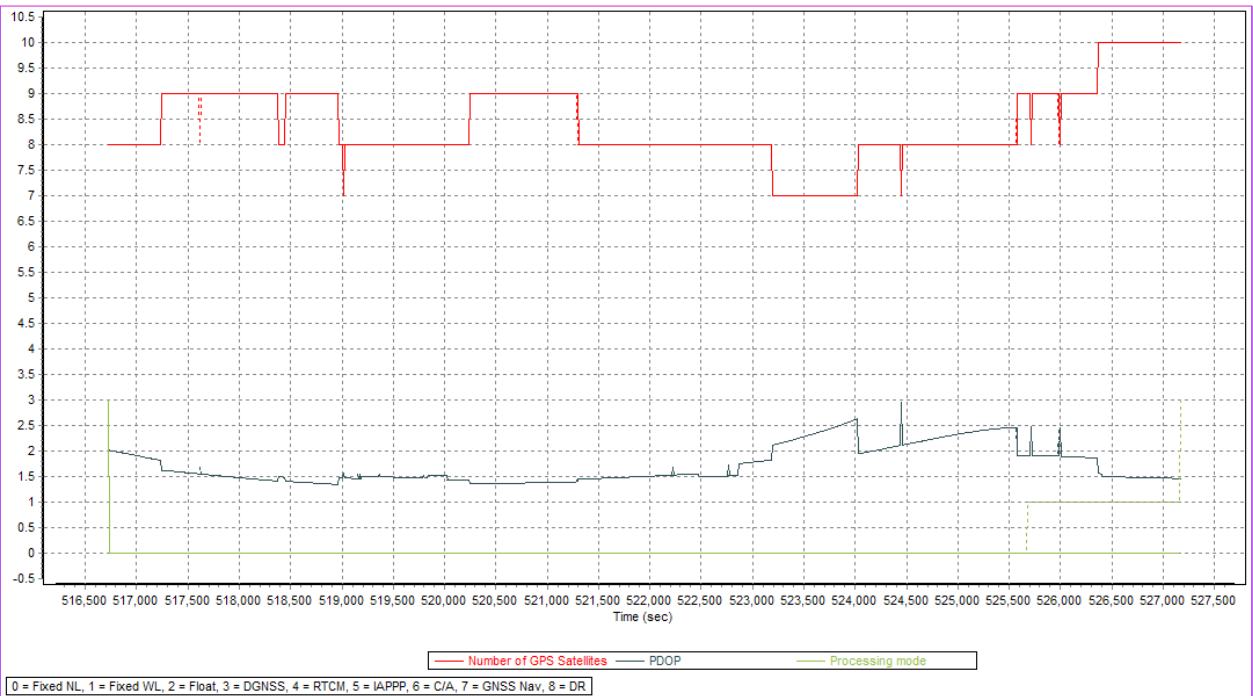


Figure A-8.162. Solution Status

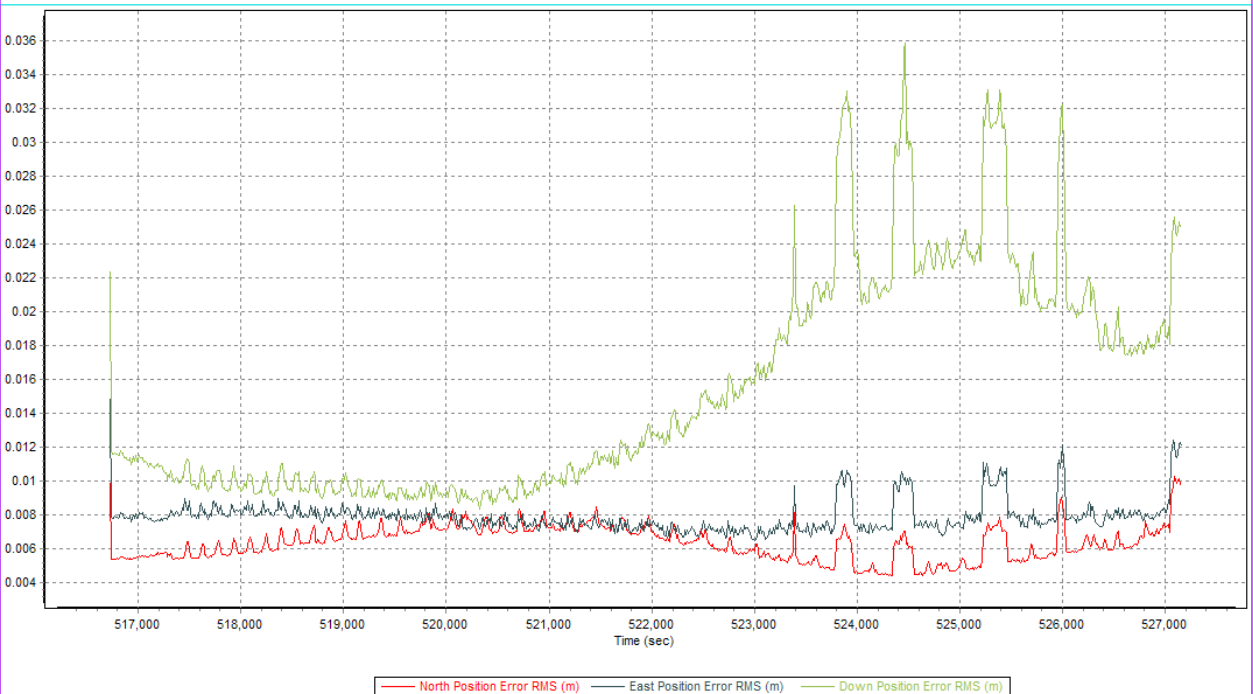


Figure A-8.163. Smoothed Performance Metrics Parameters

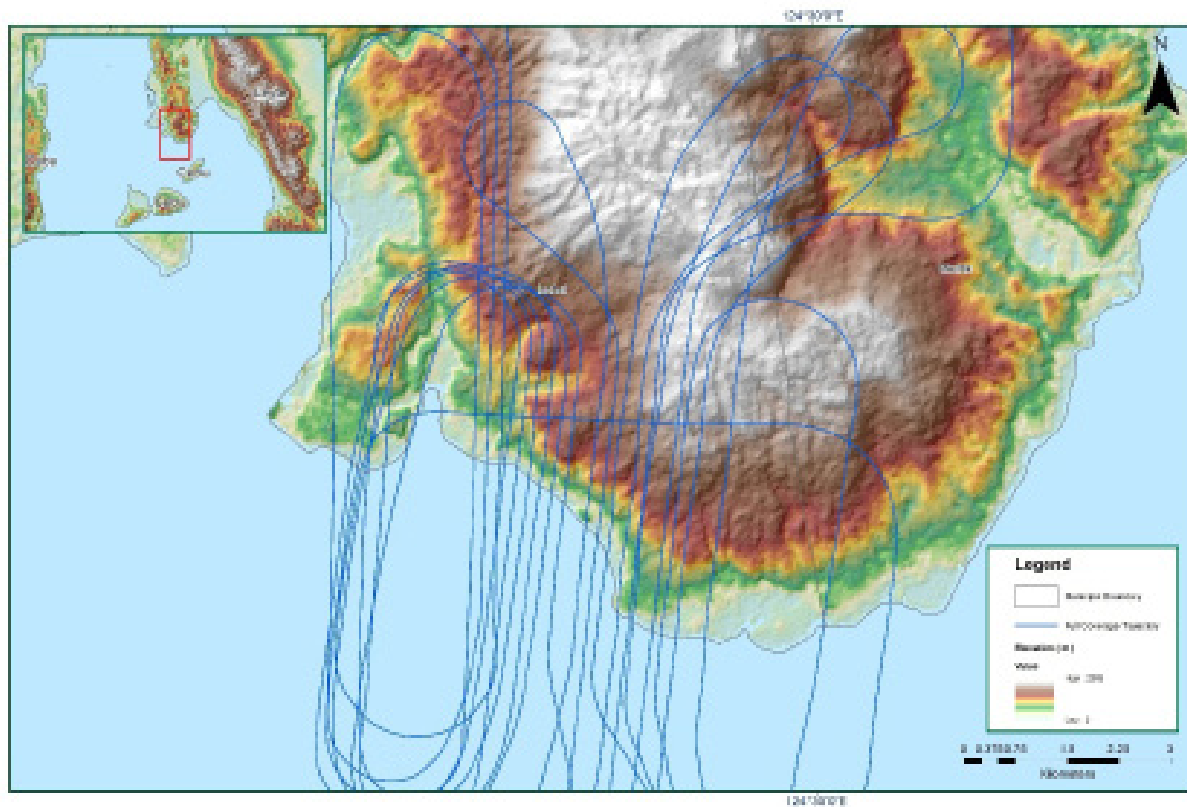


Figure A-8.164. Best Estimated Trajectory

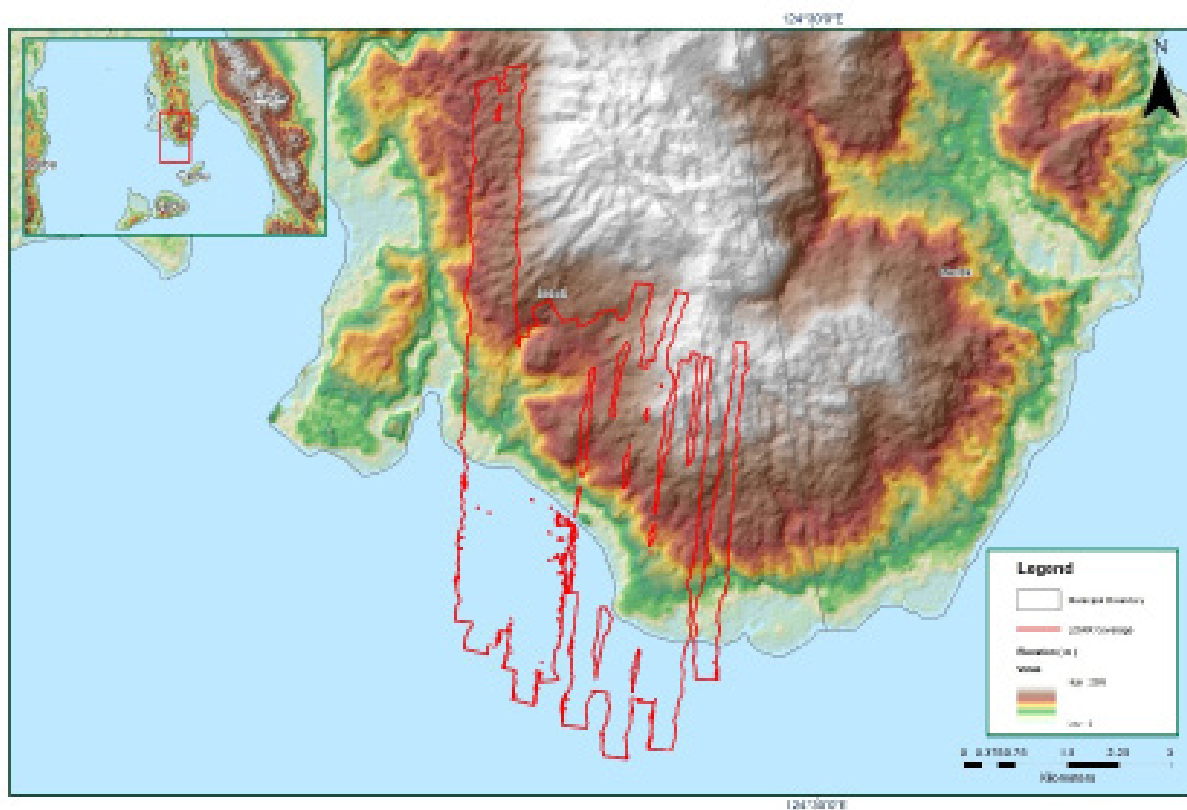


Figure A-8.165. Coverage of LiDAR data

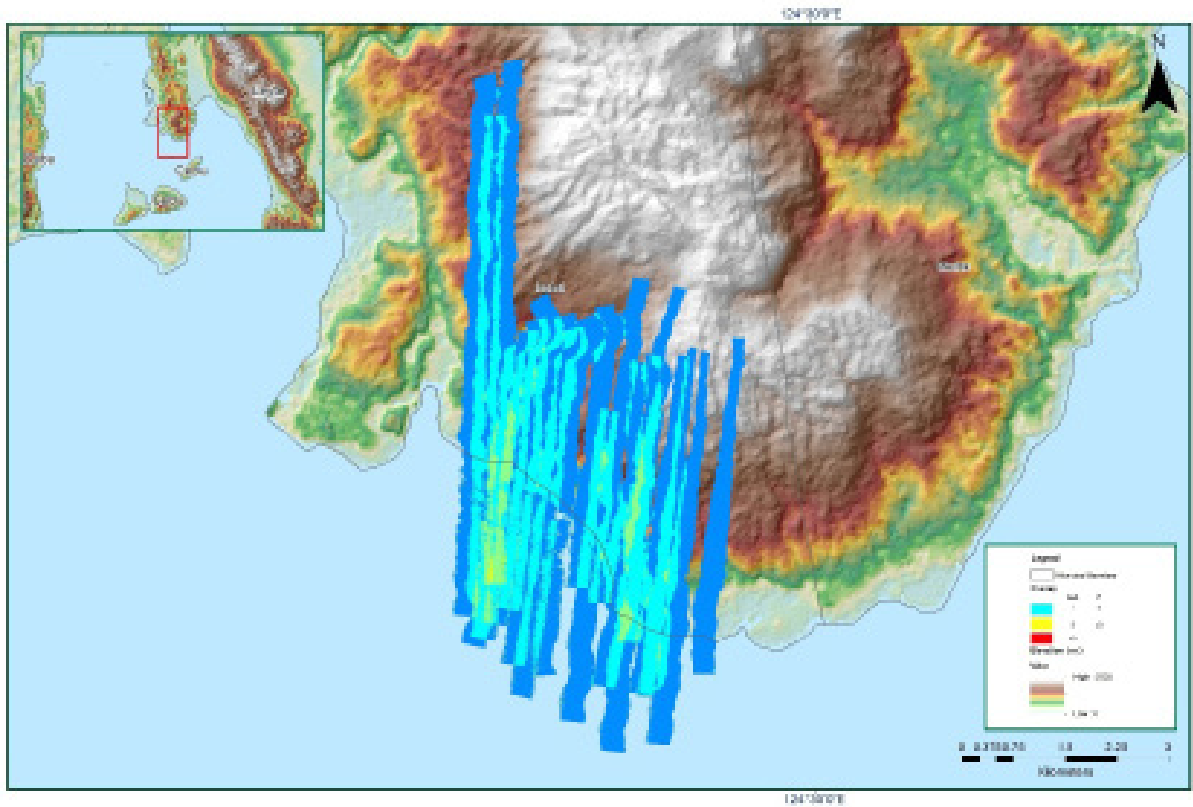


Figure A-8.166. Image of data overlap

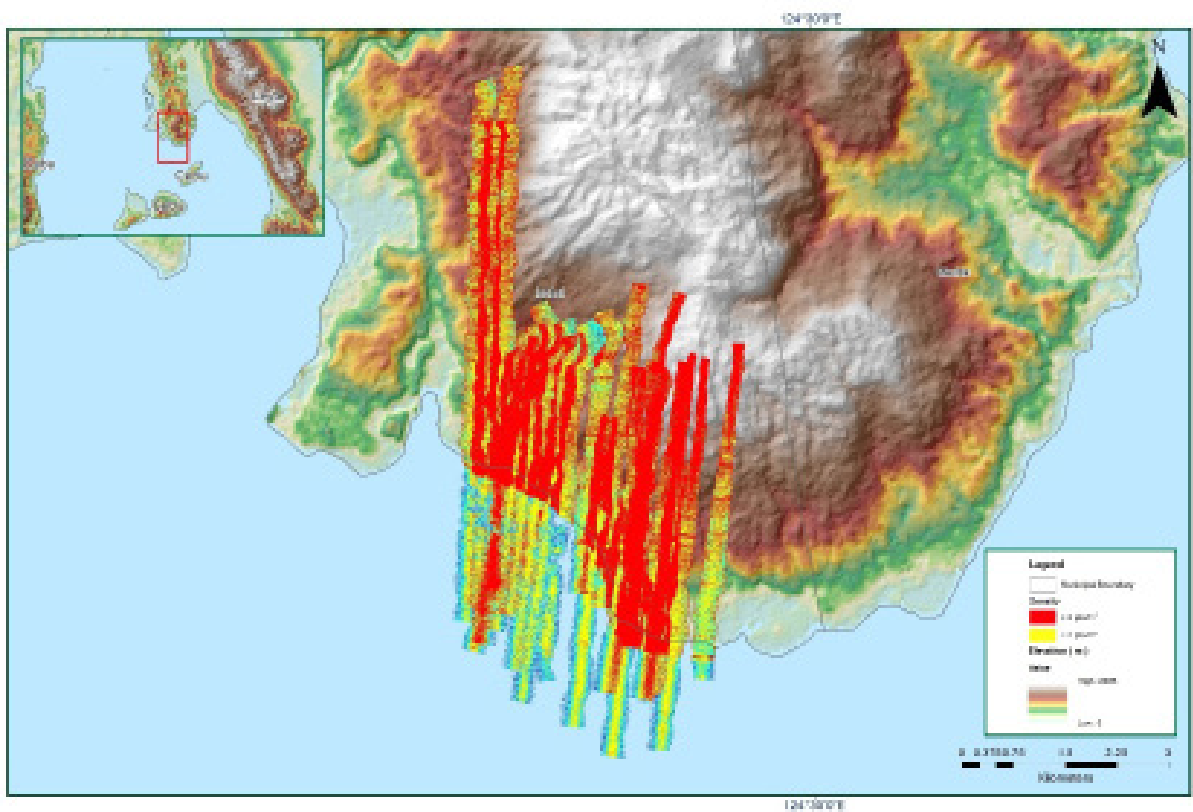


Figure A-8.167. Density map of merged LiDAR data



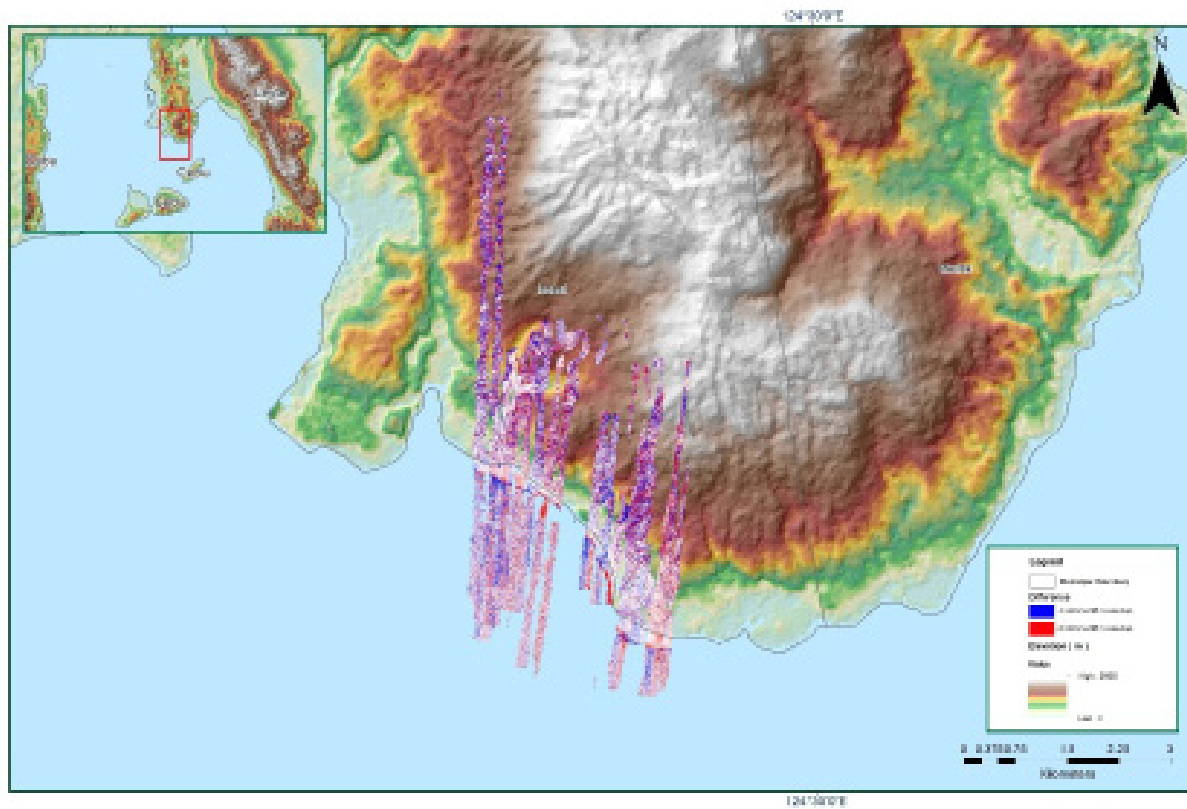


Figure A-8.168. Elevation difference between flight lines

Table A-8.25. Mission Summary Report for Mission Blk35J

Flight Area	Ormoc_Camotes
<b>Mission Name</b>	Blk35J
<b>Inclusive Flights</b>	8409AC_2
<b>Range data size</b>	4.86 GB
<b>POS</b>	87.4 MB
<b>Image</b>	35.4 MB
<b>Base Station</b>	263 MB
<b>Transfer date</b>	April 22, 2016
<b>Solution Status</b>	
<b>Number of Satellites (&gt;6)</b>	Yes
<b>PDOP (&lt;3)</b>	No
<b>Baseline Length (&lt;30km)</b>	No
<b>Processing Mode (&lt;=1)</b>	No
<b>Smoothed Performance Metrics (in cm)</b>	
<b>RMSE for North Position (&lt;4.0 cm)</b>	1.07
<b>RMSE for East Position (&lt;4.0 cm)</b>	1.02
<b>RMSE for Down Position (&lt;8.0 cm)</b>	3.55
<b>Boresight correction stdev (&lt;0.001deg)</b>	0.000307
<b>IMU attitude correction stdev (&lt;0.001deg)</b>	0.002496
<b>GPS position stdev (&lt;0.01m)</b>	0.0196
<b>Minimum % overlap (&gt;25)</b>	29.46
<b>Ave point cloud density per sq.m. (&gt;2.0)</b>	3.37
<b>Elevation difference between strips (&lt;0.20 m)</b>	Yes
<b>Number of 1km x 1km blocks</b>	44
<b>Maximum Height</b>	242.26
<b>Minimum Height</b>	60.52
<b>Classification (# of points)</b>	
<b>Ground</b>	11,888,555
<b>Low vegetation</b>	12,280,429
<b>Medium vegetation</b>	16,442,055
<b>High vegetation</b>	23,149,620
<b>Building</b>	1,462,594
<b>Orthophoto</b>	None
<b>Processed by</b>	Engr. Analyn Naldo, Engr. Velina Angela Bemida, Alex John Escobido

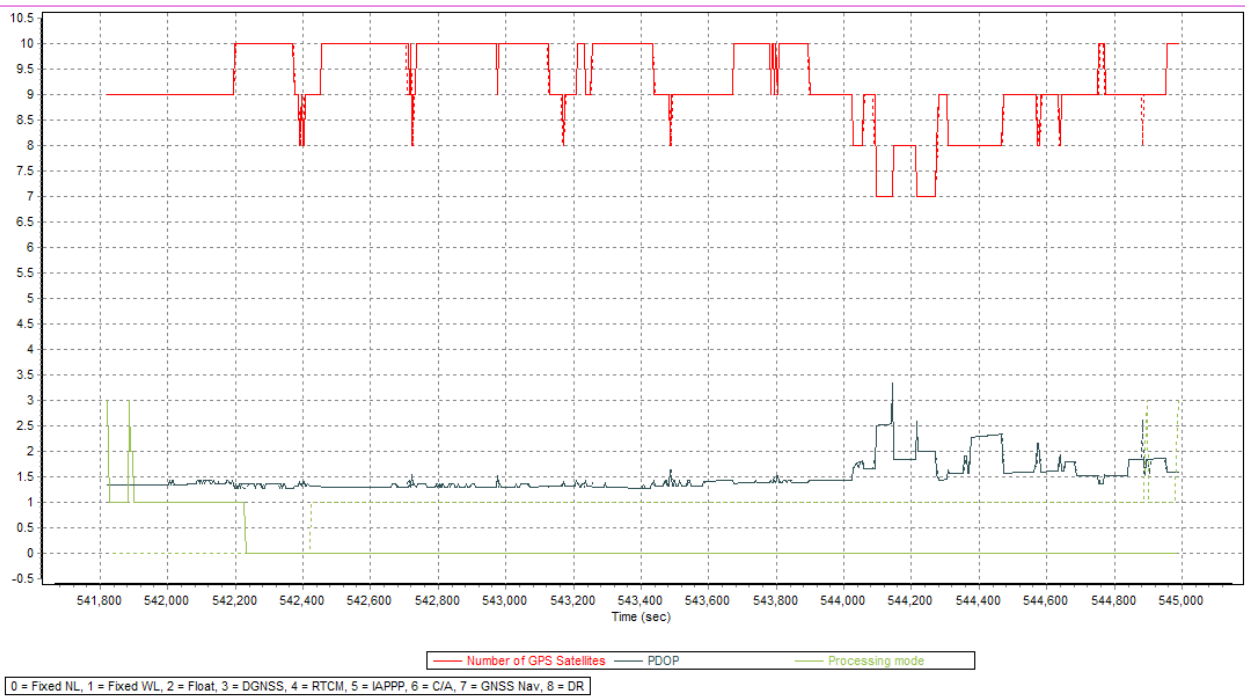


Figure A-8.169. Solution Status

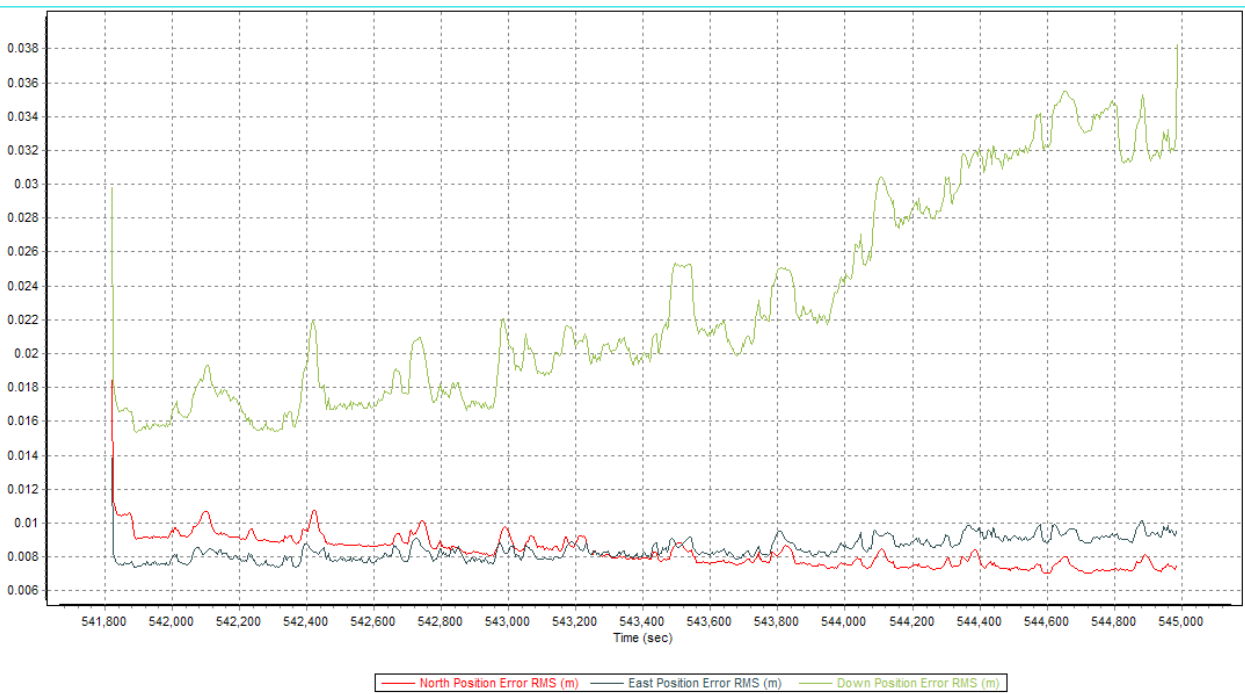


Figure A-8.170. Smoothed Performance Metrics Parameters

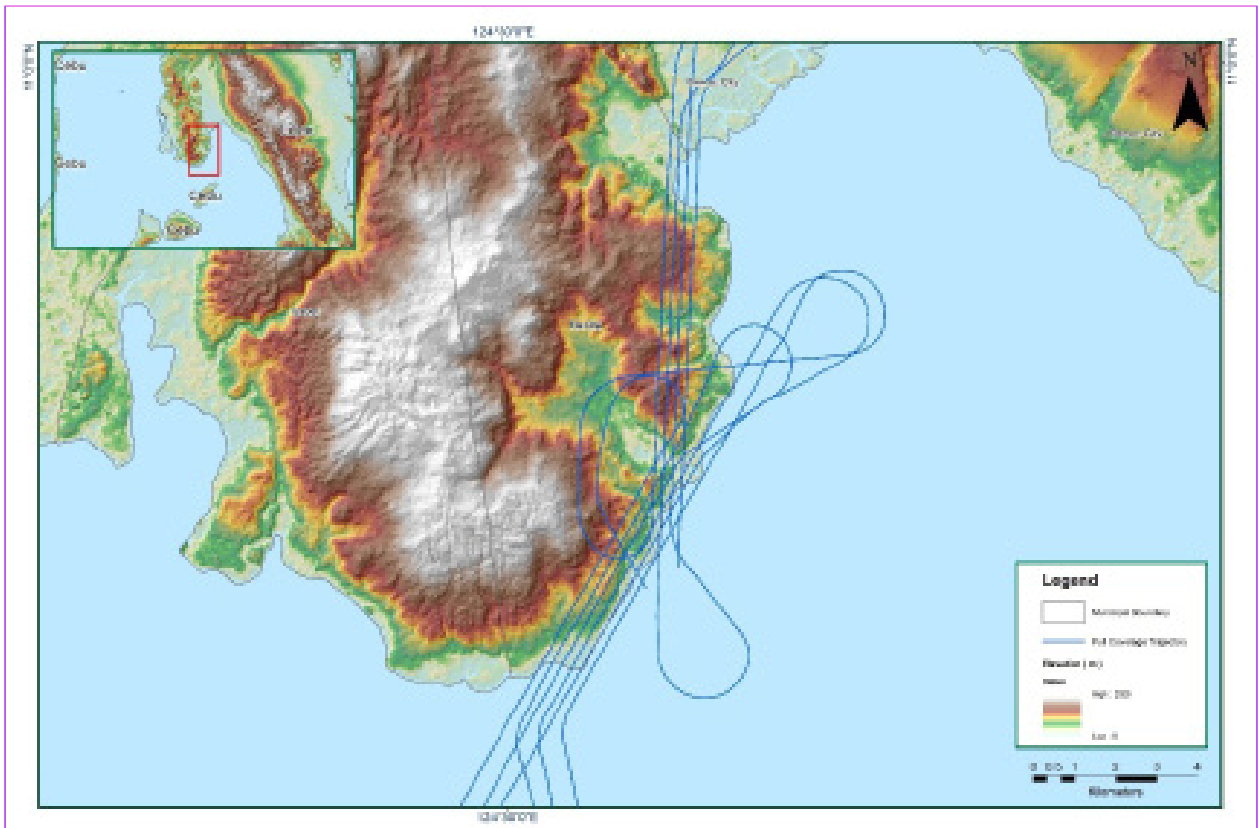


Figure A-8.171. Best Estimated Trajectory

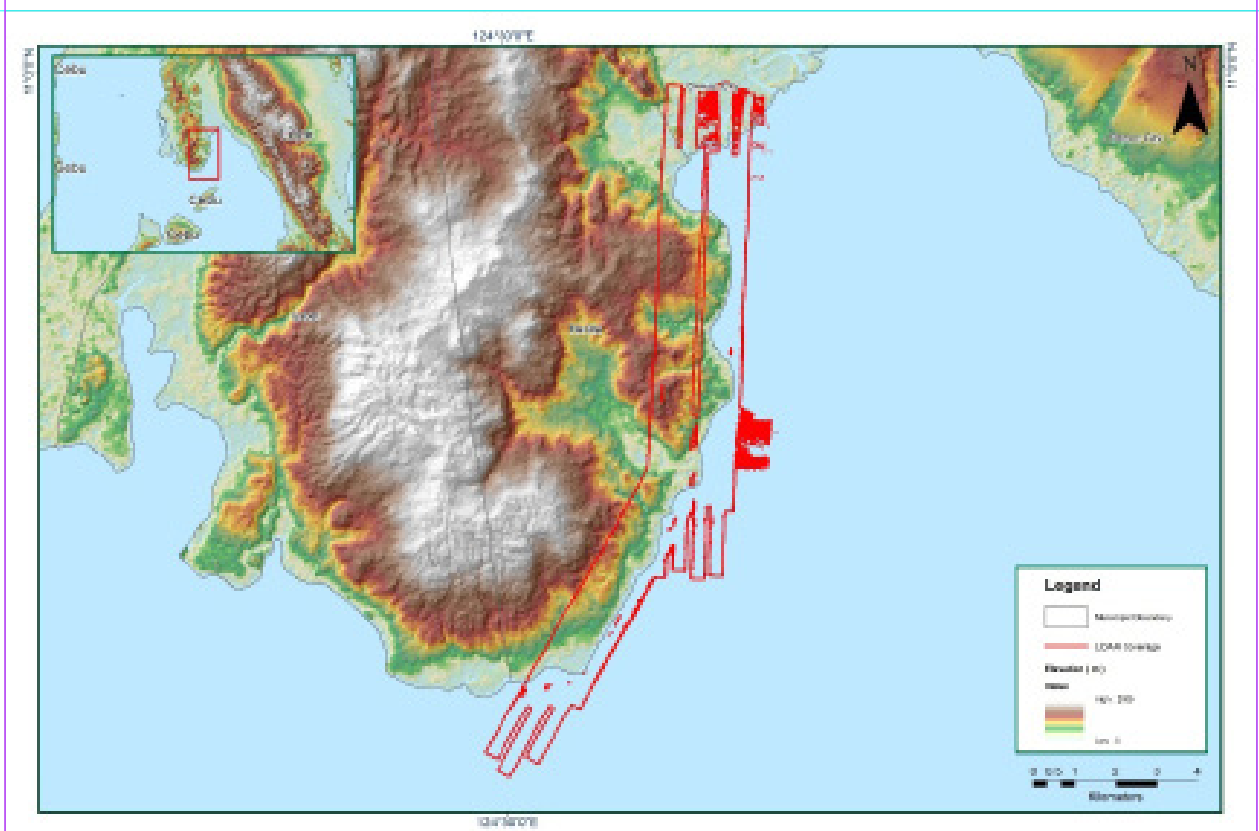


Figure A-8.172. Best Estimated Trajectory

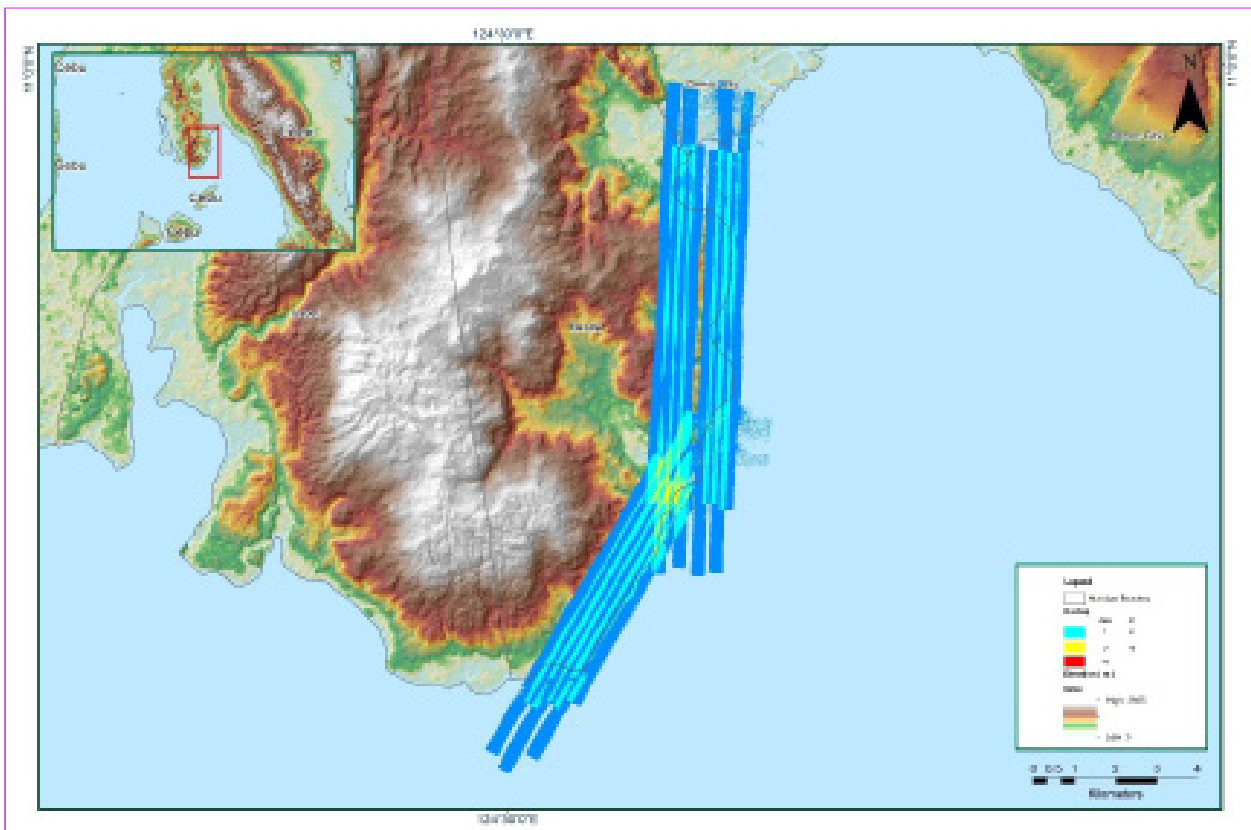


Figure A-8.173. Image of data overlap

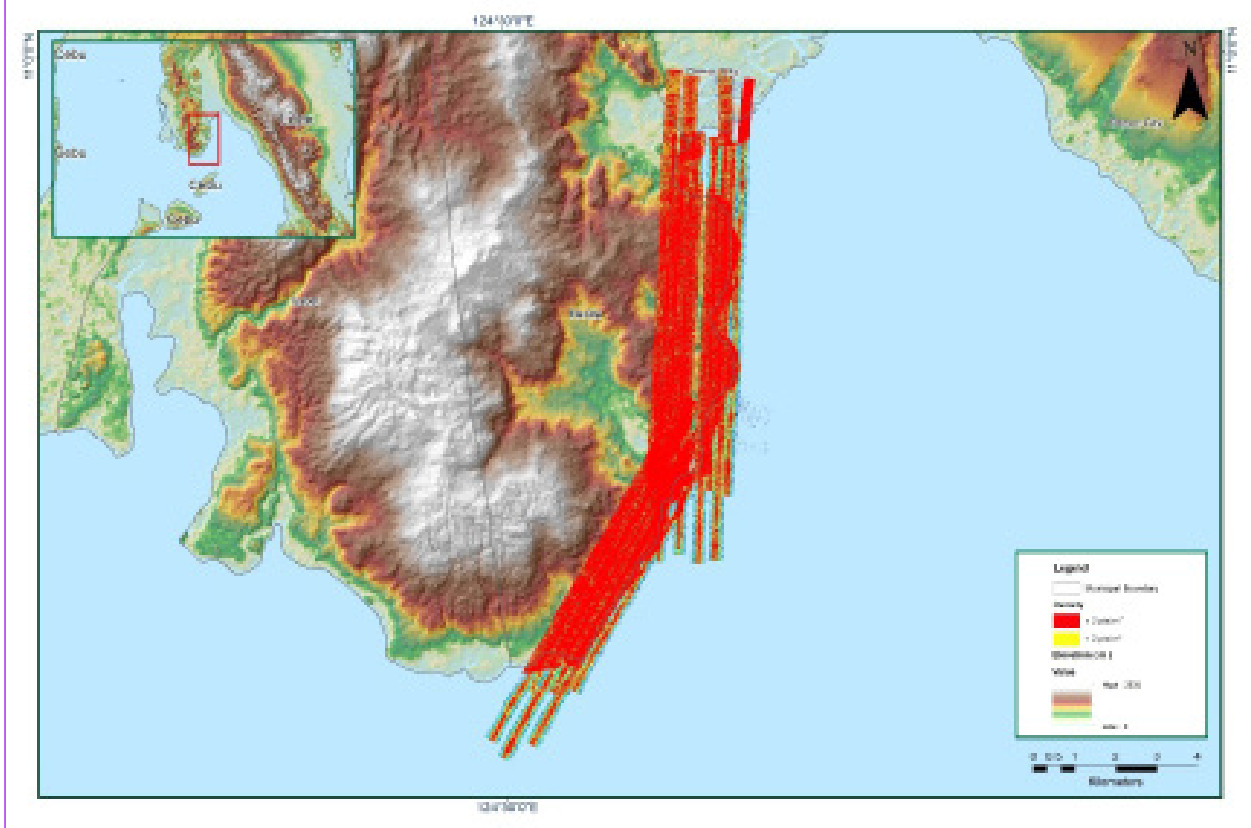


Figure A-8.174. Density map of merged LiDAR data

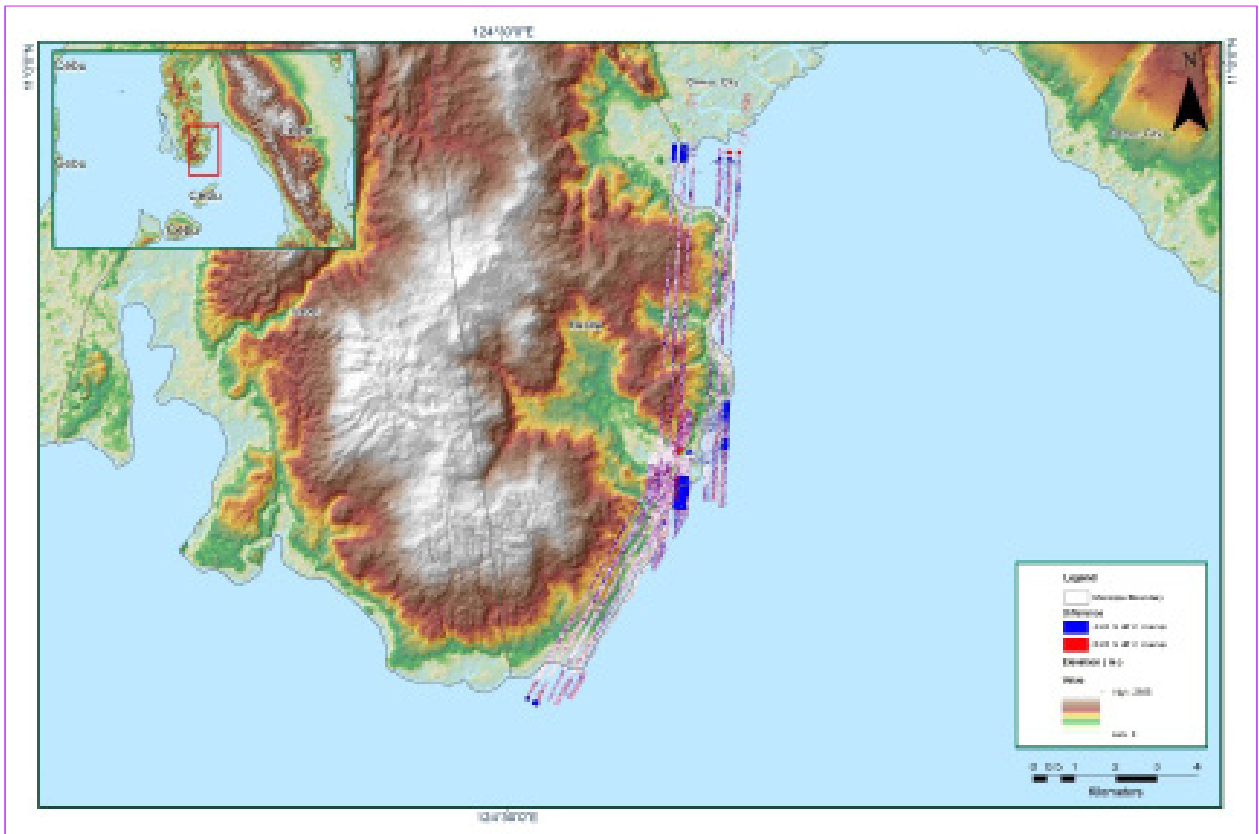


Figure A-8.175. Elevation difference between flight lines

Table A-8.26. Mission Summary Report for Mission Blk35A

Flight Area	Ormoc South
Mission Name	Blk35A
Inclusive Flights	3945G
Range data size	17.1 GB
POS data size	267 MB
Base data size	19.5 MB
Image	NA
Transfer date	May 6, 2016
Solution Status	
Number of Satellites (>6)	Yes
PDOP (<3)	Yes
Baseline Length (<30km)	Yes
Processing Mode (<=1)	No
Smoothed Performance Metrics (in cm)	
RMSE for North Position (<4.0 cm)	1.36
RMSE for East Position (<4.0 cm)	1.29
RMSE for Down Position (<8.0 cm)	3.25
Boresight correction stdev (<0.001deg)	0.000280
IMU attitude correction stdev (<0.001deg)	0.001977
GPS position stdev (<0.01m)	0.0018
Minimum % overlap (>25)	43.31
Ave point cloud density per sq.m. (>2.0)	4.53
Elevation difference between strips (<0.20 m)	Yes
Number of 1km x 1km blocks	137
Maximum Height	431.88 m
Minimum Height	60.28 m
Classification (# of points)	
Ground	62,206,138
Low vegetation	88,553,270
Medium vegetation	168,431,674
High vegetation	144,388,933
Building	1,926,447
Orthophoto	No
Processed by	Engr. Irish Cortez, Aljon Rie Araneta, Engr. Melissa Fernandez

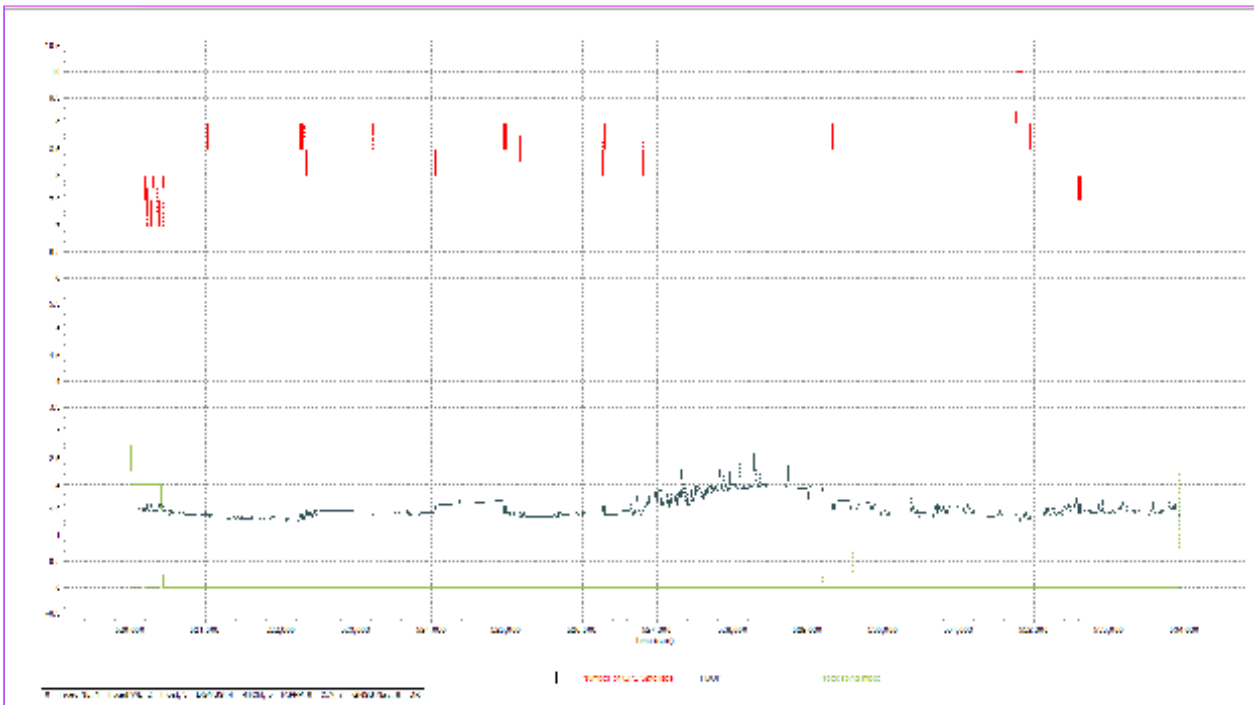


Figure A-8.176. Solution Status

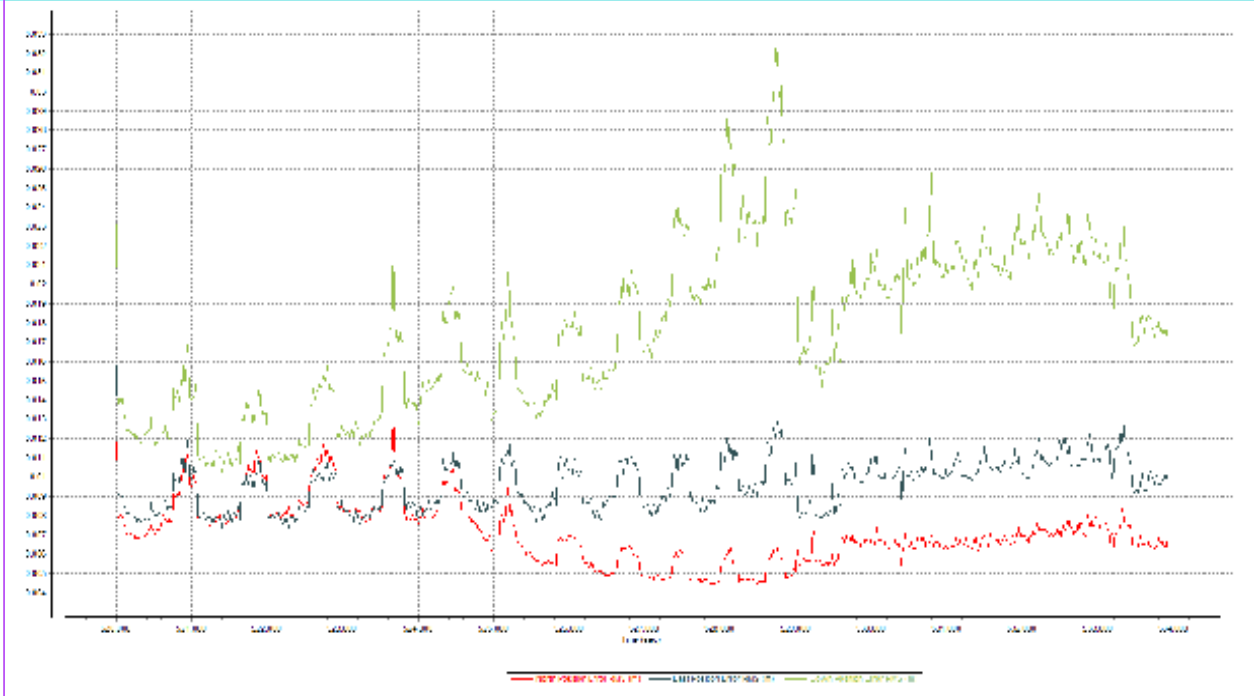


Figure A-8.177. Smoothed Performance Metrics Parameters



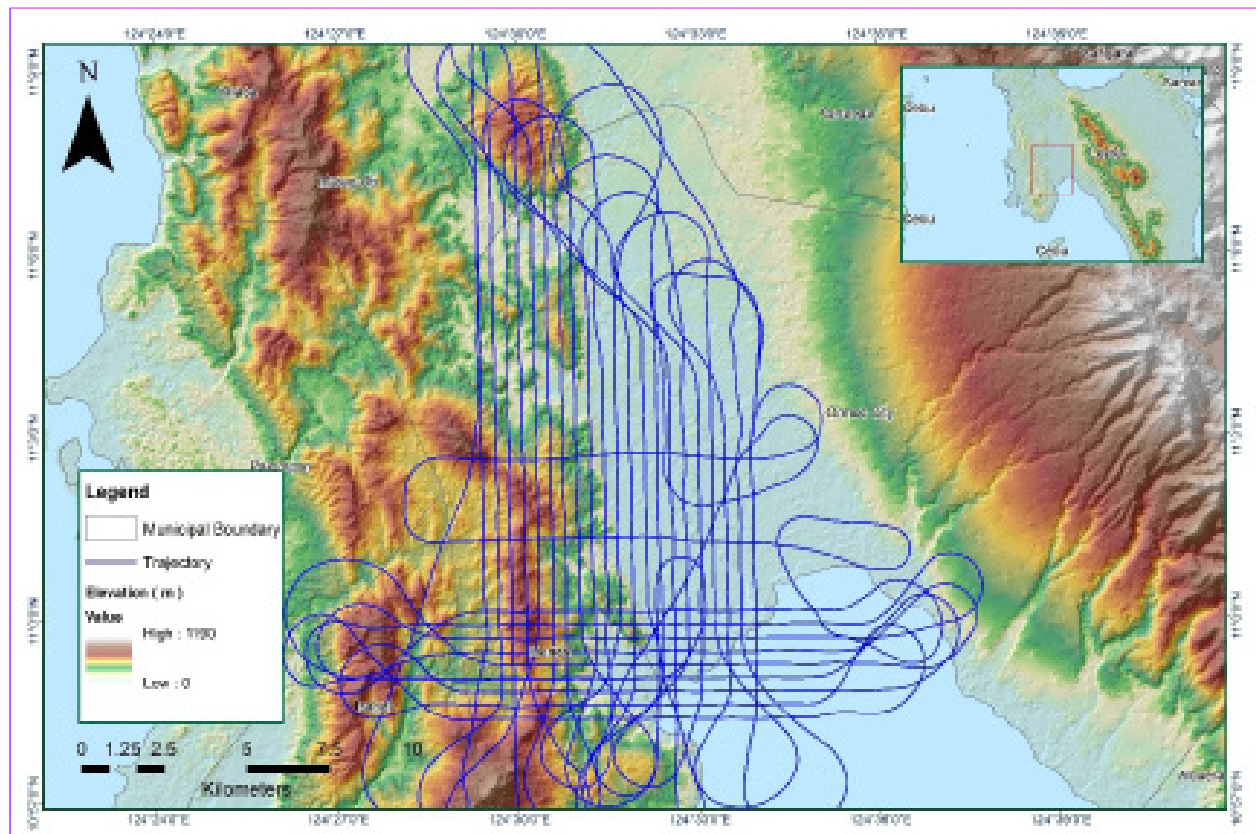


Figure A-8.178. Best Estimated Trajectory

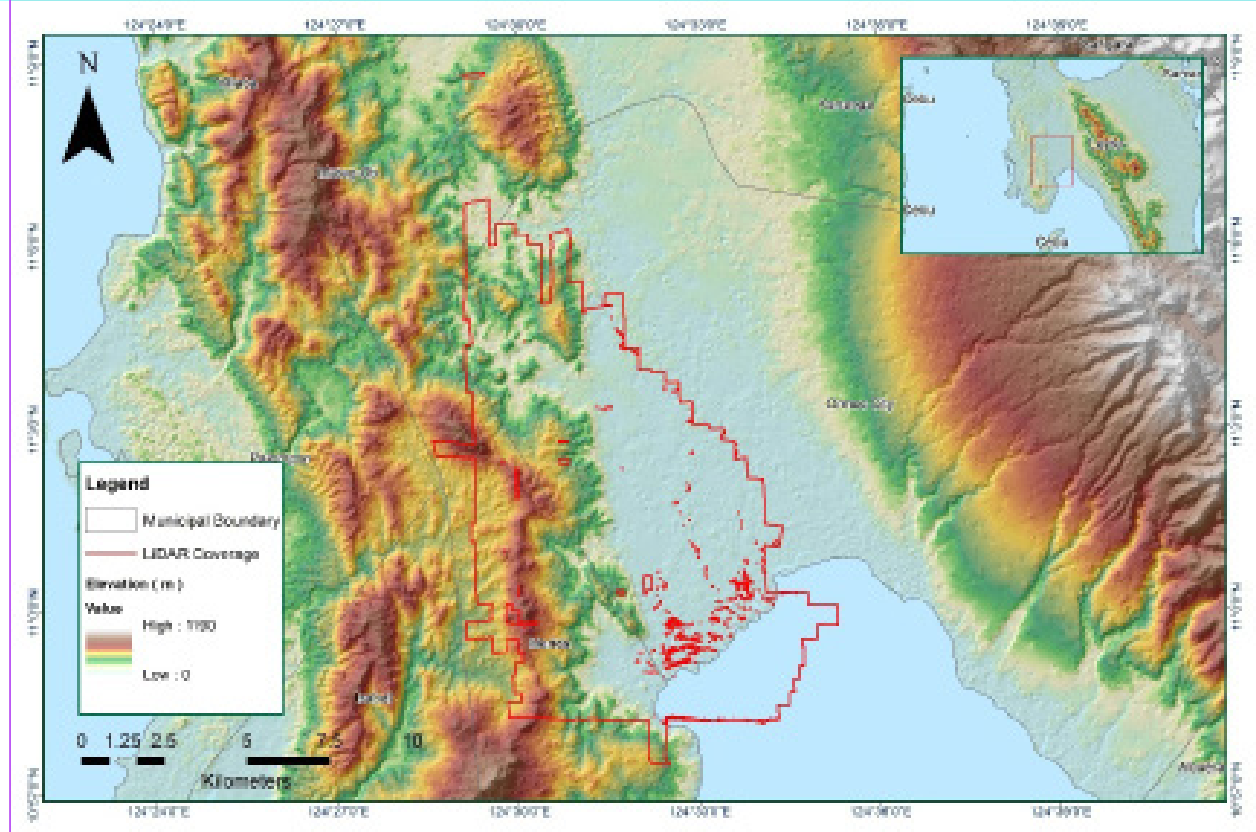


Figure A-8.179. Coverage of LiDAR data

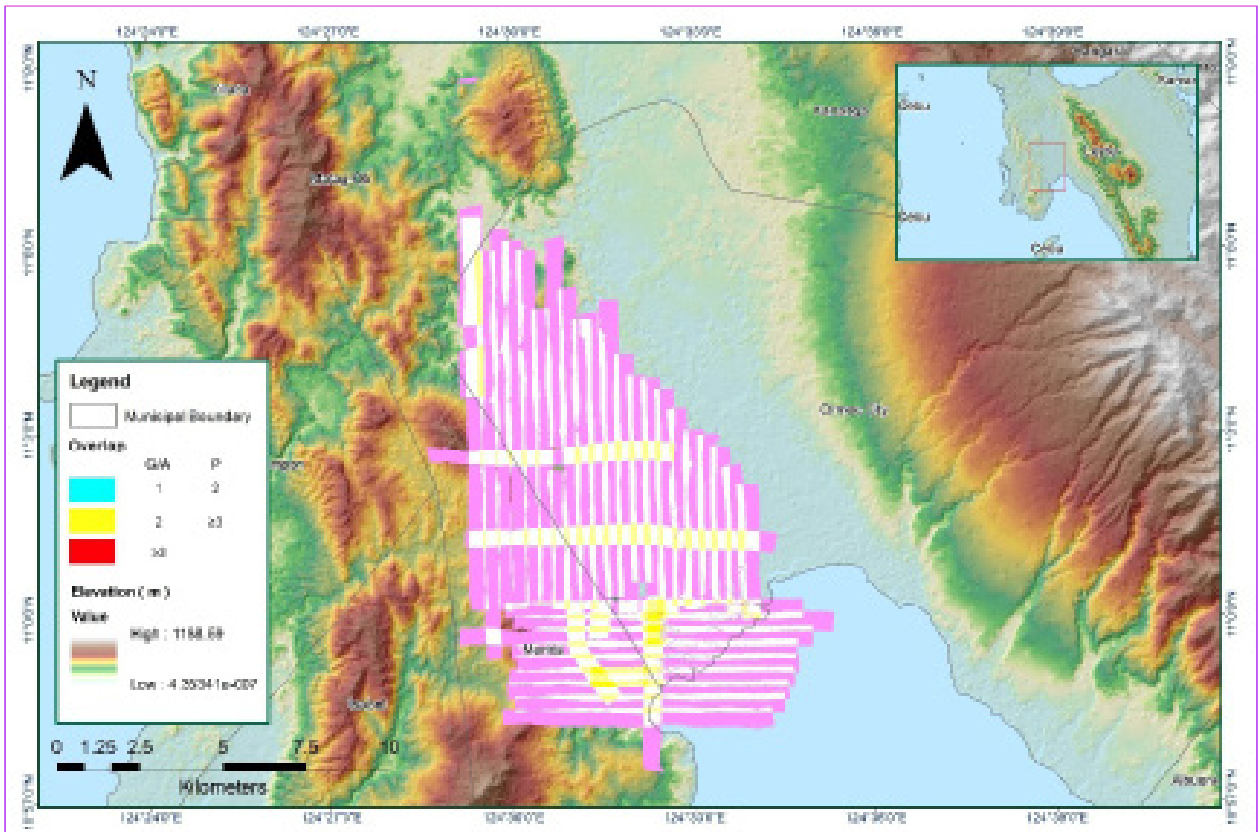


Figure A-8.180. Image of data overlap

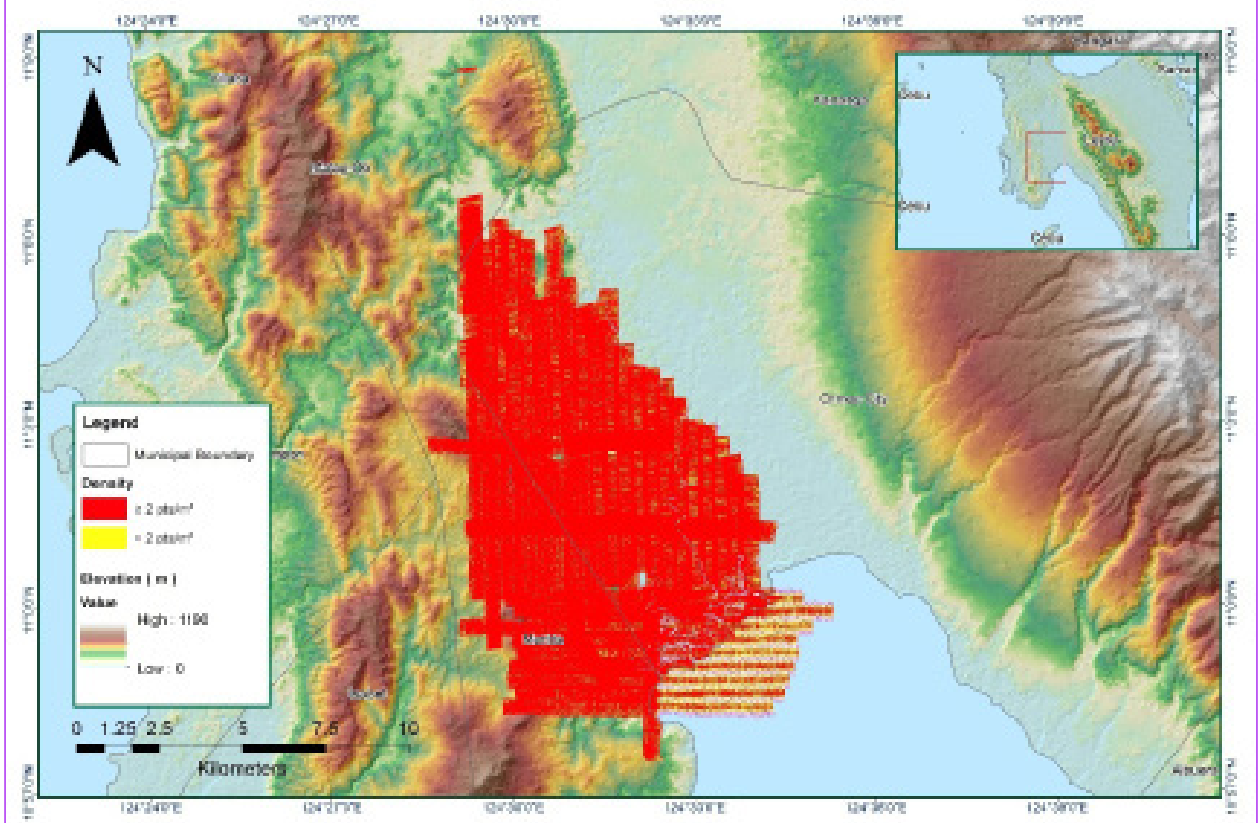


Figure A-8.181. Density map of merged LiDAR data

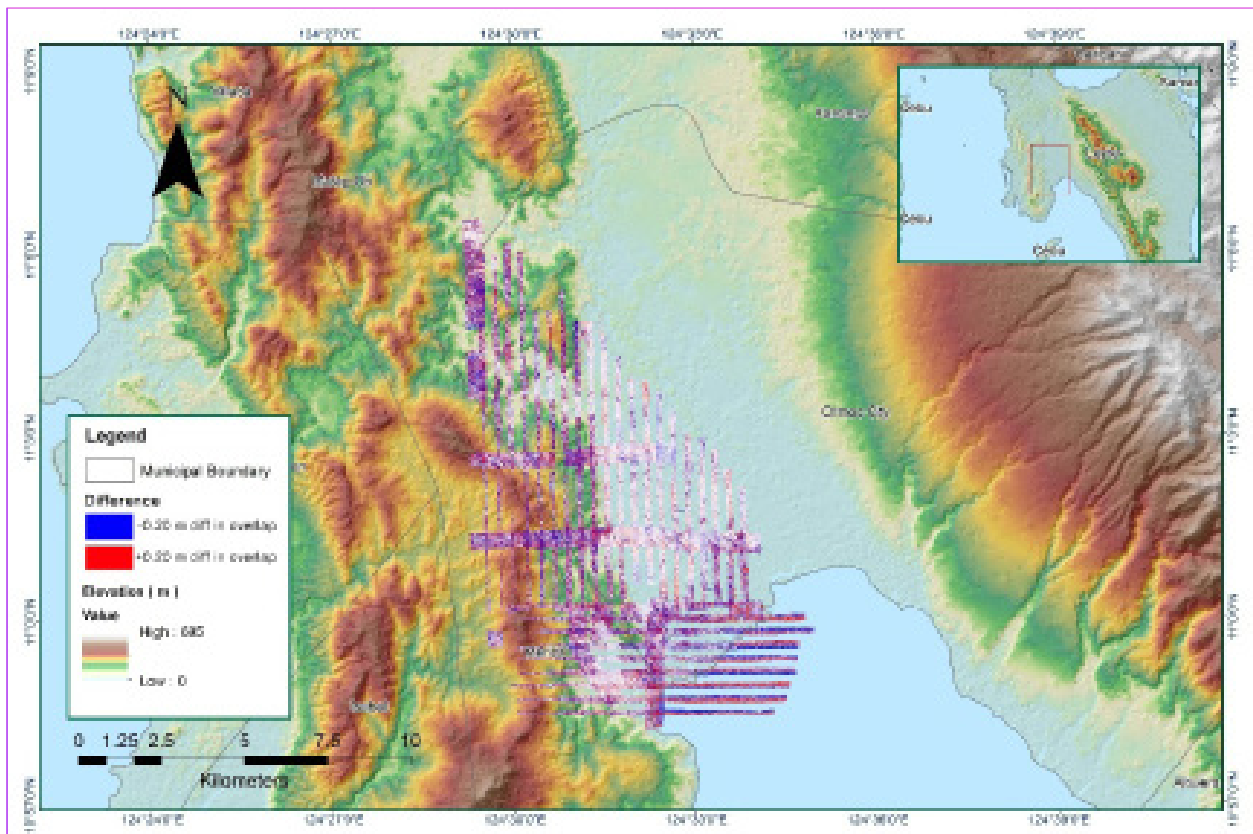


Figure A-8.182. Elevation difference between flight lines

Table A-8.27. Mission Summary Report for Mission Blk35B

Flight Area	Ormoc South
<b>Mission Name</b>	Blk35B
<b>Inclusive Flights</b>	3945G, 3947G
<b>Range data size</b>	38.1 GB
<b>POS data size</b>	545 MB
<b>Base data size</b>	39 MB
<b>Image</b>	NA
<b>Transfer date</b>	May 6, 2016
<b>Solution Status</b>	
<b>Number of Satellites (&gt;6)</b>	Yes
<b>PDOP (&lt;3)</b>	Yes
<b>Baseline Length (&lt;30km)</b>	Yes
<b>Processing Mode (&lt;=1)</b>	Yes
<b>Smoothed Performance Metrics (in cm)</b>	
<b>RMSE for North Position (&lt;4.0 cm)</b>	1.03
<b>RMSE for East Position (&lt;4.0 cm)</b>	1.32
<b>RMSE for Down Position (&lt;8.0 cm)</b>	3.25
<b>Boresight correction stdev (&lt;0.001deg)</b>	NA
<b>IMU attitude correction stdev (&lt;0.001deg)</b>	NA
<b>GPS position stdev (&lt;0.01m)</b>	NA
<b>Minimum % overlap (&gt;25)</b>	38.65
<b>Ave point cloud density per sq.m. (&gt;2.0)</b>	3.46
<b>Elevation difference between strips (&lt;0.20 m)</b>	Yes
<b>Number of 1km x 1km blocks</b>	78
<b>Maximum Height</b>	567.81 m
<b>Minimum Height</b>	60.87 m
<b>Classification (# of points)</b>	
<b>Ground</b>	28,967,711
<b>Low vegetation</b>	27,502,827
<b>Medium vegetation</b>	74,982,705
<b>High vegetation</b>	65,341,688
<b>Building</b>	393,179
<b>Orthophoto</b>	No
<b>Processed by</b>	Engr. Abigail Joy Ching, Aljon Rie Araneta, Engr. Monalynne Rabino



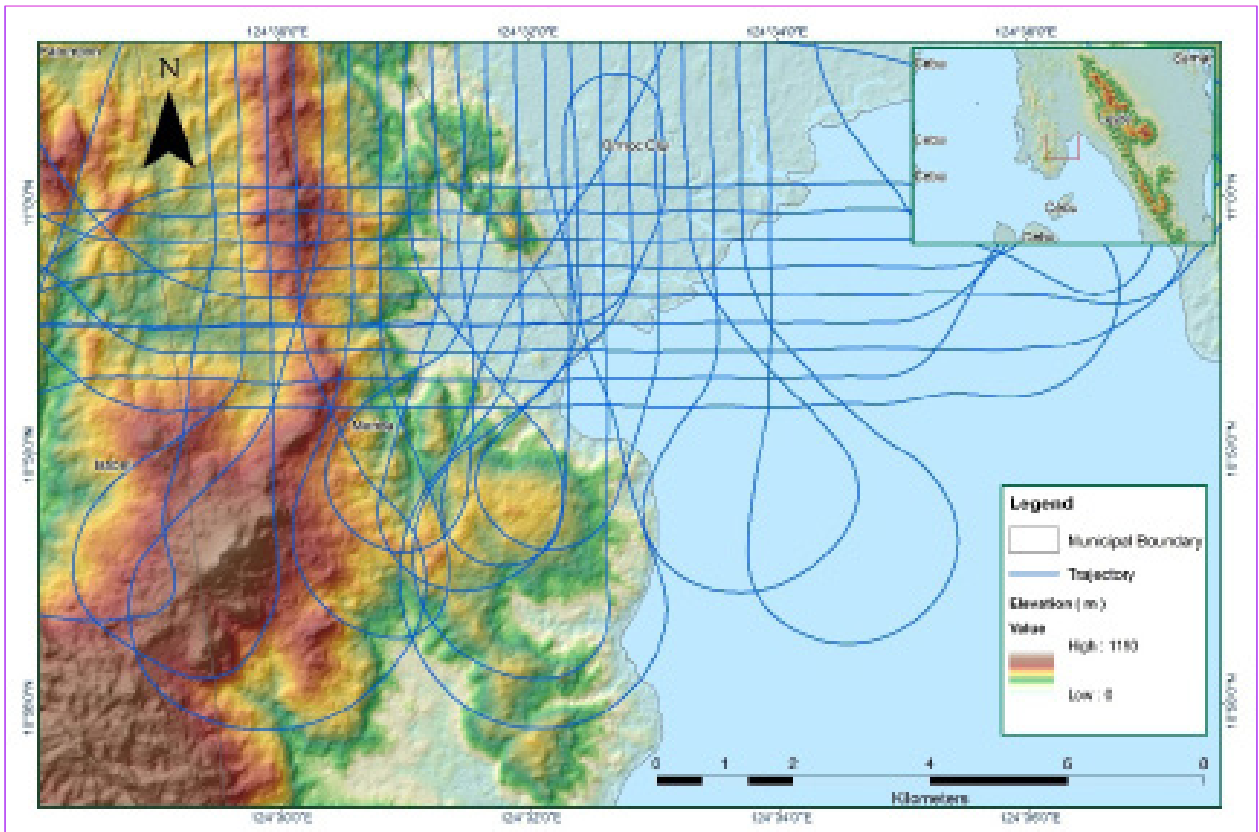


Figure A-8.185. Best Estimated Trajectory

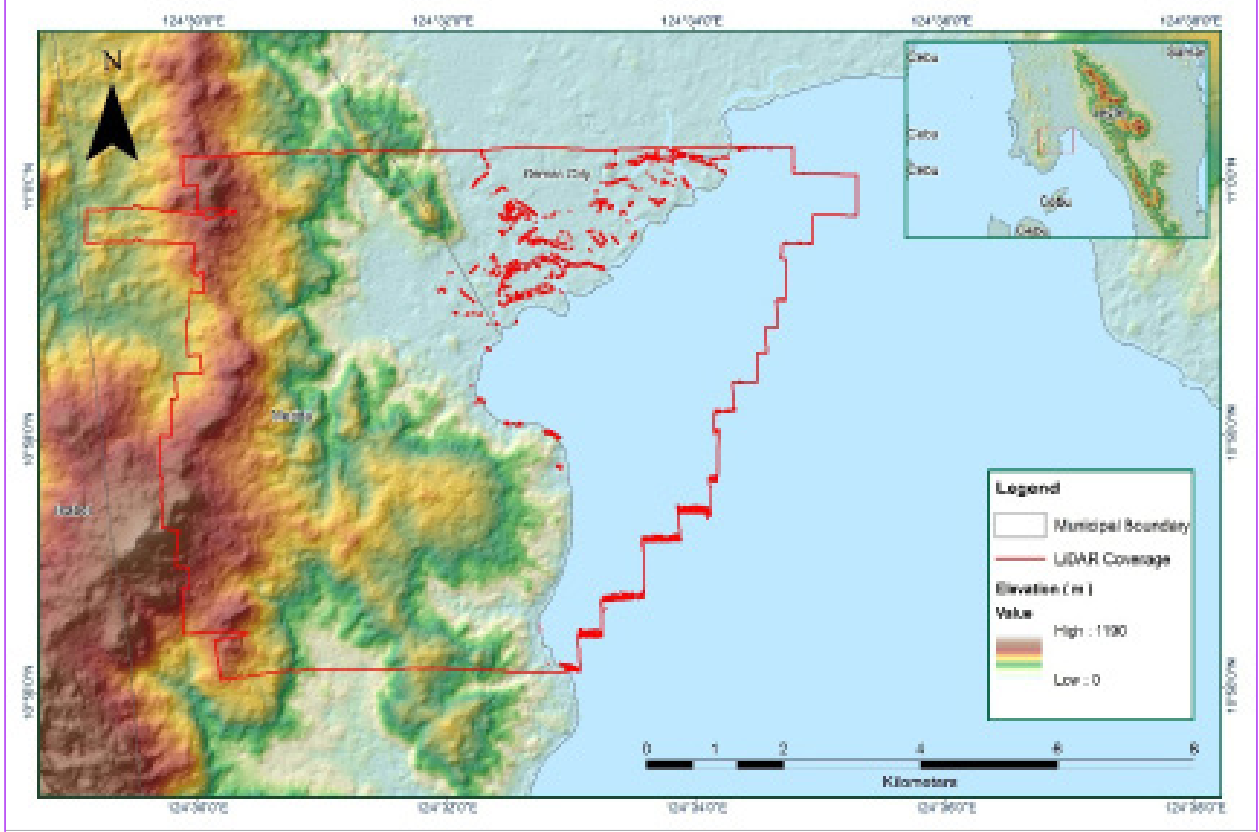


Figure A-8.186. Best Estimated Trajectory

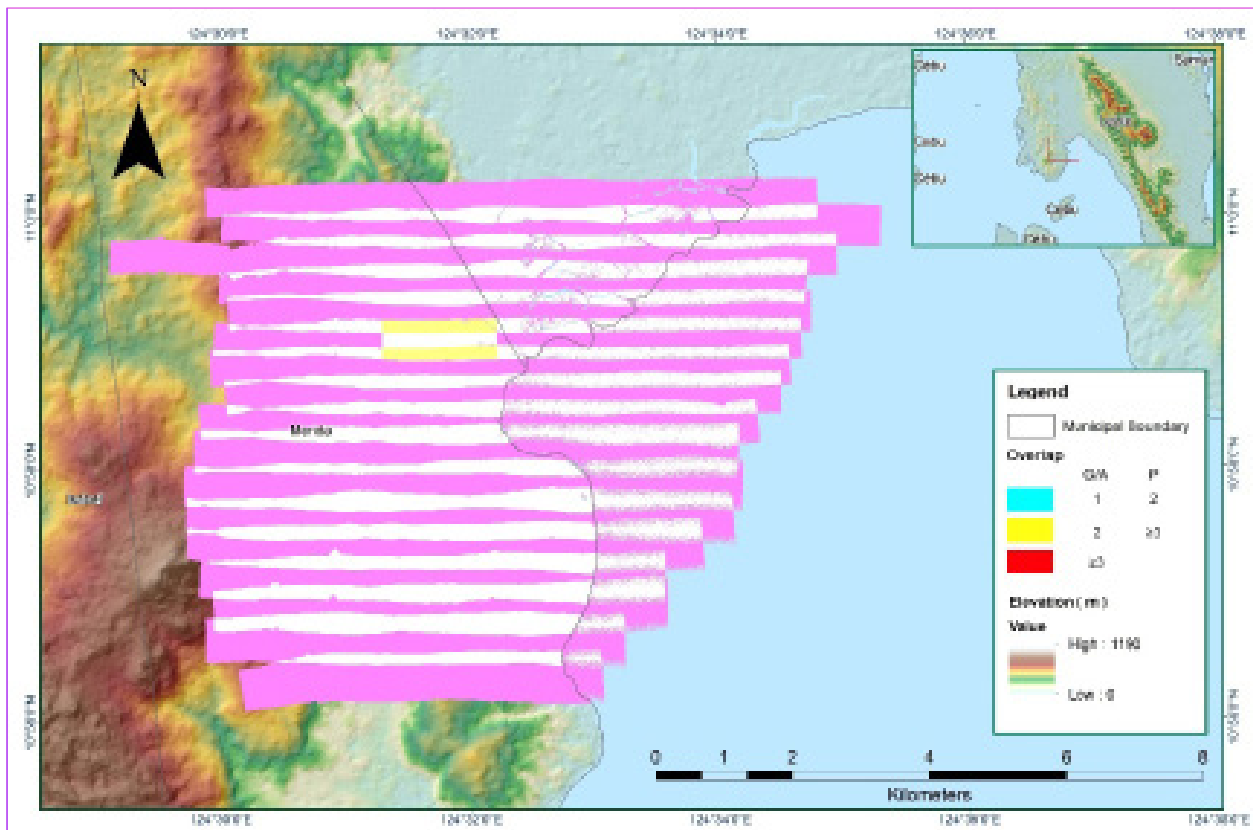


Figure A-8.187. Image of data overlap

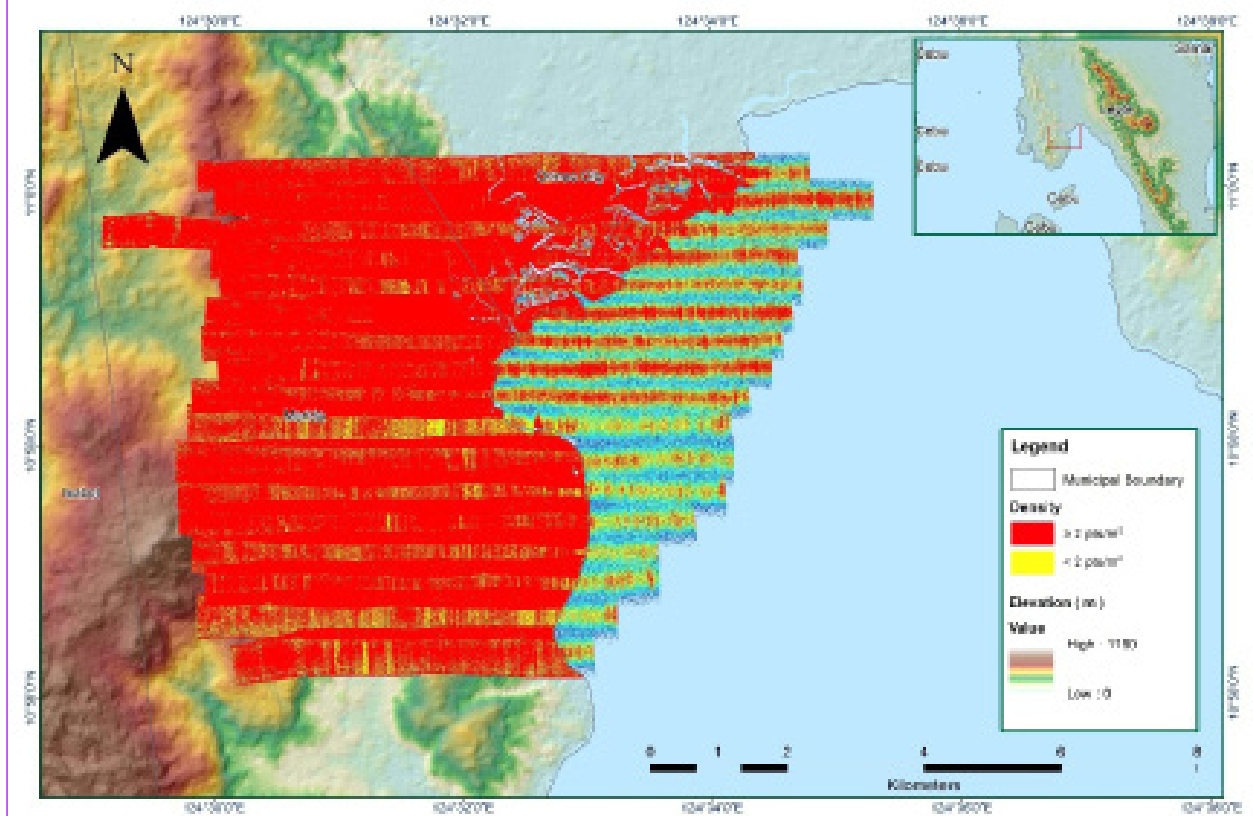


Figure A-8.188. Density map of merged LiDAR data

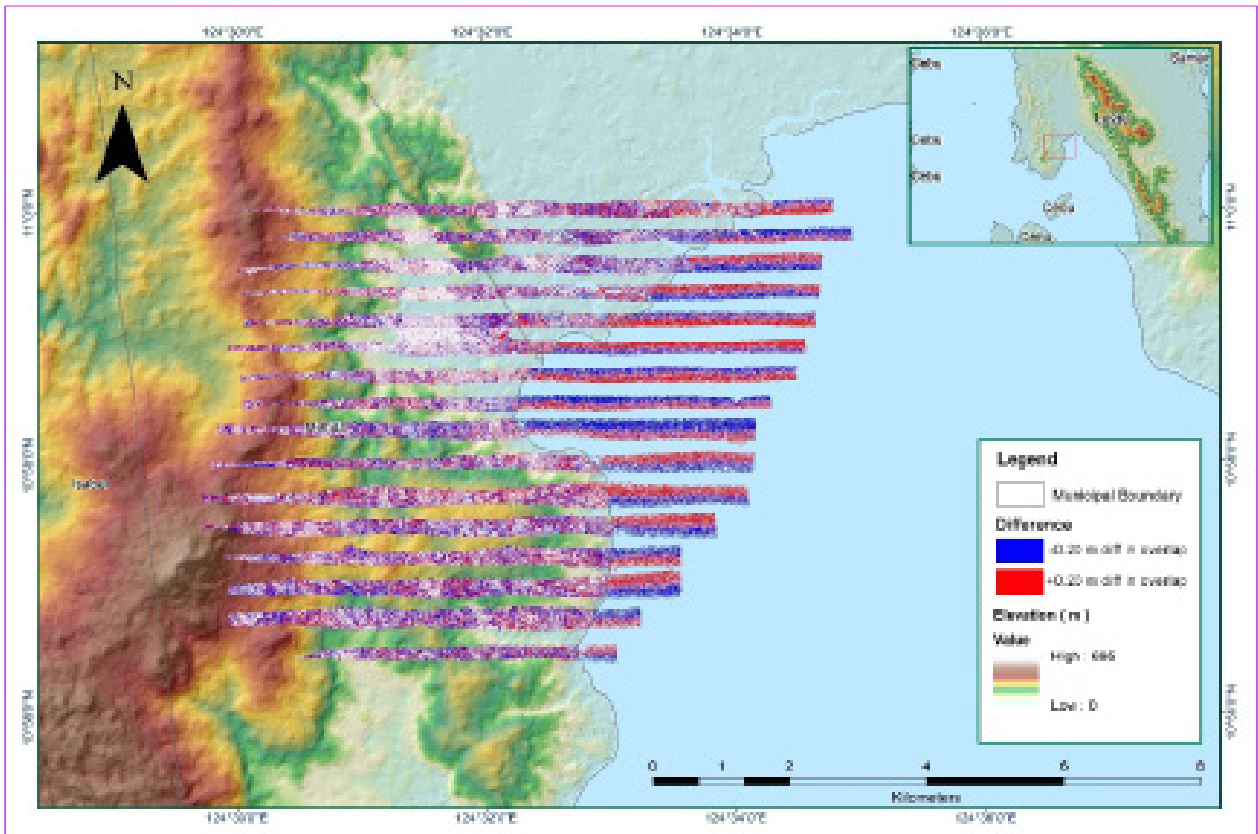
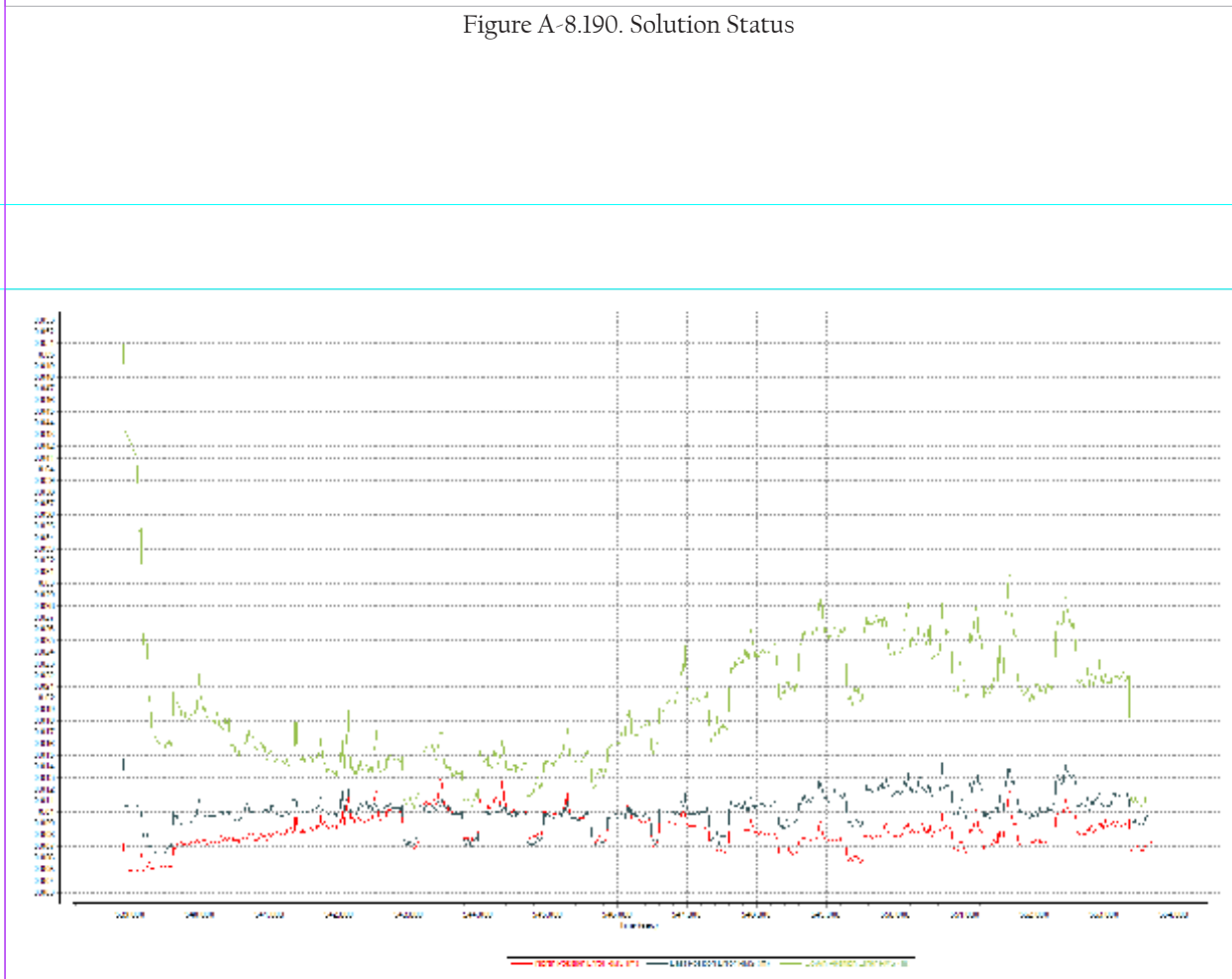
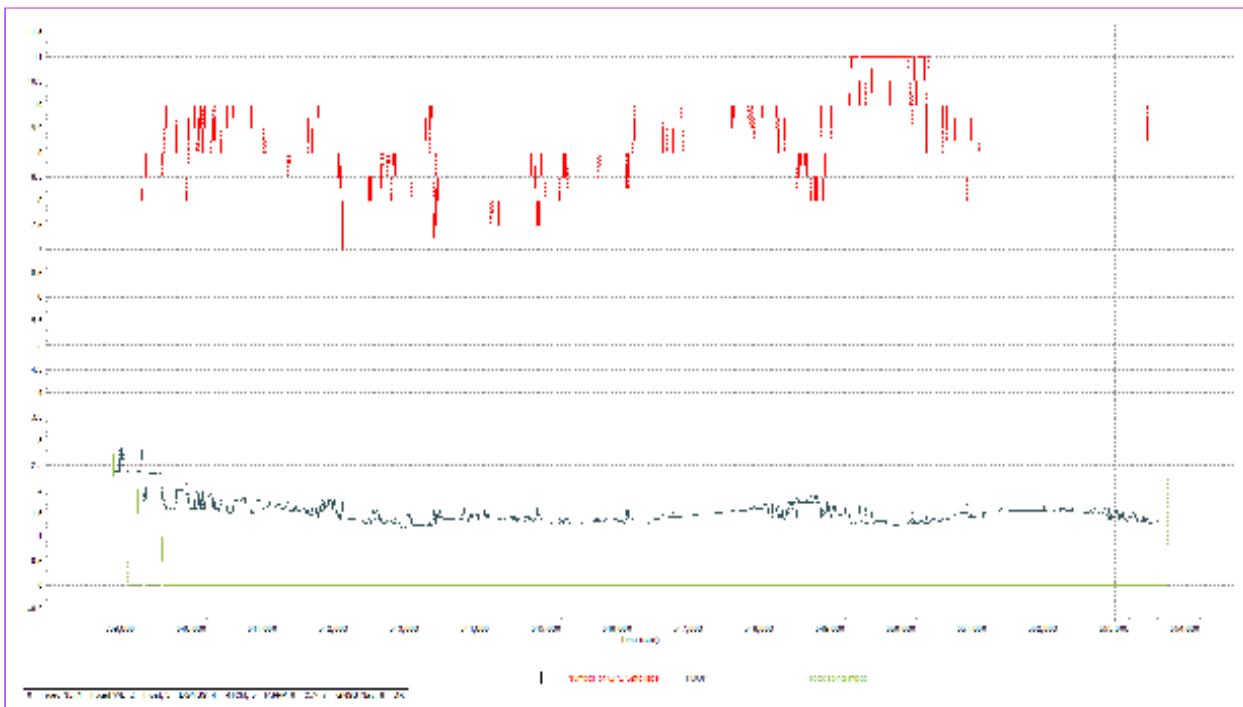


Figure A-8.189. Elevation difference between flight lines



Table A-8.28. Mission Summary Report for Mission Blk35C

<b>Flight Area</b>	<b>Ormoc South</b>
<b>Mission Name</b>	Blk35C
<b>Inclusive Flights</b>	3947G
<b>Range data size</b>	21 GB
<b>POS data size</b>	278 MB
<b>Base data size</b>	19.5 MB
<b>Image</b>	NA
<b>Transfer date</b>	May 6, 2016
<b>Solution Status</b>	
<b>Number of Satellites (&gt;6)</b>	Yes
<b>PDOP (&lt;3)</b>	Yes
<b>Baseline Length (&lt;30km)</b>	No
<b>Processing Mode (&lt;=1)</b>	No
<b>Smoothed Performance Metrics (in cm)</b>	
<b>RMSE for North Position (&lt;4.0 cm)</b>	1.29
<b>RMSE for East Position (&lt;4.0 cm)</b>	1.43
<b>RMSE for Down Position (&lt;8.0 cm)</b>	3.07
<b>Boresight correction stdev (&lt;0.001deg)</b>	0.001347
<b>IMU attitude correction stdev (&lt;0.001deg)</b>	0.007265
<b>GPS position stdev (&lt;0.01m)</b>	0.0023
<b>Minimum % overlap (&gt;25)</b>	46.44
<b>Ave point cloud density per sq.m. (&gt;2.0)</b>	4.67
<b>Elevation difference between strips (&lt;0.20 m)</b>	Yes
<b>Number of 1km x 1km blocks</b>	130
<b>Maximum Height</b>	664.42 m
<b>Minimum Height</b>	45.81 m
<b>Classification (# of points)</b>	
<b>Ground</b>	55,143,313
<b>Low vegetation</b>	41,566,187
<b>Medium vegetation</b>	160,423,665
<b>High vegetation</b>	124,246,531
<b>Building</b>	187,280
<b>Orthophoto</b>	No
<b>Processed by</b>	Engr. Abigail Joy Ching, Engr. Justine Francisco, Engr. Monalyne Rabino



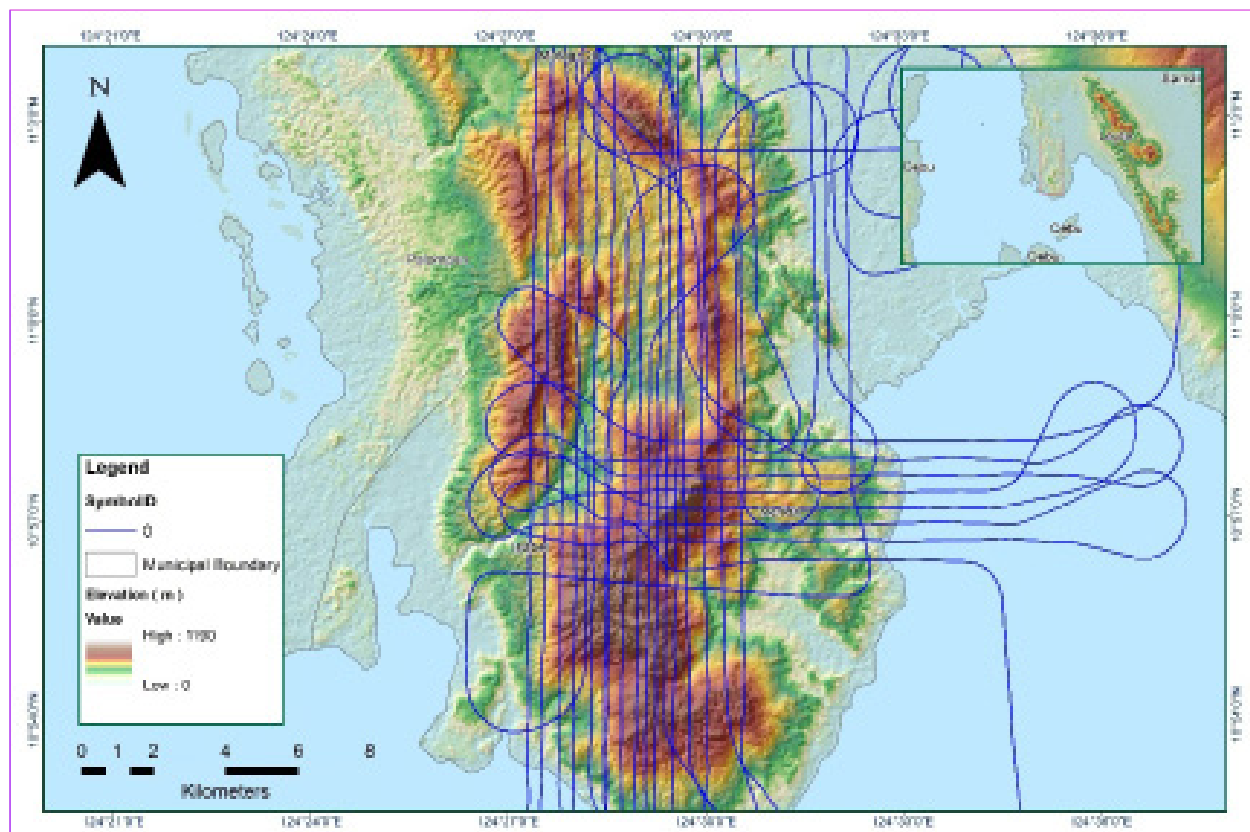


Figure A-8.192. Best Estimated Trajectory

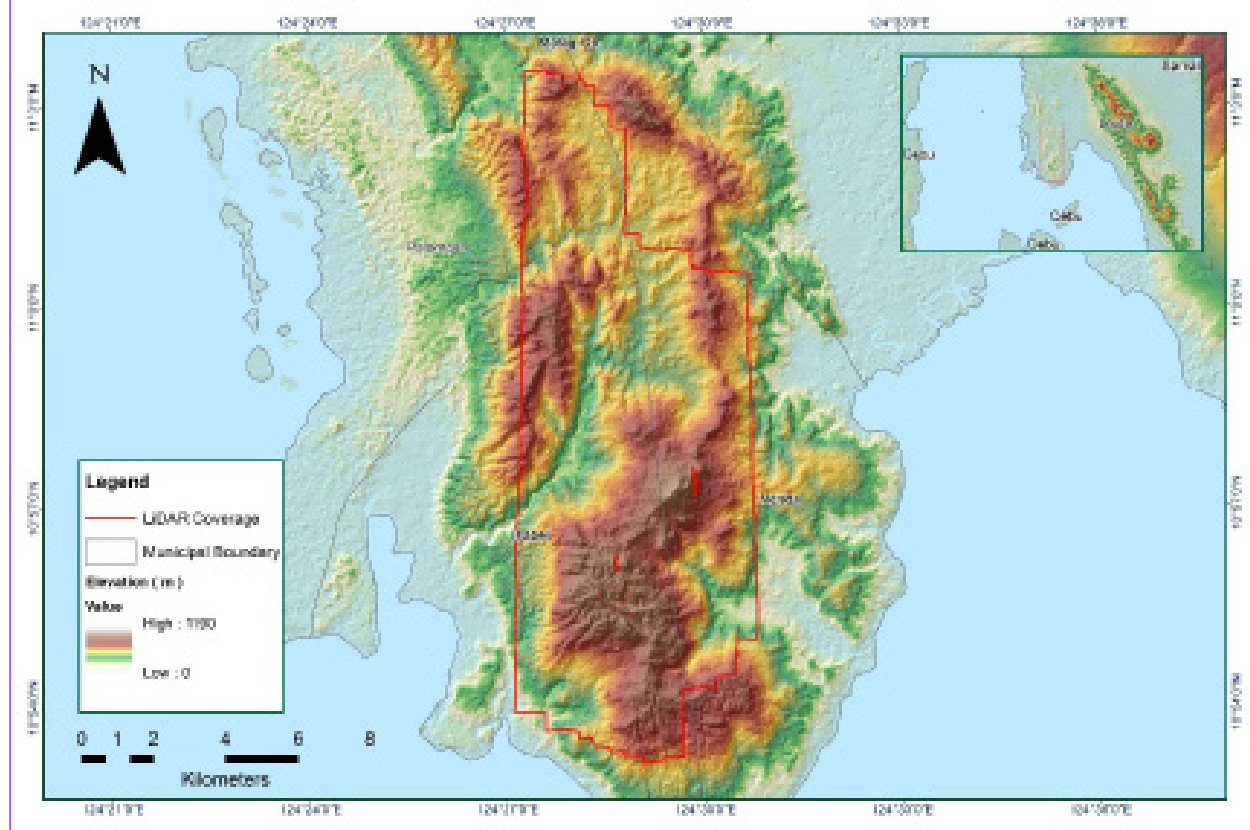


Figure A-8.193. Coverage of LiDAR data

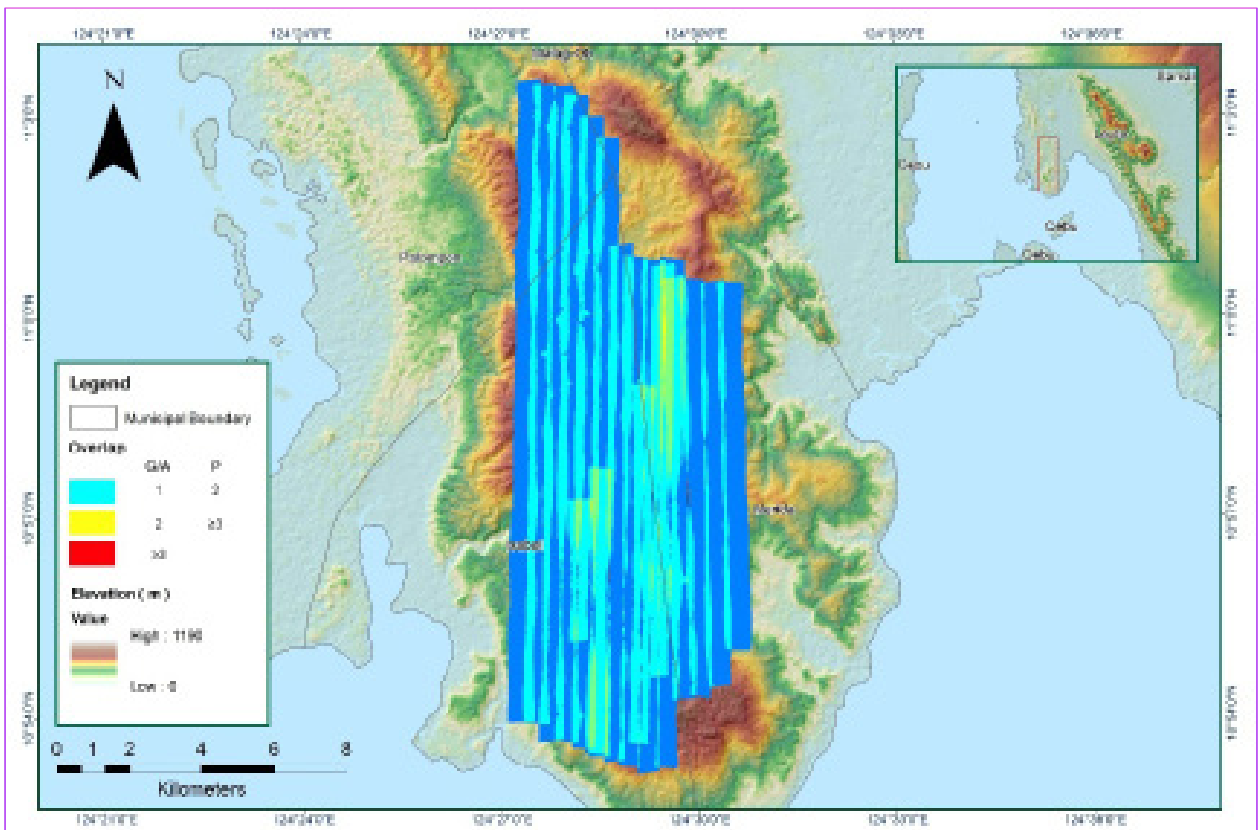


Figure A-8.194. Image of data overlap

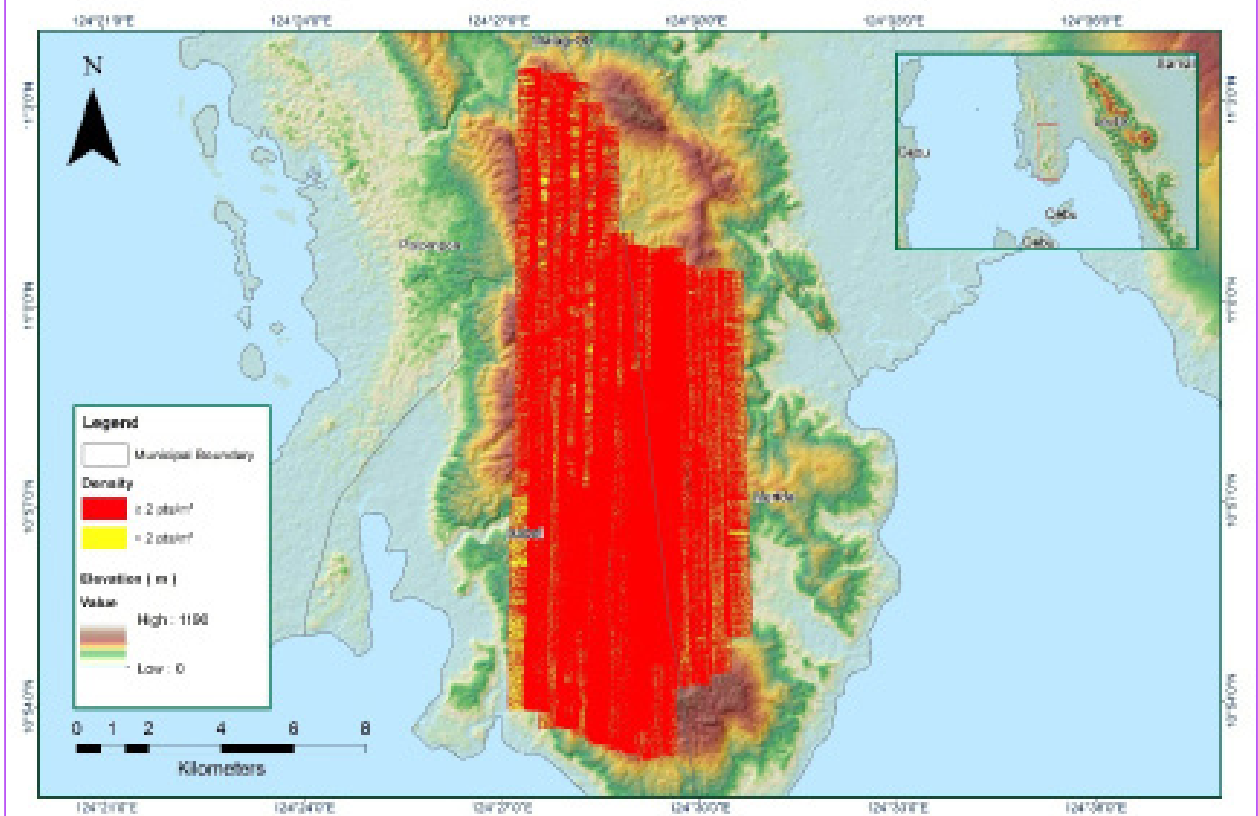


Figure A-8.195. Density map of merged LIDAR data

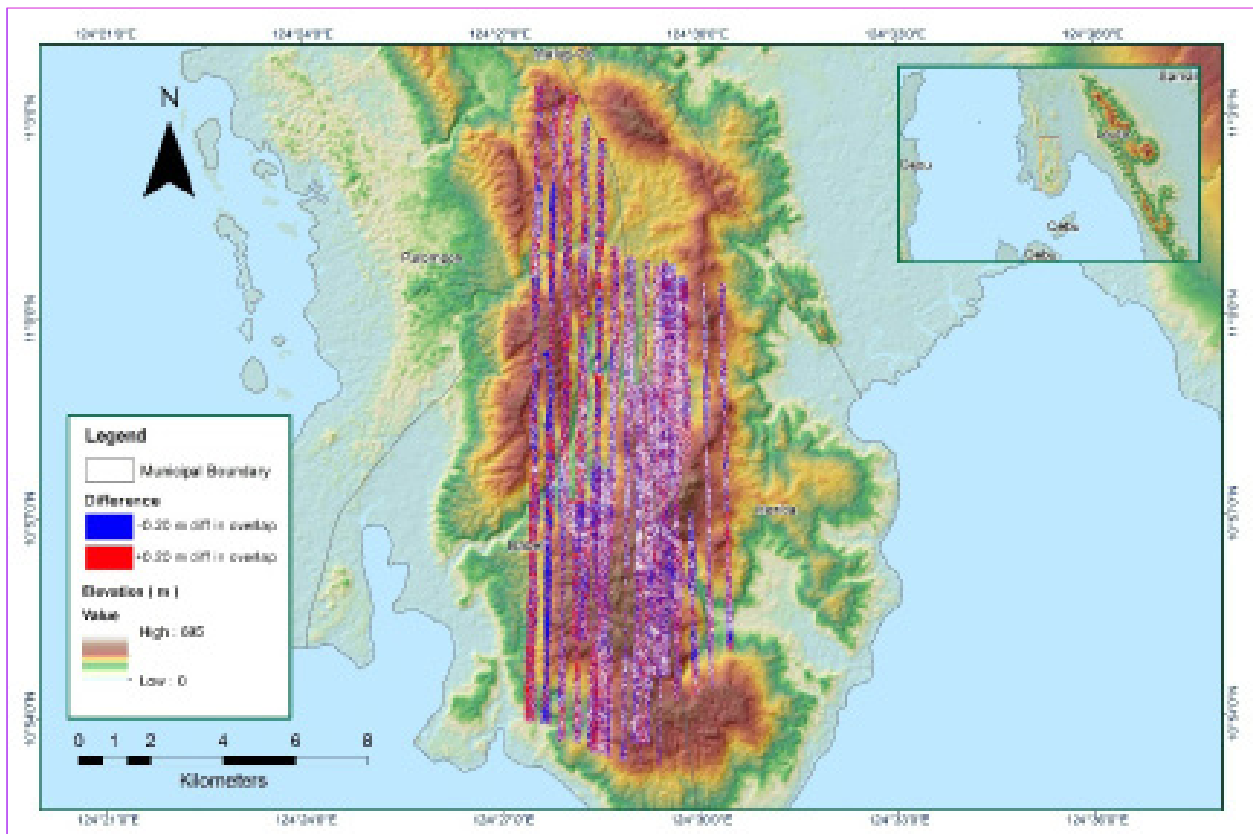


Figure A-8.196. Elevation difference between flight lines

Table A-8.29. Mission Summary Report for Mission I032A

<b>Flight Area</b>	<b>Tacloban</b>
<b>Mission Name</b>	1032A
<b>Inclusive Flights</b>	1032A
<b>Range data size</b>	13.7 GB
<b>POS data size</b>	54.6 MB
<b>Base data size</b>	10.8 MB
<b>Image</b>	24.4 GB
<b>Transfer date</b>	February 3, 2015
<b>Solution Status</b>	
<b>Number of Satellites (&gt;6)</b>	Yes
<b>PDOP (&lt;3)</b>	No
<b>Baseline Length (&lt;30km)</b>	No
<b>Processing Mode (&lt;=1)</b>	Yes
<b>Smoothed Performance Metrics (in cm)</b>	
<b>RMSE for North Position (&lt;4.0 cm)</b>	1.1
<b>RMSE for East Position (&lt;4.0 cm)</b>	1.1
<b>RMSE for Down Position (&lt;8.0 cm)</b>	2.8
<b>Boresight correction stdev (&lt;0.001deg)</b>	0.007721
<b>IMU attitude correction stdev (&lt;0.001deg)</b>	0.005490
<b>GPS position stdev (&lt;0.01m)</b>	0.0036
<b>Minimum % overlap (&gt;25)</b>	26.50%
<b>Ave point cloud density per sq.m. (&gt;2.0)</b>	2.41
<b>Elevation difference between strips (&lt;0.20 m)</b>	Yes
<b>Number of 1km x 1km blocks</b>	47
<b>Maximum Height</b>	171.52 m
<b>Minimum Height</b>	68.07 m
<b>Classification (# of points)</b>	
<b>Ground</b>	4,251,370
<b>Low vegetation</b>	3,342,368
<b>Medium vegetation</b>	14,184,838
<b>High vegetation</b>	246,147
<b>Building</b>	93,165
<b>Orthophoto</b>	No
<b>Processed by</b>	Engr. Irish Cortez, Celina Rosete, Ailyn Biñas

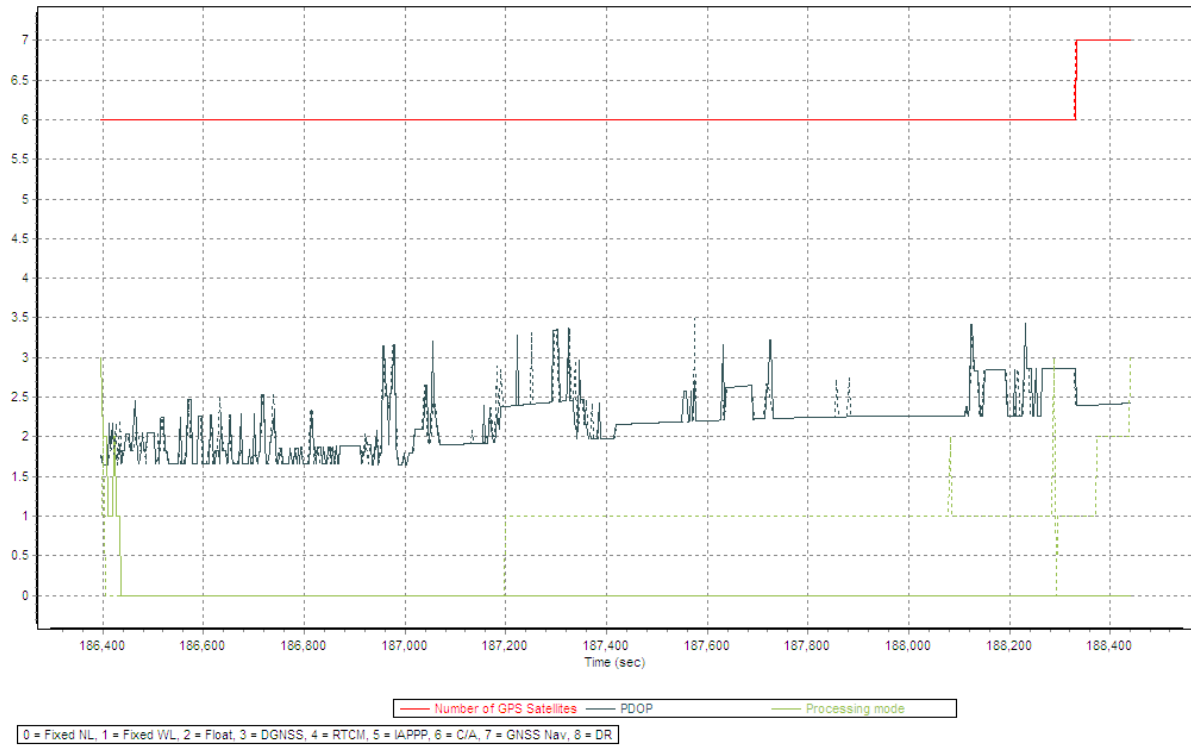


Figure A-8.197. Solution Status

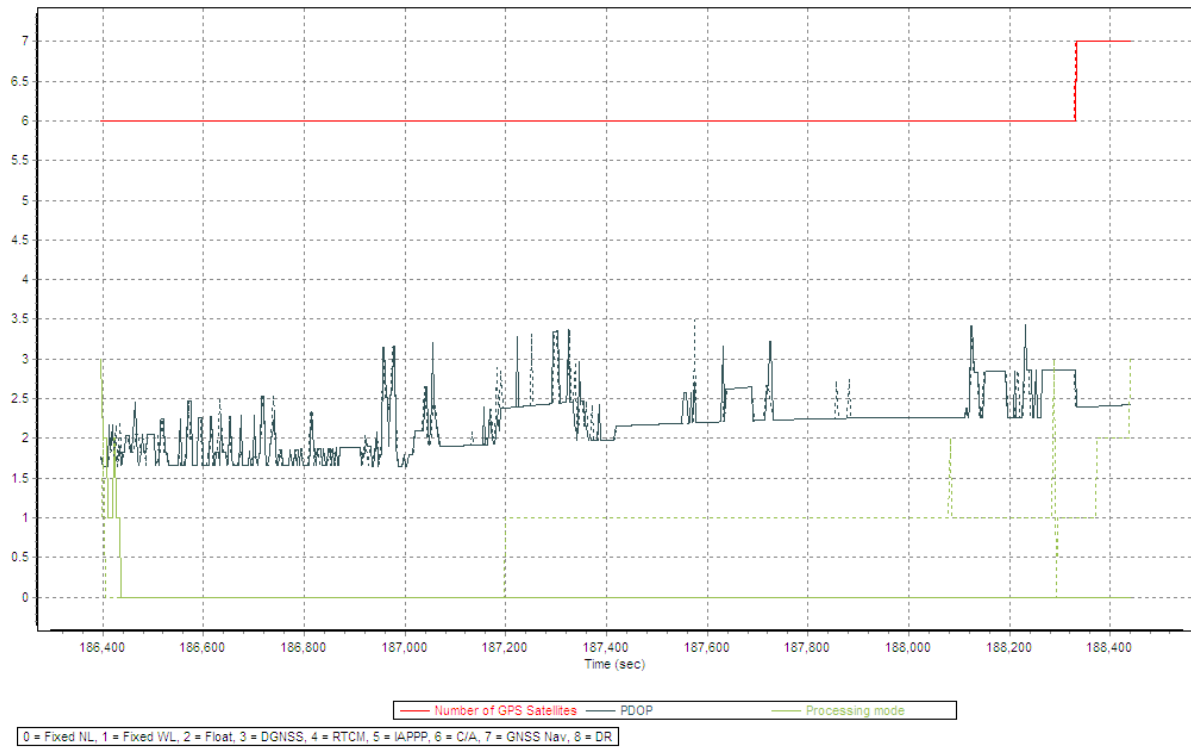


Figure A-8.198. Smoothed Performance Metrics Parameters

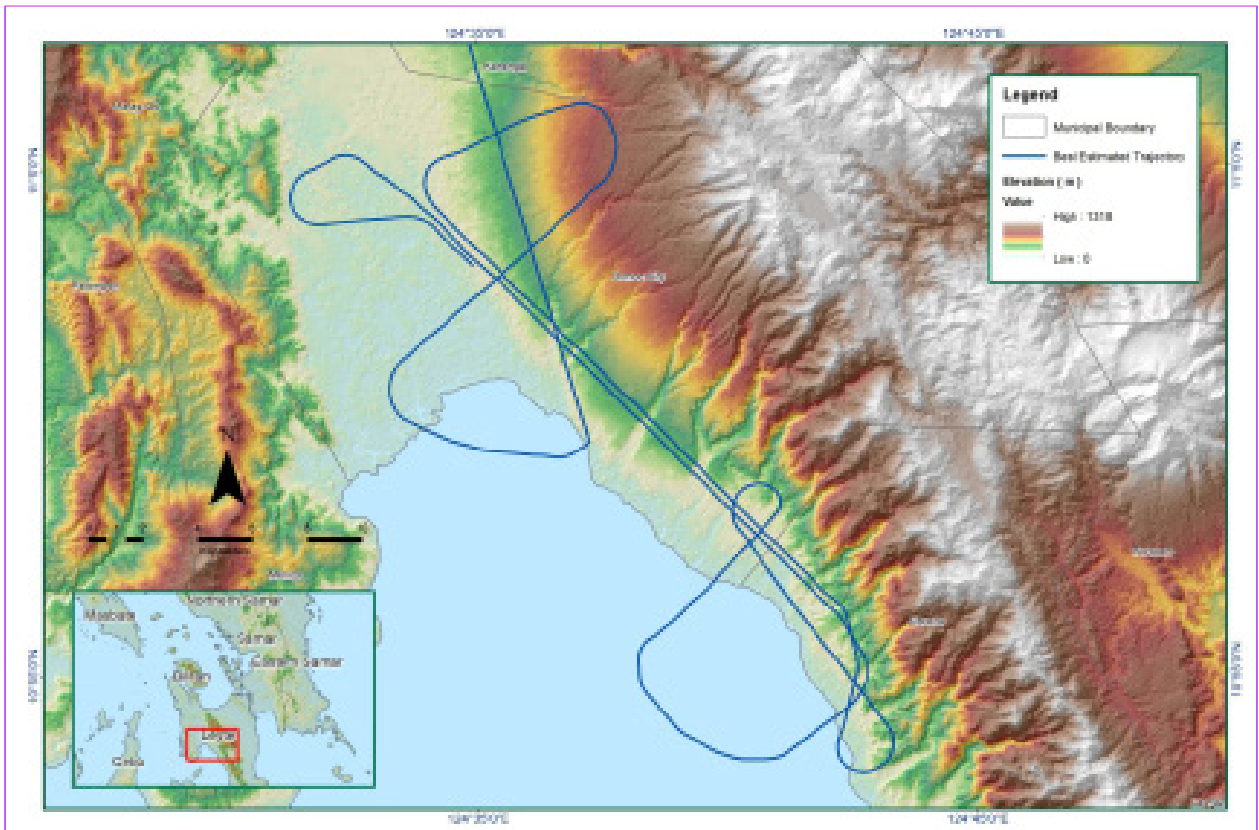


Figure A-8.199. Best Estimated Trajectory

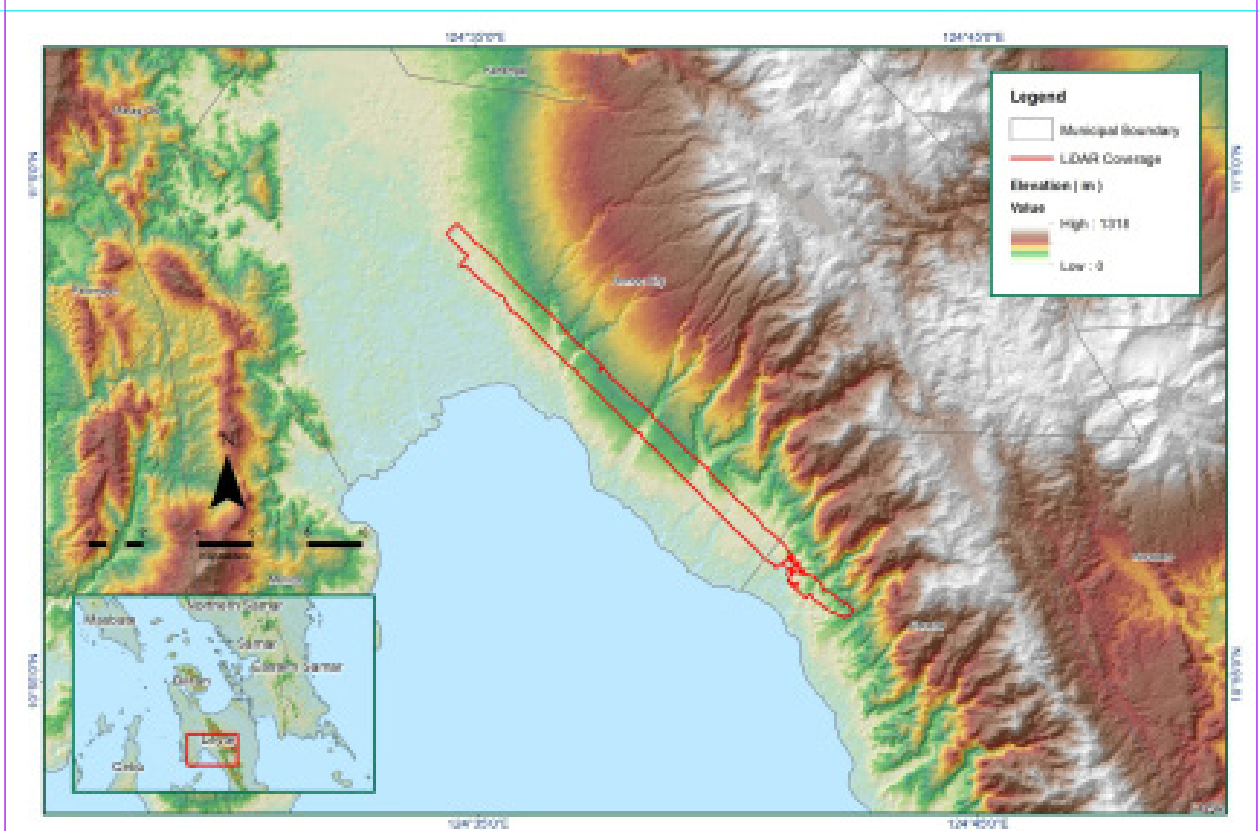


Figure A-8.200. Best Estimated Trajectory



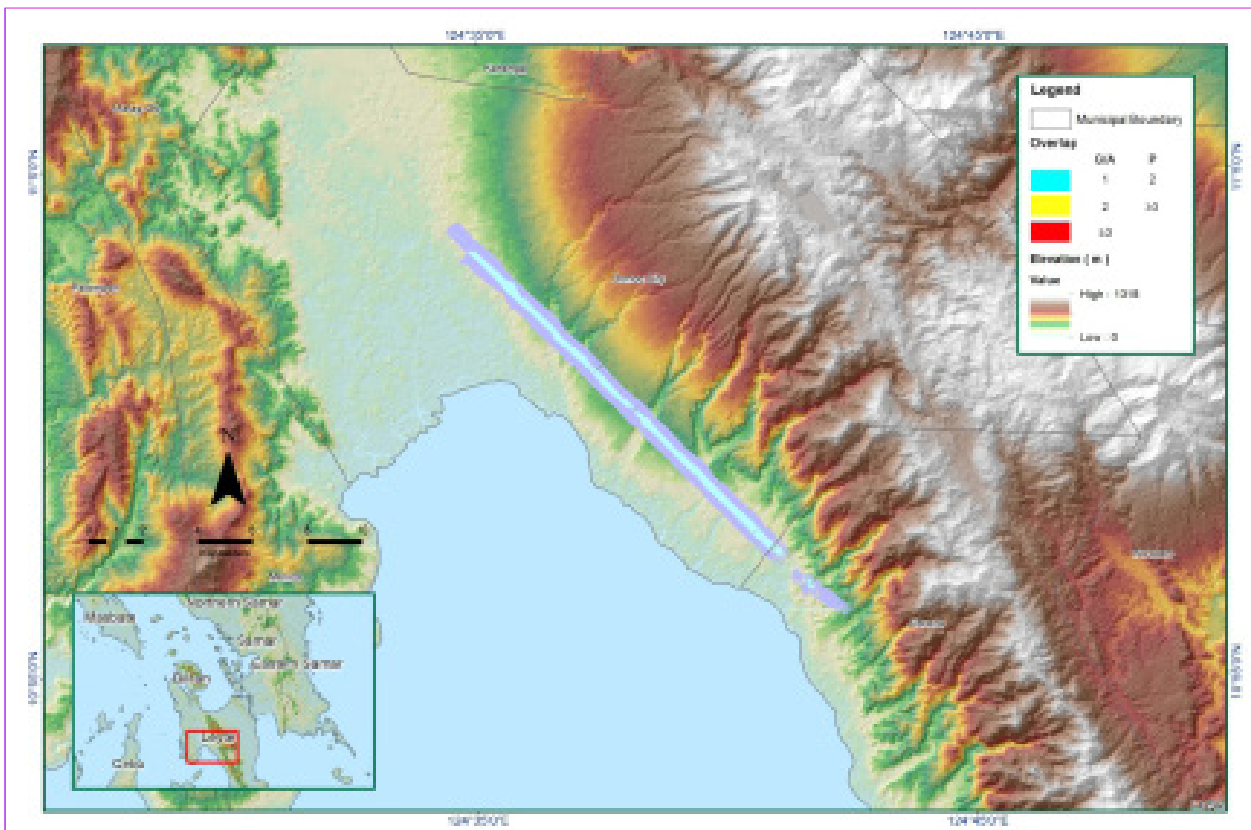


Figure A-8.201. Image of data overlap

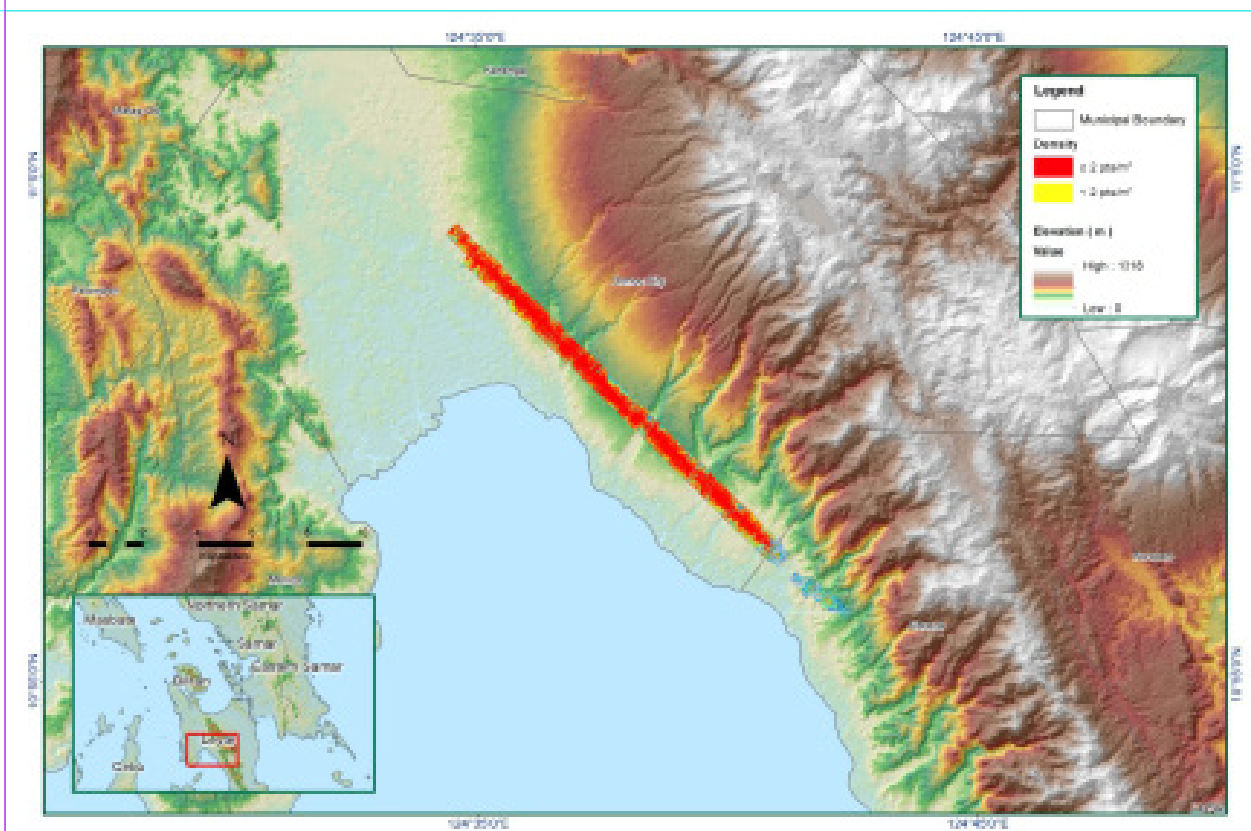


Figure A-8.202. Density map of merged LiDAR data

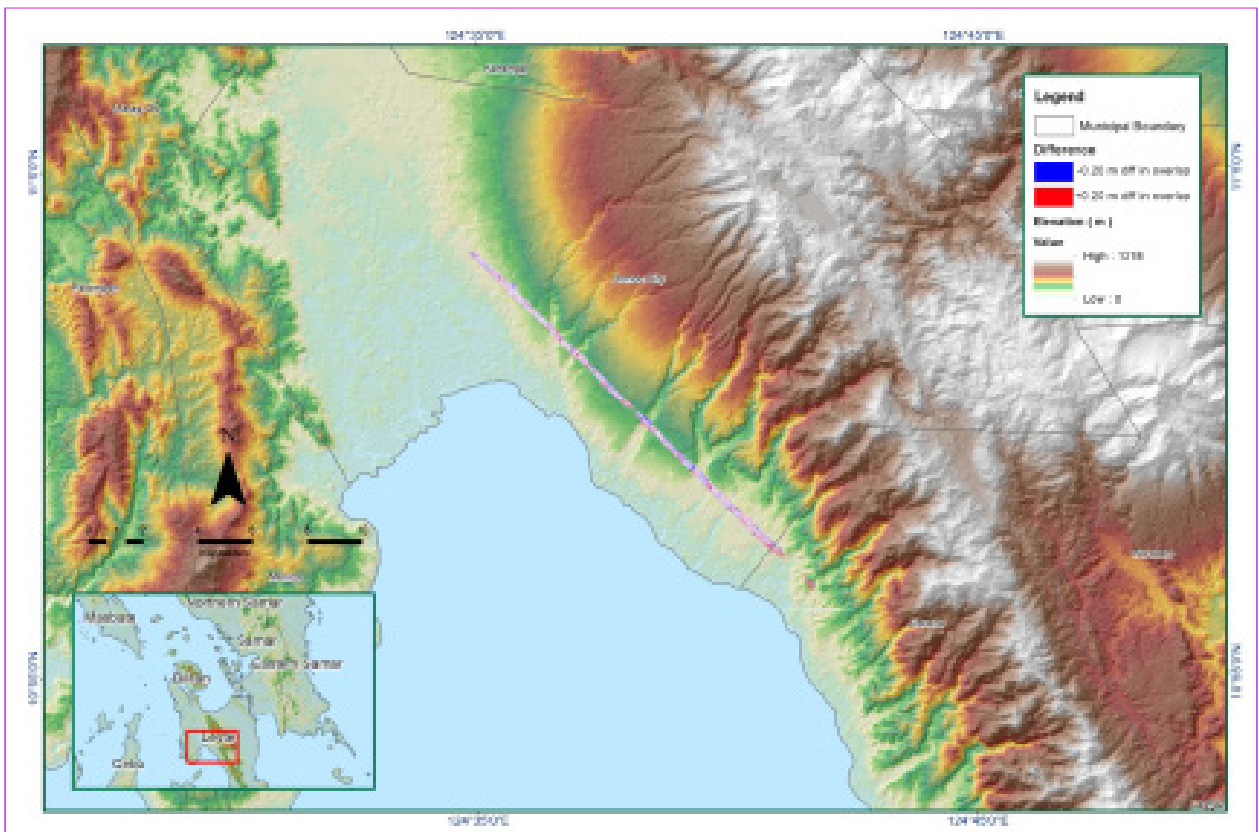


Figure A-8.203. Elevation difference between flight lines

Table A-8.30. Mission Summary Report for Mission Blk35I\_additional

<b>Flight Area</b>	<b>Samar-Leyte</b>
<b>Mission Name</b>	Blk35I_additional
<b>Inclusive Flights</b>	1502A
<b>Range data size</b>	13.9 GB
<b>POS</b>	278 MB
<b>Image</b>	86.7 GB
<b>Transfer date</b>	June 10, 2014
<b>Solution Status</b>	
<b>Number of Satellites (&gt;6)</b>	Yes
<b>PDOP (&lt;3)</b>	Yes
<b>Baseline Length (&lt;30km)</b>	No
<b>Processing Mode (&lt;=1)</b>	No
<b>Smoothed Performance Metrics (in cm)</b>	
<b>RMSE for North Position (&lt;4.0 cm)</b>	2.945
<b>RMSE for East Position (&lt;4.0 cm)</b>	2.56
<b>RMSE for Down Position (&lt;8.0 cm)</b>	5.176
<b>Boresight correction stdev (&lt;0.001deg)</b>	NA
<b>IMU attitude correction stdev (&lt;0.001deg)</b>	NA
<b>GPS position stdev (&lt;0.01m)</b>	NA
<b>Minimum % overlap (&gt;25)</b>	34.24%
<b>Ave point cloud density per sq.m. (&gt;2.0)</b>	3.36
<b>Elevation difference between strips (&lt;0.20 m)</b>	Yes
<b>Number of 1km x 1km blocks</b>	51
<b>Maximum Height</b>	426.96 m
<b>Minimum Height</b>	55.88 m
<b>Classification (# of points)</b>	
<b>Ground</b>	13,787,383
<b>Low vegetation</b>	8,617,597
<b>Medium vegetation</b>	14,734,063
<b>High vegetation</b>	6,099,763
<b>Building</b>	85,084
<b>Orthophoto</b>	No
<b>Processed by</b>	Engr. Irish Cortez, Engr. Harmond Santos, Engr. Gladys Mae Apat

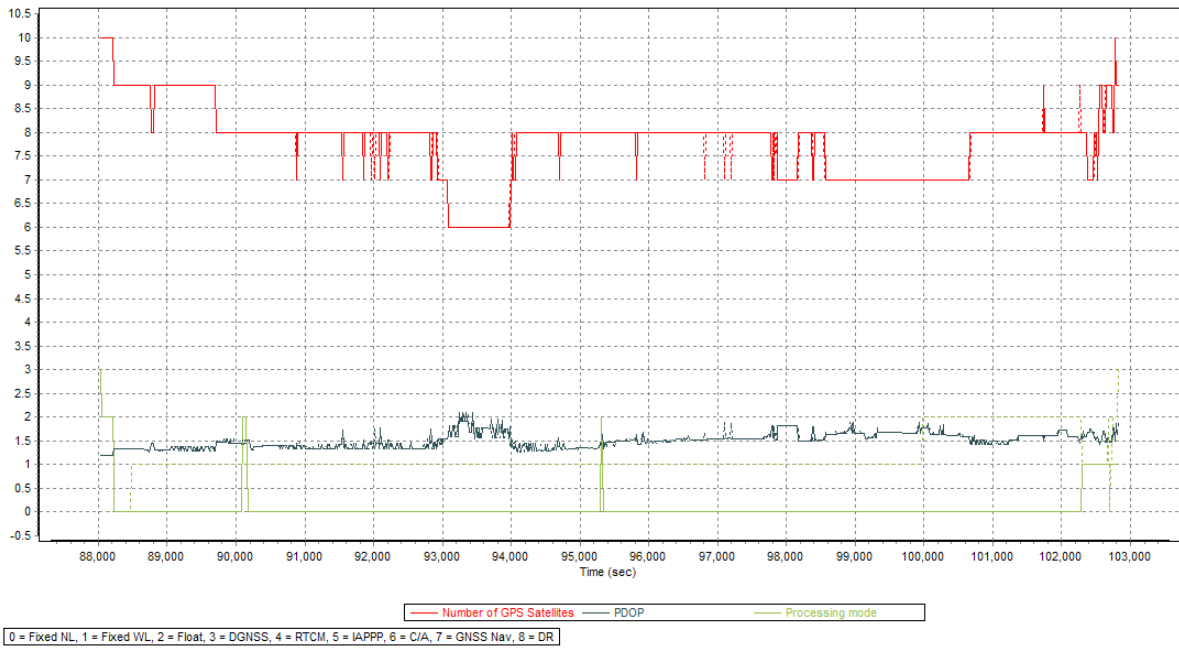


Figure A-8.204. Solution Status

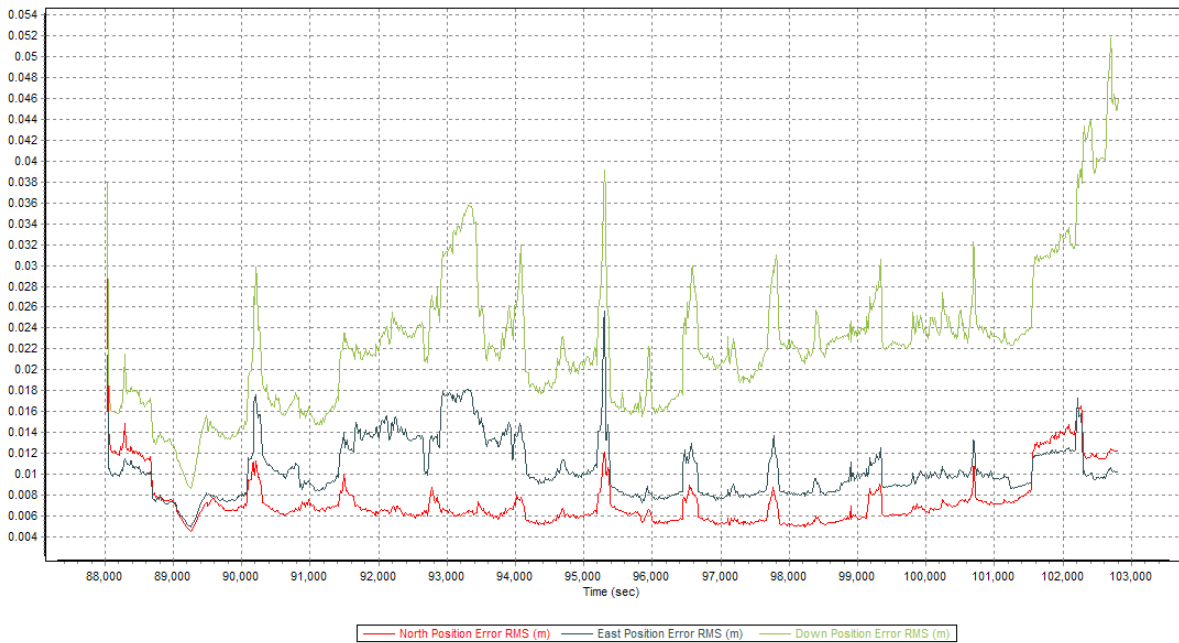


Figure A-8.205. Smoothed Performance Metrics Parameters

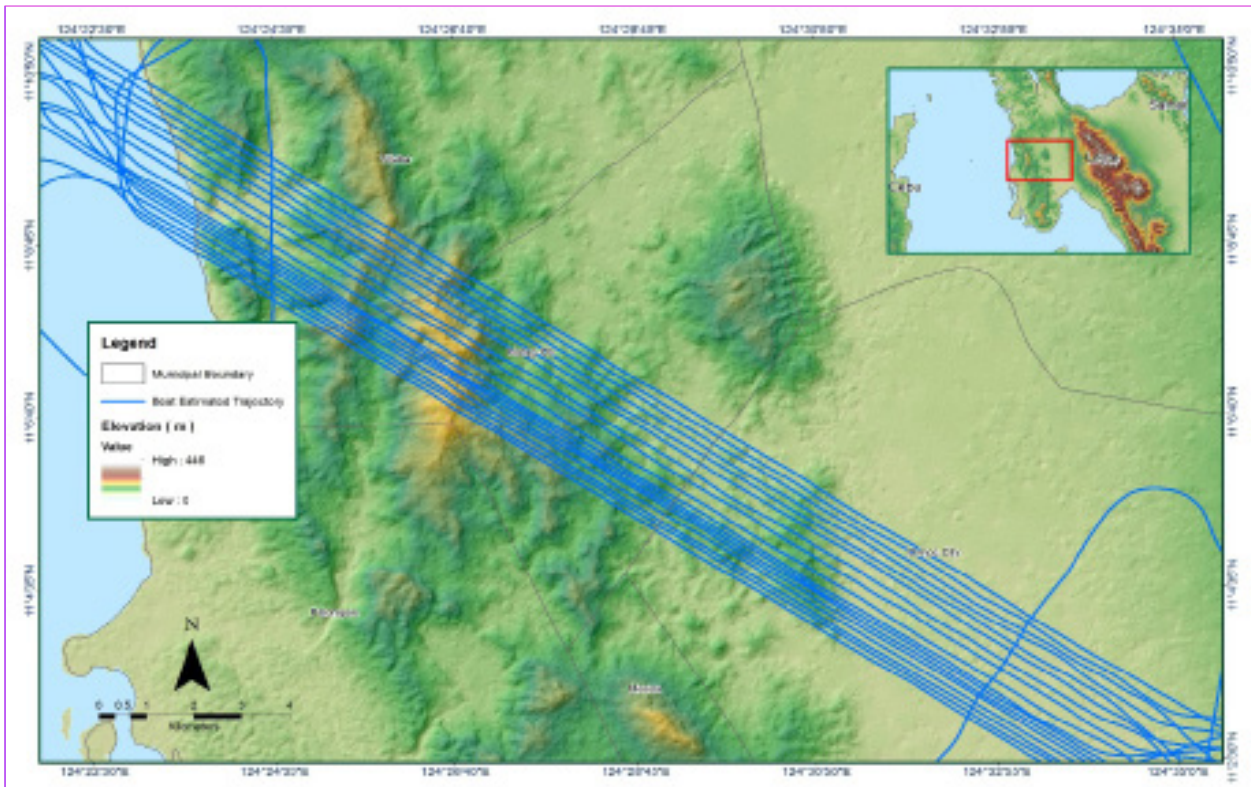


Figure A-8.206. Best Estimated Trajectory

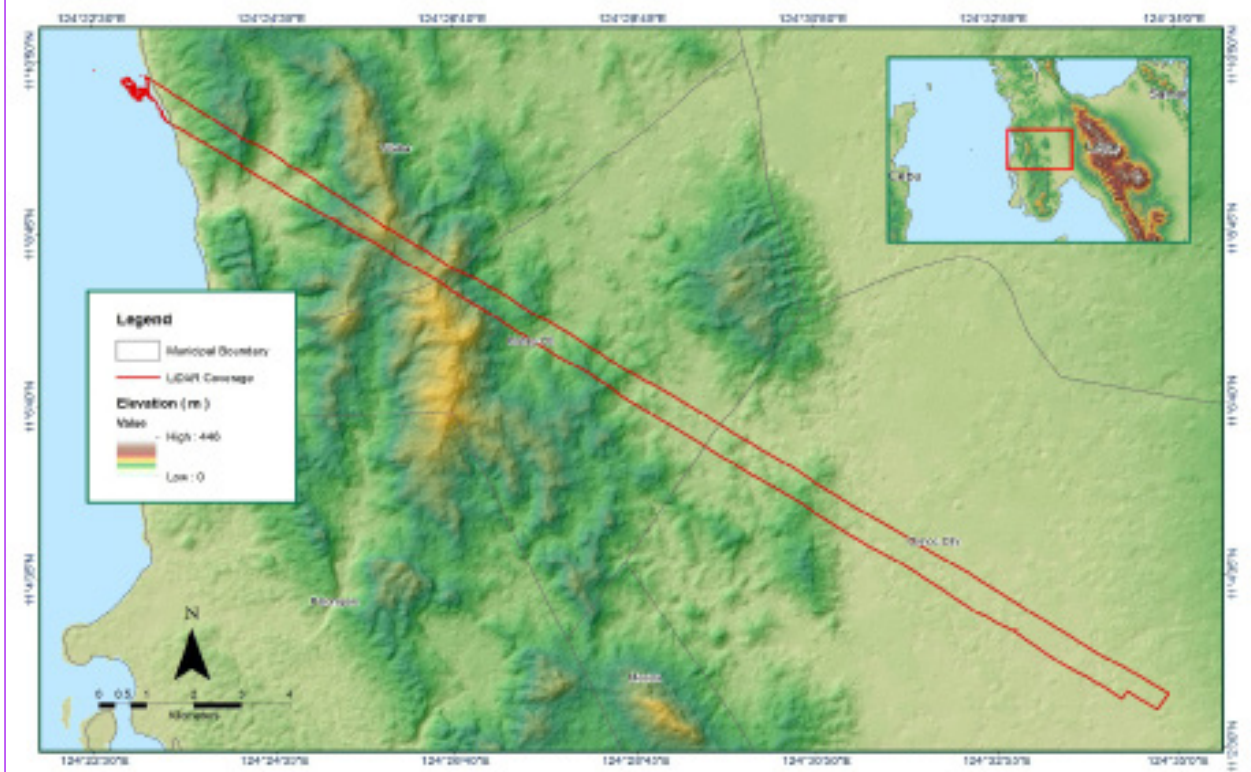


Figure A-8.207. Coverage of LiDAR data

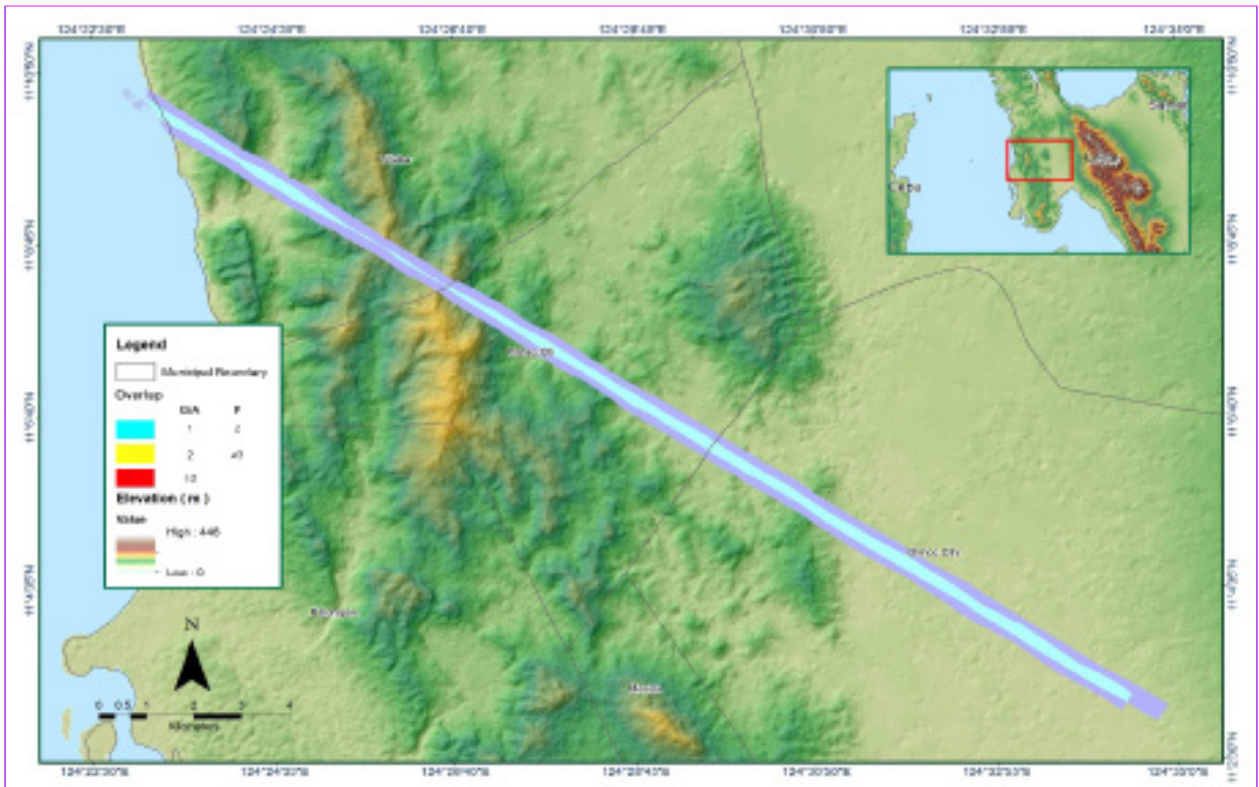


Figure A-8.208. Image of data overlap

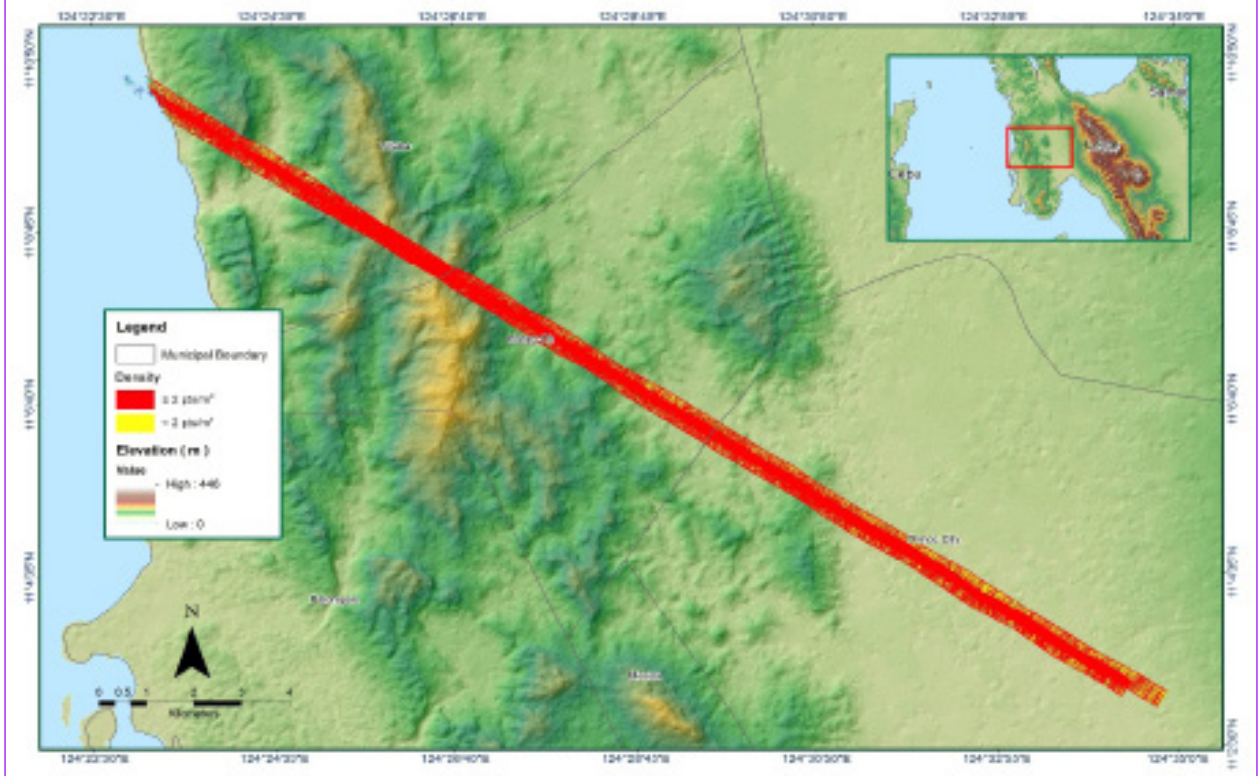


Figure A-8.209. Density map of merged LiDAR data

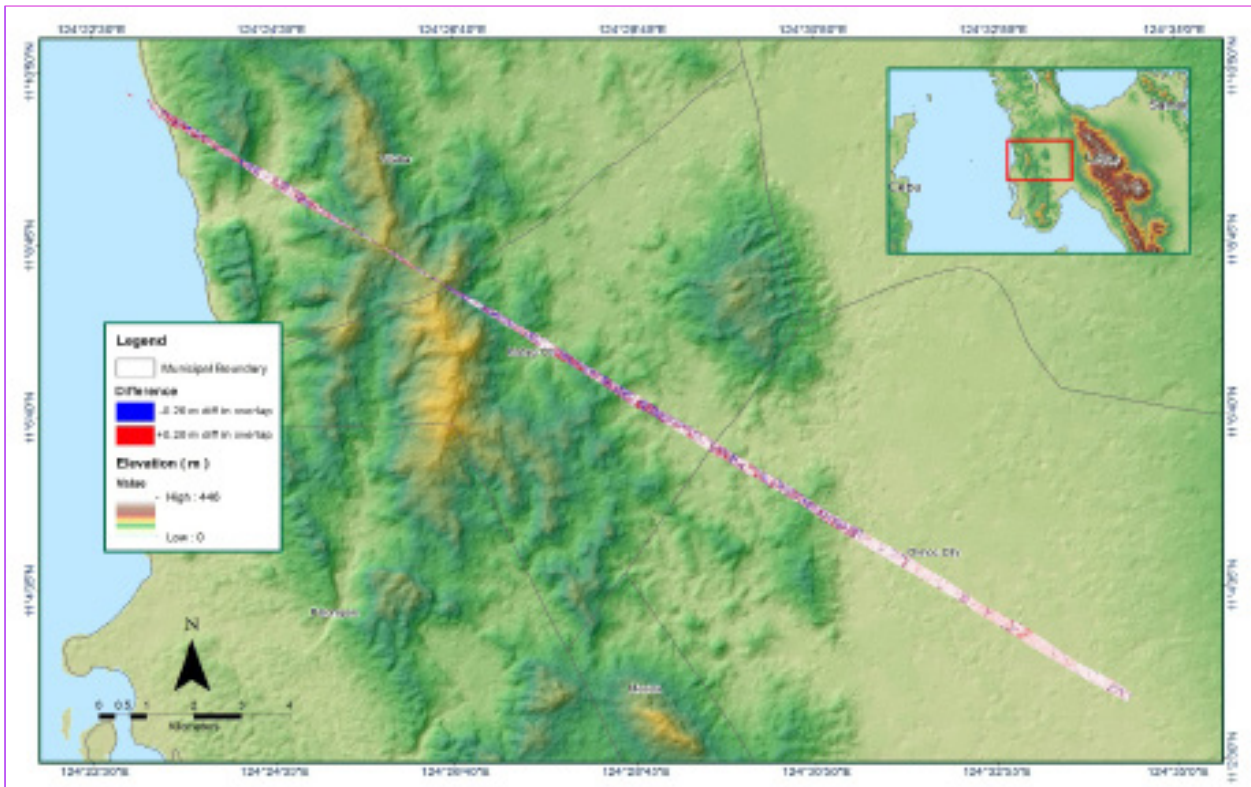


Figure A-8.210. Elevation difference between flight lines

ANNEX 9. Pagsangahan Model Basin Parameters

Table A-9.1. Pagsangahan Model Basin Parameters

Basin Number	SCS Curve Number Loss			Clark Unit Hydrograph Transform		Recession Baseflow				
	Initial Abstraction (mm)	Curve Number	Impervious (%)	Time of Concentration (HR)	Storage Coefficient (HR)	Initial Type	Initial Discharge (cms)	Recession Constant	Threshold Type	Ratio to Peak
W1000	12.892	78.850	0	1.3659	16.719	Discharge	0.751	1	Ratio to Peak	0.1
W1010	11.023	75.897	0	1.1530	14.113	Discharge	0.449	1	Ratio to Peak	0.1
W1020	10.729	74.100	0	1.9129	23.414	Discharge	0.110	1	Ratio to Peak	0.1
W520	11.874	68.037	0	2.5941	31.752	Discharge	1.840	1	Ratio to Peak	0.1
W530	19.004	74.586	0	2.6583	32.538	Discharge	0.849	1	Ratio to Peak	0.1
W540	26.947	78.015	0	2.1199	25.947	Discharge	0.416	1	Ratio to Peak	0.1
W550	11.457	73.325	0	1.5118	18.504	Discharge	0.399	1	Ratio to Peak	0.1
W560	13.233	78.850	0	2.1081	25.803	Discharge	0.643	1	Ratio to Peak	0.1
W570	10.945	76.536	0	1.9855	24.303	Discharge	0.422	1	Ratio to Peak	0.1
W580	16.616	78.850	0	1.4128	17.293	Discharge	0.349	1	Ratio to Peak	0.1
W590	9.3840	79.226	0	2.7966	34.231	Discharge	0.469	1	Ratio to Peak	0.1
W600	14.986	77.779	0	1.7972	21.998	Discharge	0.447	1	Ratio to Peak	0.1
W610	7.1679	69.835	0	1.6001	19.586	Discharge	0.552	1	Ratio to Peak	0.1
W620	7.1010	62.700	0	0.0335	0.4107	Discharge	0.001	1	Ratio to Peak	0.1
W630	10.534	78.301	0	4.7507	58.148	Discharge	0.812	1	Ratio to Peak	0.1
W640	9.5862	76.128	0	3.1826	38.954	Discharge	0.780	1	Ratio to Peak	0.1
W650	9.7383	78.950	0	2.5654	31.401	Discharge	0.812	1	Ratio to Peak	0.1
W660	7.3841	72.308	0	1.6599	20.317	Discharge	1.074	1	Ratio to Peak	0.1
W670	14.759	80.997	0	2.3515	28.782	Discharge	1.097	1	Ratio to Peak	0.1
W680	7.8413	74.100	0	2.6710	32.692	Discharge	0.111	1	Ratio to Peak	0.1



Basin Number	SCS Curve Number Loss			Clark Unit Hydrograph Transform		Recession Baseflow				
	Initial Abstraction (mm)	Curve Number	Impervious (%)	Time of Concentration (HR)	Storage Coefficient (HR)	Initial Type	Initial Discharge (cms)	Recession Constant	Threshold Type	Ratio to Peak
W690	37.239	84.094	0	0.99106	12.131	Discharge	0.169	1	Ratio to Peak	0.1
W700	9.0972	84.191	0	1.3828	16.925	Discharge	0.358	1	Ratio to Peak	0.1
W710	7.7202	79.478	0	2.2154	27.117	Discharge	0.906	1	Ratio to Peak	0.1
W720	17.551	80.726	0	4.5477	55.664	Discharge	0.629	1	Ratio to Peak	0.1
W730	10.824	80.523	0	1.7411	21.311	Discharge	0.509	1	Ratio to Peak	0.1
W740	31.376	83.781	0	1.2765	15.624	Discharge	0.430	1	Ratio to Peak	0.1
W750	14.730	74.356	0	2.2954	28.096	Discharge	0.170	1	Ratio to Peak	0.1
W760	9.5024	83.128	0	2.1629	26.474	Discharge	0.485	1	Ratio to Peak	0.1
W770	10.805	55.370	0	1.6764	20.519	Discharge	0.839	1	Ratio to Peak	0.1
W780	7.0467	81.385	0	1.8009	22.043	Discharge	0.979	1	Ratio to Peak	0.1
W790	26.947	83.300	0	1.3442	16.453	Discharge	0.549	1	Ratio to Peak	0.1
W800	30.385	71.320	0	1.2022	14.714	Discharge	0.413	1	Ratio to Peak	0.1
W810	13.762	79.105	0	1.5404	18.854	Discharge	0.436	1	Ratio to Peak	0.1
W820	18.108	59.321	0	2.8130	34.431	Discharge	1.132	1	Ratio to Peak	0.1
W830	10.973	74.389	0	2.5650	31.395	Discharge	0.200	1	Ratio to Peak	0.1
W840	6.8552	80.838	0	2.4979	30.574	Discharge	0.170	1	Ratio to Peak	0.1
W850	14.757	79.130	0	1.2412	15.192	Discharge	0.385	1	Ratio to Peak	0.1
W860	17.475	84.270	0	0.6558	8.0275	Discharge	0.196	1	Ratio to Peak	0.1
W870	14.718	62.700	0	0.5855	7.1675	Discharge	0.098	1	Ratio to Peak	0.1
W880	12.037	60.045	0	2.0935	25.625	Discharge	1.639	1	Ratio to Peak	0.1
W890	14.836	75.505	0	1.7666	21.623	Discharge	0.814	1	Ratio to Peak	0.1
W900	18.088	70.743	0	1.0241	12.535	Discharge	0.200	1	Ratio to Peak	0.1

Basin Number	SCS Curve Number Loss			Clark Unit Hydrograph Transform		Recession Baseflow				
	Initial Abstraction (mm)	Curve Number	Impervious (%)	Time of Concentration (HR)	Storage Coefficient (HR)	Initial Type	Initial Discharge (cms)	Recession Constant	Threshold Type	Ratio to Peak
W910	17.768	78.913	0	3.6438	44.600	Discharge	0.634	1	Ratio to Peak	0.1
W920	6.2787	84.550	0	0.6346	7.7682	Discharge	0.009	1	Ratio to Peak	0.1
W930	14.101	74.359	0	1.8075	22.123	Discharge	0.474	1	Ratio to Peak	0.1
W940	16.792	71.399	0	2.5141	30.772	Discharge	0.202	1	Ratio to Peak	0.1
W950	14.062	74.403	0	1.2805	15.673	Discharge	0.475	1	Ratio to Peak	0.1
W960	11.409	77.577	0	1.1234	13.750	Discharge	0.35737	1	Ratio to Peak	0.1
W970	14.180	74.269	0	3.8842	47.5423654	Discharge	0.40618	1	Ratio to Peak	0.1
W980	17.399	70.763	0	3.0016	36.740	Discharge	0.61078	1	Ratio to Peak	0.1
W990	17.082	71.094	0	3.323893	40.684	Discharge	0.71920	1	Ratio to Peak	0.1

## ANNEX 10. Pagsangahan Model Reach Parameters

Table A-10.1. Pagsangahan Model Reach Parameters

Reach Number	Muskingum Cunge Channel Routing						
	Time Step Method	Length (m)	Slope	Manning's n	Shape	Width	Side Slope
R130	Automatic Fixed Interval	1806.5	0.0007	0.5175	Trapezoid	30	45
R140	Automatic Fixed Interval	3761.6	0.0015	0.1459	Trapezoid	30	45
R150	Automatic Fixed Interval	3512.3	0.0022	0.3649	Trapezoid	30	45
R160	Automatic Fixed Interval	2685.4	0.0028	0.0129	Trapezoid	30	45
R180	Automatic Fixed Interval	3376.5	0.0014	0.0583	Trapezoid	30	45
R190	Automatic Fixed Interval	5795.5	0.0024	0.0257	Trapezoid	30	45
R210	Automatic Fixed Interval	1955.8	0.0010	0.1611	Trapezoid	30	45
R230	Automatic Fixed Interval	5125.2	0.0006	0.0964	Trapezoid	30	45
R240	Automatic Fixed Interval	9314.2	0.0008	0.0325	Trapezoid	30	45
R260	Automatic Fixed Interval	2428.4	0.0029	0.1623	Trapezoid	30	45
R300	Automatic Fixed Interval	3832.9	0.0008	0.0129	Trapezoid	30	45
R310	Automatic Fixed Interval	3312.8	0.3146	0.1621	Trapezoid	30	45
R330	Automatic Fixed Interval	501.84	0.0318	0.0622	Trapezoid	30	45
R340	Automatic Fixed Interval	2267.4	0.0029	0.4026	Trapezoid	30	45
R350	Automatic Fixed Interval	3259.3	0.0017	1	Trapezoid	30	45
R370	Automatic Fixed Interval	12095	0.0152	0.0331	Trapezoid	30	45
R380	Automatic Fixed Interval	1300.8	0.0008	0.1220	Trapezoid	30	45
R400	Automatic Fixed Interval	694.56	0.0067	0.0899	Trapezoid	30	45
R440	Automatic Fixed Interval	3378.4	0.0046	0.1016	Trapezoid	30	45
R450	Automatic Fixed Interval	2793.7	0.0008	0.0446	Trapezoid	30	45
R490	Automatic Fixed Interval	7343.5	0.0031	0.1011	Trapezoid	30	45
R500	Automatic Fixed Interval	6193.3	0.0010	0.0141	Trapezoid	30	45
R510	Automatic Fixed Interval	1157.5	0.0008	0.1425	Trapezoid	30	45
R60	Automatic Fixed Interval	2858.7	0.0026	0.0712	Trapezoid	30	45
R80	Automatic Fixed Interval	114.85	0.0008	0.2442	Trapezoid	30	45

## ANNEX 11. Pagsangahan Field Validation Points

Table A-11.1. Pagsangahan Field Validation Points for the 5-Year Flood Depth Map

Point Number	Validation Coordinates		Model Var (m)	Validation Points (m)	Error (m)	Event/Date	Rain Return/ Scenario
	Lat	Long					
2	11.071	124.54	0.061	0	0.06	Typhoon Ruby/ December 07, 2014	5 -Year
4	11.075	124.53	0.754	0.36	0.39	Typhoon Ruby/ December 07, 2014	5 -Year
7	11.080	124.53	3.532	0.1	3.43	Typhoon Yolanda/ November 8, 2013	5 -Year
9	11.070	124.54	0.589	0.48	0.11	Typhoon Yolanda/ November 8, 2013	5 -Year
10	11.068	124.54	1.021	0.48	0.54	Typhoon Yolanda/ November 8, 2013	5 -Year
11	11.075	124.56	0.030	0.95	-0.92	Typhoon Yolanda/ November 8, 2013	5 -Year
12	11.075	124.56	0.030	0.1	-0.07	Typhoon Yolanda/ November 8, 2013	5 -Year
13	11.077	124.56	0.030	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
14	11.079	124.56	0.030	0.1	-0.07	Typhoon Ruby/ December 07, 2014	5 -Year
17	11.077	124.57	0.030	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
18	11.069	124.56	0.340	0	0.34	Typhoon Ruby/ December 07, 2014	5 -Year
21	11.076	124.54	0.030	0.1	-0.07	Typhoon Ruby/ December 07, 2014	5 -Year
22	11.082	124.54	0.030	0.95	-0.92	Typhoon Yolanda/ December 07, 2014	5 -Year
23	11.086	124.54	0.056	0	0.06	Typhoon Ruby/ December 07, 2014	5 -Year
24	11.094	124.55	0.030	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
25	11.098	124.55	0.035	0	0.04	Typhoon Ruby/ December 07, 2014	5 -Year
26	11.099	124.56	0.035	0	0.04	Typhoon Ruby/ December 07, 2014	5 -Year
27	11.100	124.56	0.035	0	0.04	Typhoon Ruby/ December 07, 2014	5 -Year
28	11.095	124.54	0.030	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
29	11.095	124.54	0.031	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
30	11.092	124.54	0.039	0	0.04	Typhoon Ruby/ December 07, 2014	5 -Year
31	11.091	124.54	0.030	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
32	11.090	124.53	0.424	0	0.42	Typhoon Ruby/ December 07, 2014	5 -Year
36	11.091	124.54	0.127	0	0.13	Typhoon Ruby/ December 07, 2014	5 -Year
37	11.058	124.55	0.510	1	-0.49	Typhoon Ruby/ December 07, 2014	5 -Year
40	11.050	124.55	0.139	0.48	-0.34	Typhoon Ruby/ December 07, 2014	5 -Year
41	11.048	124.55	0.550	0.48	0.07	Typhoon Ruby/ December 07, 2014	5 -Year
42	11.046	124.55	0.494	0.48	0.01	Typhoon Ruby/ December 07, 2014	5 -Year
43	11.041	124.55	0.030	0.48	-0.45	Typhoon Ruby/ December 07, 2014	5 -Year
44	11.042	124.55	0.160	0.66	-0.50	Typhoon Ruby/ December 07, 2014	5 -Year
45	11.042	124.55	0.404	0.95	-0.55	Typhoon Ruby/ December 07, 2014	5 -Year
46	11.040	124.55	0.030	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
47	11.034	124.57	0.030	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
48	11.036	124.56	0.437	0.95	-0.51	Typhoon Ruby/ December 07, 2014	5 -Year

Point Number	Validation Coordinates		Model Var (m)	Validation Points (m)	Error (m)	Event/Date	Rain Return/Scenario
	Lat	Long					
49	11.036	124.55	0.339	0	0.34	Typhoon Ruby/ December 07, 2014	5 -Year
50	11.036	124.55	0.339	0	0.34	Typhoon Ruby/ December 07, 2014	5 -Year
51	11.033	124.55	0.172	0.66	-0.49	Typhoon Ruby/ December 07, 2014	5 -Year
52	11.030	124.55	0.509	0.66	-0.15	Typhoon Ruby/ December 07, 2014	5 -Year
53	11.026	124.55	0.409	0.36	0.05	Typhoon Ruby/ December 07, 2014	5 -Year
54	11.024	124.55	0.390	0.36	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
55	11.024	124.55	0.030	0.36	-0.33	Typhoon Ruby/ December 07, 2014	5 -Year
56	11.024	124.55	0.030	0.36	-0.33	Typhoon Ruby/ December 07, 2014	5 -Year
57	11.021	124.56	0.092	0.36	-0.27	Typhoon Ruby/ December 07, 2014	5 -Year
58	11.020	124.56	0.756	0.48	0.28	Typhoon Ruby/ December 07, 2014	5 -Year
59	11.018	124.56	0.166	0.48	-0.31	Typhoon Ruby/ December 07, 2014	5 -Year
60	11.018	124.56	0.131	0.95	-0.82	Typhoon Ruby/ December 07, 2014	5 -Year
62	11.019	124.56	0.334	0.48	-0.15	Typhoon Ruby/ December 07, 2014	5 -Year
63	11.020	124.55	0.071	0.48	-0.41	Typhoon Ruby/ December 07, 2014	5 -Year
64	11.023	124.55	0.030	0.48	-0.45	Typhoon Ruby/ December 07, 2014	5 -Year
65	11.039	124.55	0.874	0.48	0.39	Typhoon Ruby/ December 07, 2014	5 -Year
67	11.040	124.55	0.230	0.95	-0.72	Typhoon Ruby/ December 07, 2014	5 -Year
68	11.039	124.55	0.658	0.95	-0.29	Typhoon Ruby/ December 07, 2014	5 -Year
70	11.042	124.54	0.866	0.95	-0.08	Typhoon Ruby/ December 07, 2014	5 -Year
71	11.043	124.54	1.074	0.95	0.12	Typhoon Ruby/ December 07, 2014	5 -Year
72	11.045	124.55	0.610	0.48	0.13	Typhoon Ruby/ December 07, 2014	5 -Year
73	11.049	124.54	1.233	0.48	0.75	Typhoon Ruby/ December 07, 2014	5 -Year
74	11.048	124.54	0.964	0.48	0.48	Typhoon Ruby/ December 07, 2014	5 -Year
75	11.046	124.55	1.008	0.48	0.53	Typhoon Ruby/ December 07, 2014	5 -Year
76	11.043	124.54	1.198	0.95	0.25	Typhoon Ruby/ December 07, 2014	5 -Year
77	11.042	124.54	1.562	0.1	1.46	Typhoon Ruby/ December 07, 2014	5 -Year
78	11.042	124.54	1.562	0.95	0.61	Typhoon Ruby/ December 07, 2014	5 -Year
79	11.041	124.54	1.411	0.48	0.93	Typhoon Ruby/ December 07, 2014	5 -Year
80	11.041	124.54	1.285	0.48	0.80	Typhoon Ruby/ December 07, 2014	5 -Year
81	11.040	124.54	1.310	0.48	0.83	Typhoon Ruby/ December 07, 2014	5 -Year
84	11.042	124.54	1.185	1.52	-0.34	Typhoon Ruby/ December 07, 2014	5 -Year
85	11.045	124.54	1.185	0.48	0.70	Typhoon Ruby/ December 07, 2014	5 -Year
86	11.045	124.54	0.839	0.48	0.36	Typhoon Ruby/ December 07, 2014	5 -Year
87	11.051	124.53	0.030	0.48	-0.45	Typhoon Ruby/ December 07, 2014	5 -Year
88	11.052	124.53	0.030	0.48	-0.45	Typhoon Ruby/ December 07, 2014	5 -Year
89	11.054	124.53	0.030	0.36	-0.33	Typhoon Ruby/ December 07, 2014	5 -Year
90	11.058	124.53	0.030	0.48	-0.45	Typhoon Ruby/ December 07, 2014	5 -Year
91	11.062	124.53	0.268	0	0.27	Typhoon Ruby/ December 07, 2014	5 -Year

Point Number	Validation Coordinates		Model Var (m)	Validation Points (m)	Error (m)	Event/Date	Rain Return/ Scenario
	Lat	Long					
92	11.036	124.56	0.038	0	0.04	Typhoon Ruby/ December 07, 2014	5 -Year
93	11.033	124.56	0.030	0.48	-0.45	Typhoon Ruby/ December 07, 2014	5 -Year
94	11.032	124.56	0.030	0.36	-0.33	Typhoon Ruby/ December 07, 2014	5 -Year
95	11.029	124.56	0.030	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
96	11.026	124.56	0.030	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
97	11.023	124.57	0.030	0.1	-0.07	Typhoon Ruby/ December 07, 2014	5 -Year
98	11.021	124.56	0.644	0.36	0.28	Typhoon Ruby/ December 07, 2014	5 -Year
99	11.026	124.56	0.644	0.36	0.28	Typhoon Yolanda/ November 8, 2013	5 -Year
105	11.074	124.52	0.031	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
107	11.076	124.52	0.031	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
108	11.082	124.52	0.034	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
109	11.083	124.52	0.211	0	0.21	Typhoon Ruby/ December 07, 2014	5 -Year
110	11.086	124.52	0.257	0	0.26	Typhoon Ruby/ December 07, 2014	5 -Year
111	11.088	124.52	0.031	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
112	11.089	124.52	0.030	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
113	11.091	124.52	0.032	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
114	11.090	124.52	1.952	0.36	1.59	Typhoon Ruby/ December 07, 2014	5 -Year
115	11.090	124.52	2.088	0.48	1.61	Typhoon Yolanda/ November 8, 2013	5 -Year
118	11.089	124.52	2.306	0.48	1.83	Typhoon Ruby/ December 07, 2014	5 -Year
119	11.090	124.52	2.222	0.48	1.74	Typhoon Ruby/ December 07, 2014	5 -Year
120	11.093	124.52	0.112	0	0.11	Typhoon Ruby/ December 07, 2014	5 -Year
121	11.093	124.52	0.031	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
122	11.094	124.52	0.031	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
123	11.095	124.52	0.030	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
124	11.074	124.52	0.031	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
125	11.073	124.52	0.579	0.48	0.10	Typhoon Ruby/ December 07, 2014	5 -Year
127	11.071	124.52	0.031	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
129	11.070	124.52	0.031	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
130	11.068	124.52	0.127	0	0.13	Typhoon Ruby/ December 07, 2014	5 -Year
131	11.068	124.52	0.327	0	0.33	Typhoon Ruby/ December 07, 2014	5 -Year
133	11.068	124.52	0.032	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
134	11.067	124.52	0.248	0	0.25	Typhoon Ruby/ December 07, 2014	5 -Year
136	11.065	124.52	0.100	0	0.10	Typhoon Ruby/ December 07, 2014	5 -Year
137	11.062	124.52	0.045	0	0.05	Typhoon Ruby/ December 07, 2014	5 -Year
139	11.064	124.52	0.094	0	0.09	Typhoon Ruby/ December 07, 2014	5 -Year
140	11.063	124.52	0.031	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
141	11.063	124.52	0.788	0	0.79	Typhoon Ruby/ December 07, 2014	5 -Year
142	11.062	124.52	0.488	0	0.49	Typhoon Ruby/ December 07, 2014	5 -Year

Point Number	Validation Coordinates		Model Var (m)	Validation Points (m)	Error (m)	Event/Date	Rain Return/Scenario
	Lat	Long					
143	11.061	124.51	0.031	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
144	11.057	124.51	0.061	0	0.06	Typhoon Ruby/ December 07, 2014	5 -Year
145	11.055	124.51	0.092	0	0.09	Typhoon Ruby/ December 07, 2014	5 -Year
146	11.055	124.52	0.060	0	0.06	Typhoon Ruby/ December 07, 2014	5 -Year
147	11.052	124.52	0.031	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
148	11.050	124.52	0.031	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
149	11.046	124.52	0.217	0	0.22	Typhoon Ruby/ December 07, 2014	5 -Year
150	11.043	124.52	0.199	0	0.20	Typhoon Ruby/ December 07, 2014	5 -Year
151	11.040	124.52	0.032	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
152	11.039	124.52	0.093	0	0.09	Typhoon Ruby/ December 07, 2014	5 -Year
153	11.036	124.53	0.030	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
154	11.037	124.53	0.030	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
155	11.038	124.53	0.139	0	0.14	Typhoon Ruby/ December 07, 2014	5 -Year
156	10.999	124.54	0.564	0.95	-0.39	Typhoon Ruby/ December 07, 2014	5 -Year
157	10.999	124.54	1.199	1.7	-0.50	Typhoon Ruby/ December 07, 2014	5 -Year
158	10.999	124.54	0.087	1.95	-1.86	Typhoon Ruby/ December 07, 2014	5 -Year
159	11.001	124.54	1.153	2.74	-1.59	Typhoon Ruby/ December 07, 2014	5 -Year
160	11.002	124.54	1.226	1.52	-0.29	Typhoon Ruby/ December 07, 2014	5 -Year
161	11.003	124.54	1.064	1.12	-0.06	Typhoon Ruby/ December 07, 2014	5 -Year
163	11.005	124.54	1.022	1.52	-0.50	Typhoon Ruby/ December 07, 2014	5 -Year
164	11.005	124.54	1.200	0.95	0.25	Typhoon Ruby/ December 07, 2014	5 -Year
167	11.000	124.54	1.288	0.95	0.34	Typhoon Ruby/ December 07, 2014	5 -Year
168	11.000	124.54	1.077	0.95	0.13	Typhoon Ruby/ December 07, 2014	5 -Year
169	10.999	124.54	1.418	0.95	0.47	Typhoon Ruby/ December 07, 2014	5 -Year
170	10.999	124.54	1.386	0.95	0.44	Typhoon Ruby/ December 07, 2014	5 -Year
171	10.999	124.54	1.171	0.95	0.22	Typhoon Ruby/ December 07, 2014	5 -Year
172	10.999	124.54	1.286	0.95	0.34	Typhoon Ruby/ December 07, 2014	5 -Year
173	11.000	124.54	1.162	1.38	-0.22	Typhoon Ruby/ December 07, 2014	5 -Year
174	11.000	124.53	0.031	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
175	11.004	124.53	0.030	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
176	11.004	124.53	0.041	0	0.04	Typhoon Ruby/ December 07, 2014	5 -Year
177	11.006	124.53	0.061	0	0.06	Typhoon Ruby/ December 07, 2014	5 -Year
178	11.008	124.53	0.031	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
179	11.009	124.53	0.030	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
180	11.012	124.53	0.031	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
181	11.016	124.53	0.030	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
182	11.017	124.53	0.071	0	0.07	Typhoon Ruby/ December 07, 2014	5 -Year
183	11.016	124.53	0.030	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year

Point Number	Validation Coordinates		Model Var (m)	Validation Points (m)	Error (m)	Event/Date	Rain Return/ Scenario
	Lat	Long					
184	11.017	124.53	0.060	0	0.06	Typhoon Ruby/ December 07, 2014	5 -Year
185	11.018	124.53	0.246	0	0.25	Typhoon Ruby/ December 07, 2014	5 -Year
186	11.020	124.53	0.353	0	0.35	Typhoon Ruby/ December 07, 2014	5 -Year
187	11.022	124.53	0.100	0	0.10	Typhoon Ruby/ December 07, 2014	5 -Year
188	11.023	124.53	0.030	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
189	11.026	124.53	0.030	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
190	11.028	124.53	0.030	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
191	11.030	124.52	0.119	0	0.12	Typhoon Ruby/ December 07, 2014	5 -Year
192	11.032	124.52	0.982	0	0.98	Typhoon Ruby/ December 07, 2014	5 -Year
193	11.037	124.53	0.076	0	0.08	Typhoon Ruby/ December 07, 2014	5 -Year
194	11.037	124.53	0.215	0.1	0.12	Typhoon Ruby/ December 07, 2014	5 -Year
195	11.036	124.53	0.493	0.1	0.39	Typhoon Ruby/ December 07, 2014	5 -Year
196	11.033	124.53	0.449	0.48	-0.03	Typhoon Ruby/ December 07, 2014	5 -Year
197	11.028	124.54	0.671	0	0.67	Typhoon Ruby/ December 07, 2014	5 -Year
198	11.029	124.54	0.759	0	0.76	Typhoon Ruby/ December 07, 2014	5 -Year
199	11.031	124.53	0.462	0	0.46	Typhoon Ruby/ December 07, 2014	5 -Year
200	11.032	124.53	0.491	0	0.49	Typhoon Ruby/ December 07, 2014	5 -Year
201	11.032	124.53	0.416	0	0.42	Typhoon Ruby/ December 07, 2014	5 -Year
202	11.012	124.52	0.042	0	0.04	Typhoon Ruby/ December 07, 2014	5 -Year
203	11.020	124.52	0.031	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
204	11.028	124.52	0.142	0	0.14	Typhoon Ruby/ December 07, 2014	5 -Year
205	11.038	124.51	0.572	0	0.57	Typhoon Ruby/ December 07, 2014	5 -Year
206	11.046	124.49	0.030	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
207	11.058	124.47	0.232	0	0.23	Typhoon Ruby/ December 07, 2014	5 -Year
208	11.078	124.49	0.047	0	0.05	Typhoon Ruby/ December 07, 2014	5 -Year
209	11.080	124.49	1.244	0	1.24	Typhoon Ruby/ December 07, 2014	5 -Year
210	11.073	124.49	0.811	0	0.81	Typhoon Ruby/ December 07, 2014	5 -Year
211	11.071	124.49	0.743	0	0.74	Typhoon Ruby/ December 07, 2014	5 -Year
212	11.060	124.50	1.480	0	1.48	Typhoon Ruby/ December 07, 2014	5 -Year
213	11.017	124.52	1.059	0	1.06	Typhoon Ruby/ December 07, 2014	5 -Year
214	11.011	124.52	0.030	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
215	11.027	124.50	0.030	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
216	11.042	124.49	0.031	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
217	11.038	124.50	0.097	0	0.10	Typhoon Ruby/ December 07, 2014	5 -Year
218	11.058	124.47	0.031	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
219	11.052	124.49	0.031	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
220	11.042	124.50	0.141	0	0.14	Typhoon Ruby/ December 07, 2014	5 -Year
221	11.072	124.49	0.045	0	0.05	Typhoon Ruby/ December 07, 2014	5 -Year



Point Number	Validation Coordinates		Model Var (m)	Validation Points (m)	Error (m)	Event/Date	Rain Return/Scenario
	Lat	Long					
222	11.063	124.50	0.056	0	0.06	Typhoon Ruby/ December 07, 2014	5 -Year
223	11.037	124.51	0.030	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
224	11.027	124.51	0.031	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
225	11.019	124.52	0.031	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
226	11.017	124.52	0.031	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year
227	11.044	124.50	0.611	0	0.61	Typhoon Ruby/ December 07, 2014	5 -Year
228	11.071	124.49	0.055	0	0.05	Typhoon Ruby/ December 07, 2014	5 -Year
229	11.027	124.51	0.350	0	0.35	Typhoon Ruby/ December 07, 2014	5 -Year
230	11.038	124.51	0.275	0	0.28	Typhoon Ruby/ December 07, 2014	5 -Year
231	11.066	124.51	0.141	0	0.14	Typhoon Ruby/ December 07, 2014	5 -Year
232	11.073	124.49	0.030	0	0.03	Typhoon Ruby/ December 07, 2014	5 -Year

Table A-11.2. Pagsangahan Field Validation Points for the 25-Year Flood Depth Map

Point Number	Validation Coordinates		Model Var (m)	Validation Points (m)	Error (m)	Event/Date	Rain Return/Scenario
	Lat	Long					
331	11.0698005	124.51904	0.0890	1.38	-1.2910	Typhoon Ondoy/ September 26, 2009	25 -Year
335	11.0680972	124.518745	0.033	0.48	-0.4470	Typhoon Ondoy/ September 26, 2009	25 -Year
341	11.0625382	124.520273	0.030999	0.1	-0.0690	Typhoon Ondoy/ September 26, 2009	25 -Year

Table A-11.3. Pagsangahan Field Validation Points for the 100-Year Flood Depth Map

Point Number	Validation Coordinates		Model Var (m)	Validation Points (m)	Error (m)	Event/Date	Rain Return/Scenario
	Lat	Long					
194	11.0731586	124.537136	1.652	0.1	1.552	Typhoon Frank/ June 20, 2008	100-Year
196	11.0739883	124.536171	2.748	1.12	1.628	Typhoon Seniang/ December 30, 2014	100-Year
200	11.0764902	124.532948	1.690	0.48	1.210	Typhoon Seniang/ December 30, 2014	100-Year
201	11.077506	124.531884	1.661	0.48	1.181	Typhoon Frank/ June 20, 2008	100-Year
204	11.0714307	124.539152	1.595	0.48	1.115	Typhoon Frank/ June 20, 2008	100-Year
211	11.0795594	124.564493	0.052	0.48	-0.428	Typhoon Frank/ June 20, 2008	100-Year
212	11.0770543	124.565777	0.034	0	0.034	Typhoon Frank/ June 20, 2008	100-Year
215	11.0683038	124.553576	1.041	0.48	0.561	Typhoon Frank/ June 20, 2008	100-Year
216	11.0671126	124.55257	1.168	0.36	0.808	Typhoon Frank/ June 20, 2008	100-Year
229	11.0902126	124.532783	1.549	0.48	1.069	Typhoon Frank/ June 20, 2008	100-Year
230	11.0898163	124.531231	2.200	0.48	1.720	Typhoon Frank/ June 20, 2008	100-Year
231	11.0900129	124.531712	2.308	0.48	1.828	Typhoon Frank/ June 20, 2008	100-Year
234	11.0530604	124.554523	1.396	0.48	0.916	Typhoon Frank/ June 20, 2008	100-Year
235	11.0530596	124.554524	1.396	0.48	0.916	Typhoon Frank/ June 20, 2008	100-Year
260	11.0174344	124.56024	1.378	1.52	-0.142	Typhoon Frank/ June 20, 2008	100-Year
265	11.0402137	124.550544	0.327	1.52	-1.193	Typhoon Frank/ June 20, 2008	100-Year
269	11.0414193	124.546882	1.032	0.95	0.082	Typhoon Frank/ June 20, 2008	100-Year
282	11.0406902	124.537444	1.289	0.95	0.339	Typhoon Seniang/ December 30, 2014	100-Year
283	11.0407649	124.537422	1.903	1.70	0.203	Typhoon Seniang/ December 30, 2014	100-Year
303	11.0658895	124.532	1.727	0.36	1.367	Typhoon Frank/ June 20, 2008	100-Year
304	11.0658915	124.532003	1.727	1.12	0.607	Typhoon Frank/ June 20, 2008	100-Year
305	11.0686817	124.529823	1.960	1.12	0.840	Typhoon Frank/ June 20, 2008	100-Year

Point Number	Validation Coordinates		Model Var (m)	Validation Points (m)	Error (m)	Event/Date	Rain Return/ Scenario
	Lat	Long					
306	11.0721085	124.52791	1.515	0.1	1.415	Typhoon Frank/ June 20, 2008	100 -Year
307	11.0757496	124.526081	2.240	1.12	1.120	Typhoon Frank/ June 20, 2008	100 -Year
309	11.0744592	124.520135	1.856	0.1	1.756	Typhoon Frank/ June 20, 2008	100 -Year
319	11.0894876	124.52225	4.297	1.70	2.597	Typhoon Frank/ June 20, 2008	100 -Year
320	11.0891136	124.522071	4.137	2	2.137	Typhoon Frank/ June 20, 2008	100 -Year
329	11.0714839	124.518913	0.032	0.48	-0.448	Typhoon Seniang/ December 30, 2014	100 -Year
338	11.0672168	124.51952	1.243	0.95	0.293	Typhoon Frank/ June 20, 2008	100 -Year
368	11.0048218	124.539583	1.548	1.12	0.428	Typhoon Seniang/ December 30, 2014	100 -Year
371	11.005468	124.544272	1.329	1.8	-0.471	Typhoon Frank/ June 20, 2008	100 -Year
372	10.9995359	124.5391	1.288	2.74	-1.452	Typhoon Frank/ June 20, 2008	100 -Year

## ANNEX 12. Educational Institutions Affected by Flooding in Pagsangahan Floodplain

Table A-12.1. Educational Institutions Affected by Flooding in the Pagsangahan Floodplain

LEYTE				
ORMOC CITY				
Building Name	Barangay	Rainfall Scenario		
		5-year	25-year	100-year
Catmon Elementary School	Airport			
Catmon Garnet Daycare Center	Airport			
Bayog Daycare Center	Bayog			Medium
Diego Silang Daycare Center	Esperanza	Medium	Medium	Medium
Esperanza Elementary School	Esperanza			
Green Valley Elementary School	Esperanza			
RM Tan Elementary School	Green Valley	High	High	High
Labrador Elementary School	Labrador			Low
Lao Elementary School	Lao	Low	Medium	Medium
Curva Elementary School	Licuma			
San Vicente Elementary School	Licuma			
Jica-Lao Elementary School	Liloan		Medium	Medium
Lao Elementary School	Liloan	Low	Medium	Medium
Liloan Daycare Center	Liloan	Low	Medium	Medium
Liloan Elementary School	Liloan	Low	Medium	Medium
Liloan National High School	Liloan	Medium	Medium	High
Licuma Daycare Center	Mabato	Low	Medium	Medium
Licuma Elementary School	Mabato		Low	Medium
Margen Elementary School	Margen			
Margen National High School	Margen	Medium	Medium	Medium
Mas-in Elementary School	Mas-In	Medium	Medium	Medium
Catmon Elementary School	Nasunogan			
Inaad Elementary School	Nueva Sociedad			
Rustico Capahi Sr. Memorial National School	Sabang Bao	Medium	Medium	High
Sabang Bao Elementary School	Sabang Bao	Low	Medium	Medium
Bayog Elementary School	San Jose			Medium
G. Lurenana National High School	San Jose	Low	Low	Medium
San Jose Elementary School	San Jose		Low	Low
San Juan Elementary School	San Juan	Medium	Medium	Medium
Curva Elementary School	San Vicente			

**ANNEX 13. Medical Institutions Affected by Flooding in Pagsangahan Floodplain**

Table A-13.1. Medical Institutions Affected by Flooding in the Pagsangahan Floodplain

<b>LEYTE</b>				
<b>ORMOC CITY</b>				
<b>Building Name</b>	<b>Barangay</b>	<b>Rainfall Scenario</b>		
		<b>5-year</b>	<b>25-year</b>	<b>100-year</b>
Catmon Health Center	Airport			
Bayog Health Center	Bayog			Low
Esperanza Health Center	Esperanza			
RM Tan Health Center	Green Valley	Medium	High	High
Curva District Health Center	Licama			Low
Liloan Health Center	Liloan	Medium	Medium	High
Licama Health Center	Mabato	Medium	Medium	High
Mas-in Health Center	Mas-In	Medium	Medium	Medium