HAZARD MAPPING OF THE PHILIPPINES USING LIDAR (PHIL-LIDAR 1)

LiDAR Surveys and Flood Mapping of Basey River





University of the Philippines Training Center for Applied Geodesy and Photogrammetry Visayas State University



Hazard Mapping of the Philippines Using LiDAR (Phil-LiDAR 1)



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LIST OF ACRONYMS AND ABBREVIATIONS

AAC	Asian Aerospace Corporation			
Ab	abutment			
ALTM	Airborne LiDAR Terrain Mapper			
ARG	automatic rain gauge			
ATQ	Antique			
AWLS	Automated Water Level Sensor			
BA	Bridge Approach			
BM	benchmark			
CAD	Computer-Aided Design			
CN	Curve Number			
CSRS	Chief Science Research Specialist			
DAC	Data Acquisition Component			
DEM	Digital Elevation Model			
DENR	Department of Environment and Natural Resources			
DOST	Department of Science and Technology			
DPPC	Data Pre-Processing Component			
DREAM	Disaster Risk and Exposure Assessment for Mitigation [Program			
DRRM	Disaster Risk Reduction and Management			
DSM	Digital Surface Model			
DTM	Digital Terrain Model			
DVBC	Data Validation and Bathymetry Component			
FMC	Flood Modeling Component			
FOV	Field of View			
GiA	Grants-in-Aid			
GCP	Ground Control Point			
GNSS	Global Navigation Satellite System			
GPS	Global Positioning System			
HEC- HMS	Hydrologic Engineering Center - Hydrologic Modeling System			
HEC- RAS	Hydrologic Engineering Center - River Analysis System			
HC	High Chord			
IDW	Inverse Distance Weighted [interpolation method]			
IMU	Inertial Measurement Unit			
kts	knots			

LAS	LiDAR Data Exchange File format			
LC	Low Chord			
LGU	local government unit			
Lidar	Light Detection and Ranging			
LMS	LiDAR Mapping Suite			
m AGL	meters Above Ground Level			
MMS	Mobile Mapping Suite			
MSL	mean sea level			
NAMRIA	National Mapping and Resource Information Authority			
NSTC	Northern Subtropical Convergence			
PAF	Philippine Air Force			
PAGASA	Philippine Atmospheric Geophysical and Astronomical Services Administration			
PDOP	Positional Dilution of Precision			
РРК	Post-Processed Kinematic [technique]			
PRF	Pulse Repetition Frequency			
PTM	Philippine Transverse Mercator			
QC	Quality Check			
QT	Quick Terrain [Modeler]			
RA	Research Associate			
RIDF	Rainfall-Intensity-Duration- Frequency			
RMSE	Root Mean Square Error			
SAR	Synthetic Aperture Radar			
SCS	Soil Conservation Service			
SRTM	Shuttle Radar Topography Mission			
SRS	Science Research Specialist			
SSG	Special Service Group			
TBC	Thermal Barrier Coatings			
UPC	University of the Philippines Cebu			
UP- TCAGP	University of the Philippines – Training Center for Applied Geodesy and Photogrammetry			
UTM	Universal Transverse Mercator			
WGS	World Geodetic System			

Hazard Mapping of the Philippines Using LiDAR (Phil-LiDAR 1)

CHAPTER 1: OVERVIEW OF THE PROGRAM AND BASEY RIVER

Enrico C. Paringit, Dr. Eng., Engr. Florentino Morales, Jr., and Omar Jayag

1.1 Background of the Phil-LiDAR 1 Program

The University of the Philippines Training Center for Applied Geodesy and Photogrammetry (UP-TCAGP) launched a research program entitled "Nationwide Hazard Mapping using LiDAR" or Phil-LiDAR 1, supported by the Department of Science and Technology (DOST) Grants-in-Aid (GiA) Program. The program was primarily aimed at acquiring a national elevation and resource dataset at sufficient resolution to produce information necessary to support the different phases of disaster management. Particularly, it targeted to operationalize the development of flood hazard models that would produce updated and detailed flood hazard maps for the major river systems in the country.

Also, the program was aimed at producing an up-to-date and detailed national elevation dataset suitable for 1:5,000 scale mapping, with 50 cm and 20 cm horizontal and vertical accuracies, respectively. These accuracies were achieved through the use of the state-of-the-art Light Detection and Ranging (LiDAR) airborne technology procured by the project through DOST.

The implementing partner university for the Phil-LiDAR 1 Program is the Visayas State University (VSU). VSU is in charge of processing LiDAR data and conducting data validation reconnaissance, cross section, bathymetric survey, validation, river flow measurements, flood height and extent data gathering, flood modeling, and flood map generation for the 28 river basins in the Eastern Visayas region. The university is located in Baybay in the province of Leyte.

1.2 Overview of the Basey River Basin

Basey River Basin covers a portion of the Municipality of Basey in the province of Samar. Based on DENR River Basin Control Office (RBCO), it has a drainage area of 250 km2 and an estimated 475 million cubic meter (MCM) annual run-off (River Basin Control Office, 2017).

Basey River is located in the southwestern part of the province of Samar and it is part of the thirty 28 river systems in the province of Samar and Leyte. It is one of the major rivers in the province that is utilized for irrigation and transportation way by the populace that lives in the interior barangays of the municipality. According to the 2015 National Census, there is a total of 9,294 people living near the river, distributed among nine (9) barangays, namely: Guirang, Loog, Burgos, Pelit, San Fernando (Nouvelas Oriental), Nouvelas Occidental, Binongtu-an, Sugponon and Iba (Philippine Statistics Authority, 2016). The Municipality of Basey, Samar is among the areas hit by Typhoon Haiyan (Yolanda) on November 8, 2013 and by Typhoon Hagupit (Ruby) on December 6, 2014 (Amadore, 2013).



Figure 1. Map of the Basey River Basin

CHAPTER 2: LIDAR DATA ACQUISITION OF THE BASEY FLOODPLAIN

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The methods applied in this chapter were based on the DREAM methods manual (Sarmiento et al., 2014) and further enhanced and updated in Paringit et al. (2017).

2.1 Flight Plans

Plans were made to acquire LiDAR data within the delineated priority area for Basey floodplain in Samar. These missions were planned for 16 lines that run for at most four and a half (4.5) hours including take-off, landing and turning time. The flight planning parameters for the Aquarius LiDAR system is found in Table 1, while the flight planning parameters for the Gemini LiDAR system is found in Table 2. Figure 2 shows the flight plan for Basey floodplain using Aquarius LiDAR system, and Figure 3 shows the flight plan for Basey floodplain using System.

Block Name	Flying Height (m AGL)	Overlap (%)	Field of View (θ)	Pulse Repetition Frequency (PRF) (kHz)	Scan Frequency	Average Speed (kts)	Average Turn Time (Minutes)
BLK33B	600	30	36	70	50	120	5
BLK33C	600	30	36	70	50	120	5
BLK33E	600	30	36	70	50	120	5
BLK33F	600	30	36	70	50	120	5
BLK33G	600	30	36	70	50	120	5
BLK33H	600	30	36	70	50	120	5
BLK34AX	600	30	36	70	50	120	5

Table 1. Flight planning parameters for Aquarius LiDAR system.

Block Name	Flying Height (m AGL)	Overlap (%)	Field of View (θ)	Pulse Repetition Frequency (PRF) (kHz)	Scan Frequency	Average Speed (kts)	Average Turn Time (Minutes)
BLK34K	900/1200	30	40	125	50	130	5
BLK34L	900/1100	30	40	125	50	130	5

Table 2. Flight planning parameters for Gemini LiDAR system



Figure 2. Flight plan and base stations used for Basey Floodplain using Aquarius LiDAR system.



Figure 3. Flight plan and base stations used to cover Basey Floodplain using Gemini LiDAR system.

2.2 Ground Base Station

The project team was able to recover four (4) NAMRIA ground control points: LYT-101, LYT-104, SMR-56 and SMR-58 which are of second (2nd) order accuracy. Three (3) NAMRIA benchmarks were also recovered: LY-110, SM-286 and SM-309 which are of first (1st) order accuracy. These benchmarks were used as vertical reference points and were also established as ground control points. The certifications for the NAMRIA reference points and benchmarks are found in Annex 2 while the baseline processing reports for the established control points is found in Annex 3. These were used as base stations during flight operations for the entire duration of the survey (May 5-4, 10-11 and 13, 2014, February 7 and 13, 2015, and January 23, 31 and February 6, 2016). Base stations were observed using dual frequency GPS receivers, TRIMBLE SPS 852, SPS 882 and SPS 985. Flight plans and location of base stations used during the aerial LiDAR acquisition in Basey floodplain are shown in Figure 2 and Figure 3.

Figure 4 to Figure 10 show the recovered NAMRIA control station within the area, in addition Table 3 to Table 10 show the details about the following NAMRIA control stations and established points, Table 11 shows the list of all ground control points occupied during the acquisition together with the dates they are utilized during the survey.



Figure 4. GPS set-up over LYT-101 within the premises of MacArthur's Landing Memorial Park, Palo, Leyte (a) and NAMRIA reference point LYT-101 (b) as recovered by the field team.

Table 3. Details of the recovered NAMRIA horizontal control point LYT-101 used as base station for the LiDAR acquisition.

Station Name	LYT-	-101			
Order of Accuracy	2nd				
Relative Error (horizontal positioning)	1 in 50,000				
Geographic Coordinates, Philippine Reference of 1992 Datum (PRS 92)	Latitude Longitude Ellipsoidal Height	11° 10' 23.89707'' 125° 0' 38.62071'' 6.58600 m			
Grid Coordinates, Philippine Transverse Mercator Zone 5 (PTM Zone 5 PRS 92)	Easting Northing	501,171.719 meters 1,235,497.253 meters			
Geographic Coordinates, World Geodetic System 1984 Datum (WGS 84)	Latitude Longitude Ellipsoidal Height	11° 10' 19.64869'' North 125° 0' 43.78230'' East 69.02100 meters			
Grid Coordinates, Universal Transverse Mercator Zone 51 North (UTM 51N PRS 1992)	Easting Northing	719,575.03 meters 1,235,811.61 meters			



Figure 5. GPS set-up over LYT-104 located and re-established along rice paddy trail, approximately 90 meters from the centerline, east side of Pastrana-Santa Fe Road, District IV, Pastrana, Leyte (a) and NAMRIA reference point LYT-104 (b) as recovered by the field team

Table 4. Details of the recovered and re-established NAMRIA horizontal control point LYT-104 used as base station for the LiDAR
acquisition.

Station Name	LYT-104			
Order of Accuracy	2nd			
Relative Error (horizontal positioning)	1 in 50,000			
Geographic Coordinates, Philippine Reference of 1992 Datum (PRS 92)	Latitude Longitude Ellipsoidal Height	11°08′38.92234″ North 124o 53′ 13.52786″ East 33.659 meters		
Geographic Coordinates, World Geodetic System 1984 Datum (WGS 84)	Latitude Longitude Ellipsoidal Height	11°08'34.67033" North 124o 53' 18.69323" East 95.861 meters		
Grid Coordinates, Universal Transverse Mercator Zone 51 North (UTM 51N PRS 1992)	Easting Northing	706089.510m 1232496.838		



Figure 6. GPS set-up over SMR-56 at Cabacungan Elementary School in Barangay Cabacungan, Sta. Rita, Samar (a) and NAMRIA reference point SMR-56 (b) as recovered by the field team.

Table 5. Details of the recovered NAMRIA horizontal control point	nt SMR-56 used as base station for the LiDAR acqu	uisition.
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Station Name	LYT-101			
Order of Accuracy	2nd			
Relative Error (horizontal positioning)	1 in 50,000			
Geographic Coordinates, Philippine Reference of 1992 Datum (PRS 92)	Latitude Longitude Ellipsoidal Height	11° 23' 6.52702'' 125° 0' 23.99607'' 11.82200 m		
Grid Coordinates, Philippine Transverse Mercator Zone 5 (PTM Zone 5 PRS 92)	Easting Northing	500,727.475 meters 1,258,927.861 meters		
Geographic Coordinates, World Geodetic System 1984 Datum (WGS 84)	Latitude Longitude Ellipsoidal Height	11° 23' 2.22413'' North 125° 0' 29.13917'' East 73.72700 meters		
Grid Coordinates, Universal Transverse Mercator Zone 51 North (UTM 51N PRS 1992)	Easting Northing	718,970.61 meters 1,259,244.38 meters		



Figure 7. GPS set-up over SMR-58 located inside Serum Elementary School, Brgy. Serum, Basey (a) and NAMRIA reference point SMR-58 (b) as recovered by the field team.

Station Name	LYT-101			
Order of Accuracy	2nd			
Relative Error (horizontal positioning)	1 in 50,000			
Geographic Coordinates, Philippine Reference of 1992 Datum (PRS 92)	Latitude Longitude Ellipsoidal Height	11o 17' 55.05617" North 125o 7' 51.16145" East 6.30062 meters		
Grid Coordinates, Philippine Transverse Mercator Zone 5 (PTM Zone 5 PRS 92)	Easting Northing	514288.239 meters 1249361.531 meters		
Geographic Coordinates, World Geodetic System 1984 Datum (WGS 84)	Latitude Longitude Ellipsoidal Height	11o 17' 50.78580" North 125o 7' 56.31100" East 68.72300 meters		
Grid Coordinates, Universal Transverse Mercator Zone 51 North (UTM 51N PRS 1992)	Easting Northing	732600.57 meters 1249768.75 meters		

Table 6. Details of the recovered NAMRIA horizontal control point SMR-58 used as base station for the LiDAR acquisition.



Figure 8. GPS set-up over LY-110 located along Palo-Pastrana Road, Pastrana, Leyte (a) and NAMRIA reference point LY-110 (b) as recovered by the field team.

coor minutes.					
Station Name	LY-110				
Order of Accuracy	2nd				
Relative Error (horizontal positioning)	1 in 50,000				
Geographic Coordinates, Philippine Reference of 1992 Datum (PRS 92)	Latitude Longitude Ellipsoidal Height	11o 10' 19.48389" North 124o 57' 32.98736" East 14.336 meters			
Geographic Coordinates, World Geodetic System 1984 Datum (WGS 84)	Latitude Longitude Ellipsoidal Height	11o 10' 15.23095" North 124o 57' 38.14961" East 76.647 meters			
Grid Coordinates, Universal Transverse Mercator Zone 51 North (UTM 51N PRS 1992)	Easting Northing	713,942.863 meters 1,235,638.117 meters			

Table 7. Details of the recovered NAMRIA vertical control point LY-110 used as base station for the LiDAR acquisition with established coordinates.

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Figure 9. GPS set-up over SM-286 located at Dalid bridge along national highway in Brgy. San Pascual, Sta. Rita, Samar (a) and NAMRIA reference point SM-286 (a) as recovered by the field team.

Table 8. Details of the recovered NAMRIA vertical control point SM-286 used as base station for the LiDAR acquisition with
established coordinates.

Station Name	SM-286			
Order of Accuracy	2nd			
Relative Error (horizontal positioning)	1 in 50,000			
Geographic Coordinates, Philippine Reference of 1992 Datum (PRS 92)	Latitude Longitude Ellipsoidal Height	11o 24' 35.73" North 124o 59' 44.05" East 5.47 meters		
Grid Coordinates, Philippine Transverse Mercator Zone 5 (PTM Zone 5 PRS 92)	Easting Northing	499516.558 meters 1261668.44 meters		
Geographic Coordinates, World Geodetic System 1984 Datum (WGS 84)	Latitude Longitude Ellipsoidal Height	11o 24' 30.81671" North 124o 59' 48.35250" East 67.268 meters		
Grid Coordinates, Universal Transverse Mercator Zone 51 North (UTM 51N PRS 1992)	Easting Northing	717869.251 meters 1261905.903 meters		



Figure 10. GPS set-up over SM-309 located at Dalid bridge along national highway in Brgy. San Pascual, Sta. Rita, Samar (a) and NAMRIA reference point SM-309 (a) as recovered by the field team.

Table 9. Details of the recovered NAMRIA vertical control point SM-309 used as base station for the LiDAR acquisition with established coordinates.

Station Name	SM-309			
Order of Accuracy	2nd			
Relative Error (horizontal positioning)	1 in 50,000			
Geographic Coordinates, Philippine Reference of 1992 Datum (PRS 92)	Latitude Longitude Ellipsoidal Height	11o 17' 59.30748" North 125o 06' 56.29744" East 9.743 meters		
Geographic Coordinates, World Geodetic System 1984 Datum (WGS 84)	Latitude Longitude Ellipsoidal Height	11o 17' 55.03553" North 125o 07' 01.44700" East 72.125 meters		

Table 10. Details of the established vertical control point PCG-TC used as base station for the LiDAR acquisition with established coordinates.

Station Name	PCG-TC		
Order of Accuracy	2nd		
Relative Error (horizontal positioning)	1 in 50,000		
Geographic Coordinates, World Geodetic System 1984 Datum (WGS 84)	Latitude Longitude Ellipsoidal Height	11o 14' 48.29466" North 124o 59' 53.38556" East 70.882 meters	
Grid Coordinates, Universal Transverse Mercator Zone 51 North (UTM 51N PRS 1992)	Easting Northing	718,144.536 meters 1,244,004.859 meters	

Date Surveyed	Flight Number	Mission Name	Ground Control Points
January 25, 2014	1022A	3BLK33BSC025B	LYT-101 and PCG-TC
May 3, 2014	1410A	AQUATACTF123A	SMR-58 and SM-286
May 4, 2014	1414A	AQUATACTF124A	LYT-101 and SMR-56
May 10, 2014	1438A	3BLK34O130A	SMR-56 and SM-286
May 10, 2014	1440A	3BLK34OSP130B	SMR-56 and SM-286
May 11, 2014	1442A	3BLK33GS131A	SMR-56 and SM-286
May 11, 2014	1444A	3BLK33GSH131B	SMR-56 and SM-286
May 13, 2014	1450A	3BLK33HS133A	SMR-56 and SM-286
May 13, 2014	014 1452A 3BLK33HSES133E		SMR-56 and SM-286
February 7, 2015	7786AC	3BLK34A038A	SMR-56 and SM-286
February 13, 2015	7798AC	3BLK34AV44A	SMR-56 and SM-286
January 23, 2016	3769G/3703G	2BLK34ADEG023A	LYT-104 and LY-110
January 31, 2016	3733G	2BLK33ABLK34L031A	SMR-58 and SM-309
February 5, 2016	3753G	2BLK34K33AB036A	SMR-58 and SM-309
February 6, 2016	3757G	2BLK34K037A SMR-58 and SM	

Table 11. Ground control points used during LiDAR data acquisition.

2.3 Flight Missions

Fifteen (15) missions were conducted to complete the LiDAR Data Acquisition in Basey Floodplain, for a total of fifty-six hours and fifty-three minutes (56+53) of flying time for RP-C9122 and RP-C9022. The missions were acquired using the Aquarius and Gemini LiDAR systems. Table 12 shows the total area of actual coverage and the corresponding flying hours per mission, while Table 13 shows the actual parameters used during the LiDAR data acquisition.

Date Flight		Flight Plan Area	Flight Surveyed Plan Area Area		Area Surveyed outside	No. of Images	Flying Hour	
Surveyed	Number	(km2)	(km2)	Floodplain (km2)	the Floodplain (km2)	(Frames)	Hr	Min
January 25, 2014	1022A	221.76	181.39	59.30	122.09	1302	4	11
May 3, 2014	1410A	196.15	128.42	17.14	111.28	772	4	47
May 4, 2014	1414A	196.15	68.14	5.91	62.23	649	3	11
May 10, 2014	1438A	169.29	157.72	32.18	125.54	1855	4	41
May 10, 2014	1440A	335.45	316.16	59.92	256.24	989	3	11
May 11, 2014	1442A	166.16	150.41	47.33	103.08	1536	4	47
May 11, 2014	1444A	400.01	123.22	14.46	108.76	1290	4	35
May 13, 2014	1450A	233.85	53.06	0.62	52.44	507	2	23
May 13, 2014	1452A	430.00	76.69	NA	76.69	819	3	53
February 7, 2015	7786AC	90.76	92.34	1.65	90.69	NA	4	23
February 13, 2015	7798AC	90.76	60.82	0.57	60.25	NA	3	11
January 23, 2016	3703G/ 3769G	101.63	167.12	NA	167.12	NA	3	29
January 31, 2016	3733G	54.18	248.73	166.37	82.36	NA	2	59
February 5, 2016	3753G	96.91	93.62	10.36	83.26	NA	4	17
February 6, 2016	3757G	96.91	77.95	12.83	65.12	NA	2	55
тот	AL	2879.97	1995.75	428.64	1567.15	9719	56	53

Table 12. Flight missions for LiDAR data acquisition in Basey Floodplain.

Flight Number	Flying Height (m AGL)	Overlap (%)	FOV (θ)	PRF (kHz)	Scan Frequency (Hz)	Average Speed (kts)	Average Turn Time (Minutes
1022A	700	40	50	70	40	130	5
1410A	700	40	36	50	50	130	5
1414A	700	40	36	50	50	130	5
1438A	600	40	44	50	45	130	5
1440A	600	40	44	50	45	130	5
1442A	700	40	36	50	50	130	5
1444A	700	40	36	50	50	130	5
1450A	700	40	36	50	50	130	5
1452A	700	40	36	50	50	130	5
7786AC	600	40	36	50	45	130	5
7798AC	700	40	36	50	45	130	5
3703G/ 3769G	1200	30	34	100	50	130	5
3733G	900	30	40	100	50	130	5
3753G	900	30	40	100	50	130	5
3757G	1100	30	36	100	50	130	5

Table 13. Actual parameters used during LiDAR data acquisition.

2.4 Survey Coverage

Basey floodplain is located in the province of Samar with majority of the floodplain situated within the municipality of Basey. The list of city and municipalities surveyed, with at least one (1) square kilometer coverage, is shown in Table 14. The actual coverage of the LiDAR acquisition for Basey floodplain is presented in Figure 11.

Province	Municipality/City	Area of Municipality/City (km2)	Total Area Surveyed (km2)	Percentage of Area Surveyed
Eastern Samar	Balangiga	206.52	66.09	32.00%
	Lawaan	141.75	11.32	7.99%
Leyte	Abuyog	256.64	17.33	6.75%
	Alangalang	145.45	1.71	1.18%
	Babatngon	136.57	95.34	69.81%
	Burauen	205.31	59.9	29.18%
	Dagami	134.08	31.43	23.44%
	Dulag	63.65	4.85	7.62%
	Julita	57.17	11.71	20.48%
	Palo	65.34	9.94	15.21%
	Pastrana	79.17	15.51	19.59%
	San Miguel	103.86	12.27	11.81%
	Santa Fe	57.15	12.42	21.73%
	Tabontabon	20.46	7.1	34.70%
	Tacloban City	118.46	39.28	33.16%
Samar	Basey	627.97	291.2	46.37%
	Daram	109.26	3.16	2.89%
	Marabut	148.82	8.77	5.89%
	Pinabacdao	118.38	20.04	16.93%
	Santa Rita	250.37	230.79	92.18%
	Talalora	26.56	25.73	96.88%
	Villareal	130.22	126.08	96.82%
Total		3203.16	1101.97	34.40%

Table 14. List of municipalities and cities surveyed during Basey floodplain LiDAR survey



Figure 11. Actual LiDAR survey coverage for Basey Floodplain.

CHAPTER 3: LIDAR DATA PROCESSING OF THE BASEY FLOODPLAIN

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The methods applied in this Chapter were based on the DREAM methods manual (Ang, et al., 2014) and further enhanced and updated in Paringit, et al. (2017).

3.1 Overview of the LiDAR Data Pre-Processing

The data transmitted by the Data Acquisition Component are checked for completeness based on the list of raw files required to proceed with the pre-processing of the LiDAR data. Upon acceptance of the LiDAR field data, georeferencing of the flight trajectory is done in order to obtain the exact location of the LiDAR sensor when the laser was shot. Point cloud georectification is performed to incorporate correct position and orientation for each point acquired. The georectified LiDAR point clouds are subject for quality checking to ensure that the required accuracies of the program, which are the minimum point density, vertical and horizontal accuracies, are met. The point clouds are then classified into various classes before generating Digital Elevation Models such as Digital Terrain Model and Digital Surface Model.

Using the elevation of points gathered in the field, the LiDAR-derived digital models are calibrated. Portions of the river that are barely penetrated by the LiDAR system are replaced by the actual river geometry measured from the field by the Data Validation and Bathymetry Component. LiDAR acquired temporally are then mosaicked to completely cover the target river systems in the Philippines. Orthorectification of images acquired simultaneously with the LiDAR data is done through the help of the georectified point clouds and the metadata containing the time the image was captured.

These processes are summarized in the flowchart shown in Figure 12.



Figure 12. Schematic Diagram for Data Pre-Processing Component

3.2 Transmittal of Acquired LiDAR Data

Data transfer sheets for all the LiDAR missions for Basey floodplain can be found in Annex 5. Data Transfer Sheets. Missions flown during the first survey conducted on January 2014 used the Airborne LiDAR Terrain Mapper (ALTM[™] Optech Inc.) Aquarius system while missions acquired during the second survey on January 2016 were flown using the Gemini system over Basey, Samar. The Data Acquisition Component (DAC) transferred a total of 223.36 Gigabytes of Range data, 3.54 Gigabytes of POS data, 189.05 Megabytes of GPS base station data, and 625.5 Gigabytes of raw image data to the data server on May 28, 2014 for the first survey and February 26, 2016 for the second survey. The Data Pre-processing Component (DPPC) verified the completeness of the transferred data. The whole dataset for Basey was fully transferred on

3.3 Trajectory Computation

The Smoothed Performance Metrics of the computed trajectory for flight 1442A, one of the Basey flights, which is the North, East, and Down position RMSE values are shown in Figure 13. The x-axis corresponds to the time of flight, which is measured by the number of seconds from the midnight of the start of the GPS week, which on that week fell on May 11, 2014 00:00AM. The y-axis is the RMSE value for that particular position.



Figure 13. Smoothed Performance Metrics of a Basey Flight 1442A.

The time of flight was from 604,000 seconds to 618,000 seconds, which corresponds to afternoon of May 11, 2014. The initial spike that is seen on the data corresponds to the time that the aircraft was getting into position to start the acquisition, and the POS system starts computing for the position and orientation of the aircraft. Redundant measurements from the POS system quickly minimized the RMSE value of the positions. The periodic increase in RMSE values from an otherwise smoothly curving RMSE values correspond to the turn-around period of the aircraft, when the aircraft makes a turn to start a new flight line. Figure 13 shows that the North position RMSE peaks at 2.20 centimeters, the East position RMSE peaks at 1.60 centimeters, and the Down position RMSE peaks at 4.30 centimeters, which are within the prescribed accuracies described in the methodology.



Figure 14. Solution Status Parameters of Basey Flight 1442A.

The Solution Status parameters of flight 1442A, one of the Basey flights, which are the number of GPS satellites, Positional Dilution of Precision (PDOP), and the GPS processing mode used, are shown in Figure 14. The graphs indicate that the number of satellites during the acquisition did not go down to 5. Majority of the time, the number of satellites tracked was between 5 and 9. The PDOP value also did not go above the value of 3, which indicates optimal GPS geometry. The processing mode stayed at the value of 0 for majority of the survey with some peaks up to 1 and 2 attributed to the turns performed by the aircraft. The value of 0 corresponds to a Fixed, Narrow-Lane mode, which is the optimum carrier-cycle integer ambiguity resolution technique available for POSPAC MMS. All of the parameters adhered to the accuracy requirements for optimal trajectory solutions, as indicated in the methodology. The computed best estimated trajectory for all Basey flights is shown in Figure 15.



Figure 15. Best Estimated Trajectory for Basey Floodplain

3.4 LiDAR Point Cloud Computation

The produced LAS data contains 217 flight lines, with each flight line containing one channel, since the Gemini and Aquarius systems both contain one channel only. The summary of the self-calibration results obtained from LiDAR processing in LiDAR Mapping Suite (LMS) software for all flights over Basey floodplain are given in Table 15

Table 15. Self-Calibration Results values for Basey flights.

Parameter	Acceptable Value	Computed Value
Boresight Correction stdev	(<0.001degrees)	0.000310
IMU Attitude Correction Roll and Pitch Corrections stdev	(<0.001degrees)	0.000915
GPS Position Z-correction stdev	(<0.01meters)	0.0027

The optimum accuracy is obtained for all Basey flights based on the computed standard deviations of the corrections of the orientation parameters. Standard deviation values for individual blocks are available in the Annex 8. Mission Summary Reports.
3.5 LiDAR Data Quality Checking

The boundary of the processed LiDAR data on top of a SAR Elevation Data over Basey Floodplain is shown in Figure 16. The map shows gaps in the LiDAR coverage that are attributed to cloud coverage.



Figure 16. Boundary of the processed LiDAR data over Basey Floodplain

The total area covered by the Basey missions is 1388.42 sq.km that is comprised of sixteen (16) flight acquisitions grouped and merged into twelve (12) blocks as shown in Table 16.

Table 13. Shift values of each LiDAR Block of	of Basey	Floodplain
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LiDAR Blocks	Flight Numbers	Area (sq. km.)	
	1444A		
Samar_Leyte_Blk33H	1450A	183.22	
	1452A		
	1440A		
Samar_Leyte_Blk33G	1442A	222.63	
	1438A		
Samar_Leyte_Blk33F	1440A	225.06	
Samar_Leyte_Blk33E_additional	1410A	98.82	
	1414A		
Samar_Leyte_Blk33E	1452A	93.33	
	3753G		
Leyte_Bik33F	3757G	103.33	
	3731G		
Leyte_Blk33E	3733G	84.72	
Leyte_Blk33E_additional	3769G	8.32	
Leyte_Blk33G	3731G	126.91	
Ormoc_Blk34AX_additional	7798AC	5.78	
	7786AC	02.55	
Urmoc_BIK34AX	7798AC	93.56	
Tacloban_1022A	1022A	142.74	
то	1388.42		

The overlap data for the merged LiDAR blocks, showing the number of channels that pass through a particular location is shown in Figure 17. Since the Gemini and Aquarius systems both employ one channel, we would expect an average value of 1 (blue) for areas where there is limited overlap, and a value of 2 (yellow) or more (red) for areas with three or more overlapping flight lines.



Figure 17. Image of data overlap for Basey Floodplain.

The overlap statistics per block for the Basey floodplain can be found in Annex 8. Mission Summary Reports. It should be noted that one pixel corresponds to 25.0 square meters on the ground. For this area, the minimum and maximum percent overlaps are 25.09% and 46.76% respectively, which passed the 25% requirement.

The pulse density map for the merged LiDAR data, with the red parts showing the portions of the data that satisfy the 2 points per square meter criterion is shown in Figure 18. It was determined that all LiDAR data for Basey floodplain satisfy the point density requirement, and the average density for the entire survey area is 3.08 points per square meter.



Figure 18. Pulse density map of merged LiDAR data for Basey Floodplain.

The elevation difference between overlaps of adjacent flight lines is shown in Figure 19. The default color range is from blue to red, where bright blue areas correspond to portions where elevations of a previous flight line, identified by its acquisition time, are higher by more than 0.20m relative to elevations of its adjacent flight line. Bright red areas indicate portions where elevations of a previous flight line are lower by more than 0.20m relative to elevations of its adjacent flight line. Areas with bright red or bright blue need to be investigated further using Quick Terrain Modeler software.



Figure 19. Elevation difference map between flight lines for Basey Floodplain.

A screen capture of the processed LAS data from a Basey flight 1442A loaded in QT Modeler is shown in Figure 20. The upper left image shows the elevations of the points from two overlapping flight strips traversed by the profile, illustrated by a dashed yellow line. The x-axis corresponds to the length of the profile. It is evident that there are differences in elevation, but the differences do not exceed the 20-centimeter mark. This profiling was repeated until the quality of the LiDAR data becomes satisfactory. No reprocessing was done for this LiDAR dataset.



Figure 20. Quality checking for a Basey flight 1442A using the Profile Tool of QT Modeler.

3.6 LiDAR Point Cloud Classification and Rasterization

Pertinent Class	Total Number of Points
Ground	706,274,194
Low Vegetation	490,619,269
Medium Vegetation	1,679,694,257
High Vegetation	1,334,876,725
Building	22,528,349

Table 17. Basey classification results in TerraScan.

The tile system that TerraScan employed for the LiDAR data and the final classification image for a block in Basey floodplain is shown in Figure 21. A total of 2,120 1km by 1km tiles were produced. The number of points classified to the pertinent categories is illustrated in Table 17. The point cloud has a maximum and minimum height of 878.23 meters and 25.54 meters.



Figure 21. Tiles for Basey Floodplain (a) and classification results (b) in TerraScan.

An isometric view of an area before and after running the classification routines is shown in Figure 22. The ground points are in orange, the vegetation is in different shades of green, and the buildings are in cyan. It can be seen that residential structures adjacent or even below canopy are classified correctly, due to the density of the LiDAR data.

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Figure 22. Point cloud before (a) and after (b) classification.

The production of last return (V_ASCII) and the secondary (T_ASCII) DTM, first (S_ASCII) and last (D_ASCII) return DSM of the area in top view display are shown in Figure 23. It shows that DTMs are the representation of the bare earth while on the DSMs, all features are present such as buildings and vegetation.



Figure 23. The production of last return DSM (a) and DTM (b), first return DSM (c) and secondary DTM (d) in some portion of Basey Floodplain.

3.7 LiDAR Image Processing and Orthophotograph Rectification

The 2,096 1km by 1km tiles area covered by Basey floodplain is shown in Figure 24. After tie point selection to fix photo misalignments, color points were added to smoothen out visual inconsistencies along the seamlines where photos overlap. The Basey floodplain has a total of 774.01 sq.km orthophotogaph coverage comprised of 9,549 images. A zoomed in version of sample orthophotographs named in reference to its tile number is shown in Figure 25.



Figure 24. Basey floodplain with available orthophotographs.



Figure 25. Sample orthophotograph tiles for Basey floodplain.

3.8 DEM Editing and Hydro-Correction

Twelve (12) mission blocks were processed for Basey flood plain. These blocks are composed of the Tacloban DEM, SamarLeyte and Leyte blocks with a total area of 1388.42 square kilometers. Table 18 shows the name and corresponding area of each block in square kilometers.

LiDAR Blocks	Area (sq.km)
Samar_Leyte_Blk33H	183.22
Samar_Leyte_Blk33G	222.63
Samar_Leyte_Blk33F	225.06
Samar_Leyte_Blk33E_additional	98.82
Samar_Leyte_Blk33E	93.33
Leyte_Blk33F	103.33
Leyte_Blk33E	84.72
Leyte_Blk33E_additional	8.32
Leyte_Blk33G	126.91
Ormoc_Blk34AX_additional	5.78
Ormoc_Blk34AX	93.56
Tacloban_1022A	142.74
TOTAL	1388.42

Table 18. LiDAR blocks with its corresponding area.

Portions of DTM before and after manual editing are shown in Figure 26. The bridge and other misclassified objects on the river (Figure 26a) are considered to be impedances to the flow of water and has to be removed (Figure 26b) in order to hydrologically correct the river. Areas with no data on the river (Figure 26c) and other locations in the flood plain (Figure 26d) has to be removed through manual editing.



Figure 26. Portions in the DTM of Basey floodplain – a bridge and other obstructions on the river before (a) and after (b) manual editing; a flat area near the river before (c) and after (d) manual editing.

3.9 Mosaicking of Blocks

No assumed reference block was used in mosaicking because the identified reference for shifting was an existing calibrated Tacloban DEM overlapping with the blocks to be mosaicked. Table 19 shows the shift values applied to each LiDAR block during mosaicking.

Mosaicked LiDAR DTM for Basey floodplain is shown in Figure 27. It can be seen that the entire Basey floodplain is 100% covered by LiDAR data.

	Shift Values (meters)			
IVIISSION BIOCKS	х	У	Z	
Tacloban_1022A	0.00	0.00	0.00	
Ormoc_Blk34AX	0.00	0.00	-0.33	
Ormoc_Blk34AX_additional	0.00	0.00	-0.33	
SamarLeyte_Blk33F	0.00	0.00	-0.62	
SamarLeyte_Blk33G	0.00	0.00	-0.62	
SamarLeyte_Blk33H	1.00	0.00	-0.62	
SamarLeyte_Blk33E_additional	0.00	0.00	-0.36	
SamarLeyte_Blk33E	0.00	0.00	-0.54	
Leyte_Blk33E_additional	1.00	0.00	-4.64	
Leyte_Blk33G	0.00	0.00	-1.12	
Leyte_Blk33E	5.00	0.00	-4.49	
Leyte_Blk33F	-1.00	1.00	-4.56	

Table 19. Shift	Values of ea	ch LiDAR	Block of	Basev f	loodblain.
· /				~ / /	



Figure 27. Map of Processed LiDAR Data for Basey Floodplain.

3.10 Calibration and Validation of Mosaicked LiDAR Digital Elevation Model

The extent of the validation survey done by the Data Validation and Bathymetry Component (DVBC) in Basey to collect points with which the LiDAR dataset is validated is shown in Figure 28. A total of 28,096 survey points were gathered for all the floodplains within Eastern and Western Samar wherein the Basey is located. However, the point dataset was not used for the calibration of the LiDAR data for Basey because during the mosaicking process, each LiDAR block was referred to the calibrated Tacloban DEM. Therefore, the mosaicked DEM of Basey can already be considered as a calibrated DEM.

A good correlation between the uncalibrated Tacloban LiDAR DTM and ground survey elevation values is shown in Figure 29. Statistical values were computed from extracted LiDAR values using the selected points to assess the quality of data and obtain the value for vertical adjustment. The computed height difference between the LiDAR DTM and calibration points is 0.14 meters with a standard deviation of 0.13 meters. Calibration of Tacloban LiDAR data was done by subtracting the height difference value, 0.14 meters, to Tacloban mosaicked LiDAR data. Table 20 shows the statistical values of the compared elevation values between Tacloban LiDAR data and calibration data. These values were also applicable to the Basey DEM.



Figure 28. Map of Basey Floodplain with validation survey points in green.



Figure 29. Correlation plot between calibration survey points and LiDAR data

Calibration Statistical Measures	Value (meters)
Height Difference	1.28
Standard Deviation	0.19
Average	1.27
Minimum	0.89
Maximum	1.64

Table 20. Calibration Statistical Measure

A total of 4,323 survey points lie within the Basey flood plain and were used for the validation of the calibrated Basey DTM. A good correlation between the calibrated mosaicked LiDAR elevation values and the ground survey elevation, which reflects the quality of the LiDAR DTM is shown in Figure 30. The computed RMSE between the calibrated LiDAR DTM and validation elevation values is 0.17 meters with a standard deviation of 0.16 meters, as shown in Table 21.



Figure 30. Correlation plot between validation survey points and LiDAR data.

Validation Statistical Measures	Value (meters)
RMSE	0.17
Standard Deviation	0.16
Average	-0.07
Minimum	-0.63
Maximum	0.76

3.11 Integration of Bathymetric Data into the LiDAR Digital Terrain Model

For bathy integration, only centerline data was available for Basey with 866 bathymetric survey points. The resulting raster surface produced was done by Inverse Distance Weighted (IDW) interpolation method. After burning the bathymetric data to the calibrated DTM, assessment of the interpolated surface is represented by the computed RMSE value of 0.0067 meters. The extent of the bathymetric survey done by the Data Validation and Bathymetry Component (DVBC) in Basey integrated with the processed LiDAR DEM is shown in Figure 31.



Figure 31. Map of Basey Flood Plain with bathymetric survey points shown in blue.

3.12 Feature Extraction

The features salient in flood hazard exposure analysis include buildings, road networks, bridges and water bodies within the floodplain area with 200 m buffer zone. Mosaicked LiDAR DEM with 1 m resolution was used to delineate footprints of building features, which consist of residential buildings, government offices, medical facilities, religious institutions, and commercial establishments, among others. Road networks comprise of main thoroughfares such as highways and municipal and barangay roads essential for routing of disaster response efforts. These features are represented by a network of road centerlines.

3.12.1 Quality Checking (QC) of Digitized Features' Boundary

Basey floodplain, including its 200 m buffer, has a total area of 226.04 sq km. For this area, a total of 7.0 sq km, corresponding to a total of 1892 building features, are considered for QC. Figure 32 shows the QC blocks for Basey floodplain.



Figure 32. QC blocks for Basey building features.

Quality checking of Basey building features resulted in the ratings shown in Table 22.

FLOODPLAIN	COMPLETENESS	CORRECTNESS	QUALITY	REMARKS
Basey	99.50	100	99.19	PASSED

3.12.2 Height Extraction

Height extraction was done for 11630 building features in Basey floodplain. Of these building features, 884 was filtered out after height extraction, resulting to 10746 buildings with height attributes. The lowest building height is at 2.00 m, while the highest building is at 9.87m.

3.12.3 Feature Attribution

The digitized features were marked and coded in the field using handheld GPS receivers. The attributes of non-residential buildings were first identified; all other buildings were then coded as residential. An nDSM was generated using the LiDAR DEMs to extract the heights of the buildings. A minimum height of 2 meters was used to filter out the terrain features that were digitized as buildings. Buildings that were not yet constructed during the time of LiDAR acquisition were noted as new buildings in the attribute table.3.12.1 Quality Checking of Digitized Features' Boundary

Table 23 summarizes the number of building features per type. On the other hand, Table 24 shows the total length of each road type, while Table 25 shows the number of water features extracted per type.

Facility Type	No. of Features
Residential	10348
School	220
Market	1
Agricultural/Agro-Industrial Facilities	12
Medical Institutions	9
Barangay Hall	24
Military Institution	2
Sports Center/Gymnasium/Covered Court	13
Telecommunication Facilities	1
Transport Terminal	0
Warehouse	7
Power Plant/Substation	0
NGO/CSO Offices	5
Police Station	1
Water Supply/Sewerage	0
Religious Institutions	29
Bank	1
Factory	0
Gas Station	1
Fire Station	1
Other Government Offices	20
Other Commercial Establishments	51
Total	10746

Table 23. Building Features Extracted for Basey Floodplain.

Table 24 Tatal I such of Estimate 1 Day 1.	f D	
Table 24. Total Length of Extracted Roads	ior duse	ν Γιοσαριατή.
		/

Floodplain	Barangay Road Road Road		Provincial National Road Road		Others	Total	
Basey	79.58	16.56	20.62	25.93	0.00	142.69	

Table 25. Number of Extracted Water Bodies for Basey Floodplain.

Water Body Type							
Floodplain	Rivers/ Streams	Lakes/Ponds	Sea	Dam	Fish Pen	Total	
Basey	18	0	0	0	0	18	

A total of 27 bridges and culverts over small channels that are part of the river network were also extracted for the floodplain.

3.12.4 Final Quality Checking of Extracted Features

All extracted ground features were completely given the required attributes. All these output features comprise the flood hazard exposure database for the floodplain. This completes the feature extraction phase of the project.

Figure 33 shows the Digital Surface Model (DSM) of Basey floodplain overlaid with its ground features.



Figure 33. Extracted features for Basey Floodplain.

CHAPTER 4: LIDAR VALIDATION SURVEY AND MEASUREMENTS OF THE BASEY RIVER BASIN

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The methods applied in this Chapter were based on the DREAM methods manual (Balicanta, et al., 2014) and further enhanced and updated in Paringit, et al. (2017).

4.1 Summary of Activities

The Data Validation and Bathymetry Component (DVBC) conducted a survey in Basey River from September 10 to 24, 2014 (Samar Phase 1) and from December 4 to18, 2014 (Samar Phase 2). The scope of work covered reconnaissance; control point survey for the establishment of a control point; cross-section, bridge as-built and water level marking in MSL of Basey Bridge for Samar Phase 1 and bathymetric survey of the Basey River from Brgy. Guirang down to Brgy. Iba (mouth of the river) with an estimated length of 13.70 km for bathymetric survey for Samar Phase 2 using PPK GNSS Survey technique.



Figure 34. Basey River Survey Extent

4.2 Control Survey

The GNSS network used for Basey River Basin is composed of three (3) loops and a baseline established on September 12, 13, 17 and 19, 2014 occupying the following reference points: SME-18, a second-order GCP in Brgy. Canciledes, Municipality of Hernani; and SE-85, a first-order BM in Brgy. Barangay 11 Poblacion, Municipality of Llorente; both in Eastern Samar.

Two control points were established along the approach of bridges namely: UP-CNG at Can-Obing Bridge in Brgy. Can-Abong, Borongan City, East Samar; and UP-BSY at Basey Bridge, in Brgy. Guirang, Municipality of Basey, Samar. NAMRIA established control points: SME-12 in Brgy. San Miguel, Municipality of Balangiga; SE-49 in Brgy. Aguinaldo, Municipality of General Macarthur, both in Easter Samar; and SMR-3322 in Brgy. Binongtu-an, Municipality of Basey; and SM-335 in Pinalanga, Municipality of Marabut, both in Samar; were also used as marker during the survey.

The summary of reference and control points and its location is summarized in Table 26 while the GNSS network established is illustrated in Figure 35.



Figure 35. Static Network for Basey River Survey

		Geographic Coordinates (WGS 84)						
Control Point	Order of Accuracy	Latitude	Longitude	Ellipsoidal Height (m)	Elevation in MSL (m)	Date Established		
SME-18	2nd Order GCP	11°21'43.08127"°	125°36'37.41862"	78.217	17.66	Sep 12, 2014		
SE-85	1st Order BM	11°24'45.65441"	125°32'20.98934"	67.52	6.31	Sep 12, 2014		
SME-12	Used as Marker	11°07'19.15395"	125°21'29.28283"	67.212	2.721	Sep 13, 2014		
SMR- 3322	Used as Marker	11°17'40.55190"	125°07'10.82309"	70.666	6.636	Sep 17, 016		
SE-49	Used as Marker	11°12'34.48802"	125°31'52.42238"	66.981	3.779	Sep 13, 2014		
SM-33S	Used as Marker	11°07'33.79721"	125°12'32.14831"	68.705	3.951	Sep 17, 2014		
UP- CNG	UP Established	11°35'44.92939"	125°26'23.62776"	67.094	6.035	Sep 12, 2014		
UP-BSY	UP Established	11°27'57.66166"	125°01'08.84182"	73.078	9.958	Sep 19, 2014		

Table 26. List of References and Control Points used in Bas	ey River survey (Source: NAMRIA, UP-TCAGP)
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The GNSS set-ups on recovered reference points and established control points in Balangiga River are shown in Figure 36 to Figure 42.



Figure 36. GNSS base receiver setup, Trimble® SPS 852 at SME-18, located inside San Jose Elem. School, Brgy. Canciledes, Municipality of Hernani, Eastern Samar



Figure 37. GNSS receiver, Trimble® SPS 882, at SE-85, located at the approach of Llorente Bridge in Bry. 11, Mun. of Llorente, Eastern Samar



Figure 38. GNSS receiver occupation, Trimble® SPS 882, at SME-12 in Brgy. San Miguel, Mun. of Balangiga, Eastern Samar



Figure 39. GNSS base occupation, Trimble® SPS 852, at SMR-3322, located at the approach of Golden Bridge in Brgy. Binongtu-an, Mun. of Basey, Samar



 $Figure~40.~GNSS~base~occupation, Trimble {\ensuremath{\mathbb SPS}}~852, at~SE-49, in~Brgy.~Aguinaldo, Mun.~of~General~Macarthur, Eastern~Samar$

Hazard Mapping of the Philippines Using LiDAR (Phil-LiDAR 1)



Figure 41. GNSS base occupation, Trimble® SPS 882, at SM-335, in Brgy. Pinalanga, Mun. of Maravut, Samar



Figure 42. GNSS receiver occupation, Trimble® SPS 882, at UP-CNG, located at the approach of Can-Obing Bridge in Brgy. Can-Abong, Borongan City, Eastern Samar

4.3 Baseline Processing

The GNSS baselines were processed simultaneously in TBC by observing that all baselines have fixed solutions with horizontal and vertical precisions within +/- 20 cm and +/- 10 cm requirement, respectively. In cases where one or more baselines did not meet all of these criteria, masking is performed. Masking is done by removing/masking portions of these baseline data using the same processing software. It is repeatedly processed until all baseline requirements are met. If the reiteration yields out of the required accuracy, resurvey is initiated. Baseline processing result of control points in Basey River Basin is summarized in Table 27, generated by TBC software.

Observation	Date of Observation	Solution Type	Prec. (Meter)	V. Prec. (Meter)	Geodetic Az.	Ellipsoid Dist. (Meter	∆Height (Meter)
SME-18 SE-85	09-12-14	Fixed	0.004	0.015	305°49′17-	9586.978	-10.699
SME-18 SE-85	09-12-14	Fixed	0.005	0.033	305°49'17-	9586.977	-10.719
SME-18 UP-CNG	09-12-14	Fixed	0.003	0.013	324°17′44-	31862.046	-11.107
SME-18 SE-49	09-13-14	Fixed	0.003	0.016	207°09′17-	18943.356	-11.212
UP-CNG SE-85	09-12-14	Fixed	0.005	0.041	331°52′51-	22970.859	-0.416
SE-85 UP-CNG	09-12-14	Fixed	0.007	0.019	331°52′51-	22970.857	-0.437
SE-49 SME-12	09-13-14	Fixed	0.004	0.019	242°52′57-	21244.542	0.227
SME-12 SM-33S	09-17-14	Fixed	0.004	0.017	271°35′44-	16305.472	1.501
SME-12 SM-33S	09-17-14	Fixed	0.019	0.033	271°35′44-	16305.477	1.450
SME-12 SMR-3322	09-17-14	Fixed	0.003	0.014	306°16′15-	32291.859	3.461
SME-18 SME-12	09-13-14	Fixed	0.004	0.018	226°05′03-	38255.209	-11.019
SMR-3322 UP-BSY	09-19-14	Fixed	0.003	0.012	38°27′35-	6709.313	1.891
SMR-332 SM-33S	09-17-14	Fixed	0.004	0.014	152°23′19-	21038.056	-1.964
SMR-3322 SM-33S	09-17-14	Fixed	0.006	0.038	152°23′20-	21038.062	-1.978

Table 27. Baseline Processing Report for Basey River static survey

As shown in Table 27 a total of fourteen (14) baselines were processed with coordinates of SME-18 and elevation value of reference point SE-85 held fixed. All of them passed the required accuracy.
4.4 Network Adjustment

After the baseline processing procedure, network adjustment is performed using TBC. Looking at the Adjusted Grid Coordinates table of the TBC generated Network Adjustment Report, it is observed that the square root of the sum of the squares of x and y must be less than 20 cm and z less than 10 cm or in equation form:

 $\sqrt{((x_e)^2 + (y_e)^2)} < 20 \text{ cm} \text{ and } z_e < 10 \text{ cm}$

Where:

 x^{e} is the Easting Error, y^{e} is the Northing Error, and z^{e} is the Elevation Error

for each control point. See the Network Adjustment Report shown in Table 28 to Table 31 for complete details.

The eight (8) control points, SME-18, SE-85, SME-12, SMR-3322, SE-49, SM-335, UP-CNG and UP-BSY were occupied and observed simultaneously to form a GNSS loop. Coordinates of SME-18 and elevation values SE-85 were held fixed during the processing of the control points as presented in Table 28. Through these reference points, the coordinates and elevation of the unknown control points will be computed.

Point ID	Туре	East σ (Meter)	North σ (Meter)	Height σ (Meter)	Elevation σ (Meter)			
SE-85	Grid				Fixed			
SME-18 Local Fixed Fixed								
Fixed = 0.000001 (Meter)								

Table 28. Control Point Constraints

The list of adjusted grid coordinates, i.e. Northing, Easting, Elevation and computed standard errors of the control points in the network is indicated in Table 29. All fixed control points have no values for grid and elevation errors.

Table 29. Adjusted Grid Coordinates

Point ID	Easting (Meter)	Easting Error (Meter)	Northing (Meter)	Northing Error (Meter)	Elevation (Meter)	Elevation Error (Meter)	Constraint
SE-49	776407.626	0.007	1240340.446	0.005	3.779	0.050	
SE-85	777079.164	0.006	1262825.941	0.004	6.310	?	е
SM-335	741264.593	0.010	1230815.204	0.007	3.951	0.061	
SME-12	757572.894	0.007	1230490.556	0.005	2.721	0.051	
SME-18	784907.431	?	1257282.043	?	17.660	0.032	LL
SMR- 3322	731377.313	0.009	1249392.087	0.007	6.636	0.060	
UP-CNG	766068.484	0.005	1282999.389	0.004	6.035	0.036	

With the mentioned equation, $\sqrt{((x_e)^2+(y_e)^2)}<20$ cm for horizontal and $z^e<10$ cm for the vertical; the computation for the accuracy are as follows:

SME-18 a. horizontal accuracy Fixed = 3.2 < 10 cm vertical accuracy = SE-85 b. $\sqrt{((0.6)^2 + (0.4)^2)}$ horizontal accuracy = $\sqrt{(0.36 + 0.16)}$ = = 0.72 < 20 cmvertical accuracy = Fixed c. **SME-12** $\sqrt{((0.7)^2 + (0.5)^2)}$ horizontal accuracy = $\sqrt{(0.49 + 0.25)}$ = 0.86 < 20 cm = vertical accuracy 5.1 < 10 cm = d. SMR-3322 $\sqrt{((0.9)^2 + (0.7)^2)}$ horizontal accuracy = $\sqrt{(0.81+0.49)}$ = 1.14 < 20 cm = vertical accuracy = 6.0 < 10 cm SE-49 e. $\sqrt{((0.7)^2 + (0.5)^2)}$ horizontal accuracy = $\sqrt{(0.49 + 0.25)}$ = 0.86 < 20 cm = vertical accuracy 5.0 < 10 cm = SM-335 f. $\sqrt{((1.0)^2 + (0.7)^2)}$ horizontal accuracy = $\sqrt{(1.0+0.49)}$ = $1.22 < 20 \text{ cm}^{2}$ = vertical accuracy = 6.1 < 10 cm **UP-CNG** g. $\sqrt{((0.5)^2 + (0.4)^2)}$ horizontal accuracy = $\sqrt{(0.25+0.16)}$ = 0.65 < 20 cm = 3.6 < 10 cm vertical accuracy =

Following the given formula, the horizontal and vertical accuracy result of the two occupied control points are within the required precision.

Point ID	Latitude	Longitude	Height (Meter)	Height Error (Meter)	Constraint
SE-49	N11°12'34.48802"	E125°31'52.42238	66.981	0.050	
SE-85	N11°24'45.65441"	E125°32'20.98934	67.520	?	е
SM-335	N11°07'33.79721"	E125°12'32.14831	68.705	0.061	
SME-12	N11°07'19.15395"	E125°21'29.28283	67.212	0.051	
SME-18	N11°21'43.08127"	E125°36'37.41862	78.217	0.032	LL
SMR-3322	N11°17'40.55190"	E125°07'10.82309	70.666	0.060	
UP-CNG	N11°35'44.92939"	E125°26'23.62776	67.094	0.036	

Table 30. Adjusted Geodetic Coordinates

The corresponding geodetic coordinates of the observed points are within the required accuracy as shown in Table 30. Based on the result of the computation, the equation is satisfied; hence, the required accuracy for the program was met.

The summary of reference and control points used is indicated in Table 31.

		Geograp	hic Coordinates (WGS	84)	UTM ZONE 51 N		
Control Point	Order of Accuracy	Latitude	Longitude	Ellipsoidal Height (m)	Northing (m)	Easting (m)	BM Ortho (m)
SME-18	2nd Order, GCP	11°21'43.08127"	125°36'37.41862"	78.217	1257282.043	784907.431	17.66
SE-85	1st Order, BM	11°24'45.65441"	125°32'20.98934"	67.52	1262825.941	777079.164	6.31
SME-12	Used as Marker	11°07'19.15395"	125°21'29.28283"	67.212	1230490.556	757572.894	2.721
SMR- 3322	Used as Marker	11°17'40.55190"	125°07'10.82309"	70.666	1249392.087	731377.313	6.636
SE-49	Used as Marker	11°12'34.48802"	125°31'52.42238"	66.981	1240340.446	776407.626	3.779
SM-335	Used as Marker	11°07'33.79721"	125°12'32.14831"	68.705	1230815.204	741264.593	3.951
UP-CNG	UP Established	11°35'44.92939"	125°26'23.62776"	67.094	1282999.389	766068.484	6.035
UP-BSY	UP Established	11°20'31.52354"	125°09'28.44378"	72.554	1254677.422	735513.124	8.581

Table 31. Reference and control points used and its location (Source: NAMRIA, UP-TCAGP)

4.5 Cross-section and Bridge As-Built survey and Water Level Marking

Cross-section and as-built survey were conducted on September 18, 2014 at the upstream side of Basey Bridge in Brgy. Guirang, Municipality of Basey, Samar as shown in Figure 43. Trimble[®] SPS 882 GNSS PPK survey technique was used as shown in Figure 44.



Figure 43. Basey Bridge taken facing upstream



Figure 44. Cross-section Survey at the left side of Basey Bridge in Brgy. Guirang, Basey, Samar







videe N	ame.	BASEY BRIDGE	Bridge D	ata For	n	Date: Sentemb	er 18 2014
Divor No	mo.	RACEV DIVED BA	CIN			Time: 11:52 AL	4
eiver rua	me	DAJET KIVEK DA	NIC			Time. 11.55 AM	n
Location Survey T	(Brgy,	Patricia Dela Cruz Team	–Data Valid	sey we ation an	d Bathymetry	Component	8
tion cor	dition	low normal	high		Weather	Condition: fr	ir Gim
HOW COI	anion.	iow normal	(night		weather	condition.	air Gainy
Latitude	11.	- 20 - 32,40417 " N.	_	Long	tude: 125	-09-29.32310*	Ε.
84	27	D	0	(BA3			
BA1		di la			BA4	igend: A = Bridge Approach P =	Pler LC = Low Cho
						b = Abutment D =	Deck HC + High Ch
	Ab1		2	АЬ2			
		P		H			
		Deck (manual and					1
evation	7.	94 M. W	vidth:	9.41 M.	de of the bank facin Spa	n (BA3-BA2): 8	4.01 M.
1		Station		High	Chord Elevatio	n Low Cho	ard Elevation
1		PIER 1			8.5332 M	5.8	332 M.
2							
2						_	
2							
4							
5		in a second a second a second					
		Bridge Approach (Hank	ited your measurem	ant from the	left side of the bank faci	(menterwoh ge	
	Stat	ion(Distance from BA1)	Elevation		Station(Dist	ance from BA1)	Elevation
BA1		0	6.3822 M.	BA3	118	.129 M.	8.2442 M.
BA2		34 640 M	7.6542 M	BA4	196	.808 M.	5.6472 M.
-	_						
butmen	t: Ist	the abutment sloping? (Yes No;	Ifyes	fill in the follow	ving information:	
		Casting ID	internet from	DA11		Florentia	_
	41.1	Station (D	Istance from	n BA1j	10	2 7162 M	n .
H	ADI		05 543 M			2.7102 1	
	ADZ	1	06.512 M.			0.9072 N	.
		PIEF (Please start your mea	surement from	the left sk	ie of the bank facin	g downstream)	
shape:	Obl	ong Number of P	iers:	1	Height o	f column footing: _	N/A
	-	Station (Distance from	m BA1)	F	levation	Pier	Width
Pier 1	1	66.213 M.				5.5	0 M
01	2						
Pier a	3						
Pier							
Pier 2 Pier 2	1						
Pier 2 Pier 2 Pier 2 Pier 2	5						
Pier 2 Pier 2 Pier 2 Pier 9	5						

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The water level elevation acquired on September 18, 2014 at 1:39:22 PM Samar Phase 1 in Basey Bridge is 0.3092 m (MSL). The initial water level marking was done on the same day, as shown in Figure 48.

These markings were recovered and converted into MSL on December 10, 2014 during the Samar Phase 2 survey to serve as reference for flow data gathering and depth gauge deployment of Visayas State University.



Figure 48. Finished Water Level Markings at Basey Bridge, Brgy. Guirang, Basey, Samar

4.6 Validation Points Acquisition Survey

Validation points acquisition survey was conducted on September 14, 15, 17, 18, 19 and 20 using a survey grade GNSS rover receiver, Trimble[®] SPS 882 mounted on a pole which was attached in front of the vehicle as shown in Figure 49. It was secured with a nylon rope to ensure that it was horizontally and vertically balanced.



Figure 49. Validation points acquisition survey set-up along Balangiga River Basin

The survey started from Brgy. Purok D1, Borongan City, going south thorugh National high-way traversing Borongan City; nine (9) Municipalities of Eastern Samar, namely: Maydolong, Balangkayan, Llorente, Hernani, General Macarthur, Quinapondan, Giporlos, Balangiga and Lawaan; and four (4) Municipalities of Samar namely: Marabut, Basey, Santa Rita, and ended in Brgy. Laygayon, Municipality of Pinabacdao, Samar. A total of 30,114 points were gathered with approximate length of 296.68 km using UP-CNG, SE-49, SM-33S, SMR-3322, and SE-85 as GNSS base stations for the entire extent validation points acquisition survey as illustrated in the map in Figure 50.



Figure 50. Validation points acquisition survey along Samar and Eastern Samar

4.7 Bathymetric Survey

Manual bathymetric survey was performed all throughout the survey because of the malfunctioning echo sounder. The team rented a boat for the bathymetric survey since the rigid boat of PCG Tacloban was not available for the survey.

The survey began in Brgy. Guirang down to the mouth of the river in Brgy. Iba. The team used a boat and positioned the range pole with an installed Trimble[®] SPS 882 on the gunwale of the boat as shown in Figure 51. A portable depth sounder was used to measure the depth of the water as shown in Figure 52. Bamboo poles and paddles were used to fix the position of the boat while encoding and entering the readings. The team also deployed a stadia rod every 100 m to check if the portable depth sounder is accurate and functioning properly.



Figure 51. Setting up- Manual Bathymetry in Basey River



Figure 52. A) Actual Execution of Bathymetric Survey in Basey River, (B) depth checking using portable depth sounder and stadia rod

Bathymetric survey started in Brgy. Guirang down to the mouth of the river in Brgy. Iba. The control point SMR-3322 was occupied as a base station throughout the bathymetric survey. The bathymetry length is about 13.7 km, with a total points of 682. Canopy cover along Brgy. Guirang prohibited GPS signals to penetrate; thus, resulting in float data. The processed data were generated into a map using a GIS software as shown in Figure 53.



Figure 53. Basey River Bathymetry in Basey Samar

A CAD drawing was also produced to illustrate the Basey riverbed profile as shown in Figure 54. The profile exhibits irregular depth in its riverbed terrain. The upstream Basey River along the bridge where cross-section was conducted on the previous field work has the deepest elevation, probably because of the unfinished construction of the pier footing. The difference in elevation of the deepest elevation in the upstream, along the bridge, to the mouth of the river is approximately 15 m.



CHAPTER 5: FLOOD MODELING AND MAPPING

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The methods applied in this Chapter were based on the DREAM methods manual (Lagmay, et al., 2014) and further enhanced and updated in Paringit, et al. (2017).

5.1 Data Used for Hydrologic Modeling

5.1.1 Hydrometry and Rating Curves

All data that affect the hydrologic cycle of the Basey River Basin were monitored, collected, and analyzed. Rainfall, water level, and flow in a certain period of time, which may affect the hydrologic cycle of the Basey River Basin were monitored, collected, and analyzed.

5.1.2 Precipitation

Precipitation data was taken from three automatic rain gauges (ARGs) installed by the Department of Science and Technology – Advanced Science and Technology Institute (DOST-ASTI). The location of the rain gauge is seen in Figure 55.



Figure 55. The location map of Basey HEC-HMS model used for calibration

5.1.3 Rating Curves and River Outflow

A rating curve was developed at Sohoton Bridge, Basey, Samar (11°20'32.48"N, 125° 9'29.09"E). It gives the relationship between the observed water levels at Sohoton Bridge and outflow of the watershed at this location.

For Sohoton Bridge, the rating curve is expressed as Q = 115.77e.3.097h as shown in Figure 57.





Figure 57. Rating Curve at Sohoton Bridge, Basey, Samar

This rating curve equation was used to compute the river outflow at Sohoton Bridge for the calibration of the HEC-HMS model. Total rain from Basey rain gauge is 220 mm. It peaked to 11 mm on 16 January 2017, 2:00. The lag time between the peak rainfall and discharge is 14 hours and 40 minutes.



Figure 58. Rainfall and outflow data at Basey used for modeling

5.2 RIDF Station

The Philippines Atmospheric Geophysical and Astronomical Services Administration (PAGASA) computed Rainfall Intensity Duration Frequency (RIDF) values for the Tacloban Rain Gauge. The RIDF rainfall amount for 24 hours was converted to a synthetic storm by interpolating and re-arranging the value in such a way certain peak value will be attained at a certain time. This station chosen based on its proximity to the Basey watershed. The extreme values for this watershed were computed based on a 59-year record.

	COMPUTED EXTREME VALUES (in mm) OF PRECIPITATION									
T (yrs)	10 mins	20 mins	30 mins	1 hr	2 hrs	3 hrs	6 hrs	12 hrs	24 hrs	
2	17.8	26.9	33.6	42.8	59.7	70.5	87.2	104	120.6	
5	24.3	36.7	45.7	57.4	80.7	95.2	117.9	140.6	161.4	
10	28.5	43.2	53.7	67.1	94.6	111.5	138.2	164.9	188.4	
15	30.9	46.8	58.3	72.5	102.5	120.7	149.6	178.6	203.7	
20	32.6	49.4	61.4	76.3	108	127.1	157.7	188.1	214.3	
25	33.9	51.4	63.9	79.3	112.2	132.1	163.8	195.5	222.6	
50	37.9	57.5	71.4	88.3	125.2	147.4	182.9	218.2	247.9	
100	41.8	63.5	78.9	97.3	138.2	162.5	201.8	240.8	273	

Table 32. RIDF values for Tacloban Rain Gauge computed by PAGASA



Figure 59. Location of Tacloban RIDF Station relative to Basey River Basin



Figure 60. Synthetic storm generated for a 24-hr period rainfall for various return periods

5.3 HMS Model

The soil dataset was generated before 2004 by the Bureau of Soils; this is under the Department of Agriculture. The land cover dataset is from the National Mapping and Resource information Authority (NAMRIA). The soil and land cover of the Basey River Basin are shown in Figures 61 and 62, respectively.



Figure 61. Soil Map of Basey River Basin



Figure 62. Land Cover Map of Basey River Basin

For Basey, the soil classes identified were silt loam, sandy clay, silty clay, clay loam, and sandy loam. The land cover types identified were shrubland, open forest, and cultivated.

Hazard Mapping of the Philippines Using LiDAR (Phil-LiDAR 1)



Figure 63. Slope Map of the Basey River Basin



Figure 64. Stream Delineation Map of the Basey River Basin

Using the SAR-based DEM, the Basey basin was delineated and further subdivided into subbasins. The model consists of 29 sub basins, 14 reaches, and 14 junctions. The main outlet is Sohoton Bridge. This basin model is illustrated in Figure 65.



Figure 65. The Basey river basin model generated using HEC-HMS

5.4 Cross-section Data

Riverbed cross-sections of the watershed are crucial in the HEC-RAS model setup. The cross-section data for the HEC-RAS model was derived using the LiDAR DEM data. It was defined using the Arc GeoRAS tool and was post-processed in ArcGIS.



Figure 66. River cross-section of Basey River generated through Arcmap HEC GeoRAS tool

5.5 Flo 2D Model

The automated modelling process allows for the creation of a model with boundaries that are almost exactly coincidental with that of the catchment area. As such, they have approximately the same land area and location. The entire area is divided into square grid elements, 10 meter by 10 meter in size. Each element is assigned a unique grid element number which serves as its identifier, then attributed with the parameters required for modelling such as x-and y-coordinate of centroid, names of adjacent grid elements, Manning coefficient of roughness, infiltration, and elevation value. The elements are arranged spatially to form the model, allowing the software to simulate the flow of water across the grid elements and in eight directions (north, south, east, west, northeast, northwest, southeast, southwest).

Based on the elevation and flow direction, it is seen that the water will generally flow from the north side of the model to the south, following the main channel. As such, boundary elements in those particular regions of the model are assigned as inflow and outflow elements respectively.



Figure 67. Screenshot of subcatchment with the computational area to be modeled in FLO-2D GDS Pro

The simulation is then run through FLO-2D GDS Pro. This particular model had a computer run time of 38.60889 hours. After the simulation, FLO-2D Mapper Pro is used to transform the simulation results into spatial data that shows flood hazard levels, as well as the extent and inundation of the flood. Assigning the appropriate flood depth and velocity values for Low, Medium, and High creates the following food hazard map. Most of the default values given by FLO-2D Mapper Pro are used, except for those in the Low hazard level. For this particular level, the minimum h (Maximum depth) is set at 0.2 m while the minimum vh (Product of maximum velocity (v) times maximum depth (h)) is set at 0 m2/s. The generated hazard maps for Basey are in Figures 71, 73, and 75.

The creation of a flood hazard map from the model also automatically creates a flow depth map depicting the maximum amount of inundation for every grid element. The legend used by default in Flo-2D Mapper is not a good representation of the range of flood inundation values, so a different legend is used for the layout. In this particular model, the inundated parts cover a maximum land area of 76,944,672.00 m2. The generated flood depth maps for Basey are in Figures 72, 74, and 76.

There is a total of 29,005,764.16 m3 of water entering the model. Of this amount, 29,005,764.16 m3 is due to rainfall while there is no inflow from other areas because it is an independent model. 10,958,439.00 m3 of this water is lost to infiltration and interception, while 14,445,841.09 m3 is stored by the flood plain. The rest, amounting up to 3,601,497.80 m3, is outflow.

5.6 Results of HMS Calibration

After calibrating the Basey HEC-HMS river basin model, its accuracy was measured against the observed values. Figure 68 shows the comparison between the two discharge data.



Figure 68. Outflow Hydrograph of Basey produced by the HEC-HMS model compared with observed outflow

Enumerated in Table 33 are the adjusted ranges of values of the parameters used in calibrating the model.

Hydrologic Element	Calculation Type	Method	Parameter	Range of Calibrated Values
	Loss	SCS Curve number	Initial Abstraction (mm)	40 - 151
			Curve Number	99
Basin		Clark Unit Hydrograph	Time of Concentration (hr)	0.1 - 7
			Storage Coefficient (hr)	0.02 - 1
	Baseflow	Recession	Recession Constant	0.9
			Ratio to Peak	0.01
Reach	Routing	Muskingum-Cunge	Manning's Coefficient	0.04

Table 33. Range of Calibrated Values for Basey

Initial abstraction defines the amount of precipitation that must fall before surface runoff. The magnitude of the outflow hydrograph increases as initial abstraction decreases. The range of values from 40mm to 151mm means that there is a high amount of infiltration or rainfall interception by vegetation per subbasin.

Curve number is the estimate of the precipitation excess of soil cover, land use, and antecedent moisture. The magnitude of the outflow hydrograph increases as curve number increases. The value of 99 for curve number is the highest possible value for this parameter.

Time of concentration and storage coefficient are the travel time and index of temporary storage of runoff in a watershed. The range of calibrated values from 0.02 to 7 hours determines the reaction time of the model with respect to the rainfall. The peak magnitude of the hydrograph also decreases when these parameters are increased.

Recession constant is the rate at which baseflow recedes between storm events and ratio to peak is the ratio of the baseflow discharge to the peak discharge. Recession constant of 0.9 indicates that the basin is unlikely to quickly go back to its original discharge and instead, will be higher. Ratio to peak of 0.01 indicates a steeper receding limb of the outflow hydrograph.

Manning's roughness coefficient of 0.04 corresponds to the common roughness of Basey watershed, which is determined to be cultivated with mature field crops (Brunner, 2010).

RMSE	58.4
r2	0.82
NSE	0.94
PBIAS	0.27
RSR	0.24

Table 34. Summary of the Efficiency Test of Basey HMS Model

The Root Mean Square Error (RMSE) method aggregates the individual differences of these two measurements. It was computed as 58.4 (m3/s).

The Pearson correlation coefficient (r2) assesses the strength of the linear relationship between the observations and the model. This value being close to 1 corresponds to an almost perfect match of the observed discharge and the resulting discharge from the HEC HMS model. Here, it measured 0.82.

The Nash-Sutcliffe (E) method was also used to assess the predictive power of the model. Here the optimal value is 1. The model attained an efficiency coefficient of 0.94.

A positive Percent Bias (PBIAS) indicates a model's propensity towards under-prediction. Negative values indicate bias towards over-prediction. Again, the optimal value is 0. In the model, the PBIAS is 0.27.

The Observation Standard Deviation Ratio, RSR, is an error index. A perfect model attains a value of 0 when the error in the units of the valuable a quantified. The model has an RSR value of 0.24.

5.7 Calculated outflow hydrographs and discharge values for different rainfall return periods

5.7.1 Hydrograph using the Rainfall Runoff Model

The summary graph (Figure 69) shows the Basey outflow using the Tacloban Rainfall Intensity-Duration-Frequency curves (RIDF) in 5 different return periods (5-year, 10-year, 25-year, 50-year, and 100-year rainfall time series) based on the Philippine Atmospheric Geophysical and Astronomical Services Administration (PAG-ASA) data. The simulation results reveal significant increase in outflow magnitude as the rainfall intensity increases for a range of durations and return periods.



Figure 69. Outflow hydrograph at Basey Station generated using Tacloban RIDF simulated in HEC-HMS

A summary of the total precipitation, peak rainfall, peak outflow and time to peak of the Basey discharge using the Tacloban Rainfall Intensity-Duration-Frequency curves (RIDF) in five different return periods is shown in Table 35.

RIDF Period	Total Precipitation (mm)	Peak rainfall (mm)	Peak outflow (m 3/s)	Time to Peak
5-Year	161.4	24.3	1028.7	1 hour, 40 minutes
10-Year	188.4	28.5	1514.0	1 hour, 40 minutes
25-Year	222.6	33.9	2129.6	1 hour, 30 minutes
50-Year	247.9	37.9	2579.1	1 hour, 30 minutes
100-Year	273.0	41.80	2999.8	1 hour, 30 minutes

Table 35. Peak values of the Basey HEC-HMS Model outflow using the Tacloban RIDF

5.8 River Analysis Model Simulation

The HEC-RAS Flood Model produced a simulated water level at every cross-section for every time step for every flood simulation created. The resulting model will be used in determining the flooded areas within the model. The simulated model will be an integral part in determining real-time flood inundation extent of the river after it has been automated and uploaded on the DREAM website. For this publication, only a sample output map river was to be shown, since only the DVC base flow was calibrated. The sample generated map of Maayon River using the calibrated HMS base flow is shown in Figure 70.



Figure 70. Sample output of Basey RAS Model

5.9 Flood Hazard and Flow Depth Map

The resulting hazard and flow depth maps have a 10m resolution. Figure 71 to Figure 76 shows the 5-, 25-, and 100-year rain return scenarios of the Basey floodplain.

The floodplain, with an area of 141.92 sq. km., covers two municipalities namely Basey and Santa Rita. Table 36 shows the percentage of area affected by flooding per municipality.

City / Municipality	Total Area	Area Flooded	% Flooded
Basey	627.97	140.21	22%
Santa Rita	250.37	1.59	1%

Table 36. Municipalities affected in Basey floodplain





94



95






5.10 Inventory of Areas Exposed to Flooding

Affected barangays in Basey river basin, grouped by municipality, are listed below. For the said basin, three municipalities consisting of 56 barangays are expected to experience flooding when subjected to 5-yr rainfall return period.

For the 5-year return period, 28.52379% of the municipality of Basey with an area of 627.97 sq. km. will experience flood levels of less 0.20 meters. 4.886182% of the area will experience flood levels of 0.21 to 0.50 meters while 2.529466%, 1.230202%, 0.745903%, and 0.260162% of the area will experience flood depths of 0.51 to 1 meter, 1.01 to 2 meters, and more than 2 meters, respectively. Listed in Table 37 are the affected areas in square kilometres by flood depth per barangay.

						r	
	Bulao	9.95	0.28	0.32	0.42	0.25	0.012
	Buenavista	6.46	2.86	0.82	0.043	0.0082	0
	Binongtu- an	68.0	0.32	0.015	0.0029	0.13	0.0073
amar	Ваурау	0.28	0.067	0.0063	0.0001	0	0
ι Basey, S	Basiao	2.67	0.32	0.46	0.16	0.019	0.0008
ırangays ir	Baloog	3.87	0.18	0.14	0.17	0.024	0
ffected Ba	Balante	3.18	1.2	0.38	0.021	0.0004	0
A	Bacubac	0.62	0.16	0.37	0.064	0	0
	Anglit	1.14	0.42	0.048	0.00031	0	0
	Amandayehan	0.79	0.14	0.13	0.074	0.0037	0
Affected Areas (in	sq.m.) by flood depth (in m.)	0.03-0.20	0.21-0.50	0.51-1.00	1.01-2.00	2.01-5.00	> 5.00

Table 37. Affected Areas in Basey, Samar during 5-Year Rainfall Return Period

Hazard Mapping of the Philippines Using LiDAR (Phil-LiDAR	1))		
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	Bulao	9.95	0.28	0.32	0.42	0.25	0.012
	Buenavista	6.46	2.86	0.82	0.043	0.0082	0
	Binongtuan	0.89	0.32	0.015	0.0029	0.13	0.0073
amar	Вауbау	0.28	0.067	0.0063	0.0001	0	0
n Basey, S	Basiao	2.67	0.32	0.46	0.16	0.019	0.0008
rangays ii	Baloog	3.87	0.18	0.14	0.17	0.024	0
ffected Ba	Balante	3.18	1.2	0.38	0.021	0.0004	0
A	Bacubac	0.62	0.16	0.37	0.064	0	0
	Anglit	1.14	0.42	0.048	0.00031	0	0
	Amandayehan	0.79	0.14	0.13	0.074	0.0037	0
Affected Areas (in	sq.m.) by flood depth (in m.)	0.03-0.20	0.21-0.50	0.51-1.00	1.01-2.00	2.01-5.00	> 5.00

	Dolongan	4.33	1.23	1.02	0.21	0.0032	0
	Del Pilar	1.66	0.71	0.15	0.0003	0	0
	Cogon	12.61	1.63	0.7	0.78	0.38	0.0088
amar	Catadman	4.75	0.41	0.3	0.26	0.034	0.0004
ays in Basey, S	Canmanila	0.83	0.16	0.15	0.02	0.0001	0
ected Barange	Cancaiyas	4.86	0.1	0.091	0.13	0.26	0.021
Affe	Can- Abay	0.68	0.12	0.06	0.065	0.0024	0
	Cambayan	1.15	0.071	0.043	0.023	0.0024	0
	Buscada	0.45	0.16	0.044	0.0024	0	0
	Burgos	1.35	0.41	0.17	0.0043	0.0016	0.017
Affected Areas (in	sq.m.) by flood depth (in m.)	0.03-0.20	0.21-0.50	0.51-1.00	1.01-2.00	2.01-5.00	> 5.00

						r	
	Manlilinab	14.01	0.42	0.45	0.61	0.93	0.44
	Magallanes	1.21	0.63	0.13	0.0034	0	0
_	Mabini	0.016	0.0001	0.0002	6000.0	0.0025	0.0019
sey, Sama	Γογο	0.5	0.043	0.027	0.0069	0	0
ays in Bas	Loog	8.09	0.51	0.41	0.18	0.21	0.21
ed Barang	Lawa- An	0.17	0.1	0.014	0.00019	0	0
Affect	Inuntan	3.42	0.22	0.22	0.12	0.039	0.0011
	lba	5.08	2.26	0.28	0.0033	0	0
	Guirang	14.9	0.7	0.7	0.75	0.85	99.0
	Guintigui- An	0.82	0.54	0.22	0.0057	0.0016	0
Affected Areas (in	sq.m.) by flood depth (in m.)	0.03-0.20	0.21-0.50	0.51-1.00	1.01-2.00	2.01-5.00	> 5.00

	Roxas	2.6	1.15	1.11	0.11	0.001	0
	Pelit	4.59	0.54	0.61	0.39	0.24	0.066
	Panugmonon	1.26	0.48	0.039	0.0008	0	0
, Samar	РаІаурау	0.14	0.061	0.012	0.00065	0	0
/s in Basey	Old San Agustin	16.67	2.94	1.45	1.18	0.46	0.016
ed Barangay	Nouvelas Occidental	1.33	0.45	0.035	0.0022	0.12	0.039
Affect	New San Agustin	2.61	1.33	0.86	0.06	0	0
	Mongabong	2.31	0.54	0.23	0.039	0.0027	0.0001
	Mercado	0.14	0.036	0.019	0.00075	0	0
	May-It	3.01	1.24	0.72	0.11	0.0092	0.0001
Affected Areas (in	sq.m.) by flood depth (in m.)	0.03-0.20	0.21-0.50	0.51-1.00	1.01-2.00	2.01-5.00	> 5.00

				Affect	ed Baranga	ays in Basey,	Samar			
San An	tonio	San Fernando	Sawa	Serum	Sugca	Sugponon	Sulod	Tinaogan	Tingib	Villa Aurora
1.1	2	6.68	2.48	1.81	1.63	1.7	0.24	0.27	1.91	15.84
0.2	21	1.51	0.75	0.62	0.54	0.59	0.06	0.0034	0.67	0.59
0	12	0.82	0.47	0.048	0.022	0.18	0.02	0.0013	0.47	0.82
0.0	37	0.26	0.2	0.0003	0.0006	0.087	0.00015	0.0007	0.045	1.09
0.00	036	0.18	0.044	0	0	0.0079	0	0.0001	0	0.46
	0	0.13	0	0	0	0	0	0	0	0.01



Figure 77. Affected Areas in Basey, Samar during 5-Year Rainfall Return Period



Figure 78. Affected Areas in Basey, Samar during 5-Year Rainfall Return Period



Figure 79. Affected Areas in Basey, Samar during 5-Year Rainfall Return Period



Figure 80. Affected Areas in Basey, Samar during 5-Year Rainfall Return Period



Figure 81. Affected Areas in Basey, Samar during 5-Year Rainfall Return Period

For the municipality of Santa Rita, with an area of 250.371sq. km., 0.554291% will experience flood levels of less 0.20 meters. 0.012747% of the area will experience flood levels of 0.21 to 0.50 meters while 0.008513%, 0.005991%, and 0.002179% of the area will experience flood depths of 0.51 to 1 meter, and 1.01 to 2 meters, respectively. Listed in Table 38 are the affected areas in square kilometres by flood depth per barangay.

Affected	Area	a of affected bar	rangays in Sa	anta Rita (in sq.	km.)
sq.m.) by flood depth (in m.)	Bagolibas	Cabacungan	Caticugan	Pagsulhogon	San Pedro
0.03-0.20	0.18	0.67	0.013	0.38	0.14
0.21-0.50	0.0033	0.019	0.0011	0.0069	0.0015
0.51-1.00	0.0043	0.0089	0.0017	0.0056	0.0009
1.01-2.00	0.001	0.0081	0.0015	0.0035	0.001
2.01-5.00	0	0.00088	0	0.0046	0
> 5.00	0	0	0	0	0

Table 38. Affected Areas in Santa Rita, Samar during 5-Year Rainfall Return Period



Figure 82. Affected Areas in Santa Rita, Samar during 5-Year Rainfall Return Period

For the 25-year return period, 25.49069% of the municipality of Basey with an area of 627.97 sq. km. will experience flood levels of less 0.20 meters. 5.234104% of the area will experience flood levels of 0.21 to 0.50 meters while 3.594518%, 2.099354%, 1.240996%, and 0.5189% of the area will experience flood depths of 0.51 to 1 meter, 1.01 to 2 meters, and more than 2 meters, respectively. Listed in Table 39 are the affected areas in square kilometres by flood depth per barangay.

Table 39. Affected Areas in Basey, Samar during 25-Year Rainfall Return Period

	Bulao	9.77	0.29	0.28	0.47	0.38	0.031
	Buenavista	4.55	3.23	2.22	0.18	0.016	0
	Binongtu- an	0.71	0.45	0.069	0.002	0.073	0.068
	Ваурау	0.25	680.0	0.012	0.0002	0	0
ays in Basey	Basiao	2.55	0.26	0.39	0.39	0.033	0.001
ected Barang	Baloog	3.76	0.21	0.14	0.2	0.059	0
Affe	Balante	2.65	1.31	0.71	0.12	0.0018	0
	Bacubac	0.51	0.12	0.27	0.32	0	0
	Anglit	0.88	0.57	0.16	0.00096	0.000068	0
	Amandayehan	0.72	0.14	0.15	0.12	0.012	0
Affected Areas (in	sq.m.) by flood depth (in m.)	0.03-0.20	0.21-0.50	0.51-1.00	1.01-2.00	2.01-5.00	> 5.00

p i					Affected Bara	angays in Base	٨			
	Burgos	Buscada	Cambayan	Can-Abay	Cancaiyas	Canmanila	Catadman	Cogon	Del Pilar	Dolongan
	0.27	1.12	0.59	4.73	0.73	4.49	11.74	1.31	3.77	3.773204
	0.23	0.076	0.17	0.11	0.15	0.43	1.89	0.81	1.32	1.321199
	0.15	0.056	0.076	0.091	0.19	0.37	0.9	0.39	0.98	0.981249
	0.015	0.031	0.065	0.13	0.094	0.36	0.72	0.0064	0.71	0.708023
	0	0.0043	0.026	0.29	0.0011	0.096	0.83	0	0.006	0.006
	0	0	0	0.11	0	0.0011	0.024	0	0	0

	Roxas	2.08	1.04	1.26	0.59	0.002	0
	Pelit	4.13	0.36	0.63	0.9	0.25	0.16
	Panugmonon	T	0.63	0.15	0.0038	0	0
	Palaypay	0.097	0.05	0.058	0.0071	0	0
ays in Basey	Old San Agustin	15.02	3.09	2	1.27	1.26	0.078
ected Barang	Nouvelas Occidental	1.07	0.6	0.13	0.0026	0.0087	0.16
Aff	New San Agustin	1.82	1.38	1.35	0.31	0.0002	0
	Mongabong	2.14	0.56	0.35	0.067	0.0042	0.0001
	Mercado	0.12	0.043	0.029	0.0018	0	0
	May-It	2.72	1.04	66.0	0.32	0.016	0.0001
Affected Areas (in	sq.m.) by flood depth (in m.)	0.03-0.20	0.21-0.50	0.51-1.00	1.01-2.00	2.01-5.00	> 5.00

Affected Areas (in				1	Affected Bara	ngays in Bas	ey			
sq.m.) by flood depth (in m.)	Guintigui- An	Guirang	lba	Inuntan	Lawa-An	Loog	Гоуо	Mabini	Magallanes	Manlilinab
0.03-0.20	0.56	13.74	3.74	3.29	0.1	7.45	0.48	0.013	6.0	13.49
0.21-0.50	0.66	0.58	2.57	0.16	0.055	0.38	0.053	0.001	0.77	0.43
0.51-1.00	0.29	0.56	1.29	0.2	0.12	0.46	0.036	0.00016	0.3	0.42
1.01-2.00	0.07	0.83	0.03	0.25	0.0067	0.75	0.013	0.00034	0.011	0.58
2.01-5.00	0.0019	1.73	0	0.12	0	0.3	0.0001	0.0015	0	1.06
> 5.00	0	1.12	0	0.002	0	0.28	0	0.0053	0	0.89

	lla ora	.42	57	67	26	83	57
	Vi Aui	15	o'	Ö	1.	o'	0.0
	Tingib	1.57	0.64	0.7	0.18	0.0014	0
	Tinaogan	0.27	0.0036	0.0023	0.0006	0.0002	0
	Sulod	0.19	0.072	0.055	0.0034	0	0
gays in Basey	Sugponon	1.28	0.68	0.33	0.24	0.041	0
ected Barang	Sugca	1.31	0.79	0.091	0.002	0	0
Aff	Serum	1.51	0.83	0.13	0.0003	0	0
	Sawa	2.1	0.81	0.6	0.27	0.17	0.0001
	San Fernando	5.56	1.65	1.29	0.74	0.085	0.26
	San Antonio	1.06	0.19	0.16	0.075	0.0015	0
Affected Areas (in	sq.m.) by flood depth (in m.)	0.03-0.20	0.21-0.50	0.51-1.00	1.01-2.00	2.01-5.00	> 5.00



Figure 83. Affected Areas in Basey, Samar during 25-Year Rainfall Return Period



Figure 84. Affected Areas in Basey, Samar during 25-Year Rainfall Return Period



Figure 85. Affected Areas in Basey, Samar during 25-Year Rainfall Return Period



Figure 86. Affected Areas in Basey, Samar during 25-Year Rainfall Return Period



Figure 87. Affected Areas in Basey, Samar during 25-Year Rainfall Return Period

For the municipality of Santa Rita, with an area of 250.371 sq. km., 0.19% will experience flood levels of less 0.20 meters. 0.005% of the area will experience flood levels of 0.21 to 0.50 meters while 0.003%, 0.004%, and 0.002% of the area will experience flood depths of 0.51 to 1 meter, and 1.01 to 2 meters, respectively.

Affected		Affected Baran	igays in Sant	a Rita, Samar	
Areas (in sq.m.) by flood depth (in m.)	Bagolibas	Cabacungan	Caticugan	Pagsulhogon	San Pedro
0.03-0.20	0.18	0.66	0.011	0.38	0.14
0.21-0.50	0.0023	0.02	0.0019	0.0099	0.0016
0.51-1.00	0.0055	0.012	0.0021	0.0055	0.0007
1.01-2.00	0.0016	0.0071	0.0024	0.0048	0.0009
2.01-5.00	0	0.0038	0.0003	0.005	0.0005
> 5.00	0	0	0	0.0001	0

Table 40. Affected Areas in Santa Rita, Samar during 25-Year Rainfall Return Period



Figure 88. Affected Areas in Santa Rita, Samar during 25-Year Rainfall Return Period

For the 100-year return period, 23.75% of the municipality of Basey with an area of 627.97 sq. km. will experience flood levels of less 0.20 meters. 4.80% of the area will experience flood levels of 0.21 to 0.50 meters while 4.46%, 2.72%, 1.76%, and 0.68% of the area will experience flood depths of 0.51 to 1 meter, 1.01 to 2 meters, and more than 2 meters, respectively. Listed in Table 41 are the affected areas in square kilometres by flood depth per barangay.

Table 41. Affected Areas in Basey, Samar during 100-Year Rainfall Return Period

	Bulao	9.64	0.3	0.27	0.46	0.5	0.047
	Buenavista	3.74	2.64	3.33	0.46	0.023	0
	Binongtu- an	9.0	0.49	0.13	0.002	0.066	0.077
nar	Вауbау	0.23	0.1	0.018	0.0003	0	0
in Basey, Sar	Basiao	2.47	0.25	0.32	0.54	0.043	0.0015
d Barangays	Baloog	3.7	0.23	0.15	0.21	0.095	0
Affecte	Balante	2.28	1.29	0.98	0.23	0.0036	0
	Bacubac	0.45	0.093	0.21	0.46	0	0
	Anglit	0.74	0.57	0.29	0.0028	0.00011	0
	Amandayehan	0.68	0.13	0.16	0.12	0.029	0
Affected Areas (in	sq.m.) by flood depth (in m.)	0.03-0.20	0.21-0.50	0.51-1.00	1.01-2.00	2.01-5.00	> 5.00

				·			
	Dolongan	3.48	1.31	1.01	0.98	0.0096	0
	Del Pilar	66:0	0.64	0.73	0.17	0	0
	Cogon	11.28	1.88	1.16	0.61	1.13	0.047
amar	Catadman	4.35	0.44	0.41	0.38	0.16	0.0023
s in Basey, Sa	Canmanila	0.68	0.14	0.19	0.16	0.0028	0
ed Barangay	Cancaiyas	4.65	0.12	0.09	0.12	0.31	0.18
Affect	Can-Abay	0.5	0.22	0.1	0.064	0.037	0
	Cambayan	1.1	0.078	0.064	0.035	6900.0	0
	Buscada	0.19	0.17	0.27	0.033	0	0
	Burgos	0.5	0.056	0.27	0.66	0.44	0.018
Affected Areas (in	sq.m.) by flood depth (in m.)	0.03-0.20	0.21-0.50	0.51-1.00	1.01-2.00	2.01-5.00	> 5.00

	Manlilinab	13.15	0.46	0.42	0.61	1.02	1.21
	Magallanes	0.72	0.8	0.44	0.021	0	0
	Mabini	0.013	0.0012	0.00011	0.000094	0.0013	0.0059
Samar	гоуо	0.46	0.061	0.043	0.017	0.0003	0
ys in Basey,	Loog	7.21	0.26	0.24	0.77	0.8	0.34
cted Baranga	Lawa-An	0.079	0.044	0.13	0.036	0	0
Affe	Inuntan	3.23	0.13	0.18	0.25	0.22	0.011
	lba	2.87	2.43	2.14	0.19	0	0
	Guirang	13.33	0.56	0.5	0.78	1.92	1.46
	Guintigui- An	0.48	0.59	0.35	0.15	0.0024	0
Affected Areas (in	sq.m.) by flood depth (in m.)	0.03-0.20	0.21-0.50	0.51-1.00	1.01-2.00	2.01-5.00	> 5.00

	Roxas	1.86	0.87	1.21	1.03	0.0027	0
	Pelit	3.95	0.29	0.43	1.04	0.56	0.17
	Panugmonon	0.5	0.3	0.62	0.36	0.0017	0
Samar	РаІаурау	0.069	0.031	0.097	0.016	0	0
ys in Basey,	Old San Agustin	14.04	3.01	2.53	1.2	1.76	0.19
cted Baranga	Nouvelas Occidental	0.56	0.53	0.56	0.15	0.0065	0.16
Affe	New San Agustin	1.4	1.26	1.61	9.0	0.0005	0
		2.05	0.51	0.46	0.089	0.0058	0.0001
	Mercado	0.11	0.05	0.033	0.0062	0	0
	May-It	2.61	0.81	1.12	0.53	0.023	0.0001
Affected Areas (in	sq.m.) by flood depth (in m.)	0.03-0.20	0.21-0.50	0.51-1.00	1.01-2.00	2.01-5.00	> 5.00

ľ										
				Affecte	ed Barangays	s in Basey, Sa	mar			
San /	Antonio	San Fernando	Sawa	Serum	Sugca	Sugponon	Sulod	Tinaogan	Tingib	Villa Aurora
	1.03	4.88	1.88	1.25	1.08	1.13	0.16	0.27	1.41	15.15
	0.17	1.35	0.8	0.9	0.89	0.68	0.063	0.0045	0.56	0.58
	0.19	1.53	0.69	0.3	0.22	0.39	0.083	0.0024	0.73	0.62
	0.095	1.29	0.26	0.019	0.0051	0.23	0.014	0.0009	0.4	1.19
0	.0034	0.28	0.31	0	0	0.14	0	0.0002	0.0056	1.17
	0	0.27	0.0019	0	0	0	0	0	0	0.096



Figure 89. Affected Areas in Basey, Samar during 100-Year Rainfall Return Period



Figure 90. Affected Areas in Basey, Samar during 100-Year Rainfall Return Period



Figure 91. Affected Areas in Basey, Samar during 100-Year Rainfall Return Period



Figure 92. Affected Areas in Basey, Samar during 100-Year Rainfall Return Period



Figure 93. Affected Areas in Basey, Samar during 100-Year Rainfall Return Period

For the municipality of Santa Rita, with an area of 250.371 sq. km., 0.545% will experience flood levels of less 0.20 meters. 0.015% of the area will experience flood levels of 0.21 to 0.50 meters while 0.011%, 0.007%, and 0.005% of the area will experience flood depths of 0.51 to 1 meter, and 1.01 to 2 meters, respectively. Listed in Table 42 are the affected areas in square kilometres by flood depth per barangay.

Affected Areas		Affected Baran	igays in Sant	a Rita, Samar	
(in sq.m.) by flood depth (in m.)	Bagolibas	Cabacungan	Caticugan	Pagsulhogon	San Pedro
0.03-0.20	0.18	0.66	0.0092	0.38	0.14
0.21-0.50	0.0025	0.021	0.0014	0.011	0.0024
0.51-1.00	0.0051	0.013	0.0031	0.0062	0.0007
1.01-2.00	0.0022	0.0069	0.003	0.005	0.0007
2.01-5.00	0.0002	0.0061	0.0007	0.0055	0.0007
> 5.00	0	0	0	0.0002	0.0001

Table 42. Affected Areas in Santa Rita, Samar during 100-Year Rainfall Return Period



Figure 94. Affected Areas in Santa Rita, Samar during 100-Year Rainfall Return Period

Among the barangays in the municipality of Basey, Villa Aurora is projected to have the highest percentage of area that will experience flood levels at 2.996%. Meanwhile, Manlilinab posted the second highest percentage of area that may be affected by flood depths at 2.686%.

Among the barangays in the municipality of Marabut, San Roque is projected to have the highest percentage of area that will experience flood levels at 0.20%.

Among the barangays in the municipality of Santa Rita, Cabacungan is projected to have the highest percentage of area that will experience flood levels at 0.281%. Meanwhile, Pagsulhogon posted the second highest percentage of area that may be affected by flood depths of at 0.162%.

Moreover, the generated flood hazard maps for the Basey Floodplain were used to assess the vulnerability of the educational and medical institutions in the floodplain. Using the flood depth units of PAG-ASA for hazard maps - "Low", "Medium", and "High" - the affected institutions were given their individual assessment for each Flood Hazard Scenario (5 yr, 25 yr, and 100 yr).

	ļ	Area Covered in sq. km	
Warning Level	5 year	25 year	100 year
Low	31.7	33.33	30.35
Medium	21.31	32.16	40.08
High	9.32	15.74	21.50
TOTAL	62.33	81.23	91.93

Table 43. Area covered by each warning level with respect to the rainfall scenario

Of the 23 identified Education Institutions in Basey Floodplain, 4 schools were assessed to be exposed to the Low level flooding during a 5 year scenario while 2 schools were assessed to be exposed to Medium level flooding. In the 25-year scenario, 8 schools were assessed to be exposed to the Low level flooding while 5 schools were assessed to be exposed to Medium level flooding. For the 100-year scenario, 6 schools were assessed for Low level flooding and 8 schools for Medium level flooding. In the same scenario, 2 schools were assessed to be exposed to High level flooding. See Annex 12 for a detailed enumeration of schools inside Basey floodplain.

For the Medical Institution identified in Basey Floodplain namely New San Agustin Health Center, it was assessed to be exposed to the Low level flooding during a 25 year scenario and to be exposed to the Medium level flooding during a 100 year scenario.

5.11 Flood Validation

In order to check and validate the extent of flooding in different river systems, there is a need to perform validation survey work. Field personnel gather secondary data regarding flood occurrence in the area within the major river system in the Philippines.

From the Flood Depth Maps produced by Phil-LiDAR 1 Program, multiple points representing the different flood depths for different scenarios are identified for validation.

The validation personnel went to the specified points identified in a river basin and gathered data regarding the actual flood level in each location. Data gathering can be done through a local DRRM office to obtain maps or situation reports about the past flooding events or interview some residents with knowledge of or have had experienced flooding in a particular area.

After which, the actual data from the field will be compared to the simulated data to assess the accuracy of the Flood Depth Maps produced and to improve on what is needed.

The flood validation consists of 397 points randomly selected all over the Basey floodplain. The points were grouped depending on the RIDF return period of the event.




The RMSE value for each flood depth map is listed in the table below:

Table 44. RMSE values for each return period of flood depth map

Return Period	RMSE
5-year	0.94
100-year	3.25



Figure 97. Flood map depth vs actual flood depth for 5-year return period

Actual	Modeled Flood Depth (m)						
Flood Depth (m)	0-0.20	0.21- 0.50	0.51- 1.00	1.01- 2.00	2.01- 5.00	> 5.00	Total
0.03-0.20	77	17	11	1	0	3	109
0.21-0.50	61	35	7	2	2	0	107
0.51-1.00	27	21	26	0	0	1	75
1.01-2.00	15	6	10	2	2	0	35
2.01-5.00	5	2	0	1	0	0	8
> 5.00	0	0	0	0	0	0	0
Total	185	81	54	6	4	4	334

Table 45. Actual Flood Depth vs Simulated Flood Depth in Basey for 5-year return period

The overall accuracy generated by the flood model is estimated at 41.92%, with 140 points correctly matching the actual flood depths. In addition, there were 119 points estimated one level above and below the correct flood depths while there were 46 points and 29 points estimated two levels above and below, and three or more levels above and below the correct flood. A total of 46 points were overestimated while a total of 148 points were underestimated in the modelled flood depths of Basey.



Figure 98. Flood map depth vs actual flood depth for 100-year return period

Actual	Modeled Flood Depth (m)						
Flood Depth (m)	0-0.20	0.21- 0.50	0.51- 1.00	1.01- 2.00	2.01- 5.00	> 5.00	Total
0.03-0.20	4	2	0	0	0	0	6
0.21-0.50	2	2	3	0	0	0	7
0.51-1.00	1	1	2	0	0	0	4
1.01-2.00	2	3	7	5	0	0	17
2.01-5.00	17	5	4	3	0	0	29
> 5.00	0	0	0	0	0	0	0
Total	26	13	16	8	0	0	63

Table 46. Actual Flood Depth vs Simulated Flood Depth in Basey for 100-year return period

The overall accuracy generated by the flood model is estimated at 20.63%, with 13 points correctly matching the actual flood depths. In addition, there were 18 points estimated one level above and below the correct flood depths while there were 8 points and 24 points estimated two levels above and below, and three or more levels above and below the correct flood. A total of 5 points were overestimated while a total of 45 points were underestimated in the modelled flood depths of Basey.

	No. of Points	%
Correct	140	41.92
Overestimated	46	13.77
Underestimated	148	44.31
Total	334	100

Table 47. Summary of Accuracy Assessment in Basey River Basin Survey

REFERENCES

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ANNEXES

Annex 1. OPTECH Technical Specification



Figure A-1.1 Aquarius Sensor

Table A-1.1 Parameters and Specifications of the Aquarius Sensor

Parameter	Specification		
Operational altitude	300-600 m AGL		
Laser pulse repetition rate	33, 50. 70 kHz		
Scan rate	0-70 Hz		
Scan half-angle	0 to ± 25 °		
Laser footprint on water surface	30-60 cm		
Depth range	0 to > 10 m (for k < 0.1/m)		
Topographic mode			
Operational altitude	300-2500		
Range Capture	Up to 4 range measurements, including 1st, 2nd, 3rd, and last returns		
Intensity capture	12-bit dynamic measurement range		
Position and orientation system	POS AVTM 510 (OEM) includes embedded 72-channel GNSS receiver (GPS and GLONASS)		
Data Storage	Ruggedized removable SSD hard disk (SATA III)		
Power	28 V, 900 W, 35 A		
Image capture	5 MP interline camera (standard); 60 MP full frame (optional)		
Full waveform capture	12-bit Optech IWD-2 Intelligent Waveform Digitizer (optional)		
Dimensions and weight	Sensor:250 x 430 x 320 mm; 30 kg;		
	Control rack: 591 x 485 x 578 mm; 53 kg		
Operating temperature	0-35°C		
Relative humidity	0-95% no-condensing		



Control Rack

Laptop

Figure A-1.2 Gemini Sensor

Parameter	Specification	
Operational envelope (1,2,3,4)	150-4000 m AGL, nominal	
Laser wavelength	1064 nm	
Horizontal accuracy (2)	1/5,500 x altitude, (m AGL)	
Elevation accuracy (2)	<5-35 cm, 1 σ	
Effective laser repetition rate	Programmable, 33-167 kHz	
Position and orientation system	POS AV™ AP50 (OEM); 220-channel dual frequency GPS/GNSS/Galileo/L-Band receiver	
Scan width (WOV)	Programmable, 0-50°	
Scan frequency (5)	Programmable, 0-70 Hz (effective)	
Sensor scan product	1000 maximum	
Beam divergence	Dual divergence: 0.25 mrad (1/e) and 0.8 mrad (1/e), nominal	
Roll compensation	Programmable, ±5° (FOV dependent)	
Range capture	Up to 4 range measurements, including 1st, 2nd, 3rd, and last returns	
Intensity capture	Up to 4 intensity returns for each pulse, including last (12 bit)	
Video Camera	Internal video camera (NTSC or PAL)	
Image capture	Compatible with full Optech camera line (optional)	
Full waveform capture	12-bit Optech IWD-2 Intelligent Waveform Digitizer (optional)	
Data storage	Removable solid state disk SSD (SATA II)	
Power requirements	28 V; 900 W;35 A(peak)	
Dimensions and weight	Sensor: 260 mm (w) x 190 mm (l) x 570 mm (h); 23 kg Control rack: 650 mm (w) x 590 mm (l) x 530 mm (h); 53 kg	
Operating temperature	-10°C to +35°C (with insulating jacket)	
Relative humidity	0-95% no-condensing	

Annex 2. NAMRIA Certificates of Reference Points Used



SMR-56

From Tacloban City, travel about 15 km. north going to Brgy, Cabacungan. Before reaching the of Sta. Rita town proper Western Samar. The monument was established at the Brgy. Cabacungan Elementary School, at the side of the road, 20 m. east fronting school's entrance gate, 50 m. northeast from Waiting Shed about, and 3 m. east along the side the of pathway. Mark is the head of a 4" copper nail flushed in a 30X30 cm. cement block embedded in the ground protruding about 20 cm., with inscriptions "SMR-56; 2007; NAMRIA."

Pupose: OR Number: T.N.:

Requesting Party: Engr. Christopher Cruz/ UP-DREAM Reference 8796021 A 2014-919

RUEL DM. BELEN, MNSA Director Mapping And Geodesy Branch 5





NAMES OFFICER Marris Carrier, Fast Bonnes St. San Nacker, 1018 Marris, Philippines, Tal. No.: (632) 810-4601 to 41 Descrit - 421 Bonnes St. San Nacker, 1018 Marris, Philippines, Tal. No. (632) 201-3494 to 38 www.namria.gov.ph

ISO 9011: 2008 CERTIFIED FOR HIMPPING AND GEOSPICTIVE INFORMATION MANAGEMENT

Figure 2.1 LYT-101



April 23, 2014

CERTIFICATION

To whom it may concern:

This is to certify that according to the records on file in this office, the requested survey information is as follows -

F	rovince: SAMAR (WEST	ERN SAMAR)		
	Station Name: SM	/IR-56		
Island: VISAYAS	Order: 2nd	Baran	gay: CAB	ACUNGAN
Municipality: SANTA RITA	PRS92 Coon	dinates		
Latitude: 11º 23' 6.52702"	Longitude: 125° 0	" 23.99607" Ellipse	oidal Hgt:	11.82200 m.
	WGS84 Coor	dinates		
Latitude: 11" 23' 2.22413"	Longitude: 125° 0	" 29.13917" Ellipse	oidal Hgt:	73.72700 m.
	PTM Coord	inates		
Northing: 1258927.861 m.	Easting: 500723	7.475 m. Zone:	5	
	UTM Coord	linates		
Northing: 1,259,244.38	Easting: 718,97	0.61 Zone:	51	

SMR-56

Location Description

SMR-56 From Tacloban City, travel about 15 km, north going to Brgy, Cabacungan. Before reaching the of Sta. Rita town proper Western Samar. The monument was established at the Brgy. Cabacungan Elementary School, at the side of the road, 20 m, east fronting school's entrance gate, 50 m, northeast from Waiting Shed about, and 3 m, east along the side the of pathway. Mark is the head of a 4" copper nail flushed in a 30X30 cm, cement block embedded in the ground protruding about 20 cm., with inscriptions "SMR-56; 2007; NAMRIA."

Requesting Party: Engr. Christopher Cruz/ UP-DREAM Reference Pupose: 8796021 A OR Number: T.N.: 2014-919

RUEL DM. BELEN, MNSA Director Mapping And Geodesy Branch 6





NAMES OFFICER Marri Lawler Artenie, Fait Bostlaco, 1094 Tagalg Gry, Philippines, Tal. No. (602) 810-4631 to 41 Darich - 421 Benera St. San Nodau, 1018 Marila, Philippines, Tal. No. (602) 201-366 to 48 www.namria.gov.ph

ISO 9011: 2008 CERTIFIED FOR IM/PING AND GEOSPICIAL INFORMATION MANAGEMENT

Figure 2.2 SMR-56



Experience of the Processes Department of East Sources and Natural Sections: NATIONAL MAPPING AND RESOURCE INFORMATION AUTHORITY

February 10, 2018

CERTIFICATION

To whom it may concern:

This is to certify that according to the records on file in this office, the requested survey information is as follows -

4	TOWINGS: SAMAR (WESTERN SAMAR)			
	Station Name: SMR-58			
	Order: 2nd			
Island, VISAYAS Municipa Iy: BASEY	Barangay. SERUM MSL Elevation: PRS92 Coordinates			
Latitude: 11º 17' 55.05617"	Longilude: 125° 7' 51.16145"	Ellipsoidal	Hgt:	6.30062 m.
	WGS84 Coordinates			
Latit.de: 11º 17' 50.78580"	Longit.da: 125' 7' 56.31100"	Ellipsoida	Hgt:	68.72300 m.
	PTIA / PRS92 Coundinates			
No thing. 1249361.531 m.	Easling. 614288.239 m.	Zona:	6	
	UTM / PRS92 Coordinates			
No:thing: 1,249,788.75	Eesting: 732,608.57	Zona:	51	

Location Description

SMR ES

Front Basey proper, I travel about 20 km, north going to Brgy. Serum, From National Road, travel another 1 km, north going to Brgy, Serum. The NAMRIA was established inside the Serum Elementary School, 10 m, east from the achool gate, and 15 m, north from the achool building. The School site was near the River about 30 m, north, Mark is the head of a 4° copper nail flusted in a 30X30 cm, cement block embedded in the ground protocting acout 20 cm, with inscriptions "SMR 08; 2007; NAMRIA."

Requesting Party:	UP DREAM
Purpose.	Reference
OR Number:	80897741
T.N.:	2016-0327
T.N.:	2016-0327

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RUEL OM BELEN, MNSA Director Mapping And Geodesy Branch 6





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ISO ROLL 2010 CERTIFICA FOR WARRING AND SUSSEMINAL INTO SWATION MANAGEMENT

Figure 2.3 SMR-58



Republic of the Philippines Department of Environment and Natural Resources NATIONAL MAPPING AND RESOURCE INFORMATION AUTHORITY

January 27, 2016

CERTIFICATION

To whom it may concern:

This is to certify that according to the records on file in this office, the requested survey information is as follows -

	Province: LEYTE Station Name: LY-110	
Island: Visayas	Municipality: PALO	Barangey: LIBERTAD
Elevation: 12.9339 +/- 0.03 m.	Order: 1st Order	Datum: Mean Sea Level
Lattude:	Longhude:	

Location Description

LY-110

Is in the Province of Leyte, Municipality of Palo, Brgy, Libertad, it is about 225m West of km post 919, 4.15 North of Contentine of the read leading to Ormoe, at the Northwest and of a 42.0m long bridge. A 24 minutes drive from Tacloban City going to South to Ormoc on a bridge located about 225 meters of km post 919. Mark is a 4" copper nail, drilled on hole on top of concrete footwalk at the top of culvert headwall and cemented flush with inscription "LY-110 2007 NAMRIA".

Requesting Party:	UP DREA
Purpose:	Reference
OR Number:	0009637 I
T.N.:	2016-0240

M e ۵

RUEL DM/BELEN, MNSA Director, Mapping And Gleodesy Branch





RANKA OFFICE Minis Laboration Fundaminate, 104 Tagung Oly, Melgorine . Tet Ma. (802) 175-4011 to 41 Jonneh: 421 Deness St. Jan Hildeler, 1910 Manila, Philogenes, Tet Ma. (823) 251-3404 to 59 www.samria.gov.ph

SO SOIL 2NECERTIFIED FOR INVPING WID GEDERATIAL INFORMATION MAINCEMENT

Figure 2.4 LY-110





NAMMA OFFICES: Mole: Lawler Avenue, For Bosteck, 1834 Taguig City, Philippines – Tel. No. : (522) 813-4531 to 41 Baach : 421 Banach St. San Nicolas, 1910 Manila, Philippines, Tel. No. (522) 241-3454 to 85 www.namria.gov.ph

ISO 9001: 2008 CERTIFIED FOR MARPING AND GEOSPATIAL INFORMATION MANAGEMENT

Figure 2.5 SM-286



Figure 2.6 SM-309

Annex 3. Baseline Processing Report of Reference Point Used

Observation	From	То	Solution Type	H. Prec. (Meter)	V. Prec. (Meter)	Geodetic Az	Ellipsoid Dist. (Meter)	∆Height (Meter)		
SMR-53 LYT-104 (B1)	SMR-53	LYT-104	Fixed	0.008	0.017	200°40'31"	42653.401	7.525		
SMR-53 LYT-104 (B2)	SMR-53	LYT-104	Fixed	0.004	0.016	200°40'31"	42653.384	7.601		

Processing Summary

Acceptance Summary									
Processed	Passed	Flag	P	Fail	•				
2	2	0		0					

Vector Components (Mark to Mark)

From:	SMR-53						
	Grid		Local	Global			
Easting	720874.133 m	Latitude	N11°30'17.85656"	Latitude		N11°30'13.52495"	
Northing	1272513.396 m	Longitude	E125°01'29.83738"	Longitude		E125°01'34.96980"	
Elevation	24.750 m	Height	26.134 m	Height		87.787 m	
To:	LYT-104						
Grid			Global				
Easting	706089.510 m	Latitude	N11°08'38.92234"	Latitude		N11°08'34.67033"	
Northing	1232496.838 m	Longitude	E124°53'13.52786"	Longitude		E124°53'18.69323	
Elevation	32.311 m	Height 33.659 m		Height		95.861 m	
Vector					5		
ΔEasting	-14784.62	3 m NS Fwd Azim	nuth	200°40'31"	ΔX	7839.600 m	
ΔNorthing	-40016.55	8 m Ellipsoid Dist		42653.401 m	ΔY	15051.644 m	
∆Elevation	7.56	61 m ∆Height		7.525 m ΔZ		-39131.928 m	

Standard Errors

Vector errors:	36 (6)		00	2	
σ ΔEasting	0.003 m	σ NS fwd Azimuth	0°00'00"	σΔΧ	0.006 m
σ ΔNorthing	0.002 m	σ Ellipsoid Dist.	0.002 m	σΔΥ	0.007 m
σ ΔElevation	0.009 m	σ ΔHeight	0.009 m	σΔΖ	0.002 m

Figure 3.1 LYT-104

Processing Summary

Observation	From	То	Solution Type	H. Prec. (Meter)	V. Prec. (Meter)	Geodetic Az.	Ellipsoid Dist. (Meter)	∆Height (Meter)
LYT 104 LY 110 (B1)	LYT 104	LY 110	Fixed	0.004	0.013	68°33'52"	8457.064	-19.323
LY 110 LYT 104 (B2)	LYT 104	LY 110	Fixed	0.004	0.015	68°33'52"	8457.047	-19.343

Acceptance Summary

Processed	Passed	Flag	Þ	Fail	•
2	2	0		0	

Vector Components (Mark to Mark)

From:	LYT 104						
	Grid		Local		Global		
Easting	706089.510 m	Latitud	le N11°08	3'38.92234"	Latitude		N11°08'34.67033"
Northing	1232496.838 m	Longitu	ude E124°53	13.52786*	Longitude		E124°53'18.69323"
Elevation	32.311 m	Height		33.659 m	Height		95.861 m
Grid			Local		Global		
	Grid		Local		Global		
Easting	713942.863 m	Latitud	le N11°10'	19.48389"	Latitude		N11°10'15.23095"
Northing	1235638.117 m	Longitu	ude E124°57	32.98736"	Longitude		E124°57'38.14961"
Elevation	12.819 m	Height		14.336 m	Height		76.647 m
Vector							
∆Easting	7853.35	3 m NS	S Fwd Azimuth		68°33'52"	ΔX	-6101.546 m
∆Northing	3141.27	9 m El	9 m Ellipsoid Dist.		8457.064 m	ΔΥ	-5012.598 m

Standard Errors

∆Elevation

Vector errors:									
σ ΔEasting	0.002 m	σ NS fwd Azimuth	0°00'00*	σΔΧ	0.004 m				
σ ΔNorthing	0.001 m	σ Ellipsoid Dist.	0.002 m	σΔΥ	0.005 m				
σ ΔElevation	0.007 m	σΔHeight	0.007 m	σΔΖ	0.002 m				

-19.323 m ΔZ

3027.816 m

-19.492 m AHeight

Figure 3.2 LYT-110

Baseline Processing Report

Observation	From	То	Occupation Start Time	Occupatio n Stop Time	Solutio n T∮pe	H. Prec. (Meter)	V. Prec. (Meter)	ΔX (Meter)	ΔY (Meter)	ΔZ (Meter)	Geodeti c Az.	Ellipsoi d Dist. (Meter)	∆ Height (Meter)	Satellit e Availat le
SM-286 SMR-56 (B1)	SMR-56	SM-286	6/11/2014 6:44:03 AM	5/11/2014 1:54:43 Рм	Fixed	0.003	0.009	1325.0 25	263.51 2	2667.2 92	335"34 25"	2989.9 04	-6.335	GPS: 14 GLONA SS: 13 Galileo: 0 QZSS: 0

Processing Summary

Acceptance Summary

Processed	Passed	Flag 📔	F	Fail	7
1	1	0		0	

Vector Components (Mark to Mark)

From:	SMR-56						
	Grid		Local	Global			
Easting	718970.608 m	Latitude	N11°23'06.52702"	Latitude		N11°23'02.22413"	
Northing	1259244.377 m	Longitude	E125°00'23.99607"	Longitude		E125°00'29.13917"	
Elevation	10.345 m	Height	11.822 m	Height		73.727 m	
To:	SM-286						
	Grid		Global				
Easting	717715.152 m	Latitude	N11°24'35.12705"	Latitude		N11°24'30.81697"	
Northing	1261958.553 m	Longitude	E124°59'43.21146"	Longitude		E124°59'48.35252"	
Elevation	4.047 m	Height	5.488 m	Height		67.304 m	
Vector							
ΔEasting	-1255.45	6 m NS Fwd Azimu	.th	335°34'25"	ΔX	1325.020 m	
∆Northing	2714.17	6 m Ellipsoid Dist.		2989.904 m	ΔY	263.518 m	
∆Elevation [-6.29	8 m ΔHeight		-6.335 m	ΔZ	2667.293 m	

Standard Errors

Vector errors:	da da	5	00	(8)	
σ ΔEasting	0.001 m	σ NS fwd Azimuth	0°00'00"	σΔΧ	0.003 m
σ ΔNorthing	0.001 m	σ Ellipsoid Dist.	0.001 m	σΔΥ	0.004 m
σ ΔElevation	0.005 m	σΔHeight	0.005 m	σΔΖ	0.001 m

Figure 3.3 SM-286

Figure A 3.4 SM-309

Processing	Summary
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Observation	From	То	Solution Type	H. Prec. (Meter)	V. Prec. (Meter)	Geodetic Az.	Ellipsoid Dist. (Meter)	∆Height (Meter)
SMR-58 SM-309 (B1)	SMR-58	SM-309	Fixed	0.002	0.003	274°29'25"	1668.981	3.442

Accep	tance	Sum	marv

Processed	Passed	Flag 📔	Fail 🟲
1	1	0	0

Vector Components (Mark to Mark)

From:	SMR-58					
	Grid	Le	xal		G	ilobal
Easting	732600.670 m	Latitude	N1111755.05616*	Latitude		N11*17'50.78580*
Northing	1249768.751 m	Longitude	E125°07'51.16148*	Longitude		E125°07'56.31100"
Elevation	4.664 m	Height	6.301 m	Height		68.723 m
Τα:	SM-309	22				
	Grid	Lo	scal		C	Nobal
Easting	730935.362 m	Latitude	N1111759.30748	Latitude		N11*17*55.03553*
Northing	1249887.315 m	Longitude	E125*06'56.29744*	Longitude		E126*07'01.44700*
Elevation	8.117 m	Height	9.743 m	Height		72.125 m
Vector						
∆Easting	-1665.20	7 m NS Fwd Azimuth		274°29'25"	ΔX	1373.678 m
∆Northing	118.56	4 m Ellipsoid Dist.		1668.981 m	ΔY	939.122 m
AElevation	3.45	3 m AHeight		3.442 m	ΔZ	128.718 m

Standard Errors					
Vector errors:					8
σ ΔEasting	0.001 m	o NS fwd Azimuth	0100/001	σΔΧ	0.001 m
σ ∆Northing	0.001 m	σ Ellipsoid Dist.	0.001 m	σΔΥ	0.001 m
σ ΔElevation	0.002 m	σ ΔHeight	0.002 m	σΔΖ	0.001 m

Figure 3.4 SM-309

Annex 4. The Survey Team

Data Acquisition Component Sub-Team	Designation	Name	Agency/ Affiliation
PHIL-LIDAR 1	Program Leader	ENRICO C. PARINGIT, D.ENG	UP-TCAGP
Data Acquisition Component Leader	Data Component Project Leader – I	ENGR. CZAR JAKIRI SARMIENTO	UP-TCAGP
	Chief Science Research Specialist (CSRS)	ENGR. CHRISTOPHER CRUZ	UP-TCAGP
Survey Supervisor	Supervising Science Research Specialist (Supervising SRS)	ENGR. LOVELYN ASUNCION	UP-TCAGP
	FIELD	TEAM	
	Supervising SRS	LOVELY GRACIA ACUÑA	UP-TCAGP
		JULIE PEARL MARS	UP-TCAGP
	Senior Science Research	ENGR. GEROME HIPOLITO	UP-TCAGP
	Specialist (SSNS)	PAULINE JOANNE ARCEO	UP-TCAGP
LiDAR Operation		ENGR. DAN CHRISTOFFER ALDOVINO	UP-TCAGP
		FAITH JOY SABLE	UP-TCAGP
	Research Associate (RA)	MARY CATHERINE ELIZABETH BALIGUAS	UP-TCAGP
		ENGR. IRO NIEL ROXAS	UP-TCAGP
		ENGR. LARAH KRISELLE PARAGAS	UP-TCAGP
		GRACE SINADJAN	UP-TCAGP
		JONATHAN ALMALVEZ	UP-TCAGP
Ground Survey, Data Download and Transfer	RA	JERIEL PAUL ALAMBAN, GEOL.	UP-TCAGP
	Airborne Security	SSG. RAYMUND DOMINE	PHILIPPINE AIR FORCE (PAF)
		SSG. RANDY SISON	PAF
LiDAR Operation		CAPT. JACKSON JAVIER	ASIAN AEROSPACE CORPORATION (AAC)
	Pilot	CAPT. NEIL ACHILLES AGAWIN	AAC
		CAPT. ALBERT PAUL LIM	AAC
		CAPT. RANDY LAGCO	AAC

	Table 4.1 LiDAR	Survey Team	Composition
--	-----------------	-------------	-------------

11		8	24	44	44	25	2'4						1 10000
	SERVES	LOCATIO	X:Mitborra Raw/1016	XcMebom Rewriton8	ACHARDON Rewin 220	XUNIDOT Rewit (22	X:MIDOT						
	PLAN	KML	BUKB	SASKE	1.21KB	Brake	652KB						
	FLIGHT	Actual	A 65KB	12143	1208	1200	6.72KB						
	CHERNOR	(001/40)	897		308	25KB	668						
	(sho	ne helo (140)	6	14	80		458 44						
	BASE STAT	EARS Di	ANB 24	AMB 24	The 2	MIS 20	MB 2			-			
		N NICEN	14 10 14	14	8	258 20	108 20			100/20/20			
		a mone	GB 00	QB 12	32	GB 57	GB 48.			25			
			- BB	2.81	12:	181	101	7		A PAIR			
2014	-	WADES	NN B	NN.	NN 0	B NA	VIN D		ived by	JO 10			
Feb 3	-	22	41.20	NA	67.76	1 75.30	20100		Race	Post			
	-	2	1.56 UB	81MB	23746	242MB	34746						
	-	ğ	EXER	147942	1.80MB	1 28%	aver 1						
	SAWLAS	AS KM	56.50	69,643	11958	815KB	GROKE						
		Output 1	- EX	NA	YN	N.N.	-			W5			
		SENSOR	ADUARLUS	ACLURING	ACLARIUS	ACCARCING	a line in the			laktur			
		MISSION NAME	SOL KTYLKTOKA	The COLLOCATION INC.	THE CORNERS	Commences into	1000		Received from	Name Laro			
		FLIGHT NO.	19403	74440	Value	TUEUR .							
		DATE			00 26, 2014	81 25, 2014	80.20.2014						

Figure 5.1 Data Transfer Sheet for Basey Floodplain - A

Annex 5. Data Transfer Sheet for Basey Floodplain

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Figure 5.3 Data Transfer Sheet for Basey Floodplain - C

and the second se			MPL I	W145				Interesting to the			TALING IN	Colectory.	OPERATOR.	HOLD	PLAN	
SER MARKED SER	Se M	E I	Owners LAS	Net, postel	rossivel	No.	IN NOTICE CASE	FILENDAR	AV10	and the	6141104(5)	data internet	HICT LACE	Actual	-	SCRATRA LOCATION
33DCIEV/00354 M010	MUL	3	2	25	8	624	ž	MA	29.62	W	18.0	108	103	-92	2	E-DMORUCK DADA
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SBUCKARDOSA ADUM	MUCH	S	W	ŝ	E	R	ă	12	11.1	242	1.40	test.	INI		ź	ZYDACIAME DATA
MUCK ACHORIDIZATION	NICH	12	XX	5	R	8	14.	1	1999	4	1996	101	1626	20	NN.	PURCHAM DATA
TRUESCOCO604000 AccuM	NUM	1	ź	111	22	-	W	N.	0.98	105	10.00	RM	0.41	2002	ž	2:000FMM
JBUEJSFNORLA ACUM	ACUM	8	ž	202	60	82	ž	2	11.0	2	2.45	(MD	16.0	311	MA	LICHCHANN DATA
TRUCTSTANDATA AGues	NOW	212	2	962	282	-	ž	2	11.0	8	10.00	169	185	4	N	2100407/00000
38UK34AW044A MOUNU	MUDH	8	N.	-	10	-	ž	2	111	101	21.4	140	183	н	N.	Z-DAC-66W DATA
SBUCKSWORK NOW	NUM	10	2	Ň	8	5	-	NN	1610	121	in.e	1620	1601	φ	£	ZYDMCHUM DATA
391/05X 3048A Agua	WIN	See.	N.N.	181	e.	8	101	NH.	6.5	101	10	160	-		2	2-LINDRAW Data
Received from							Faceford by									
エアのビアフトノーを見	TURNER	4					Name Pr	Terrant								

Figure 5.4 Data Transfer Sheet for Basey Floodplain - D

153

DATA TRANSFER SHEET Leyte 2/11/16

WEAR NAM			1		OPERATO 1	No. of Manager, No. of Manager		A Print Land
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200 La	8	23.0	18	855 1KB	606	an	E.	Z-IDNORMW DATA
212 ra	Z	20.3	ED .	9.2 1KB	BM1	57.02	g	Z1DACIENNI DATA
248 ro	2	10.8	80	4.74 tKB	94	27/25/59	a	Z-IDACIRAW DATA
212	2 2	20 00 10 10	ra ra 20.3 ra ra 16.8	ra 20.3 Fa ra ra 10.8 ra	ra ra 20.3 ra 9.2 H/B ra ra 10.8 ra 4.74 H/B	ra na 20.3 ra 9.2 1KB 148 na 16.8 ra 4.14 1KB 140	ra ra 20.3 ra 9.2 1KB 14B 57.02 ra ra 16.8 ra 4.74 1KB 14B 27.0359	ra ra 20.3 ra 9.2 H/B 149 57.22 ra ra 10.8 ra 4.74 H/B 140 27.2516 ra

Received from

MILOGOL . D

2 C Bona

2/12/12 Receiv



	LOCATION	Z3DACIBAWI DATA	Z-IDAGIBAW DATA	ZYDACIBAW DATA	ZYDACURAW	Z:IDACHUMN DATA	ZIDACIRAW DATA	
DLAN	KINL	NA	NA	NA	NA	NA	NIA	
PLICENT	Actual	206	200	2002001594	238/210/210	2504510250	378	
	LOSS LOSS	110	tion .	193	103	143	1KB	
ATTEND	Base Info	1KB	1KB	1KB	1KB	tka	193	
NAME OF	BARE	4.2	608	3.19	3.84	4.1	4.61	
	DIGITURE	NA	NK	NA	NN	MA	YN.	relity
	RANDE	22.8	20.3	242	11.4	162	10.2	L t
	FILE/CASI	N.	N.	12	W	NA	NN	Por State
	RAW MAGESICAGE	MA	NA	NA	NA	N	N.	Received by Name AC Processon Signature
	POS	243	243	200	112	122	177	
	LOGS[MB]	1453	0.97	KA	103	712	483	
	LAS KIII (swath)	322	562	20	648	659	772	
	Contrast AN	NK	NK	NK	12	NN	2	
	SENSOR	GEMNI	GEMNI	GEMNA	GUNN	GENIN	GEMINI	Purit
	MISSION NAME	26UC34U0258	A0E0LHAEULBS	28LH34LM030B	2BUK33ABLK34L031A	28.034633480364	2845346037A	Nacting tom
	FUGHT NO.	37276	17293	57530	37336	37536	37576	
	ATE	29-Jan	30-Jan	30-Jan	St-Jan	6-Feb	0-Feb	

Figure 5.6 Data Transfer Sheet for Basey Floodplain - F

Image: State of the state o	LIDAR Operator: DV AddWD Pilot: 8 Co-1	2 ALTM Model: AUNU 3 Mission 1 10t: 9 Route:	Name: 302, 33, 94 & 29 4 Type: VFR	5 Aircraft Type: Cesnna T206H	6 Alrcraft Identification: PCGVV
Otenaris: Use of dat 1/4 forein on fu carb add Use of dat 1/4 forein on fu carb add Use of dat 1/4 forein on fu carb add Intervention: Intervention: Intervention:	0 Date: J.M. 78, 764 3 Engine On: IV (232 0)	the Nipor of Departure (Nipor, UN)	phe Time: 16 Take off:	17 Landing:	18 Total Flight Time:
12 Problems and Solution: 12 Problems and Prob	0 Remarks: cut	due to terraria on It	a cast side		
Advision flight Approved by Aquision flight Approved by Aq	21 Problems and Solutions:				
	Acquisition Flight Approved b Acquisition Flight Approved b CERLINE Suppliere over Printed Name Signature over Printed Name Signature	Acquisition Flight Cert Recommendation Signature over Printee (PAP Representative)	Ind by Pilot-in Comm	and Printed Name	idar Operator



Pilot: J. Jahnenk Bizontilter 0 1000: J. Jahnenk Bizontilter J. J. Aliport of Coperatine (Aliport, City/Province); 13 Engine On: 1000: J. J. Aliport of Coperatine (Aliport, City/Province); J. Aliport of Anival (Aliport, City/Province); 13 Engine On: 1000: J. Engine On: J. Aliport of Coperatine (Aliport, City/Province); J. Aliport of Anival (Aliport, City/Province); 13 Engine On: J. Engine On: J. Engine On: J. Engine On: J. Engine On: 14 Engine On: Long Ora Dark Fill (Alit Time: J. Engine J. Engine 15 Engine On: Long Ora Dark Fill (Alit Time: J. Engine J. Engine 16 Engine On: Long Ora Dark Fill (Alit Time: J. Engine J. Engine 17 Engine Time: J. Engine Dark Fill (Alit Time: J. Engine J. Engine 18 Engine Time: J. Engine Dark Fill (Alit Time: J. Engine 18 Engine Time: J. Engine J. Engine J. Engine 19 Engine Market Fill (Alit) P. Engine J. Engine 20 Engine Market Engine Market Engine J. Engine 21 Engine Market Engine J. Engine J. Engine	1 LIDAR Operator: NINKOC	9 2	ALTM Model: PRUM	3 Mission Name: Abuilthor	PI24A 4 Type: VFR	5 Aircraft Type: Cesnna T206H	6 Aircraft Identification:
100 lot: March 4, sult 12 Alliport of Animal (Aliport of Chylinovince); 12 Alliport of Animal (Aliport, Chylinovince); 13 Engine On: 100 lot: 100 lot: 100 lot: 100 lot: 100 lot: 13 Engine On: 100 lot: 100 lot: 100 lot: 100 lot: 100 lot: 10 We alter One of the sult 0 more 100 lot: 100 lot: 100 lot: 0.0 Meanuk: One of the sult 0 more 100 lot: 100 lot: 100 lot: 0.0 Remarks: One of the sult 0 more 100 lot: 100 lot: 100 lot: 0.0 Remarks: One of the sult 0 more 100 lot: 100 lot: 100 lot: 0.0 Remarks: One of the sult 0 more 100 lot: 100 lot: 100 lot: 0.0 Remarks: One of the sult 0 more 100 lot: 100 lot: 100 lot: 0.0 Remarks: One of the sult 0 more 100 lot: 100 lot: 100 lot: 0.0 Remarks: 0 more 100 lot: 100 lot: 100 lot: 100 lot: 0.0 Remarks: 0 more 100 lot: 100 lot: 100 lot: 100 lot: 0.0 Remarks: 0 more 0 more 100 lot: 100 lot: 100 lot:	7 Pilot: J. JAVIER	8 Co-Pilo	t: N. AGRININ	9 Route:		remains descentions on difference on the	
Jéregine Oi: Jéregine Oi: Jánding: Jánding: Jánding: Jánding: Jánding: 9 Weather	10 Date: MAY 4, A	bid I	2 Airport of Departure	(Airport, Gty/Province):	12 Airport of Arrival	(Airport, Gty/Province):	
13 Woather 20 Remarks: Completed: Less Frlight par aquaritie over gureg area put shill (g live) 11 Problems and Solutions: 12 Problems and Solutions: 12 Problems and Solutions: 13 Problems and Solutions: 14 Problems and Solutions: 14 Problems and Solutions: 14 Problems and Solutions: 15 Problems and Solutions: 16 Problems and Solutions: 17 Problems and Solutions: 18 Problems an	13 Engine On: 1050	14 Engin	e Off: 1409	15 Total Engine Time: 3 + 11	16 Take off:	17 Landing:	18 Total Flight Time:
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Complete line register per equarite over gureg oren pue self of fixe)	20 Remarks:						
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					Dist	D aster Risk and Exposure Assessr	R E A M



1 LIDAR Operator: [10 hext	75 2 ALTM Model: M6uMRUy	3 Mission Name: 28LK34	osphord Type: VFR	5 Aircraft Type: Cesnna T206H	6 Almraft Identification biol
7 Pilot: J. JAVIER 80	CO-Pilot: N. AGRUN	9 Route:		10000 attentions and a second of	
10 Date: MAN 10, 20 H	12 Airport of Departure	(Airport, Gty/Province):	12 Airport of Arrival	(Airport, Gty/Province):	
13 Engine On: اور 14	Engine Off: Logo	15 Total Engine Time: 3494 Bhill and	16 Take off:	17 Landing:	18 Total Flight Time:
19 Weather					
20 Remarks:		Completed Is lines	over BUC34P		
21 Problems and Solutions:					
Acquisition Flight Approved March Control HIP OLL Signature over Printed Nam (End User Representative)	tby Acquist	ion Flight Certified by UGEON 4 UDI UTTOU (Jan e over Printed Name presentative)	Pilot-in-Comman	of U	lar Operator
			Disa	D Ster Risk and Exposure Assessn	R E A M
		Figure 6.5 Flight Log	for Mission 1440	A	

1 UDAR Operator: ILO RoxAS	2 ALTM Model: AQUANUCK	3 Mission Name: 3 Buk &	SISIA 4 Type: VFR	5 Aircraft Type: Cesnna T206H	6 Aircraft Identification.	N
7 Pilot: J.J. ONIER 8 CO-	Pilot: N. MANUN	9 Route:		1007 i Billion and i Manna	o Alloan Identification:	HEGI22
10 Date: MAY 11, 2014	12 Airport of Departure (Airport, Gty/Province):	12 Airport of Arrival	(Airport, Gty/Province):		
13 Engine On: 14 En	gine Off: [2.09]	15 Total Engine Time: 4 + 41	16 Take off:	17 Landing:	18 Total Flight Time:	
19 Weather						
20 Remarks:						
	(D mpl	otel 15/21 fine o	roy alksy a			
		2 lines trom	buk 34th			
21 Problems and Solutions:						
		1				
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(End User Representative)	(PAF Repr	resentative)		Starting variate	insture over Printed Name	
				1000		(
			Disas	D ster Risk and Exposure Assessm	R E A M	
		Figure 6.6 Flight L	og for Mission 14	42A		



Onte::::::::::::::::::::::::::::::::::::	Pilot: L. dwtee	Stry of	2 ALTM Model: PO	OPhus 3 Mission Name: 3buk 34 &	Sibo 4 Type: VFR	S Aircraft Type: Cesnna T206	6 Aircraft Identification: 28- ar 20
Mikel All Indial All Indial All Renards Indial All Indial All Indial All Renards Indial All Indial All Indial All Neether Indial All Indial All Indial All And All Indial All Indial All Indial All And All Indial All Indial All Indial All	CONTRACT OF CONTRACT	4-00.8	HOLE N. ABACIN	9 Route:			IN ISON
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Wester Remerks: Remerks: Remerks: Proprieted in bill in will ow ble it in intervention in the intervention interventinterventinterventintervention intervention intervention inter	Engine On: Q: 0U	14 Eng	tine Off: 11:23	15 Total Engine Time: 24-7-2	16 Take off:	17 Landing:	18 Total Flight Time:
Arments: Indicate and Solutions: Indicate and Solutions: Indicate Anony Anti-Anti-Anti-Anti-Anti-Anti-Anti-Anti-	Weather			0			
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Disaster Risk and Exposure Assessment for Mitigation						Ì	(
					Disa	Ster Risk and Exposure Assess	R E A M

Figure 6.8 Flight Log for Mission 1450A

10 Date: MAY 13, 2014 12 Airport of Departu 13 Engine On: 1413 George 14 1413 George 14 10 Remarks: Completed 6/	ire (Niport, Oty/Province): 15 Total Engine Time: 2009-09 3453 19 linus lefel on BLK348.	12 Airport of Arrival (, 16 Take off: Goundrad in Tau	Airport. Giy/Province): 17 Landing: airzacpt's temperature.	18 Total Flight Time:
13 Engine On: 13 Engine On: 14 Engine Off: 14 Engine Off: 15 Off 16 Off 16 Off 17 Engine Off: 16 Off 17 Engine Off: 17 Engine Off: 17 Engine Off: 18 Engine Off:	15 Total Engine Times: 15 Total Engine Times: 2009.000 3.453 19 linus left own Bilkithis. 19 linus left own Bilkithis.	12 Airport of Arrival () 16 Take off: Geunkergel in The	Nirport City/Province): 17 Landing: airzaspt's keupentur.	18 Total Flight Time:
^{3 Engine On:} ^{3 Engine On:} ^{9 Weather} ^{0 Remarks:} ⁶ Missier, de	15 Total Engine Time: 2009033353 19 lipus lefts on Blk348. Borted due ta problem an	16 Take off: Counteral in The	17 Landing: aircrapt's keupentur.	18 Total Flight Time:
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o Remarks: . Complefed 6/	19 lives hepbourn Bilkigha. Borted alve to problem an	counterd in the	aircapt's temperatur.	
Milssien. de	norted also to problem an	countered in the	aircrapt's keupentur.	
21 Problems and Solutions:				
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		Disast	er Risk and Exposure Assessm	K E A IVI

Figure 6.9 Flight Log for Mission 1452A

PHIL-LIDAR 1 Data Acquisition Flight Log	Flight Log No.: 77	3
1 LIDAR OPERATOR: LK PRINTINGS 2 ALTM Model: ATC 3 Mission Name: 38/k 34/X 4 Type: VFR 5 Aircraft Type:	cesnna1206H 6 Aircraft Identification: 7322	
7 Pilot: Apgre A acornio: // UGAPAP 2 anone. 12 Airport of Arrival (Airport, City/Province): 12 Airport of Arrival (Airport, City/Province): 12 Airport of Arrival (Airport, City/Province): 0.2 - 7 - 1 - 5 - 7 - 1 - 5 - 7 - 1 - 5 - 7 - 6 - 5 - 7 - 6 - 5 - 7 - 6 - 5 - 7 - 7 - 7 - 7 - 7 - 7 - 7 - 7 - 7	nce):	
13 Engine On: $6 + 40$ 14 Engine Off: 703 15 Total Engine Time: 16 Take off: 17 Landing: $70 + 5$	9 18 Total Flight Time:	
19 Weather Fair & Windy		
20 Remarks:		
Completed Blk 34AX with Digitzer		
No CASI		
21 Problems and Solutions:		
Acquisition Flight Approved by Acquisition Jught Certified by Acquisition Flight Approved by Acquisition Jught Certified by Acquisition Flight Approved by Command Signature over Printed Name (End Updr Representative) Signature over Printed Name (End Updr Representative)	Udar Operator LK PH rea of Signature of Printed Name	
Figure 6.10 Flight Log for Mission 7786AC		

iDAR 1 Data Acquisition Flight Log		1111 1110	E Alorente Tuno. Cocona T206H	6 Aircraft Identification:
AR ODERATOR 6 . Sirood parks ALTM Model: A. C.	3 Mission Name: 381/434/AVD	HAA Type: VFR	5 Aircraft Type: Cesnna Levon	
N MCANIN 8 CO-PILOT: 4. DE CCOMPO	9 Route:	India Internet	Minnet Chulbroutneel:	
ale: 12 Airport of Departure	2 (Alrport, City/Province): 1.	2 Airport of Arrival	Arpon, utyrnomer.	
14 Engine Off: 04 415	15 Total Engine Time: 1	6 Take off:	17 Landing:	18 Total Flight time:
eather Choung				
emarks: < Successful fin	MM. NO CASI.		•	
Problems and Solutions:				
Acquisition Flight Approved by Acquisition Flight Approved by Signature over Printed Name (End User Rughresentative)	Acquisition Flight Certified by	Pilot-in-Co	mmand	Lidar Operator

Figure 6.11 Flight Log for Mission 7798AC

10 Date: 11 Alt Engine Off: 12 Altport of Departure (Miport, Gry/Province) 13 Engine On: 14 Engine Off: 14 Engine Off: 15 Total Engine Time 13 Engine On: 14 Engine Off: 14 Engine Off: 15 Total Engine Time 13 Engine On: 14 Engine Off: 14 Engine Off: 15 Total Engine Time 13 Engine On: 14 Engine Off: 14 Engine Off: 15 Total Engine Time 19 Weasther 20.6 Billable 20.6 Others 30.6 Others 20.8 Billable 20.6 Others 20.6 Others 30.6 Others 20.8 Billable 20.6 Others 20.6 Others 30.6 Others 20.9 Entry Fight 0 Altrant Frait 0 Phil-UDAR Apin 0 System Test Fight 0 Others: 0 Phil-UDAR Apin 0 System Problem 0 System Problem 0 Others: 0 Phile 0 Others: 0 Others: 0 Others: 0 Phile 0 Others: 0 Others: 0 Others: 0 Phile 10 Others: 0 Others: 0 Others: 0 Phile	me: 16 Take off: 16 Take off: 16 Take off: 17 Particonol 16 Take off: 21 Remarks 21 Remarks 10 C C 2	mort, Ctty/Province):	
13 Englace Off. 12 Airport of De partier (Airport, City) Province) 13 Englace Off. 14 Englace Off. 15 Total Englace Time 13 Englace Off. 14 Englace Off. 15 Total Englace Time 13 Weather 20 Flight Classification 20 Cothers 20 Flight Classification 20 Aircraft Test Flight 0 IDAR System 20 System Test Flight 0 Aircraft Test Flight 0 Aircraft Maint 20 System Test Flight 0 Others: 0 Phil-UDAR Adi 20 System Test Flight 0 Others: 0 Phil-UDAR Adi 21 Problems and Solutions 0 Others: 0 Phil-UDAR Adi 22 Problems and Solutions 0 Others: 0 Phil-UDAR Adi 23 Problems and Solutions 0 Others: 0 Phil-UDAR Adi 24 Out Flight 0 Others: 0 Phil-UDAR Adi 23 Problems and Solutions 0 Phile 0 Phile 24 Out Flight 0 Others: 0 Phile 25 Problems 0 Others: 0 Phile 26 Others 0 Others: 0 Phile 27 Problem 0 Phile 0 Phile 28 Problem 0 Others: 0 Phile 29 Problem 0 Others: 0 Phile 29 Problem 0 Others: 0 Phile 29 Problem 0 Phile 0 Phile	ce): 12 Airport of Arrival (A) me: 16 Take off: h:10 21 Remarks 21 Remarks m Maintenance	mort, City/Province):	
13 Englace Ori: 14 Englace Off: 15 Total Englace Time 19 Weather 19 Weather 15 Total Englace Time 20 Hight Classification 20.6 Others 20.6 Others 20.a Billable 0 Alcraft Test Flight 0 Ind Rystem 20.5 System Fight 0 Others: 0 Phil-UDAR Add 21.6 Forty Flight 0 Others: 0 Phil-UDAR Add 22.7 Problems and Solutions 0 Others: 0 Phile 23.7 Problems and Solutions 0 Others: 0 Phile 23.8 Problems 0 Others: 0 Others: 0 Phile 24.9 Problem 0 Others: 0 Others: 0 Phile 24.0 Vitin Fight 0 Others: 0 Others: 0 Phile 24.0 Vitin Fight 0 Others: 0 Others: 0 Phile	me: 16 Take off: H-10 21 Remarks m Maintenance		
19 We ather Under Stillcation 20 Flight Classification 20.0 Non Billable 20.1 Billable 20.0 Others 20.2 Problems 20.0 Non Billable 20.3 Billable 20.0 Others 20.4 Fight 0 Alicraft Test Flight 20.5 System Test Flight 0 Others: 20.5 System Test Flight 0 Others: 21 Problems and Solutions 0 Others: 22 Problems and Solutions 0 Others: 23 Problems and Solutions 0 Others: 24 Problems 0 Others: 25 Problems and Solutions 0 Others: 26 System Problem 0 Others: 27 Problems 0 Others: 28 Problems 0 Others:	21 Remarks Maintenance	D'Landing: B : 3 9.	18 Total Flight Time: 3 + 16
20 Flight Classification 20.5 Non Billable 20.5 Cothers 20.a Billable 20.5 Non Billable 20.5 Cothers 20 Ferry Flight 0 Aircraft Teat Flight 0 UDAR System 0 System Test Flight 0 Aircraft Teat Flight 0 Nai-LIDAR Adit 0 System Test Flight 0 Others: 0 Aircraft Teat Flight 0 Aircraft Main 0 System Test Flight 0 Others: 0 Aircraft Teat Flight 0 Aircraft Main 0 System Test Flight 0 Others: 0 Aircraft Main 0 Phil-LIDAR Adit 0 System Problem 0 Others: 0 Aircraft Problem 0 Phil-LIDAR Adit 22 Problems and Solutions 0 Others: 0 Aircraft Problem 0 Phile 0 System Problem 0 Aircraft Problem 0 Others: 0 Aircraft Problem 0 Others: 0 Others: 0 Others: 0 Aircraft Centified by	21 Remarks m Maintenance		
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22 Problems and Solutions C Weather Problem C System Problem C Alrcraft Problem C Plot Problem C Others: C Others:	intenance Admin Activities	sty) High.	
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Parlines Arcev segreament & Domin Par	Pilot-In-Command	Uthe Operator	Aircraft Mechanic/ LIDAR Technician
	Ale af Chin	6. Stagen	hit
Signature over Printed Name Signatule over Printed Name S (End User Representative) (PAF Representative)	Signature over Printed Name	Signature dour Printed Name	Signature over Printed Name
	7		

Figure 6.12 Flight Log for Mission 3703G/3769G

7 Pilot: A. 1 AM	Malue 2 2 ALTM Model: "DUNI 8 CO-PILOT: R -LOTA CO	M 3 Mission Name: £ 844 3344 9 Route:	outsuloWa Type: VFR	5 Aircra ft Type: Cesni	na T206H 6 Aircraft Identification: AIC
10 Date: . 3) ~ [(0	12 Airport of Departure	(Airport, City/Province):	12 Airport of Arriva	I (Airport, Gty/Province):	
13 Engine On; 13 15 7	14 Engine Off:	15 Total Engine Time: 2 1 7 G	16 Take off: 13 : 57	17 Landing: 16: 40	18 Total Filght Time:
19 Weather	mindy				41.41
20 Flight Classification 20.a Billable Acquisition Flight O Ferry Flight O System Test Flight O Calibration Flight	 20.b Non Billable 20.b Non Billable Ancraft Test Flight AAC Admin Flight Others: 	20.c Others O LIDAR System Maint O Aircraft Maintenanci O Phil-LiDAR Admin Ac	21 Remar	mpletul a tew stud flight	lives over BIK 33A mly. Out to strong
22 Problems and Solutions	-				
 Weather Problem System Problem Aircraft Problem Pilot Problem Others: 					
Acquisition Flught Approved b Signature over Printed Name (End User Representative)	Acquisition Flight Cert	Dominu A	completes	UDAR Operator	Aircraft Mechanic/ UDAR Technic TUL 7 5 Ignature over Printed Name


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1 UDAR Operator: J.Aln 7 Pilot: A - Li W	Actures 2 ALTM Model: Print 8 Co-Pilot: K - Lotage	9 Route: 7.00 - 7	A Type: VFR	5 Alicra ft Type: Cesnna	Flight Log No.: 57 206H 6 Aircraft identification: 4222
10 Date: 2 - 1 - 1 6	12 Airport of Departure	(Airport, Gty/Province):	12 Airport of Arrival	(Airport, City/Province):	
13 Engine On: 0754/H	14 Engine Off: Lo 5 a H	15 Total Engine Time:	16 Take off: 1	17 Landing:	22 18 Total Flight Time:
19 Weather				ken!	2 412
0 Hight Classification			21 Remark	2	
0.a Billable <	20.b Non Billable O Aircraft Test Flight O AMC Admin Flight	20.c Others O LiDAR System Mainte	nance 6	vecess ful	Fright_
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2 Problems and Solutions					
O Weather Problem O System Problem					
 Aircraft Problem Pilot Problem Others: 		5			
				-	
Acquisition Flight Approved by	Acquisition Flight Cartl	led by Pilot-in-C) potentia	LibaR Operator	Aircraft Mechanic/ LIDAR Technician
1 - A IFCeD Signature over Printed Name (End User Representative)	Sa Parkine over Planed	A Murrie Supplying	ANA Pointed Name	J. Aprilia N.	L Z VA me Signature over Printed Name

Figure 6.15 Flight Log for Mission 3757G

Annex 7. Flight Status Report

SAMAR

(May 5-4, 10-11 and 13, 2014; February 7 and 13, 2015; and January 23, 31 and February 6, 2016)

FLIGHT NO	AREA	MISSION	OPERATOR	DATE FLOWN	REMARKS
1022A	BLK33B, BLK33C	3BLK33BSC025B	D.C. Aldovino	January 25, 2014	Lines cut due to terrain on the east side.
1410A	BLK33E	3BLK33E124A	I. Roxas	May 3, 2014	Completed test flight for Aquarius over survey area BLK33E.
1414A	BLK33E	3BLK33E124A	P.J. Arceo	May 4, 2014	Completed test flight for Aquarius over survey area BLK33E.
1438A	BLK33F	3BLK33F130A	P.J. Arceo	May,10 2014	Completed 18 lines over BLK34F.
1440A	BLK33F, BLK33G	3BLK33FSG130B	I. Roxas	May 10, 2014	Completed 15 lines over BLK33G.
1442A	BLK33G	3BLK33GS131A	I. Roxas	May 11, 2014	Completed 15/21 lines over BLK33G.
1444A	BLK33G, BLK33H	3BLK33GSH131B	P.J. Arceo	May 11, 2014	Completed 16 lines over BLK33H and 2 lines over BLK33G.
1450A	BLK33H	3BLK33HS133A	P.J. Arceo	May 13, 2014	Completed 6 out of 9 lines left over BLK34H, need to abort due to problem encountered in the aircraft temperature.
1452A	BLK33H, BLK33E	3BLK33HSES133B	I. Roxas	May 13, 2014	Completed mission over BLK34H and some voids over BLK33E.
7786AC	BLK34AX	3BLK34AX038A	L.K. Paragas	February 7, 2015	Completed Blk34AX with digitizer; No CASI.
7798AC	BLK34AX+VOIDS	3BLK34AV044A	G. Sinadjan	February 13, 2015	Completed Blk34A and some voids with digitizer; No CASI.

Table 4.1 LiDAR Survey Team Composition

3703G/ 3769G	BLK34D, BLK34F	2BLK34ADEG023A	J. Almalvez	January 23, 2016	Completed BLK34A, BLK34D and BLK 34E; Surveyed 6 lines at BLK34G.
3733G	BLK34L	2BLK33ABLK34L031A	J. Almalvez	January 31, 2016	Completed BLK34L and surveyed 7 lines at BLK33A.
3753G	BLK34K	2BLK34K33AB036A	G. Sinadjan	February 5, 2016	Surveyed BLK34K and completed BLK33A & 33B.
3757G	BLK34K	2BLK34K037A	J. Almalvez	February 6, 2016	Completed BLK34K.

LAS BOUNDARIES PER FLIGHT

Flight No. :	1022A				
Area:	BLK33B, BLK3	3C			
Mission Name:	3BLK33BSC02	3BLK33BSC025B			
Parameters:	Altitude:	600;			
	Scan Angle:	25deg;			

Scan Frequency: Overlap:

40Hz; 40%



Figure A-7.1 Swath for Flight No. 1022A



1410A BLK33E AQUATACTF123A Altitude: 600; Scan Angle: 18deg;

Scan Frequency:
Overlap:

50Hz; 30%



Figure A-7.2 Swath for Flight No.1410

Flight No. :	1414A	
Area:	BLK33E	
Mission Name:	AQUATACTF12	24A
Parameters:	Altitude:	600;
	Scan Angle:	18deg;

Scan Frequency:	50Hz;
Overlap:	30%





Figure A-7.3 Swath for Flight No. 1414A

50Hz; 30%

Flight No. :	1438A	
Area:	BLK33F	
Mission Name:	3BLK33E124A	
Parameters:	Altitude:	600;
	Scan Angle:	18deg;

Scan Frequency:	
Overlage	
Overlap:	



Figure A 7.4 Swath for Flight No. 1438A

Flight No. :	1438A			
Area:	BLK33F			
Mission Name:	3BLK33F130A	L .		
Parameters:	Altitude: Scan Angle:	600; 18deg;	Scan Frequency: Overlap:	50Hz; 30%





Figure A-7.5 Swath for Flight No. 1438A

1440A BLK33F, BLK33G 3BLK33FSG130B Altitude: 600; Scan Angle: 18deg;

Scan Frequency:	
Overlap:	

50Hz; 30%



Figure A-7.6 Swath for Flight No. 1440A

1442A		
BLK33G		
3BLK33GS131A	١	
Altitude:	600;	Sca
Scan Angle:	18deg;	Ove
	1442A BLK33G 3BLK33GS131A Altitude: Scan Angle:	1442A BLK33G 3BLK33GS131A Altitude: 600; Scan Angle: 18deg;

Scan Frequency:	50Hz;
Overlap:	30%





Figure A-7.7 Swath for Flight No. 1442A

1444A BLK34G, BLK34H 3BLK33GSH131B Altitude: 600; Scan Angle: 18deg;

Scan	Frequency:
Over	lap:

50Hz; 30%



Figure A-7.8 Swath for Flight No. 1444A

Flight No. :	1450A		
Area:	BLK33H		
Mission Name:	3BLK33HS133A		
Parameters:	Altitude:	600;	
	Scan Angle:	18deg;	

Scan Frequency:	
Overlap:	

50Hz; 30%



Figure A-7.9 Swath for Flight No. 1450A

1452A BLK33H, BLK33E 3BLK33HSES133B Altitude: 600; Scan Angle: 18deg;

Scan Frequency:
Overlap:

50Hz; 30%



Figure A-7.10 Swath for Flight No. 1452A

Flight No. :	7786AC
Area:	BLK34AX
Mission Name:	3BLK34AX038A
Parameters:	Altitude:
	Scan Angle:

Scan Frequency:	4
Overlap:	35

45Hz; 35%



600; 18deg;



Figure A-7.11 Swath for Flight No. 7786AC

7798AC BLK34AX+VOIDS 3BLK34AX044A Altitude: 600; Scan Angle: 18deg;

Scan Frequency:	
Overlap:	

45Hz; 35%



Figure A-7.12 Swath for Flight No. 7798AC

Flight No. :	3703G/3769G	ì	
Area:	BLK34D, BLK3	4E	
Mission Name:	2BLK34ADEG	023A	
Parameters:	Altitude:	1200;	
	Scan Angle:	17deg;	

Scan Frequency:	50Hz;
Overlap:	30%



Figure A-7.13 Swath for Flight No. 3703G/3769G

Flight No. : 3733G	
Area: BLK34L	
Mission Name: 2BLK33ABLK34L0)31A
Parameters: Altitude: 8	350;
Scan Angle: 2	Odeg;

Scan Frequency:	
Overlap:	

50Hz; 35%



Figure A-7.14 Swath for Flight No. 3733G

Flight No. :	3753G			
Area:	BLK34K			
Mission Name:	2BLK34K33AB0	36A		
Parameters:	Altitude: Scan Angle:	850; 20deg;	Scan Frequency: Overlap:	50Hz; 35%



Figure A-7.15 Swath for Flight No. 3753G

Flight No. :	3757G			
Area:	BLK34K			
Mission Name:	2BLK34K037A			
Parameters:	Altitude: Scan Angle:	850; 20deg;	Scan Frequency: Overlap:	50Hz; 35%



Figure A 7.16 Swath for Flight No. 3757G

Annex 8. Mission Summary Report

Flight Area	Samar-Leyte	
Mission Name	Blk33H	
Inclusive Flights	1444A, 1450A, 1452A	
Range data size	30.84 GB	
POS data size	619 MB	
Base data size	36 MB	
Image	160.5 GB	
Transfer date	May 28, 2014	
Solution Status		
Number of Satellites (>6)	Yes	
PDOP (<3)	Yes	
Baseline Length (<30km)	Yes	
Processing Mode (<=1)	No	
Smoothed Performance Metrics (in cm)		
PMSE for North Position (<4.0 cm)	1.8	
RMSE for Fast Position (<4.0 cm)	1.6	
	1.0	
RMSE for Down Position (<8.0 cm)	2.9	
Boresight correction stdey (<0.001deg)	0.000310	
IMU attitude correction stdev (<0.001deg)	0.000915	
GPS position stdev (<0.01m)	0.0030	
Minimum % overlap (>25)	46.76%	
Ave point cloud density per sq.m. (>2.0)	3.36	
Elevation difference between strips (<0.20 m)	Yes	
Number of 1km x 1km blocks	261	
Maximum Height	328.04 m	
Minimum Height	56.94 m	
Classification (# of points)		
Ground	120,058,822	
Low vegetation	54,325,156	
Medium vegetation	230,234,006	
High vegetation	163,298,807	
Building	1,762,420	
Orthophoto	Yes	
Processed by	Engr. Irish Cortez, Aljon Rie Araneta, Engr. Gladys Mae Apat	

Table A-8.1 Mission Summary Report for Blk33H



Figure A 8.1. Solution Status



Figure A 8.2 Smoothed Performance Metrics Parameters



Figure A 8.3 Best Estimated Trajectory



Figure A 8.4 Coverage of LiDAR data



Figure A 8.5 Image of Data Overlap



Figure A 8.6 Density map of merged LiDAR data



Figure A 8.7 Elevation difference between flight lines

Flight Area	Samar-Leyte	
Mission Name	Blk33G	
Inclusive Flights	1440A, 1442A	
Range data size	28 GB	
POS data size	459 MB	
Base data size	31.8 MB	
Image	174.8 GB	
Transfer date	May 28, 2014	
Solution Status		
Number of Satellites (>6)	No	
PDOP (<3)	Yes	
Baseline Length (<30km)	No	
Processing Mode (<=1)	No	
Smoothed Performance Metrics (in cm)		
RMSE for North Position (<4.0 cm)	2.2	
RMSE for East Position (<4.0 cm)	1.9	
RMSE for Down Position (<8.0 cm)	4.3	
Boresight correction stdev (<0.001deg)	0.000322186	
IMU attitude correction stdev (<0.001deg)	0.0609276	
GPS position stdev (<0.01m)	0.034031	
Minimum % overlap (>25)	32.09%	
Ave point cloud density per sq.m. (>2.0)	3.01	
Elevation difference between strips (<0.20 m)	Yes	
Number of 1km x 1km blocks	312	
Maximum Height	365.67 m	
Minimum Height	58.80 m	
Classification (# of points)		
Ground	77 148 752	
	65 926 334	
Medium vegetation	201.996.077	
High vegetation	198.312.411	
Building	3.402.990	
Orthophoto	Yes	
Processed hy	Engr Carlyn Ann Ibañez Engr Antonio Chua Ir	
	Ailyn Biñas	

Table A-8.2 Mission Summary Report for Blk33G







Figure A 8.9 Smoothed Performance Metrics Parameters



Figure A 8.10 Best Estimated Trajectory



Figure A 8.11 Coverage of LiDAR data



Figure A 8.12 Image of data overlap



Figure A 8.13 Density map of merged LiDAR data



Figure A 8.14 Elevation difference between flight lines

Flight Area	Samar-Leyte	
Mission Name	Blk33F	
Inclusive Flights	1438A, 1440A	
Range data size	28.6 GB	
POS data size	463 MB	
Base data size	35 MB	
Image	188.8 GB	
Transfer date	May 28, 2014	
Solution Status		
Number of Satellites (>6)	No	
PDOP (<3)	Yes	
Baseline Length (<30km)	No	
Processing Mode (<=1)	No	
Smoothad Barfarmanca Matrics (in cm)		
	2.2	
RMISE for North Position (<4.0 cm)	2.3	
RMSE for East Position (<4.0 cm)	2.1	
RMSE for Down Position (<8.0 cm)	5.3	
Boresight correction stdev (<0.001deg)	0.000408	
INU attitude correction stdev (<0.001deg)	0.000997	
GPS position stdev (<0.01m)	0.0088	
Minimum % overlan (>25)	44 22%	
Ave point cloud density per sq m (>2.0)	3 01	
Elevation difference between strins (<0.20 m)	Ves	
Number of 1km x 1km blocks	315	
Maximum Height	304.65 m	
Minimum Height	52.08 m	
Classification (# of points)		
Ground	91,416,640	
Low vegetation	73,231,907	
Medium vegetation	216,370,969	
High vegetation	167,159,477	
Building	1,402,580	
Orthophoto	Yes	
Processed by	Engr. Carlyn Ann Ibañez, Engr. Melanie Hingpit, Engr. Gladys Mae Apat	

Table A-8.3 Mission Summary Report for Blk33F







Figure A 8.16 Smoothed Performance Metrics Parameters



Figure A 8.17 Best Estimated Trajectory



Figure A 8.18 Coverage of LiDAR data



Figure A 8.19 Image of data overlap



Figure A 8.20 Density map of merged LiDAR data



Figure A 8.21 Elevation difference between flight lines

Flight Area	Samar-Leyte	
Mission Name	Blk33E_addtional	
Inclusive Flights	1410A	
Range data size	15.3 GB	
POS data size	281 MB	
Base data size	7.61 MB	
Image	51 GB	
Transfer date	May 28, 2014	
Solution Status		
Number of Satellites (>6)	Yes	
PDOP (<3)	Yes	
Baseline Length (<30km)	No	
Processing Mode (<=1)	No	
Smoothed Performance Metrics (in cm)		
RMSE for North Position (<4.0 cm)	1.9	
RMSE for East Position (<4.0 cm)	2.3	
RMSE for Down Position (<8.0 cm)	3.7	
Boresight correction stdev (<0.001deg)	0.000358	
IMU attitude correction stdev (<0.001deg)	0.000887	
GPS position stdev (<0.01m)	0.0028	
Minimum % overlap (>25)	39.41%	
Ave point cloud density per sq.m. (>2.0)	2.82	
Elevation difference between strips (<0.20 m)	Yes	
Number of 1km x 1km blocks	179	
Maximum Height	419.70 m	
Minimum Height	58.53 m	
Classification (# of points)		
Ground	20 002 221	
	20,302,321	
Nedium vegetation	20,520,279	
	50,819,190	
	03,360,000	
	072,021 No	
Processed by	Victoria Rejuso, Engr. Melanie Hingpit, Engr. Gladys Mae Apat	

Table A-8.4 Mission Summary Report for Blk33E_additional



Figure A 8.22 Solution Status



Figure A 8.23 Smoothed Performance Metrics Parameters



Figure A 8.24 Best Estimated Trajectory



Figure A 8.25 Coverage of LiDAR data


Figure A 8.26 Image of data overlap



Figure A 8.27 Density map of merged LiDAR data

Hazard Mapping of the Philippines Using LiDAR (Phil-LiDAR 1)



Figure A 8.28 Elevation difference between flight lines

Flight Area	Samar-Leyte
Mission Name	Blk33E
Inclusive Flights	1452A
Range data size	9.57 GB
POS data size	233 MB
Base data size	11.2 MB
Image	47.1 GB
Transfer date	May 28, 2014
Solution Status	
Number of Satellites (>6)	Yes
PDOP (<3)	Yes
Baseline Length (<30km)	No
Processing Mode (<=1)	No
Smoothed Performance Metrics (in cm)	
RMSE for North Position (<4.0 cm)	1.58
RMSE for East Position (<4.0 cm)	2.28
RMSE for Down Position (<8.0 cm)	3.9
Boresight correction stdev (<0.001deg)	0.000498
IMU attitude correction stdev (<0.001deg)	0.000909
GPS position stdev (<0.01m)	0.0025
Minimum % overlap (>25)	33.85%
Ave point cloud density per sq.m. (>2.0)	2.63
Elevation difference between strips (<0.20 m)	Yes
Number of 1km x 1km blocks	190
Maximum Height	419.67 m
Minimum Height	56.02 m
Classification (# of points)	
Ground	31,505,889
Low vegetation	25,749,491
Medium vegetation	53,225,191
High vegetation	64,445,794
Building	866,018
Orthophoto	Yes
Processed by	Victoria Rejuso, Engr. Melanie Hingpit, Engr. Ma. Ailyn Olanda

Table A-8.5 Mission Summary Report for Blk33E



Figure A 8.29 Solution Statust



Figure A 8.30 Smoothed Performance Metrics Parameters



Figure A 8.31 Best Estimated Trajectory



Figure A 8.32 Coverage of LiDAR data



Figure A 8.33 Image of data overlap



Figure A 8.34 Density map of merged LiDAR data



Figure A 8.35 Elevation difference between flight lines

Flight Area	Samar-Leyte
Mission Name	33F
Inclusive Flights	3781G, 23773G
Range data size	20.36
POS data size	386
Base data size	13.57
Image	n/a
Transfer date	March 04, 2016
Solution Status	
Number of Satellites (>6)	Yes
PDOP (<3)	No
Baseline Length (<30km)	Yes
Processing Mode (<=1)	Yes
Smoothed Performance Metrics (in cm)	
RMSE for North Position (<4.0 cm)	1.0
RMSE for East Position (<4.0 cm)	1.4
RMSE for Down Position (<8.0 cm)	3.1
Boresight correction stdev (<0.001deg)	0.001088
IMU attitude correction stdev (<0.001deg)	0.002573
GPS position stdev (<0.01m)	0.0113
Minimum % overlap (>25)	41.49
Ave point cloud density per sq.m. (>2.0)	4.86
Elevation difference between strips (<0.20 m)	Yes
Number of 1km x 1km blocks	142
Maximum Height	315.78 m
Minimum Height	25.54 m
(lacsification (# of points)	
Ground	25 222 202
	25,232,203
Medium vegetation	132 149 471
High vegetation	162,406,497
Building	2 147 712
Orthophoto	no
Processed by	Engr Don Matthew Banatin Engr Melanie Hingnit
FIOLESSED by	Engr. Monalyne Rabino

Table A-8.6 Mission Summary Report for Blk33F



Figure A 8.36. Solution Status



Figure A 8.37 Smoothed Performance Metric Parameters



Figure A 8.38 Best Estimated Trajectoryt



Figure A 8.39 Coverage of LiDAR Data



Figure A 8.40 Image of data overlap



Figure A 8.41 Density map of merged LiDAR data



Figure A 8.42 Elevation difference between flight lines

Flight Area	Samar-Leyte
Mission Name	33E
Inclusive Flights	3731G, 3733G
Range data size	41
POS data size	456
Base data size	7.93
Image	n/a
Transfer date	February 26, 2016
Solution Status	
Number of Satellites (>6)	Yes
PDOP (<3)	Yes
Baseline Length (<30km)	No
Processing Mode (<=1)	Yes
Smoothed Performance Metrics (in cm)	
RMSE for North Position (<4.0 cm)	1.6
RMSE for East Position (<4.0 cm)	1.7
RMSE for Down Position (<8.0 cm)	3.1
Boresight correction stdev (<0.001deg)	0.001467
IMU attitude correction stdev (<0.001deg)	0.015072
GPS position stdev (<0.01m)	0.0030
Minimum % overlap (>25)	25.09
Ave point cloud density per sq.m. (>2.0)	3.27
Elevation difference between strips (<0.20 m)	Yes
Number of 1km x 1km blocks	120
Maximum Height	424.91 m
Minimum Height	65.68 m
Classification (# of points)	
Ground	39 315 973
	28 880 555
Medium vegetation	99.951 686
High vegetation	100.500.330
Building	422.184
Orthophoto	No
Processed by	Engr. Abigail Joy Ching, Engr. Velina Angela Bemida, Maria Tamsyn Malabanan

Table A-8.7 Mission Summary Report for Blk33E



Figure A 8.43 Solution Status



Figure A 8.44 Smoothed Performance Metric Parameters



Figure A 8.45 Best Estimated Trajectory



Figure A 8.46 Coverage of LiDAR Data



Figure A 8.47 Image of data overlap



Figure A 8.48 Density map of merged LiDAR data



Figure A 8.49 Elevation difference between flight lines

Flight Area	Samar-Leyte
Mission Name	33E_Additional
Inclusive Flights	3731G, 3733G
Range data size	41
POS data size	456
Base data size	7.93
Image	n/a
Transfer date	February 26, 2016
Solution Status	
Number of Satellites (>6)	Yes
PDOP (<3)	Yes
Baseline Length (<30km)	No
Processing Mode (<=1)	Yes
Smoothed Performance Metrics (in cm)	
RMSE for North Position (<4.0 cm)	1.6
RMSE for East Position (<4.0 cm)	1.7
RMSE for Down Position (<8.0 cm)	3.1
Boresight correction stdev (<0.001deg)	0.001467
IMU attitude correction stdev (<0.001deg)	0.015072
GPS position stdev (<0.01m)	0.0030
Minimum % overlap (>25)	N/A
Ave point cloud density per sq.m. (>2.0)	2.66
Elevation difference between strips (<0.20 m)	Yes
Number of 1km x 1km blocks	31
Maximum Height	162.61 m
Minimum Height	66.12 m
Classification (# of points)	
Ground	2 493 277
Low vegetation	1.964.480
Medium vegetation	9.685.599
High vegetation	6,040,442
Building	183,120
Orthophoto	No
Processed by	Engr. Abigail Joy Ching, Aljon Rie Araneta, Jovy Narisma

Table A-8.8 Mission Summary Report for Blk33E_additional



Figure A 8.50 Solution Status



Figure A 8.51 Smoothed Performance Metric Parameters



Figure A 8.52 Best Estimated Trajectory



Figure A 8.53 Coverage of LiDAR Data



Figure A 8.54 Image of data overlap



Figure A 8.55 Density map of merged LiDAR data

Flight Area	Samar-Leyte
Mission Name	33G
Inclusive Flights	3731G
Range data size	24.2
POS data size	208
Base data size	3.19
Image	n/a
Transfer date	February 26, 2016
Solution Status	
Number of Satellites (>6)	Yes
PDOP (<3)	Yes
Baseline Length (<30km)	No
Processing Mode (<=1)	Yes
Smoothed Performance Metrics (in cm)	
RMSE for North Position (<4.0 cm)	1.3
RMSE for East Position (<4.0 cm)	1.5
RMSE for Down Position (<8.0 cm)	3.2
Boresight correction stdev (<0.001deg)	0.056859
IMU attitude correction stdev (<0.001deg)	0.014534
GPS position stdev (<0.01m)	0.0028
Minimum % overlap (>25)	33.88
Ave point cloud density per sq.m. (>2.0)	4.58
Elevation difference between strips (<0.20 m)	Yes
Number of 1km x 1km blocks	163
Maximum Height	878.23 m
Minimum Height	60.91 m
Classification (# of points)	
Ground	31 482 852
Low vegetation	14.484.247
Medium vegetation	240,244.360
High vegetation	329,944,677
Building	458,985
Orthophoto	No
Processed by	Engr. Abigail Joy Ching, Ma. Joanne Balaga, Marie Denise Bueno

Table A-8.9 Mission Summary Report for Blk33G



Figure A 8.55 Solution Statust



Figure A 8.56 Smoothed Performance Metric Parameters



Figure A 8.57 Best Estimated Trajectory



Figure A 8.58 Coverage of LiDAR Data



Figure A 8.59 Image of data overlap



Figure A 8.60 Density map of merged LiDAR data



Figure A 8.61 Elevation difference between flight lines

Flight Area	Samar-Leyte
Mission Name	Blk34AX
Inclusive Flights	7786AC, 7798AC
Range data size	19.6 GB
POS	440 MB
Base data size	41.28 MB
Image	0 GB
Transfer date	March 9 2015
Solution Status	
Number of Satellites (>6)	Yes
PDOP (<3)	Yes
Baseline Length (<30km)	Yes
Processing Mode (<=1)	Yes
Smoothed Performance Metrics (in cm)	
RMSE for North Position (<4.0 cm)	1.35
RMSE for East Position (<4.0 cm)	1.32
RMSE for Down Position (<8.0 cm)	2.56
Boresight correction stdev (<0.001deg)	0.000269
IMU attitude correction stdev (<0.001deg)	0.000970
GPS position stdev (<0.01m)	0.0010
Minimum % overlap (>25)	43.46
Ave point cloud density per sq.m. (>2.0)	3.17
Elevation difference between strips (<0.20 m)	Yes
Number of 1km x 1km blocks	165
Maximum Height	486.81 m
Minimum Height	58.38 m
Classification (# of points)	
Ground	51,480,658
Low vegetation	54,126,552
Medium vegetation	96,821,393
High vegetation	72,112,485
Building	1,892,628
Orthophoto	No
Processed by	Engr. Sheila-Maye Santillan, Engr. Harmond Santos, Engr. Krisha Marie Bautista

Table A-8.10 Mission Summary Report for Blk34AX



Figure A 8.62Solution Status



Figure A 8.63 Smoothed Performance Metric Parameters



Figure A 8.64 Best Estimated Trajectory



Figure A 8.65 Coverage of LiDAR data



Figure A 8.66 Image of data overlap



Figure A 8.67 Density map of merged LiDAR data



Figure A 8.68 Elevation difference between flight lines

Flight Area	Samar-Leyte
Mission Name	Blk34AX_additional
Inclusive Flights	7798AC
Range data size	7.81 GB
POS data size	186 MB
Base data size	31.8 MB
Image	N/A
Transfer date	March 9, 2015
Solution Status	
Number of Satellites (>6)	Yes
PDOP (<3)	Yes
Baseline Length (<30km)	Yes
Processing Mode (<=1)	Yes
Smoothed Performance Metrics (in cm)	
RMSE for North Position (<4.0 cm)	1.75
RMSE for East Position (<4.0 cm)	1.75
RMSE for Down Position (<8.0 cm)	1.83
Boresight correction stdev (<0.001deg)	0.000564
IMU attitude correction stdev (<0.001deg)	0.000970
GPS position stdev (<0.01m)	0.0022
Minimum % overlap (>25)	N/A
Ave point cloud density per sq.m. (>2.0)	1.89
Elevation difference between strips (<0.20 m)	Yes
Number of 1km x 1km blocks	24
Maximum Height	272.69 m.
Minimum Height	0.0 m.
Classification (# of points)	
Ground	2.417.317
Low vegetation	1.752.643
Medium vegetation	2,609,904
High vegetation	1,582,659
Building	36,220
Orthophoto	No
Processed by	Engr. Abigail Joy Ching, Engr. Harmond Santos, Krisha



Figure A 8.69 Solution Status



Figure A 8.70 Smoothed Performance Metric Parameters



Figure A 8.71 Best Estimated Trajectory



Figure A 8.72Coverage of LiDAR data



Figure A 8.73 Image of data overlap



Figure A 8.74 Density map of merged LiDAR data

Flight Area	Samar-Leyte
Mission Name	1022A
Inclusive Flights	1022A
Range data size	18.9 GB
POS	242 MB
Image	75.3 GB
Transfer date	February 3, 2015
Solution Status	
Number of Satellites (>6)	Yes
PDOP (<3)	Yes
Baseline Length (<30km)	Yes
Processing Mode (<=1)	Yes
Smoothed Performance Metrics (in cm)	
RMSE for North Position (<4.0 cm)	3.1
RMSE for East Position (<4.0 cm)	1.7
RMSE for Down Position (<8.0 cm)	5.0
Boresight correction stdev (<0.001deg)	0.018287
IMU attitude correction stdev (<0.001deg)	0.088089
GPS position stdev (<0.01m)	0.018843
Minimum % overlap (>25)	27.88%
Ave point cloud density per sq.m. (>2.0)	1.60
Elevation difference between strips (<0.20 m)	Yes
Number of 1km x 1km blocks	218
Maximum Height	420.48 m
Minimum Height	56.96 m
Classification (# of points)	
Ground	204,739,490
Low vegetation	116,809,603
Medium vegetation	339,586,405
High vegetation	57,374,755
Building	9,080,871
Orthophoto	Yes
Processed by	Engr. Irish Cortez, Engr. Melanie Hingpit, Engr. Gladys Mae Apat


Figure A 8.75 Solution Status



Figure A 8.76 Smoothed Performance Metrics Parameters



Figure A 8.77 Best Estimated Trajectory



Figure A 8.78 Coverage of LiDAR data



Figure A 8.79 Image of data overlap



Figure A 8.80 Density map of merged LiDAR data



Figure A 8.81 Elevation difference between flight lines

Clark Unit Hydrograph SCS Curve Number Loss **Recession Baseflow** Transform Basin Number Initial Time of Storage Initial Ratio Curve Impervious Initial Recession Threshold Abstraction Concentration Coefficient Discharge to Number Constant (%) Туре Type (HR) (HR) (M3/S) (mm) Peak Ratio to W580 39.7265 0 0.10376 1.4018 0.9 0.01 0.25 99 0.01881 Peak Ratio to W570 89.3169 0 2.0847 0.378 1.4018 0.01 0.25 99 0.9 Peak Ratio to 0 0.25 W560 46.5764 99 1.8347 0.3327 1.4018 0.9 0.01 Peak Ratio to W550 151.213 99 0 5.168 0.937 1.4018 0.9 0.01 0.25 Peak Ratio to W540 46.9726 99 0 0.6978 0.1265 1.4018 0.9 0.01 0.25 Peak Ratio to 0.25 W530 51.6607 99 0 1.391 0.2522 1.4018 0.9 0.01 Peak Ratio to W520 46.9726 99 0 1.1295 0.2048 1.4018 0.9 0.01 0.25 Peak Ratio to W510 46.9726 99 0 2.8529 0.517 1.4018 0.9 0.01 0.25 Peak Ratio to 46.9726 0 W500 99 0.5799 0.1052 1.4018 0.9 0.01 0.25 Peak Ratio to W490 46.9726 99 0 1.6538 0.2999 1.4018 0.01 0.25 0.9 Peak Ratio to W480 46.9726 0 0.9163 1.4018 0.9 0.01 0.25 99 0.1662 Peak Ratio to W470 88.8318 99 0 1.4043 0.2546 1.4018 0.9 0.01 0.25 Peak Ratio to W460 108.71 99 0 1.1627 0.2108 1.4018 0.9 0.01 0.25 Peak Ratio to 0.25 W450 46.9726 0 1.4008 1.4018 0.9 0.01 99 0.254 Peak Ratio to W440 46.9726 99 0 1.3713 0.2487 1.4018 0.9 0.01 0.25 Peak Ratio to W430 97.2889 99 0 6.597 1.196 1.4018 0.9 0.01 0.25 Peak Ratio to W420 89.3691 99 0 3.2796 0.595 1.4018 0.9 0.01 0.25 Peak Ratio to 0.25 W410 99.2902 0 1.6926 0.3069 1.4018 0.9 0.01 99 Peak Ratio to W400 84.6667 99 0 1.032 0.1871 1.4018 0.9 0.01 0.25 Peak Ratio to W390 84.6667 99 0 2.5212 0.5658 1.4018 0.9 0.01 0.25 Peak Ratio to 0.0048898 51.820218 0.0 0.8054 0.65720 Discharge 0.20700 0.25 W1460 0.19 Peak Ratio to W1450 0.0033612 61.204077 0.0 0.64588 0.52704 0.25607 0.19 0.25 Discharge Peak

Annex 9. Basey Model Basin Parameters

Annex 10. Basey Model Reach Parameters

	Muskingum Cunge Channel Routing											
Reach Number	Time Step Method	Length (m)	Slope	Manning's n	Shape	Width	Side Slope					
R30	Automatic Fixed Interval	2661.1	0.0197065	0.04	Trapezoid	6.345	0.1					
R60	Automatic Fixed Interval	3036.1	0.0162086	0.04	Trapezoid	4.50625	0.1					
R70	Automatic Fixed Interval	113.14	0.0756556	0.04	Trapezoid	7.4525	0.1					
R90	Automatic Fixed Interval	2624.2	0.000655691	0.04	Trapezoid	9.92	0.1					
R120	Automatic Fixed Interval	7678.9	0.0032939	0.04	Trapezoid	6.975	0.1					
R140	Automatic Fixed Interval	6104.1	0.0082528	0.04	Trapezoid	22.49625	0.1					
R170	Automatic Fixed Interval	168.28	9.92E-05	0.04	Trapezoid	7.19125	0.1					
R180	Automatic Fixed Interval	7733.6	0.0114894	0.04	Trapezoid	17.235	0.1					
R190	Automatic Fixed Interval	7362.5	0.000869694	0.04	Trapezoid	5.27375	0.1					
R210	Automatic Fixed Interval	3958.6	0.0101424	0.04	Trapezoid	12.63625	0.1					
R230	Automatic Fixed Interval	3022.7	9.92E-05	0.04	Trapezoid	10.33875	0.1					
R240	Automatic Fixed Interval	752.55	0.0082966	0.04	Trapezoid	12.60125	0.1					
R260	Automatic Fixed Interval	2469.7	0.0053036	0.04	Trapezoid	61.94625	0.1					
R280	Automatic Fixed Interval	243.99	9.92E-05	0.04	Trapezoid	57.1575	0.1					

in Return/ icenario	5Yr	5Yr	5Yr	5Yr	5Yr	5Yr	5Yr	5Yr	5Yr	5Yr	5Yr	5Yr	5Yr
Date of Ra Occurence		December 06, 2014	December 06, 2014		December 06, 2014		December 06, 2014	December 28, 2014		December 06, 2014	December 06, 2014	December 28, 2014	
Event	Nov. 19-20	Ruby	Ruby		Ruby	Heavy Rain	Ruby	Senyang	Dec. 2015	Ruby	Ruby	Senyang	Undang
Error	-0.08	0.22	0.03	0.03	-0.36	-0.16	-0.02	-0.02	-0.02	-4.97	-4.92	-0.32	-0.92
Model Var (m)	0.220	0.220	0.030	0.030	0.040	0.040	0.280	0.280	0.280	0.030	0.080	0.080	0.080
Validation Points (m)	0.3	0	0	0	0.4	0.2	0.3	0.3	0.3	5	5	0.4	1
Longitude	125.1600624	125.1600624	125.1584962	125.1542203	125.1533064	125.1533064	125.152725	125.152725	125.152725	125.1467403	125.1462274	125.1462274	125.1462274
Latitude	11.26460874	11.26460874	11.26567114	11.26848755	11.27174576	11.27174576	11.27288855	11.27288855	11.27288855	11.27860249	11.27813193	11.27813193	11.27813193
Point Number	1	2	m	4	5	9	2	œ	6	10	11	12	13

Annex 11. Basey Field Validation

Rain Return/ Scenario	5Υr	5Υr	5Υr	БҮr	5Yr	5Yr	5Υr	БҮr	БҮr	5Yr	5Υr	5Yr	5Yr	5Υr	5Υr	5Υr
Date of Occurence	December 06, 2014			December 06, 2014	December 06, 2014	December 06, 2014	December 06, 2014	December 28, 2014	December 06, 2014		December 06, 2014			December 06, 2014	December 28, 2014	December 06, 2014
Event	Ruby	Heavy Rain	Heavy Rain	Ruby	Ruby	Ruby	Ruby	Senyang	Ruby	Heavy Rain	Ruby	Heavy Rain	Heavy Rain	Ruby	Senyang	Ruby
Error	0.03	-0.07	0.02	-0.28	0.15	0.03	-0.07	0.03	0.03	-0.07	0.03	-0.37	0.03	-0.37	-0.37	-1.26
Model Var (m)	0.030	0:030	0.220	0.220	0.150	0.030	0:030	0.030	0:030	0:030	0:030	0:030	0:030	0:030	0.030	0.040
Validation Points (m)	0	0.1	0.2	5.0		0	0.1	0	0	0.1	0	0.4	0	0.4	0.4	1.3
Longitude	125.1455251	125.1455251	125.1487922	125.1487922	125.1454892	125.1383577	125.1313067	125.1313067	125.1277848	125.1277848	125.1220953	125.1215032	125.1446257	125.1446257	125.1446257	125.1457168
Latitude	11.2781906	11.2781906	11.28061918	11.28061918	11.28311548	11.28591679	11.28767733	11.28767733	11.28818703	11.28818703	11.28996626	11.28856086	11.30282284	11.30282284	11.30282284	11.30388575
Point Number	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29

Rain Return/ Scenario	БҮr	БҮr	БҮr	БҮr	5Yr	БҮr	БҮr	БҮr	БҮr	БҮr	БҮr	БҮr	БҮr	БҮr
Date of Occurence	December 28, 2014		December 06, 2014	December 28, 2014				December 06, 2014	December 06, 2014		December 06, 2014		December 06, 2014	
Event	Senyang	Ruping	Ruby	Senyang	Ruping	Ondoy	Heavy Rain	Ruby	Ruby	Undang	Ruby	Undang	Ruby	Undang
Error	-1.26	0.04	-0.96	0.04	-0.96	-0.96	-0.96	-0.24	0.07	-2.63	-0.18	-1.42	0.08	-0.91
Model Var (m)	0.040	0.040	0.040	0.040	0.040	0.040	0.040	0.260	0.370	0.370	0.120	0.080	0.080	060.0
Validation Points (m)	1.3	0	1	0	1	1	1	0.5	0.3	m	0.3	1.5	0	1
Longitude	125.1457168	125.1457168	125.1469968	125.1469968	125.1469968	125.1469968	125.1469968	125.132101	125.1300947	125.1300947	125.1305735	125.1178368	125.1178368	125.0811016
Latitude	11.30388575	11.30388575	11.30464573	11.30464573	11.30464573	11.30464573	11.30464573	11.29918308	11.29911594	11.29911594	11.29792982	11.29624506	11.29624506	11.29249684
Point Number	30	31	32	33	34	35	36	37	38	39	40	41	42	43

Annex 12. Educational Institutions Affected in Basey Floodplain

SAMAR											
BASEY											
Puilding Name	Parangay	Rainfall Scenario									
	Багапдау	5-year	25-year	100-year							
ANGLIT ELEMENTARY SCHOOL	Anglit	Low	Medium	Medium							
SAMAR STATE UNIVERSITY	Balante										
VALERIANO C. YANCHA MEMORIAL AGRICULTURE	Balante										
SAMAR STATE UNIVERSITY	Baloog										
VALERIANO C. YANCHA MEMORIAL AGRICULTURE	Baloog										
BALUD ELEMENTARY SCHOOL	Binongtu-an		Low	Low							
DAY CARE CENTER	Binongtu-an		Low	Low							
BRGY. DAY CARE CENTER	Buenavista	Low	Low	Low							
BUENAVISTA ELEMENTARY SCHOOL	Buenavista										
BURGOS INTEGRATED SCHOOL	Burgos		Low	Medium							
COGON ELEMENTARY SCHOOL	Cogon										
VALERIANO C. YANCHA MEMORIAL AGRICULTURE	Dolongan										
DAY CARE CENTER	Iba		Low	Low							
IBA ELEMENTARY SCHOOL	Iba	Low	Low	Medium							
SAWA ELEMENTARY SCHOOL	Iba	Low	Low	Medium							
MAGALLANES ELEMENTARY SCHOOL	Magallanes			Low							
NEW SAN AGUSTIN ELEMENTARY SCHOOL	New San Agustin	Medium	Medium	Medium							
BALUD ELEMENTARY SCHOOL	Nouvelas Occidental			Low							
SERUM ELEMENTARY SCHOOL	Nouvelas Occidental		Low	Medium							
OLD SAN AGUSTIN ELEMENTARY SCHOOL	Old San Agustin	Medium	Medium	Medium							
PANUGMONON ELEMENTARY SCHOOL	Panugmonon		Medium	High							
PANUGMONON ELEMENTARY SCHOOL	San Fernando		Medium	High							
SERUM ELEMENTARY SCHOOL	Serum			Medium							

Annex 13. Medical Institutions Affected in Basey Floodplain

Table A-13.1. Medical Institutions in Dipolog City, Zamboanga del Norte affected by flooding in Dipolog Floodplain

ZAMBOANGA DEL NORTE											
DIPOLOG CITY											
Duilding Name	Barangay	Rainfall Scenario									
	Darangay	5-year	25-year	100-year							
NEW SAN AGUSTING HEALTH CENTER	New San Agustin		Low	Medium							